

## Plan for today

- MCMC: what have we learned
- More on MCMC
- Special cases of the MH algorithm
- The Gibbs sampler

## MCMC what we have learned:

- **Problem:** Sample from  $\pi(x)$ ,  $x \in S$ .
- **MCMC idea:**
  - ▶ Construct **Markov chain with  $\pi(x)$  as limiting distribution.**
  - ▶ Simulate the Markov chain for a long time so that it has time to converge.
  - ▶ **Most MCMC samplers are based on reversible Markov chains**  
 $\Rightarrow$  Their convergence is proved by checking the detailed balance equation.

## Review: Metropolis-Hastings construction

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$$P(y | x) = \begin{cases} Q(y | x)\alpha(y | x), & y \neq x \\ 1 - \sum_{z \neq x} Q(z | x)\alpha(z | x), & y = x \end{cases}$$

•

$$\alpha(y | x) = \min \left\{ 1, \frac{\pi(y)}{\pi(x)} \cdot \frac{Q(x | y)}{Q(y | x)} \right\}$$

## Review: Metropolis-Hastings algorithm

- 1: Init  $x_0 \sim g(x_0)$
- 2: **for**  $i = 1, 2, \dots$  **do**
- 3:   Generate a proposal  $y \sim Q(y|x_{i-1})$
- 4:    $u \sim U(0, 1)$
- 5:   **if**  $u < \underbrace{\min \left( 1, \frac{\pi(y)}{\pi(x_{i-1})} \times \underbrace{\frac{Q(x_{i-1}|y)}{Q(y|x_{i-1})}}_{\text{Proposal ratio}} \right)}_{\text{Acceptance probability } \alpha}$  **then**
- 6:      $x_i \leftarrow y$
- 7:   **else**
- 8:      $x_i \leftarrow x_{i-1}$
- 9:   **end if**
- 10: **end for**

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- **Irreducible**: Must be checked in each case. Must choose  $Q(y | x)$  so that this is ok.
- **Aperiodic**: Sufficient that  $P(x | x) > 0$  for one  $x \in S$ , so sufficient that  $\alpha(y | x) < 1$  for one pair  $y, x \in S$ .
- **Positive recurrent**: for finite  $S$ , irreducibility is sufficient. More difficult in general, but if Markov chain is not recurrent we will see this as drift in the simulations. (In practice usually no problem).

## What about continuous distributions?

See Notes

## Metropolis-Hastings algorithm

Elements of the problem:

- Target distribution  $\pi(x)$ : Given by the problem
- Proposal distribution  $Q(y|x)$ : Chosen by the user
- Acceptance probability  $\alpha(y|x)$ : Derived in order to fulfill the detailed balance condition.

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## Remarks on the Metropolis-Hastings algorithm

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For more comments and details see: Chib, S. and Greenberg, E. (1995), *Understanding the*

*Metropolis-Hastings algorithm*, *The American Statistician*, 49: 327–335

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- However, the **speed of convergence** and the **dependence between the successive samples** depends strongly on the proposal distribution.
- Since we only need to compute the ratio  $\pi(y)/\pi(x)$ , the **proportionality constant is irrelevant**.
- Similarly, we only care about  $Q(\cdot)$  up to a constant.
- Often it is advantageous to calculate the acceptance probability on **log-scale**, which makes the computations more stable.

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## Special cases of the Metropolis-Hastings algorithm

Depending on the choice of  $Q(x|x_{i-1})$  different special cases result.

In particular, two classes are important

- **The independence proposal**
- **The Metropolis algorithm**
  - ▶ Random walk proposals

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Special cases

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## Independence proposal

- The proposal distribution does not depend on the current value  $x_{i-1}$

$$Q(x|x_{i-1}) = Q(x).$$

- $Q(x)$  is an approximation to  $\pi(x)$   
⇒ **Acceptance rate should be close to 1.**
- **The sampler is closer to rejection sampler.** However, here if we reject, then we retain the sample.

Experience:

- Performance is either very good or very bad, usually very bad.
- The tails of the proposal distribution should be at least as heavy as the tails of the target distribution.

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Special cases

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## The Metropolis algorithm

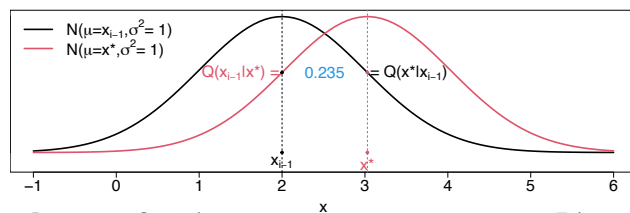
The proposal density is symmetric around the current value, that means

$$Q(x_{i-1}|y) = Q(y|x_{i-1}).$$

Hence,

$$\alpha = \min \left( 1, \frac{\pi(y)}{\pi(x_{i-1})} \times \frac{Q(x_{i-1}|y)}{Q(y|x_{i-1})} \right) = \min \left( 1, \frac{\pi(y)}{\pi(x_{i-1})} \right)$$

A particular case is the **random walk proposal**, defined as the current value  $x_{i-1}$  plus a random variate of a 0-centred symmetric distribution.



## Examples for random walks proposal

Assume  $x$  is scalar.

Then all proposal kernels, which **add a random variable generated from a zero-symmetrical distribution to the current value  $x_{i-1}$** , are random walk proposals. For example:

$$y \sim \mathcal{N}(x_{i-1}, \sigma^2)$$

$$y \sim t_\nu(x_{i-1}, \sigma^2)$$

$$y \sim \mathcal{U}(x_{i-1} - d, x_{i-1} + d)$$

See R-code `demo_mcmcRW_2D.R`.

## Efficiency of the Metropolis-Hastings algorithm

The efficiency and performance of the Metropolis-Hastings algorithm depends crucially on the **relative frequency of acceptance**.

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- Too large acceptance rate  $\Rightarrow$  slow target density exploration
- Too small acceptance rate  $\Rightarrow$  large moves proposed, but rarely accepted

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Tuning the acceptance rate:

- For **random walk proposals**, acceptance rates between **20% and 50%** are typically recommended. They can be achieved by changing the variance of the proposal distribution.
- For **independence proposals** a **high acceptance rate** is desired, which means the proposal density is close to the target density.

## Example: Random walk proposal

Exploration of a standard Gaussian distribution ( $\mathcal{N}(0, 1)$ ) using a random walk Metropolis algorithm. As proposal assume a Gaussian distribution with variance  $\sigma^2$ , where.

- $\sigma = 0.24$
- $\sigma = 2.4$
- $\sigma = 24$

See R-code `demo_mcmcRW.R`.

## Example of Rao (1973)

The vector  $\mathbf{y} = (y_1, y_2, y_3, y_4) = (125, 18, 20, 34)$  is multinomial distributed with probabilities

$$\left\{ \frac{1}{2} + \frac{\theta}{4}, \frac{1-\theta}{4}, \frac{1-\theta}{4}, \frac{\theta}{4} \right\}$$

We would like to simulate from the posterior distribution (assuming a uniform prior)

$$f(\theta|\mathbf{y}) \propto (2 + \theta)^{y_1} (1 - \theta)^{y_2 + y_3} \theta^{y_4}.$$

using MCMC and **compare two proposal kernels**:

1. **independence proposal**
2. **random walk proposal**

See R-code `demo_mcmcRao.R`.

## Rao: Independence proposal

$$\theta^* \sim \mathcal{N}(\text{Mod}(\theta|\mathbf{y}), F^2 \times I_p^{-1}), \quad (5)$$

where  $\text{Mod}(\theta|\text{data})$  denotes the posterior mode,  $I_p$  the negative curvature of the log posterior at the mode, and  $F$  a factor to blow up the standard deviation.

## Rao: Random walk proposal

$$\theta^* \sim U(\theta^{(k)} - d, \theta^{(k)} + d),$$

where  $\theta^{(k)}$  denotes the current state of the Markov chain and  $d = \sqrt{12}/2 \cdot 0.1$ .

## Numerical Note

How to compute

$$\alpha(y|x) = \min \left\{ 1, \frac{\pi(y) Q(x|y)}{\pi(x) Q(y|x)} \right\}$$

Naive strategy: Compute  $\pi(y)$ ,  $\pi(x)$ ,  $Q(y|x)$ ,  $Q(x|y)$ . Then compute the ratio.

## Comments on the Metropolis-Hasting algorithm

- A trivial special case results when

$$Q(x^*|x_{i-1}) = \pi(x^*),$$

That means, we propose realisations from the target distribution. Then  $\alpha = 1$  and all proposals are accepted.

- The advantage of the MH-algorithm is that **arbitrary proposal kernels** can be used. The algorithm will always converge to the target distribution.
- However, the **speed of convergence** and the **dependence between the successive samples** depends strongly on the proposal distribution.

## Numerical Note

How to compute

$$\alpha(y|x) = \min \left\{ 1, \frac{\pi(y) Q(x|y)}{\pi(x) Q(y|x)} \right\}$$

Naive strategy: Compute  $\pi(y)$ ,  $\pi(x)$ ,  $Q(y|x)$ ,  $Q(x|y)$ . Then compute the ratio.

Solution:

- Simplify the expression as much as possible
- Compute everything in log-scale

## MCMC and iterative conditioning

MH-algorithms are sometimes applied iteratively on components of  $\mathbf{x}$ .

Let  $\mathbf{x}$  be decomposed by several (for simplicity scalar) components.

$$\mathbf{x} = (x^1, \dots, x^p)$$

Now the MH-algorithm is applied iteratively on the components  $x^j$ , conditioning on the current values of  $\mathbf{x}^{-j}$  with

$$\mathbf{x}^{-j} = (x^1, \dots, x^{j-1}, x^{j+1}, \dots, x^p)$$

## MCMC and iterative conditioning

To be concrete, one uses

- a proposal kernel  $Q(y^j | x_{i-1}^j, \mathbf{x}_{i-1}^{-j})$ ,  $j = 1, \dots, p$ .
- with acceptance probability

$$\alpha = \min \left( 1, \frac{\pi(y^j | \mathbf{x}_{i-1}^{-j})}{\pi(x_{i-1}^j | \mathbf{x}_{i-1}^{-j})} \times \frac{Q(x_{i-1}^j | y^j, \mathbf{x}_{i-1}^{-j})}{Q(y^j | x_{i-1}^j, \mathbf{x}_{i-1}^{-j})} \right)$$

This algorithm **converges to the stationary distribution with density  $\pi(\mathbf{x})$** , as long as all components are updated arbitrarily often.

## Iterative conditioning: Conditional densities

In this case, the acceptance probability  $\alpha$  only uses the **full conditional densities**  $\pi(x^j | \mathbf{x}^{-j})$ ,  $j = 1, \dots, p$ , and not the joint density  $\pi(\mathbf{x})$ .

Both are related as follows

$$\pi(x^j | \mathbf{x}^{-j}) = \frac{\pi(\mathbf{x})}{\pi(\mathbf{x}^{-j})} \propto \pi(\mathbf{x})$$

Thus, the (non-normalised) conditional densities of  $x^j | \mathbf{x}^{-j}$  can be directly derived from  $\pi(\mathbf{x})$  by **omitting all multiplicative factors, that do not depend on  $x^j$** .

## Gibbs sampling

It seems natural to use the conditional densities as proposal kernels, i.e.

$$Q(y^j | x_{i-1}^j, \mathbf{x}_{i-1}^{-j}) = \pi(x^j | \mathbf{x}_{i-1}^{-j}).$$

In this case, we get  $\alpha = 1$ , which leads to the well known **Gibbs sampler**. Gibbs sampling updates parameters iteratively by sampling from the corresponding full conditional distributions.



## Gibbs sampling

Let  $\mathbf{x} = (x^1, \dots, x^p)$ ,  $\mathbf{x} \sim \pi(\mathbf{x})$ ,  $p$  proposal distributions are defined by:

- propose  $y^j \sim \pi(y^j | \mathbf{x}^{-j})$
- keep  $y^k = x^k$  for  $k \neq j$

Notation:

- $\mathbf{x} = (x^1, \dots, x^p)$
- $\mathbf{x}^{-j} = (x^1, \dots, x^{j-1}, x^{j+1}, \dots, x^p)$
- $\mathbf{y} = (y^1, \dots, y^p) = (x^1, \dots, x^{j-1}, y^j, x^{j+1}, \dots, x^p)$

What is the acceptance probability for the Gibbs sampling?

## Gibbs-Sampling algorithm

Idea: **Sequentially sample** from univariate conditional distributions

1. Select starting values  $\mathbf{x}_0$  and set  $i = 0$ .
2. Repeatedly:

Sample  $x_{i+1}^1 | \cdot \sim \pi(x^1 | x_i^2, \dots, x_i^p)$

Sample  $x_{i+1}^2 | \cdot \sim \pi(x^2 | x_{i+1}^1, x_i^3, \dots, x_i^p)$

$\vdots$

Sample  $x_{i+1}^{p-1} | \cdot \sim \pi(x^{p-1} | x_{i+1}^1, x_{i+1}^2, \dots, x_{i+1}^{p-2}, x_i^p)$

Sample  $x_{i+1}^p | \cdot \sim \pi(x^p | x_{i+1}^1, \dots, x_{i+1}^{p-1})$

where  $|\cdot$  denotes conditioning on the most recent updates of all other elements of  $\mathbf{x}$ .

3. Increment  $i$  and go to step 2.