# R-INLA: An R-package for INLA

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<sup>&</sup>lt;sup>1</sup>Slides are based on lecture notes kindly provided by Andrea Riebler. ■ ▶

### Getting R-INLA

► The web page www.r-inla.org contains source-code, worked-through examples, reports and instructions for installing the package.

## Getting R-INLA

- ► The web page www.r-inla.org contains source-code, worked-through examples, reports and instructions for installing the package.
- ► The R-package R-INLA works on Linux, Windows and Mac and can be installed by

#### Later, it can be upgraded with

```
1 update.packages("INLA", dep=TRUE)
```

### Data organization

The responses and covariates are collected in a list or data frame. Assume response y, covariates x1 and x2, and time index t. Then they can be organized with

```
# Option 1
data = list(y = y, x1 = x1, x2 = x2, t = t)

# Option 2
data = data.frame(y = y, x1 = x1, x2 = x2, t = t)
```

# formula: specifying the linear predictor

The model is specified through formula similar to glm:

formula = 
$$y \sim x1 + x2 + f(t, ...)$$

- y is the name of the response in the data
- ▶ The fixed effects are given i.i.d. Gaussian priors
- ► The f function specifies random effects (e.g. temporal, spatial, smooth effect of covariates and Besag model)
- ▶ Use -1 if you don't want an automatic intercept

#### The inla function

```
result = inla(
 2
         # Description of linear predictor
         formula.
4
5
6
7
8
         # Likelihood
         family = "gaussian",
         # List or data frame with response, covariates, etc.
         data = data.
         ## This is all that is needed for a basic call
10
         # check what happens
11
         verbose = TRUE,
12
         # keep working files
13
         keep = TRUE,
14
15
         # there are also some "control statements"
16
         # to customize things
17
```

#### Likelihood functions

- ▶ "gaussian"
- ▶ "poisson"
- "nbinomial"
- "binomial"
- ► To see the list of available likelihood models

```
names(inla.models()$likelihood)
```

# Example: Simple linear regression

$$y_i = \underbrace{\beta_0 + \beta_1 x_i}_{\eta_i} + \epsilon_i \text{ with } \epsilon_i \sim \mathcal{N}(0, \sigma_0^2)$$

Stage 1: Gaussian likelihood

$$y_i \mid \eta_i \sim \mathcal{N}(\eta_i, \sigma_o^2)$$

Stage 2: Covariates are connected to likelihood by

$$\eta_i = \beta_0 + \beta_1 x_i$$

Stage 3:  $\sigma_0^2$ : variance of observation noise

# Example: Simple linear regression

```
> library(INLA)
> # Generate data
> x = sort(runif(100))
> y = 1 + 2*x + rnorm(n = 100, sd = 0.1)
> # Run inla
> formula = y ~ 1 + x
> result = inla(formula,
+ data = list(x = x, y = y),
family = "gaussian")
```

#### Get summary

```
> summary(result)
Call:
  c("inla(formula = formula, family = \"gaussian\", data = list(x = x, ",
  Time used:
   Pre = 1.05, Running = 0.12, Post = 0.0666, Total = 1.24
Fixed effects:
                  sd 0.025quant 0.5quant 0.975quant mode kld
(Intercept) 1.01 0.020 0.970 1.01 1.050 1.01 0
x
          1.97 0.037 1.898 1.97 2.043 1.97 0
Model hyperparameters:
                                              sd 0.025quant 0.5quant
                                       mean
Precision for the Gaussian observations 107.19 15.16
                                                     79.54 106.47
                                     0.975quant
                                                 mode
Precision for the Gaussian observations
                                        138.91 105.04
Expected number of effective parameters(stdev): 2.06(0.009)
Number of equivalent replicates: 48.44
Marginal log-Likelihood: 75.05
```

#### Fixed Effects

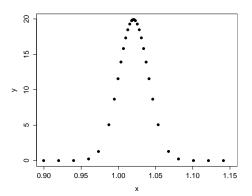
#### > result\$summary.fixed

```
mean sd 0.025quant 0.5quant 0.975quant mode (Intercept) 1.009816 0.02030048 0.9698763 1.009815 1.049722 1.009816 x 1.970149 0.03691115 1.8975289 1.970148 2.042708 1.970149 kld (Intercept) 4.072744e-06 x 4.072741e-06
```

## Marginal posterior densities

The marginal posterior densities are stored as a matrix with x- and y-values

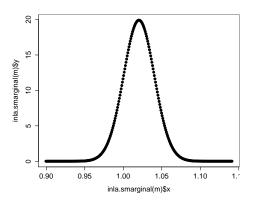
```
m = result$marginals.fixed[[1]]
plot(m)
```



# Marginal posterior densities

#### The rough shape can be interpolated to higher resolution

```
plot(inla.smarginal(m))
```



## Marginal posterior densities

```
# Extract quantiles
2
3
4
5
6
7
8
9
     > inla.qmarginal(0.05, m)
     [1] 0.9818604
     # Distribution function
     > inla.pmarginal(0.975, m)
     [1] 0.02314047
     # Density function
10
     > inla.dmarginal(1, m)
11
     [1] 15.80794
12
13
     # Generate realizations
14
     > inla.rmarginal(4, m)
15
     [1] 1.009122 1.013116 1.032004 1.007458
```

# Organisation of the returned inla-object

```
> names(result)
2
      [1] "names.fixed"
                                          "summary.fixed"
                                          "summary.lincomb"
      [3] "marginals.fixed"
      [5] "marginals.lincomb"
                                          "size.lincomb"
      [7] "summary.lincomb.derived"
                                          "marginals.lincomb.
          derived"
      [9] "size.lincomb.derived"
                                          "mlik"
     [11] "cpo"
                                          "po"
     [13] "waic"
                                          "model.random"
     [15] "summary.random"
                                          "marginals.random"
10
     [17] "size.random"
                                          "summary.linear.
         predictor"
11
     [19] "marginals.linear.predictor"
                                          "summary.fitted.values"
12
                                          "size.linear.predictor"
     [21] "marginals.fitted.values"
13
                                          "marginals.hyperpar"
     [23] "summary.hyperpar"
14
     . . .
```

#### Add random effects

```
f(name, model="...", hyper=...,
constr=FALSE, cyclic=FALSE, ...)
```

- name the index of the effect (each f-function needs its own!)
- model the type of latent model. E.g. "iid", "rw2", "ar1", "besag", and so on
- hyper specify the prior on the hyperparameters
- constr sum-to-zero constraint?
- cyclic is it cyclic?

# Example: Add random effect

Add an AR(1) random effect to the linear predictor.

Stage 1:

$$y_i | \eta_i \sim \mathcal{N}(\eta_i, \sigma_{\text{o}}^2)$$

Stage 2: Covariates and AR(1) component connected to likelihood by:

$$\eta_i = \beta_0 + \beta_1 x_i + a_i.$$

x<sub>i</sub>: covariate

 $ightharpoonup a_i$ : AR(1) process

Stage 3:  $ightharpoonup \sigma_o^2$ : variance of observation noise

 $\triangleright$   $\rho$ : dependence in AR(1) process

 $ightharpoonup \sigma^2$ : variance of the innovations in AR(1) process

### Example: Add random effect

```
# Generate AR(1) sequence
2
3
4
5
6
7
8
     t = 1:100
     ar = rep(0,100)
     for(i in 2:100)
         ar[i] = 0.8*ar[i-1]+rnorm(n = 1, sd = 0.1)
     # Generate data with AR(1) component
     x = runif(100)
9
     y = 1 + 2*x + ar + rnorm(n = 100, sd = 0.1)
10
11
     # Run inla
12
     formula = y \sim 1 + x + f(t, model="ar1")
13
     result = inla(formula.
14
                    data = list(x = x, y = y, t = t),
15
                    family = "gaussian")
16
17
     # Get summary
18
     summary(result)
```

# summary(result)

#### Fixed effects:

|             | mean   | sd     | 0.025quant | 0.5quant | 0.975quant | mode   | kld |
|-------------|--------|--------|------------|----------|------------|--------|-----|
| (Intercept) | 1.0354 | 0.0624 | 0.913      | 1.0344   | 1.1635     | 1.0328 | 0   |
| x           | 2.0173 | 0.0459 | 1.927      | 2.0173   | 2.1077     | 2.0173 | 0   |

#### Random effects:

Name Model

t AR1 model

#### Model hyperparameters:

|               |     |                  |              | mean     | sd      | 0.025quant | 0.5quant |
|---------------|-----|------------------|--------------|----------|---------|------------|----------|
| Precision for | the | Gaussian         | observations | 129.8753 | 49.6529 | 60.8214    | 120.5645 |
| Precision for | t   |                  |              | 38.3033  | 13.9965 | 16.8866    | 36.4192  |
| Rho for t     |     |                  |              | 0.8031   | 0.0817  | 0.6028     | 0.8181   |
|               |     | 0.975quant mode  |              |          |         |            |          |
| Precision for | the | ${\tt Gaussian}$ | observations | 251.9389 | 104.190 | )4         |          |
| Precision for | t   |                  |              | 70.9695  | 32.709  | 97         |          |
| Rho for t     |     |                  |              | 0.9185   | 0.846   | 33         |          |

#### Other choices for f-terms

#### For example:

- ▶ rw1, rw2
- besag
- ▶ iid

For a complete list see: names(inla.models()\$latent)

# Changing the prior: Internal scale

▶ Hyperparameters are represented internally with more well-behaved transformations, e.g. precision  $\tau$  and correlation  $\rho$  are internally represented as

$$heta_1 = \log( au)$$
  $heta_2 = \log\left(rac{1+
ho}{1-
ho}
ight)$ 

▶ The prior must be set on the parameter in internal scale

# Changing the prior: Code

```
hyper = list(prec = list(prior = "loggamma",
param = c(1, 0.1))

formula = y ~ f(idx, model = "iid", hyper = hyper) + ...
```

## EPIL example

Seizure counts in a randomised trial of anti-convulsant therapy in epilepsy. From WinBUGS manual.

| Patient | y1 | y2 | y3 | y4 | Trt | Base | Age |
|---------|----|----|----|----|-----|------|-----|
| 1       | 5  | 3  | 3  | 3  | 0   | 11   | 31  |
| 2       | 3  | 5  | 3  | 3  | 0   | 11   | 30  |
| 3       | 2  | 4  | 0  | 5  | 0   | 6    | 25  |
|         |    |    |    |    |     |      |     |
| 59      | 1  | 4  | 3  | 2  | 1   | 12   | 37  |

Covariates are treatment (0,1), 8-week baseline seizure counts, and age in years.

## Repeated Poisson counts

$$\begin{array}{lll} y_{jk} & \sim & \mathsf{Poisson}(\mu_{jk}); \ j=1,\ldots,59; \ k=1,\ldots,4 \\ \\ \mathsf{log}(\mu_{jk}) & = & \alpha_0 + \alpha_1 \, \mathsf{log}(\mathsf{Base}_j/4) + \alpha_2 \mathsf{Trt}_j \\ & + \alpha_3 \mathsf{Trt}_j \, \mathsf{log}(\mathsf{Base}_j/4) + \alpha_4 \, \mathsf{log}(\mathsf{Age}_j) \\ & + \alpha_5 \, V4 + \mathsf{Ind}_j + \beta_{jk} \\ \\ & \alpha_i & \sim & \mathcal{N}(0,\tau_\alpha) & \tau_\alpha \, \mathsf{known} \, (0.001) \\ & \mathsf{Ind}_j & \sim & \mathcal{N}(0,\tau_{\mathsf{Ind}}) & \tau_{\mathsf{Ind}} \sim \mathsf{Gamma}(1,0.01) \\ & \beta_{jk} & \sim & \mathcal{N}(0,\tau_\beta) & \tau_\beta \sim \mathsf{Gamma}(1,0.01) \end{array}$$

Here, V4 is an indicator variable for the 4th visit.

### Prepare the dataset

```
> library(tidyverse)
> data(Epil)
> head(Epil, n = 2)
 y Trt Base Age V4 rand Ind
15 0 11 31 0 1 1
2 3 0 11 31 0 2 1
> my.center = function(x) (x - mean(x))
> Epil = Epil %>% mutate(
     CTrt
            = my.center(Trt),
     ClBase4 = my.center(log(Base/4)),
     CV4 = my.center(V4),
     ClAge = my.center(log(Age)))
> Epil %>% round(2) %>% head(n=2)
 y Trt Base Age V4 rand Ind CTrt ClBase4 CV4 ClAge
1.5
     0 11 31 0
                    1 1 -0.53 -0.76 -0.25 0.11
2 3
     0 11 31 0 2 1 -0.53 -0.76 -0.25 0.11
```

# Model specification in INLA

```
1234567
     > data(Epil)
     > head(Epil,n=3)
        y Trt Base Age V4 rand Ind
                                             CTrt
                                                       ClBase4
                                                                 CV4
                                                                              ClAge
                                    1 -0.5254237
                                                   -0.75635379 -0.25
                                                                        0.11420370
    2 3 0 11 31 0 2 1 -0.5254237 -0.75635379 -0.25
3 3 0 11 31 0 3 1 -0.5254237 -0.75635379 -0.25
                                                                       0.11420370
                                                                       0.11420370
        3 0 11 31 1 4
                                                                        0.11420370
                                    1 -0.5254237 -0.75635379
                                                                0.75
```

# Model specification in INLA

## Model specification in INLA

```
> result = inla(formula, family="poisson", data = Epil,

control.fixed = list(prec.intercept = 0.001,

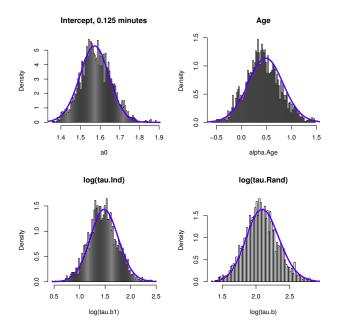
prec = 0.001))
```

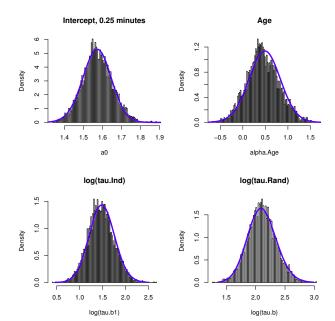
## Comparing results with MCMC

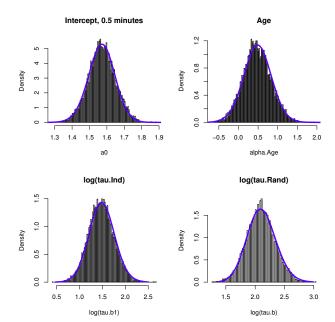
▶ When comparing the results of R-INLA with MCMC, it is important to use the same model. That means, same data, same priors, same constraints on parameters, intercept included or not, . . . .

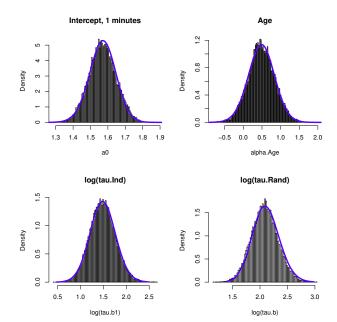
# Comparing results with MCMC

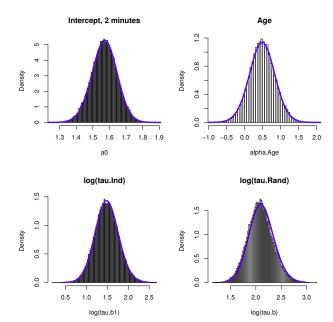
- ▶ When comparing the results of R-INLA with MCMC, it is important to use the same model. That means, same data, same priors, same constraints on parameters, intercept included or not, . . . .
- ► Here we have compared the results with those obtained using JAGS via the rjags package

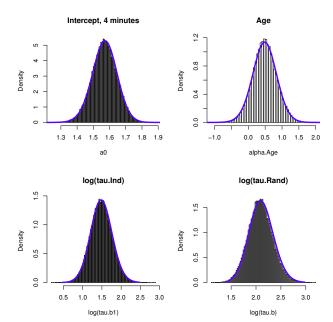


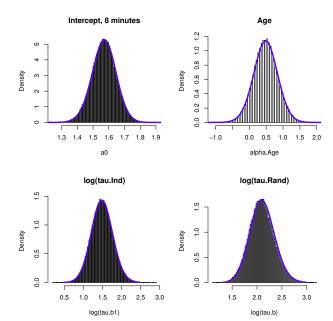


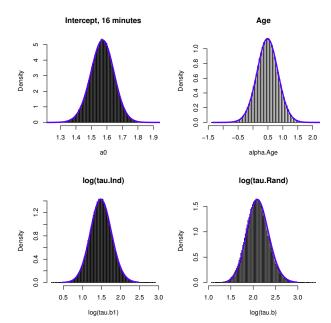


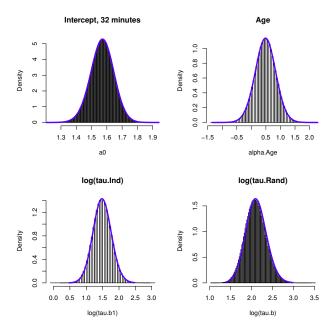


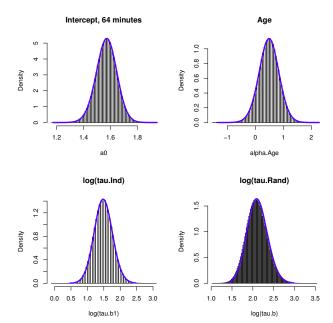


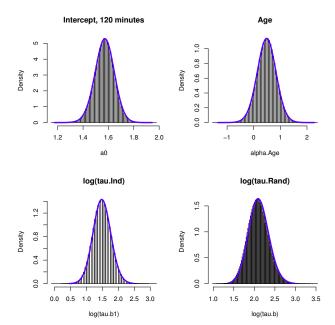












control.xxx statements control computations

▶ control.fixed

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  - prec: Default precision for all fixed effects except the intercept. prec.intercept: Precision for intercept (Default: 0.0)

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  - dic: Compute measures of fit, here DIC, to do model comparison?
- ▶ There are various others as well; see help.

## Model choice

There is a need to compare and choose between various models, i.e. with covariates versus without, smoothed effects versus linear, etc.

One option to this in R-INLA is the deviance information criterion (DIC):

```
result = inla(formula,

data = data,

control.compute=list(dic=TRUE))

# See result
result$dic$dic
```

# Deviance information criterion

DIC is a measure of complexity and fit. It is used to compare complex hierarchical models and is defined as:

$$DIC = \overline{D} + p_D$$

where  $\overline{D}$  is the posterior mean of the deviance (measures model fit) and  $p_D$  is the effective number of parameters (measures model complexity).

 $\Rightarrow$  Smaller values of the DIC indicate a better trade-off between complexity and fit of the model to the data.

The DIC is based on the deviance

$$D(\boldsymbol{\theta}, \boldsymbol{x}; \boldsymbol{y}) = -2\log(\pi(\boldsymbol{y}|\boldsymbol{\theta}, \boldsymbol{x}))$$

through

$$DIC = E_{\boldsymbol{\theta}, \mathbf{x}|\mathbf{y}}[D(\boldsymbol{\theta}, \mathbf{x}; \mathbf{y})] + D(\boldsymbol{\theta}^*, E_{\mathbf{x}|\mathbf{y}}[\mathbf{x}]; \mathbf{y}),$$

where  $\theta^*$  is the mode of  $\pi(\theta|\mathbf{y})$ .



## Useful features

There are several features that can be used to extend the standard models in R-INLA.

However, we do not have time to cover those in this course.