

1/10-23 Ex 4

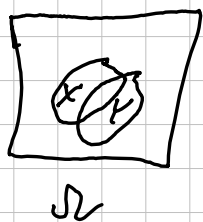
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① The definition: $EX = \sum_i x_i P(A_i)$
 where $A_i = (X = x_i)$. This gives
 more generally (since P is finitely additive)

$$E\left(\sum_i x_i A_i\right) = \sum_i x_i P(A_i) \quad (1)$$

as long as $A_i \cap A_j = \emptyset$ $i \neq j$
 and $\Omega = A_1 \cup \dots \cup A_n$

a) (i) $E(\alpha X + \beta Y) = \alpha P(XY^c) + (\alpha + \beta)P(XY) + \beta P(X^cY) + 0 \cdot P(X^cY^c)$



4 sets

A_1, \dots, A_n

$$\alpha EX = \alpha \cdot [P(XY) + P(XY^c)]$$

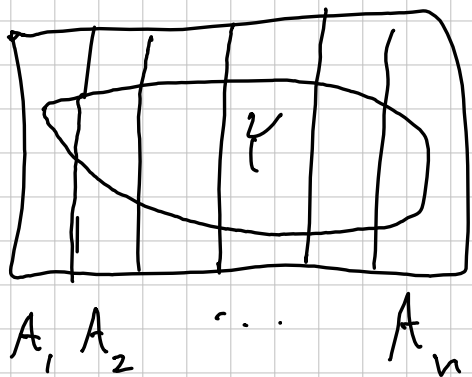
$$\beta EY = \beta [P(YX) + P(YX^c)]$$

$$\Rightarrow E(\alpha X + \beta Y) = \alpha EX + \beta EY$$

ii) $E(\alpha X + \beta Y) = \sum_i (\alpha x_i P(A_i Y) + (\alpha x_i + \beta) P(A_i Y^c))$

$$\alpha EX = \sum_i \alpha x_i P(A_i), \beta EY = \beta P(Y), A_i = A_i Y + A_i Y^c$$

ii) $Y = \sum_i (YA_i + YA_i^c)$ and insertion gives $E(\alpha X + \beta Y) = \alpha EX + \beta EY$



$2n$ pieces.

iii) Let X take n values and Y take m values, so Ω is divided in $n \times m$ pieces (some may be $= \emptyset$). The value of $\alpha X + \beta Y$ is $\alpha x_i + \beta y_j$ on $A_{ij} = (X=x_i) \cap (Y=y_j)$.

The value of αX is αx_i on A_{ij} . Value of βY is βy_j on A_{ij} .

$$E(\alpha X + \beta Y) = \sum_{i,j} (\alpha x_i + \beta y_j) P(A_{ij})$$

$$= \alpha \sum_{i,j} x_i P(A_{ij}) + \beta \sum_{i,j} y_j P(A_{ij})$$

$$= \alpha EX + \beta EY$$

$$(1) \hookrightarrow E \varphi(W) = \sum_i \varphi_i \cdot P(W=w_i)$$

with $\varphi_i = \varphi(w_i)$.

$$E_w \varphi = \sum_i \varphi_i P_w(\{w_i\})$$

$$\text{so } E \varphi(W) = E_w \varphi.$$

Note: Eq. 1 is used in both cases: Some of the φ_i values may be equal. In the first case it is used on Ω . In the second case it is used on Ω_w .

laeL short $E T = \sum t f(t) = \sum t(x) f(x)$
 since $f(t) = \sum_{t(x)=t} f(x)$ from additivity of P .
 $E(\alpha X + \beta Y) = \sum_{t(x)=t} (\alpha x + \beta y) f(x, y) = \alpha E X + \beta E Y$.
 $E \varphi(W) = E_w \varphi$ since $P_{\varphi(W)}(A) = (P_w \varphi)(A)$.

$$\begin{aligned}
 \textcircled{1} \hookrightarrow \text{Let } W = (X, Y), \text{ so} \\
 E(\alpha X + \beta Y) &= E \varphi(W) \\
 &= E \varphi = \sum_W \varphi(W) P_W \{W\} \\
 &= \alpha \sum_W X P_W \{W\} + \beta \sum_W Y P_W \{W\} \\
 &= \alpha EX + \beta EY
 \end{aligned}$$

using the change-of-variables theorem again on $(X, Y) \mapsto X$ and $(X, Y) \mapsto Y$. Easier proof by first proving

$$E \varphi(W) = \sum_W f(W) \varphi(W)$$

directly:

$$E \varphi(W) = \sum_y y P(\varphi(W) = y) = \text{etc.}$$

a) a) $\in \mathbb{I}$ with induction

①

$$C_n : E\left(\sum_{i=1}^n \alpha_i A_i\right) = \sum_{i=1}^n \alpha_i E A_i$$

$$n=1 : E \alpha A = \sum \alpha a_i E A_i = \alpha E A$$

$$n=k+1 : E\left(\sum_{i=1}^k \alpha_i A_i + \alpha_{k+1} A_{k+1}\right)$$

$$\stackrel{(ii)}{=} E\left(\sum_{i=1}^k \alpha_i A_i\right) + \alpha_{k+1} E A_{k+1}$$

$$\stackrel{C_k}{=} \sum_{i=1}^{k+1} \alpha_i E A_i$$

so C_n is true for $n=1, 2, 3, \dots$

$$iii) : E(\alpha X + \beta Y)$$

$$= E\left(\sum \alpha x_i X_i + \sum \beta y_j Y_j\right)$$

$$= \sum \alpha x_i E X_i + \sum \beta y_j E Y_j$$

$$= \alpha E X + \beta E Y$$

⑦ c)

$$\begin{array}{ccc}
 \mathcal{L} & \xrightarrow{T} & \mathcal{L}_T \\
 x \mapsto \mathcal{L}_x & \nearrow t(-) &
 \end{array}$$

$$(X=x) \subset (T=t) //$$

when $t(x) = t$. It is assumed that $D(X) = D(T)$. The inclusion of level sets is equivalent with $T = t(X)$, so equality of level sets means that $t(-)$ is a one-one transformation between $R(X)$ and $R(T)$.

The factorization theorem proves that \mathcal{L} is minimal, and hence its level sets equals the level sets of any minimal suff. stat. //

① c) Suff. principle: If $t(x) = t(\tilde{x})$ then same inference for x and \tilde{x} . (This must hold for any sufficient statistic $T = t(X)$). It is hence ensured if it holds for a single minimal sufficient statistic.)

Suff. principle:
same inference if $x \sim \tilde{x}$

The level sets of $t(\cdot)$ defines a partition $\{A_t\}_{t \in R(T)}$ by $A_t = \{x \mid t(x) = t\}$.

of $R(X)$. This defines an equivalence relation (any partition does)

$$x \sim \tilde{x} \Leftrightarrow t(x) = t(\tilde{x})$$

i) Reflexive.

ii) Symmetric

Transitive

iii) $x \sim y, y \sim z \Rightarrow x \sim z$

$$A_{20} = \{d \mid |d| < R_{20}\} //$$

$$(2) \quad a) \quad A_s = \{d \mid R_{s+1} \leq |d| < R_s\} \quad 0 \leq s \leq 9$$

$$0 < R_{20} < R_9 < \dots < R_1 < R_0 = \infty //$$

$$R_{10} = R_{20} \quad s \in R(S) = \{0, 1, \dots, 9, 20\} //$$

b) Let $I \subset R(S)$ and define

$$A_I = \bigcup_{s \in I} A_s. \quad \text{The family}$$

$$\mathcal{E}_D = \{A_I \mid I \subset R(S)\} //$$

has 2^n elements since $2^n = |2^{R(S)}| = \text{number of subsets of } R(S)$
 $= \text{number of binary sequences of length } n.$

$$P_D(A_I) = \sum_{s \in I} P_D(A_s) //$$

b) Check of axioms for \mathcal{E}_D :

(2) i) $\emptyset \in \mathcal{E}_D$ since $A_{\emptyset} = \emptyset //$

ii) $(A_{\underline{I}})^c = A_{\underline{I}^c} //$

iii) $A_{\underline{I}_1} \cup A_{\underline{I}_2} \cup \dots = A_{\underline{I}_1 \cup \dots} //$

Check of axioms for \mathcal{P}_D :

(i) $\mathcal{P}_D(A_{\underline{I}}) = \sum_{s \in \underline{I}} \mathcal{P}_D(A_s) \geq 0 //$

(ii) $\mathcal{P}_D(\Omega_D) = \mathcal{P}_D(A_{R(s)})$
 $= \sum_{s \in R(s)} \mathcal{P}_D(A_s) = 1 //$

(iii) $A_{\underline{I}_1}, A_{\underline{I}_2}, \dots$ disjoint

$\mathcal{P}_D(\cup A_{\underline{I}_i}) = \sum_i \mathcal{P}_D(A_{\underline{I}_i}) //$

b) Alternative and better:

$$(2) \quad (D \in A_s) = \{\omega \mid D(\omega) \in A_s\}$$

is by assumption an event for all s . This gives that

$$(D \in A_I) = \bigcup_{s \in I} (D \in A_s) \text{ is}$$

always an event. It follows then that P_D defined by $P_D(A) = P(D \in A)$ is a probability since P is.

Ω_D equipped with \mathcal{E}_D is a sample space.

Ω_D with P_D is a probability space.

$\{(0,0)\} \subset \Omega_D$, but is not an event

b) since $\{(0,0)\} \notin \mathcal{E}_D$.

② More generally: Any set $A \subset \Omega_D$ with $A \notin \mathcal{E}_D$ is not an event. In particular any proper non-empty σ -alg \mathcal{A}_D .
Many subsets of Ω_D are not events.

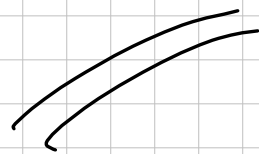
Note: This is the most common situation. An event is a set, but a set need not be an event.

c) $\Theta = (p_0, \dots, p_9, p_{20})$
 $\in \Omega_\Theta \approx \mathbb{R}^n$.

$$R(\Theta) = \{\Theta \mid 0 \leq \theta_s \leq 1, \sum_s \theta_s = 1\}$$

$$(2) \quad d) \quad s(a) = \sum_{s \in R(S)} s \cdot A_s(a) \quad \text{so}$$

s is a function of the data
 $\equiv A$ statistic.



Level set

$$A_s = \{d \mid \varphi(d) = s\}$$



from $\varphi(d) = \sum_{s \in R(S)} s A_s(d)$

$$\begin{aligned} S &= \varphi(D) \\ &= s(D) \end{aligned} \quad \begin{aligned} &\dot{=} \\ &\} \theta_s = p_s \end{aligned}$$

$$\mu = ES = \sum s f(s) = \sum s \theta_s$$

is a function of $\theta = A$ parameter

$= E_D \varphi //$ by Change-of-Var.



d) Law of large numbers

(2)

$$E(S) = \lim_{n \rightarrow \infty} \frac{S_1 + \dots + S_n}{n}$$

if $S_i \sim S$ and independent.

Interpretation: If the ^{dart} Vexp. is repeated many times, then the empirical average \bar{S} tends to $E(S)$.

It must be assumed that $E|S| < \infty$, but this is fine here since $|S| \leq 20$.

$$P(S \in A) = \lim_{n \rightarrow \infty} \frac{(S_1 \in A) + \dots + (S_n \in A)}{n}$$

so relative frequency \rightarrow probability.

② $\Omega_\theta = \mathbb{R}^n$ still.

$$\begin{aligned}\Omega_D &= \{d \mid d_i \in \mathbb{R}^2, i=1, \dots, n\} \\ &= \mathbb{R}^{2n}.\end{aligned}$$

$\{d\} \notin \mathcal{E}_D$ so $\{d\}$ is
not an event.

The previous partition in l
events gives now a partition
into l^n events. The number
of events in \mathcal{E}_D is hence

$$|\mathcal{E}_D| = 2^{(l^n)}$$

Experiment = n throws with a dart.

(2) $M_s = \sum_{i=1}^n A_s(D_i)$ is a random variable since it is a sum of random variables
= # darts hitting A_s
 $\sim B(n, p_s)$

$M \sim \text{Multinomial}(n, \theta)$

it is minimal and complete, and the distribution is from an exponential family.

Argument: Consider $n=1$ first.
The distribution of D_1 is in one-one correspondence with the distribution of $[A_0(D_1), \dots, A_{20}(D_1)]$.
Similarly for D and $[A_0(D), \dots, A_{20}(D)]$.

② f) The likelihood for the statistic is

$$L = \prod_{i=1}^n p_0^{x_0(i)} \cdots p_{20}^{x_{20}(i)}$$

where $x_s(i) = A_s(d_i)$
= indicator for dart i
hitting A_s .

$$L = e^{m_0 \ln p_0 + \cdots + m_{20} \ln p_{20}}$$

is an exp. family. Note
restriction $m_0 + \cdots + m_{20} = n$
and $p_0 + \cdots + p_{20} = 1$.

This proves minimal completeness
(Can change coordinates to
10 dimensional to get stat. form.)

② ^{g)} $\hat{\Theta} = \frac{m}{n}$ (Elimination of p_{20} or Lagrange multiplier for $\hat{\Theta} = \arg \min L$ with $\sum_s \theta_s = 1$.)

$$\mu = \sum_s s p_s, \quad \hat{\mu} = \sum_s s \hat{\theta}_s$$

Yes, unbiased since

$$E A_s(D_i) = p_s$$

$$\text{and } E \hat{\mu}(D) = \sum_s s E \hat{\theta}_s(D) = \sum_s s \theta_s = \mu$$

h) The set Ω is unchanged, but the sample space Ω_D is different $= \mathbb{R}^{2n}$. In with $\mathcal{E}_D = \text{Borel}$

② h) ω -algebra = smallest family of events containing all $(-\infty, a]$, $a \in \mathbb{R}^{2n}$.

$$L = \prod_{i=1}^n \left[\frac{1}{\sqrt{2\pi}} \omega \right]^2 \cdot e^{-\frac{x_i^2 + y_i^2}{2\sigma^2}}$$

$$= \left[\frac{1}{\sqrt{2\pi}} \cdot \frac{1}{\omega} \right]^{2n} \cdot e^{-\frac{\sum_{i=1}^n (x_i^2 + y_i^2)}{2\sigma^2}}$$

$$\hat{\omega} = \sqrt{\frac{\sum_{i=1}^n (x_i^2 + y_i^2)}{2n}}$$

Complete minimal sufficient since exp. family form

i) $\hat{\mu}(d)$ cannot be computed from the (minimal) suff. stat. $\hat{\omega}$, da it conflicts with the suff. principle $\mu(\hat{\omega})$ is in harmony with

② i) Note: $\mu = \mu(\omega)$ since
each $P_0 = P_0(\omega)$ by integration
over A_0 .

μ^* is unbiased since $\hat{\mu}(\omega)$
is unbiased

$$(E(E(X|T)) = E(X))$$

It is an estimator since $\hat{\mu}$
is suff., and optimal unique
from completeness of $\hat{\mu}$

∴ μ^* is the unique
UMVU.

(Rao-Blackwellization, Leh. Schulte)

i)
(2) $\text{Std } \mu^*(D)$ depends on d .

μ can be calculated by simulation giving μ_1^*, \dots, μ_N^* as d by giving S_N as μ . ($N=10^6$)

This requires calculation of $\mu^*(d)$ which also can be done by simulation (but actually also analytically)

Calculation of both μ^* and its standard uncertainty is challenging.

(2) i) $g(D)$ bivariate normal
sample with standard dev.
 $g(d)$: Group model //

Family of distributions for
data D is invariant
when G acts on the data. //

(*) $X_i = \sigma u_i$, $Y_i = \sigma v_i$
i.i.d. $u_i, v_i \sim N(0, 1)$.

$\hat{\sigma} = \hat{\sigma}(d)$ and

$\hat{\sigma}(g d) = g \hat{\sigma}(d)$ from

(*) and formula for $\hat{\sigma}$.
equivariant //

$$\textcircled{2} \quad b) \quad 2n \hat{\sigma}^2 / \sigma^2 = \chi^2_{2n}$$

$$\Rightarrow \hat{\sigma}^2 \sim \frac{\sigma^2}{2n} \chi^2_{2n}$$

(equal Gam also)

$$C1 \quad 1 - \alpha = P(a \leq \chi^2 \leq b)$$

$$): \quad \frac{2n \hat{\sigma}^2}{b} \leq \sigma^2 \leq \frac{2n \hat{\sigma}^2}{a}$$

$$\left[\frac{1}{\sqrt{b}}, \frac{1}{\sqrt{a}} \right] \cdot \sqrt{2n} \hat{\sigma} = [\hat{\sigma}_1, \hat{\sigma}_2]$$

(2) ^{b)} $\mu = \mu(\omega)$ is decreasing
in ω (ω small gives more
high scores) so

$$[\mu(\hat{\omega}_2), \mu(\hat{\omega}_1)]$$

$\hat{\omega}$ is complete suff. an

a is ancillary

$$(a = \frac{(u, v)}{\bar{u} + \bar{v}} \leq)$$

$\Rightarrow \hat{\omega}$ and a are independent

Orbits are rays, and each
ray is uniquely given by a maximal
invariant. Not maximal

$(\hat{\omega}, a) \leftrightarrow d$ fails \Rightarrow invariant