# COMP37111 - Advanced Algorithms I

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## 1 Course Unit Structure

- 10 credit module. Online exam 75%.
- 2 labs worth 25%.
  - 1. Coursework A: Due Thursday, 19th October at 12:00 (SSO).
  - 2. Coursework A: Due Thursday, 23rd November at 12:00 (SSO).

## 2 Some Basic Graph Algorithms

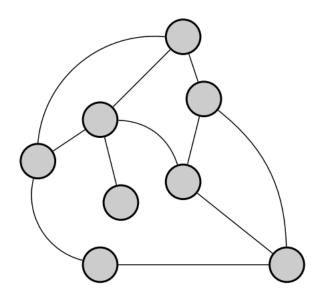
### 2.1 Graphs and directed graphs

#### **2.1.1** Graphs

**Graph:** A graph is a pair G = (V, E), where V is a finite set and E a set of subsets of V of cardinality 2. Where V = vertices, E = edges.

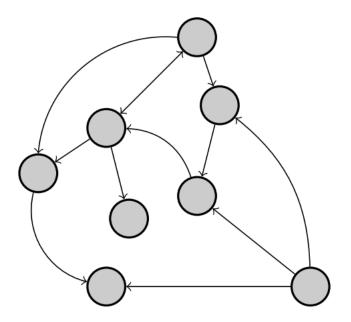
#### Formal notation for a graph:

- If  $\{u, v\} \in E$ , we say that u and v are neighbours.
- If  $v \in V$ ,  $e \in E$  and  $v \in e$ , we say v and e are adjacent.



#### 2.1.2 Directed Graphs

**Directed graph:** A pair G = (V, E), where V is a set and E a set of ordered pairs of distinct elements of V. Where V = vertices, E = edges, the same as a normal graph.



## 2.1.3 Graph storage

• A directed graph can be stored using adjacency lists:

$$\begin{array}{c|cccc} \text{Vertex } 1 \rightarrow & \boxed{2} & \boxed{3} \\ \text{Vertex } 2 \rightarrow & \boxed{1} \\ \text{Vertex } 3 \rightarrow & \boxed{1} & \boxed{2} & \boxed{4} \\ \text{Vertex } 4 \rightarrow & \boxed{1} & \boxed{3} \end{array}$$

- From any vertex, the adjacent edges can be accessed efficiently.
- From any edge, the adjacent vertices can be accessed efficiently.
- An undirected graph can be stored using a symmetric matrix:

$$\begin{array}{c|ccccc}
V1 & V2 & V3 & V4 \\
V1 & * & 0 & 1 & 1 \\
V2 & * & 1 & 1 \\
V3 & 0 & * & 1 & 1 \\
V4 & 1 & 1 & 0 & *
\end{array}$$

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- Wasteful in memory but more convenient.

#### 2.1.4 Graph definitions

**Reachable:** We say that v is reachable from u if there is a path between them.

**Connected:** A graph is connected if every node is reachable from every other.

**Strongly Connected:** A directed graph is strongly connected if every vertex is reachable from every other.

**Connected Component:** A connected component of a graph is a maximal set of vertices each of which is reachable from any other.

**Strongly Connected Component:** A strongly connected component of a directed graph is a maximal set of vertices each of which is reachable (in the directed graph sense) from any other.

**Cycle:** A cycle in a directed graph G is a sequence of vertices  $v0, ..., vk = v0 (k \ge 2)$  such that, for all i  $(0 \le ik), (vi, vi + 1)$  is an edge. Just a fancy way of saying there is a loop between some vertices.

Cyclic/Acyclic: We call a graph cyclic if it has a cycle, otherwise it's acyclic.

#### 2.1.5 Some problems

Given the definitions above, how can we compute the following functions?

#### Algorithm 1 Connected Components

- 1: Input A graph G = (V, E).
- 2: **Return** The connected components of G.

#### Algorithm 2 Strongly Connected Components

- 1: Input A graph G = (V, E).
- 2: **Return** The strongly connected components of G.

## Algorithm 3 Cyclicity

- 1: **Input** A directed graph G = (V, E).
- 2: Return True if G is cyclic, False otherwise.