Figure 1: Consistency for simulated dataset
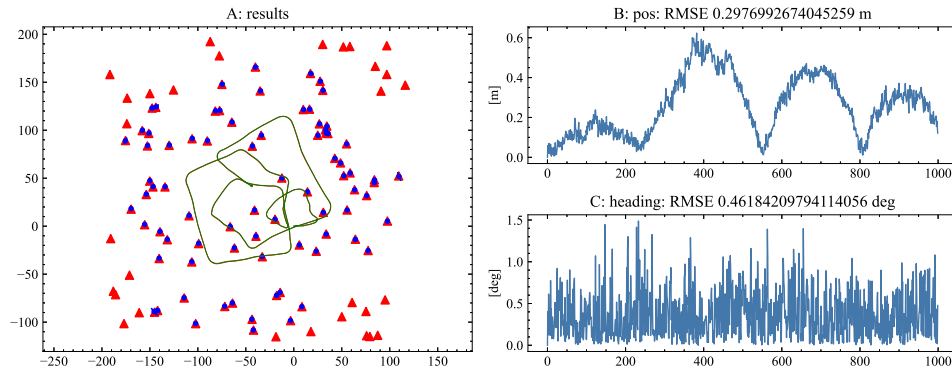

Figure 2: Result and RMSE for simulated dataset

1 Tuning

1.1 Thoughts on tuning VP

- Higher R_1 Less landmarks

- Trust odometry to much causes predicted position to change making it harder to make associations

- Too large R, we overfit and NIS becomes small