

# **PSL-C v2.0 — RFC Specification**

This document defines the full RFC-style specification for PSL-C (Prompt Structured Language — Cinematic). Version 2.0 includes the new OBJ category and the finalized hierarchical ordering sequence.

## **1. Introduction**

PSL-C is a deterministic, structured cinematic prompting standard optimized for AI-driven video generation.

## **2. Purpose**

The purpose of PSL-C is to provide a consistent, interpretable grammar for video models, enabling cinematic continuity and repeatable results.

## **3. Design Philosophy**

PSL-C follows a global-to-local hierarchical semantic cascade that mirrors transformer interpretive paths.

## **4. Terminology**

Each PSL-C category represents a semantic lane. Categories may be required or optional.

## **5. PSL-C Category Ordering**

STYLE  
COLOR  
LOCATION  
VIBE  
MOTION  
ANIMAL (optional)  
ANIMAL BEHAVIOR (optional)  
INTERACTION  
CHARACTER BEHAVIOR  
OBJECTS (optional)  
CAMERA  
LIGHTING  
AUDIO  
TIMING  
WEATHER  
PHYSICS  
MATERIALS

ENVIRONMENT INTERACTION  
LANGUAGE  
DIALOGUE  
CLIP LENGTH

## 6. Compact Format Tokens

PSL-C defines 3-letter category codes such as STY, COL, LOC, MOT, CHR, OBJ, CAM, LGT, etc.

## 7. Token Efficiency

PSL-C reduces natural-language scene prompts (1000–2000 tokens) to 40–70 tokens in compact mode.

## 8. Optional Categories

ANIMAL, ANIMAL BEHAVIOR, and OBJECTS are fully optional and triggered only when required.

## 9. Licensing Notice

The formula ordering, DSL structure, category taxonomy, and specific syntax patterns remain copyrighted by Zach Bogart.

## 10. Versioning & Governance

PSL-C v2.0 establishes the OBJ category and finalizes placement after CHARACTER BEHAVIOR.