

Robotics with the Board of Education Shield for Arduino

<http://learn.parallax.com/ShieldRobot>

Print this table to use with Chapter 2, Activity 6: Testing the Servos and Chapter 4, Activity 1: Basic BOE Shield-Bot Maneuvers.

Table 2-2: writeMicroseconds(us) Combinations			
Pin 13 servoLeft	Pin 12 servoRight	Description	Behavior
1700	1300	Full speed, pin 13 servo counter-clockwise, pin 12 servo clockwise.	
1300	1700		
1700	1700		
1300	1300		
1500	1700		
1300	1500		
1500	1500	Both servos should stay still.	
1520	1480		
1540	1460		
1700	1450		
1550	1300		