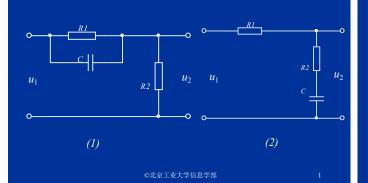
#### 计算机控制原理与技术

## 1、图中各电路,u1为输入量,u2为输出量,试写出动态方程。



#### 计算机控制原理与技术

# (1)解答:

$$u_{1}(t) = u_{R1}(t) + u_{R2}(t) = u_{R1}(t) + u_{2}(t) \qquad u_{1}$$

$$i_{1}(t) = \frac{u_{R1}(t)}{R_{1}} = \frac{u_{1}(t) - u_{2}(t)}{R_{1}}$$

$$i_{2}(t) = C\frac{du_{C}(t)}{dt} = C \cdot \left(\frac{du_{1}(t)}{dt} - \frac{du_{2}(t)}{dt}\right)$$

$$u_{2}(t) = R_{2} \cdot (i_{1}(t) + i_{2}(t)) = R_{2} \frac{u_{1}(t) - u_{2}(t)}{R_{1}} + R_{2}C \cdot \left(\frac{du_{1}(t)}{dt} - \frac{du_{2}(t)}{dt}\right)$$

$$R_{1} \cdot u_{2}(t) = R_{2}u_{1}(t) - R_{2}u_{2}(t) + R_{1}R_{2}C \cdot \frac{du_{1}(t)}{dt} - R_{1}R_{2}C \cdot \frac{du_{2}(t)}{dt}$$

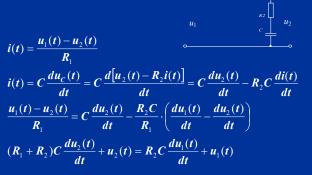
$$R_{1}R_{2}C \cdot \frac{du_{2}(t)}{dt} + (R_{1} + R_{2}) \cdot u_{2}(t) = R_{1}R_{2}C \cdot \frac{du_{1}(t)}{dt} + R_{2}u_{1}(t)$$

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## (2)解答:



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## 2、求下面象函数F(s)的原函数f(t)

$$F(s) = \frac{s^2 + 5s + 5}{s^2 + 4s + 3}$$

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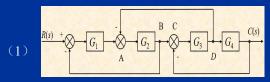
#### 解发.

$$F(s) = \frac{s^2 + 5s + 5}{s^2 + 4s + 3} = 1 + \frac{s + 2}{s^2 + 4s + 3}$$
$$= 1 + \frac{s + 2}{(s + 3)(s + 1)} = 1 + \frac{1/2}{s + 1} + \frac{1/2}{s + 3}$$
$$\therefore f(t) = \delta(t) + \frac{1}{2}e^{-t} + \frac{1}{2}e^{-3t}$$

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#### 计算机控制原理与技术

### 3、求以下系统的闭环传递函数C(s)/R(s)



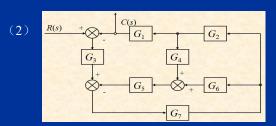
### (1)解答:

$$\frac{\mathbf{C}(s)}{R(s)} = \frac{G_1 G_2 G_3 G_4}{1 + G_1 G_2 + G_3 G_4 + G_2 G_3 + G_1 G_2 G_3 G_4}$$

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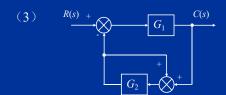
## 3、求以下系统的闭环传递函数C(s)/R(s)



# (2)解答:

$$\frac{C(s)}{R(s)} = \frac{G_1 G_2 G_3 G_7}{1 + G_5 G_6 G_7 + G_2 G_4 G_5 G_7 + G_1 G_2 G_3 G_7}$$

3、求以下系统的闭环传递函数C(s)/R(s)



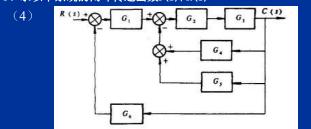
(3)解答:

$$\frac{\boldsymbol{C}(\boldsymbol{s})}{\boldsymbol{R}(\boldsymbol{s})} = \frac{\boldsymbol{G}_1(1 - \boldsymbol{G}_2)}{1 - \boldsymbol{G}_2 + \boldsymbol{G}_1\boldsymbol{G}_2}$$

计算机控制原理与技术

计算机控制原理与技术

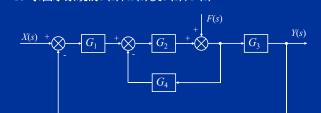
## 3、求以下系统的闭环传递函数C(s)/R(s)



## (4)解答:

$$\frac{C(S)}{R(S)} = \frac{G1G2G3}{1 + G2G3G4 + G2G3G5 + G1G2G3G6}$$

4、求图示系统的Y(s)/X(s)及Y(s)/F(s)



解答: 
$$\frac{Y(s)}{X(s)} = \frac{G_1G_2G_3}{1 + G_2G_4 + G_1G_2G_3}$$
$$\frac{Y(s)}{F(s)} = \frac{G_3}{1 + G_2G_4 + G_1G_2G_3}$$