# U-Boot beagleboneblack Documentation

# **Abstract**

# About this Document

The documentation is written in reStructuredText and converted into a pdf document. Some parts of this document are created automatically out of the log files from the tbot build process.

This document is generated for the beagleboneblack with U-Boot version

U-Boot 2017.09-rc2-00151-g2d7cb5b (Aug 23 2017 - 08:35:31 +0200)

# Introduction

This document describes how to use the firmware U-Boot and the operating system Linux in Embedded Power Architecture®, ARM and MIPS Systems.

There are many steps along the way, and it is nearly impossible to cover them all in depth, but we will try to provide all necessary information to get an embedded system running from scratch. This includes all the tools you will probably need to configure, build and run U-Boot and Linux.

First, we describe how to install the Cross Development Tools Embedded Linux Development Kit which you probably need - at least when you use a standard x86 PC running Linux or a Sun Solaris 2.6 system as build environment.

Then we describe what needs to be done to connect to the serial console port of your target: you will have to configure a terminal emulation program like cu or kermit.

In most cases you will want to load images into your target using ethernet; for this purpose you need TFTP and DHCP / BOOTP servers. A short description of their configuration is given.

A description follows of what needs to be done to configure and build the U-Boot for the beagleboneblack board, and how to install it and get it working on that board.

The configuration, building and installing of Linux in an embedded configuration is the next step. We use SELF, our Simple Embedded Linux Framework, to demonstrate how to set up both a development system (with the root filesystem mounted over NFS) and an embedded target configuration (running from a ramdisk image based on busybox).

This document does not describe what needs to be done to port U-Boot or Linux to a new hardware platform. Instead, it is silently assumed that your board is already supported by U-Boot and Linux.

# Disclaimer

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# **U-Boot**

## **Current Versions**

Das U-Boot (or just "U-Boot" for short) is Open Source Firmware for Embedded Power Architecture®, ARM, MIPS, x86 and other processors. The U-Boot project is hosted by DENX, where you can also find the project home page: http://www.denx.de/wiki/U-Boot/

The current version of the U-Boot source code can be retrieved from the DENX "git" repository.

You can browse the "git" repositories at http://git.denx.de/

The trees can be accessed through the git, HTTP, and rsync protocols. For example you can use one of the following commands to create a local clone of one of the source trees:

```
git clone git://git.denx.de/u-boot.git u-boot/
git clone http://git.denx.de/u-boot.git u-boot/
git clone rsync://git.denx.de/u-boot.git u-boot/
```

For details please see here.

Official releases of U-Boot are also available through FTP. Compressed tar archives can downloaded from the directory ftp://ftp.denx.de/pub/u-boot/.

# Get U-Boot code for the beagleboneblack

# define some PATH variables

### Export our workdirectory:

```
$ export TBOT_BASEDIR=/work/hs/tbot
$
```

#### and cd into it

```
$ cd $TBOT_BASEDIR
$
```

# clone the U-Boot code

Now we simply clone the U-Boots source code with git:

```
$ git clone /home/hs/git/u-boot u-boot-am335x_evm
Klone nach 'u-boot-am335x_evm'...
Fertig.
$
```

cd into it

```
$ cd u-boot-am335x_evm
$
```

checkout the branch you want to test

```
$ git checkout master
Bereits auf 'master'
Ihr Branch ist auf dem selben Stand wie 'origin/master'.
$
```

just for the records, print some info of the branch

```
$ git describe --tags
v2017.09-rc2-151-g2d7cb5b
$
```

# setup toolchain

This depends on the toolchain you use.

```
$ printenv PATH | grep --color=never /opt/eldk-5.4/armv5te/sysroots/i686-eldk-linux/usr/bin/armv5te-\
    linux-gnueabi
$ export PATH=/opt/eldk-5.4/armv5te/sysroots/i686-eldk-linux/usr/bin/armv5te-linux-gnueabi:$PATH
$ export CROSS_COMPILE=arm-linux-gnueabi-
$
```

# compile U-Boot for the beagleboneblack

Add the path to the dtc command to your PATH variable

```
$ export PATH=$TBOT_BASEDIR/dtc:$PATH
$
```

#### clean the source code

```
$ make mrproper
$
```

#### configure source for the beagleboneblack

```
$ make am335x_evm_defconfig
HOSTCC scripts/basic/fixdep
HOSTCC scripts/kconfig/conf.o
SHIPPED scripts/kconfig/zconf.tab.c
SHIPPED scripts/kconfig/zconf.lex.c
SHIPPED scripts/kconfig/zconf.hash.c
HOSTCC scripts/kconfig/zconf.tab.o
HOSTLD scripts/kconfig/conf
#
# configuration written to .config
#
$
```

#### Now compile it

```
$ make -s DTC_FLAGS="-S 0xb000" all
  ** Your GCC is older than 6.0 and will not be supported starting in v2018.01.
Warning (unit_address_vs_reg): Node /memory has a reg or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/dpll_core_ck has a reg\
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  or ranges property, but no unit name
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  or ranges property, but no unit name
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   reg property
Warning (unit address vs reg): Node /ocp/ethernet@4a100000/slave@4a100300 has a unit name, but no
   reg property
Warning (unit address vs req): Node /memory has a req or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/dpll_core_ck has a reg\
   or ranges property, but no unit name
```

```
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/dpl1_core_m4_ck has a
  reg or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/dpll_core_m5_ck has a
 reg or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/dpl1_core_m6_ck has a
 reg or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/dpll_mpu_ck has a reg\
 or ranges property, but no unit name
reg or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/dpl1_ddr_ck has a reg\
 or ranges property, but no unit name
reg or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/dpll_disp_ck has a reg\
 or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/dpll_disp_m2_ck has a
 reg or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/dpll_per_ck has a reg\
 or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/dpll_per_m2_ck has a
 reg or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/cefuse_fck has a reg or
 ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/clkdiv32k_ick has a reg\
 or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/pruss_ocp_gclk has a
 reg or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/mmu_fck has a reg or\
 ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/timer1_fck has a reg or\
 ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/timer2_fck has a reg or\
 ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/timer3_fck has a reg or\
 ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/timer4 fck has a reg or\
 ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/timer5_fck has a reg or\
 ranges property, but no unit name
Warning (unit address vs reg): Node /ocp/14 wkup@44c00000/prcm@200000/clocks/timer6 fck has a reg or
 ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/timer7_fck has a reg or\
 ranges property, but no unit name
Warning (unit address vs reg): Node /ocp/14 wkup@44c00000/prcm@200000/clocks/usbotg fck has a reg or
 ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/ieee5000_fck has a reg\
 or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/wdt1_fck has a req or\
 ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/cpsw_cpts_rft_clk has a
 reg or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/gpio0_dbclk_mux_ck has
 a reg or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/gpio0_dbclk has a reg\
 or ranges property, but no unit name
or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/gpio2_dbclk has a reg\
 or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/gpio3_dbclk has a reg\
 or ranges property, but no unit name
Warning (unit address vs reg): Node /ocp/14 wkup@44c00000/prcm@200000/clocks/lcd gclk has a reg or
 ranges property, but no unit name
Warning (unit address vs req): Node /ocp/14 wkup@44c00000/prcm@200000/clocks/qfx fclk clksel ck has\
 a reg or ranges property, but no unit name
Warning (unit address vs reg): Node /ocp/14 wkup@44c00000/prcm@200000/clocks/gfx fck div ck has a
 reg or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/sysclkout_pre_ck has a
 reg or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/clkout2_div_ck has a
 reg or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/dbg_sysclk_ck has a reg\
 or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/dbg_clka_ck has a reg\
 or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/stm_pmd_clock_mux_ck\
 has a reg or ranges property, but no unit name
```

```
\label{lem:warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/trace_pmd_clk_mux_ck\\ \\ \end{tabular}
 has a reg or ranges property, but no unit name
reg or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/trace_clk_div_ck has a
 reg or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/14_wkup@44c00000/prcm@200000/clocks/clkout2_ck has a reg or\
 ranges property, but no unit name
\label{local_wave} \mbox{Warning (unit\_address\_vs\_reg): Node /ocp/14_wkup@44c00000/scm@210000/scm\_conf@0/clocks/sys\_clkin\_ck\end{array}. }
 has a reg or ranges property, but no unit name
Warning (unit_address_vs_reg): Node /ocp/ethernet@4a100000/slave@4a100200 has a unit name, but no
 reg property
Warning (unit_address_vs_reg): Node /ocp/ethernet@4a100000/slave@4a100300 has a unit name, but no
 reg property
This board uses CONFIG_DM_I2C_COMPAT. Please remove
(possibly in a subsequent patch in your series)
before sending patches to the mailing list.
______
Ś
```

after U-Boot is compiled, copy the resulting binaries we need later to our tftpboot directory.

```
$ cp u-boot.bin /var/lib/tftpboot/beagleboneblack/tbot
$
$ cp u-boot.img /var/lib/tftpboot/beagleboneblack/tbot
$
$ cp MLO /var/lib/tftpboot/beagleboneblack/tbot
$
```

We also copy the u-boot.dtb file to our tftp directory, as we do some testing with it later.

```
$ cp u-boot.dtb /var/lib/tftpboot/beagleboneblack/tbot
$
```

# **U-Boot installation**

### install U-Boot

for this example, we install the new U-Boot on the SD card, as we use SD card bootmode.

```
=> print tbot_upd_uboot load_uboot upd_uboot
tbot_upd_uboot=run load_uboot;run upd_uboot
load_uboot=tftp ${load_addr_r} ${ubfile}
upd_uboot=fatwrite mmc 1:1 ${load_addr_r} u-boot.img ${filesize}
=>
```

tfpt the new u-boot image into ram and write it to the sd card.

### install SPL

for this example, we install the new SPL on the SD card, as we use SD card bootmode.

```
=> print tbot_upd_spl load_mlo upd_mlo
tbot_upd_spl=run load_mlo;run upd_mlo
load_mlo=tftp ${load_addr_r} ${mlofile}
upd_mlo=fatwrite mmc 1:1 ${load_addr_r} mlo ${filesize}
=>
```

tfpt the new SPL image into ram and write it to the sd card.

## Tool Installation

U-Boot uses a special image format when loading the Linux kernel or ramdisk or other images. This image contains (among other things) information about the time of creation, operating system, compression type, image type, image name and CRC32 checksums.

The tool mkimage is used to create such images or to display the information they contain. When using the ELDK, the mkimage command is already included with the other ELDK tools.

If you don't use the ELDK then you should install mkimage in some directory that is in your command search PATH, for instance:

```
$ cp tools/mkimage /usr/local/bin/
```

mkimage is readily available in several distributions; for example, in Ubuntu it is part of the u-boot-tools package, so it can be installed with:

```
$ sudo apt-get install u-boot-tools
```

In Fedora the package name is uboot-tools, and the command to install it is:

```
$ sudo dnf install uboot-tools
```

Finally, if you're building with OpenEmbedded or Yocto Project, you would want to add the u-boot-fw-utils recipe to your image.

# **U-Boot Command Line Interface**

The following section describes the most important commands available in U-Boot. Please note that U-Boot is highly configurable, so not all of these commands may be available in the configuration of U-Boot installed on your hardware, or additional commands may exist. You can use the help command to print a list of all available commands for your configuration.

For most commands, you do not need to type in the full command name; instead it is sufficient to type a few characters. For instance, help can be abbreviated as h.



The behaviour of some commands depends on the configuration of U-Boot and on the definition of some variables in your U-Boot environment.

Almost all U-Boot commands expect numbers to be entered in hexadecimal input format. (Exception: for historical reasons, the sleep command takes its argument in decimal input format.)

Be careful not to use edit keys besides 'Backspace', as hidden characters in things like environment variables can be very difficult to find.

### **Information Commands**

### bdinfo - print Board Info structure

```
=> help bdinfo
bdinfo - print Board Info structure

Usage:
bdinfo
=>
```

The bdinfo command (bdi) prints the information that U-Boot passes about the board such as memory addresses and sizes, clock frequencies, MAC address, etc. This information is mainly needed to be passed to the Linux kernel.

```
=> bdi
arch_number = 0x00000E05
boot_params = 0x80000100
DRAM bank = 0x00000000
-> start = 0x80000000
-> size = 0x20000000
baudrate = 115200 bps
TLB addr = 0x9FFF0000
relocaddr = 0x9FF4E000
reloc off = 0x1F74E000
irq_sp = 0x9DF21EC0
sp start = 0x9DF21EB0
Early malloc usage: 188 / 400
fdt_blob = 9df21ed8
=>
```

### coninfo - print console devices and informations

```
=> help conin
coninfo - print console devices and information

Usage:
coninfo
=>
```

The coninfo command (conin) displays information about the available console I/O devices.

```
=> conin
List of available devices:
serial@44e09000 00000007 IO stdin stdout stderr
serial 00000003 IO
=>
```

The output contains the device name, flags, and the current usage. For example, the output

```
serial@44e09000 00000003 IO stdin stdout stderr
```

means that the serial device provides input (flag 'I') and output (flag 'O') functionality and is currently assigned to the 3 standard I/O streams stdin, stdout and stderr.

### flinfo - print FLASH memory information

```
=> help flinfo
Unknown command 'flinfo' - try 'help' without arguments for list of all known commands
=>
```

The command flinfo (fli) can be used to get information about the available flash memory (see Flash Memory Commands below).

```
=> flinfo
Unknown command 'flinfo' - try 'help'
=>
```

### help - print online help

The help command (h or ?) prints online help. Without any arguments, it prints a list of all U-Boot commands that are available in your configuration of U-Boot. You can get detailed information for a specific command by typing its name as argument to the help command:

```
=> help printenv tftp
printenv - print environment variables

Usage:
printenv [-a]
    - print [all] values of all environment variables
printenv name ...
    - print value of environment variable 'name'
tftpboot - boot image via network using TFTP protocol

Usage:
tftpboot [loadAddress] [[hostIPaddr:]bootfilename]
=>
```

## **Memory Commands**

### base - print or set address offset

```
=> help base
base - print or set address offset

Usage:
base
    - print address offset for memory commands
base off
    - set address offset for memory commands to 'off'
=>
```

You can use the base command (ba) to print or set a "base address" that is used as the address offset for all subsequent memory commands; the default value of the base address is 0, so all addresses you enter are used unmodified. However, when you repeatedly have to access a certain memory region (like the internal memory of some embedded Power Architecture® processors) it can be very convenient to set the base address to the start of this area and then use only the offsets:

ToDo

#### crc32 - checksum calculation

The crc32 command (crc) can be used to calculate a CRC32 checksum over a range of memory:

```
=> crc 0x80000004 0x3fc a6d53e40
=>
```

When used with 3 arguments, the command stores the calculated checksum at the given address:

```
=> crc 0x80000004 0x3fc 0x80000000 a6d53e40
=> md 0x80000000 4
80000000: 403ed5a6 b9070000 38000000 ..>@.....8...8
=>
```

As you can see, the CRC32 checksum was not only printed, but also stored at address passed in the 3th argument.

### cmp - memory compare

```
=> help cmp
cmp - memory compare

Usage:
cmp [.b, .w, .1] addr1 addr2 count
=>
```

With the cmp command you can test whether the contents of two memory areas are identical or not. The command will test either the whole area as specified by the 3rd (length) argument, or stop at the first difference.

Like most memory commands the :redtext:cmp` can access the memory in different sizes: as 32 bit (long word), 16 bit (word) or 8 bit (byte) data. If invoked just as cmp the default size (32 bit or long words) is used; the same can be selected explicitly by typing cmp.l instead. If you want to access memory as 16 bit or word data, you can use the variant cmp.w instead; and to access memory as 8 bit or byte data please use cmp.b.



Please note that the count argument specifies the number of data items to process, i. e. the number of long words or words or bytes to compare.

```
=> cmp.l 0x80000000 0x80100000 40000
Total of 262144 word(s) were the same
=> cmp.w 0x80000000 0x80100000 80000
Total of 524288 halfword(s) were the same
=> cmp.b 0x80000000 0x80100000 100000
Total of 1048576 byte(s) were the same
=>
```

### cp - memory copy

```
=> help cp
cp - memory copy

Usage:
cp [.b, .w, .l] source target count
=>
```

The cp command is used to copy memory areas.

```
=> cp 0x80000000 0x80100000 10000
=>
```

The cp command understands the type extensions .l, .w and .b :

```
=> cp.1 0x80000000 0x80100000 10000
=> cp.w 0x80000000 0x80100000 20000
=> cp.b 0x80000000 0x80100000 40000
=>
```

### md - memory display

```
=> help md
md - memory display

Usage:
md [.b, .w, .l] address [# of objects]
=>
```

The md command can be used to display memory contents both as hexadecimal and ASCII data.

```
=> md 0x80000000
80000000: 1cec5b8c 381401ad 6778e393 01fbbcc3
                                                .[....8..xg...
80000010: 89e9712a 0fb40e16 6f236743 3b46fbe6
                                                *q.....Cg#o..F;
                                                .V#..T|nw.V....{
80000020: ea2356f6 6e7c540f e056e377 7bd28a9f
80000030: cfa9bcec b19ace51 b27f4dc5 8eeca28b
                                                ....Q....M....
                                                .....v...b.k
80000040: ee9bld07 09f8e8lf 969e7603 6be76204
                                                ....b`..^.Z.N..i
80000050: b0de9f91 0b9a6062 825adf5e 6914b64e
80000060: 31eb81cc ec1b3009 b7096df7 0546f59b
                                                ...1.0...m....F.
80000070: d94137a6 3d455fld 01549ffb 4d7b0a2d
                                                .7A.._E=..T.-.{M
80000080: 8e8650b9 e2101ce1 d705d373 34455d16
                                                .P.....]E4
80000090: b3776306 bb40cb3b 246c65e8 25587336
800000a0: 65f88cel 33c09949 67ca3299 e88b24bf
                                                ...eI..3.2.g.$..
800000b0: 2057a219 45fe820a c5ae6da8 e9b39578
                                                ..W ...E.m..x...
800000c0: 0d27e891 5201230c da4c518d bfa2cc2b
                                                 .'..#.R.QL.+...
800000d0: 98386a41 803c36df 1b0d4c5d 09e31558
                                                Aj8..6<.]L..X...
800000e0: 58ae8bfl 681bc92b 752a350e 3f057db9
                                                ...X+..h.5*u.}.?
800000f0: a5e3bbbd c7c2239e ecf15559 e91c4375
                                                ....#..YU..uC..
```

This command can also be used with the type extensions .l, .w and .b:

```
=> md.w 0x80000000
80000000: 5b8c 1cec 01ad 3814 e393 6778 bcc3 01fb
                                                     .[....8..xq....
80000010: 712a 89e9 0e16 0fb4 6743 6f23 fbe6 3b46
                                                     *q.....Cg#o..F;
                                                    .V#..T|nw.V....{
80000020: 56f6 ea23 540f 6e7c e377 e056 8a9f 7bd2
80000030: bcec cfa9 ce51 b19a 4dc5 b27f a28b 8eec
                                                    ....Q....M.....
80000040: 1d07 ee9b e81f 09f8 7603 969e 6204 6be7
                                                    .....v...b.k
                                                    ....b`..^.Z.N..i
80000050: 9f91 b0de 6062 0b9a df5e 825a b64e 6914
80000060: 81cc 31eb 3009 ec1b 6df7 b709 f59b 0546
                                                    ...1.0...m....F.
80000070: 37a6 d941 5fld 3d45 9ffb 0154 0a2d 4d7b
                                                    .7A.._E=..T.-.{M
=> md.b 0x80000000
80000000: 8c 5b ec 1c ad 01 14 38 93 e3 78 67 c3 bc fb 01
                                                            .[....8..xq....].
80000010: 2a 71 e9 89 16 0e b4 0f 43 67 23 6f e6 fb 46 3b
                                                            *q.....Cg#o..F;
80000020: f6 56 23 ea 0f 54 7c 6e 77 e3 56 e0 9f 8a d2 7b
                                                            .V#..T|nw.V....{
80000030: ec bc a9 cf 51 ce 9a b1 c5 4d 7f b2 8b a2 ec 8e
                                                            ....Q....M.....
```

The last displayed memory address and the value of the count argument are remembered, so when you enter md again without arguments it will automatically continue at the next address, and use the same count again.

```
=> md.b 0x80000000 0x20
80000000: 8c 5b ec 1c ad 01 14 38 93 e3 78 67 c3 bc fb 01
80000010: 2a 71 e9 89 16 0e b4 0f 43 67 23 6f e6 fb 46 3b
=> md.w 0x80000000
80000000: 5b8c 1cec 01ad 3814 e393 6778 bcc3 01fb
                                                    .[....8..xg....
80000010: 712a 89e9 0e16 0fb4 6743 6f23 fbe6 3b46
                                                   *q.....Cg#o..F;
                                                  .V#..T|nw.V....{
80000020: 56f6 ea23 540f 6e7c e377 e056 8a9f 7bd2
80000030: bcec cfa9 ce51 b19a 4dc5 b27f a28b 8eec
=> md 0x80000000
80000000: 1cec5b8c 381401ad 6778e393 01fbbcc3
                                               .[....8..xg....
                                              *q.....Cg#o..F;
80000010: 89e9712a 0fb40e16 6f236743 3b46fbe6
80000020: ea2356f6 6e7c540f e056e377 7bd28a9f
                                              .V#..T|nw.V....{
80000030: cfa9bcec b19ace51 b27f4dc5 8eeca28b
                                               ....Q....M.....
                                               ....b`..^.Z.N..i
80000040: ee9bld07 09f8e81f 969e7603 6be76204
80000050: b0de9f91 0b9a6062 825adf5e 6914b64e
80000060: 31eb81cc ec1b3009 b7096df7 0546f59b
                                               ...1.0...m....F.
80000070: d94137a6 3d455fld 01549ffb 4d7b0a2d
                                               .7A.._E=..T.-.{M
```

### mm - memory modify (auto-incrementing)

```
=> help mm
mm - memory modify (auto-incrementing address)

Usage:
mm [.b, .w, .l] address
=>
```

The mm command is a method to interactively modify memory contents. It will display the address and current contents and then prompt for user input. If you enter a legal hexadecimal number, this new value will be written to the address. Then the next address will be prompted. If you don't enter any value and just press ENTER, then the contents of this address will remain unchanged. The command stops as soon as you enter any data that is not a hex number (like .):

```
=> mm 0x8000000

80000000: lcec5b8c ? 0

80000004: 381401ad ? 0xaabbccdd

80000008: 6778e393 ? 0x01234567

8000000c: 01fbbcc3 ? .

=> md 0x80000000 10

80000000: 00000000 aabbccdd 01234567 01fbbcc3 .....gE#....

80000010: 89e9712a 0fb40e16 6f236743 3b46fbe6 *q....Cg#o..F;

80000020: ea2356f6 6e7c540f e056e377 7bd28a9f .V#..T|nw.V...{

80000030: cfa9bcec b19ace51 b27f4dc5 8eeca28b ...Q...M.....
```

Again this command can be used with the type extensions .l, .w and .b:

```
=> mm.w 0x8000000
80000000: 0000 ? 0x0101
80000002: 0000 ? 0x0202
80000004: ccdd ? 0x4321
80000006: aabb ? 0x8765
80000008: 4567 ?
=> md 0x8000000 10
80000000: 02020101 87654321 01234567 01fbbcc3
                                                ....!Ce.gE#.....
80000010: 89e9712a 0fb40e16 6f236743 3b46fbe6
                                                *q.....Cg#o..F;
80000020: ea2356f6 6e7c540f e056e377 7bd28a9f
                                               .V#..T|nw.V....{
80000030: cfa9bcec b19ace51 b27f4dc5 8eeca28b
                                                ....Q....M.....
=> mm.b 0x8000000
80000000: 01 ? 0x48
80000001: 01 ? 0x65
80000002: 02 ? 0x6c
80000003: 02 ? 0x6c
80000004: 21 ? 0x6f
80000005: 43 ? 0x20
80000006: 65 ? 0x20
80000007: 87 ? 0x20
80000008: 67 ?
=> md 0x80000000 10
80000000: 6c6c6548 2020206f 01234567 01fbbcc3
                                              Hello gE#....
80000010: 89e9712a 0fb40e16 6f236743 3b46fbe6
                                                *q.....Cg#o..F;
80000020: ea2356f6 6e7c540f e056e377 7bd28a9f
                                                .V#..T|nw.V....{
80000030: cfa9bcec b19ace51 b27f4dc5 8eeca28b
                                                ....O....M.....
```

### mw - memory write (fill)

```
=> help mw
mw - memory write (fill)

Usage:
mw [.b, .w, .l] address value [count]
=>
```

The mw command is a way to initialize (fill) memory with some value. When called without a count argument, the value will be written only to the specified address. When used with a count value, the entire memory area will be initialized with this value:

```
=> md 0x80000000 0x10
80000000: 6c6c6548 2020206f 01234567 01fbbcc3
                                             Hello gE#....
80000010: 89e9712a 0fb40e16 6f236743 3b46fbe6
                                              *q.....Cg#o..F;
80000020: ea2356f6 6e7c540f e056e377 7bd28a9f
                                             .V#..T|nw.V....{
80000030: cfa9bcec b19ace51 b27f4dc5 8eeca28b
                                             ....Q....M.....
=> mw 0x80000000 0xaabbccdd
=> md 0x80000000 0x10
80000000: aabbccdd 2020206f 01234567 01fbbcc3
                                              ....o gE#.....
80000010: 89e9712a 0fb40e16 6f236743 3b46fbe6
                                             *q.....Cg#o..F;
.V#..T|nw.V....{
80000020: ea2356f6 6e7c540f e056e377 7bd28a9f
80000030: cfa9bcec b19ace51 b27f4dc5 8eeca28b
                                             ....Q....M.....
=> mw 0x80000000 0 6
=> md 0x80000000 0x10
80000010: 00000000 00000000 6f236743 3b46fbe6
                                              80000020: ea2356f6 6e7c540f e056e377 7bd28a9f
                                             .V#..T|nw.V....{
80000030: cfa9bcec b19ace51 b27f4dc5 8eeca28b
                                             ....Q....M.....
```

This is another command that accepts the type extensions .l, .w and .b:

```
=> mw.w 0x80000004 0x1155 6
=> md 0x80000000 0x10
                                               ....U.U.U.U.U.U.
80000000: 00000000 11551155 11551155 11551155
80000010: 00000000 00000000 6f236743 3b46fbe6
                                                .........Cg#o..F;
                                                .V#..T|nw.V....{
80000020: ea2356f6 6e7c540f e056e377 7bd28a9f
80000030: cfa9bcec b19ace51 b27f4dc5 8eeca28b
                                                ....Q....M.....
=> mw.b 0x80000007 0xff 7
=> md 0x80000000 0x10
80000000: 00000000 ff551155 ffffffff 1155ffff
                                                ....U.U.....U.
                                                ........Cg#o..F;
80000010: 00000000 00000000 6f236743 3b46fbe6
80000020: ea2356f6 6e7c540f e056e377 7bd28a9f
                                                .V#..T|nw.V....{
80000030: cfa9bcec b19ace51 b27f4dc5 8eeca28b
                                                 ....Q....M.....
```

### nm - memory modify (constant address)

```
=> help nm
nm - memory modify (constant address)

Usage:
nm [.b, .w, .l] address
=>
```

The nm command (non-incrementing memory modify) can be used to interactively write different data several times to the same address. This can be useful for instance to access and modify device registers:

The nm command also accepts the type .l, .w and .b

### loop - infinite loop on address range

```
=> help loop
loop - infinite loop on address range

Usage:
loop [.b, .w, .1] address number_of_objects
=>
```

The loop command reads in a tight loop from a range of memory. This is intended as a special form of a memory test, since this command tries to read the memory as fast as possible.



This command will never terminate. There is no way to stop it but to reset the board!

### **Execution Control Commands**

### source - run script from memory

```
=> help source
source - run script from memory

Usage:
source [addr]
    - run script starting at addr
    - A valid image header must be present

For FIT format uImage addr must include subimage
unit name in the form of addr:<subimg_uname>
=>
```

With the source command you can run "shell" scripts under U-Boot: You create a U-Boot script image by simply writing the commands you want to run into a text file; then you will have to use the mkimage tool to convert this text file into a U-Boot image (using the image type script).

This image can be loaded like any other image file, and with source you can run the commands in such an image. For instance, the following text file:

```
$ cat source_example.txt
echo
echo Network Configuration:
echo ------
echo Target:
printenv ipaddr hostname
echo
echo Server:
printenv serverip rootpath
echo
$
```

can be converted into a U-Boot script image using the mkimage command like this:

```
$ mkimage -A ppc -O linux -T script -C none -a 0 -e 0 -n "autoscr example script" -d\
    $TBOT_BASEDIR/source_example.txt /var/lib/tftpboot/beagleboneblack/tbot/source.scr
Image Name:    autoscr example script
Created:    Wed Aug 23 09:23:32 2017
Image Type:    PowerPC Linux Script (uncompressed)
Data Size:    157 Bytes = 0.15 kB = 0.00 MB
Load Address:    00000000
Entry Point:    00000000
Contents:
    Image 0: 149 Bytes = 0.15 kB = 0.00 MB
$
```

Now you can load and execute this script image in U-Boot:

## bootm - boot application image from memory

```
=> help bootm
bootm - boot application image from memory
bootm [addr [arg ...]]
    - boot application image stored in memory
     passing arguments 'arg ...'; when booting a Linux kernel,
      'arg' can be the address of an initrd image
     When booting a Linux kernel which requires a flat device-tree
      a third argument is required which is the address of the
     device-tree blob. To boot that kernel without an initrd image,
      use a '-' for the second argument. If you do not pass a third
     a bd_info struct will be passed instead
For the new multi component uImage format (FIT) addresses
     must be extended to include component or configuration unit name:
     addr:<subimg_uname> - direct component image specification
                         - configuration specification
      addr#<conf uname>
      Use iminfo command to get the list of existing component
      images and configurations.
Sub-commands to do part of the bootm sequence. The sub-commands must be
issued in the order below (it's ok to not issue all sub-commands):
     start [addr [arg ...]]
     loados - load OS image
      ramdisk - relocate initrd, set env initrd start/initrd end
             - relocate flat device tree
      cmdline - OS specific command line processing/setup
     bdt - OS specific bd_t processing
             - OS specific prep before relocation or go
     prep
             - start OS
```

The bootm command is used to start operating system images. From the image header it gets information about the type of the operating system, the file compression method used (if any), the load and entry point addresses, etc. The command will then load the image to the required memory address, uncompressing it on the fly if necessary. Depending on the OS it will pass the required boot arguments and start the OS at it's entry point.

The first argument to **bootm** is the memory address (in RAM, ROM or flash memory) where the image is stored, followed by optional arguments that depend on the OS.

Linux requires the flattened device tree blob to be passed at boot time, and bootm expects its third argument to be the address of the blob in memory. Second argument to bootm depends on whether an initrd initial ramdisk image is to be used. If the kernel should be booted without the initial ramdisk, the second argument should be given as "-", otherwise it is interpreted as the start address of initrd (in RAM, ROM or flash memory).

To boot a Linux kernel image without a initrd ramdisk image, the following command can be used:

```
=> bootm ${kernel_addr} - ${fdt_addr}
```

If a ramdisk image shall be used, you can type:

```
=> bootm ${kernel_addr} ${ramdisk_addr} ${fdt_addr}
```

Both examples of course imply that the variables used are set to correct addresses for a kernel, fdt blob and a initrd ramdisk image.



When booting images that have been loaded to RAM (for instance using TFTP download) you have to be careful that the locations where the (compressed) images were stored do not overlap with the memory needed to load the uncompressed kernel. For instance, if you load a ramdisk image at a location in low memory, it may be overwritten when the Linux kernel gets loaded. This will cause undefined system crashes.

## go - start application at address 'addr'

```
=> help go
go - start application at address 'addr'

Usage:
go addr [arg ...]
    - start application at address 'addr'
    passing 'arg' as arguments
=>
```

U-Boot has support for so-called standalone applications. These are programs that do not require the complex environment of an operating system to run. Instead they can be loaded and executed by U-Boot directly, utilizing U-Boot's service functions like console I/O or malloc() and free().

This can be used to dynamically load and run special extensions to U-Boot like special hardware test routines or bootstrap code to load an OS image from some filesystem.

The go command is used to start such standalone applications. The optional arguments are passed to the application without modification.

TODO For more information see 5.12. U-Boot Standalone Applications.

## **Download Commands**

# bootp - boot image via network using BOOTP/TFTP protocol

```
=> help bootp
bootp - boot image via network using BOOTP/TFTP protocol

Usage:
bootp [loadAddress] [[hostIPaddr:]bootfilename]
=>
```

## dhcp - invoke DHCP client to obtain IP/boot params

```
=> help dhcp
dhcp - boot image via network using DHCP/TFTP protocol

Usage:
dhcp [loadAddress] [[hostIPaddr:]bootfilename]
=>
```

## loadb - load binary file over serial line (kermit mode)

With kermit you can download binary data via the serial line.

Make sure you use the following settings in kermit.

```
set carrier-watch off
($TBOT_BASEDIR/) C-Kermit>set handshake none
($TBOT_BASEDIR/) C-Kermit>set flow-control none
($TBOT_BASEDIR/) C-Kermit>robust
($TBOT_BASEDIR/) C-Kermit>set file type bin
($TBOT_BASEDIR/) C-Kermit>set file name lit
($TBOT_BASEDIR/) C-Kermit>set rec pack 100
($TBOT_BASEDIR/) C-Kermit>set send pack 100
($TBOT_BASEDIR/) C-Kermit>set window 5
($TBOT_BASEDIR/) C-Kermit>
```

If you have problems with downloading, may you set the values

```
set rec pack
set send pack
```

to smaller values.

Now for example download u-boot.img.

```
=> loadb 80000000
\mbox{\tt \#\#} Ready for binary (kermit) download to 0x80000000 at 115200 bps...
(Back at localhost.localdomain)
($TBOT_BASEDIR/) C-Kermit>
C-Kermit 9.0.302 OPEN SOURCE:, 20 Aug 2011, localhost.localdomain [192.168.1.105]\
   Current Directory: $TBOT_BASEDIR
Communication Device: /dev/ttybbb\
Communication Speed: 115200\
              Parity: none\
         RTT/Timeout: 01 / 02
             SENDING: => /lib/tftpboot/beagleboneblack/tbot/u-boot.img\
           File Type: BINARY\
           File Size: 734224\
        :01
            \dots 10 \dots 20 \dots 30 \dots 40 \dots 50 \dots 60 \dots 70 \dots 80 \dots 90 \dots 100 \setminus
  :02
       teElapsed Time: 00:01:59\
5 Transfer67ate, CPS: 6197\
  69
        55ndow Slots: 1 of 1\
  2705
         75cket Type: B6\
6
  918482
        P921et Count: 11819\
  3276
 cket Length:\
  0 (
resend) Error Count: 4\
          Last Error:\
        Last Message: SUCCESS. Files: 1, Bytes: 734224, 6167 CPS\
($TBOT BASEDIR/) C-Kermit>connect\
Connecting to /dev/ttybbb, speed 115200\
Escape character: Ctrl-\ (ASCII 28, FS): enabled\
```

```
Type the escape character followed by C to get back,\
or followed by ? to see other options. \setminus
CACHE: Misaligned operation at range [80000000, 800b3410] \setminus
                 = 0x000b3410 = 734224 Bytes\
## Total Size
## Start Addr
                    = 0x80000000\
=>\
=> imi 80000000
## Checking Image at 80000000 ...
   FIT image found
   FIT description: Firmware image with one or more FDT blobs
   Created:
                     2017-08-23 6:36:19 UTC
    Image 0 (firmware@1)
     Description: U-Boot 2017.09-rc2-00151-g2d7cb5b for am335x board
     Created: 2017-08-23 6:36:19 UTC
     Type:
                    Firmware
     Compression: uncompressed
Data Start: unavailable
     Data Size:
                    unavailable
     Architecture: ARM
     Load Address: 0x80800000
    Image 1 (fdt@1)
     Description: am335x-evm
     Created:
                2017-08-23
Firmware
                                   6:36:19 UTC
     Type:
     Compression: uncompressed
Data Start: unavailable
Data Size: unavailable
     Architecture: ARM
     Load Address: unavailable
    Image 2 (fdt@2)
     Description: am335x-bone
Created: 2017-08-23 6:36:19 UTC
     Type:
                     Firmware
     Compression: uncompressed
     Data Start: unavailable
     Data Size:
                    unavailable
     Architecture: ARM
     Load Address: unavailable
    Image 3 (fdt@3)
     Description: am335x-boneblack
Created: 2017-08-23 6:36:19 UTC
Type: Firmware
     Compression: uncompressed Data Start: unavailable
     Data Size:
                     unavailable
     Architecture: ARM
     Load Address: unavailable
    Image 4 (fdt@4)
     Description: am335x-evmsk
Created: 2017-08-23
                                   6:36:19 UTC
                     Firmware
     Type:
     Compression: uncompressed
Data Start: unavailable
     Data Size:
                     unavailable
     Architecture: ARM
     Load Address: unavailable
    Image 5 (fdt@5)
     Description: am335x-bonegreen
Created: 2017-08-23 6:36
Type: Firmware
                                   6:36:19 UTC
     Compression: uncompressed
     Data Start: unavailable
     Data Size:
                    unavailable
     Architecture: ARM
     Load Address: unavailable
    Image 6 (fdt@6)
     Description: am335x-icev2
Created: 2017-08-23 6:36:19 UTC
     Type:
                     Firmware
     Compression: uncompressed
     Data Start: unavailable
     Data Size:
                     unavailable
     Architecture: ARM
     Load Address: unavailable
    Default Configuration: 'conf@1'
```

```
Configuration 0 (confel)

Description: am335x-evm

Kernel: unavailable

FDT: fdt@1

Configuration 1 (conf@2)

Description: am335x-bone

Kernel: unavailable

FDT: fdt@2

Configuration 2 (conf@3)

Description: am335x-boneblack

Kernel: unavailable

FDT: fdt@3

Configuration 3 (conf@4)

Description: am335x-evmsk

Kernel: unavailable

FDT: fdt@4

Configuration 4 (conf@5)

Description: am335x-bonegreen

Kernel: unavailable

FDT: fdt@5

Configuration 5 (conf@6)

Description: am335x-icev2

Kernel: unavailable

FDT: fdt@6

Configuration 5 (conf@6)

Description: am335x-icev2

Kernel: unavailable

FDT: fdt@6

Configuration 5 (conf@6)

Description: am335x-icev2

Kernel: unavailable

FDT: fdt@6

Configuration 5 (conf@6)

Description: am34x-icev2

Kernel: unavailable

FDT: fdt@6

Configuration 5 (conf@6)

Description: am35x-icev2

Kernel: unavailable

FDT: fdt@6

Configuration 5 (conf@6)

Description: am35x-icev2

Kernel: unavailable

FDT: fdt@6

Configuration 5 (conf@6)

Description: am35x-icev2

Kernel: unavailable

FDT: fdt@6

Configuration 5 (conf@6)

Description: am35x-icev2

Kernel: unavailable

FDT: fdt@6

# Checking hash(es) for FIT Image at 80000000 ...

Hash(es) for Image 0 (firmware@1): error!

Can't get image data/size for '' hash node in 'firmware@1' image node

Bad hash in FIT image!

->
```

### loads - load S-Record file over serial line

## rarpboot- boot image via network using RARP/TFTP protocol

```
=> help rarp
Unknown command 'rarp' - try 'help' without arguments for list of all known commands
=>
```

# tftpboot- boot image via network using TFTP protocol

```
=> help tftp
tftpboot - boot image via network using TFTP protocol
Usage:
tftpboot [loadAddress] [[hostIPaddr:]bootfilename]
=>
```

## **Environment Variables Commands**

## printenv- print environment variables

```
=> help printenv
printenv - print environment variables

Usage:
printenv [-a]
    - print [all] values of all environment variables
printenv name ...
    - print value of environment variable 'name'
=>
```

The printenv command prints one, several or all variables of the U-Boot environment. When arguments are given, these are interpreted as the names of environment variables which will be printed with their values:

```
=> printenv ipaddr hostname netmask ipaddr=192.168.2.10 ## Error: "hostname" not defined netmask=255.255.255.0 =>
```

Without arguments, printenv prints all a list with all variables in the environment and their values, plus some statistics about the current usage and the total size of the memory available for the environment.

```
=> printenv
Heiko=Schocher
arch=arm
args_mmc=run finduuid;setenv bootargs console=${console} ${optargs} root=PARTUUID=${uuid} rw\
      rootfstype=${mmcrootfstype}
baudrate=115200
board=am335x
board_name=A335BNLT
board_rev=00C0
board_serial=414BBBK0180
boot\_a\_script=load $\{devtype\} $\{devnum\}: $\{distro\_bootpart\} $\{scriptaddr\} $\{prefix\} $\{script\}; source = f(distro_bootpart) $\{devtype\} $\{devnum\}: f(distro_bootpart) $\{devtype\} $\{devtype\} $\{devnum\}: f(distro_bootpart) $\{devtype\} $\{
boot\_efi\_binary=load $\{devtype\} $\{devnum\}: $\{distro\_bootpart\} $\{kernel\_addr\_r\} = fi/boot/bootarm.efi; $\{distro\_bootpart\} = fi/boot/bootarm.efi
      if fdt addr ${fdt_addr_r}; then bootefi ${kernel_addr_r} ${fdt_addr_r};else bootefi ${kernel_addr_r}
\verb|boot_extlinux=sysboot| $$\{devtype\} $$\{devnum\}: $\{distro\_bootpart\} $$ any $$\{scriptaddr\} $$ and $\{scriptaddr\} $$ and $\{script
      ${prefix}extlinux/extlinux.conf
boot_fdt=try
boot fit=0
boot_net_usb_start=usb start
boot_prefixes=/ /boot/
boot_script_dhcp=boot.scr.uimg
 boot_scripts=boot.scr.uimg boot.scr
boot_targets=mmc0 legacy_mmc0 mmc1 legacy_mmc1 nand0 pxe dhcp
bootcmd=if test ${boot_fit} -eq 1; then run update_to_fit;fi;run findfdt; run init_console; run\
      envboot; run distro_bootcmd
bootcmd_dhcp=run boot_net_usb_start; if dhcp ${scriptaddr} ${boot_script_dhcp}; then source
       ${scriptaddr}; fi;setenv efi_fdtfile ${fdtfile}; if test -z "${fdtfile}" -a -n "${soc}"; then setenv\
       efi_fdtfile ${soc}-${board}${boardver}.dtb; fi; setenv efi_old_vci ${bootp_vci}; setenv efi_old_arch\
       ${bootp_arch};setenv bootp_vci PXEClient:Arch:00010:UNDI:003000;setenv bootp_arch 0xa;if dhcp
      ${kernel_addr_r}; then tftpboot ${fdt_addr_r} dtb/${efi_fdtfile}; if fdt addr ${fdt_addr_r}; then
      bootefi ${kernel_addr_r} ${fdt_addr_r}; else bootefi ${kernel_addr_r} ${fdtcontroladdr};fi;fi;setenv
      bootp_vci ${efi_old_vci};setenv bootp_arch ${efi_old_arch};setenv efi_fdtfile;setenv\
      efi_old_arch;setenv efi_old_vci;
bootcmd_legacy_mmc0=setenv mmcdev 0; setenv bootpart 0:2; run mmcboot
bootcmd_legacy_mmc1=setenv mmcdev 1; setenv bootpart 1:2; run mmcboot
bootcmd_mmc0=setenv devnum 0; run mmc_boot
bootcmd_mmc1=setenv devnum 1; run mmc_boot
bootcmd_nand=run nandboot
bootcmd_pxe=run boot_net_usb_start; dhcp; if pxe get; then pxe boot; fi
bootcount=5
```

```
bootdelay=2
bootdir=/boot
bootenvfile=uEnv.txt
bootfile=zImage
bootm_size=0x10000000
bootpart=0:2
bootscript=echo Running bootscript from mmc${mmcdev} ...; source ${loadaddr}
console=ttyO0,115200n8
cpu=armv7
dfu_alt_info_emmc=rawemmc raw 0 3751936
dfu_alt_info_mmc=boot part 0 1;rootfs part 0 2;MLO fat 0 1;MLO.raw raw 0x100 0x100;u-boot.img.raw
     raw 0x300 0x1000;u-env.raw raw 0x1300 0x200;spl-os-args.raw raw 0x1500 0x200;spl-os-image.raw raw
     0x1700 0x6900;spl-os-args fat 0 1;spl-os-image fat 0 1;u-boot.img fat 0 1;uEnv.txt fat 0 1 \,
dfu_alt_info_nand=SPL part 0 1;SPL.backup1 part 0 2;SPL.backup2 part 0 3;SPL.backup3 part 0 4;u-boot\
     part 0 5;u-boot-spl-os part 0 6;kernel part 0 8;rootfs part 0 9
dfu_alt_info_ram=kernel ram 0x80200000 0x4000000;fdt ram 0x80f80000 0x80000;ramdisk ram 0x81000000\
    0x4000000
distro_bootcmd=for target in ${boot_targets}; do run bootcmd_${target}; done
efi_dtb_prefixes=/ /dtb/ /dtb/current/
\verb|envboot=mmc| dev $\{mmcdev|; if mmc| rescan; then echo SD/MMC| found on device $\{mmcdev|; if run \setminus run \in SD/MMC| found on device $\{mmcdev|; if run \in SD
     loadbootscript; then run bootscript; else if run loadbootenv; then echo Loaded env from\
     ${bootenvfile};run importbootenv;fi;if test -n $uenvcmd; then echo Running uenvcmd ...;run\
     uenvcmd;fi;fi;fi;
eth1addr=6c:ec:eb:83:40:33
ethact=ethernet@4a100000
ethaddr=6c:ec:eb:83:40:31
fdt. addr r = 0 \times 880000000
fdtaddr=0x88000000
fdtcontroladdr=9df21ed8
fdt.file=undefined
fileaddr=80100000
filesize=b3410
findfdt=if test $board_name = A335BONE; then setenv fdtfile am335x-bone.dtb; fi; if test $board_name\
     = A335BNLT; then setenv fdtfile am335x-boneblack.dtb; fi; if test $board_name = BBBW; then setenv
     fdtfile am335x-boneblack-wireless.dtb; fi; if test $board_name = BBG1; then setenv fdtfile am335x-\
     bonegreen.dtb; fi; if test $board_name = BBGW; then setenv fdtfile am335x-bonegreen-wireless.dtb;
     fi; if test $board name = BBBL; then setenv fdtfile am335x-boneblue.dtb; fi; if test $board name = \
    A33515BB; then setenv fdtfile am335x-evm.dtb; fi; if test $board_name = A335X_SK; then setenv\ fdtfile am335x-evmsk.dtb; fi; if test $board_name = A335_ICE; then setenv fdtfile am335x-icev2.dtb;\
     fi; if test $fdtfile = undefined; then echo WARNING: Could not determine device tree to use; fi;
finduuid=part uuid mmc ${bootpart} uuid
fit bootfile=fitImage
fit loadaddr=0x88000000
importbootenv=echo Importing environment from mmc${mmcdev} ...; env import -t ${loadaddr}\
    ${filesize}
init_console=if test $board_name = A335_ICE; then setenv console tty03,115200n8;else setenv console\
    ttv00,115200n8;fi;
ipaddr=192.168.2.10
kernel addr r=0x82000000
load_efi_dtb=load ${devtype} ${devnum}:${distro_bootpart} ${fdt_addr_r} ${prefix}${efi_fdtfile}
loadaddr=0x82000000
loadbootenv=fatload mmc {\mbox{mmcdev}} \ {loadaddr} {bootenvfile} loadbootscript=load mmc {\mbox{mmcdev}} \ {loadaddr} boot.scr
loadfdt=load ${devtype} ${bootpart} ${fdtaddr} ${bootdir}/${fdtfile}
loadfit=run args_mmc; bootm ${loadaddr}#${fdtfile};
loadimage=load ${devtype} ${bootpart} ${loadaddr} ${bootdir}/${bootfile}
loadramdisk=load mmc ${mmcdev} ${rdaddr} ramdisk.gz
mmc_boot=if mmc dev ${devnum}; then setenv devtype mmc; run scan_dev_for_boot_part; fi
mmcboot=mmc dev ${mmcdev}; setenv devnum ${mmcdev}; setenv devtype mmc; if mmc rescan; then echo\
    else run mmcloados;fi;fi;fi;
mmcdev=0
mmcloados=run args_mmc; if test ${boot_fdt} = yes || test ${boot_fdt} = try; then if run loadfdt;\
    then bootz ${loadaddr} - ${fdtaddr}; else if test ${boot_fdt} = try; then bootz; else echo WARN:\
Cannot load the DT; fi; fi; else bootz; fi;
mmcrootfstype=ext4 rootwait
mtdids=nand0=nand.0
\verb| mtdparts=mtdparts=nand.0:128k(NAND.SPL)|, 128k(NAND.SPL.backup1), 128k(NAND.SPL.backup2)|, 
    \verb|backup3|, 256k(NAND.u-boot-spl-os), \verb|lm(NAND.u-boot)|, 128k(NAND.u-boot-env)|, 128k(NAND.u-boot-e
     env.backup1),8m(NAND.kernel),-(NAND.file-system)
nandargs=setenv bootargs console=${console} ${optargs} root=${nandroot} rootfstype=${nandrootfstype}\
nandboot=echo Booting from nand ...; run nandargs; nand read ${fdtaddr} NAND.u-boot-spl-os; nand\
   read ${loadaddr} NAND.kernel; bootz ${loadaddr} - ${fdtaddr}
nandroot=ubi0:rootfs rw ubi.mtd=NAND.file-system,2048
nandrootfstype=ubifs rootwait=1
netargs=setenv bootargs console=${console} ${optargs} root=/dev/nfs\
    nfsroot=${serverip}:${rootpath},${nfsopts} rw ip=dhcp
netboot=echo Booting from network ...; setenv autoload no; dhcp; run netloadimage; run netloadfdt;\
```

```
run netargs; bootz ${loadaddr} - ${fdtaddr}
netloadfdt=tftp ${fdtaddr} ${fdtfile}
netloadimage=tftp ${loadaddr} ${bootfile}
netmask=255.255.255.0
nfsopts=nolock
partitions=uuid_disk=${uuid_gpt_disk};name=rootfs,start=2MiB,size=-,uuid=${uuid_gpt_rootfs}
pxefile_addr_r=0x80100000
ramargs=setenv bootargs console=${console} ${optargs} root=${ramroot} rootfstype=${ramrootfstype}
ramboot=echo Booting from ramdisk ...; run ramargs; bootz ${loadaddr} ${rdaddr} ${fdtaddr}
ramdisk_addr_r=0x88080000
ramroot=/dev/ram0 rw
ramrootfstype=ext2
rdaddr=0x88080000
rootpath=/export/rootfs
\verb|scan_dev_for_boot=echo Scanning $$\{devtype\} $$\{devnum\}: $\{distro_bootpart\}...; for prefix in $$\{dev_for_bootpart\}...$| for prefix in $$\{dev_for_bootpart]...$| for $$\{dev_for_bootpart]...$| for $$\{dev_for_bootpart]...$| for $$\{dev_for_bootpart]...$| for $$\{dev_for_bootpart]...$| for
${boot_prefixes}; do run scan_dev_for_extlinux; run scan_dev_for_scripts; done;run scan_dev_for_efi;
scan_dev_for_boot_part=part list ${devtype} ${devnum} -bootable devplist; env exists devplist ||\
     setenv devplist 1; for distro_bootpart in ${devplist}; do if fstype ${devtype}\
${devnum}:${distro_bootpart} bootfstype; then run scan_dev_for_boot; fi; done
scan_dev_for_efi=setenv efi_fdtfile ${fdtfile}; if test -z "${fdtfile}" -a -n "${soc}"; then setenv\
     efi_fdtfile ${soc}-${board}${boardver}.dtb; fi; for prefix in ${efi_dtb_prefixes}; do if test -e\
    ${devtype} ${devnum}:${distro_bootpart} ${prefix}${efi_fdtfile}; then run load_efi_dtb; fi;done;if\
    test -e ${devtype} ${devnum}:${distro_bootpart} efi/boot/bootarm.efi; then echo Found EFI removable
    media binary efi/boot/bootarm.efi; run boot_efi_binary; echo EFI LOAD FAILED: continuing...; fi;
    setenv efi_fdtfile
scan_dev_for_extlinux=if test -e ${devtype} ${devnum}:${distro_bootpart}\
    ${prefix}extlinux/extlinux.conf; then echo Found ${prefix}extlinux/extlinux.conf; run boot_extlinux;\
    echo SCRIPT FAILED: continuing...; fi
scan_dev_for_scripts=for script in ${boot_scripts}; do if test -e ${devtype}\
    run boot_a_script; echo SCRIPT FAILED: continuing...; fi; done
scriptaddr=0x80000000
serverip=192.168.2.1
soc=am33xx
spiboot=echo Booting from spi ...; run spiargs; sf probe ${spibusno}:0; sf read ${loadaddr}\
    ${spisrcaddr} ${spiimgsize}; bootz ${loadaddr}
spibusno=0
spiimgsize=0x362000
spiroot=/dev/mtdblock4 rw
spirootfstype=jffs2
spisrcaddr=0xe0000
\verb|static_ip=$\{ipaddr\}:$\{serverip\}:$\{gatewayip\}:$\{netmask\}:$\{hostname\}::offfice for each of the context of the
stderr=serial@44e09000
stdin=serial@44e09000
stdout=serial@44e09000
test=test2
test2=echo This is another Test; printenv hostname; echo Done.
update_to_fit=setenv loadaddr $\fit_loadaddr\; setenv bootfile $\fit_bootfile\
usb_boot=usb start; if usb dev ${devnum}; then setenv devtype usb; run scan_dev_for_boot_part; fi
vendor=ti
ver=U-Boot 2017.09-rc2-00151-g2d7cb5b (Aug 23 2017 - 08:35:31 +0200)
Environment size: 9569/131068 bytes
```

### saveeny - save environment variables to persistent storage

```
=> help saveenv
saveenv - save environment variables to persistent storage

Usage:
saveenv
=>
```

All changes you make to the U-Boot environment are made in RAM only. They are lost as soon as you reboot the system. If you want to make your changes permanent you have to use the saveenv command to write a copy of the environment settings to persistent storage, from where they are automatically loaded during startup:

```
=> saveenv
Saving Environment to FAT...
writing uboot.env
FAT: Misaligned buffer address (9df01d48)
done
=>
```

#### setenv - set environment variables

```
=> help setenv
setenv - set environment variables

Usage:
setenv [-f] name value ...
   - [forcibly] set environment variable 'name' to 'value ...'
setenv [-f] name
   - [forcibly] delete environment variable 'name'
=>
```

To modify the U-Boot environment you have to use the setenv command. When called with exactly one argument, it will delete any variable of that name from U-Boot's environment, if such a variable exists. Any storage occupied for such a variable will be automatically reclaimed:

```
=> setenv foo This is an example value.
=> printenv foo
foo=This is an example value.
=> setenv foo
=> printenv foo
## Error: "foo" not defined
=>
```

When called with more arguments, the first one will again be the name of the variable, and all following arguments will (concatenated by single space characters) form the value that gets stored for this variable. New variables will be automatically created, existing ones overwritten.

```
=> printenv bar
## Error: "bar" not defined
=> setenv bar This is a new example.
=> printenv bar
bar=This is a new example.
=> setenv bar
=>
```

Remember standard shell quoting rules when the value of a variable shall contain characters that have a special meaning to the command line parser (like the \$ character that is used for variable substitution or the semicolon which separates commands). Use the backslash () character to escape such special characters, or enclose the whole phrase in apstrophes ('). Use "\${name}" for variable expansion.

```
=> setenv cons_opts 'console=tty0 console=ttyS0,\${baudrate}'
=> printenv cons_opts
cons_opts=console=tty0 console=ttyS0,${baudrate}
=> setenv cons_opts
=>
```

There is no restriction on the characters that can be used in a variable name except the restrictions imposed by the command line parser (like using backslash for quoting, space and tab characters to separate arguments, or semicolon and newline to separate commands). Even strange input like =-/|()+=| is a perfectly legal variable name in U-Boot.



#### A common mistake is to write

setenv name=value

### instead of

setenv name value

There will be no error message, which lets you believe everything went OK, but it didn't: instead of setting the variable name to the value value you tried to delete a variable with the name name=value - this is probably not what you intended! Always remember that name and value have to be separated by space and/or tab characters!

## Flattened Device Tree support

U-Boot is capable of quite comprehensive handling of the flattened device tree blob, implemented by the fdt family of commands:

```
=> help fdt
fdt - flattened device tree utility commands
fdt addr [-c] <addr> [<length>] - Set the [control] fdt location to <addr>
fdt apply <addr>
                           - Apply overlay to the {\tt DT}
<extrasize> if needed
fdt print <path> [<prop>]
                          - Recursive print starting at <path>
fdt list <path> [<prop>]
                          - Print one level starting at <path>
fdt get size <var> <path> [<prop>] - Get size of [<property>] or num nodes and store in <var>
fdt rsymem delete <index> - Delete a mem leserves
fdt chosen [<start> <end>] - Add/update the /chosen branch in the tree
NOTE: Dereference aliases by omitting the leading '/', e.g. fdt print ethernet0.
=>
```

#### fdt addr - select FDT to work on

First, the blob that is to be operated on should be stored in memory, and U-Boot has to be informed about its location by the fdt addr command. Once this command has been issued, all subsequent fdt handling commands will use the blob stored at the given address. This address can be changed later on by issuing fdt addr or fdt move command. Here's how to load the blob into memory and tell U-Boot its location:

## fdt list - print one level

Having selected the device tree stored in the blob just loaded, we can inspect its contents. As an FDT usually is quite extensive, it is easier to get information about the structure by looking at selected levels rather than full hierarchies. fdt list allows us to do exactly this. Let's have a look at the hierarchy one level below the cpus node:

```
=> fdt list /cpus
cpus {
    #address-cells = <0x00000001>;
    #size-cells = <0x00000000>;
    cpu@0 {
      };
};
=>
```

## fdt print - recursive print

To print a complete subtree we use fdt print. In comparison to the previous example it is obvious that the whole subtree is printed:

#### fdt mknode - create new nodes

fdt mknode can be used to attach a new node to the tree. We will use the fdt list command to verify that the new node has been created and that it is empty:

```
=> fdt list /
      #address-cells = <0x00000001>;
      #size-cells = <0x00000001>;
      compatible = "ti,am335x-evm",
                                     "ti,am33xx";
      interrupt-parent = <0x00000001>;
      model = "TI AM335x EVM";
      chosen {
      aliases {
      memory {
      };
      cpus {
      pmu {
      soc {
      ocp {
      fixedregulator@0 {
      fixedregulator@1 {
      fixedregulator@2 {
      matrix_keypad@0 {
```

```
volume_keys@0 {
       backlight {
       };
       panel {
       sound {
=> fdt mknode / testnode
=> fdt list /
/ {
       #address-cells = <0x00000001>;
       #size-cells = <0x00000001>;
compatible = "ti,am335x-evm", "ti,am33xx";
       interrupt-parent = <0x00000001>;
model = "TI AM335x EVM";
       testnode {
       chosen {
       aliases {
       memory {
       cpus {
       pmu {
};
       soc {
       ocp {
       fixedregulator@0 {
       fixedregulator@1 {
       fixedregulator@2 {
       matrix_keypad@0 {
       volume_keys@0 {
       backlight {
       panel {
       sound {
=> fdt list /testnode
testnode {
```

## fdt set - set node properties

Now, let's create a property at the newly created node; again we'll use fdt list for verification:

```
=> fdt set /testnode testprop
=> fdt set /testnode testprop testvalue
=> fdt list /testnode
testnode {
    testprop = "testvalue";
};
=>
```

## fdt rm - remove nodes or properties

The fdt rm command is used to remove nodes and properties. Let's delete the test property created in the previous paragraph and verify the results:

```
=> fdt rm /testnode testprop
=> fdt list /testnode
testnode {
=> fdt rm /testnode
=> fdt list /
      #address-cells = <0x00000001>;
      #size-cells = <0x00000001>;
compatible = "ti,am335x-evm", "ti,am33xx";
      interrupt-parent = <0x00000001>;
      model = "TI AM335x EVM";
chosen {
      aliases {
      };
      memory {
      cpus {
      };
      pmu {
      };
      soc {
      };
      ocp {
      fixedregulator@0 {
      fixedregulator@1 {
      fixedregulator@2 {
      matrix_keypad@0 {
      volume_keys@0 {
      backlight {
      panel {
      };
      sound {
```

## fdt move - move FDT blob to new address

To move the blob from one memory location to another we will use the fdt move command. Besides moving the blob, it makes the new address the "active" one - similar to fdt addr:

```
soc {
       };
       ocp {
       fixedregulator@0 {
       fixedregulator@1 {
       fixedregulator@2 {
       matrix_keypad@0 {
       };
       volume_keys@0 {
       backlight {
       panel {
       };
       sound {
=> fdt mknod / foobar
=> fdt list /
/ {
      chosen {
       aliases {
       memory {
       };
       cpus {
       };
       pmu {
       };
       soc {
       };
       ocp {
       fixedregulator@0 {
       fixedregulator@1 {
       };
fixedregulator@2 {
       };
       matrix_keypad@0 {
       };
       volume_keys@0 {
       backlight {
       panel {
       sound {
};
=>
=> fdt addr ${fdt_addr_r}
=> fdt list /
/ {
       #address-cells = <0x00000001>;
       #size-cells = <0x00000001>;
compatible = "ti,am335x-evm", "ti,am33xx";
       interrupt-parent = <0x000000001>;
model = "TI AM335x EVM";
chosen {
       };
aliases {
       memory {
       };
```

```
cpus {
    };
    pmu {
    };
    soc {
    };
    ocp {
    };
    fixedregulator@0 {
    };
    fixedregulator@1 {
    };
    fixedregulator@2 {
    };
    matrix_keypad@0 {
    };
    volume_keys@0 {
    };
    backlight {
    };
    panel {
    };
    sound {
    };
};
};
=>
```

## fdt chosen - fixup dynamic info

One of the modifications made by U-Boot to the blob before passing it to the kernel is the addition of the /chosen node. Linux 2.6 Documentation/powerpc/booting-without-of.txt says that this node is used to store "some variable environment information, like the arguments, or the default input/output devices." To force U-Boot to add the /chosen node to the current blob, fdt chosen command can be used. Let's now verify its operation:

```
=> fdt list /
       #address-cells = <0x00000001>;
       #size-cells = <0x00000001>;
compatible = "ti,am335x-evm", "ti,am33xx";
       interrupt-parent = <0x00000001>;
model = "TI AM335x EVM";
       chosen {
       aliases {
       memory {
       cpus {
       pmu {
       };
       soc {
       };
       ocp {
       fixedregulator@0 {
       fixedregulator@1 {
       fixedregulator@2 {
       matrix_keypad@0 {
       volume_keys@0 {
       backlight {
       };
       panel {
       sound {
```

```
=> fdt chosen
=> fdt list /
        #address-cells = <0x00000001>;
        #size-cells = <0x00000001>;
compatible = "ti,am335x-evm", "ti,am33xx";
       interrupt-parent = <0x000000001>;
model = "TI AM335x EVM";
chosen {
        aliases {
       memory {
        cpus {
       pmu {
};
        soc {
        };
        ocp {
        fixedregulator@0 {
        fixedregulator@1 {
        fixedregulator@2 {
        };
        matrix_keypad@0 {
        };
        volume_keys@0 {
        };
        backlight {
       panel {
        sound {
        };
};
=> fdt list /chosen
chosen {
       stdout-path = "/ocp/serial@44e09000";
tick-timer = "/ocp/timer@48040000";
};
=>
```

Note: fdt boardsetup performs board-specific blob updates, most commonly setting clock frequencies, etc. Discovering its operation is left as an excercise for the reader.

# links