Rechnernetze - Computer Networks

Problem Set 8: Internetworking & Routing

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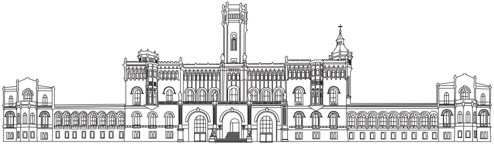

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1.1 Difference between forwarding, switching and routing:

- **Forwarding:** router-local action of transferring a packet from an input link interface to the appropriate output link interface.
- **Switching:** moving packets between devices on the same network.
- **Routing:** a network-wide process that determine the end-to-end paths that packets take from source to destination.

1.2 Link-state vs. distance-vector routing

- **Link-state routing**
  - Nodes intercommunicate with all other nodes via broadcast ...
  - and provide the costs of the directly connected links
  - Requires knowledge of the entire network topology
- **Distance-vector routing**
  - Only neighbouring nodes exchange information ...
  - they provide each least-cost estimates from itself to all other (known) nodes
  - Requires only connections to the neighbours and no topology information

1.3 Link cost selection

- Can be chosen arbitrarily
- Often associated with a network metric, e.g., bandwidth, delay
- Can force traffic to flow along a certain path

1.4 Drawbacks of dynamic link weights

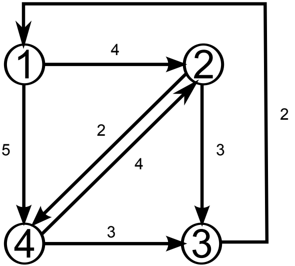
- More responsive to network changes
- Can cause routing instabilities such as routing loops and oscillations

1.5 Internet routing

- Interconnected autonomous systems (ASes)
- Intra-domain (local) routing within each AS
- Inter-domain routing: edge routers forward packets to neighbouring ASes

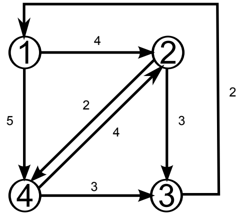
2.1 Plot the topology:

$$E = \begin{pmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \end{pmatrix}, \quad C = \begin{pmatrix} 0 & 4 & 0 & 5 \\ 0 & 0 & 3 & 2 \\ 2 & 0 & 0 & 0 \\ 0 & 4 & 3 & 0 \end{pmatrix}$$



2.2 Network Graph, Reachability

$$E = \begin{pmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \end{pmatrix}$$

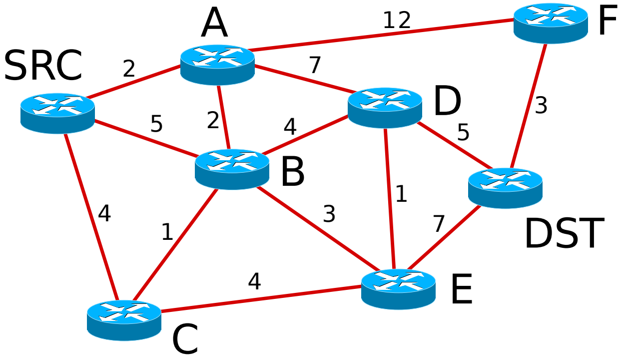


- E denotes the nodes that are reachable in one step
- E^2 denotes the number of two step paths
- E^3 denotes the number of three step paths …

$$E^2 = \begin{pmatrix} 0 & 1 & 2 & 1 \\ 1 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 1 \end{pmatrix}, \quad E^3 = \begin{pmatrix} 2 & 1 & 2 & 1 \\ 1 & 1 & 1 & 2 \\ 0 & 1 & 2 & 1 \\ 1 & 2 & 1 & 1 \end{pmatrix}, \quad E^4 = \begin{pmatrix} 2 & 3 & 2 & 3 \\ 1 & 3 & 3 & 2 \\ 2 & 1 & 2 & 1 \\ 1 & 2 & 3 & 3 \end{pmatrix}$$

$$E + E^2 + E^3 + E^4 = \begin{pmatrix} 4 & 6 & 6 & 6 \\ 3 & 5 & 6 & 5 \\ 3 & 3 & 4 & 3 \\ 3 & 5 & 6 & 5 \end{pmatrix}$$

Since all matrix elements are non-zero, all nodes are reachable.



Least-cost path SRC → DST ?

Denote

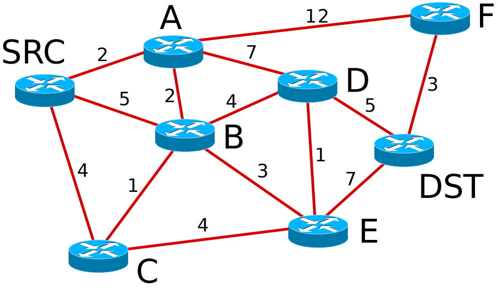
- $c(i, j)$ the cost of link $e_{i,j}$ from node i to node j
  - $c(i, j) = \infty$ if link $e_{i,j}$ does not exist
- $d(i)$ cost (distance) from the source to node i
- $p(i)$ predecessor of node i on the least-cost path from the source to node i
- M set of nodes for which least-cost paths are uniquely determined

3.1 Dijkstra's Algorithm

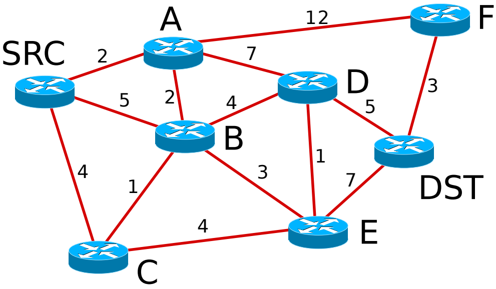
$M = \{a\}$
for all nodes i **do**
  if link $e_{a,i}$ exists **then**
    $d(i) = c(a,i)$
  else
    $d(i) = \infty$
  end if
end for
repeat
  find a node j not in M such that $d(j)$ is minimal
  add j to M
  for all nodes k not in M **do**
    if $d(k) > d(j) + c(j,k)$ **then**
      $d(k) = d(j) + c(j,k)$
      $p(k) = j$
    end if
  end for
until all nodes in M

3.1 Dijkstra's Algorithm - Example

step	M	d(A)	d(B)	d(C)	d(D)	d(E)	d(F)	d(DST)
init	SRC	$\mathbf{2}_{SRC}$	5_{SRC}	4_{SRC}	∞	∞	∞	∞

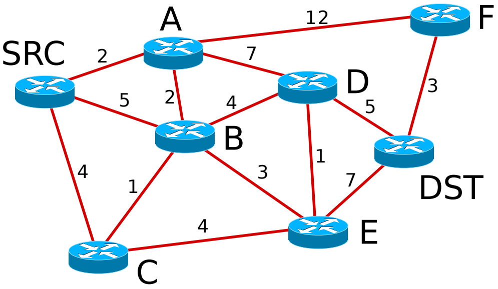


step	M	d(A)	d(B)	d(C)	d(D)	d(E)	d(F)	d(DST)
init	SRC	$\mathbf{2}_{SRC}$	5_{SRC}	4_{SRC}	∞	∞	∞	∞
1	SRC,A		$\mathbf{4}_{A}$	$\mathbf{4}_{SRC}$	9_{A}	∞	14_{A}	∞



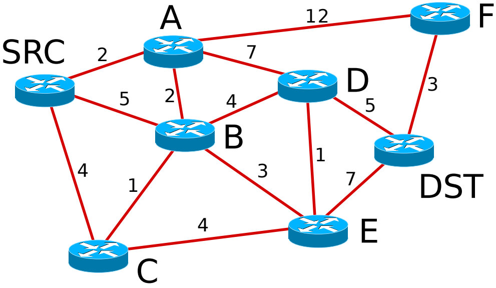
3.1 Dijkstra's Algorithm - Example

step	M	d(A)	d(B)	d(C)	d(D)	d(E)	d(F)	d(DST)
init	SRC	$\mathbf{2}_{SRC}$	5_{SRC}	4_{SRC}	∞	∞	∞	∞
1	SRC,A		$\mathbf{4}_{A}$	$\mathbf{4}_{SRC}$	9_{A}	∞	14_{A}	∞
2.1	SRC,A,B			$\mathbf{4}_{SRC}$	8_{B}	7_{B}	14_{A}	∞



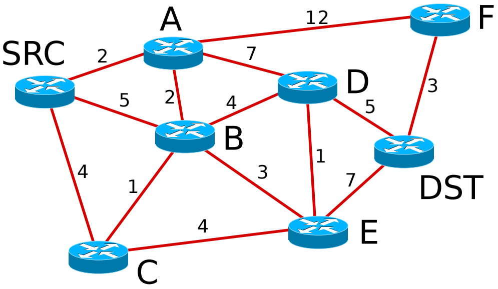
3.1 Dijkstra's Algorithm - Example

step	M	d(A)	d(B)	d(C)	d(D)	d(E)	d(F)	d(DST)
init	SRC	$\mathbf{2}_{SRC}$	5_{SRC}	4_{SRC}	∞	∞	∞	∞
1	SRC,A		$\mathbf{4}_{A}$	$\mathbf{4}_{SRC}$	9_{A}	∞	14_{A}	∞
2.1	SRC,A,B			$\mathbf{4}_{SRC}$	8_{B}	7_{B}	14_{A}	∞
2.2	SRC,A,C		$\mathbf{4}_{A}$		9_{A}	8_{C}	14_{A}	∞

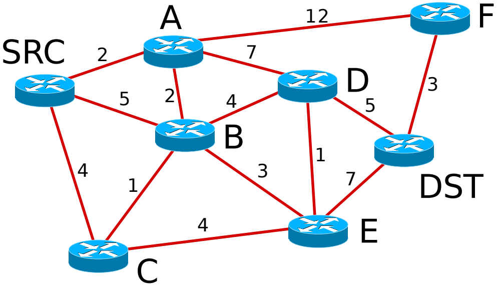


3.1 Dijkstra's Algorithm - Example

step	M	d(A)	d(B)	d(C)	d(D)	d(E)	d(F)	d(DST)
init	SRC	$\mathbf{2}_{SRC}$	5_{SRC}	4_{SRC}	∞	∞	∞	∞
1	SRC,A		$\mathbf{4}_{A}$	$\mathbf{4}_{SRC}$	9_{A}	∞	14_{A}	∞
2	SRC,A,B			$\mathbf{4}_{SRC}$	8_{B}	7_{B}	14_{A}	∞
3	SRC,A,B,C				8_{B}	$\mathbf{7}_{B}$	14_{A}	∞

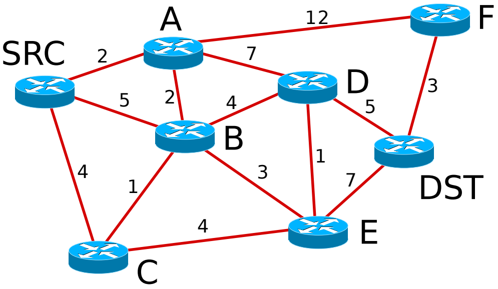


step	M	d(A)	d(B)	d(C)	d(D)	d(E)	d(F)	d(DST)
init	SRC	$\mathbf{2}_{SRC}$	5_{SRC}	4_{SRC}	∞	∞	∞	∞
1	SRC,A		$\mathbf{4}_{A}$	$\mathbf{4}_{SRC}$	9_{A}	∞	14_{A}	∞
2	SRC,A,B			$\mathbf{4}_{SRC}$	8_{B}	7_{B}	14_{A}	∞
3	SRC,A,B,C				8_{B}	$\mathbf{7}_{B}$	14_{A}	∞
4	SRC,A,B,C,E				$\mathbf{8}_{B}$		14_{A}	14_{E}

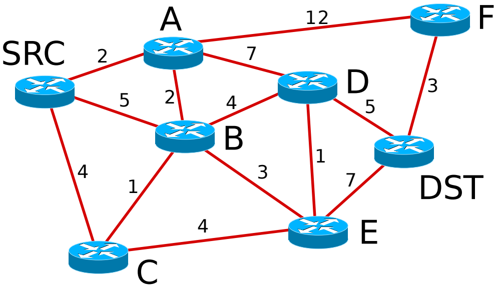


3.1 Dijkstra's Algorithm - Example

step	M	d(A)	d(B)	d(C)	d(D)	d(E)	d(F)	d(DST)
init	SRC	$\mathbf{2}_{SRC}$	5_{SRC}	4_{SRC}	∞	∞	∞	∞
1	SRC,A		$\mathbf{4}_{A}$	$\mathbf{4}_{SRC}$	9_{A}	∞	14_{A}	∞
2	SRC,A,B			$\mathbf{4}_{SRC}$	8_{B}	7_{B}	14_{A}	∞
3	SRC,A,B,C				8_{B}	$\mathbf{7}_{B}$	14_{A}	∞
4	SRC,A,B,C,E				$\mathbf{8}_{B}$		14_{A}	14_{E}
5	SRC,A,B,C,E,D						14_{A}	$\mathbf{13}_{D}$



step	M	d(A)	d(B)	d(C)	d(D)	d(E)	d(F)	d(DST)
init	SRC	$\mathbf{2}_{SRC}$	5_{SRC}	4_{SRC}	∞	∞	∞	∞
1	SRC,A		$\mathbf{4}_A$	$\mathbf{4}_{SRC}$	9_A	∞	14_A	∞
2	SRC,A,B			$\mathbf{4}_{SRC}$	8_B	7_B	14_A	∞
3	SRC,A,B,C				8_B	$\mathbf{7}_B$	14_A	∞
4	SRC,A,B,C,E				$\mathbf{8}_B$		14_A	14_E
5	SRC,A,B,C,E,D						14_A	$\mathbf{13}_D$
6	SRC,A,B,C,E,D,DST						$\mathbf{14}_A$	



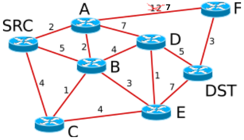
step	M	d(A)	d(B)	d(C)	d(D)	d(E)	d(F)	d(DST)
init	SRC	$\mathbf{2}_{SRC}$	5_{SRC}	4_{SRC}	∞	∞	∞	∞
1	SRC,A		$\mathbf{4}_{A}$	$\mathbf{4}_{SRC}$	9_{A}	∞	14_{A}	∞
2	SRC,A,B			$\mathbf{4}_{SRC}$	8_{B}	7_{B}	14_{A}	∞
3	SRC,A,B,C				8_{B}	$\mathbf{7}_{B}$	14_{A}	∞
4	SRC,A,B,C,E				$\mathbf{8}_{B}$		14_{A}	14_{E}
5	SRC,A,B,C,E,D						14_{A}	$\mathbf{13}_{D}$
6	SRC,A,B,C,E,D,DST						$\mathbf{14}_{A}$	
7	SRC,A,B,C,E,D,DST,F							

The least-cost path from SRC to DST has a cost of **13** over the path **SRC-A-B-D-DST**.

3.2 Link Cost Change

Link *A*-*F* Cost: $12 \to 7$

step	M	d(A)	d(B)	d(C)	d(D)	d(E)	d(F)	d(DST)
init	SRC	$\mathbf{2}_{SRC}$	5_{SRC}	4_{SRC}	∞	∞	∞	∞
1	SRC,A		$\mathbf{4}_A$	$\mathbf{4}_{SRC}$	9_A	∞	$14_A \cancel{14_A} 9_A$	∞
2	SRC,A,B			$\mathbf{4}_{SRC}$	8_B	7_B	$14_A \cancel{14_A} 9_A$	∞
3	SRC,A,B,C				8_B	$\mathbf{7}_B$	$14_A \cancel{14_A} 9_A$	∞
4	SRC,A,B,C,E				$\mathbf{8}_B$		$14_A \cancel{14_A} 9_A$	14_E
5	SRC,A,B,C,E,D						$14_A \cancel{14_A} \mathbf{9}_A$	$\mathbf{13}_D$ 13_D
6	SRC,A,B,C,E,D,DST ~~SRC,A,B,C,E,D,DST~~ SRC,A,B,C,E,D,F						$14_A \cancel{14_A}$	$\mathbf{12}_F$
7	SRC,A,B,C,E,D,DST,F ~~SRC,A,B,C,E,D,DST,F~~ SRC,A,B,C,E,D,F,DST							



The least-cost path from SRC to DST has then a cost of **12** over the path **SRC-A-F-DST** (instead of $SRC - A - B - D - DST$).

Denote

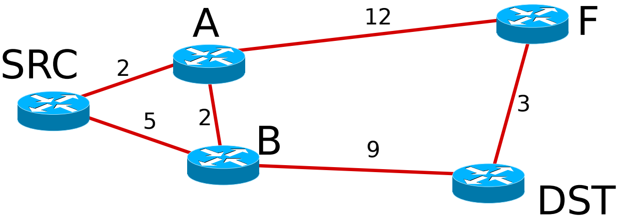
- D^x distance table of node x
  - example: $D^x(y,z) = 4$ route to destination y has cost 4 via next hop z
- F^x forwarding table of node x
  - example: $F^x(y) = (4,z)$ shortest path to destination y via next hop z has cost 4

Mode of operation

- node z computes the shortest path to destination y as $c(z,y) = \min_w\{D^z(y,w)\}$
- node z stores the next hop w that achieves the minimum in its forwarding table $F^z(y) = (c(z,y),w)$
- node z sends its forwarding table to it's neighboring node x
- node x computes $D^x(y,z) = c(x,z) + c(z,y)$

4 Distance Vector Routing

- **for** all neighbors y **do**
  - $D^x(y,y) = c(x,y)$
- **end for**
- **for** all destinations z **do**
  - send $\min_w\{D^x(z,w)\}$ to all neighbors y
- **end for**
- **loop**
  - **if** $c(x,y)$ for neighbor y changes by d **then**
    - update $D^x(z,y) = D^x(z,y) + d$ for all destinations z
  - **else if** updated $c(y,z)$ received from neighbor y **then**
    - recompute $D^x(z,y) = c(x,y) + c(y,z)$
  - **end if**
  - **if** a new $\min_w\{D^x(z,w)\}$ exists for any destination z **then**
    - send new $\min_w\{D^x(z,w)\}$ to all neighbors y
  - **end if**
- **end loop**



Least-cost path SRC $\rightarrow$ DST ?

4.1 Distance Vector Algorithm Example

initialization: the distance vector of each host x is initialized with the link cost $c(x, y)$ to the direct node neighbors y:
$D^x(y, y) = c(x, y)$

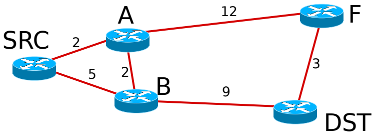
D^S	A	B
A	2	
B		5
F		
D		

D^A	S	B	F
S	2		
B		2	
F			12
D			

D^B	S	A	D
S	5		
A		2	
F			
D			9

D^F	A	D
S		
A	12	
B		
D		3

D^D	B	F
S		
A		
B	9	
F		3



Each node sends an update to all of its neighbors.

T=1

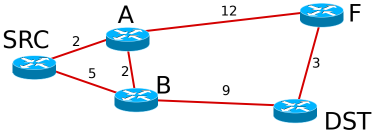
D^S	A	B
A	**2**	7
B	**4**	5
F	**14**	
D		**14**

D^A	S	B	F
S	2	7	
B	7	**2**	
F			**12**
D		**11**	15

D^B	S	A	D
S	5	**4**	
A	7	**2**	
F		14	**12**
D			**9**

D^F	A	D
S	**14**	
A	**12**	
B	14	**12**
D		**3**

D^D	B	F
S	**14**	
A	**11**	15
B	**9**	
F		**3**



Each node sends an update to all of its neighbors when a cheaper path is discovered

4.1 Distance Vector Algorithm Example

T=2

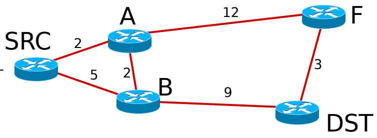
D^S	A	B
A	**2**	7
B	**4**	5
F	**14**	16
D	<u>**13**</u>	14

D^A	S	B	F
S	**2**	6	26
B	6	**2**	24
F	16	14	**12**
D	16	**11**	15

D^B	S	A	D
S	5	**4**	23
A	7	**2**	20
F	19	14	**12**
D	19	13	**9**

D^F	A	D
S	**14**	17
A	**12**	14
B	14	**12**
D	23	**3**

D^D	B	F
S	<u>**13**</u>	17
A	**11**	15
B	**9**	15
F	21	**3**



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T=3

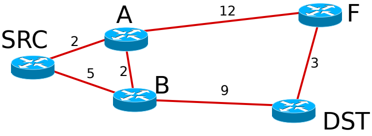
D^S	A	B
A	**2**	7
B	**4**	5
F	**14**	16
D	**13**	14

D^A	S	B	F
S	**2**	6	26
B	6	**2**	24
F	16	14	**12**
D	15	**11**	15

D^B	S	A	D
S	5	**4**	22
A	7	**2**	20
F	19	14	**12**
D	17	13	**9**

D^F	A	D
S	**14**	16
A	**12**	14
B	14	**12**
D	23	**3**

D^D	B	F
S	**13**	17
A	**11**	15
B	**9**	15
F	21	**3**

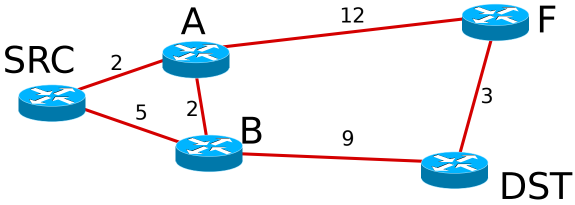


Distance vectors reached stable-state, no more updates sent

Example, Forwarding table for A after step 3:

D^A	S	B	F
S	**2**	6	26
B	6	**2**	24
F	16	14	**12**
D	15	**11**	15

F^A	
S	2,S
B	2,B
F	12,F
D	11,B



Path SRC → DST ?

After t=1: SRC → B → DST

After t=2: SRC → A → B → DST