1. Fix Y-axes on all of the stability zones plots

Done!

1. Drawing red rectangle

Done!

1. Check the maximum force (limits)

actionThreshold = 1; cartForce = 10; forceFactor = 2

self.action\_space = spaces.Box(-self.actionThreshold, self.actionThreshold, (1,), dtype=np.float32)

force = action \* self.cartForce \* self.forceFactor

1. Find a way to show control force

Adjust the code with lControl

1. Marking epochs after the model saving (for stability zones)

Done

1. Make stability zones for different agents via one single run (dif epochs)

Need to make stability zones for the created agents for A2C

1. Presentation on Thursday

Done

1. Observations for RL
2. Find a place where the action is being read by environment
3. Start running tests for double pendulum
4. Send SSH key
5. Force for the already learned agent