

Tasks	Priority	day1 2h	day2 2h	day3 2h	day4 2h
Sprint 3					
Image acquisition	1				
Manual calibration of a homography (Python, opencv)	1				
Automatic detection of features in the pattern (Python o opencv)	3				
Automatic calibration (Python o opencv)	3				
Localization of objects	1				
Communication with the robot	2				
Stereovision	?				
Graphical interface	1				
Demo & Pecha Kucha preparation	1				
Presentation	1				