

| Tasks | Priority | day1 2h | day2 2h | day3 2h | day4 2h |
|--|----------|------------|------------|------------|------------|
| Sprint 3 | | | | | |
| Image acquisition | 1 | | | | |
| Manual calibration of a homography (Python, opencv) | 1 | | | | |
| Automatic detection of features in the pattern (Python o opencv) | 3 | | | | |
| Automatic calibration (Python o opencv) | 3 | | | | |
| Localization of objects | 1 | | | | |
| Comunication with the robot | 2 | | | | |
| Stereovision | ? | | | | |
| Graphical interface | 1 | | | | |
| Demo & Pecha Kucha preparation | 1 | | | | |
| Presentation | 1 | | | | |