DetectRotationsV2

January 13, 2022

```
[27]: import numpy as np
      import pandas as pd
      import matplotlib.pyplot as plt
      from matplotlib.backends.backend_pdf import PdfPages
      from datetime import timedelta
      from scipy import signal
[28]: Player = 9
      Game = 2
      df_Player = pd.read_csv('matrix_Player_' + str(Player) + '_game_' + str(Game) +__

¬'.csv')
      df_Player.columns =__
       →['frAcc','frRoAcc','frDispl','frRoAng','frSpeed','timeLine','frameRotationalSpeedX','frameR
      df_Action = pd.read_csv('Ned_DUI_Game_' + str(Game) + '.csv')
      df_Player
[28]:
                        frRoAcc frDispl frRoAng
                                                      frSpeed
                                                               timeLine
                 frAcc
                                      0.0 0.00000 0.000000
                                                                   0.01
      0
              0.000000
                             0.0
      1
              0.000000
                             0.0
                                      0.0 0.00000
                                                     0.000000
                                                                   0.02
      2
                             0.0
                                      0.0 0.00000
                                                                   0.03
              0.000000
                                                     0.000000
      3
                                      0.0 0.00000
                                                    0.000000
              0.000000
                             0.0
                                                                   0.04
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                                      0.0 0.00000
                                                                   0.05
              0.000000
                                                     0.000000
      754220 -0.030424
                          4981.9
                                   6585.3 -0.11980 -0.001860
                                                                7542.20
                                   6585.3 -0.11723 -0.002164
      754221 0.062668
                          4981.9
                                                                7542.20
      754222 0.019899
                          4981.9
                                   6585.2 -0.13407 -0.001537
                                                                7542.20
      754223
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      754224
                   NaN
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              {\tt frameRotationalSpeedX}
                                                              {\tt frameRotationalSpeedZ}
                                      frameRotationalSpeedY
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      4
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      754220
                             0.97222
                                                      2.4578
                                                                            -0.98778
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754221
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                      754224
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                      754220
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                      754223
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                      754224
                                                                                                    0.081667
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                                                    frRoSpeed
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                      3
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                      754220
                                                          0.25656
                                                  -1.68370
                      754221
                      754222
                                                                      NaN
                      754223
                                                                          NaN
                      754224
                                                                          NaN
                      [754225 rows x 13 columns]
[29]: | # -----
                      #LowPass Filter
                      #Lowpass filter design for rotation and wheelspeed to improve accuracy of code_
                       \hookrightarrow (Butterworth filter)
                      df_Filter = df_Player
                      df_Filter = df_Filter.fillna(0)
                      Order = 5
                      cutoff_freq = 1.5
                      sampling_freq = 100
```

sampling_duration = len(df_Filter.wheelRotationalSpeedX)/100

```
normalized_cutoff_freq = 2 * cutoff_freq / sampling_freq
numerator_coeffs, denominator_coeffs = signal.butter(Order,__
→normalized_cutoff_freq)
filtered WheelRotationspeed = signal.lfilter(numerator coeffs,
→denominator_coeffs, df_Filter.wheelRotationalSpeedX)
filtered_FrameRotationspeed = signal.lfilter(numerator_coeffs,__
→denominator_coeffs, df_Filter.frameRotationalSpeedZ)
       #Operations
#Play with different operations to see clearer patterns
Sub = filtered_WheelRotationspeed + filtered_FrameRotationspeed
\#Old\_Conv1 = filtered\_FrameRotationspeed / filtered\_WheelRotationspeed
Conv1 = (abs(filtered FrameRotationspeed)+abs(filtered WheelRotationspeed))/
→filtered_WheelRotationspeed
\#Diff = arr[i+1] - arr[i]
DiffFrame = np.diff(df_Filter.frameRotationalSpeedZ,n=1)
DiffFrame = np.insert(DiffFrame, 0, 0)
DiffWheel = np.diff(df_Filter.wheelRotationalSpeedX,n=1)
DiffWheel = np.insert(DiffWheel,0,0)
Multi = filtered_WheelRotationspeed + filtered_FrameRotationspeed
#This isn't used
#Set all data into a datafram
Data = pd.DataFrame({'Time':df_Player.timeLine,'WheelRotationspeed':
→filtered_WheelRotationspeed,
                     'FrameRotationspeed':filtered_FrameRotationspeed,
                     'Sub':Sub ,'Conv':Conv1, 'DiffFrame':DiffFrame,
→ 'DiffWheel':DiffWheel},
                     columns=['Time', |
→ 'WheelRotationspeed', 'FrameRotationspeed', 'Sub', 'Conv', 'DiffFrame', 'DiffWheel'])
#Convert data into chunks of n/100 of a second
```

```
n = 50 #chunk row size
Data_chunks = [Data[i:i+n] for i in range(0,Data.shape[0],n)]
#Search for the sprints
Startsprint = []
Stopsprint = []
Sprinting = False
Stop = True
#Use Sub en Conv to detect sprints
for chunks in Data_chunks:
    if abs(chunks['Conv'].max()) < 3 and chunks['Sub'].mean() > 300 and
Startsprint.append(chunks['Time'].min())
       Sprinting = True
       Stop = False
   elif abs(chunks['Conv'].max() < 3) and chunks['Sub'].mean() > 300 and
⇒chunks['WheelRotationspeed'].min() > 200:
       Sprinting = True
       Stop = False
   elif Stop == False:
       Stopsprint.append(chunks['Time'].min())
       Sprinting = False
       Stop = True
#Use wheelrotation, framerotation and conv to detect rotations
Startrotate = []
Stoprotate = []
Rotate = False
Stop = True
count = 0
for chunks in Data_chunks:
   if abs(chunks['FrameRotationspeed'].max()) > 75 and abs(chunks['Conv'].
→mean()) > 1.15 and count!=29 and Rotate == False:
       #this condition count!=29 is to make sure that it doesn't start a_{\sqcup}
\rightarrowrotation in the last
       #point of the graph because that way it would never enc
       Startrotate.append(chunks['Time'].min())
       Rotate = True
       Stop = False
```

```
elif abs(chunks['FrameRotationspeed'].max()) > 75 and abs(chunks['Conv'].
 →mean()) > 1.15 and count == 29 and Rotate == True:
        #this comes due to the need of matching sizes (between startsprint and \Box
⇒stopsprint), as in one fast defense
        #theres a rotation that never ends in the plot, so I'm forcing it (had
 →to add Rotate == True so that this condition only
       #happens when a rotation has started before the last point of the graph)
       Stoprotate.append(chunks['Time'].min())
       Rotate = False
       Stop = True
   elif abs(chunks['FrameRotationspeed'].max()) > 75 and abs(chunks['Conv'].
 →mean()) > 1.15:#si abs menor que num sique siendo rotation
       #Rotate =True is implicit
       Rotate = True
       Stop = False
   elif Stop == False : #Rotate==True and the previous conditions aren't met, ...
 \hookrightarrow thats implicit
       Stoprotate.append(chunks['Time'].min())
       Rotate = False
       Stop = True
   count +=1
   #Pop small sprints out
#Filter Sprints by lenght, if length is below 2 delete sprint
Deleted = 0
if len(Startsprint) > len(Stopsprint):
   Startsprint.pop(-1)
if len(Startsprint) == len(Stopsprint):
   for i in range(0,len(Startsprint)-1):
       if (Stopsprint[i-Deleted] - Startsprint[i-Deleted]) < 5:</pre>
           Startsprint.pop(i-Deleted)
           Stopsprint.pop(i-Deleted)
           Deleted = Deleted + 1
# -----
```

/tmp/ipykernel_48350/3389962776.py:28: RuntimeWarning: invalid value encountered

```
in true_divide
   Conv1 = (abs(filtered_FrameRotationspeed)+abs(filtered_WheelRotationspeed))/fi
ltered_WheelRotationspeed
```

```
[30]: Starting =[]
      Stopping = []
      df_Filter = df_Player
      df_Filter = df_Filter.fillna(0)
      Order = 5
      cutoff_freq = 1.5
      sampling_freq = 100
      sampling_duration = len(df_Filter.wheelRotationalSpeedX)/100
      normalized_cutoff_freq = 2 * cutoff_freq / sampling_freq
      numerator_coeffs, denominator_coeffs = signal.butter(Order,__
       →normalized_cutoff_freq)
      filtered WheelRotationspeedX = signal.lfilter(numerator_coeffs,_
       →denominator_coeffs, df_Filter.wheelRotationalSpeedX)
      filtered FrameRotationspeedZ = signal.lfilter(numerator coeffs,
       →denominator_coeffs, df_Filter.frameRotationalSpeedZ)
      df_Player['Sum_WheelX_FrameZ'] = df_Player.wheelRotationalSpeedX + df_Player.
       \hookrightarrowframeRotationalSpeedZ
      df_Player['Div_FrameZ_WheelX'] = df_Player.frameRotationalSpeedZ / df_Player.
      →wheelRotationalSpeedX
      df_Player['Filt_WheelX'] = filtered_WheelRotationspeedX
      df_Player['Filt_FrameZ'] = filtered_FrameRotationspeedZ
      print(Startsprint, Stopsprint)
      df_Player['Action'] = ""
      for i in range(0,len(Startsprint)):
          df_Player['Action'].iloc[int(Startsprint[i]*100):int(Stopsprint[i]*100)] = 1
      df_Player.to_csv('matrix_Player_' + str(Player) + '_game_' + str(Game) +__
      →' All Action.csv')
```

[997.01, 1019.0, 1041.5, 1062.5, 1078.0, 1086.0, 1093.5, 1105.5, 1138.0, 1161.0, 1181.5, 1201.0, 1232.5, 1248.5, 1257.0, 1427.5, 1485.5, 1511.5, 1538.0, 1566.0, 1593.0, 1626.5, 1659.5, 1676.0, 1734.0, 1832.0, 1912.0, 2216.5, 2224.5, 2235.5,

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2433.5, 2465.5, 2490.0, 2558.0, 2598.0, 2631.0, 2647.0, 2671.5, 2684.0, 2786.0,
     2800.0, 2850.0, 2873.0, 2888.5, 2940.0, 2956.5, 3004.5, 3025.5, 3049.0, 3074.0,
     3093.5, 3118.5, 3137.5, 3156.0, 3256.0, 3276.0, 3329.5, 3372.0, 3506.5, 3530.0,
     3555.5, 3602.5, 3628.0, 3654.0, 3685.0, 3703.5, 5040.0, 5053.5, 5080.5, 5095.0,
     5135.5, 5146.5, 5177.0, 5207.0, 5324.0, 5345.5, 5369.0, 5400.5, 5411.0, 5434.0,
     5462.0, 5510.5, 5594.5, 5621.0, 5704.0, 5745.5, 5842.5, 5895.0, 5927.5, 5955.5,
     5974.5, 5993.0, 6044.5, 6059.5, 6076.5, 6897.0, 6912.5, 6923.0, 6950.5, 6963.0,
     6981.0, 6998.0, 7051.0, 7186.5, 7206.0, 7225.5, 7249.0, 7281.0] [1008.0, 1041.0,
     1047.0, 1074.0, 1083.5, 1093.0, 1103.0, 1121.0, 1148.5, 1181.0, 1186.5, 1219.5,
     1246.0, 1254.0, 1262.0, 1433.5, 1490.5, 1516.5, 1543.5, 1571.0, 1598.0, 1632.0,
     1665.5, 1681.5, 1739.0, 1837.0, 1917.5, 2221.5, 2231.5, 2241.5, 2441.0, 2471.0,
     2495.0, 2566.5, 2607.5, 2640.0, 2654.5, 2680.0, 2689.5, 2795.0, 2807.0, 2856.0,
     2879.0, 2894.0, 2946.5, 2963.5, 3011.5, 3031.0, 3057.0, 3081.0, 3100.0, 3126.0,
     3144.0, 3162.5, 3264.5, 3283.0, 3335.0, 3378.0, 3513.5, 3536.0, 3563.5, 3611.5,
     3634.5, 3661.0, 3691.5, 3708.5, 5046.0, 5079.0, 5092.5, 5132.5, 5146.0, 5172.0,
     5201.0, 5227.5, 5333.0, 5353.0, 5377.0, 5405.5, 5419.5, 5440.0, 5470.5, 5519.0,
     5604.5, 5626.5, 5710.5, 5755.5, 5848.5, 5903.5, 5934.0, 5962.0, 5981.0, 6001.0,
     6051.0, 6067.0, 6089.0, 6903.0, 6918.5, 6928.0, 6955.5, 6977.0, 6989.5, 7008.0,
     7057.5, 7193.0, 7211.5, 7234.5, 7254.5, 7285.0]
     /opt/jupyterhub/anaconda/lib/python3.8/site-
     packages/pandas/core/indexing.py:1637: SettingWithCopyWarning:
     A value is trying to be set on a copy of a slice from a DataFrame
     See the caveats in the documentation: https://pandas.pydata.org/pandas-
     docs/stable/user_guide/indexing.html#returning-a-view-versus-a-copy
       self._setitem_single_block(indexer, value, name)
[31]: print(len(Stoprotate))
     print(len(Startrotate))
     688
     688
[]:
```