

Phase 3 Updates

SlashBurn (graph decomposition algorithm)

We successfully implemented the modified **SlashBurn** algorithm that the paper uses as step 1 out of 3 for the entire VoG algorithm. This can be seen in the `src/slashburn.py` file and can be run by calling `$ python3 src/slashburn.py`.

Implementing **SlashBurn** involved:

- Switching the adjacency list output to concentrate the hub nodes to the top left instead of the bottom right.
- Creating a global subgraphs list that only stores subgraphs of size greater than 2 and less than the GCC (Giant Connected Component).

Note: GCC was labelled as the largest subgraph generated but we can change that if there is some other method to identify GCC.

- Adding the hub plus all immediate neighbors as a subgraph in addition to all other subgraphs generated by the original **SlashBurn** method.

MDL

We have begun to implement code that gets the total encoded length for a model M . That is, we have been writing code to implement the function $L(M)$. The bulk of getting the encoded length of a model M comes from the encoded length of the specific graph structure type $L(s)$, which is the function `get_encoded_length_by_graph_type` we have written in `src/MDL.py`. Specifically, we have written code for the encoded length of each specific graph structure in our vocabulary $\omega = \{fc, nc, fb, nb, ch, st\}$.

Note that `MDL.py` is not runnable because we have not yet adapted the code for the different graph structure classes. However, any functions/properties that a graph object calls within `MDL.py` (such as `graph.numEdges`) already exist in the code we are planning to adapt.

Next steps

Our next steps include:

- Adapting code that deals with identifying a subgraph as a specific graph structure (e.g. star or chain) so that it works with the MDL code we have already written
- Writing a function for the overall encoded length of a model $L(M)$ that incorporates the function for $L(s)$ we have written
- Writing a function that deals with encoding the length of the error matrix $L(E)$
- Making sure that we can pass in data in the proper format from our non-toy datasets to our SlashBurn algorithm
- Figuring out how many subgraphs are in each model so that we can pass in a model family to step 2 of the algorithm after running SlashBurn
- Implementing step 3 of the VoG algorithm (which deals with heuristics)
- Testing our entire VoG algorithm on the datasets outlined in our project plan