# Software Testing

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### 1 Test Plan

#### 1.1 Introduction

MASON is a software library for creating agent-based simulations in Java. The software fits into the category of shrinkwrap meaning it might be in use in a wide range of real-world production environments. The software is freely-available and open-source, which is a special case of shrinkwrap software. A common trait of open-source software is that tasks 'that are not considered "fun" often don't get done'.[1] For MASON in particular, it is likely that the software has not been thoroughly tested as there is no trace of any automated testing, either on the MASON website, or its GitHub repository.

#### 1.1.1 Tools

The IntelliJ IDE was used to explore the code and develop automated tests. This IDE gives powerful features, including plugins for generating code metrics and displaying coverage of unit testing. Specifically, the MetricsReloaded plugin[2] has been used for generating the statistics in Fig. 3.

JUnit has been used to create automated testing for the software, this includes both unit and integration testing. Git version control has been used to manage the code for these JUnit tests. For a long term project, this would be particularly advantageous as any automated tests could be updated and versioned alongside any future code changes.

#### 1.2 Test Coverage

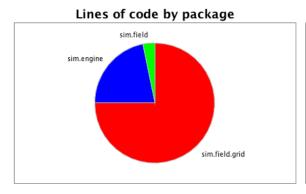
#### 1.2.1 System Overview

In order to design appropriate test cases an understanding of all levels of the system was needed. As resources here are significantly limited, with only 8 testcases are allowed, it will be necessary to ensure they are used in the most effective way. As stated in the project brief, the testing only needs to cover the following packages, but not their subpackages:

- sim.engine is responsible for the core simulation management, including the agent scheduling.
- sim.field provides abstract classes for the representations of space in MASON simulation models, with subpackages managing specific instances of these.
- sim.field.grid provides various 2D and 3D grid representations of simulation space.

Fig. 1a shows the proportional sizes of each of these three modules, while Fig. 6 shows their code components.

It has been shown across software projects that some modules of code may be significantly more error prone than others. The Pareto principle is said to hold with software bugs, with





(a) Lines of Code

(b) Cyclomatic Complexity

Figure 1: Charts showing various metrics of MASON

80% of software bugs being found within 20% of the code[3, pp. 124]. We can use a variety of metrics about our software to predict which parts of the code that these bugs may be hiding in[4].

High cyclomatic complexity (Fig. 1b/Fig. 3c) can be a good indicator of the most bugridden sections of applications. The causality here can be easily understood: complexity creates confusion which results in developers misunderstanding the software they are trying to build. This misunderstanding can provoke a large number of bugs in the code. The graphs show that sim.field.grid has a slightly higher share of the code's complexity than lines of code, this should be investigated in further detail.

Fig. 3d shows how the packages in the test scope interact with other packages in the system. In particular, sim.engine is relied on by a large number of packages. Code coverage has provided a good understanding of which parts of the [code] are regularly used while running the software. How often different source files have changes is also a particularly useful metric. Files which are subject to frequent change have had more opportunity to develop additional bugs.

Producing the right metrics to help test the application have been particularly difficult in this case. No real history of previous bug tracking GitHub commits are all credited to *eclab* rather than individual developers

#### 1.2.2 Testing Goals

There are a number of goals we could define for our testing, such as finding the maximum number of bugs or complying with regulator set demands. The given requirement here is to verify, with a limited number of resources, that the software is dependable. In general, it's

better to test with the aim of showing a product fails, if we cannot do so then the product is reliable enough[5, pp. 20]. As such, the main requirement for our testing is to find any significant undiscovered bugs in commonly used code.

Due to limited resources, the tests will aim to cover the parts of the software which are likely to be used more often by the target users. MASON is bundled with some demo simulations that give example usages for the library. Running these simulations with code coverage detection turned on has given a good overview of which parts of the code are used regularly (Fig. 7). Core simulation code that is used routinely by all simulations regardless of their customisations should be tested the most rigourously. Both the documentation[6, pp.85] and code coverage checks indicate that this type of code can be found within sim.engine.

#### 1.2.3 Expected Behaviour

The system behaviour has been tested against the inferred requirements of the client, a private biological research institute.

The expected behaviour of the software has been determined using the extensive MASON documentation[6] and first-party example implementations. The brief has not provided any specific use cases for the software, so the tests cannot be easily targeted at the end-user's specific needs.

#### 1.2.4 Unit Testing

Unit Testing allows the testing of small sections of source code. In this case, unit tests will help us to isolate the select packages that are within the scope of testing from the rest of the system.

Unit testing should focus on core code that is a dependency for other modules, code that regularly gathers bugs and code that is changed by a number of different developers. It should not cover trivial code, such as accessors and mutators, code with non-deterministic results or UI code.[8] In this case, we will target our unit testing at ensuring the core software functionality is correct, specifically that simulations can be created and run.

As previously mentioned, it has been shown that approximately 20% of the code, contains 80% of our program's bugs. Our unit testing will aim for 60-70% code coverage of core code and  $\sim 20\%$  of the overall application, as recommended in [8].

#### 1.2.5 Integration Testing

Java is a heavily object-oriented (OO) language. This will affect our testing as in this type of software, much of the complexity is moved from algorithms in methods, to the connection of software components[9, pp.236]. We will therefore need a much greater focus on integration testing than unit testing.

#### 1.2.6 System Testing

While testing the system as a whole will not help us find low-level bugs, it will give a high-level view of whether the bulk of the functionality appears to work as expected. System testing of the application will be conducted using the MASON UI as a black-box test. As such, although the test relies on functionality provided by classes outside the test scope, the test cases will only attempt to verify functionality provided by classes which are in scope.

System testing will also help us to verify the non-functional requirements that have been previously determined. In particular, our system testing will cover

Acceptance Testing is a particularly useful form of system testing. Acceptance Testing could be performed to determine if the software can be operated effectively by our end users. It can be useful for understanding the domain of our software better, but as we are not intending to further develop MASON, this is not particularly relevant here. It should be performed ON?/BY? domain experts?- I am NOT a domain expert..

While acceptance testing will not help us determine that the software is *dependable*, it would help to discover if it is appropriate for the target audience. In particular, our users have supposedly only received a basic level of Java training. It has been stated that MASON is less-suited to beginner programmers, when compared to other tools, such as NetLogo[10].

#### 1.2.7 Regression Testing

Unfortunately neither the website nor the GitHub repository for MASON provide any previously implemented automated testing. Either this testing has not been done, which is common with freely-distributed software, or it has not been publicly distributed. As such, it will not be possible to run any regression testing as part of the project.

### 2 Test Case Specifications

- 2.1 Test Case 1
- 2.2 Test Case 2
- 2.3 Test Cases 3-4

As previously stated, our initial integration testing will focus on the simulation scheduler which provides the core functionality for MASON. This scheduler works with the SimState class and custom implementations of the Steppable interface to provide the functionality that simulates the passing of time.

While this integration between classes may appear to be complex at first glance, with numerous methods available (Fig. 2), many of its methods are simply overloads, due to Java's lack of real support for default function arguments. Testing a single example of scheduleOnce function, will provide a reasonable assurance that the functionality works, as code is shared with each overloaded instance calling the private \_scheduleOnce method.

Test Case 1 will add a Steppable object to the Schedule and ensure that the step method work as expected. A by-product of this test, is the as-

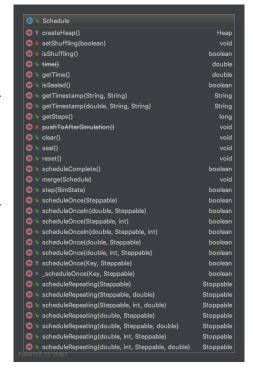


Figure 2: Schedule Class

surance that the \_scheduleOnce method also works as expected. As \_scheduleOnce is a private method, it will be called indirectly by one of its overloading methods: scheduleOnce(Steppable). Other overloading methods could be used instead with no difference on the test case as the scheduler skips any empty timesteps. In order to facilitate this test, a simple Increment class (Fig. 4) has been created. The scheduler will be stepped a number of times (10) to ensure that the Increment value is correctly stepped.

Test Case 2 is similar, but will utilise the scheduleRepeating(Steppable) to ensure that the Schedule correctly manages recurring events. As mentioned, the scheduler skips any empty timesteps, so providing a different start time or time interval will make little difference to the test.

- 2.4 Test Case 5
- 2.5 Test Case 6
- 2.6 Test Case 7
- 2.7 Test Case 8

# 3 Test Results

Case	Pass	Level	Expected	Actual	Details
1	✓	Unit			
2	✓	Unit			
3	✓	Integration	i variable is incre-	i is incremented once,	Behaved as expected,
			mented once, in first	despite the simula-	no notable side-effects.
			simulation step.	tion being stepped 10	
				times.	
4	✓	Integration	i variable is incre-	i is incremented ten	Behaved as expected,
			mented once for each	times, once at each	no notable side-effects.
			simulation step.	step.	
5	✓	Integration			
6	✓	Integration			
7	X	System	The simulation runs	The simulation is run,	
			and stops after 200,000	but does not stop.	
			steps.		
8	✓	System			

# 4 Test Summary Report

The significant limitations of testing resources reduce the level of confidence with which we can say that the software is free from defects. I can assure that the core functionality, including the simulation scheduler works.

### 5 References

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### 6 Appendix

Package	Lines of Code
sim.engine	2,961
sim.field	444
sim.field.grid	10,248
Total	13,653
Average	4,551

Package	Class Count
sim.engine	25
sim.field	6
sim.field.grid	14
Total	45
Average	15

(a) Lines of Code

(b) Class	Count
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Package	v(G)			
1 ackage	Average	Total		
sim.engine	2.43	374		
sim.field	2.38	57		
sim.field.grid	3.75	1,829		
Total		2,260		
Average	3.39	753.33		

Package	Dependencies	Dependants
sim.engine	2	54
sim.field	1	24
sim.field.grid	2	20
Average	1.67	32.67

(c) Cyclomatic Complexity

(d) Package Dependency

Figure 3: Code Metrics for the relevant MASON libraries

```
class Increment implements Steppable {
    private int i = 0;

    @Override
    public void step(SimState state) {
        i++;
    }
}
```

Figure 4: Simple Increment class used for Unit Testing

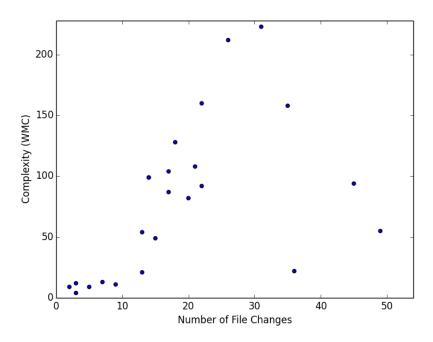


Figure 5: Cyclomatic Complexity and Number of File Revisions for classes in test scope

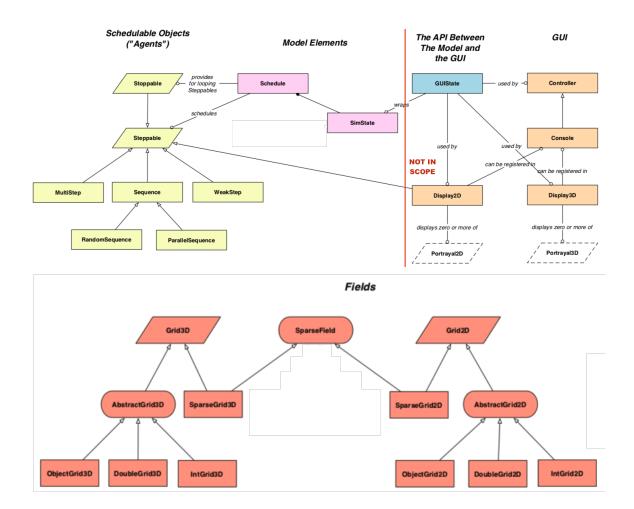


Figure 6: UML diagrams of hierarchy for classes in the test scope[11]

		HeatBugs Coverage (%)		Tutorial 4 Coverage (%)		Mouse Traps Coverage (%)	
Package	Class						
		Method	Line	Method	Line	Method	Line
	AsynchronousSteppable						
	IterativeRepeat	60	70	60	71		
	MethodStep						
	MultiStep						
	ParallelSequence	38	59				
	RandomSequence						
sim.engine	Repeat						
	Schedule	41	51	38	49	35	46
	Sequence	11	12				
	SimState	31	18	55	48	31	18
	TentativeStep						
	ThreadPool	66	76				
	WeakStep						
sim.field	SparseField	21	34	24	37		
	AbstractGrid2D	10	1	5	0	5	0
	AbstractGrid3D						
	DenseGrid2D						
	DenseGrid3D						
	DoubleGrid2D	11	7	7	5		
sim.field.grid	DoubleGrid3D						
Sim.lieid.giid	IntGrid2D					17	10
	IntGrid3D						
	ObjectGrid2D						
	ObjectGrid3D						
	SparseGrid2D	10	2	4	1		
	SparseGrid3D						

Figure 7: Code Coverage from Demo Simulation Runs