$$E_{rr} = -\frac{4GQk^2}{r^3} \left( \left( -1 + \frac{3}{k^2r^2} \right) \cos\left(\omega t - kr\right) - \frac{3}{kr} \sin\left(\omega t - kr\right) \right) \left( 3\cos^2\left(\theta\right) - 1 \right)$$

$$E_{r\theta} = -\frac{4GQk^2}{r^3} \left( \left( -3 + \frac{6}{k^2r^2} \right) \cos\left(\omega t - kr\right) + \left( kr - \frac{6}{kr} \right) \sin\left(\omega t - kr\right) \right) \sin\left(\theta\right) \cos\left(\theta\right)$$

$$E_{\theta\theta} = -\frac{GQk^2}{r^3} \left( -\left( 2kr - \frac{3}{kr} \right) \sin\left(\omega t - kr\right) + \left( -k^2r^2 + 3 - \frac{3}{k^2r^2} \right) \cos\left(\omega t - kr\right) \right) \sin^2\left(\theta\right)$$

$$(9)$$