$$E_r = -\frac{Qk^2}{4\pi\varepsilon_0 r^2} \left( \left( 1 - \frac{3}{k^2 r^2} \right) \cos(\omega t - kr) + \frac{3}{kr} \sin(\omega t - kr) \right) \left( 3\cos^2(\theta) - 1 \right)$$

$$E_\theta = -\frac{Qk^2}{4\pi\varepsilon_0 r^2} \left( \left( 3 - \frac{6}{k^2 r^2} \right) \cos(\omega t - kr) - \left( kr - \frac{6}{kr} \right) \sin(\omega t - kr) \right) \sin(\theta) \cos(\theta)$$

$$(4)$$