- 4. Find the minimizer of $c^T x$ (for $c \in \mathbb{R}^n$ a constant vector and $x \in \mathbb{R}^n$ a variable) over Ω , where Ω is each of the following sets:
 - (a) The unit ball: $\{x \mid ||x||_2 \le 1\}$;
 - (b) The unit simplex: $\{x \in \mathbb{R}^n \mid x \ge 0, \sum_{i=1}^n x_i = 1\};$
 - (c) A box: $\{x \mid 0 \le x_i \le 1, i = 1, 2, \dots, n\}.$

$$\forall f(X^{\nu}) : C$$
 we have $-\nabla f(X^{\nu}) \in N_{\nu}(X^{\nu})$

(a) for unit ball
$$\{x : \|x\|_{L^{2}} \le 1\}$$
then we have $\{x^{3}\}_{L^{2}} = -\|c\|_{L^{2}}$

$$|C^{T} V| \leq |C|| \cdot |V|| \cdot \leq |C|| \cdot$$

$$|C^{T} V| \leq |C|| \cdot |V|| \cdot \leq |C|| \cdot$$

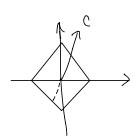
$$|C^{T} V| \leq |C^{T} V| \cdot |C^{T} V|$$

$$(p) \qquad \mathcal{N} = \left\{ \begin{array}{ll} X \in \mathbb{K}_{\nu} \middle| X \downarrow 0^{\nu} & \sum_{i=1}^{\nu} X_{i} > 1 \end{array} \right\}$$

$$X^{b} = C_{argmin} C;$$

$$X^{i} = \begin{cases} 1 & i = argmin \\ j = 1 & i \end{cases}$$

$$0 & i \neq argmin \\ j = 1 & i \end{cases}$$



for
$$\forall N \in \mathbb{N}$$
, suppose $C_i = \underset{i \in J}{\min} C_j$, then: $X_i = 1$ $X_j = 0$ $(j \neq i)$

$$N - X' = (N_i \cdots N_i - 1), N_i + 1, \cdots N_n)$$

$$\angle C_i N - X'' > = \int_{\mathbb{T}^2}^{\mathbb{T}} (jN_j - C_i - 7 - j_i) C_i N_j - C_i = 0$$

(c)
$$N = \{ x \mid 0 \leq x_{i+1}, j_{i+1}, j_{i+1}, n \}$$

$$\begin{cases} x_{i} = x_{i+1} \\ 0 & \text{ciso} \end{cases}$$

$$V_{i} \in [0,1] \qquad V_{i-1} \leq 0$$

$$V_{i} = \{0,1\} \qquad V_{i-1} \leq 0$$

Q 2. Consider the unconstrained optimization problem $\min_{\mathbf{x} \in \mathbb{R}^n} f(\mathbf{x})$, where f is an L-smooth convex function. Assume that $\|\mathbf{x}_0 - \mathbf{x}^*\|_2 \le R$, for some $R \in (0, \infty)$, and let $f_{\epsilon}(\mathbf{x}) = f(\mathbf{x}) + \frac{\epsilon}{2R^2} \|\mathbf{x} - \mathbf{x}_0\|_2^2$. Let $\mathbf{x}^* = \operatorname{argmin}_{\mathbf{x} \in \mathbb{R}^n} f(\mathbf{x})$ and $\mathbf{x}^*_{\epsilon} = \operatorname{argmin}_{\mathbf{x} \in \mathbb{R}^n} f_{\epsilon}(\mathbf{x})$. You have already shown in previous homework (with possibly minor modifications) that:

$$(\forall \mathbf{x} \in \mathbb{R}^n) : f(\mathbf{x}) - f(\mathbf{x}^*) \le f_{\epsilon}(\mathbf{x}) - f_{\epsilon}(\mathbf{x}^*_{\epsilon}) + \frac{\epsilon}{2}.$$

- (i) Prove that Nesterov's method for smooth and strongly convex minimization applied to f_{ϵ} will find a solution \mathbf{x}_k with $f(\mathbf{x}_k) f(\mathbf{x}^*) \leq \epsilon$ in $O(\sqrt{\frac{L}{\epsilon}}R\log(\frac{LR^2}{\epsilon}))$ iterations. [5pts]
- (ii) Using the lower bound for smooth minimization we have proved in class, prove the following lower bound for L-smooth and m-strongly convex optimization: any method satisfying the same assumption as we used in class (that $\mathbf{x}_k \in \mathbf{x}_0 + \mathrm{Lin}\{\nabla f(\mathbf{x}_0), \dots, \nabla f(\mathbf{x}_{k-1})\}$) must take at least $k = \Omega(\sqrt{\frac{L}{m}})$ iterations in the worst case to construct a point \mathbf{x}_k such that $f(\mathbf{x}_k) f(\mathbf{x}^*) \le \epsilon$, for any $\epsilon > 0$.
- (i) From the besture, we have:

 Given a smooth strongly convex function; apply (A+AGD) we have: $f(X_{k}^{out}) f(X_{k}^{out}) \leq \Sigma$ in $O\left(\int_{-\infty}^{\infty} \log_{2}\left(\frac{\|X_{0} X_{0}^{out}\|_{2}^{2}}{\Sigma}\right)\right)$ iterations

$$Sin(a. f_{S}|x) = f_{|x|} + \frac{2}{2R^2} ||x-x_0||_{r}^{2}$$

$$\nabla f_{S}(x) = \nabla f_{|x|} + \frac{2}{R^2} (x-x_0)$$

$$\forall x, y \in \mathbb{R}^n$$
 $\| \forall f_{\xi}(y) - \forall f_{\xi}(x) \| \leq \| \forall f_{\xi}(y) - \forall f_{\xi}(x) \| + \frac{\xi}{\mathbb{R}^2} \| y - x \|$
 $\leq \left(\left[+ \frac{\xi}{\mathbb{R}^2} \right] \| y - x \| \right) = \int_{\mathbb{R}^2} \left[+ \frac{\xi}{\mathbb{R}^2} \right] \| y - x \|$

According to Taylor's theorem:
$$f_{\Sigma(Y)} - f_{\Sigma(X)} >_{,} \langle \nabla f_{[X]}, Y_{-X} \rangle + 2 \frac{\Sigma}{R^{2}} ||Y_{-X}||_{L^{2}}^{2}$$

$$= \langle \nabla f_{\Sigma(X)}, Y_{-X} \rangle + \frac{\Sigma}{2R^{2}} ||Y_{-X}||_{L^{2}}^{2}$$

$$= M^{2} = \frac{\Sigma}{R^{2}}$$

Then applying
$$(A+MD)$$
 we have:
$$f_{\Sigma}(X_{E}^{ore}) - f_{\Sigma}(X_{E}^{ore}) \stackrel{\Sigma}{=} \frac{\Sigma}{2} \text{ in }$$

$$O\left(\sqrt{\frac{L+\frac{\Sigma}{R^{2}}}{E}} \log\left(\frac{2(L+\frac{\Sigma}{R^{2}})R^{2}}{E}\right)\right)$$

$$= O\left(\sqrt{\frac{L}{E}} R\log\left(\frac{LR^{2}}{E}\right)\right) \text{ iteration.}$$

(ii) According to the theorem: for any $1 \le k \le \frac{1}{2}(n-1)$, exists a function $f \in F_L^{\infty}(\mathbb{R}^n)$ any method satisfy the assumption:

$$f(x_{k}) - f(x^{*}) = \frac{3L\|X-X^{*}\|_{2}^{2}}{3x(k+1)^{2}}$$

$$3 \le 2 \le 3m \| x_0 - x^{k} \|_{\nu}^{2} \le 4,$$
 $f(x_0) - f(x_0^{k}) \le 2$ must take $k = 2 \cdot (\sqrt{\frac{L}{m}})$

Q 4. In this part, you will compare the heavy ball method to Nesterov's method for smooth and strongly convex optimization. Your problem instance is the following one-dimensional instance: $\min_{x \in \mathbb{R}} f(x)$, where

$$f(x) = \begin{cases} \frac{25}{2}x^2, & \text{if } x < 1\\ \frac{1}{2}x^2 + 24x - 12, & \text{if } 1 \le x < 2\\ \frac{25}{2}x^2 - 24x + 36, & \text{if } x \ge 2. \end{cases}$$

Prove that f is m-strongly convex and L-smooth with m=1 and L=25. What is the global minimizer of f? (Justify your answer.)

Run Nesterov's method and the heavy-ball method, starting from $x_0 = 3.3$. Plot the optimality gap of Nesterov's method and the heavy ball method over 100 iterations. What do you observe? What does this plot tell you? [30pts]

4. Since
$$f$$
 is smooth and strongly convex:

Consider Taylor's theorem. for $\forall x.y \in R'$
 $|\nabla f(y) - \nabla f(x)| = |\int_0^1 \nabla^2 f(x+vp)| P dv|$
 $\leq |\int_0^1 25| P dv| \leq 25|Y-x|$

For $\forall x.y \in R'$
 $|\nabla f(y) - f(x)| = |\nabla f(x)| P = \frac{1}{2}\nabla^2 f(x) \cdot P^2$
 $|\nabla f(y) - f(x)| = |\nabla f(y)| P = \frac{1}{2}\nabla^2 f(x) \cdot P^2$

Then f is M -convexity and L smooth.

 $|L| = 25$. $|M| = 1$

Q 5. Suppose that I give you an algorithm (let's call it AGD-G) that given an initial point $\mathbf{x}_0 \in \mathbb{R}^n$ and gradient access to an L-smooth function $f : \mathbb{R}^n \to \mathbb{R}$ (where $0 < L < \infty$) after k iterations returns a point $\mathbf{x}_k \in \mathbb{R}^n$ that satisfies:

$$\|\nabla f(\mathbf{x}_k)\|_2 \leq \sqrt{\frac{2L(f(\mathbf{x}_0) - f(\mathbf{x}^*))}{(k+1)^2}}.$$

Note that AGD-G does not need to know the value of L.

Show that you can use AGD-G to obtain an algorithm that for any m-strongly convex and L-smooth function and any $\epsilon>0$ can construct a point \mathbf{x}_k with $f(\mathbf{x}_k)-f(\mathbf{x}^*)\leq \epsilon$ in $k=O\Big(\sqrt{\frac{L}{m}}\log\big(\frac{L\|\mathbf{x}_0-\mathbf{x}^*\|_2^2}{\epsilon}\big)\Big)$ iterations. Your algorithm should work without the knowledge of the values of L and m.

Extract

Since
$$(AGD-G)$$
 have:

 $\|\nabla f(x_0)\|_{2} \le \int \frac{1}{2} \|f(x_0) - f(x_0)\|_{2} \le \int \frac{1}{2} \|x_0 - x^0\|_{2}^{2}$
 $f(x_0) - f(x_0)\|_{2} \le \int \frac{1}{2} \|f(x_0) - f(x_0)\|_{2}^{2} \le \int \frac{1}{2} \|x_0 - x^0\|_{2}^{2}$
 $f(x_0) - f(x_0)\|_{2} \le \int \frac{1}{2} \|x_0 - x^0\|_{2}^{2} \le \int \frac{1}{2} \|x_0 - x^0\|_{2}^{2}$
 $= \frac{1}{2} \|x_0 - x^0\|_{2}^{2}$

$$\begin{array}{lll} \text{d}: & \text{for } j = 1: G \\ & \chi_{j}^{\text{out}} = AGD - G\left(\chi_{j-1}^{\text{out}}, \; k = \frac{2L}{m}\right) \\ & \text{WANT}; \; \|\chi_{j}^{\text{out}} - \chi^{*}\|_{2}^{2} \leq 2 \\ & \text{G} \; \text{7} \; \text{frg}_{2}\left(\frac{\|\chi_{0} - \chi^{*}\|_{2}^{2}}{2}\right) \end{array}$$

then:
$$f(X_G^{ont}) - f(X_J^{ont}) \le \frac{L}{2} \|X_G^{ont} - X_J^{ont}\|_2^2 \le \frac{L}{2} \le \frac{Z}{2}$$
Let $\widetilde{Z} = \frac{L}{2} \le 2 = \frac{Z}{2} = \frac{Z}{2}$
Then:
$$f(X_G^{ont} - X_J^{ont}) \le \widetilde{Z}$$
when $G > log_2(\frac{L||X_0 - X_J^{ont}||_2^2}{2 \cdot \overline{Z}})$
Total A+ AG)-G:
$$K = O(\frac{L}{m} \cdot log_2(\frac{L||X_0 - X_J^{ont}||_2^2}{\overline{Z}})$$