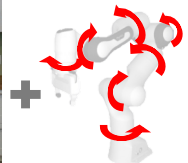
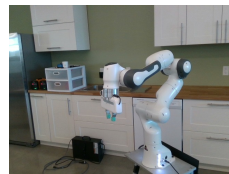


(A)

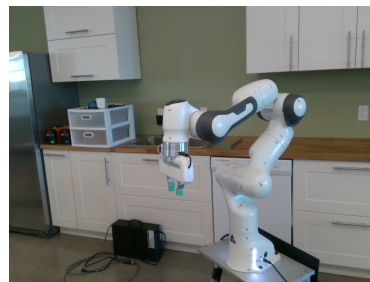


Model

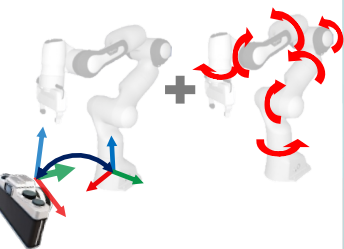


Output Pose

Input Image + Joint States



Model



Output Pose + Joint States

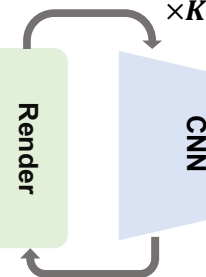
Input Image

(B)

RoboPose

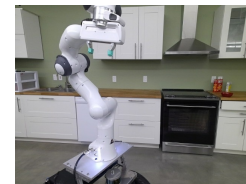


Input Image

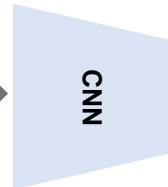


FPS $\uparrow = 1.8$
 AUC $\uparrow = 70.4$
 Avg. Err. $\downarrow = 34.3$ mm

Ours



Input Image



FPS $\uparrow = 22.6$
 AUC $\uparrow = 82.2$
 Avg. Err. $\downarrow = 18.9$ mm