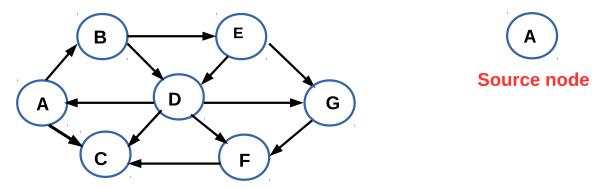
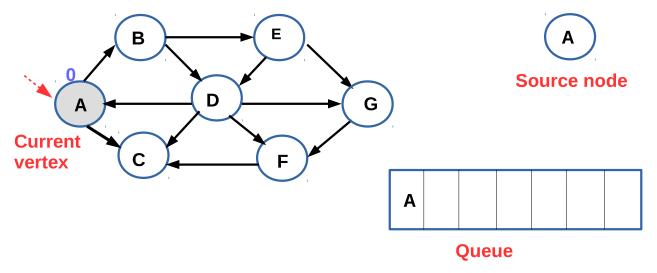
Consider the directed graph below, use the breadth first search procedure to give the BFS tree when A is the source node



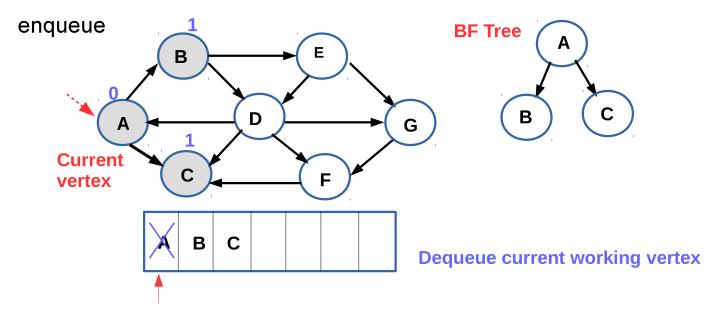
- Note: This is an instance of the unweighted shortest-path computation.
- We try to reach every other node in the graph from the source node and ensure each vertex is visited only once

Consider the directed graph below, use the breadth first search procedure to give the BFS tree when A is the source node

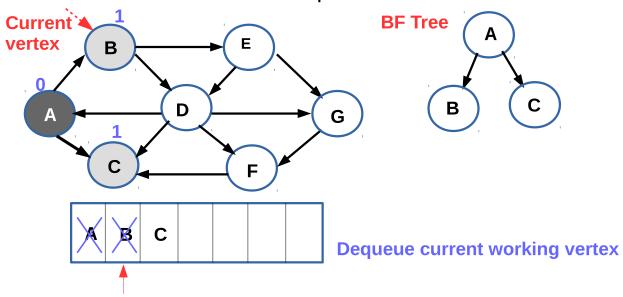


The graph after the starting vertex has been marked as reachable in zero edges

Now check all adjacent vertices to the "current node" and

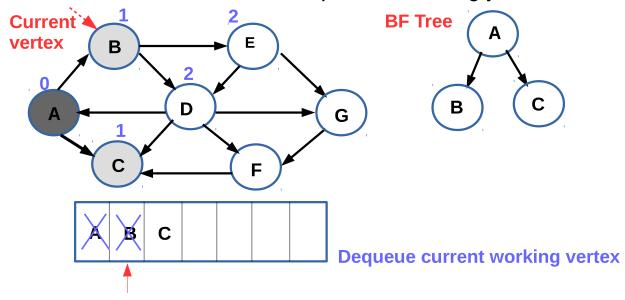


- Breadth first tree (BF Tree) after corresponding adjacent vertices have been discovered
- Graph after all vertices whose path length from the starting vertex is 1 have been found

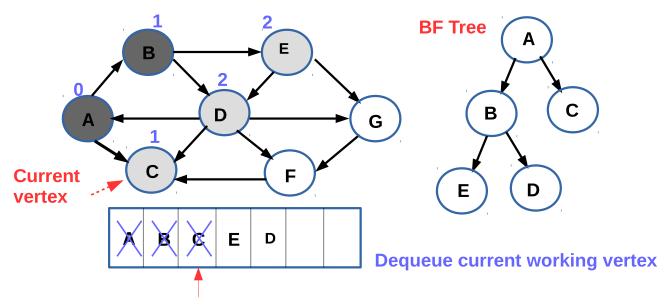


- Darkest shaded vertices have already been completely processed
- Current "working" node (current vertex) is B

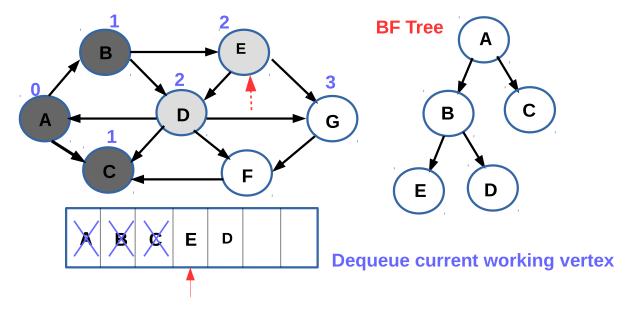
Move pointer to the next item in the queue and check all adjacent vertices to the "current node" and enqueue accordingly.



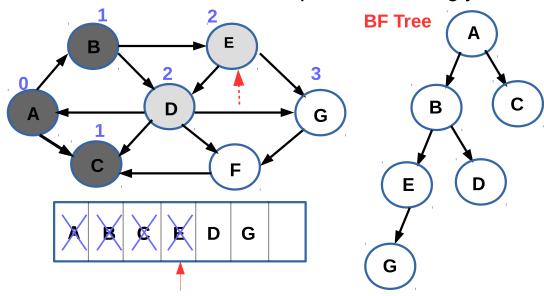
Graph after all vertices whose path length from the starting vertex is 2 have been found



- Graph after all vertices whose path length from the starting vertex is 2 have been found
- Note: node C has no adjacent node(s). Continue the process

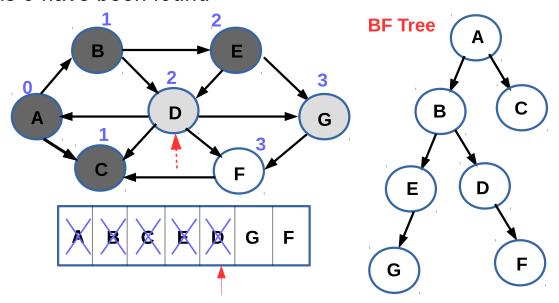


- Note: node C has no adjacent node(s). Node C turns black. So continue the process
- Advance the pointer accordingly.

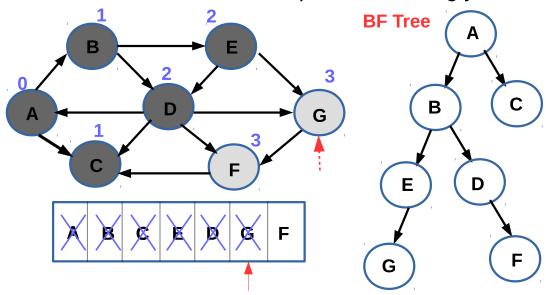


- Node E is the current working node, so turns gray and dequeued
- Enqueue (newly discovered) adjacent nodes to E and update tree

Graph after all vertices whose path length from the starting vertex is 3 have been found

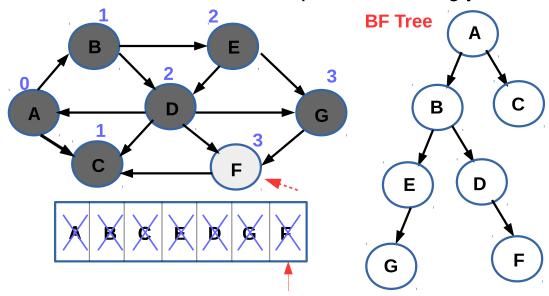


- Node D is the current working node, so <u>dequeued</u>
- Enqueue (newly discovered) adjacent nodes to D and update tree

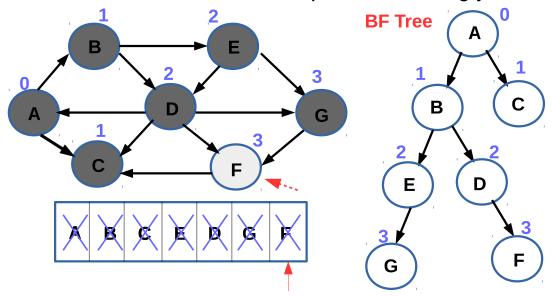


- Node G is the current working node, so turns gray and dequeued
- Enqueue (newly discovered) adjacent nodes to G (<u>if any</u>) and update tree

Move pointer to the next item in the queue and check all adjacent vertices to the "current node" and enqueue accordingly.



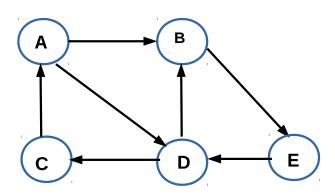
By the time the pointer gets to F, we discover that <u>all nodes</u>
<u>have been visited and the queue is empty</u>



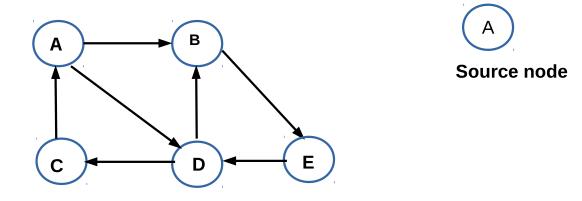
- By the time the pointer gets to F, we discover that <u>all nodes</u>
 have been visited and the queue is empty
- Operation terminates once the queue is empty

Breadth First Search – Exercise in Class

- Consider the directed graph below, use the breadth first search (BFS) procedure to give the BFS tree when A is the source node
- Show all intermediate steps with tree diagrams

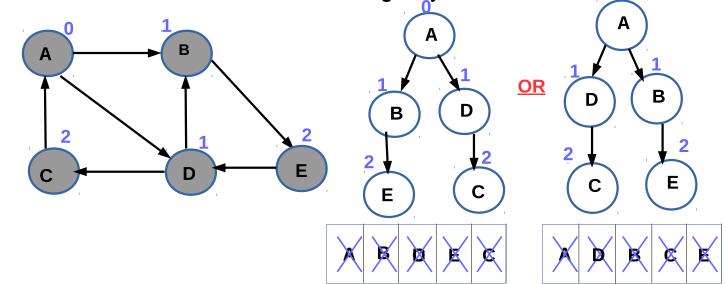


- Consider the directed graph below, use the breadth first search (BFS) procedure to give the BFS tree when A is the source node
- Show each step of your operation



Note: Follow the same procedure in the previous example

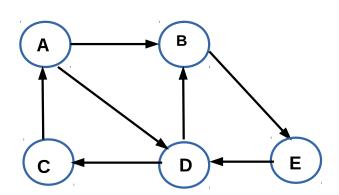
- If you follow the procedure correctly, when A is the source node
- You should have one of the following as your final solution one



- Note: all nodes have been visited only once
- Easy to compute shortest path with breadth first procedure (i.e. breadth first tree)

Exercise in Class -

- Consider the directed graph below, use the breadth first search (BFS) procedure to give the BFS tree when D is the source node
- That is find the shortest unweighted path from D to all other nodes in the graph below

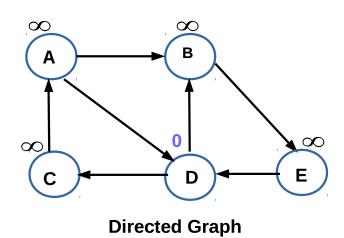




Source node

 \blacksquare Let the shortest path from D to any node be k and that k = ∞

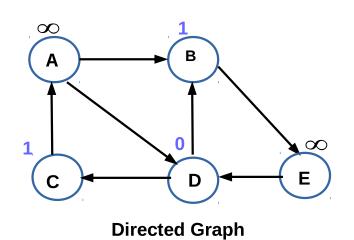




Breadth First Tree

- \blacksquare Let the shortest path from D to any node be k and that k = ∞
- Update each node's (unweighted) path length as at when

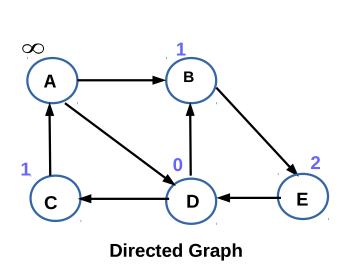
discovered

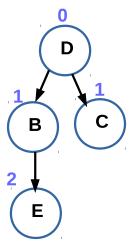


Breadth First Tree

D

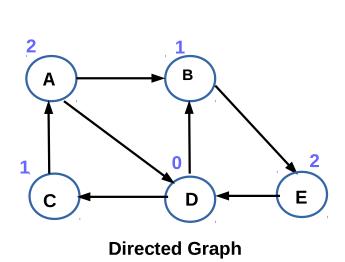
- Let the shortest path from D to any node be k and that $k = \infty$
- Update each node's path length as at when discovered

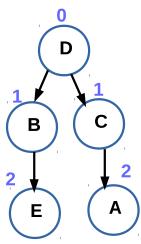




Breadth First Tree

- \blacksquare Let the shortest path from D to any node be k and that k = ∞
- Update each node's path length as at when discovered





Breadth First Tree