# SheafCanon_OF

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## Modeling Robinson's SheafCanon Sheaf:

For specifics and citations, reference https://arxiv.org/abs/1603.01446

Robinson, Michael. "Sheaves Are the Canonical Data Structure for Sensor Integration." Information Fusion, vol. 36, Elsevier B.V, 2017, pp. 208–24, https://doi.org/10.1016/j.inffus.2016.12.002.

```
library(tidyverse)
```

```
## -- Attaching packages --------------------------------------- tidyverse 1.3.1 --
```

```
## v ggplot2 3.3.5     v purrr   0.3.4
## v tibble  3.1.6     v dplyr   1.0.8
## v tidyr   1.2.0     v stringr 1.4.0
## v readr   2.1.2     v forcats 0.5.1
```

```
## -- Conflicts ------------------------------------------ tidyverse_conflicts() --
## x dplyr::filter() masks stats::filter()
## x dplyr::lag()    masks stats::lag()
```

```
Table1 <- read.csv("Assignment2.csv") # Copied Table 1, page 218.
Table1
```

```
##         Sensor Key entity     Case1     Case2     Case3  Units
## 1  Flight plan  U1      x    70.662    70.663    70.612      W
## 2  Flight plan  U1      y    42.829    42.752    42.834      N
## 3  Flight plan  U1      z 11178.000 11299.000 11237.000      m
## 4          ATC  U2      x    70.587    70.657    70.617      W
## 5          ATC  U2      y    42.741    42.773    42.834      N
## 6          ATC  U2      z 11346.000 11346.000 11236.000      m
## 7          ATC  U2    v_x  -495.000  -495.000  -419.000 km/h W
## 8          ATC  U2    v_y   164.000   164.000   310.000 km/h N
## 9        RDF 1  U3 Theta1    77.100    77.200    77.200 true N
## 10       RDF 1  U3      t     0.943     0.930     0.985      h
## 11       RDF 2  U4 Theta2    61.300    63.200    63.300 true N
## 12       RDF 2  U4      t     0.890     0.974     1.050      h
## 13         Sat  U5      s        NA        NA        NA
## 14         Sat  U5    s_x    64.599    64.630    62.742      W
## 15         Sat  U5    s_y    44.243    44.287    44.550      N
```

```
## 16       Field   X      x    70.649    70.668    70.626      W
## 17       Field   X      y    42.753    42.809    42.814      N
## 18       Field   X      z 11220.000 11431.000 11239.000      m
## 19       Field   X    v_x  -495.000  -495.000  -419.000 km/h W
## 20       Field   X    v_y   164.000   164.000   311.000 km/h N
## 21       Field   X      t     0.928     1.050     1.020      h
```

```
#Should these be global variables?
r_1x <- -73.662574
r_1y <- 42.733838
r_2x <- -77.0897
r_2y <- 38.935
```

What should be done with variables outside of the assignment table that we need? Constraints for functions not in any assignment table...

## Restriction Functions:

Page 214: s_x, s_y are coordinates of an object detected in the satellite image, r_1x, r_1y are coordinates of the first RDF sensor and r_2x, r_2y are coordinates of the second RDF sensor.

$$A(x, y, z, v_x, v_y, t) = \left( tan^{-1} \frac{x + v_x t - r_{1x}}{y + v_y t - r_{1y}}, t \right)$$

```
A <- function(stalk) {
  r_1x <- -73.662574
  r_1y <- 42.733838

  stalk %>%
    mutate(Theta1=atan2(x + v_x*t - r_1x, y + v_y*t - r_1y)) %>%
    select(Theta1, t)

}
```

$$B(x, y, z, v_x, v_y, t) = \left( tan^{-1} \frac{x + v_x t - r_{2x}}{y + v_y t - r_{2y}}, t \right)$$

```
B <- function(stalk) {
  r_2x <- -77.0897
  r_2y <- 38.935

    stalk %>%
      mutate(Theta2=atan2(x + v_x*t - r_2x, y + v_y*t - r_2y))
}
```

$$C(s_x, s_y) = tan^{-1} \frac{s_x - r_{1x}}{s_y - r_{1y}}$$

```
C <- function(stalk) {
  r_1x <- -73.662574
  r_1y <- 42.733838

  stalk %>%
    mutate(Theta1=atan2(s_x - r_1x, s_y - r_1y)) %>%
    select(c(Theta1))
}
```

$$D(s_x, s_y) = tan^{-1} \frac{s_x - r_{2x}}{s_y - r_{2y}}$$

```
D <- function(stalk){
  r_2x <- -77.0897
  r_2y <- 38.935

  stalk %>%
    mutate(Theta2=atan2(s_x - r_2x, s_y - r_2y)) %>%
    select(c(Theta2))
}
```

$$E(x, y, z, v_x, v_y, t) = (x + v_x t, y + v_y t)$$

s = expected location, where coordinates = y + displacement and x+ displacement from the equation

```
E <- function(stalk) {
    stalk %>%
      mutate(s_x = c(x + v_x*t), s_y = c(y + v_y*t)) %>%
      select(c(s_x, s_y))
}
```

**Check Example 15:**

```
pr1xpr2 <- function(stalk){
  stalk %>%
      select(c(x, y, z, v_x, v_y))
}
```

pr1 for u2 -> u1

```
U2_pr1 <- function(stalk){
  stalk %>%
  select(c(x, y, z))
}
```

pr1 for u3 -> v1

```
U3_pr1 <- function(stalk){
  stalk %>%
      select(c(Theta1))
}
```

pr2 for u3 -> v3

```
U3_pr2 <- function(stalk){
  stalk %>%
      select(c(t))
}
```

pr1 for u4 -> v2

```
U4_pr1 <- function(stalk){
  stalk %>%
      select(c(Theta2))
}
```

pr1 for u4 -> v3

```
U4_pr2 <- function(stalk){
  stalk %>%
      select(c(t))
}
```

### ID function return itself, refer to image for components.

```
ID_X <- function(stalk){
  stalk %>%
    select(c(x, y, z, v_x, v_y, s_x, s_y, t, Theta1, Theta2))
}
```

```
ID_U1 <- function(stalk){
  stalk %>%
    select(c(x, y, z))
}
```

```
ID_U2 <- function(stalk){
  stalk %>%
    select(c(x, y, z, v_x, v_y))
}
```

```
ID_U3 <- function(stalk){
  stalk %>%
    select(c(Theta1, t))
}
```

```
ID_U4 <- function(stalk){
  stalk %>%
    select(c(Theta2, t))
}
```

```
ID_U5 <- function(stalk){
  stalk %>%
    select(c(s_x, s_y, Theta1, Theta2))
}
```

```
ID_V1 <- function(stalk){
  stalk %>%
      select(c(Theta1))
}
```

```
ID_V2 <- function(stalk){
  stalk %>%
      select(c(Theta2))
}
```

```
ID_V3 <- function(stalk){
  stalk %>%
      select(c(t))
}
```

Table representation of Figure 6 (b), page 214:

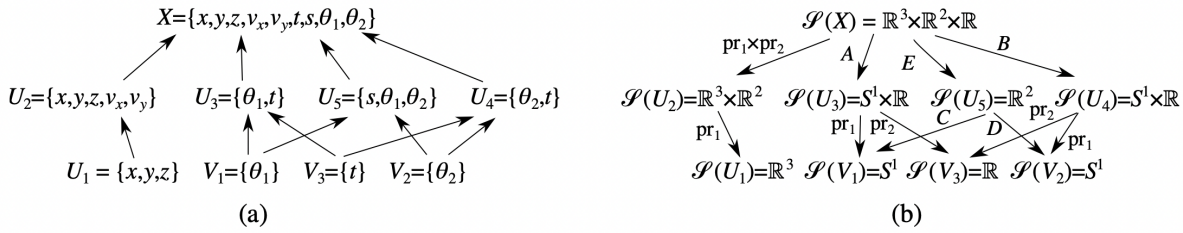


Figure 1: Figure 6

```
SixB <- tibble(SSource = c("X", "X", "X", "X", "U2", "U3", "U3", "U5", "U5", "U4",
                           "U4", "X", "U1", "U2", "U3", "U4", "U5", "V1", "V2", "V3"),
               SDest =  c("U2", "U3", "U5", "U4", "U1", "V1", "V3", "V1", "V2", "V3",
                          "V2", "X", "U1", "U2", "U3", "U4", "U5", "V1", "V2","V3"),
               DMap = c(pr1xpr2, A, E, B, U2_pr1, U3_pr1, U3_pr2, C, D, U4_pr2,
                        U4_pr1, ID_X, ID_U1, ID_U2, ID_U3, ID_U4, ID_U5, ID_V2,
                        ID_V2, ID_V3))

#ID maps w functions and SSource+SDest =.
```

Note: exec takes the function in .x and runs with input .y

```
Table1 %>%
  select(entity, Case1, Key) %>%
  pivot_wider(names_from = entity, values_from = Case1) %>%
  right_join(SixB, by = c(Key = "SSource")) %>%
  nest(stalkinput = 2:12) %>%
  mutate(stalkoutput = map2(.x= DMap, .y = stalkinput, .f = exec)) -> FinSheaf

FinSheaf
```

```
## # A tibble: 20 x 5
##    Key   SDest DMap   stalkinput        stalkoutput
##    <chr> <chr> <list> <list>            <list>
##  1 U1    U1    <fn>   <tibble [1 x 11]> <tibble [1 x 3]>
##  2 U2    U1    <fn>   <tibble [1 x 11]> <tibble [1 x 3]>
##  3 U2    U2    <fn>   <tibble [1 x 11]> <tibble [1 x 5]>
##  4 U3    V1    <fn>   <tibble [1 x 11]> <tibble [1 x 1]>
##  5 U3    V3    <fn>   <tibble [1 x 11]> <tibble [1 x 1]>
##  6 U3    U3    <fn>   <tibble [1 x 11]> <tibble [1 x 2]>
##  7 U4    V3    <fn>   <tibble [1 x 11]> <tibble [1 x 1]>
##  8 U4    V2    <fn>   <tibble [1 x 11]> <tibble [1 x 1]>
##  9 U4    U4    <fn>   <tibble [1 x 11]> <tibble [1 x 2]>
## 10 U5    V1    <fn>   <tibble [1 x 11]> <tibble [1 x 1]>
## 11 U5    V2    <fn>   <tibble [1 x 11]> <tibble [1 x 1]>
## 12 U5    U5    <fn>   <tibble [1 x 11]> <tibble [1 x 4]>
## 13 X     U2    <fn>   <tibble [1 x 11]> <tibble [1 x 5]>
## 14 X     U3    <fn>   <tibble [1 x 11]> <tibble [1 x 2]>
## 15 X     U5    <fn>   <tibble [1 x 11]> <tibble [1 x 2]>
## 16 X     U4    <fn>   <tibble [1 x 11]> <tibble [1 x 11]>
## 17 X     X     <fn>   <tibble [1 x 11]> <tibble [1 x 10]>
## 18 V1    V1    <fn>   <tibble [1 x 11]> <tibble [1 x 1]>
## 19 V2    V2    <fn>   <tibble [1 x 11]> <tibble [1 x 1]>
## 20 V3    V3    <fn>   <tibble [1 x 11]> <tibble [1 x 1]>
```

Consistency Radius: radius=ish sd/var of stalkoutputs/ diameter of stalkoutputs. Coord. comp Unnest. pivot wider, aggregate along all of the columns. UNNESTWIDER Put the STD together, remember units are diff chi square, norm. var. Ideally have user supply aggregation function.

process below should be a specific function, so to optimize consistency radius. best consistency radius function like lm() taking consistency radius function.

```
#FinSheaf %>%
# group_by(SDest) %>%
# summarize(rad = ) # have pre-consistency radii , un-group and aggregate all rads to
# get consistency radius.
# ends with: for each stalk you have a radius, then aggregate them, max, sum of squares.
```

**Relevant Testing:**

```
# Keep in mind when pivoting for consistency rad.

Table1 %>%
```

```
  mutate(label = str_c(Sensor, ".", entity))%>%
  select(label, Case1, Key)%>%
  pivot_wider(names_from = label, values_from = Case1)
```

```
## # A tibble: 6 x 22
##   Key   `Flight plan.x` `Flight plan.y` `Flight plan.z` ATC.x ATC.y ATC.z
##   <chr>           <dbl>           <dbl>           <dbl> <dbl> <dbl> <dbl>
## 1 U1               70.7            42.8           11178  NA    NA      NA
## 2 U2               NA              NA                NA  70.6  42.7 11346
## 3 U3               NA              NA                NA  NA    NA      NA
## 4 U4               NA              NA                NA  NA    NA      NA
## 5 U5               NA              NA                NA  NA    NA      NA
## 6 X                NA              NA                NA  NA    NA      NA
## # ... with 15 more variables: ATC.v_x <dbl>, ATC.v_y <dbl>,
## #   `RDF 1.Theta1` <dbl>, `RDF 1.t` <dbl>, `RDF 2.Theta2` <dbl>,
## #   `RDF 2.t` <dbl>, Sat.s <dbl>, Sat.s_x <dbl>, Sat.s_y <dbl>, Field.x <dbl>,
## #   Field.y <dbl>, Field.z <dbl>, Field.v_x <dbl>, Field.v_y <dbl>,
## #   Field.t <dbl>
```