Lab 8.5: Review for Exam II

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Agenda

- Annoucements
- Review of gaussian mixture models
- Gibbs sampling exercise
- ► Appendix: general review of sampling methods

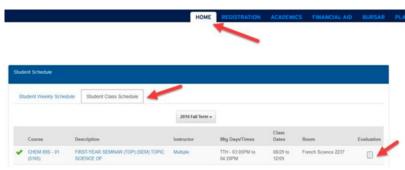
Announcements

Announcements

- Please vote!
 - Forgot to register? Not a problem! Bring an ID and proof of residence (e.g. bank statement or utility bill) to vote before October 31 at an early voting site.
- ▶ Please fill out the TA section of your class evaluation!
 - Your evaluations are very important to me.

Announcements

On DukeHub:



After filling out the course evaluation, you should have the option to add an evaluation for your TAs.

Let's consider the **two-component** gaussian mixture model from Module 7 (part 3).

We have height data X_i , $i=1,2,\ldots,n$, corresponding to males $(Z_i=0)$ and females $(Z_i=1)$. Here we assume that the variable Z_i are unobserved.

Model: If $Z_i = 0$, then $X_i \sim N(\mu_1, \lambda^{-1})$. If $Z_i = 1$, then $X_i \sim N(\mu_2, \lambda^{-1})$. We assume that the X_i are conditionally independent given the other variables.

Priors:

- $ightharpoonup Z_i \mid \pi \sim^{i.i.d.} \mathsf{Bernouilli}(\pi)$
- ▶ $\pi \sim \text{Beta}(a, b)$
- $\blacktriangleright \mu_i \sim^{i.i.d.} N(m, \ell^{-1})$
- $ightharpoonup \lambda \sim \mathsf{Gamma}(c,d)$

Task 1: Write down the likelihood of the data $X_{1:n}$.

Task 2: Write down the joint posterior distribution (up to a proportionality constant).

Task 3: Derive the full conditional distributions for all of the parameters:

- 1. $Z_i | \sim ?$
- 2. $\pi \mid \sim ?$
- 3. $\mu_i \mid \sim ?$
- 4. $\lambda \mid -\sim ?$

Gibbs sampling exercise

From Lab 7:

Consider the following Exponential model for observations $x = (x_1, \dots, x_n)$:

$$p(x|a,b) = ab \exp(-abx)I(x>0)$$

and suppose the prior is

$$p(a,b) = \exp(-a-b)I(a,b>0).$$

You want to sample from the posterior p(a, b|x).

Gibbs sampling exercise

Task 1: Write down the joint posterior distribution, up to a normalization constant.

Task 2: Derive the full conditional distributions.

Task 3: Implement a Gibbs sampler.

Supplementary exercices

modern-bayes/exercises/exercises-exam-two/practice-exercises-examII.pdf

Hoff book:

- ► Exercise 6.1
- ► Exercise 6.2

Appendix: review of sampling methods

Review of sampling methods

- 1. Inverse CDF method
- 2. Rejection sampling
- 3. MCMC methods
 - Metropolis-Hastings
 - ► Gibbs sampling

1. Inverse CDF method

Goal: Generate samples X_1, X_2, \ldots, X_n from a distribution on \mathbb{R} with CDF F.

The trick: If F is invertible and $U \sim \text{Unif}(0,1)$, then $X = F^{-1}(U)$ has the correct distribution.

When is it used? - Works only for *univariate* distributions. - You need to be able to evaluate F^{-1} .

1. Inverse CDF method

Example: Sampling from an $Exp(\lambda)$ distribution

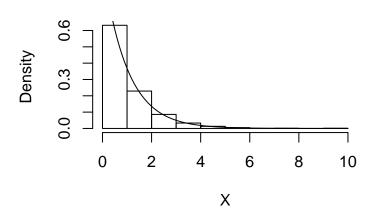
- 1. The CDF of $X \sim \text{Exp}(\lambda)$ is $F(x) = 1 e \lambda x$.
- 2. Its inverse is $F^{-1}(u) = -\log(1-u)/\lambda$.

```
F.inv <- function(u, lambda=1) -log(1-u)/lambda
n = 1000
X = F.inv(runif(n))</pre>
```

1. Inverse CDF method

```
hist(X, prob=TRUE)
curve(dexp(x), add=TRUE)
```

Histogram of X



Goal: Generate samples $X_1, X_2, ..., X_n$ from a distribution with density (proportional to) p(x).

The trick: Try to find a density q(x) which you can sample from and such that $cq(x) \ge p(x)$ for some c.

Algorithm:

- 1. Generate $X \sim q(x)$ and $Y \sim \text{Unif}(0, cq(X))$.
- 2. If Y < p(X), then return X. Otherwise go back to step 1.

Example:

```
Let p(x) = \sin^2(\pi x) be defined on [0,1] and let q(x) = 1 for all x. Take c = 1 since p(x) \le 1.
```

```
p <- function(x) sin(pi*x)^2
q <- Vectorize(function(x) 1)

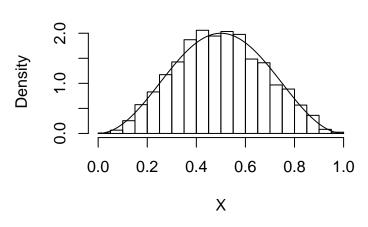
# Vectorized form of rejection sampling:
k = 5000
X = runif(k) # Samples from q
Y = runif(k) # Samples uniform between 0 and cq(X)
X = X[Y < p(X)] # Only keep the X for which Y < p(X).

length(X)/5000 # Acceptance rate</pre>
```

```
## [1] 0.4876
```

```
hist(X, prob=TRUE, breaks=20)
curve(2*p(x), add=TRUE)
```

Histogram of X



When is rejection sampling used?

- Works great for univariate densities (just like the inverse CDF method).
- You don't even need a normalizing constant for p (e.g. posterior distributions!).
- Trickier for higher-dimensional distributions (that's where Gibbs sampling comes in).

3. Metropolis-Hastings

Goal: Generate a Markov Chain $X^{(1)}, X^{(2)}, \dots, X^{(n)}$ with stationary distribution (proportional to) p(x).

▶ In practice the $X^{(s)}$ are seen as correlated samples from the density proportional to p(x).

The trick:

- ▶ Given $X^{(s)} = x$, propose $X^{(s+1)} = x^*$ following some distribution $J(x^* \mid x)$.
- Accept the proposal with probability

$$\alpha = \min \left\{ 1, \frac{p(x^*)J(x \mid x^*)}{p(x)J(x^* \mid x)} \right\},\,$$

• Otherwise set $X^{(s+1)} = X^{(s)} = x$.

Metropolis-Hastings

https://gfycat.com/relieved glossy howler monkey

3. Metropolis-Hastings

When is it used?

- To sample from high-dimensional distributions
- No need to know a normalizing constant for p(x) (e.g. posterior distributions!).

What to watch out for?

- Convergence issues: you want your samples to be a good approximation to p and to not be too correlated with one another.
- ► The acceptance rate of the proposals can help diagnose issues, but it doen't tell you about convergence.
- You need to look at convergence diagnostics.

4. Gibbs sampling

Goal: Generate a Markov Chain $X^{(1)}, X^{(2)}, \dots, X^{(n)}$ with stationary distribution (proportional to) p(x), where $x = (x_1, x_2, \dots, x_k)$.

The trick: Reduce to sampling from the *full conditional* distributions $p(x_i \mid x_{(-i)})$.

Algorithm:

- 1. Initialize $X^{(1)} = (X_1^{(1)}, X_2^{(1)}, \dots, X_k^{(1)})$ to fixed values.
- 2. For s = 2, 3, ..., n. do:

$$X_1^{(s)} \sim p(x_1 \mid X_2^{(s-1)}, X_2^{(s-1)}, \dots, X_k^{(s-1)})$$

$$X_2^{(s)} \sim p(x_2 \mid X_1^{(s)}, X_3^{(s-1)}, \dots, X_k^{(s-1)})$$

$$X_3^{(s)} \sim p(x_3 \mid X_1^{(s)}, X_2^{(s)}, X_4^{(s-1)}, \dots, X_k^{(s-1)})$$

$$X_k^{(s)} \sim p(x_k \mid X_1^{(s)}, X_2^{(s)}, \dots, X_{k-1}^{(s)})$$

4. Gibbs sampling

Example: Go back to the gaussian mixture model example.

When is it used?:

- To sample from high-dimensional distributions
- No need to know a normalizing constant for p(x) (e.g. posterior distributions!).
- You need to derive the full-posterior distributions.

What to watch out for:

- Convergence issues: you want your samples to be a good approximation to p and to not be too correlated with one another.
- You need to look at convergence diagnostics.