

Classification and Topology

(or Consequences of Sobolev Consistency)

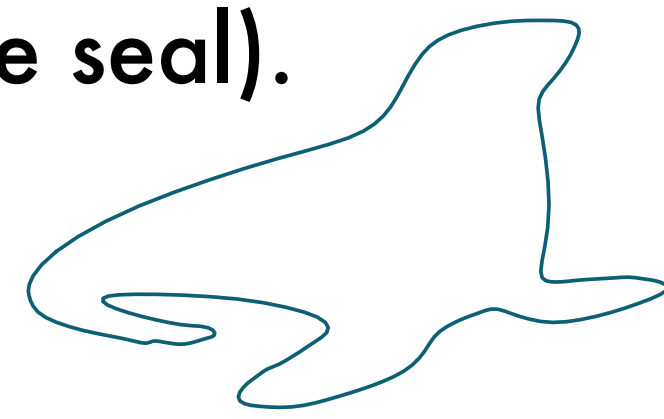
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Key points

- **Topologically accurate** class boundary reconstruction in binary classification.
- A fruitful **relationship with topology** and real algebraic geometry is highlighted.
- Hints at a **research project**: Can the technique be adapted to different surface reconstruction frameworks? Can similar results be obtained in Bayesian nonparametrics or with neural nets?

The Problem

Starting point: $\gamma \subset (0, 1)^k$ a compact connected hypersurface (think of the seal).

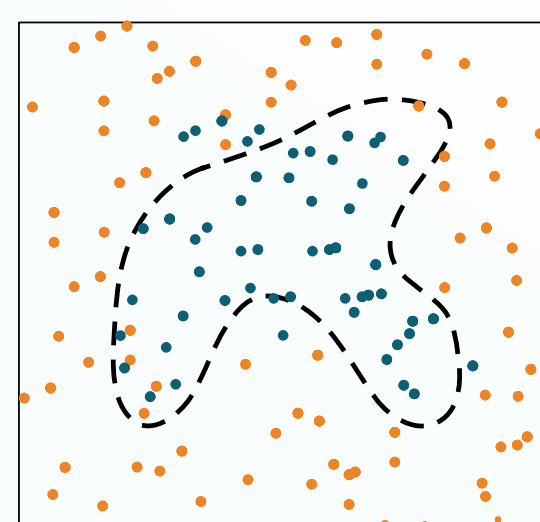


By the **Jordan-Brouwer separation theorem**, γ separates the space in two connected components, one of which is bounded. These components are called **classes** and γ is the **separation surface** (or class boundary).

A priori, γ is unknown and we are trying to reconstruct it using the following labelled points indexed by $i \in \{1, 2, \dots, n\}$:

$$\ell_i \mid x_i \sim \text{Ber}(p(x_i))$$

$$x_i \text{ i.i.d. } \text{uniform}((0, 1)^k)$$



where

A1: $p : (0, 1)^k \rightarrow [0, 1]$ is smooth and has regular value $1/2$;

A2: $p > 1/2$ in the interior of γ and $p < 1/2$ in the exterior of γ .

Note: $\gamma = p^{-1}(1/2)$

A Solution

By the **Nash-Tognoli theorem** of real algebraic geometry, compact surfaces are not topologically distinguishable from compact non-singular real algebraic varieties. This suggests estimating γ by $f^{-1}(1/2)$ where $f : (0, 1)^k \rightarrow \mathbb{R}$ is a polynomial function.

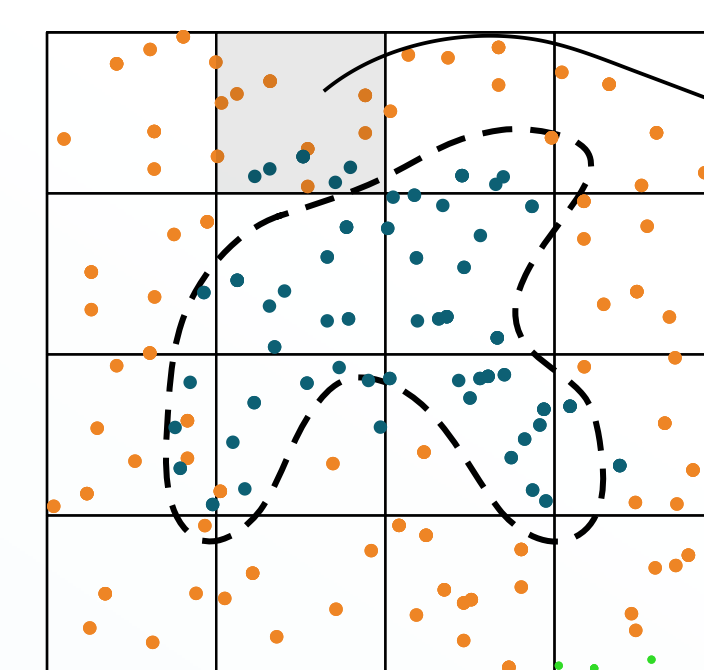
This is done by first estimating p globally using a **two-step method**.

1. Histogram approximation over the regions

$$R_{i,j}^d = \left[\frac{i}{d+1}, \frac{i+1}{d+1}\right] \times \left[\frac{j}{d+1}, \frac{j+1}{d+1}\right]$$

$$E_{1,2}^4 = \frac{5+1}{13+2}$$

$$\approx (4+1)^2 \int_{R_{1,2}^4} p(\mathbf{x}) d\mathbf{x}$$



2. Bernstein polynomial smoothing:

$$\hat{f}_d(u, v) = (d+1)^2 \sum_{i,j=1}^d E_{i,j}^d B_{i,d}(u) B_{j,d}(v)$$

where

$$B_{i,d}(u) = \binom{d}{i} u^i (1-u)^{d-i}$$

We let the degree $d \rightarrow \infty$ as the sample size increase, and our estimate of the surface γ is

$$\hat{\gamma} = \hat{f}_d^{-1}(1/2).$$

But does it converge? In what sense?

Main results

Let

$$W^{2,\infty} = \{f : [0, 1]^k \rightarrow \mathbb{R} \mid \|f\|_{W^{2,\infty}} < \infty\}$$

be a Sobolev space of twice continuously differentiable functions endowed with its norm

$$\|f\|_{W^{2,\infty}} = \|f\|_{\infty} + \|\nabla f\|_{\infty}.$$

Theorem

Let $p \in W^{2,\infty}$ have regular value 0 with $p^{-1}(0) \subset (0, 1)^k$ and let \hat{f}_d be a $W^{2,\infty}$ -consistent* estimator of p . Then a.s.:

1. $\hat{f}_d^{-1}(0)$ converges to $p^{-1}(0)$ in the **Hausdorff distance** as $d \rightarrow \infty$,
2. $\hat{f}_d^{-1}(0)$ is **eventually diffeomorphic** to $p^{-1}(0)$

Hausdorff distance is:

$$d_H(A, B) = \max \left\{ \sup_{x \in A} d(x, B), \sup_{y \in B} d(A, y) \right\}.$$

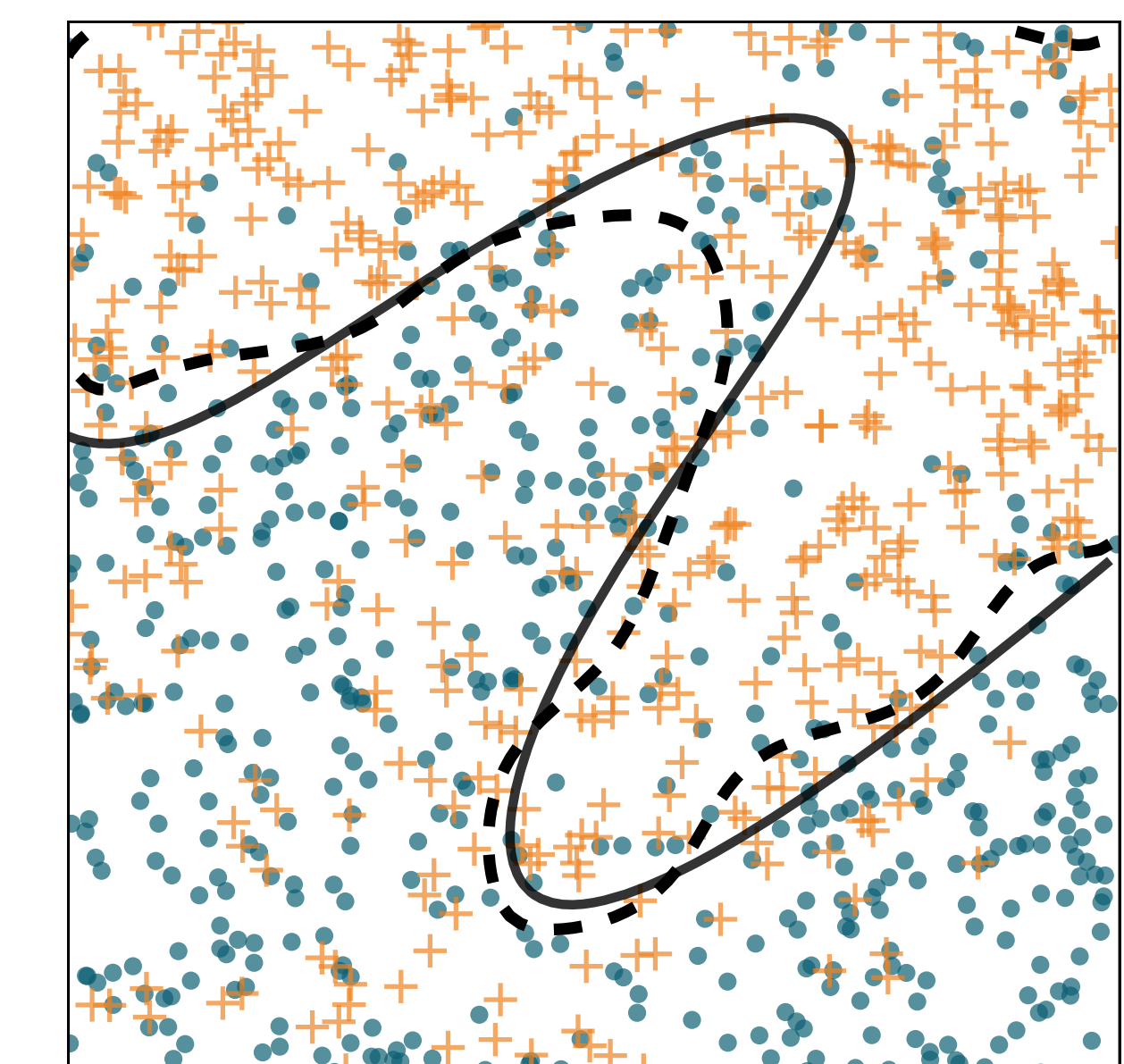
Corollary

If the degree d grows sufficiently slowly in the number of observations, then our estimator $\hat{\gamma}$ is **consistent** in the **Hausdorff + diffeomorphic topology** of compact manifold space.

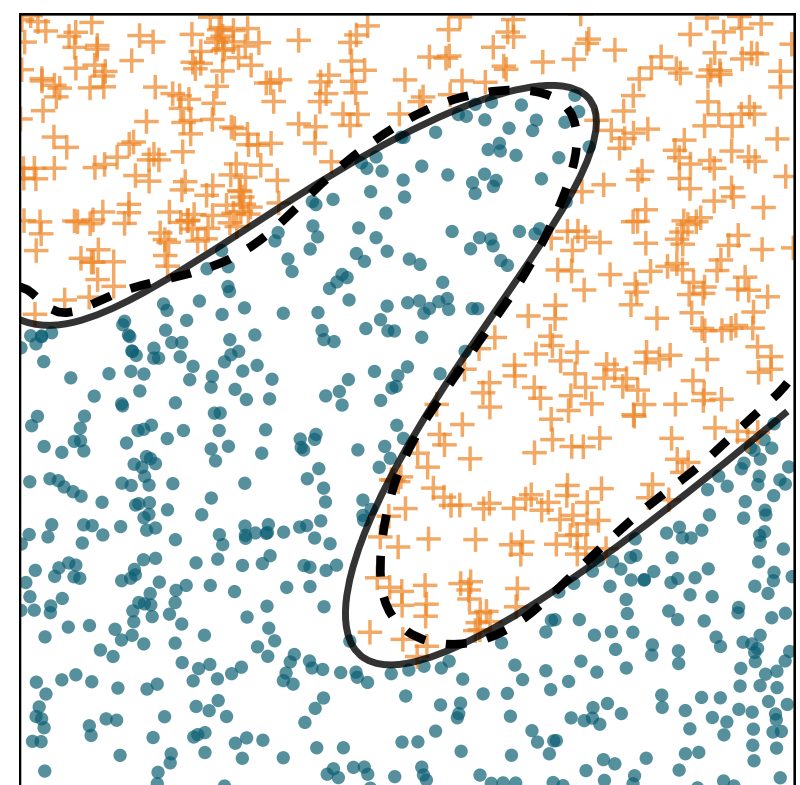
* i.e. \hat{f}_d almost surely converges to p in the Sobolev norm.

Examples

Binary classification:

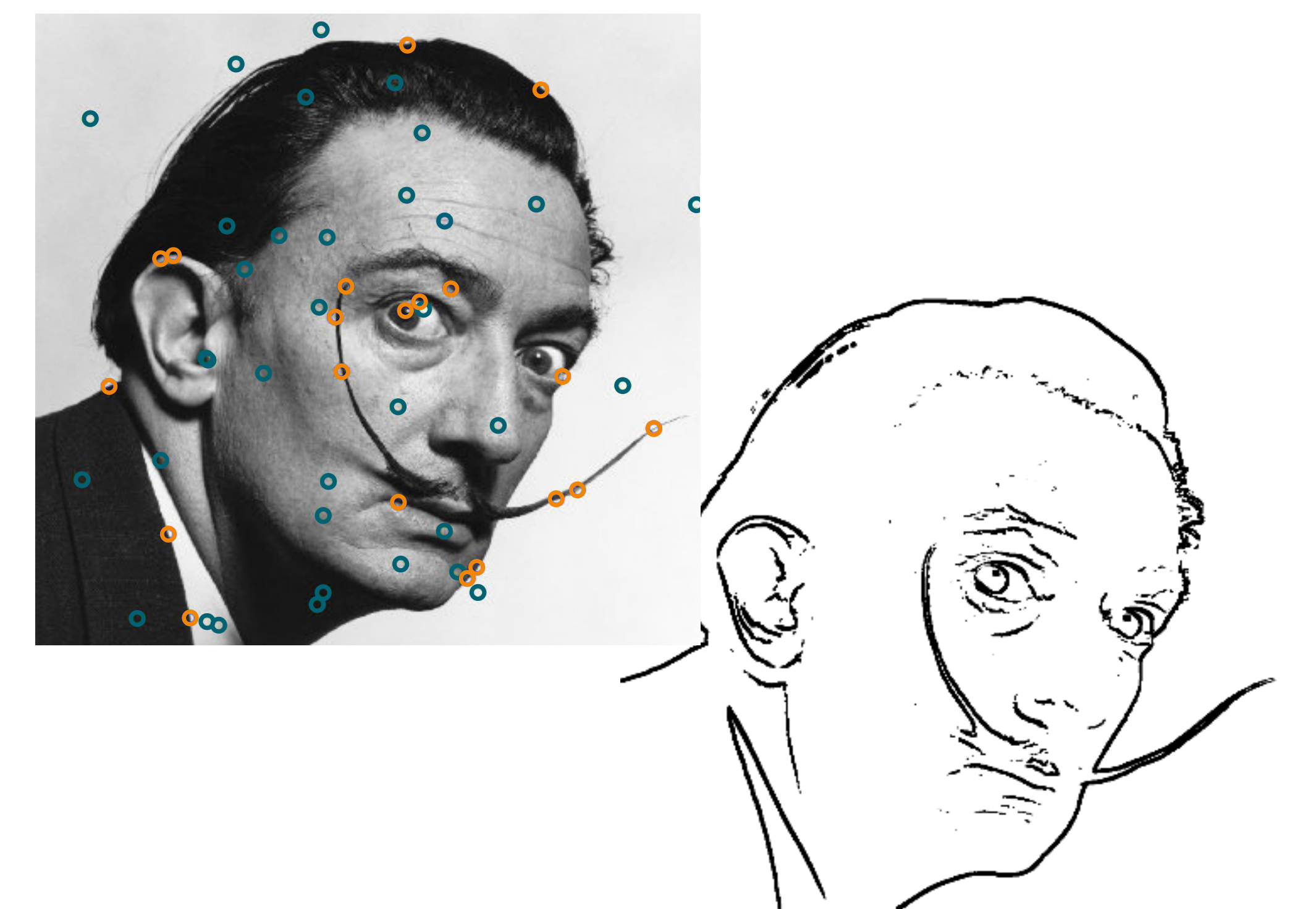


noise



no noise

Supervised edge detection:



References

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- Lima, E.K. (1988) The Jordan-Brouwer separation theorem for smooth hypersurfaces. *Amer. Math. Monthly* 95 (1)
- Telyakovskii, S. A. (2008) On the approximation of differentiable functions by Bernstein polynomials and Kantorovich polynomials. *Proc. Steklov Inst. Math.* 260 (1)
- Kollar, J. (2017) Nash's Work in Real Algebraic Geometry. *Bull. Amer. Math. Soc. (N.S.)* 54 (2)