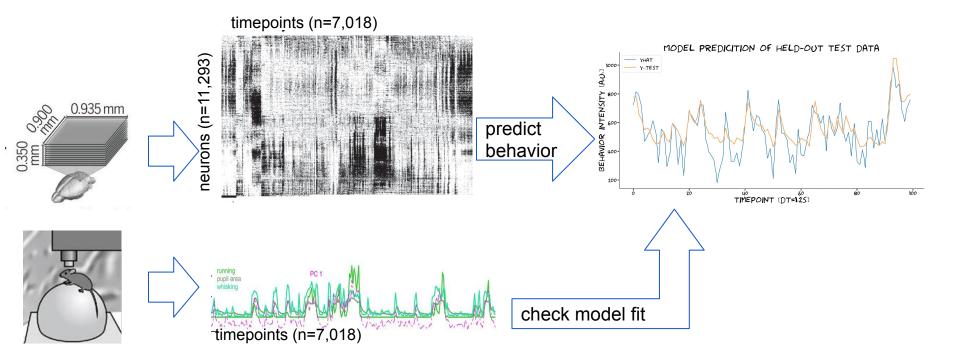
Decoding motion from visual cortex



By: Olukayode, Polina, Tristan, Verena, Yang, Zhiyi Compsognathus Belly / Hypertuned



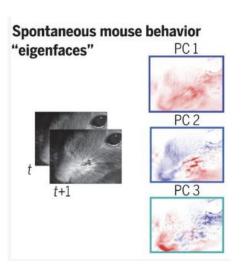
Are different motor behaviors encoded by overlapping populations in V1

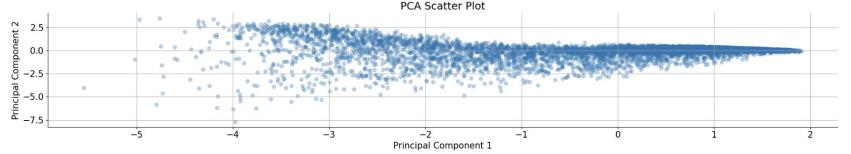


PCA analysis on behavioral data

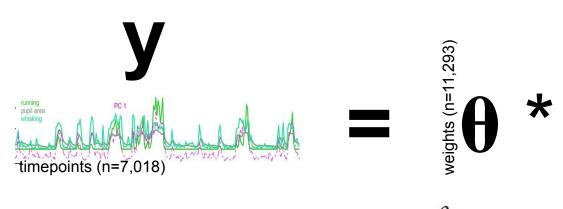
Behavioral data: pupil diameter, eye speed, running speed, eigenfaces

Main conclusion: PC1 and PC2 explains 84% of variance of behavioral data => <u>Different behavioral datasets is highly correlated</u>





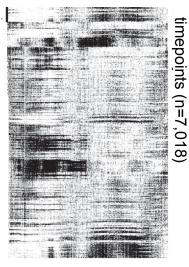
L2 - regularized linear model



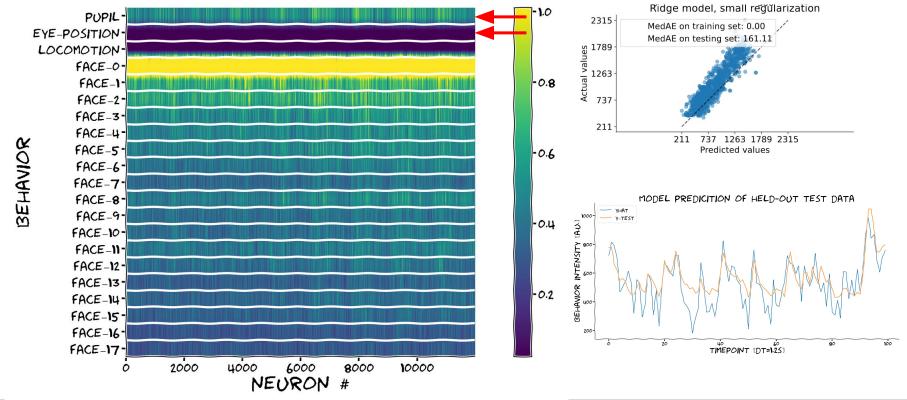
$$-\log \mathcal{L}'(\theta|X,y) = -\log \mathcal{L}(\theta|X,y) + \frac{\beta}{2} \sum_{i} \theta_{i}^{2}$$

- optimize for β
- 2. solve for θ

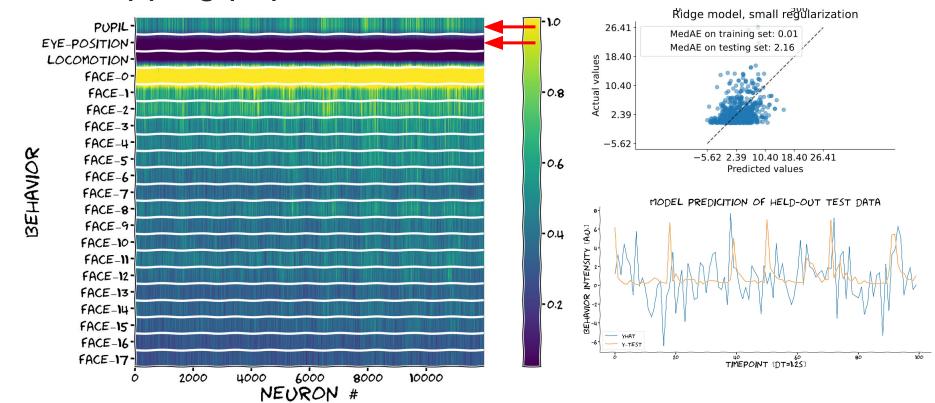




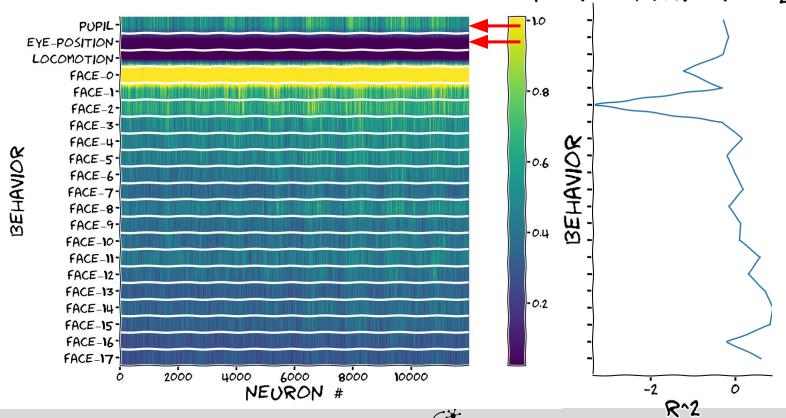
Overlapping populations encode different behaviors



Overlapping populations encode different behaviors

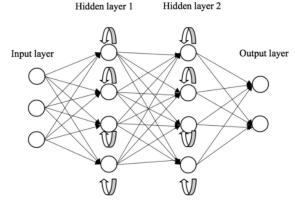


COEFFICIENT OF DETERMINATION PER BEHAVIOR MODEL



RNN

Input: subset of neurons and timepoints



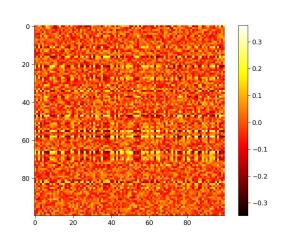
General Form of RNNs

Output:

prediction of pupil size per timepoint based on neural activity

Weight matrix layer1 (100 hidden units):

Training → learn weights between units (How strongly units are connected and contribute to the prediction of pupil size)



Future:

- optimize model parameters
- evaluate model performance
- train model for further behaviors (running speed, whisking), ... & compare models
- Prediction: if different motor behaviors are encoded by overlapping V1 populations, model performance should be similar



Discussion

- Different behavioral datasets (pupil diameter, eye speed, running speed, eigenfaces) is highly correlated
- Overlapping V1 populations most likely encode this shared behavior dimension, not precise motor output

What we tried:

- UMAP on neuronal data ->
 gives us fixed values, but we
 want to predict varying data ->
 not suitable
- GLM from scratch -> to understand the math
- L1 regularisation model on pupil diameter, running speed and pupil position
- RNN



Thank you for your attention!

Many thanks to our mentors - Nando, Aalok, Enny

Happy to answer your questions





