

# Microcontroller

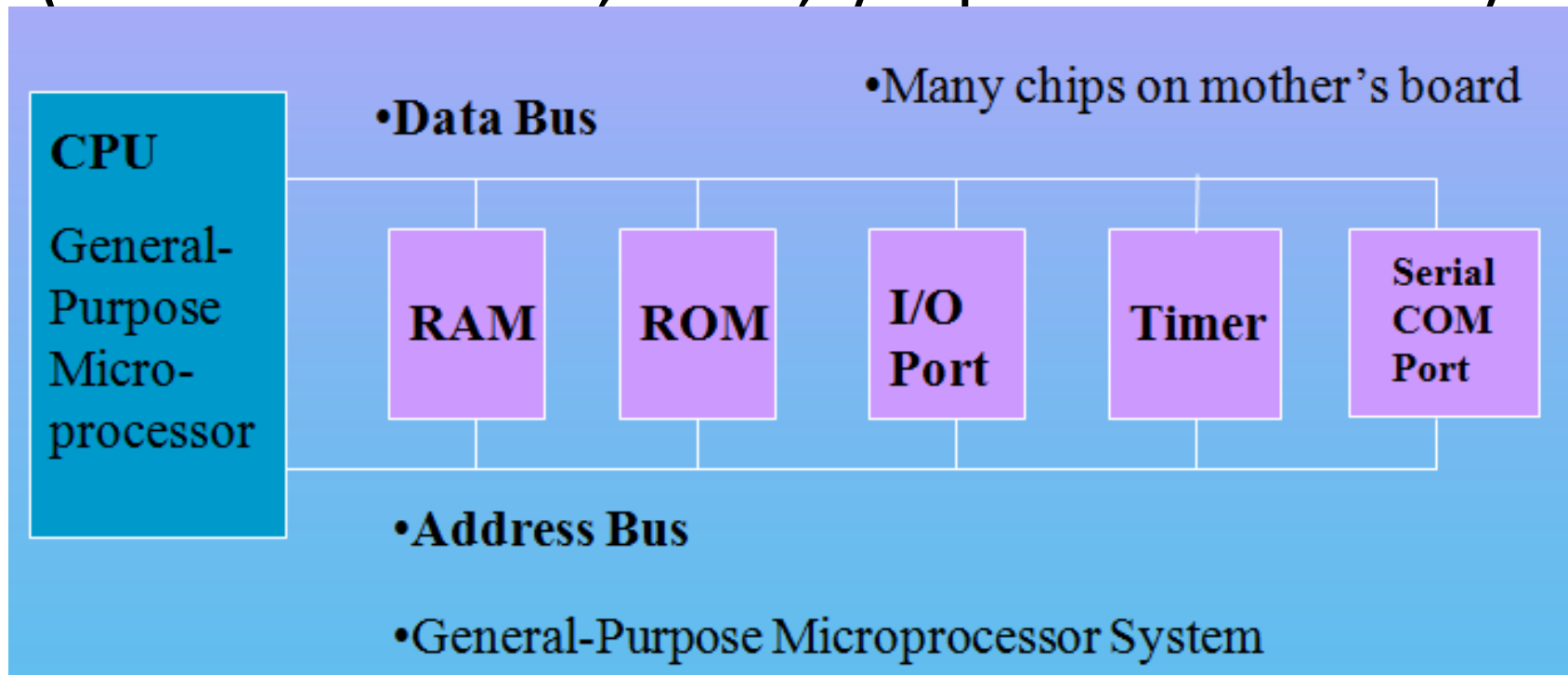
8051

# Microprocessor Based System

CPU

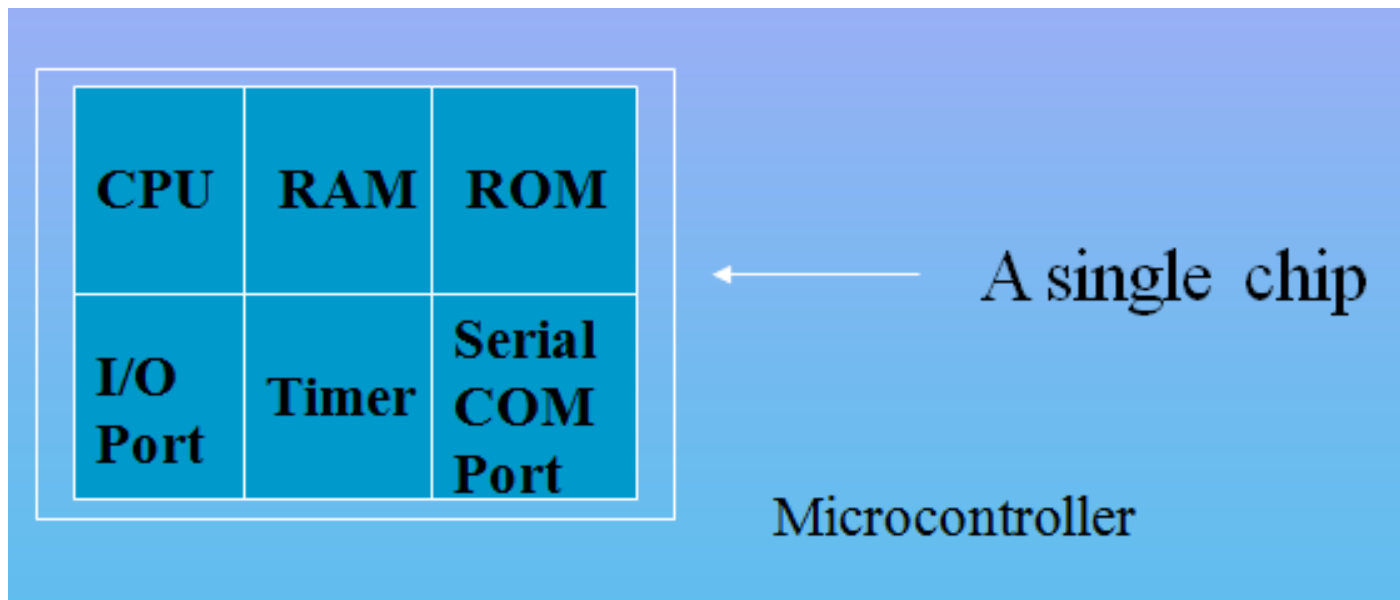
External RAM, ROM, I/O

(No internal RAM, ROM, I/O ports in the CPU)



# Microcontroller

- A smaller computer on a CHIP
- On-chip RAM, ROM, I/O Ports, Timer, Serial Controller...
- Example: Motorola's 6811, Intel's 8051, Atmel 32



# Microprocessor vs. Microcontroller

## Microprocessor

- CPU is stand-alone, RAM, ROM, I/O, timer are separate
- Designer can decide on the amount of ROM, RAM and I/O ports.
- Expensive
- Versatility
- General-purpose

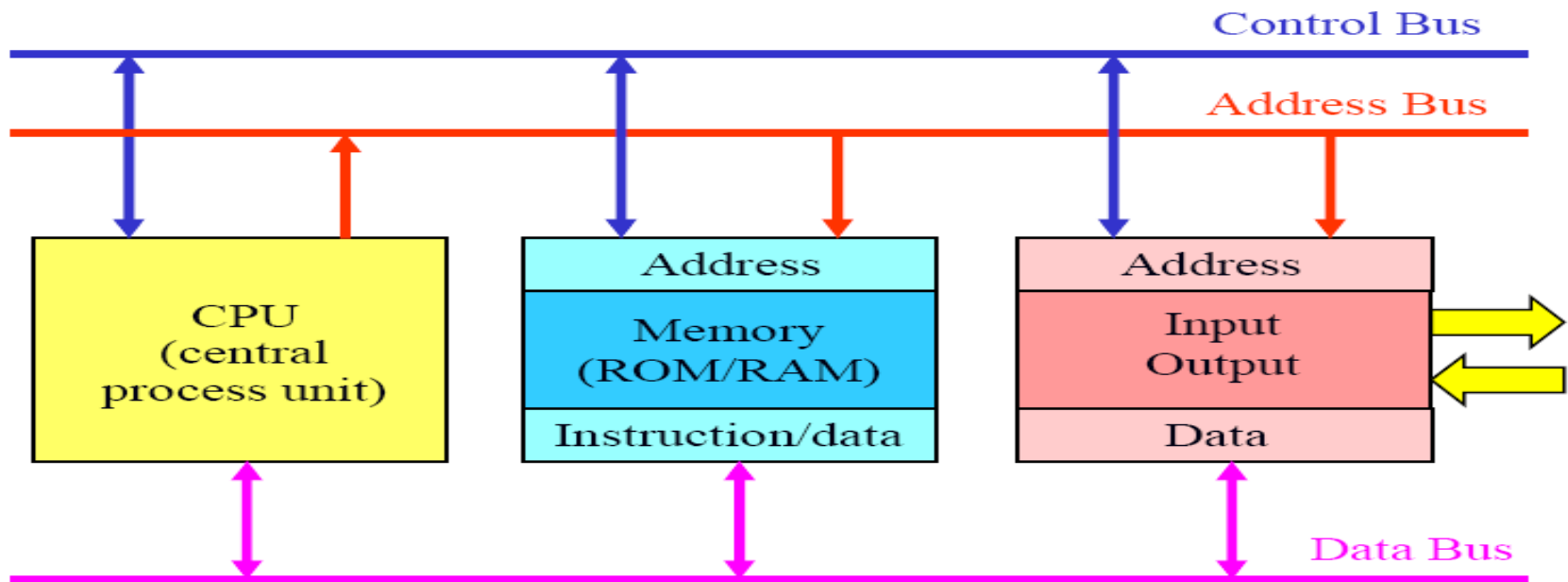
## Microcontroller

- CPU, RAM, ROM, I/O and timer are all on a single chip
- Fixed amount of on-chip ROM, RAM, I/O ports
- Not Expensive
- Single-purpose
- Special Purpose.

# Von Neumann Architecture

Von Neumann Architecture—another type of computer architecture where the instructions and data are stored in the same memory space

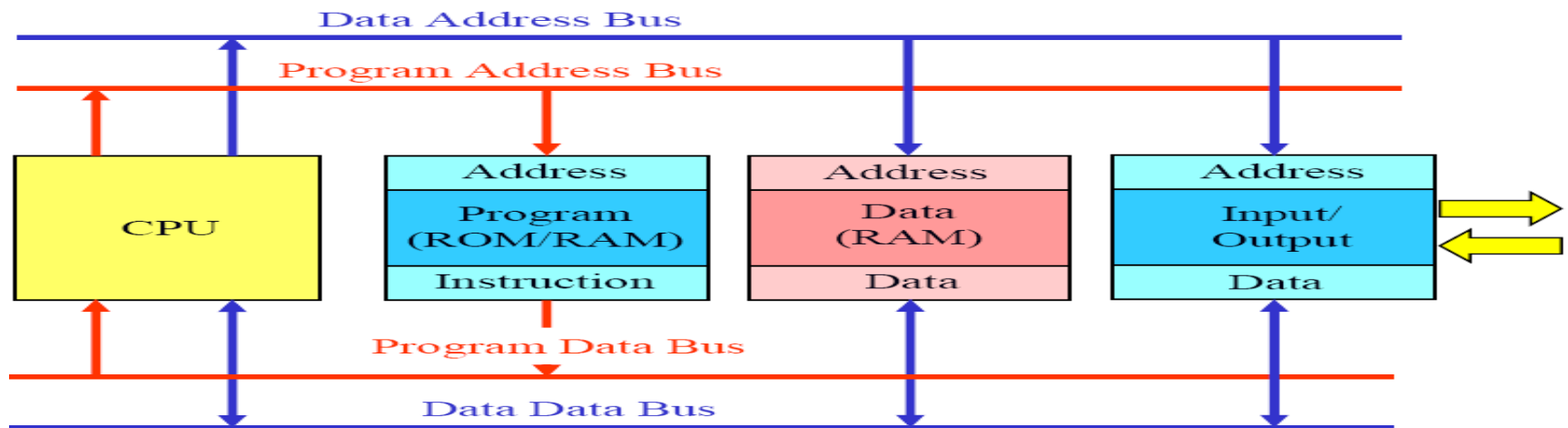
Example: Intel x86 architecture (Intel Pentium, AMD Athlon, etc.)



# Harvard Architecture

Harvard Architecture—a type of computer architecture where the instructions (program code) and data are stored in separate memory spaces

Example: Intel 8051 architecture



Often separate buses are used to access memory and inputs/outputs

# 8051 CPU Operation

1. Features

2. Pin Diagram

3. Block Diagram

# 8051 Microcontroller

- Intel introduced 8051, referred as MCS- 51, in 1981.
- The 8051 is an **8-bit processor**
  - The CPU can work on only 8 bits of data at a time
- The 8051 became widely popular after allowing other manufactures to make and market any flavor of the 8051.



# Features of 8051

8 bit Processor

4KB Internal ROM

128 Bytes Internal RAM

Four 8 BIT I/O PORTS (32 I/O LINES)

Two 16 Bit Timers/Counters

On Chip Full Duplex UART for Serial Communication

5 Vector Interrupts ( 2 External, 3 Internal - Timer0,Timer1,Serial)

On Chip Clock Oscillator

16 bit Address bus

64k External Code Memory

64k External Data Memory

16-bit program counter to access external Code Memory and

16 bit Data Pointer to access external Data Memory

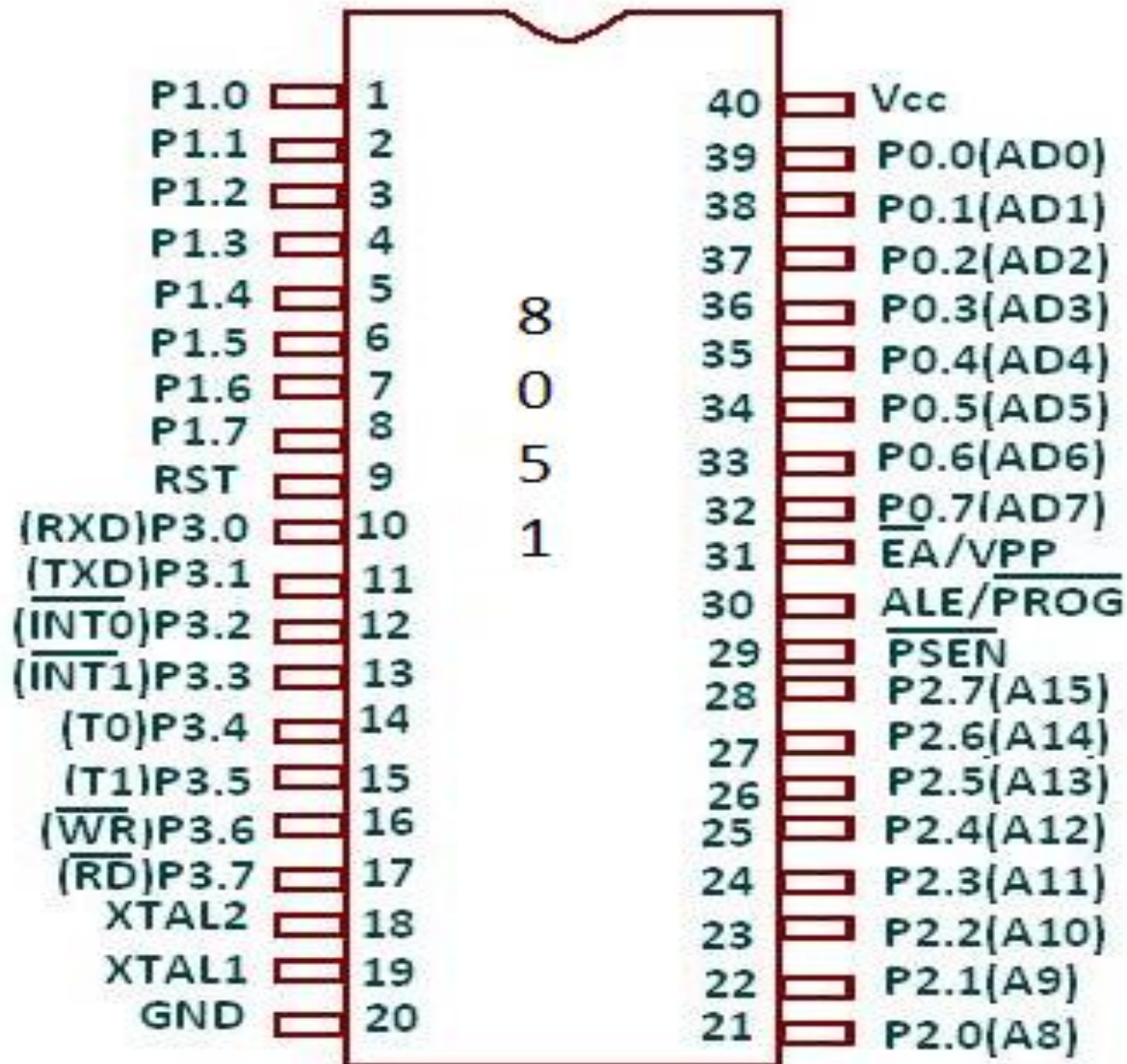
128 user defined flags

# 8051 Family

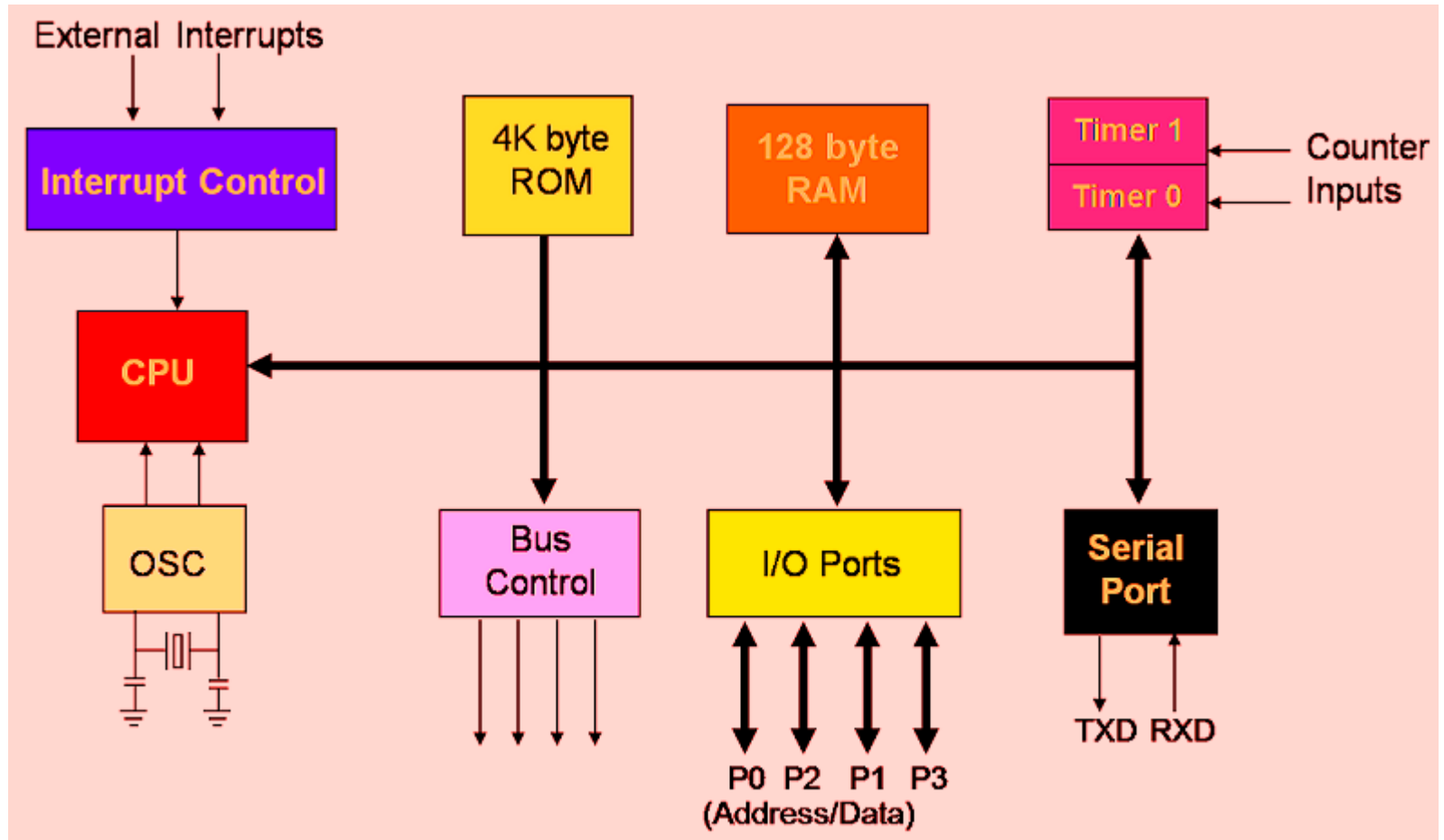
- The 8051 is a subset of the 8052
- The 8031 is a ROM-less 8051
  - Add external ROM to it
  - You lose two ports, and leave only 2 ports for I/O operations

Feature	8051	8052	8031
ROM (on-chip program space in bytes)	4K	8K	0K
RAM (bytes)	128	256	128
Timers	2	3	2
I/O pins	32	32	32
Serial port	1	1	1
Interrupt sources	6	8	6

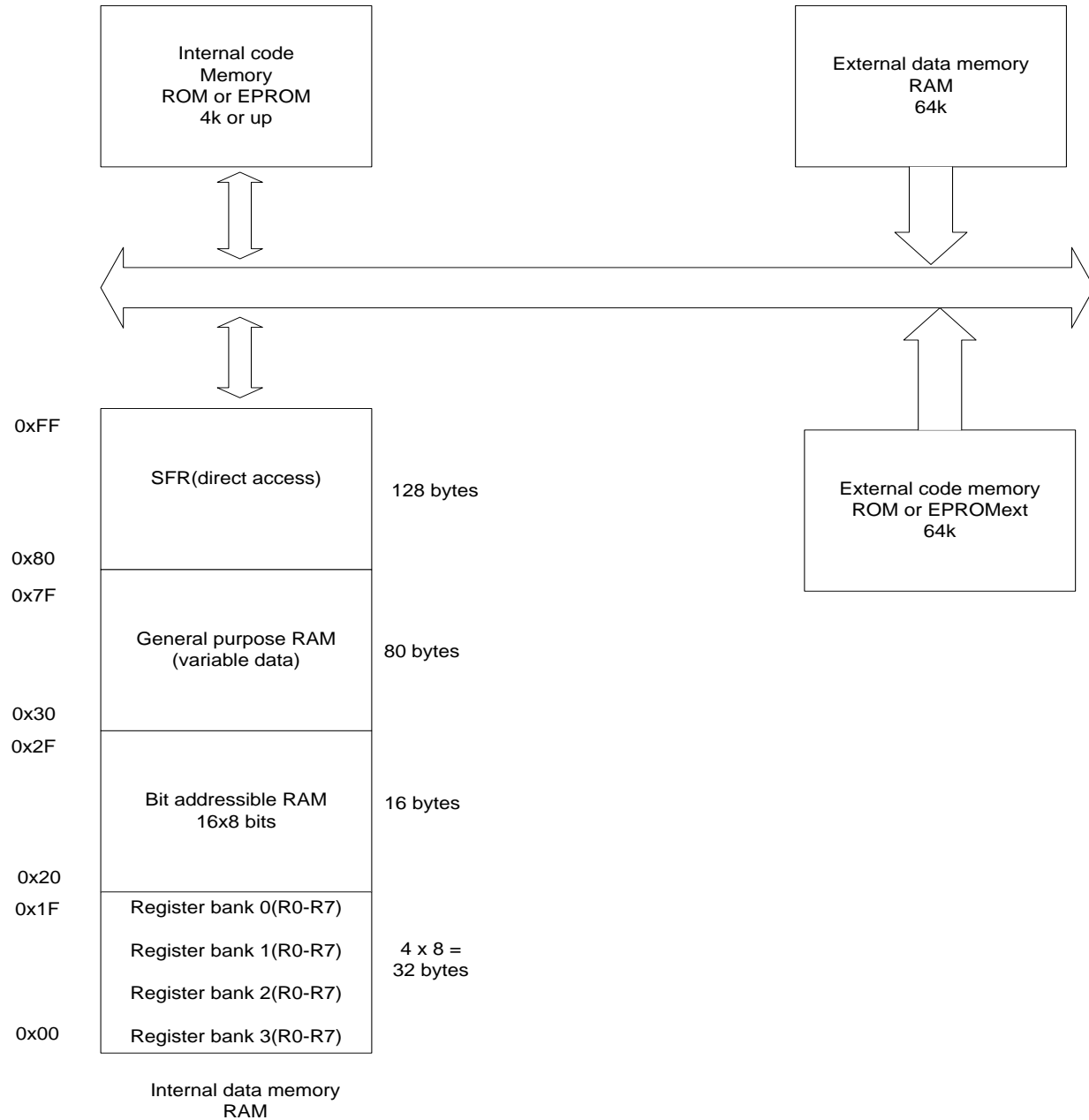
# Pin Diagram



# Block Diagram of 8051



# Separate read instructions for external data and code memory.

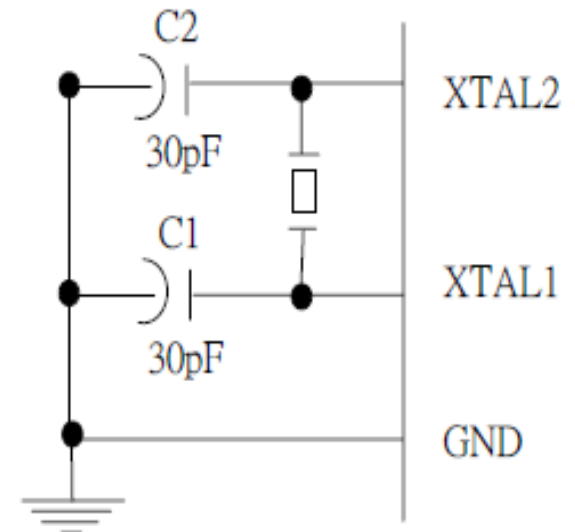


# Pin Description of the 8051

- 8051 family members (e.g., 8751, 89C51, 89C52, DS89C4x0)
  - Have **40 pins** dedicated for various functions such as I/O, RD, WR, address, data, and interrupts.
  - Come in different packages, such as
    - *DIP(dual in-line package),*
    - *QFP(quad flat package), and*
    - *LLC(leadless chip carrier)*
- Some companies provide a 20-pin version of the 8051 with a reduced number of I/O ports for less demanding applications

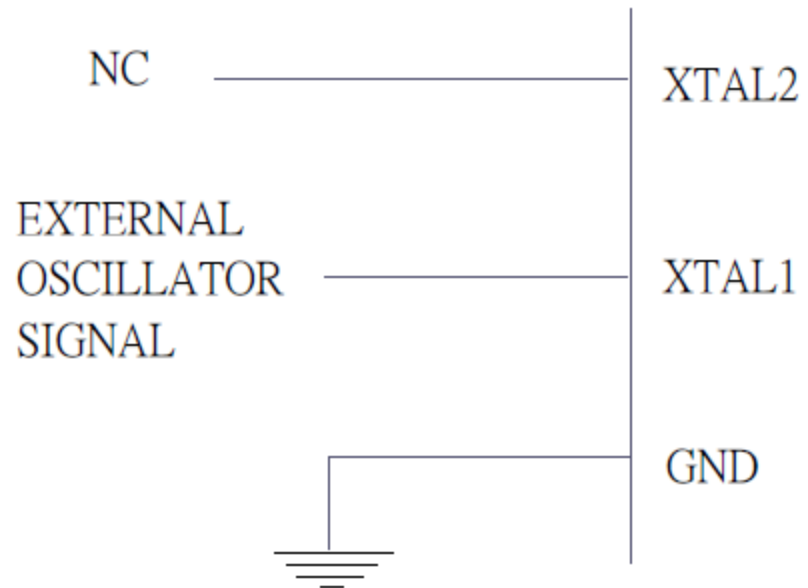
# XTAL1 and XTAL2

- The 8051 has an on-chip oscillator but requires an external crystal to run it
  - A quartz crystal oscillator is connected to inputs XTAL1 (pin19) and XTAL2 (pin18)
  - The quartz crystal oscillator also needs two capacitors of 30 pF value
  - The original 8051 operates at 12 MHz



# XTAL1 and XTAL2 .....

- If you use a frequency source other than a crystal oscillator, such as a TTL oscillator:
  - It will be connected to XTAL1
  - XTAL2 is left unconnected





# RST

- RESET pin is an input and is active high (normally low)
- Upon applying a high pulse to this pin, the microcontroller will reset and terminate all activities
- This is often referred to as a power-on reset
- Activating a power-on reset will cause all values in the registers to be lost

RESET value of some  
8051 registers

we must place  
the first line of  
source code in  
ROM location 0

Register	Reset Value
PC	0000
DPTR	0000
ACC	00
PSW	00
SP	07
B	00
P0-P3	FF

# EA'

- EA', “external access”, is an input pin and must be connected to Vcc or GND
- The 8051 family members all come with on-chip ROM to store programs and also have an external code and data memory.
- Normally EA pin is connected to Vcc (Internal Access)
- EA pin must be connected to GND to indicate that the code or data is stored externally.

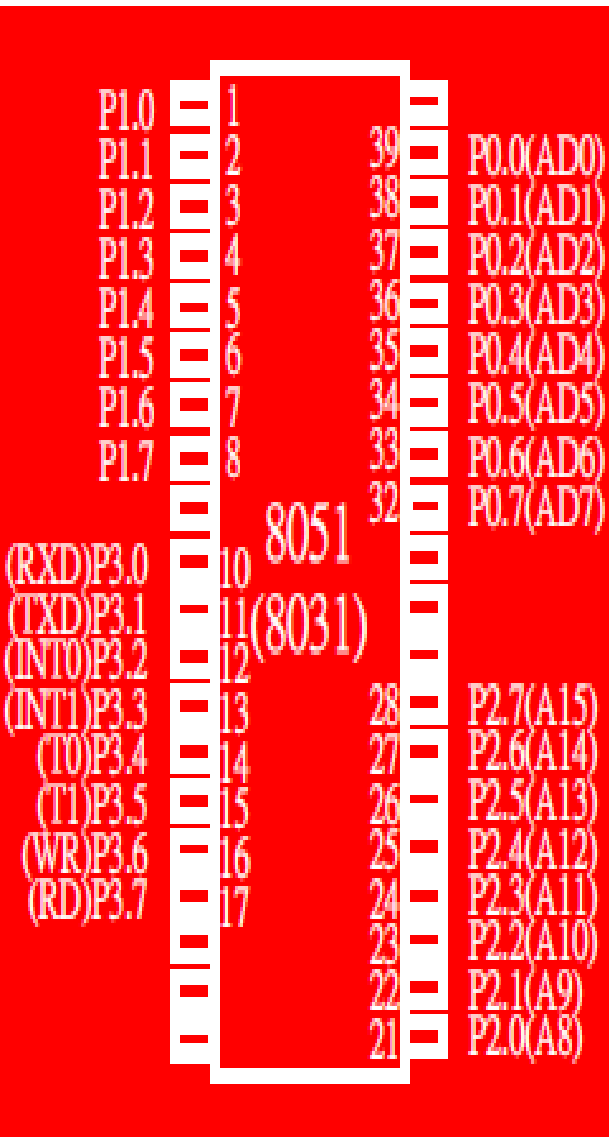
# PSEN' and ALE

- PSEN, “program store enable”, is an output pin
- This pin is connected to the OE pin of the external memory.
- For External Code Memory,  $PSEN' = 0$
- For External Data Memory,  $PSEN' = 1$
- ALE pin is used for demultiplexing the address and data.

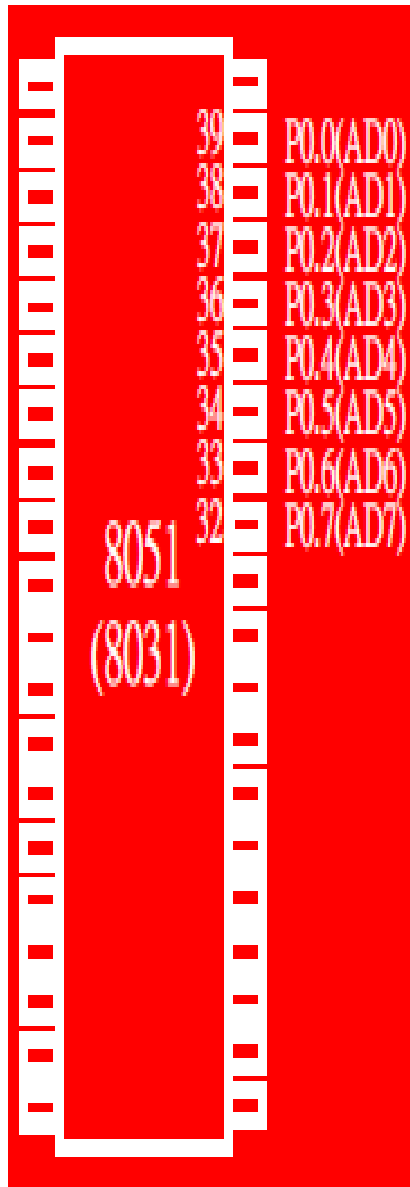
# I/O Port Pins

The four 8-bit I/O ports **P0**, **P1**, **P2** and **P3** each uses 8 pins.

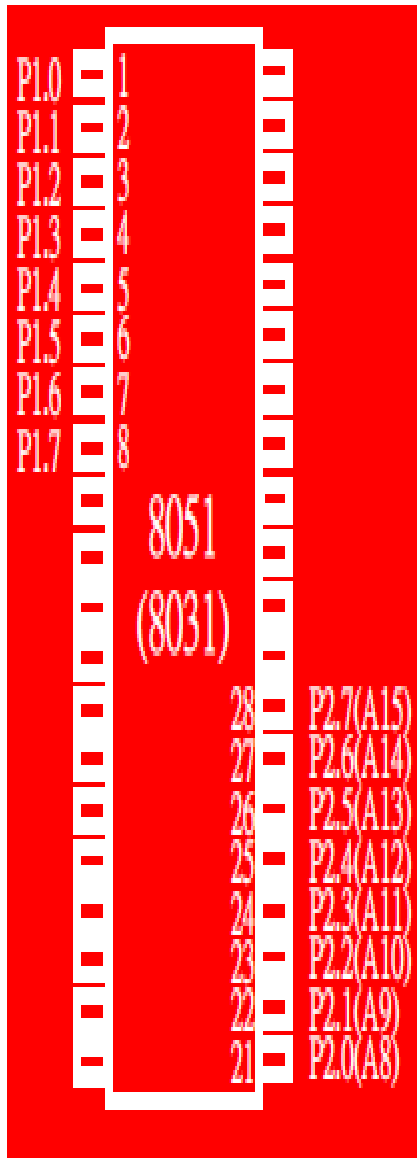
All the ports upon RESET are configured as output, ready to be used as input ports by the external device.



# Port 0



- Port 0 is **also** designated as **AD0-AD7**.
- When connecting an 8051 to an external memory, port 0 provides both address and data.
- The 8051 multiplexes address and data through port 0 to save pins.
- **ALE** indicates if P0 has address or data.
  - *When ALE=0, it provides data D0-D7*
  - *When ALE=1, it has address A0-A7*



# Port 1 and Port 2

- In 8051-based systems **with no external memory connection**:
  - Both P1 and P2 are used as simple I/O.
- In 8051-based systems **with external memory connections**:
  - Port 2 must be used along with P0 to provide the 16-bit address for the external memory.
  - P0 provides the lower 8 bits via A0 – A7.
  - P2 is used for the upper 8 bits of the 16-bit address, designated as A8 – A15, and it cannot be used for I/O.

# Port 3

P3 Bit	Function	Pin	
P3.0	RxD	10	{ Serial communications
P3.1	TxD	11	
P3.2	<u>INT0</u>	12	{ External interrupts
P3.3	<u>INT1</u>	13	
P3.4	T0	14	{ Timers
P3.5	T1	15	
P3.6	<u>WR</u>	16	{ Read/Write signals of external memories
P3.7	<u>RD</u>	17	

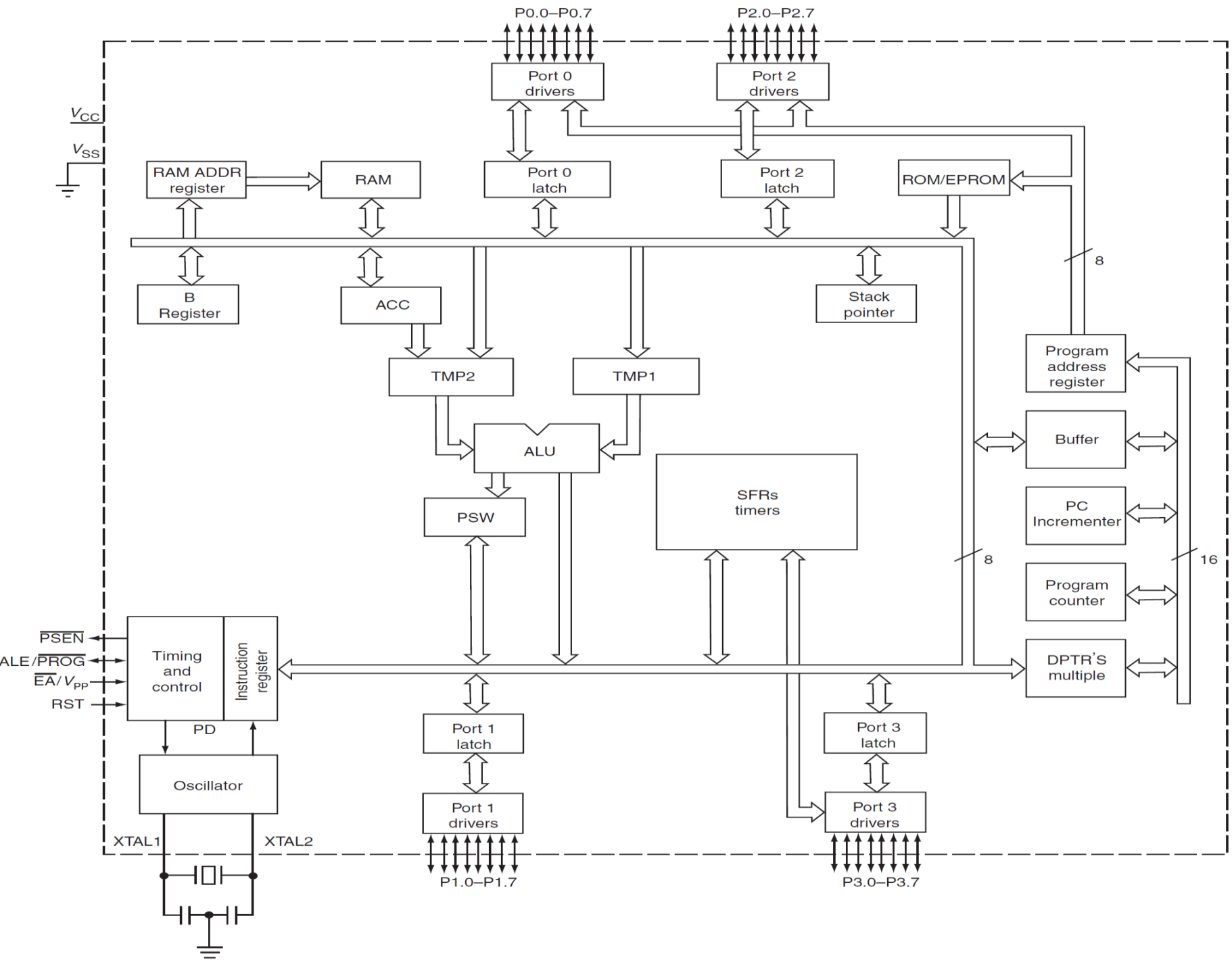
# Pin Description Summary

PIN	TYPE	NAME AND FUNCTION
Vss	I	Ground: 0 V reference.
Vcc	I	Power Supply: This is the power supply voltage for normal, idle, and power-down operation.
P0.0 - P0.7	I/O	Port 0: Port 0 is an open-drain, bi-directional I/O port. Port 0 is also the multiplexed low-order address and data bus during accesses to external program and data memory.
P1.0 - P1.7	I/O	Port 1: Port 1 is an 8-bit bi-directional I/O port.
P2.0 - P2.7	I/O	Port 2: Port 2 is an 8-bit bidirectional I/O. Port 2 emits the high order address byte during fetches from external program memory and during accesses to external data memory that use 16 bit addresses.
P3.0 - P3.7	I/O	Port 3: Port 3 is an 8 bit bidirectional I/O port. Port 3 also serves special features as explained.



# Pin Description Summary

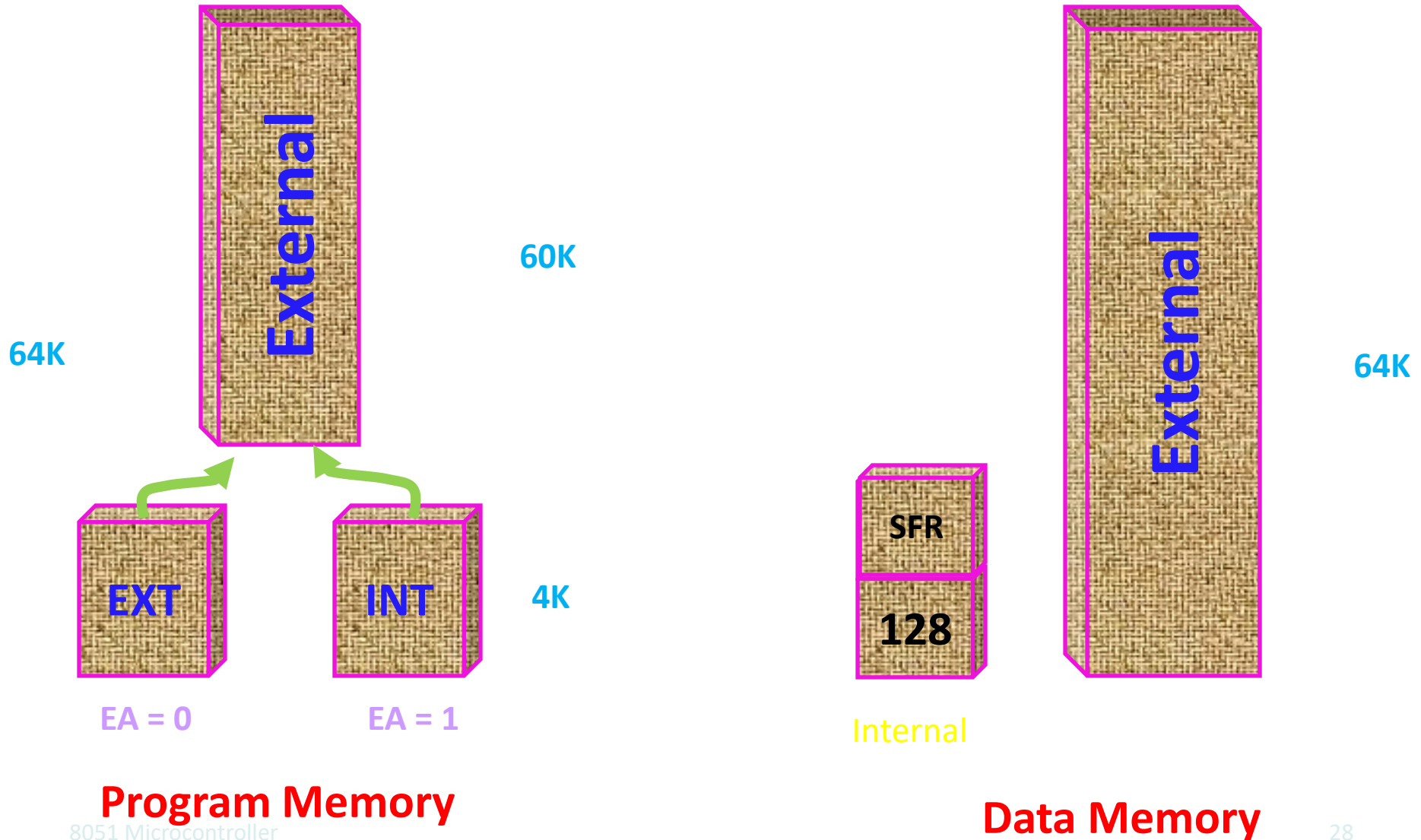
PIN	TYPE	NAME AND FUNCTION
RST	I	Reset: A high on this pin for two machine cycles while the oscillator is running, resets the device.
ALE	O	Address Latch Enable: Output pulse for latching the low byte of the address during an access to external memory.
PSEN*	O	Program Store Enable: The read strobe to external program memory. When executing code from the external program memory, PSEN* is activated twice each machine cycle, except that two PSEN* activations are skipped during each access to external data memory.
EA*/VPP	I	External Access Enable/Programming Supply Voltage: EA* must be externally held low to enable the device to fetch code from external program memory locations. If EA* is held high, the device executes from internal program memory. This pin also receives the programming supply voltage Vpp during Flash programming. (applies for 89c5x MCU's)



# 8051

# Memory Space

# 8051 Memory Structure



# Internal RAM Structure

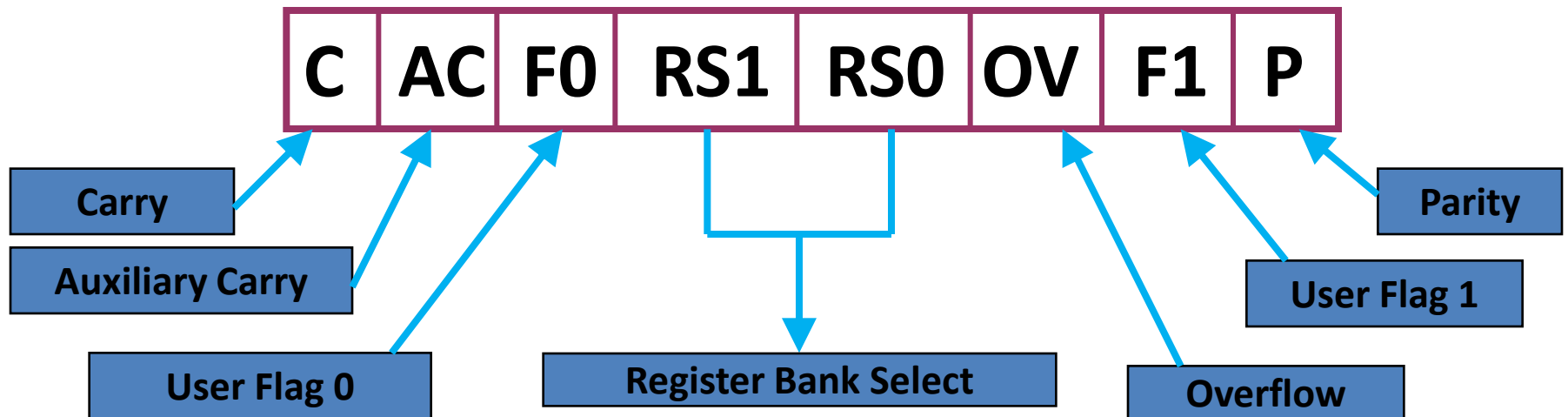


# Special function register

80	PO
81	SP
82	DPL
83	DPH
87	PCON
88	TCON
89	TMOD
8A	TL0
8B	TL1
8C	TH0
8D	TH1

90	P1
98	SCON
99	SBUF
A0	P2
A8	IE
B0	P3
B8	IP
D0	PSW
E0	ACC
F0	B

# Program Status Word [PSW]



# 8051 instructions that affects flag

Instruction	CY	OV	AC
ADD	X	X	X
ADDC	X	X	X
SUBB	X	X	X
MUL	0	X	
DIV	0	X	
DA	X		
RPC	X		
PLC	X		
SETB C	1		
CLR C	0		
CPL C	X		
ANL C, bit	X		
ANL C, /bit	X		
ORL C, bit	X		
ORL C, /bit	X		
MOV C, bit	X		
CJNE	X		

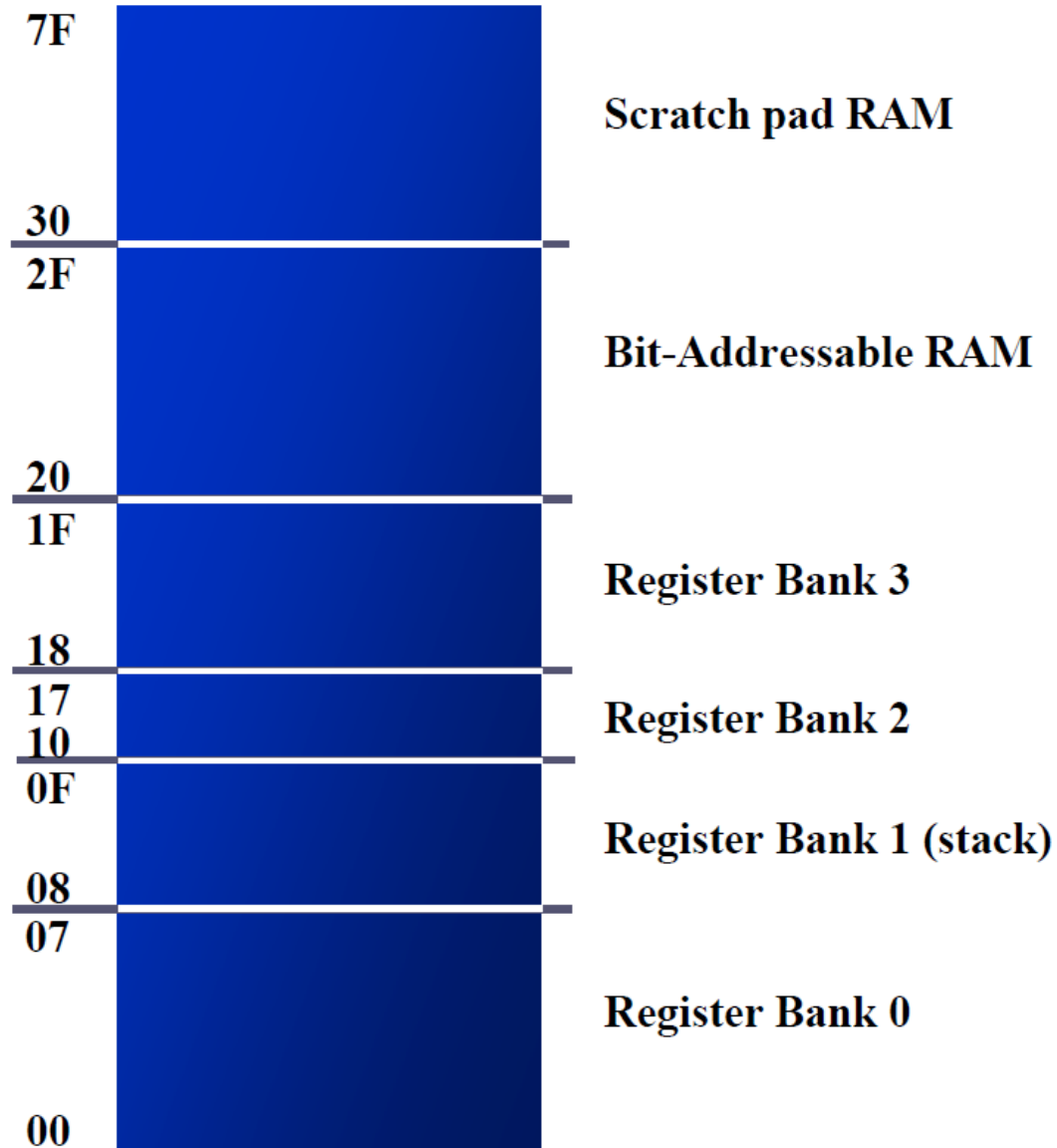


# 128 Byte RAM

- There are 128 bytes of RAM in the 8051.
  - Assigned addresses 00 to 7FH
- The **128 bytes are divided into 3 different groups** as follows:
  1. A total of **32 bytes** from locations 00 to 1F hex are set aside for **register banks** and the **stack**.
  2. A total of **16 bytes** from locations 20H to 2FH are set aside for **bit-addressable** read/write memory.
  3. A total of **80 bytes** from locations 30H to 7FH are used for read and write storage, called **scratch pad**.



# 8051 RAM with addresses



# 8051 Register Bank Structure



# 8051 Register Banks with address

Register bank 0		Register bank 1		Register bank 2		Register bank 3	
00	R0	08	R0	10	R0	18	R0
01	R1	09	R1	11	R1	19	R1
02	R2	0A	R2	12	R2	1A	R2
03	R3	0B	R3	13	R3	1B	R3
04	R4	0C	R4	14	R4	1C	R4
05	R5	0D	R5	15	R5	1D	R5
06	R6	0E	R6	16	R6	1E	R6
07	R7	0F	R7	17	R7	1F	R7

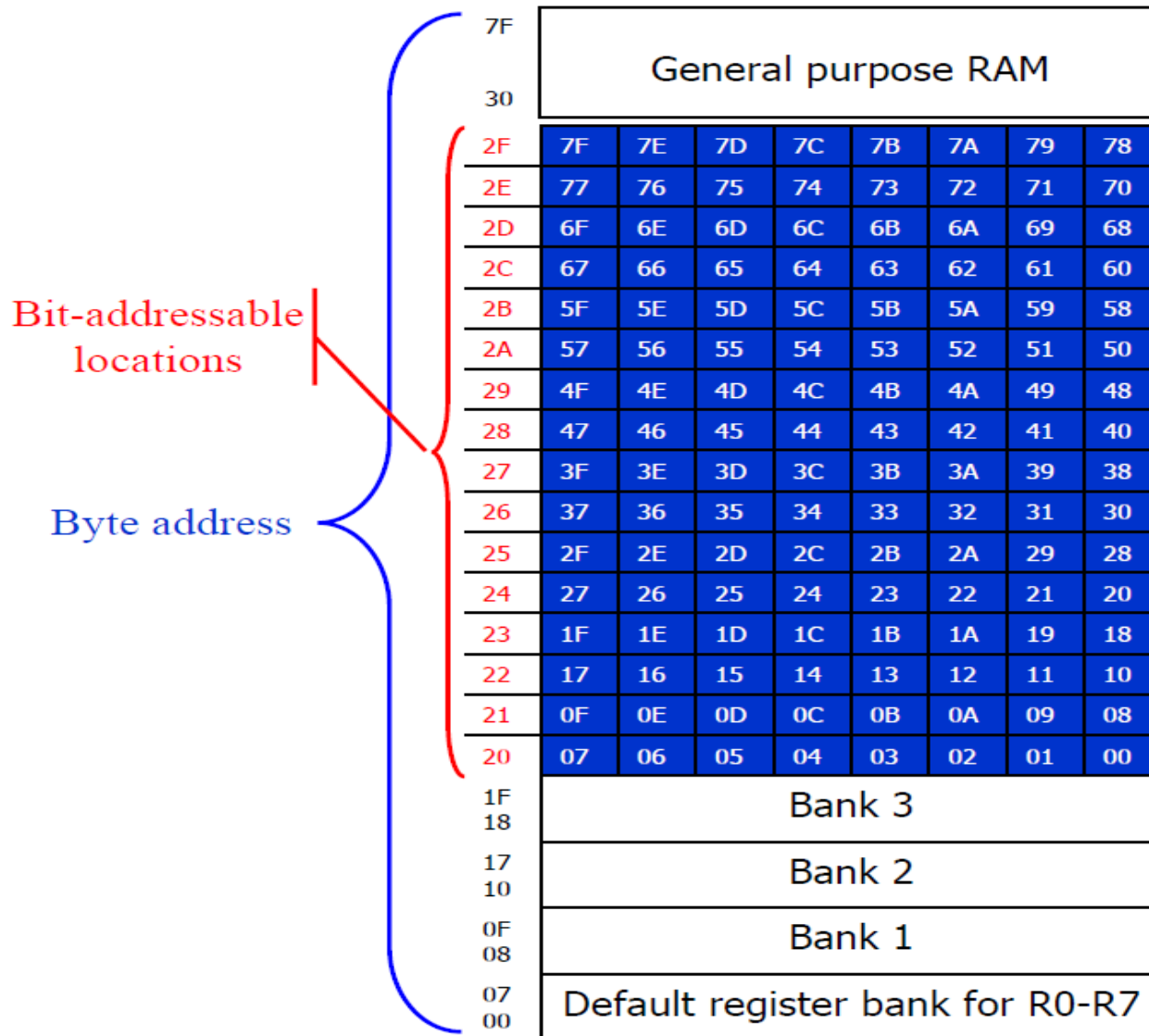
# 8051 Stack

- The **stack** is a section of RAM used by the CPU to store information **temporarily**.
  - This information could be data or an address
- The register used to access the stack is called the **SP (stack pointer) register**
  - The stack pointer in the 8051 is **only 8 bit wide**, which means that it can take value of 00 to FFH
  - When the 8051 is powered up, the SP register contains value 07
  - RAM location 08 is the first location begin used for the stack by the 8051

# 8051 Stack

- The storing of a CPU register in the stack is called a **PUSH**
  - SP is pointing to the last used location of the stack
  - As we push data onto the stack, the **SP is incremented** by one
  - This is **different** from many microprocessors
- Loading the contents of the stack back into a CPU register is called a **POP**
  - With every pop, the top byte of the stack is copied to the register specified by the instruction and the stack pointer is **decremented** once

# Bit Addressable & Byte Addressable



# Single bit Instructions

## Single-Bit Instructions

Instruction	Function
SETB bit	Set the bit (bit = 1)
CLR bit	Clear the bit (bit = 0)
CPL bit	Complement the bit (bit = NOT bit)
JB bit, target	Jump to target if bit = 1 (jump if bit)
JNB bit, target	Jump to target if bit = 0 (jump if no bit)
JBC bit, target	Jump to target if bit = 1, clear bit (jump if bit, then clear)



# Bit Addressable Programming

- Example:** Find out to which by each of the following bits belongs. Give the address of the RAM byte in hex

(a) SETB 42H, (b) CLR 67H, (c) CLR 0FH (d) SETB 28H, (e) CLR 12, (f) SETB 05

**Solution:**

(a) D2 of RAM location 28H

(b) D7 of RAM location 2CH

(c) D7 of RAM location 21H

(d) D0 of RAM location 25H

(e) D4 of RAM location 21H

(f) D5 of RAM location 20H

	D7	D6	D5	D4	D3	D2	D1	D0
2F	7F	7E	7D	7C	7B	7A	79	78
2E	77	76	75	74	73	72	71	70
2D	6F	6E	6D	6C	6B	6A	69	68
2C	67	66	65	64	63	62	61	60
2B	5F	5E	5D	5C	5B	5A	59	58
2A	57	56	55	54	53	52	51	50
29	4F	4E	4D	4C	4B	4A	49	48
28	47	46	45	44	43	42	41	40
27	3F	3E	3D	3C	3B	3A	39	38
26	37	36	35	34	33	32	31	30
25	2F	2E	2D	2C	2B	2A	29	28
24	27	26	25	24	23	22	21	20
23	1F	1E	1D	1C	1B	1A	19	18
22	17	16	15	14	13	12	11	10
21	0F	0E	0D	0C	0B	0A	09	08
20	07	06	05	04	03	02	01	00

# 8051 Software Overview

1. Addressing Modes
2. Instruction Set
3. Programming

# 8051 Addressing Modes

- The CPU can access data in various ways, which are called addressing modes

1. Immediate
2. Register
3. Direct
4. Register indirect
5. External Direct

# Immediate Addressing Mode

- The source operand is a **constant**.
- The immediate data must be preceded by the pound sign, “#”
- Can load information into **any registers**, including 16-bit DPTR register
  - DPTR can also be accessed as two 8-bit registers, the high byte DPH and low byte DPL

```
MOV A, #25H      ;load 25H into A
MOV R4, #62      ;load 62 into R4
MOV B, #40H      ;load 40H into B
MOV DPTR, #4521H ;DPTR=4512H
MOV DPL, #21H    ;This is the same
MOV DPH, #45H    ;as above

;illegal!! Value > 65535 (FFFFH)
MOV DPTR, #68975
```

# Register Addressing Mode

- Use registers to hold the data to be manipulated.

```
MOV A,R0      ;copy contents of R0 into A
MOV R2,A      ;copy contents of A into R2
ADD A,R5      ;add contents of R5 to A
ADD A,R7      ;add contents of R7 to A
MOV R6,A      ;save accumulator in R6
```

- The source and destination registers must match in size.

**MOV DPTR,A** will give an error

```
MOV DPTR,#25F5H
MOV R7,DPL
MOV R6,DPH
```

- The movement of data between Rn registers is not allowed

**MOV R4,R7** is invalid

# Direct Addressing Mode

- It is most often used the direct addressing mode to access RAM locations 30 – 7FH.
- The entire 128 bytes of RAM can be accessed.
- Contrast this with immediate addressing mode, there is no “#” sign in the operand.

MOV R0,40H ;save content of 40H in R0

MOV 56H,A ;save content of A in 56H

# SFR Registers & their Addresses

**MOV 0E0H,#55H** ;is the same as  
**MOV A,#55H** ;which means load 55H into A (A=55H)

**MOV 0F0H,#25H** ;is the same as  
**MOV B,#25H** ;which means load 25H into B (B=25H)

**MOV 0E0H,R2** ;is the same as  
**MOV A,R2** ;which means copy R2 into A

**MOV 0F0H,R0** ;is the same as  
**MOV B,R0** ;which means copy R0 into B

# Example

Write code to send 55H to port P1 and P2 using their names and their addresses.

```
1. MOV A,#55H  
   MOV P1,A  
   MOV P2,A
```

```
2. MOV A,#55H  
   MOV 80H,A  
   MOV 0A0,A
```



# Stack and Direct Addressing Mode

Show the code to push R5 and A onto the stack and then pop them back them into R2 and B, where  $B = A$  and  $R2 = R5$

## Solution:

```
PUSH 05      ;push R5 onto stack
PUSH 0E0H    ;push register A onto stack
POP  0F0H    ;pop top of stack into B
           ;now register B = register A
POP  02      ;pop top of stack into R2
           ;now R2=R6
```

# Register Indirect Addressing Mode

- A **register** is used as a pointer to the data.
- Only register **R0** and **R1** are used for this purpose.
- **R2 – R7** cannot be used to hold the address of an operand located in RAM.
- When **R0** and **R1** hold the addresses of RAM locations, they must be preceded by the “@” sign.

```
MOV A, @R0    ;move contents of RAM whose  
               ;address is held by R0 into A  
MOV @R1, B    ;move contents of B into RAM  
               ;whose address is held by R1
```

# Register Indirect Addressing Mode

- Write a program to copy the value 55H into RAM memory locations 40H to 41H using (a) direct addressing mode, (b) register indirect addressing mode without a loop, and (c) with a loop.

## Solution:

(a)

```
MOV A, #55H    ;load A with value 55H
MOV 40H, A      ;copy A to RAM location 40H
MOV 41H, A      ;copy A to RAM location 41H
```

(b)

```
MOV A, #55H    ;load A with value 55H
MOV R0, #40H   ;load the pointer. R0=40H
MOV @R0, A      ;copy A to RAM R0 points to
INC R0          ;increment pointer. Now R0=41h
MOV @R0, A      ;copy A to RAM R0 points to
```

(c)

```
MOV A, #55H    ;A=55H
MOV R0, #40H   ;load pointer. R0=40H,
MOV R2, #02    ;load counter, R2=3
AGAIN: MOV @R0, A ;copy 55 to RAM R0 points to
INC R0          ;increment R0 pointer
DJNZ R2, AGAIN ;loop until counter = zero
```

# Register Indirect Addressing Mode

- The advantage is that it makes accessing data dynamic rather than static as in **direct addressing mode**.
- **Looping is not possible in direct addressing mode.**
- Write a program to clear 16 RAM locations starting at RAM address 60H.

```
CLR  A           ;A=0
MOV  R1,#60H     ;load pointer. R1=60H
MOV  R7,#16      ;load counter, R7=16
AGAIN: MOV @R1,A  ;clear RAM R1 points to
      INC R1      ;increment R1 pointer
      DJNZ R7,AGAIN ;loop until counter=zero
```

# External Memory RAM

- External Memory is accessed.
- There are only two commands that use External memory to mode:
  - **MOVX A, @DPTR**  
**MOVX @DPTR, A**
- DPTR must first be loaded with the address of external memory.

# External Memory ROM

- External ROM can be accessed by MOVC instruction.
- This instruction moves a byte of data located in program ROM into register A.
- `MOVC A,@A+DPTR`
- `MOVC A,@A+PC`
- This allows us to put strings of data, such as lookup table elements.

# 8051 Instruction Set

- **8051 instructions have 8-bit opcode**
- **There are 256 possible instructions of which 255 are implemented**

# MOV Instruction

- **MOV destination, source ;** copy source to destination.
- MOV A,#55H ;load value 55H into reg. A  
MOV R0,A ;copy contents of A into R0  
;(now A=R0=55H)  
MOV R1,A ;copy contents of A into R1  
;(now A=R0=R1=55H)  
MOV R2,A ;copy contents of A into R2  
;(now A=R0=R1=R2=55H)  
MOV R3,#95H ;load value 95H into R3  
;(now R3=95H)  
MOV A,R3 ;copy contents of R3 into A  
;now A=R3=95H



# ADD Instruction

- **ADD A, source** ;ADD the source operand to the accumulator
- MOV A, #25H ;load 25H into A  
MOV R2,#34H ;load 34H into R2  
ADD A,R2 ;add R2 to accumulator  
;(A = A + R2)

# Structure of Assembly Language

ORG 0H	;start (origin) at location 0
MOV R5,#25H	;load 25H into R5
MOV R7,#34H	;load 34H into R7
MOV A,#0	;load 0 into A
ADD A,R5	;add contents of R5 to A ;now $A = A + R5$
ADD A,R7	;add contents of R7 to A ;now $A = A + R7$
ADD A,#12H	;add to A value 12H ;now $A = A + 12H$
HERE: SJMP HERE	;stay in this loop
END	;end of asm source file

# Data Types & Directives

```
ORG 500H
```

```
DATA1: DB 28
```

```
DATA2: DB 00110101B
```

```
DATA3: DB 39H
```

```
ORG 510H
```

```
DATA4: DB "2591"
```

```
ORG 518H
```

```
DATA6: DB "My name is Joe"
```

# Multiplication of Unsigned Numbers

**MUL AB ;  $A \times B$ , place 16-bit result in B and A**

<b>MOV A,#25H</b>	<b>;load 25H to reg. A</b>
<b>MOV B,#65H</b>	<b>;load 65H in reg. B</b>
<b>MUL AB</b>	<b>;25H * 65H = E99 where B = 0EH and A = 99H</b>

Table 6-1:Unsigned Multiplication Summary (MUL AB)

Multiplication	Operand 1	Operand 2	Result
byte byte	A	B	A=low byte, B=high byte

# Division of Unsigned Numbers

`DIV AB ; divide A by B`

- `MOV A,#95H ;load 95 into A`
- `MOV B,#10H ;load 10 into B`
- `DIV AB ;now A = 09 (quotient) and B = 05 (remainder)`

Table 6-2:Unsigned Division Summary (DIV AB)

Division	Numerator	Denominator	Quotient	Remainder
byte / byte	A	B	A	B

# List of bit addressable registers

- Following are the bit addressable registers:
  - Acc
  - B
  - PSW
  - P0,P1,P2,P3
  - IP
  - IE
  - TCON
  - SCON

# Logical Instructions

- ANL indicates AND operation
  - ANL A,Rn
  - ANL A,direct
  - ANL A,@Ri
  - ANL Mask,A
  - ANL direct,#data
  - ANL C,bit
  - ANL C,/bit
- Similarly ORL/XRL instructions are meant for logical OR and XOR operation.

# Logical Instructions

- CLR A
- CPL A
- RL A
- RR A
- RLC A
- RRC A
- SWAP A                     $\Rightarrow D7-D4 \leftrightarrow D3-D0$



# Checking an input bit

**JNB (jump if no bit) ; JB (jump if bit = 1)**

Assume that bit P2.3 is an input and represents the condition of an oven. If it goes high, it means that the oven is hot. Monitor the bit continuously. Whenever it goes high, send a low to high pulse to port P1.5 to turn on buzzer.

**Soln:**

OVEN\_HOT BIT P2.3

BUZZER BIT P1.5

Here: JNB OVEN\_HOT,Here

CLR BUZZER

SETB BUZZER

- A switch is connected to pin P1.7. Write a program to check the status of SW and perform the following:

    If SW=0, send letter 'N' to P2

    If SW=1, send letter 'Y' to P2

Soln:     SETB P1.7

    Again: JB P1.2,over

        MOV P2,#'N'

        SJMP Again

Over:     MOV P2,#'Y'

        SJMP Again

# Switch Register Banks

## Example 2-7

State the contents of the RAM locations after the following program:

```
SETB PSW.4      ;select bank 2
MOV R0,#99H      ;load R0 with value 99H
MOV R1,#85H      ;load R1 with value 85H
MOV R2,#3FH      ;load R2 with value 3FH
MOV R7,#63H      ;load R7 with value 63H
MOV R5,#12H      ;load R5 with value 12H
```

### Solution:

By default, PSW.3=0 and PSW.4=0; therefore, the instruction "SETB PSW.4" sets RS1=1 and RS0=0, thereby selecting register bank 2. Register bank 2 uses RAM locations 10H - 17H. After the execution of the above program we have the following:

RAM location 10H has value 99H	RAM location 11H has value 85H
RAM location 12H has value 3FH	RAM location 17H has value 63H
RAM location 15H has value 12H	

# Pushing onto Stack

## Example 2-8

Show the stack and stack pointer for the following. Assume the default stack area and register 0 is selected.

```
MOV R6, #25H
MOV R1, #12H
MOV R4, #0F3H
PUSH 6
PUSH 1
PUSH 4
```

**Solution:**

	After PUSH 6	After PUSH 1	After PUSH 4
0B	0B	0B	0B
0A	0A	0A	0A F3
09	09	09 12	09 12
08	08 25	08 25	08 25
Start SP = 07	SP = 08	SP = 09	SP = 0A

# Popping from Stack

## Example 2-9

Examining the stack, show the contents of the registers and SP after execution of the following instructions. All values are in hex.

```
POP 3      ;POP stack into R3
POP 5      ;POP stack into R5
POP 2      ;POP stack into R2
```

### Solution:

	After POP 3	After POP 5	After POP 2
<u>0B 54</u>	<u>0B</u>	<u>0B</u>	<u>0B</u>
<u>0A F9</u>	<u>0A F9</u>	<u>0A</u>	<u>0A</u>
<u>09 76</u>	<u>09 76</u>	<u>09 76</u>	<u>09</u>
<u>08 6C</u>	<u>08 6C</u>	<u>08 6C</u>	<u>08 6C</u>
Start SP = 0B	SP = 0A	SP = 09	SP = 08

# Looping

Write a program to

(a) clear ACC, then

(b) add 3 to the accumulator ten times.

**Solution:**

;This program adds value 3 to the ACC ten times

```
                MOV    A,#0          ;A=0, clear ACC
                MOV    R2,#10        ;load counter R2=10
AGAIN:          ADD    A,#03         ;add 03 to ACC
                DJNZ   R2,AGAIN      ;repeat until R2=0(10 times)
                MOV    R5,A          ;save A in R5
```

# Loop inside a Loop (Nested Loop)

Write a program to (a) load the accumulator with the value 55H, and (b) complement the ACC 700 times.

## **Solution:**

Since 700 is larger than 255 (the maximum capacity of any register), we use two registers to hold the count. The following code shows how to use R2 and R3 for the count.

```
                MOV  A,#55H
                MOV  R3,#10
NEXT:           MOV  R2,#70
AGAIN:          CPL  A
                DJNZ R2,AGAIN
                DJNZ R3,NEXT
```

```
;A=55H
;R3=10, the outer loop count
;R2=70, the inner loop count
;complement A register
;repeat it 70 times (inner loop)
```

# 8051 Conditional Jump Instructions

Instruction	Action
JZ	Jump if A = 0
JNZ	Jump if A $\neq$ 0
DJNZ	Decrement and jump if register $\neq$ 0
CJNE A, data	Jump if A $\neq$ data
CJNE reg, #data	Jump if byte $\neq$ #data
JC	Jump if CY = 1
JNC	Jump if CY = 0
JB	Jump if bit = 1
JNB	Jump if bit = 0
JBC	Jump if bit = 1 and clear bit



# Conditional Jump

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- The 8051 offers a variety of conditional jump instructions
- JZ and JNZ tests the accumulator for a particular condition
- DJNZ (decrement and jump if not zero) is a useful instruction for building loops
- To execute a loop N times, load a register with N and terminate the loop with a DJNZ to the beginning of the loop
- CJNE (compare and jump if not equal) is another conditional jump instruction
- CJNE: two bytes in the operand field are taken as unsigned integers. If the first one is less than the second one, the carry is set
- Example: It is desired to jump to BIG if the value of the accumulator is greater than or equal to 20<sub>H</sub>

**CJNE A,#20<sub>H</sub>,\$+3**

**JNC BIG**

- \$ is an assembler symbol representing the address of the current instruction
- Since CJNE is a 3-byte instruction, \$+3 is the address of next instruction JNC

# Conditional Jump Example

Write a program to determine if R5 contains the value 0. If so, put 55H in it.

**Solution:**

```
        MOV    A,R5        ;copy R5 to A
        JNZ    NEXT        ;jump if A is not zero
        MOV    R5,#55H
NEXT:    ...
```

Example 2: Write a program to bring in data in serial form from P0.0 and send it out in parallel form to P1.

```
        MOV    R0,#08
        SETB   P0.0
Back:    MOV    C,P0.0
        RRC    A
        DJNZ   R0, Back
        MOV    P1,A
        END
```

Example: Find the sum of the values 79H, F5H, E2H. Put the sum in registers R0 (low byte) and R5 (high byte).

```
    MOV A,#0    ;A=0
    MOV R5,A    ;clear R5
    ADD A,#79H  ;A=0+79H=79H ;
    JNC N_1     ;if CY=0, add next number ;
    INC R5      ;if CY=1, increment R5
N_1: ADD A,#0F5H ;A=79+F5=6E and CY=1
    JNC N_2     ;jump if CY=0
    INC R5      ;if CY=1,increment R5 (R5=1)
N_2: ADD A,#0E2H ;A=6E+E2=50 and CY=1
    JNC OVER    ;jump if CY=0
    INC R5      ;if CY=1, increment 5
OVER: MOV R0,A  ;now R0=50H, and R5=02
```

# Unconditional Jump Instructions

- All conditional jumps are short jumps
  - Target address within -128 to +127 of PC
- **LJMP** (long jump): 3-byte instruction
  - 2-byte target address: 0000 to FFFFH
  - Original 8051 has only 4KB on-chip ROM
- **SJMP** (short jump): 2-byte instruction
  - 1-byte relative address: -128 to +127

# Call Instructions

- **LCALL** (long call): 3-byte instruction
  - 2-byte address
  - Target address within 64K-byte range
- **ACALL** (absolute call): 2-byte instruction
  - 11-bit address
  - Target address within 2K-byte range

- Write an assembly language program to transfer N = 05 bytes of data from location 30h to location 40h.

```
mov r0,#30h           //source address
```

```
mov r1,#40h           //destination address
```

```
mov r7,#05h           //Number of bytes to be moved
```

```
back: mov a,@r0
```

```
mov @r1,a
```

```
inc r0
```

```
inc r1
```

```
djnz r7,back //repeat till all data transferred end
```

- **Write an assembly language program to find the largest element in a given array of N =\_06h bytes at location 4000h. Store the largest element at location 4062h.**

```

        mov  r3,#6                //length of the array
        mov  dptr,#4000H          //starting address of array
        movx a,@dptr
        mov  r1,a
nextbyte: inc  dptr
        movx a,@dptr
        clr  c                    //reset borrow flag
        mov  r2,a                //next number in the array
        subb a,r1                //other Num-Prev largest no.
        jc   skip                // JNC FOR SMALLEST ELEMENT
        mov  a,r2                //update larger number in r1
        mov  r1,a
skip:    djnz r3,nextbyte
        mov  dptr, #4062H         //location of the result-4062h
        mov  a,r1                //largest number
        movx @dptr,a             //store at #4062H
end

```

- Add two 32 bit numbers starting at location 40H to 43H and 50H to 53H. Store the result at address 60H to 63H.

CLR C

MOV R0,#40H

MOV R1,#50H

MOV R2,#04

SETB PSW.3

MOV R0,#60H

CLR PSW.3

Back: MOV A,@R0

ADDC A,@R1

INC R0

INC R1

SETB PSW.3

MOV @R0,A

INC R0

CLR PSW.3

DJNZ R2,Back



- Write an assembly language program to find whether given eight bit number is odd or even. If odd store 00h in accumulator. If even store FFh in accumulator.

```
mov    a,20h                // 20h=given number, to find
                             is it even or odd
jb     acc.0,odd             //jump if direct bit is set i.e., if lower
                             bit is 1 then number is odd

mov     a,#0FFh
sjmp    ext
odd:    mov  a,#00h
Ext:    end
```

- Compute the logical AND of the input signals on bits 0 and 1 of port 1 and output the result to bit 2 of port 1.
- Soln       SETB P1.0  
              SETB P1.1  
              Loop:MOV C,P1.0  
                  ANL C,P1.1  
                  MOV P1.2,C  
                  SJMP Loop

- Write a program to perform the following:
  - i. Keep monitoring pin P0.1 until becomes high
  - ii. When P0.1 becomes high, read in the data from Port 1.
  - iii. Send a low to high pulse on P0.2 to indicate that the data has been read.

SETB P0.1

MOV P1,#0FFH

Here: JNB P0.1, Here

MOV A,P1

CLR P0.2

SETB P0.2

END

- Assuming that ROM space starting at 250H contains “DDU”, write a program to transfer the bytes into RAM location starting at 40H.

```
ORG 0000
MOV DPTR,#Mydata
MOV R0,#40H
MOV R2,#3
```

```
Back: CLR A
      MOVC A,@A+DPTR
      MOV @R0,A
      INC DPTR
      INC R0
      DJNZ R2,Back
```

```
Here: SJMP Here
```

```
ORG 250H
Mydata DB “DDU”
END
```

- **Write an assembly language program to implement (display) an eight bit UP/DOWN binary (hex) counter on watch window.**

```
        mov a,#00                                //mov a, #0ffh for down counter
back:   acall delay
        inc a                                    //dec a for binary down counter
        jnz back
here:   sjmp here
delay:  mov r1,#0ffh
decr1:  mov r2,#0ffh
decr:   mov r3,#0ffh
Here1:  djnz r3,here1
        djnz r2,decr
        djnz r1,decr1
        ret
end
```