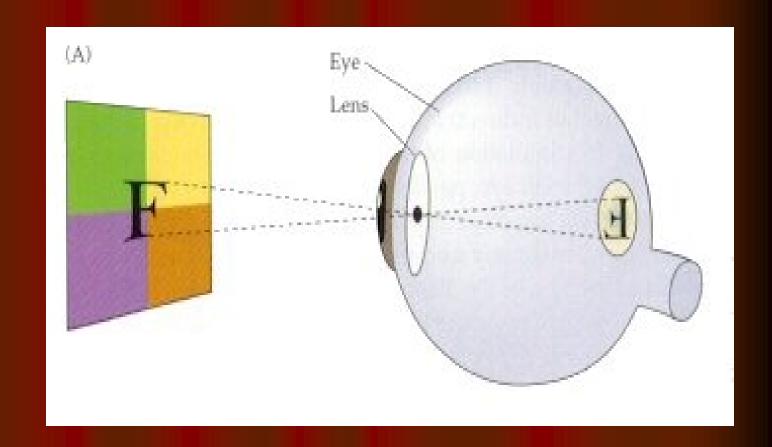
Digital Image Processing Using MATLAB

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Elements of Visual Perception

- Structure of the human eye
- Image formation in the human eye
- Brightness adaptation and discrimination
- Psycho visual Effects

Image Formation



Elements of Visual Perception Structure of the human eye

- > The cornea and sclera outer cover
- > The choroid
 - Ciliary body
 - > Iris diaphragm
 - > Lens

Elements of Visual Perception Structure of the human eye

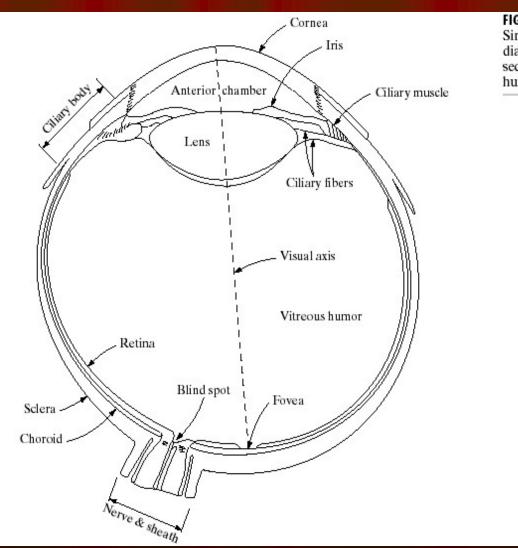


FIGURE 2.1 Simplified diagram of a cross section of the human eye.

Elements of Visual Perception Structure of the human eye

- 1. The *lens* contains 60-70% water, 6% of fat.
- 2. The *iris* diaphragm controls amount of light that enters the eye.
- 3. Light receptors in the retina
 - About 6-7 millions *cones* for bright light vision called *photopic*
 - Density of cones is about 150,000 elements/mm².
 - Cones involve in color vision.
 - Cones are concentrated in *fovea* about 1.5x1.5 mm².
 - About 75-150 millions *rods* for dim light vision called *scotopic*
 - Rods are sensitive to low level of light and are not involved color vision.
- 4. Blind spot is the region of emergence of the optic nerve from the eye.

Elements of Visual Perception Structure of the human eye

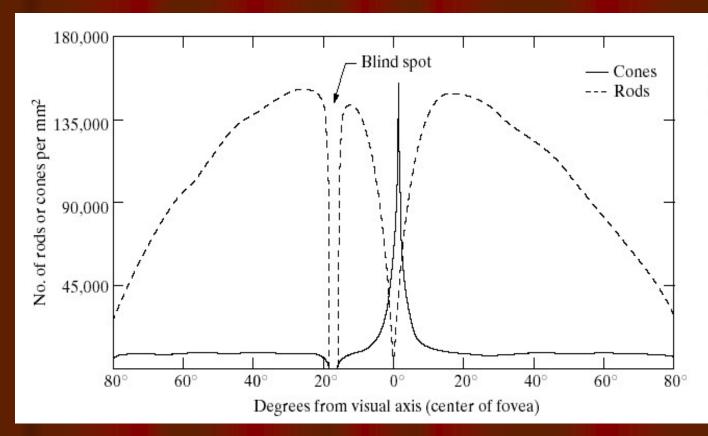


FIGURE 2.2 Distribution

Distribution of rods and cones in the retina.

Elements of Visual Perception Image formation in the human eye

- Flexible lens: the principle difference from an ordinary optical lens.
- Controlled by the tension in the fibers of the ciliary body
 - > To focus on distant objects flattened
 - ➤ To focus on objects near eye thicker
 - Near-sighted and far-sighted

Elements of Visual Perception Image formation in the human eye

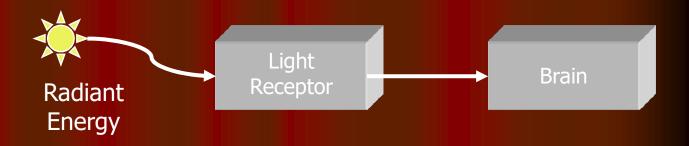
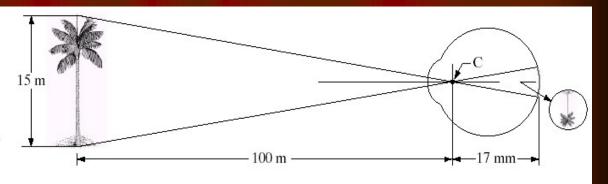


FIGURE 2.3 Graphical representation of the eye looking at a palm tree. Point C is the optical center of the lens.



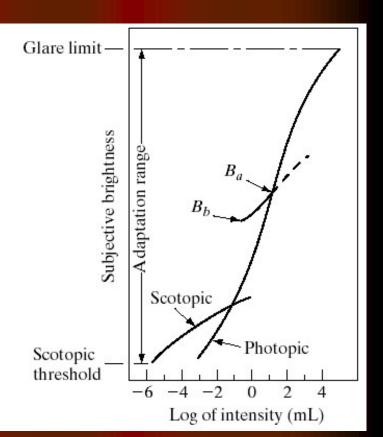
Elements of Visual Perception Brightness adaptation

- ▶ Dynamic range of human visual system: 10⁻⁶~10⁴ mL (millilambert)
- Can not accomplish this range simultaneously
- The current sensitivity level of the visual system is called brightness adaptation level

Elements of Visual Perception Brightness adaptation

FIGURE 2.4

Range of subjective brightness sensations showing a particular adaptation level.



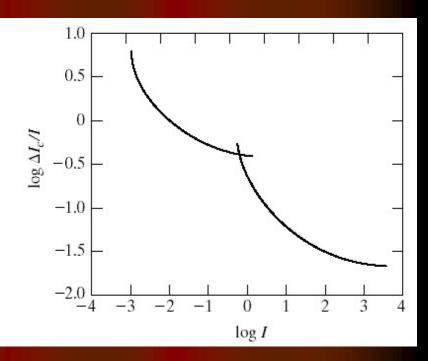
Elements of Visual Perception Brightness discrimination

- \triangleright Weber ratio (the experiment) : $\Delta I_C/I$
 - > I: the background illumination
 - $\triangleright \Delta I_c$: the increment of illumination
 - Small Weber ratio indicates good discrimination
 - Larger Weber ratio indicates poor discrimination

Elements of Visual Perception Brightness discrimination

FIGURE 2.6

Typical Weber ratio as a function of intensity.

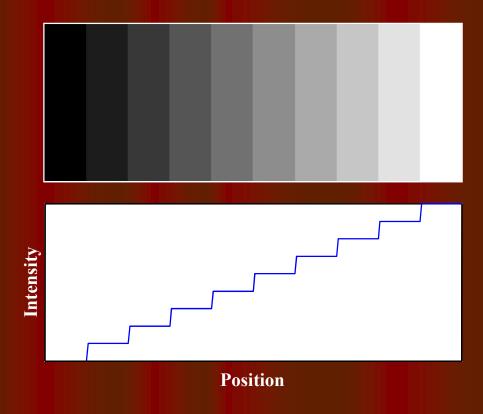


Psycho-visual effects

The perceived brightness is not a simple function of intensity

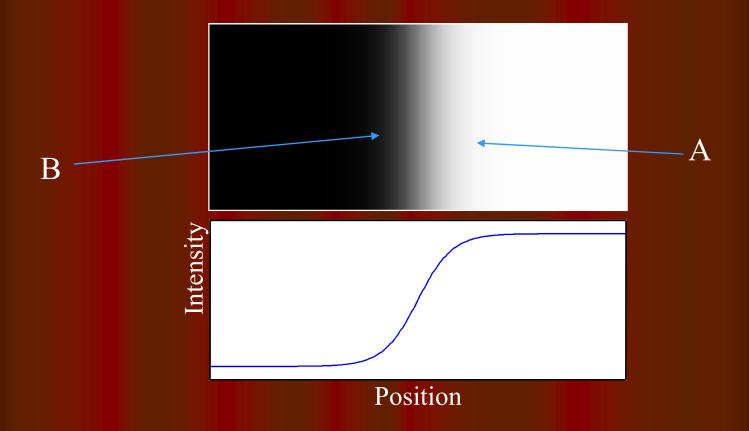
- > Mach band pattern
- > Simultaneous contrast
- > Optical illusion

Mach band pattern



Intensities of surrounding points effect perceived brightness at each point. In this image, edges between bars appear brighter on the right side and darker On the left side.

Mach band pattern



In area A, brightness perceived is darker while in area B is brighter. This phenomenon is called *Mach Band Effect*.

Simultaneous contrast

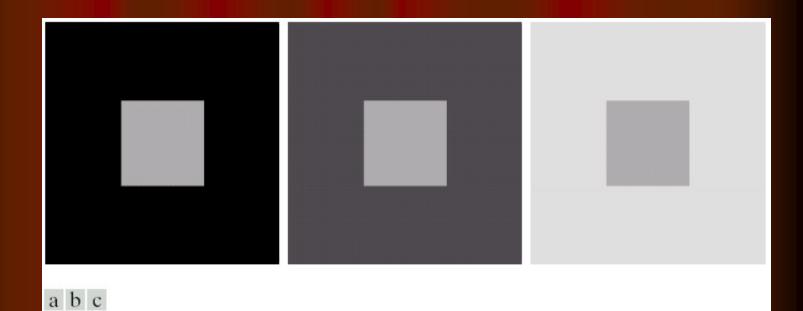
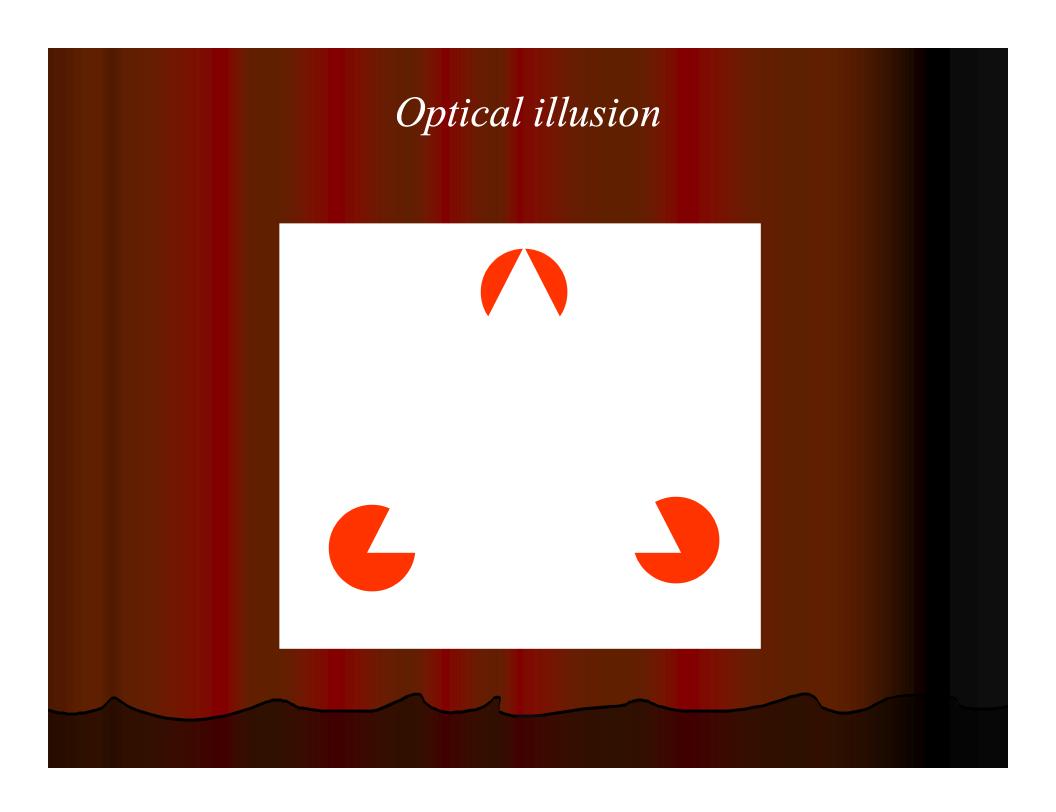
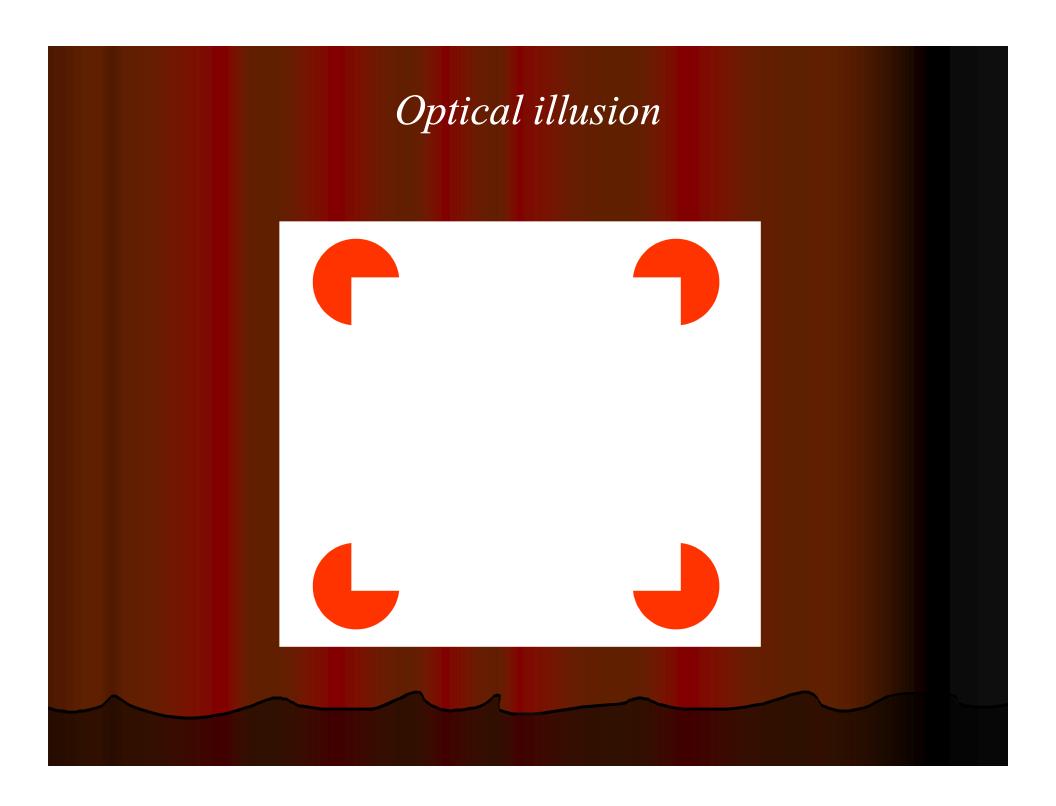
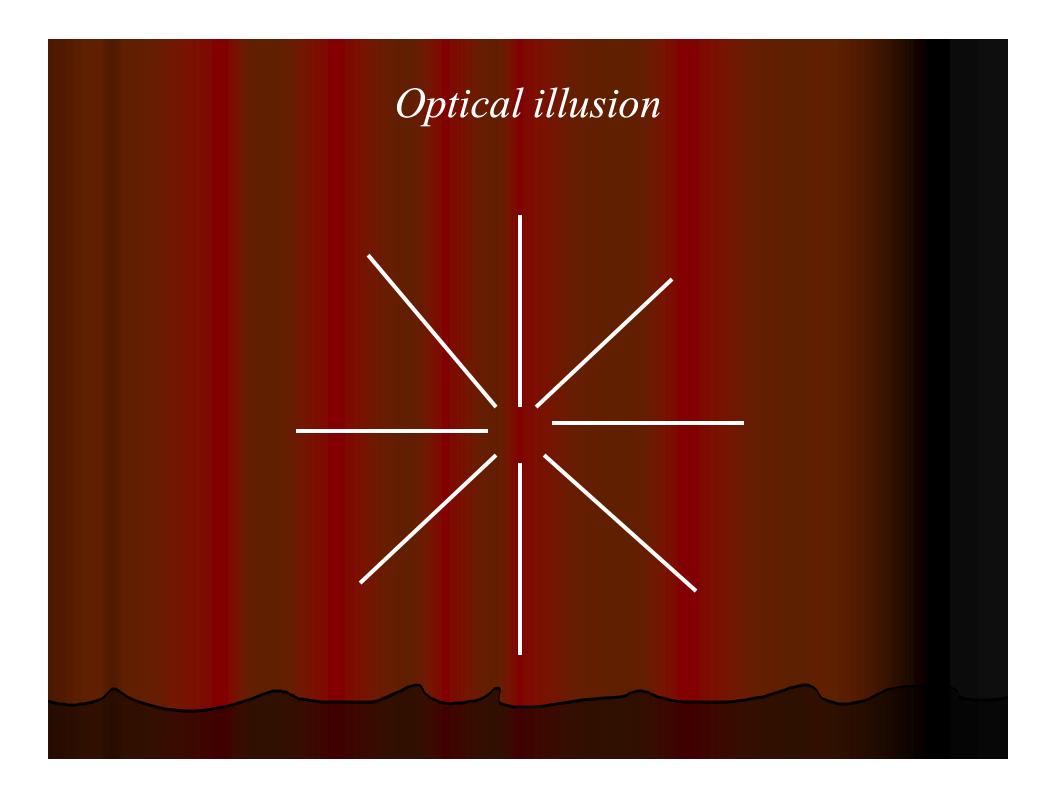
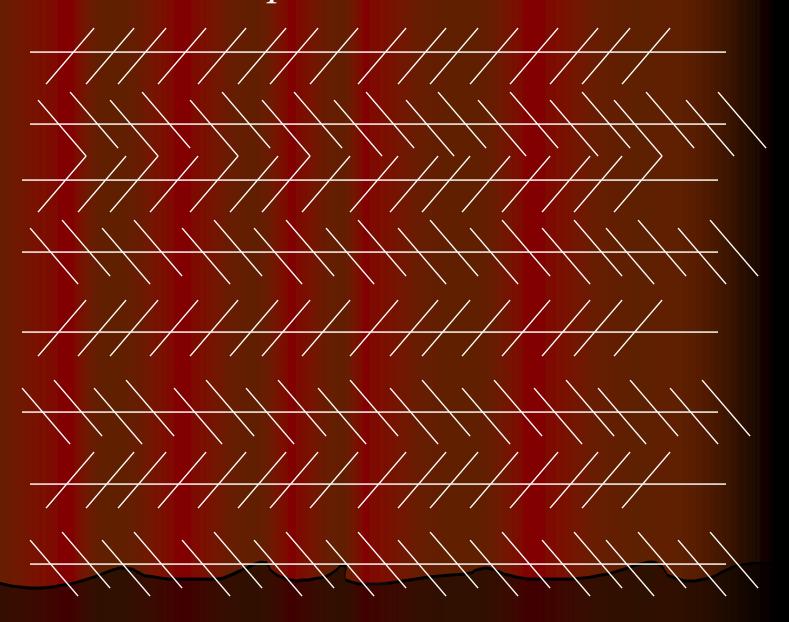


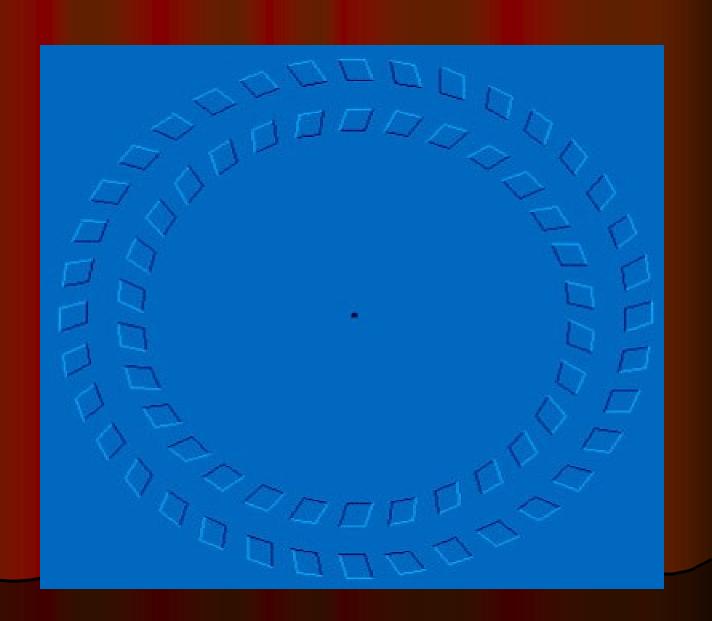
FIGURE 2.8 Examples of simultaneous contrast. All the inner squares have the same intensity, but they appear progressively darker as the background becomes lighter.

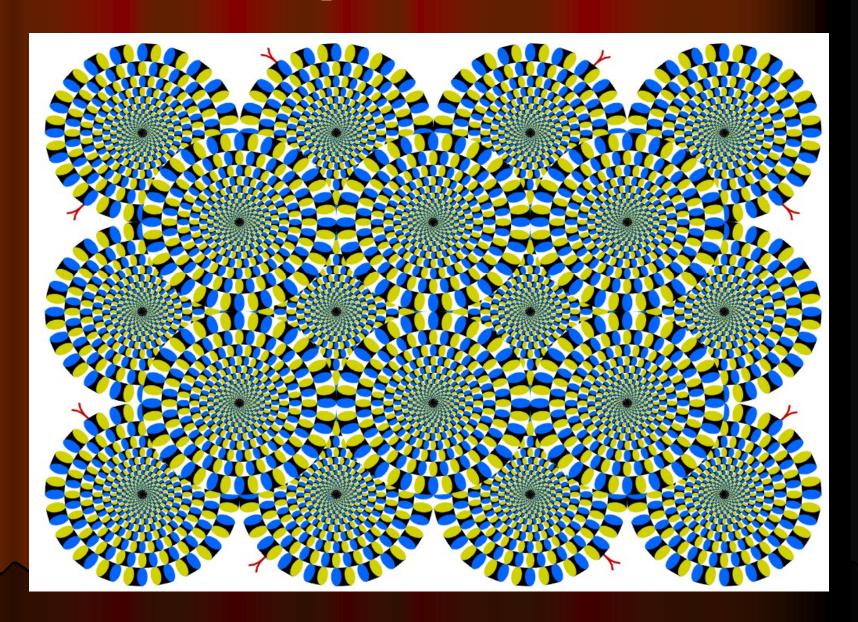


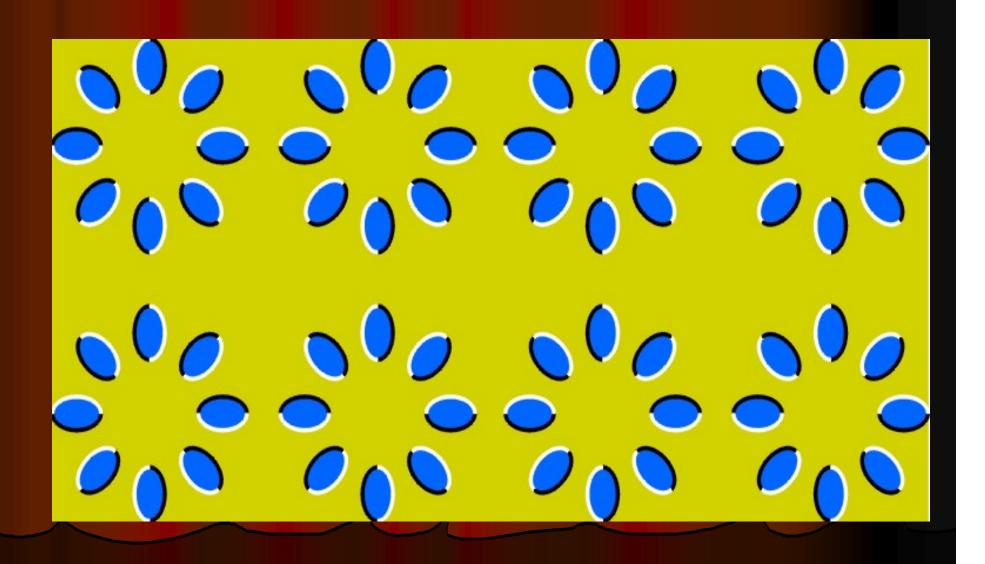


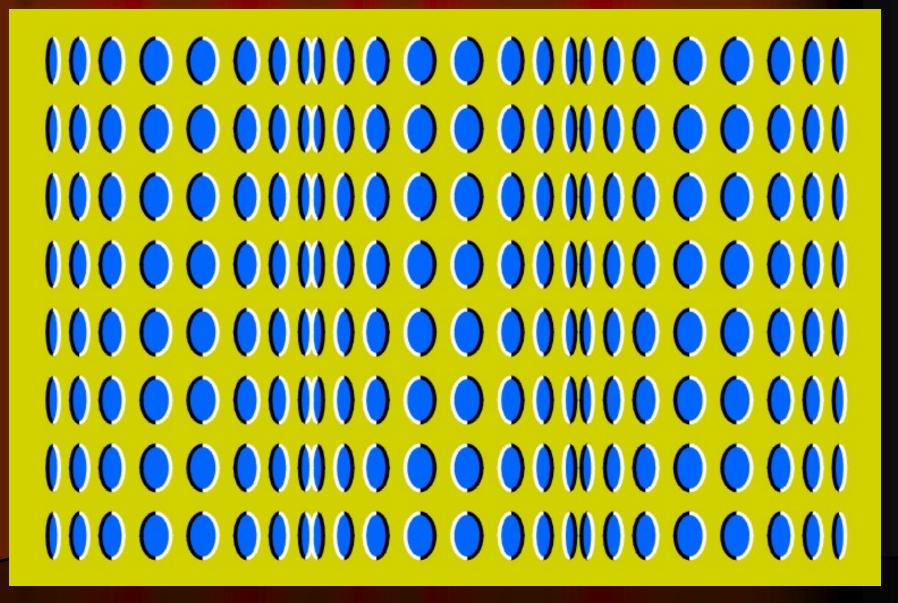


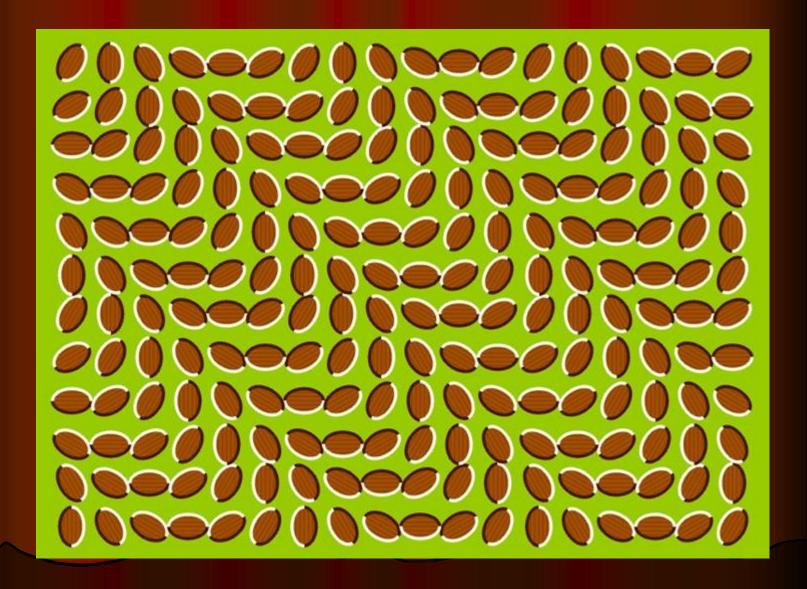


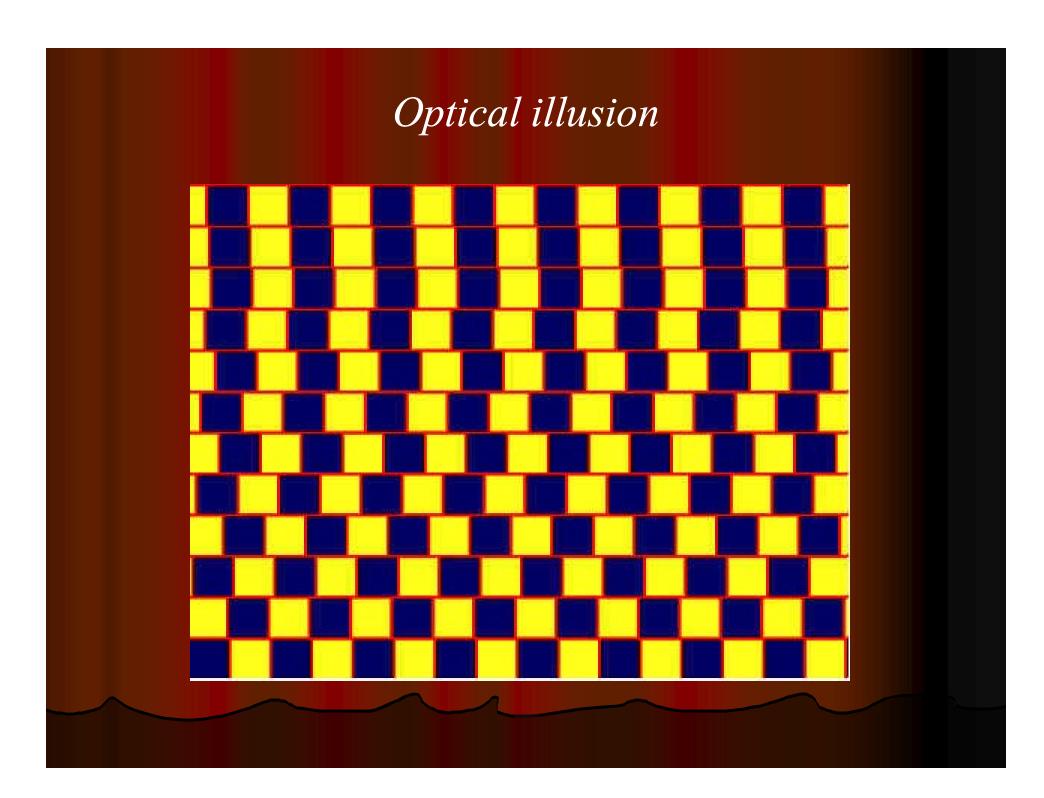








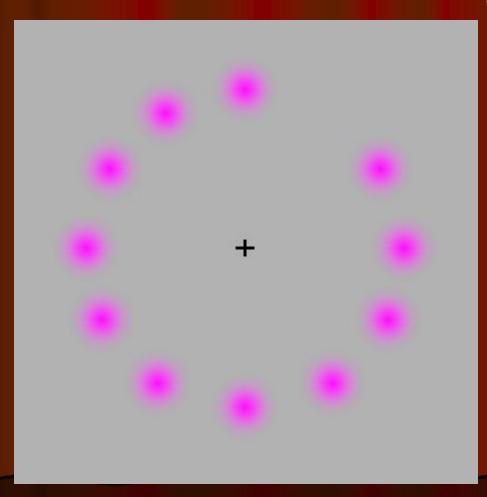






Concentrate on the cross in the middle, after a while you will notice that this moving purple

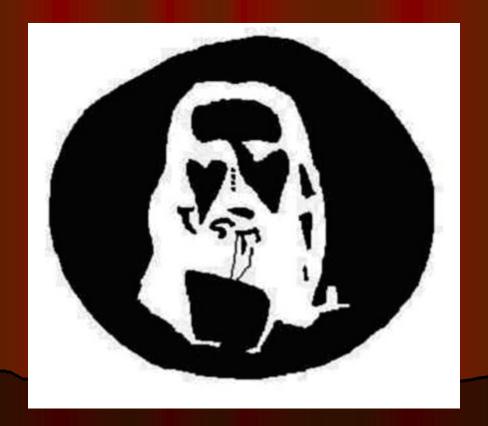
dot will turn green!



Look at the cross a bit longer and you'll notice that all dots except the green one will disappear.

Follow the instruction below.

- 1) Stare at the 4 little dots on the middle of the picture for 30 seconds
- 2) then look at a wall near you
- 3) a bright spot will appear
- 4) twinkle a few times and you'll see a figure
- 5) What do you see? Or even WHO do you see?





 \rightarrow A = imread (filename, fmt)

This function reads a grayscale or true color image named filename into matrix A.

If the file contains a grayscale image, A is a 2-Dimensional array i.e. m x n.

If the file contains a true color image (RGB) image, A is a 3-Dimensional Array i.e. m x n x 3.

fmt indicate various possible file formats (image types) that can be opened directly in MATLAB.

Format	Description	
Bmp	Windows Bitmap	
Ico	Windows icon resources	
Jpeg	Joint Photographic Experts Group	
Pcx	Windows Paint Brush	
Tiff	Tagged Image file format	
Png	Portable Network Graphic	

imwrite (A, filename, fmt)

This function writes the image matrix A to filename in the format specified by fmt.

A can be grayscale image or a true color image.

If A is of class uint8 or uint16, the function writes the actual values in the array to the file.

If A is of class double, imwrite rescales the values in the array before writing using uint8(round(255 *A)).

This operation converts the floating point numbers in the range [0,1] to 8-bit integers in the range [0 255].

> imshow (A)

This function displays the image matrix A.

The function imshow (A, n) displays the image with n discrete levels of gray.

If you omit n, imshow uses 256 gray levels on 24-bit displays or 64 gray levels on other systems.

rgb2gray (A)

Convert rgb image to grayscale image.

rgb2gray converts RGB image to grayscale image by eliminating the hue and saturation information while retaining the luminance (Value).

imfinfo filename

This gives us the information of image file like name, size, format, width, height, colortype etc.

mat2gray (A)

Converting an arbitrary array of class double to an array of class double scaled to the range [0,1].

im2double (A)

im2double takes an image as input and returns an image of class double.

If the imput image is of class double, the output image is identical to it.

If the imput image is of class uint8 or uint16, im2double returns the equivalent image of class double, rescaling the data in the range [0.1].

If an array of class double results from the computations yield values outside the range [0,1], inputing this array into im2double will have no effect.

```
h= uint8( [ 25 50 ; 128 200]);

g = im2double(h)

g =

0.0980 0.1961

0.4706 0.7843
```

> im2uint8(A)

Function detects the class of input data and performs necessary scaling for the toolbox to recognize the data as valid image data.

consider f of class double

g = im2uint8(f)

gives

$$g = 0$$
 128
191 255

Data Class Name	Description	
double	Double precision floating point numbers	
uint8	Unsigned 8-bit integers in range [0,255]	
uint16	Unsigned 16-bit integers in range [0,65535]	
uint32	Unsigned 32-bit integers	
char	Character (2 bytes per element)	
logical	Values are 0 or 1 (1 bye per element)	

Name	Output	Input
im2uint8	uint8	logical, uint8, uint16 and double
im2uint16	uint16	logical, uint8, uint16 and double
mat2gray	double	double
	(in range [0, 1])	
Im2double	double	logical, uint8, uint16 and double
im2bw	Logical	uint8, uint16 and
	1	double