

## Assignment A3

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import sys, heapq
from collections import defaultdict
from math import inf
from rich import print

def selectionSort(A):
    U = A.copy()
    for i in range(len(A)):
        min_idx = i
        for j in range(i+1, len(A)):
            if A[min_idx] > A[j]:
                min_idx = j

        A[i], A[min_idx] = A[min_idx], A[i]

    print(f'Selection Sort:\nUnsorted array: {U}\nSorted array: {A}')

def jobScheduling(arr):
    n = len(arr)
    arr.sort(key=lambda x: x[1])
    result = []
    maxHeap = []

    for i in range(n - 1, -1, -1):
        if i == 0:
            slots_available = arr[i][1]
        else:
            slots_available = arr[i][1] - arr[i - 1][1]

        heapq.heappush(maxHeap, (-arr[i][2], arr[i][1], arr[i][0]))

        while slots_available and maxHeap:
            profit, deadline, job_id = heapq.heappop(maxHeap)
            slots_available -= 1
            result.append([job_id, deadline])

    result.sort(key=lambda x: x[1])
    print(f'3\n\nJob Scheduling Problem:\nFollowing is maximum profit sequence of jobs: {result}')

class PGraph:
    def __init__(self, vertices, graph):
        self.V = vertices
        self.graph = graph

    def minKey(self, key, mstSet):
        min = sys.maxsize

        for v in range(self.V):
            if key[v] < min and mstSet[v] == False:
                min = key[v]
                min_index = v
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        return min_index

def primMST(self):
    key = [sys.maxsize] * self.V
    parent = [None] * self.V
    key[0] = 0
    mstSet = [False] * self.V

    parent[0] = -1

    for cout in range(self.V):
        u = self.minKey(key, mstSet)

        mstSet[u] = True
        for v in range(self.V):
            if self.graph[u][v] > 0 and mstSet[v] == False and key[v]
> self.graph[u][v]:
                key[v] = self.graph[u][v]
                parent[v] = u

    print(f'\n\nPrim's Minimum Spanning Tree:\nEdge \tWeight')
    minimumCost = 0
    for i in range(1, self.V):
        print(f'{parent[i]} -- {i} == {self.graph[i][parent[i]]}')
        minimumCost += self.graph[i][parent[i]]
    print(f'Minimum cost = {minimumCost}')

class KGraph:
    def __init__(self, vertices, graph):
        self.V = vertices
        self.graph = []

        for i in range(self.V):
            for j in range(i, self.V):
                if graph[i][j] != 0:
                    self.graph.append([i, j, graph[i][j]])

    def find(self, parent, i):
        if parent[i] == i:
            return i
        return self.find(parent, parent[i])

    def union(self, parent, rank, x, y):
        xroot = self.find(parent, x)
        yroot = self.find(parent, y)

        if rank[xroot] < rank[yroot]:
            parent[xroot] = yroot
        elif rank[xroot] > rank[yroot]:
            parent[yroot] = xroot
        else:
            parent[yroot] = xroot
            rank[xroot] += 1

    def KruskalMST(self):
        result = []
        i = 0

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e = 0
self.graph = sorted(self.graph, key = lambda item: item[2])

parent = []
rank = []

for node in range(self.V):
    parent.append(node)
    rank.append(0)

while e < self.V - 1:
    u, v, w = self.graph[i]
    i = i + 1
    x = self.find(parent, u)
    y = self.find(parent, v)

    if x != y:
        e = e + 1
        result.append([u, v, w])
        self.union(parent, rank, x, y)

minimumCost = 0
print(f'\n\nKruskal's Minimum Spanning Tree:\nEdge \tWeight')
for u, v, weight in result:
    minimumCost += weight
    print(f'{u} -- {v} == {weight}')
print(f'Minimum cost = {minimumCost}')

def dijkstra(inp: list, source: str, dest: str) -> int:
    graph = defaultdict(list)
    weight = {}
    path = [dest]

    for i in range(len(inp)):
        for j in range(i, len(inp)):
            if inp[i][j] != 0:
                s, d, c = i, j, inp[i][j]
                graph[s].append(d)
                weight[f'{s} {d}'] = int(c)

                graph[d].append(s)
                weight[f'{d} {s}'] = int(c)

    Q = list(graph.keys())
    A, d, p = [], {}, defaultdict(list)

    for v in Q:
        d[v] = inf
        p[v] = []

    d[source] = 0

    while Q:
        u = min(Q, key=lambda x: d[x])
        A.append(u)
        Q.remove(u)

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        for v in set(graph[u]).intersection(Q):
            alt = d[u] + weight[f'{u} {v}']
            if d[v] > alt:
                d[v] = alt
                p[v].append(u)

    if u == dest:
        break

    key = dest
    while p[key]:
        path.append(p[key][-1])
        key = p[key][-1]
    path.reverse()

    print(f'\n\nDijkstra Single-Source Shortest Path:\nPath:
{path}\nMinimum Cost: {d[dest]}\n\n')

if __name__ == '__main__':

    A = [64, 25, 12, 22, 11]
    selectionSort(A)

    A = [
        ['A', 2, 100],
        ['B', 1, 19],
        ['C', 2, 27],
        ['D', 1, 25],
        ['E', 3, 15]
    ]
    jobScheduling(A)

    graph = [
        [0, 4, 0, 0, 0, 0, 0, 8, 0],
        [4, 0, 8, 0, 0, 0, 0, 11, 0],
        [0, 8, 0, 7, 0, 4, 0, 0, 2],
        [0, 0, 7, 0, 9, 14, 0, 0, 0],
        [0, 0, 0, 9, 0, 10, 0, 0, 0],
        [0, 0, 4, 14, 10, 0, 2, 0, 0],
        [0, 0, 0, 0, 0, 2, 0, 1, 6],
        [8, 11, 0, 0, 0, 0, 1, 0, 7],
        [0, 0, 2, 0, 0, 0, 6, 7, 0]
    ]

    g = PGraph(9, graph)
    g.primMST()

    g = KGraph(9, graph)
    g.KruskalMST()

    dijkstra(graph, 0, 4)

```

## Output :-

Selection Sort:

Unsorted array: [64, 25, 12, 22, 11]

Sorted array: [11, 12, 22, 25, 64]

Job Scheduling Problem:

Following is maximum profit sequence of jobs: [['A', 2], ['C', 2], ['E', 3]]

Prim's Minimum Spanning Tree:

Edge	Weight
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0 -- 1 ==	4
-----------	---

1 -- 2 ==	8
-----------	---

2 -- 3 ==	7
-----------	---

3 -- 4 ==	9
-----------	---

2 -- 5 ==	4
-----------	---

5 -- 6 ==	2
-----------	---

6 -- 7 ==	1
-----------	---

2 -- 8 ==	2
-----------	---

Minimum cost = 37

Kruskal's Minimum Spanning Tree:

Edge	Weight
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6 -- 7 ==	1
-----------	---

2 -- 8 ==	2
-----------	---

5 -- 6 ==	2
-----------	---

0 -- 1 ==	4
-----------	---

2 -- 5 ==	4
-----------	---

2 -- 3 ==	7
-----------	---

0 -- 7 ==	8
-----------	---

3 -- 4 ==	9
-----------	---

Minimum cost = 37

Dijkstra Single-Source Shortest Path:

Path: [0, 7, 6, 5, 4]

Minimum Cost: 21