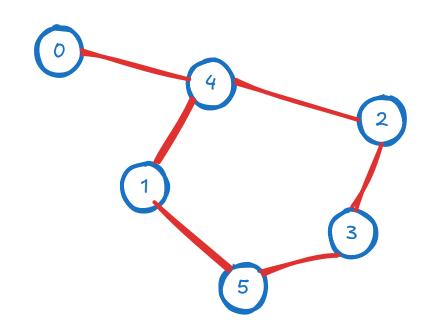
## Depth First Search

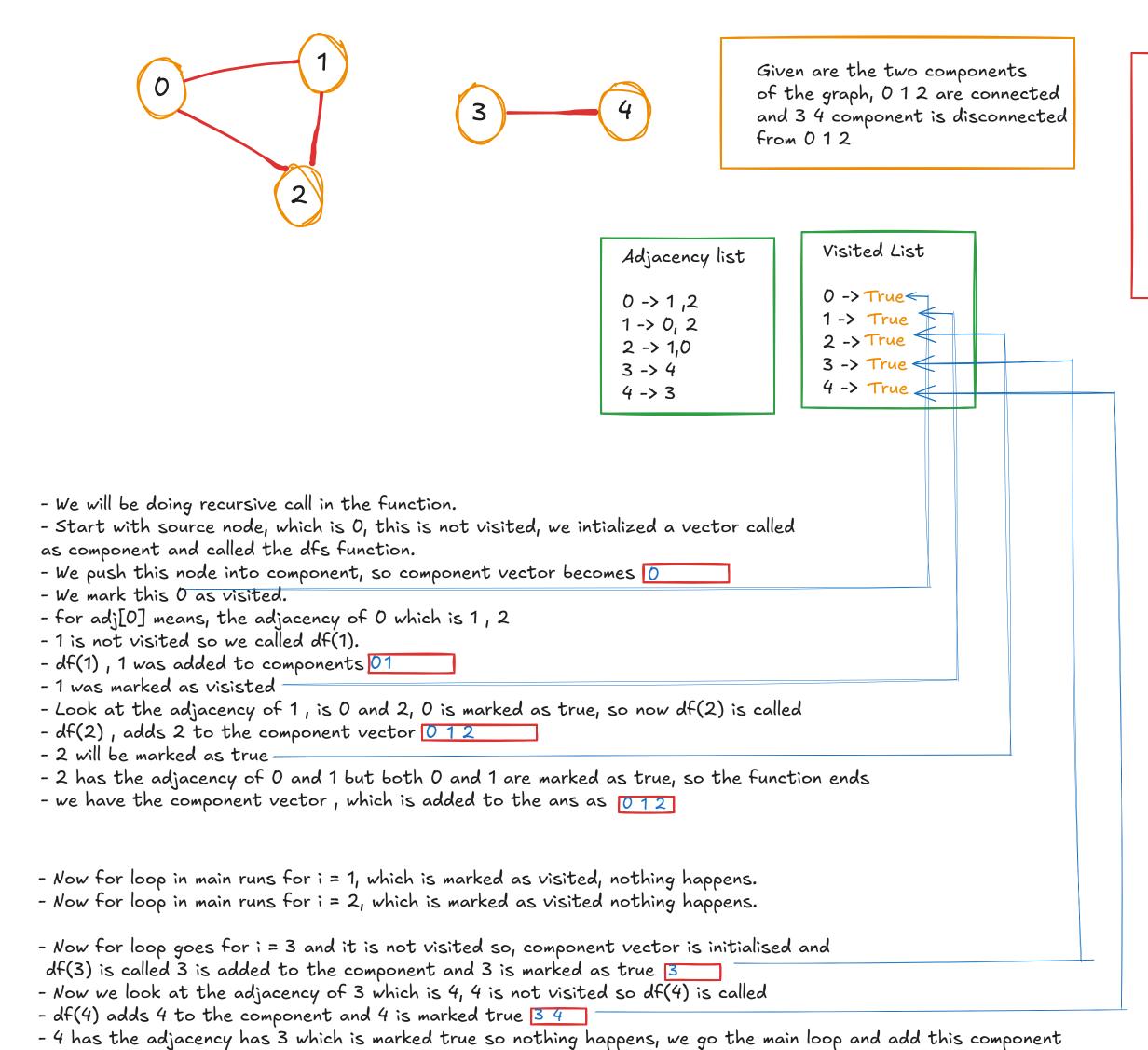


```
BFS: 0, 4, 2, 1, 3, 5

DFS: 0, 4, 2, 3, 5, 1 or 0, 4, 1, 5, 3, 2
```

```
include<bits/stdc++.h>
using namespace std;
void dfs( int node, unordered_map< int, bool > &visited, unordered_map< int,list<int> > &adj, vector<int> &component ){
   component.push_back(node);
   visited[node] = true;
    for( auto i : adj[node]){
        if(!visited[i]){
            dfs(i , visited, adj, component);
vector<vector<int>> depthFirstSearch(int V, int E, vector<vector<int>> &edges)
    vector<vector<int>> ans;
   unordered_map< int,list<int> > adj;
    for( int i = 0; i < edges.size(); i++){}
       int u = edges[i][0];
int v = edges[i][1];
        adj[u].push_back(v);
        adj[v].push_back(u);
    unordered_map< int, bool > visited;
    for( int i = 0; i < V; i ++){}
        if(!visited[i]){
            vector<int> component;
            dfs(i, visited, adj, component);
            ans.push_back(component);
    return ans
```

## Explanation of the code and the logic for Depth-First-Search



There is a catch in this visited list making in here, we just initializer this visited array as unoreder\_map< int, bool > though we do not explicitly intialise all of the edges to false,

Initially all of the visited map is empty with no keys, when we ask for visited[1], we get false because there is no key of Node 1 and when we do visited[1] = true, a key of 1 is made mapped with true. So we actually no need to make map with all node initialised to false.

to the answer