

Mastering Embedded System Online Diploma

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First Term (Final Project 1)
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My Profile:

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Case Study



Specifications:

- A pressure controller should inform the crew of a cabin with an alarm when the pressure exceeds 20 bars in the cabin.
- The alarm duration equals 60 seconds.
- The system keeps tracking the measured values.

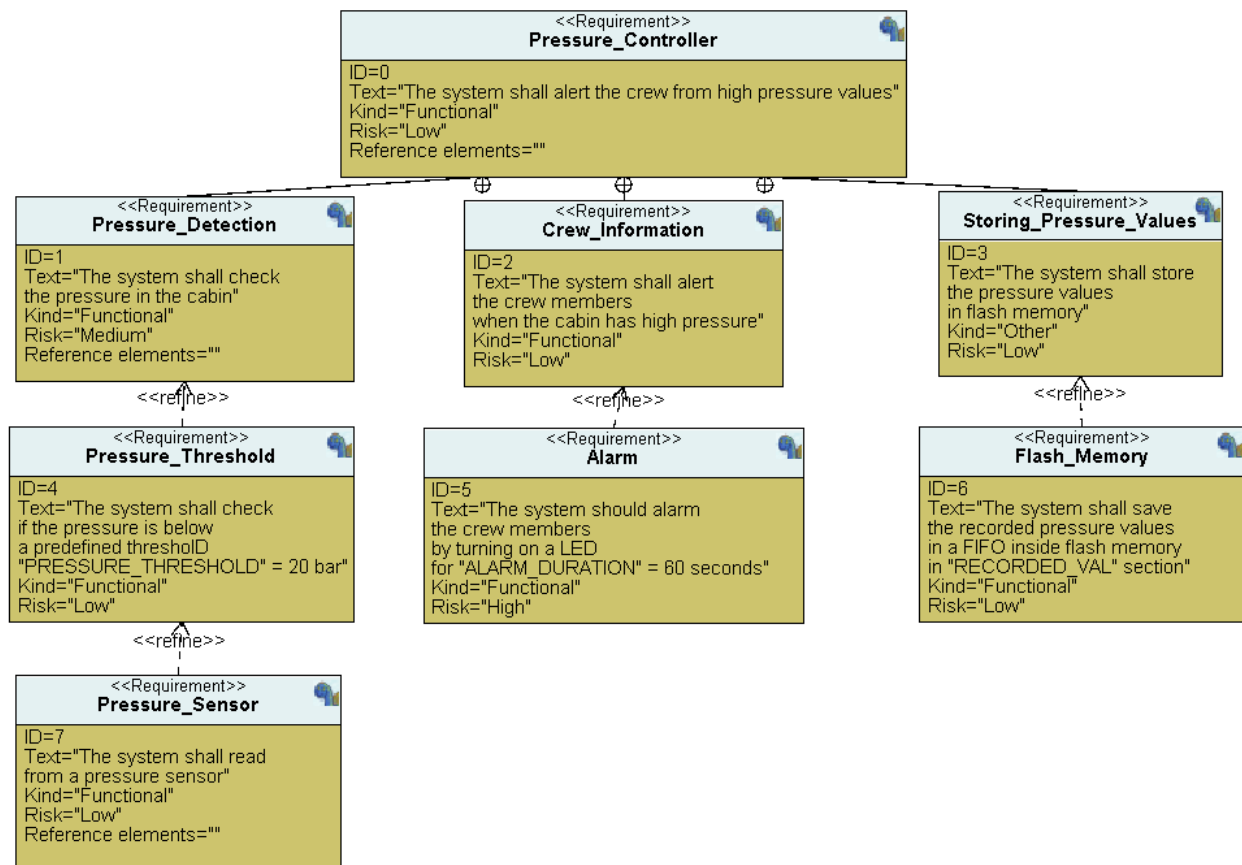
Pressure Controller Assumptions

- The controller set up and shutdown procedures are not modeled.
- The controller maintenance is not modeled.
- The pressure sensor never fails.
- The alarm never fails.
- The controller never faces power cut.

Versioning:

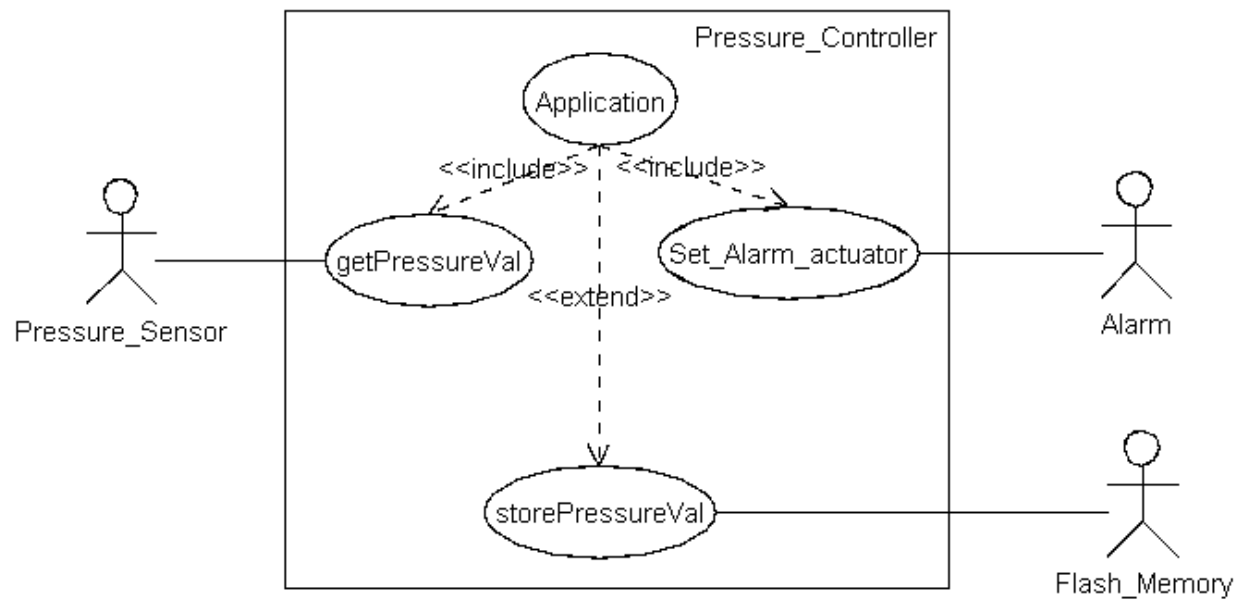
The “keeps tracking the measured values” option is not modeled in the first version of the design.

Requirement Diagram

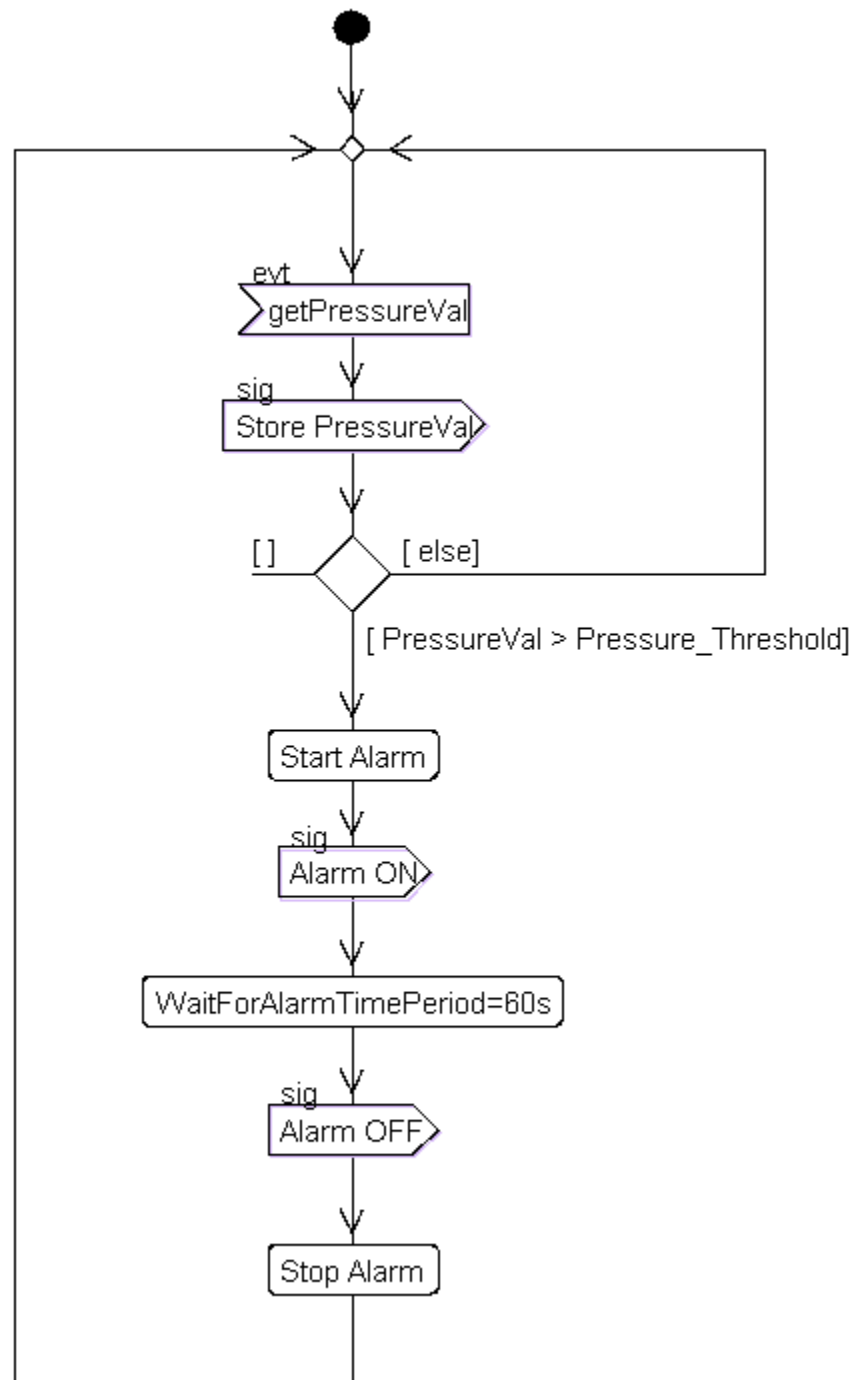


System Analysis

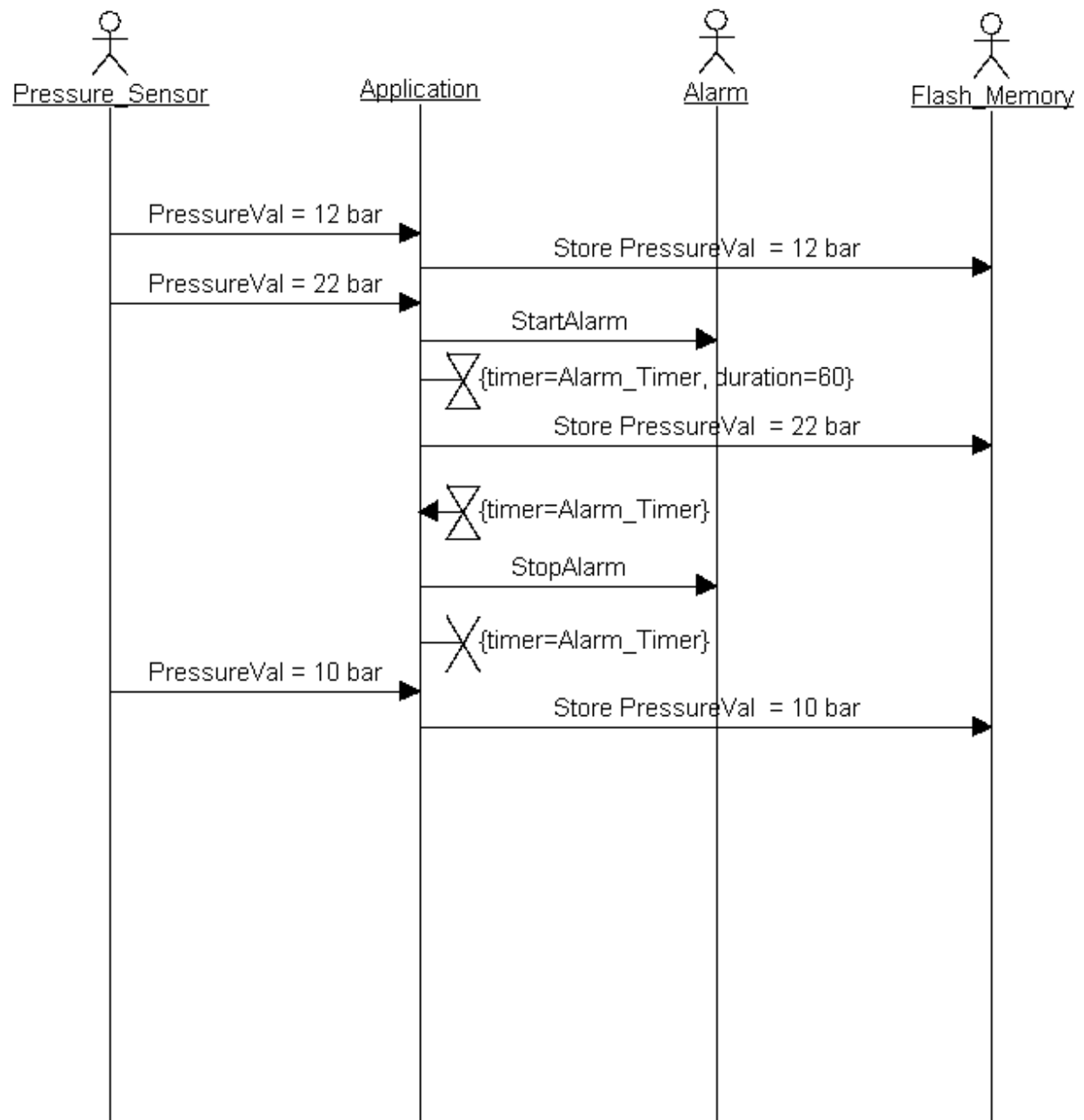
Use Case Diagram



Activity Diagram

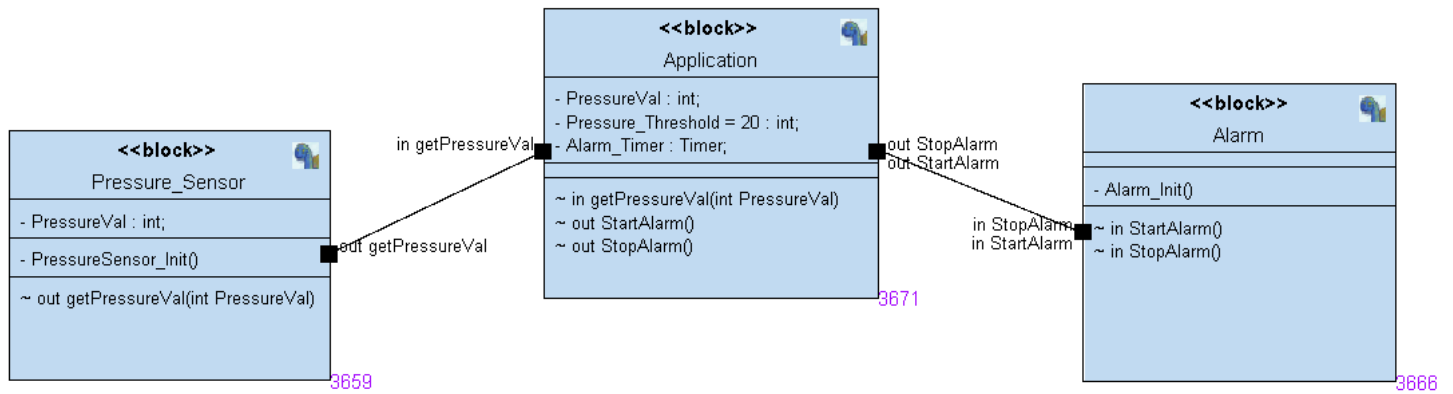


Sequence Diagram



This sequence diagram describes a scenario of the system.

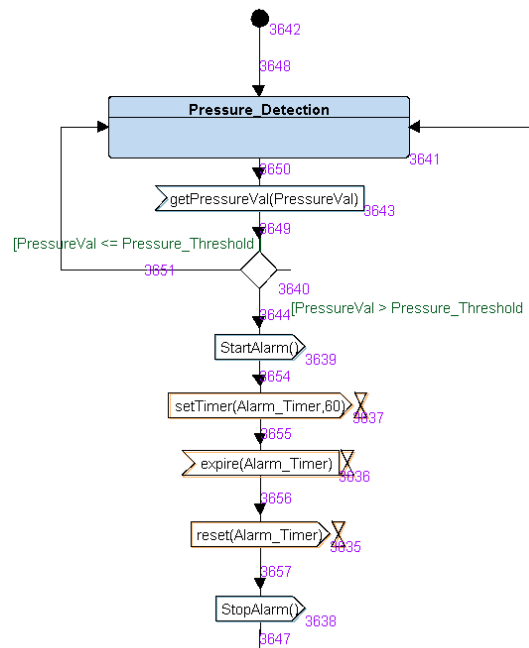
System Design



System Components

- Pressure sensor
- Alarm actuator
- Main application

Application



```

/*
 * App.h
 *
 * Created on: Apr 5, 2023
 * Author: O. A.
 *
 * Description:
 *
 */
#ifndef APP_H_
#define APP_H_

#include "state.h"
#include "driver.h"

#define ONE_SECOND_DELAY (534000U)
#define ALARM_TIME_PERIOD (ONE_SECOND_DELAY * 60)

/* State pointer to functions */
extern void (*PRESSURE_DETECTION_STATE) ();

STATE_DEFINE(PRESSURE_DETECTION);

#endif /* APP_H_ */

```

```

#include "App.h"
#include "Alarm.h"
#include "Pressure_Sensor.h"

volatile int g_pressureVal = 0U;
const int pressure_Threshold = 20U; /* 20 bar*/

/* state ptr. to function*/
void (*PRESSURE_DETECTION_STATE) (void);

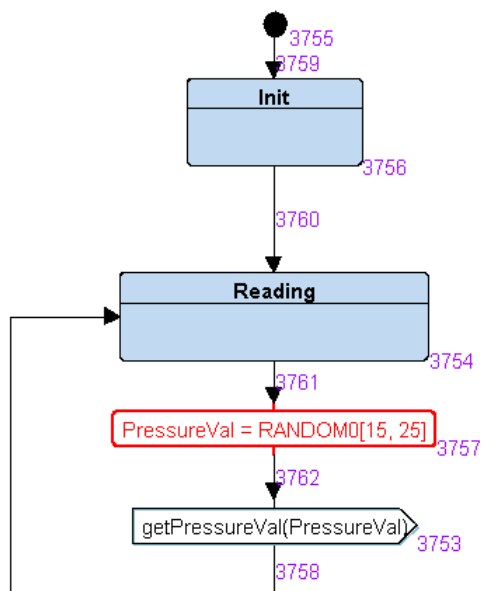
/* define states */
enum
{
    PRESSURE_DETECTION,
}PRESSURE_DETECTION_STATE_ID;

STATE_DEFINE(PRESSURE_DETECTION)
{
    PRESSURE_DETECTION_STATE_ID = PRESSURE_DETECTION;

    if(g_pressureVal > pressure_Threshold)
    {
        StartAlarm();
        Delay(ALARM_TIME_PERIOD);
        StopAlarm();
    }
    else
    {
        /**/
    }
}

```

Pressure Sensor Module



```
* Pressure_Sensor.h
*
* Created on: Apr 4, 2023
* Author: O. A.
*
* Description:
*
*/
#ifndef PRESSURE_SENSOR_H_
#define PRESSURE_SENSOR_H_

#include "state.h"
#include "driver.h"

void PressureSensor_Init(void);

/* State pointer to functions */
extern void (*PS_STATE) ();

STATE_DEFINE(PS_READING);

#endif /* PRESSURE_SENSOR_H_ */
```

```
* Pressure_Sensor.c
*
* Created on: Apr 4, 2023
* Author: O. A.
*
* Description:
*
*/
#include "Pressure_Sensor.h"

extern int g_pressureVal;

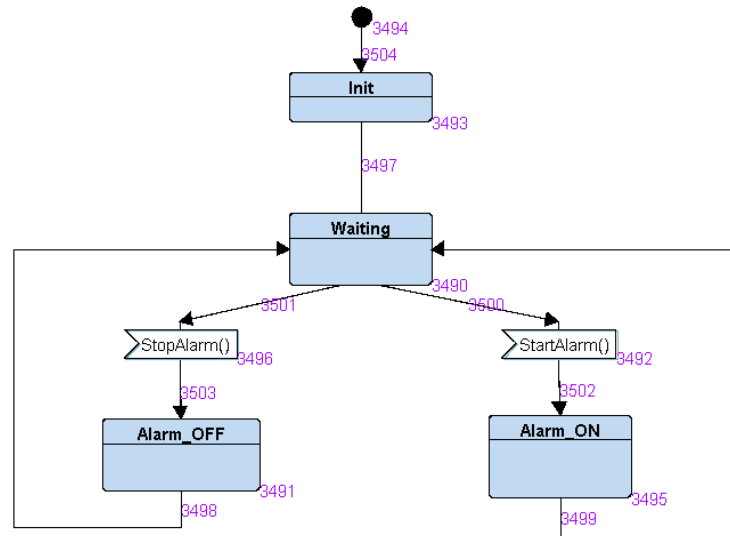
void PressureSensor_Init(void)
{
    /* Sensor Driver Init */
}

/* state ptr to function*/
void (*PS_STATE) (void);

/* define states */
enum
{
    PS_READING,
}PS_STATE_ID;

STATE_DEFINE(PS_READING)
{
    PS_STATE_ID = PS_READING;
    g_pressureVal = getPressureVal();
}
```

Alarm Module



```

/*
 * Alarm.h
 *
 * Created on: Apr 4, 2023
 * Author: O. A.
 *
 * Description:
 *
 */

#ifndef ALARM_H_
#define ALARM_H_

#include "state.h"
#include "driver.h"

void Alarm_Init(void);
void StartAlarm(void);
void StopAlarm(void);

/* State pointer to functions */
extern void (*ALARM_STATE) ();

STATE_DEFINE(ALARM_OFF);
STATE_DEFINE(ALARM_ON);
STATE_DEFINE(ALARM_WAITING);

#endif

```

```

#include "Alarm.h"
/* state ptr to function*/
void (*ALARM_STATE) (void);
/* define states */
enum{
    ALARM_OFF,
    ALARM_ON,
    ALARM_WAITING
}ALARM_STATE_ID;

STATE_DEFINE(ALARM_WAITING){
    ALARM_STATE_ID = ALARM_WAITING;
}

STATE_DEFINE(ALARM_ON){
    ALARM_STATE_ID = ALARM_ON;
    Set_Alarm_actuator(ALARM_ON);
    ALARM_STATE = STATE(ALARM_WAITING);
}

STATE_DEFINE(ALARM_OFF){
    ALARM_STATE_ID = ALARM_OFF;
    Set_Alarm_actuator(ALARM_OFF);
    ALARM_STATE = STATE(ALARM_WAITING);
}

void Alarm_Init(void){
    Set_Alarm_actuator(ALARM_OFF);
}

void StartAlarm(void){
    ALARM_STATE = STATE(ALARM_ON);
    ALARM_STATE();
}

void StopAlarm(void){
    ALARM_STATE = STATE(ALARM_OFF);
    ALARM_STATE();
}

```

Compilation

Makefile

```
#@copyright : Omar Anwer

#Project name
PROJECT_NAME = Pressure_Controller

#Architectures Specific Flags
CPU           = cortex-m3
CFLAGS_ARCH  = -mcpu=$(CPU)
#CFLAGS_ARCH  = -mcpu=$(CPU) -m$(ARCH) --specs=$(SPECS)

#Compiler Flags and Defines
CC            = arm-none-eabi-
DBGCFLAGS     = -g -gdwarf-2
CFLAGS        = -ansi -std=c89 -O0 -Wall $(CFLAGS_ARCH) $(DBGCFLAGS)

#Linker Flags
LINKER_FILE    = linker_script.ld
LDFLAGS_ARCH  = -T $(LINKER_FILE)
STARTUP_FILE   = startup.s

#includes
INCS           = -I .
LIBS           =

#.c and .s files
SRC            = $(wildcard *.c)
AS             = $(wildcard *.s)

PRE            = $(SRC:.c=.i)
SRCOBJ         = $(SRC:.c=.o)
ASOBJ          = $(AS:.s=.o)

all: $(PROJECT_NAME).bin
    @echo ""
    @$$(CC)size.exe $(PROJECT_NAME).elf
    @echo ""
    @echo "Building done..."

%.o: %.s
    $(CC)as.exe $(INCS) $< -o $@
    @echo ""

%.o: %.c
    $(CC)gcc.exe -S $(INCS) $<
    @echo ""
    $(CC)gcc.exe -c $(CFLAGS) $(INCS) $< -o $@
    @echo ""
```

```

%.i: %.c
    $(CC)gcc.exe -E $(INCS) $< -o $@
    @echo ""

$(PROJECT_NAME).elf: $(ASOBJ) $(SRCOBJ) $(PRE)
    $(CC)ld.exe $(LDFLAGS_ARCH) $(LIBS) $(ASOBJ) $(SRCOBJ) -o $@ -
Map=$(PROJECT_NAME).map
    @echo ""
    $(CC)objdump.exe -h $@
    @echo ""
    $(CC)readelf.exe -S $@
    @echo ""
    @cp $(PROJECT_NAME).elf $(PROJECT_NAME).axf

$(PROJECT_NAME).bin: $(PROJECT_NAME).elf
    $(CC)objcopy.exe -O binary $< $@
    @echo ""
    $(CC)objcopy.exe -O ihex $< $(PROJECT_NAME).hex
    @echo ""

clean:
    @rm *.bin *.hex *.elf *.axf *.map

clean-all:
    #@rm -rf $(filter-out $(STARTUP_FILE), $(AS))
    @rm *.s
    @rm *.i *.o *.bin *.hex *.elf *.axf *.map
    @echo "All cleaned..."

```

Startup code

```
#include <stdint.h>

/*#define stack_top 0x20001000*/

extern int main(void);

extern uint32_t _stack_top;
extern uint32_t _E_text;
extern uint32_t _S_data;
extern uint32_t _E_data;
extern uint32_t _S_bss;
extern uint32_t _E_bss;

void Reset_Handler(void)
{
    /* copy .data section byte by byte from FLASH to SRAM */
    uint8_t* pSrc = (uint8_t*)&_E_text;
    uint8_t* pDst = (uint8_t*)&_S_data;
    uint32_t DATA_SIZE = (uint8_t*)&_E_data - (uint8_t*)&_S_data;

    uint32_t i;
    for(i = 0; i < DATA_SIZE; ++i)
    {
        *pDst = *pSrc;
        pSrc++;
        pDst++;
    }

    /* initialize .data section in SRAM */
    pDst = (uint8_t*)&_S_bss;
    uint32_t BSS_SIZE = (uint8_t*)&_E_bss - (uint8_t*)&_S_bss;

    for(i = 0; i < BSS_SIZE; ++i)
    {
        *pDst = 0;
        pDst++;
    }

    /* jump to main() */
    main();
}

/* initialize vectors */
void Default_Handler(void)
{
    Reset_Handler();
}

void NMI_Handler(void) __attribute__((weak,
alias("Default_Handler")));
void H_fault_Handler(void) __attribute__((weak, alias("Default_Handler")));
```

```
void MM_fault_Handler(void)          __attribute__(( weak,  
alias("Default_Handler") ));  
void Bus_fault_Handler(void)        __attribute__(( weak, alias("Default_Handler") ));  
void Usage_fault_Handler(void)      __attribute__(( weak, alias("Default_Handler") ));  
  
uint32_t vectors[] __attribute__((section(".vectors"))) = {  
    (uint32_t) &_stack_top,  
    (uint32_t) &Reset_Handler,  
    (uint32_t) &NMI_Handler,  
    (uint32_t) &H_fault_Handler,  
    (uint32_t) &MM_fault_Handler,  
    (uint32_t) &Bus_fault_Handler,  
    (uint32_t) &Usage_fault_Handler,  
};
```

Linker Script

```
/*
    Linker script Cortex-M3
    By Eng.Omar
*/

ENTRY(Reset_Handler)

MEMORY
{
    FLASH (rx) : ORIGIN = 0x08000000, LENGTH = 64K
    SRAM (rwX) : ORIGIN = 0x20000000, LENGTH = 20K
}

SECTIONS
{
    .text :
    {
        *(.vectors*)
        *(.text*)
        *(.rodata)
        . = ALIGN(4);
        _E_text = .;
    }>FLASH

    .data :
    {
        _S_data = .;
        *(.data)
        . = ALIGN(4);
        _E_data = .;
    }>SRAM AT>FLASH

    .bss :
    {
        _S_bss = .;
        *(.bss*)
        _E_bss = .;
        . = ALIGN(4);
        . = . + 0x1000;
        _stack_top = .;
    }>SRAM
}
```

/*stack top after 4 KB*/

Symbol table

```
user@Huawei-phone MINGW64 /d/Programs/eclipse/eclipse-workspace/Pressure Controller
$ arm-none-eabi-nm.exe Pressure_Controller.elf
20000019 B _E_bss
20000000 D _E_data
080002dc T _E_text
20000000 B _S_bss
20000000 D _S_data
2000101c B _stack_top
08000084 T Alarm_Init
20000000 B ALARM_STATE
20000004 B ALARM_STATE_ID
080002cc W Bus_fault_Handler
080002cc T Default_Handler
0800012c T Delay
20000008 B g_pressureVal
080001d8 T getPressureVal
0800014e T GPIO_INITIALIZATION
080002cc W H_fault_Handler
080001f0 T main
080002cc W MM_fault_Handler
080002cc W NMI_Handler
2000000c B PRESSURE_DETECTION_STATE
20000010 B PRESSURE_DETECTION_STATE_ID
080002d8 T pressure_Threshold
08000100 T PressureSensor_Init
20000014 B PS_STATE
20000018 B PS_STATE_ID
08000240 T Reset_Handler
080001a0 T Set_Alarm_actuator
0800005c T ST_ALARM_OFF
08000034 T ST_ALARM_ON
0800001c T ST_ALARM_WAITING
080000cc T ST_PRESSURE_DETECTION
0800010c T ST_PS_READING
08000092 T StartAlarm
080000b0 T StopAlarm
080002cc W Usage_fault_Handler
08000000 T vectors
```

Map file

Memory Configuration

| Name | Origin | Length | Attributes |
|-----------|------------|------------|------------|
| FLASH | 0x08000000 | 0x00010000 | xr |
| SRAM | 0x20000000 | 0x00005000 | xrw |
| *default* | 0x00000000 | 0xffffffff | |

Linker script and memory map

| | | | |
|--------------|------------|-------|-----------------------|
| .text | 0x08000000 | 0x2dc | |
| *(.vectors*) | | | |
| .vectors | 0x08000000 | 0x1c | startup.o |
| | 0x08000000 | | vectors |
| *(.text*) | | | |
| .text | 0x0800001c | 0xb0 | Alarm.o |
| | 0x0800001c | | ST_ALARM_WAITING |
| | 0x08000034 | | ST_ALARM_ON |
| | 0x0800005c | | ST_ALARM_OFF |
| | 0x08000084 | | Alarm_Init |
| | 0x08000092 | | StartAlarm |
| | 0x080000b0 | | StopAlarm |
| .text | 0x080000cc | 0x34 | App.o |
| | 0x080000cc | | ST_PRESSURE_DETECTION |
| .text | 0x08000100 | 0x2c | Pressure_Sensor.o |

| | | |
|------------|------------|---------------------|
| | 0x08000100 | PressureSensor_Init |
| | 0x0800010c | ST_PS_READING |
| .text | 0x0800012c | 0xc4 driver.o |
| | 0x0800012c | Delay |
| | 0x0800014e | GPIO_INITIALIZATION |
| | 0x080001a0 | Set_Alarm_actuator |
| | 0x080001d8 | getPressureVal |
| .text | 0x080001f0 | 0x50 main.o |
| | 0x080001f0 | main |
| .text | 0x08000240 | 0x98 startup.o |
| | 0x08000240 | Reset_Handler |
| | 0x080002cc | MM_fault_Handler |
| | 0x080002cc | Usage_fault_Handler |
| | 0x080002cc | Bus_fault_Handler |
| | 0x080002cc | Default_Handler |
| | 0x080002cc | H_fault_Handler |
| | 0x080002cc | NMI_Handler |
| *(.rodata) | | |
| .rodata | 0x080002d8 | 0x4 App.o |
| | 0x080002d8 | pressure_Threshold |
| | 0x080002dc | . = ALIGN (0x4) |
| | 0x080002dc | _E_text = . |
| .glue_7 | 0x080002dc | 0x0 |
| .glue_7 | 0x080002dc | 0x0 linker stubs |

| | | |
|---------------|------------|--------------------------------|
| .glue_7t | 0x080002dc | 0x0 |
| .glue_7t | 0x080002dc | 0x0 linker stubs |
| .vfp11_veneer | 0x080002dc | 0x0 |
| .vfp11_veneer | 0x080002dc | 0x0 linker stubs |
| .v4_bx | 0x080002dc | 0x0 |
| .v4_bx | 0x080002dc | 0x0 linker stubs |
| .iplt | 0x080002dc | 0x0 |
| .iplt | 0x080002dc | 0x0 Alarm.o |
| .rel.dyn | 0x080002dc | 0x0 |
| .rel.iplt | 0x080002dc | 0x0 Alarm.o |
| .data | 0x20000000 | 0x0 load address 0x080002dc |
| | 0x20000000 | _S_data = . |
| *(.data) | | |
| .data | 0x20000000 | 0x0 Alarm.o |
| .data | 0x20000000 | 0x0 App.o |
| .data | 0x20000000 | 0x0 Pressure_Sensor.o |
| .data | 0x20000000 | 0x0 driver.o |
| .data | 0x20000000 | 0x0 main.o |
| .data | 0x20000000 | 0x0 startup.o |
| | 0x20000000 | . = ALIGN (0x4) |
| | 0x20000000 | _E_data = . |
| .igot.plt | 0x20000000 | 0x0 load address 0x080002dc |
| .igot.plt | 0x20000000 | 0x0 Alarm.o |
| | | |
| .bss | 0x20000000 | 0x101c load address 0x080002dc |

```

                                0x20000000      _S_bss = .

*(.bss*)

.bss      0x20000000      0x5 Alarm.o

                                0x20000000      ALARM_STATE

                                0x20000004      ALARM_STATE_ID

*fill*    0x20000005      0x3

.bss      0x20000008      0x9 App.o

                                0x20000008      g_pressureVal

                                0x2000000c      PRESSURE_DETECTION_STATE

                                0x20000010      PRESSURE_DETECTION_STATE_ID

*fill*    0x20000011      0x3

.bss      0x20000014      0x5 Pressure_Sensor.o

                                0x20000014      PS_STATE

                                0x20000018      PS_STATE_ID

.bss      0x20000019      0x0 driver.o

.bss      0x20000019      0x0 main.o

.bss      0x20000019      0x0 startup.o

                                0x20000019      _E_bss = .

                                0x2000001c      . = ALIGN (0x4)

*fill*    0x20000019      0x3

                                0x2000101c      . = (. + 0x1000)

*fill*    0x2000001c      0x1000

                                0x2000101c      _stack_top = .

LOAD Alarm.o

LOAD App.o

```

LOAD Pressure_Sensor.o

LOAD driver.o

LOAD main.o

LOAD startup.o

OUTPUT(Pressure_Controller.elf elf32-littlearm)

LOAD linker stubs

| | | |
|---------------|------------|-------------------------|
| .debug_info | 0x00000000 | 0x6ea |
| .debug_info | 0x00000000 | 0x163 Alarm.o |
| .debug_info | 0x00000163 | 0x116 App.o |
| .debug_info | 0x00000279 | 0x10b Pressure_Sensor.o |
| .debug_info | 0x00000384 | 0x10c driver.o |
| .debug_info | 0x00000490 | 0xc5 main.o |
| .debug_info | 0x00000555 | 0x195 startup.o |
| | | |
| .debug_abbrev | 0x00000000 | 0x472 |
| .debug_abbrev | 0x00000000 | 0xe3 Alarm.o |
| .debug_abbrev | 0x000000e3 | 0xbf App.o |
| .debug_abbrev | 0x000001a2 | 0xcb Pressure_Sensor.o |
| .debug_abbrev | 0x0000026d | 0xc5 driver.o |
| .debug_abbrev | 0x00000332 | 0x6e main.o |
| .debug_abbrev | 0x000003a0 | 0xd2 startup.o |
| | | |
| .debug_loc | 0x00000000 | 0x3a4 |
| .debug_loc | 0x00000000 | 0x120 Alarm.o |

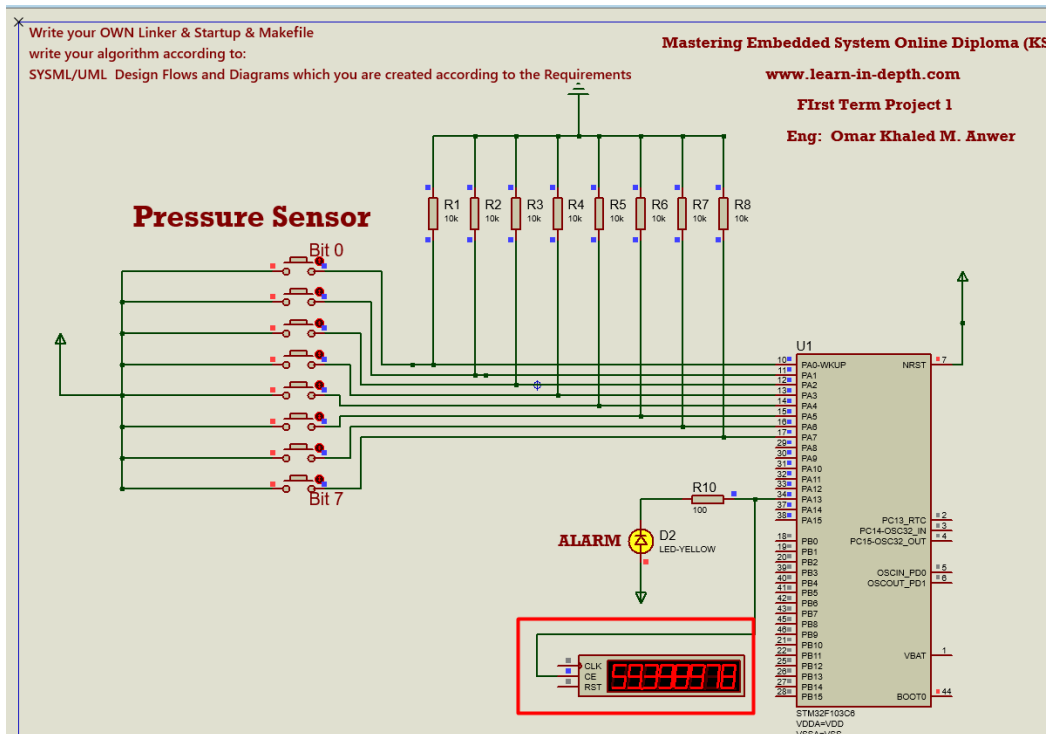
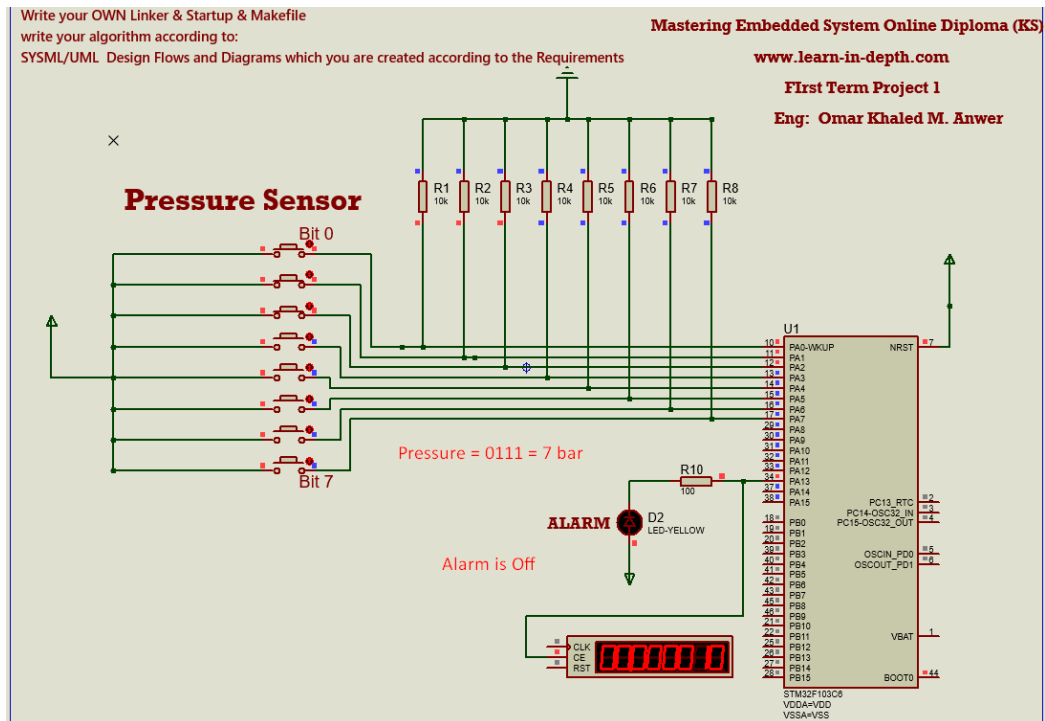
| | | |
|----------------|------------|------------------------|
| .debug_loc | 0x00000120 | 0x2c App.o |
| .debug_loc | 0x0000014c | 0x70 Pressure_Sensor.o |
| .debug_loc | 0x000001bc | 0x140 driver.o |
| .debug_loc | 0x000002fc | 0x2c main.o |
| .debug_loc | 0x00000328 | 0x7c startup.o |
| | | |
| .debug_aranges | 0x00000000 | 0xc0 |
| .debug_aranges | | |
| | 0x00000000 | 0x20 Alarm.o |
| .debug_aranges | | |
| | 0x00000020 | 0x20 App.o |
| .debug_aranges | | |
| | 0x00000040 | 0x20 Pressure_Sensor.o |
| .debug_aranges | | |
| | 0x00000060 | 0x20 driver.o |
| .debug_aranges | | |
| | 0x00000080 | 0x20 main.o |
| .debug_aranges | | |
| | 0x000000a0 | 0x20 startup.o |
| | | |
| .debug_line | 0x00000000 | 0x431 |
| .debug_line | 0x00000000 | 0x7f Alarm.o |
| .debug_line | 0x0000007f | 0x51 App.o |
| .debug_line | 0x000000d0 | 0x68 Pressure_Sensor.o |
| .debug_line | 0x00000138 | 0x120 driver.o |

| | | |
|-------------|------------|------------------------------|
| .debug_line | 0x00000258 | 0x85 main.o |
| .debug_line | 0x000002dd | 0x154 startup.o |
| .debug_str | 0x00000000 | 0x317 |
| .debug_str | 0x00000000 | 0x171 Alarm.o |
| | | 0x1cb (size before relaxing) |
| .debug_str | 0x00000171 | 0x72 App.o |
| | | 0x1c2 (size before relaxing) |
| .debug_str | 0x000001e3 | 0x49 Pressure_Sensor.o |
| | | 0x19f (size before relaxing) |
| .debug_str | 0x0000022c | 0x57 driver.o |
| | | 0x19d (size before relaxing) |
| .debug_str | 0x00000283 | 0xc main.o |
| | | 0x177 (size before relaxing) |
| .debug_str | 0x0000028f | 0x88 startup.o |
| | | 0x1dc (size before relaxing) |
| .comment | 0x00000000 | 0x49 |
| .comment | 0x00000000 | 0x49 Alarm.o |
| | | 0x4a (size before relaxing) |
| .comment | 0x00000049 | 0x4a App.o |
| .comment | 0x00000049 | 0x4a Pressure_Sensor.o |
| .comment | 0x00000049 | 0x4a driver.o |
| .comment | 0x00000049 | 0x4a main.o |
| .comment | 0x00000049 | 0x4a startup.o |

| | | |
|-----------------|------------|------------------------|
| .ARM.attributes | 0x00000000 | 0x2d |
| .ARM.attributes | 0x00000000 | 0x2d Alarm.o |
| .ARM.attributes | 0x0000002d | 0x2d App.o |
| .ARM.attributes | 0x0000005a | 0x2d Pressure_Sensor.o |
| .ARM.attributes | 0x00000087 | 0x2d driver.o |
| .ARM.attributes | 0x000000b4 | 0x2d main.o |
| .ARM.attributes | 0x000000e1 | 0x2d startup.o |
| .debug_frame | 0x00000000 | 0x250 |
| .debug_frame | 0x00000000 | 0xbc Alarm.o |
| .debug_frame | 0x000000bc | 0x2c App.o |
| .debug_frame | 0x000000e8 | 0x4c Pressure_Sensor.o |
| .debug_frame | 0x00000134 | 0xa0 driver.o |
| .debug_frame | 0x000001d4 | 0x2c main.o |
| .debug_frame | 0x00000200 | 0x50 startup.o |

Simulation

Simulaton video



SYSML/UML Design Flows and Diagrams which you are created according to the Requirements

www.learn-in-depth.com

Eng: Omar Khaled M. Anwer

