

# **COMP 446 / 546**

# **ALGORITHM DESIGN**

# **AND ANALYSIS**

**LECTURE 3 DIVIDE AND CONQUER**

**ALPTEKİN KÜPÇÜ**

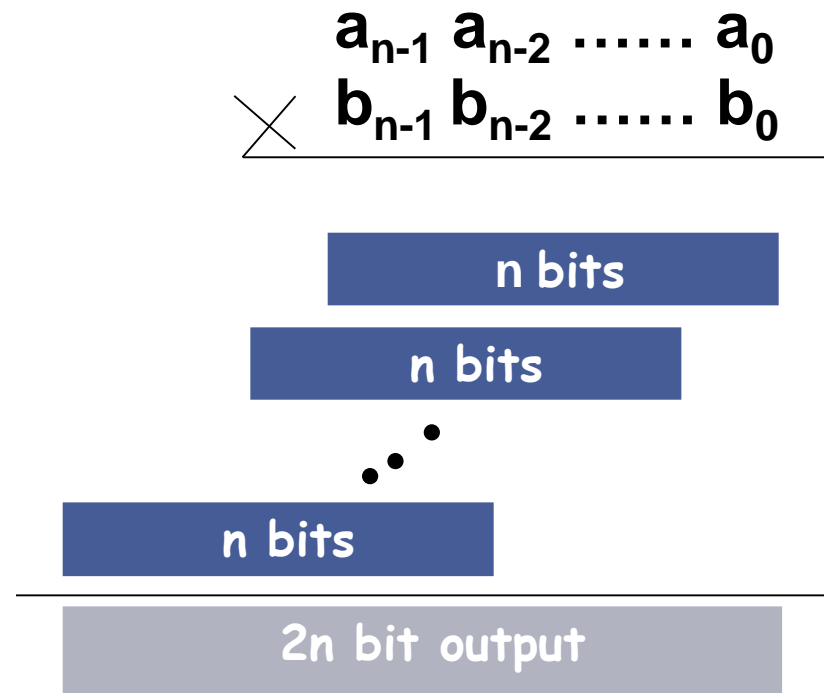
Based on slides of Shafi Goldwasser, David Luebke, George Kollios, Roger Crawfis, and Cevdet Aykanat

# RECAP

- What have we seen?
  - Worst-case vs. average-case analysis
  - Stable Marriage Problem
    - Fun problem applicable to many scenarios
    - Algorithm design must take into account the goals
    - Simple correctness proofs
  - Insertion Sort
    - A daily algorithm (sorting a deck of cards)
  - Merge Sort
    - Analyzing recurrence relations
    - **Divide-and-Conquer** paradigm
- Let's remember:
  - Binary Search

# MULTIPLYING LARGE INTEGERS

- Given two  $n$ -bit integers  $a$  and  $b$ , compute  $c=ab$
- Naive (grade-school) algorithm
- Cost?
- Total work  $\Theta(n^2)$



# MULTIPLYING LARGE INTEGERS: DIVIDE AND CONQUER

**Divide:** Write  $a = A_1 2^{n/2} + A_0$   
 $b = B_1 2^{n/2} + B_0$  } for  $A_0, A_1, B_0, B_1$   
 $n/2$  bit integers  
Assume  $n=2^k$  w.l.o.g.

**Conquer:**  $ab = A_1 B_1 2^n + A_1 B_0 2^{n/2} + B_1 A_0 2^{n/2} + A_0 B_0$   
 $= A_1 B_1 2^n + (A_1 B_0 + B_1 A_0) 2^{n/2} + A_0 B_0$

Reduces to 4 multiplications of  $n/2$ -bit integers (done recursively), plus 3 additions and 2 shifts.  
Additions and shifts cost  $\Theta(n)$ .

# MULTIPLYING LARGE INTEGERS: DIVIDE AND CONQUER

$$T(n) = \underbrace{4}_{\text{\# subproblems}} \underbrace{T(n/2)}_{\substack{\text{Subproblem} \\ \text{size} \\ \text{recursive calls}}} + \underbrace{cn}_{\substack{\text{Work dividing} \\ \text{and combining} \\ \text{additions and shifts}}}$$

❑ Case 1 of Master Theorem

❑  $T(n) = \Theta(n^2)$

No better than the grade school algorithm???

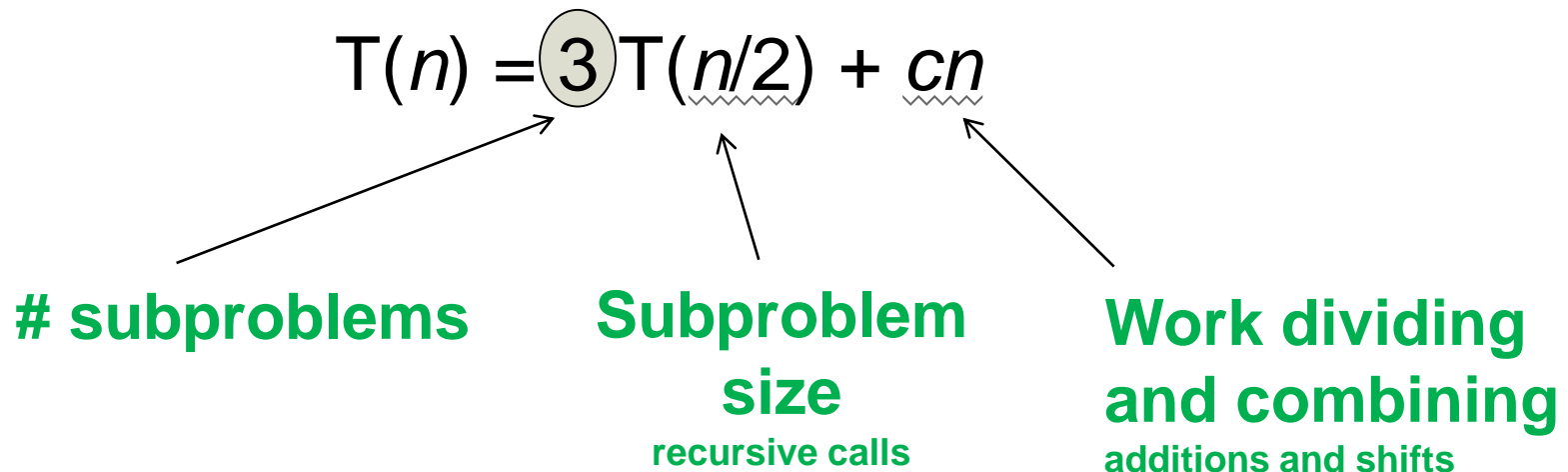
# MULTIPLYING LARGE INTEGERS: KARATSUBA'S ALGORITHM

Compute  $x = A_1 B_1$ ,  $y = A_0 B_0$ ,  $z = (A_0 + A_1)(B_0 + B_1)$   
Let  $ab = x 2^n + (z - y - x) 2^{n/2} + y$

Multiply  $(n, a, b)$

- $a$  and  $b$  are  $n$ -bit integers
  - assume  $n$  is a power of 2 for simplicity
1. If  $n < 2$  then use grade-school algorithm else
  2.  $A_1 \leftarrow a \text{ div } 2^{n/2}$  ;  $B_1 \leftarrow b \text{ div } 2^{n/2}$
  3.  $A_1 \leftarrow a \text{ mod } 2^{n/2}$  ;  $B_1 \leftarrow b \text{ mod } 2^{n/2}$
  4.  $x$       MULTIPLY  $(n/2, A_1, B_1)$
  5.  $y$       MULTIPLY  $(n/2, A_0, B_0)$
  6.  $z$       MULTIPLY  $(n/2, A_0 + A_1, B_0 + B_1)$
  7.      Output  $x 2^n + (z - x - y) 2^{n/2} + y$

# MULTIPLYING LARGE INTEGERS: KARATSUBA'S ALGORITHM



❑ Case 1 of Master Theorem

❑  $T(n) = \Theta(n^{\log_2 3} = n^{1.58496})$

Much better. But can we do even better??

# WHY STOP HERE?

- We can obtain a sequence of asymptotically faster integer multiplication algorithm by **splitting the inputs into more pieces**.
- If we split A and B into **k** equal parts then the corresponding multiplication algorithm is obtained from an interpolation-based polynomial multiplication algorithm of two degree **k-1** polynomials.
- Since the product is of degree **2(k-1)**, we need to evaluate **2k-1** points. Thus there are **2k-1** multiplications each of size **n/k** and time for splitting and adding is still **O(n)**.
- $T(n) = (2k-1)T(\frac{n}{k}) + cn = \Theta(n^{\log_k 2k-1}) \approx n^\varepsilon$  for any  $\varepsilon > 1$
- **Fastest:  $T(n) = \Theta(n \log n \log \log n)$** 
  - Based on the Fast Fourier Transform



# EXPONENTIATION

- Problem: compute  $a^n$ , where  $n$  is in  $\mathbb{N}$ .
- Naive algorithm: Compute  $a^1, a^2, a^3, \dots, a^n$  Complexity:  $\Theta(n)$  multiplications
- Divide-and-Conquer algorithm:

$$a^n = \begin{cases} a^{n/2} \cdot a^{n/2} & \text{if } n \text{ is even} \\ a^{n-1/2} \cdot a^{n-1/2} \cdot a & \text{if } n \text{ is odd} \end{cases}$$

$$T(n) = T(n/2) + c \Rightarrow T(n) = \Theta(\log n) \text{ multiplications}$$

# MATRIX MULTIPLICATION

Input:  $A = [a_{ij}]$  ;  $B = [b_{ij}]$

Output:  $C = [c_{ij}] = AB$

$i, j = 1, 2, \dots, n$

$$\begin{pmatrix} c_{11} & c_{12} & \dots & \dots & c_{1n} \\ \vdots & c_{22} & \ddots & \ddots & \vdots \\ c_{n1} & c_{n2} & \dots & \dots & c_{nn} \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} & \dots & \dots & a_{1n} \\ \vdots & a_{22} & \ddots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & \dots & a_{nn} \end{pmatrix} \cdot \begin{pmatrix} b_{11} & b_{12} & \dots & \dots & b_{1n} \\ \vdots & b_{22} & \ddots & \ddots & \vdots \\ b_{n1} & b_{n2} & \dots & \dots & b_{nn} \end{pmatrix}$$

$$c_{ij} = \sum_{1 \leq k \leq n} a_{ik} \cdot b_{kj}$$

# STANDART ALGORITHM

```
for  $i \leftarrow 2$  to length[A]
  do for  $j \leftarrow 1$  to  $n$ 
    do  $c_{ij} \leftarrow 0$ 
      for  $k \leftarrow 1$  to  $n$ 
        do  $c_{ij} \leftarrow c_{ij} + a_{ik} \cdot b_{kj}$ 
```

**Running time =  $\Theta(n^3)$**   
**unit multiplications and additions**

Non-square matrices?

# DIVIDE AND CONQUER ALGORITHM

- **Idea:**  $n \times n$  matrix =  $2 \times 2$  matrix of  $(n/2) \times (n/2)$  submatrices

$$\begin{bmatrix} c_{11} & c_{12} \\ c_{21} & c_{22} \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \cdot \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix}$$

$$\mathbf{C} = \mathbf{A} \cdot \mathbf{B}$$

$$c_{11} = a_{11} b_{11} + a_{12} b_{21}$$

$$c_{12} = a_{11} b_{12} + a_{12} b_{22}$$

$$c_{21} = a_{21} b_{11} + a_{22} b_{21}$$

$$c_{22} = a_{21} b_{21} + a_{22} b_{22}$$

8 mults of  $(n/2) \times (n/2)$  submatrices

4 adds of  $(n/2) \times (n/2)$  submatrices

# ANALYSIS OF D&C ALGORITHM

$$T(n) = 8 T(n/2) + cn^2$$

**# subproblems**

**Subproblem size**  
recursive calls on  
(n/2) x (n/2) matrices

**Work dividing submatrices**

❑ Case 1 of Master Theorem

❑  $T(n) = \Theta(n^{\log_2 8} = n^3)$

No better than the standard algorithm??

# STRASSEN'S IDEA

- **Same Idea:**  $n \times n$  matrix =  $2 \times 2$  matrix of  $(n/2) \times (n/2)$  submatrices
- But multiply  $2 \times 2$  matrices with only **7** recursive mults

- $P_1 = a_{11} \times (b_{12} - b_{22})$

- $P_2 = (a_{11} + a_{12}) \times b_{22}$

- $P_3 = (a_{21} + a_{22}) \times b_{11}$

- $P_4 = a_{22} \times (b_{21} - b_{11})$

- $P_5 = (a_{11} + a_{22}) \times (b_{11} + b_{22})$

- $P_6 = (a_{11} - a_{22}) \times (b_{21} + b_{22})$

- $P_7 = (a_{11} - a_{21}) \times (b_{11} + b_{12})$

- $C_{11} = P_5 + P_4 - P_2 + P_6$

- $C_{12} = P_1 + P_2$

- $C_{21} = P_4 + P_3$

- $C_{22} = P_5 + P_1 - P_3 - P_7$

**7** mults

**18** adds/subs

# ANALYSIS OF STRASSEN'S ALGORITHM

$$T(n) = 7T(n/2) + cn^2$$

The diagram illustrates the recurrence relation  $T(n) = 7T(n/2) + cn^2$ . Three arrows point from descriptive text below to components of the equation: one from '# subproblems' to the coefficient 7, one from 'Subproblem size' to the term  $T(n/2)$ , and one from 'Work dividing submatrices' to the term  $cn^2$ . The term  $cn^2$  is underlined with a wavy line.

# subproblems

Subproblem size  
recursive calls on  
 $(n/2) \times (n/2)$  matrices

Work dividing submatrices

❑ Case 1 of Master Theorem

❑  $T(n) = \Theta(n^{\log_2 7} = n^{2.81})$

Beats the standard algorithm for  $n > 30$ .

Best known today:  $\Theta(n^{2.376})$  [Coppersmith-Winograd] only of theoretical interest.

# CONCLUSIONS

- **Divide and conquer is just one of several powerful techniques for algorithm design.**
  - Can lead to more efficient algorithms.
- **Divide and conquer algorithms can be analyzed using recurrence relations.**
  - So practice this math.



# QUICKSORT

- Proposed by C.A.R. Hoare in 1962.
- Divide and conquer algorithm but the work is in **divide** rather than in **combine**
- Different versions:
  - **Basic**: Good in average case (for a random input)
  - **Randomized**: good for all inputs in expectation (Randomized Las Vegas algorithm)
- Sorts **in place** (like insertion sort, but unlike merge sort).
- Very practical (even though asymptotically not optimal).

# IDEA: DIVIDE AND CONQUER

- Quicksort an  $n$ -element array  $A$ :

- **Divide:**

1. Pick a pivot element  $x$  in  $A$
2. Partition the array into three sub-arrays  
 $L(\text{elements} < x)$ ,  $E(\text{elements} = x)$ ,  $G(\text{elements} > x)$



**Conquer:** Recursively sort sub-arrays  $L$  and  $G$

**Combine:** Do nothing.

# HOW TO CHOOSE PIVOT X

## Basic Quick Sort:

Pivot is the first element:  $X = A[1]$

Time: worst case  $O(n^2)$  time

$O(n \log n)$  time for average input

## Randomized Quick Sort:

X is chosen at random from the array A  
(recursively each time a random choice)

Time: Expected  $O(n \log n)$  for all inputs

Randomness gives us more control over runtime.

# PSEUDOCODE FOR BASIC QUICKSORT

QUICKSORT ( $A, p, r$ )

if  $p < r$  then

$q \leftarrow \text{PARTITION}(A, p, r)$

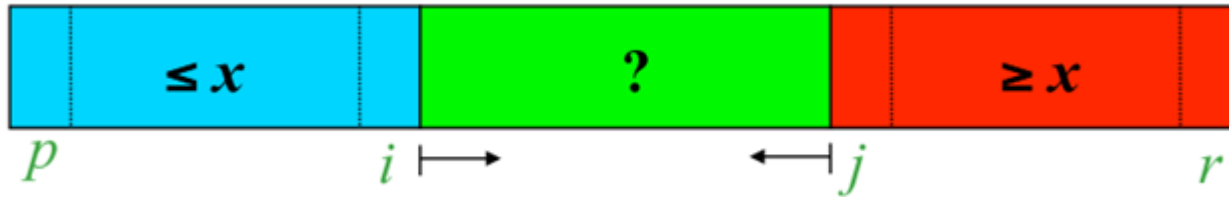
    QUICKSORT( $A, p, q-1$ )

    QUICKSORT( $A, q+1, r$ )

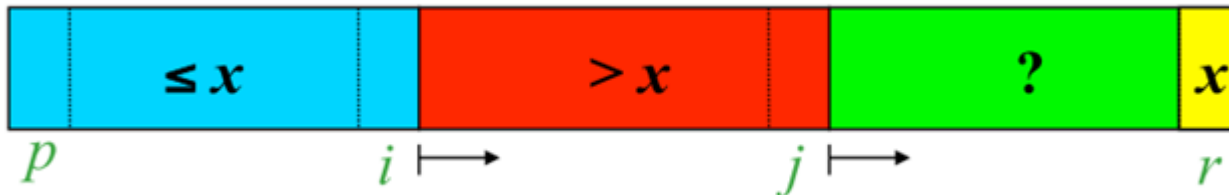
- $p$  and  $r$  denote beginning and ending indices
- Initial call: QUICKSORT( $A, 1, n$ )

# TWO PARTITIONING ALGORITHMS

1. Hoare's algorithm: Partitions around the first element of sub-array (pivot  $x = A[p]$ ). Partitions grow in opposite directions.

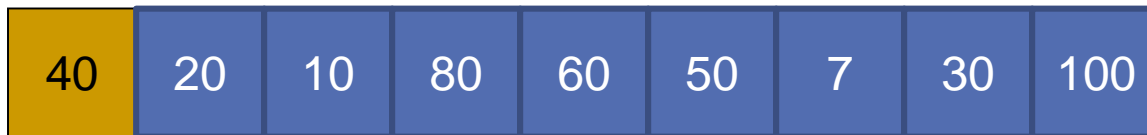


2. Lomuto's algorithm: Partitions around the last element of sub-array (pivot  $x = A[r]$ ). Partitions grow in the same direction.

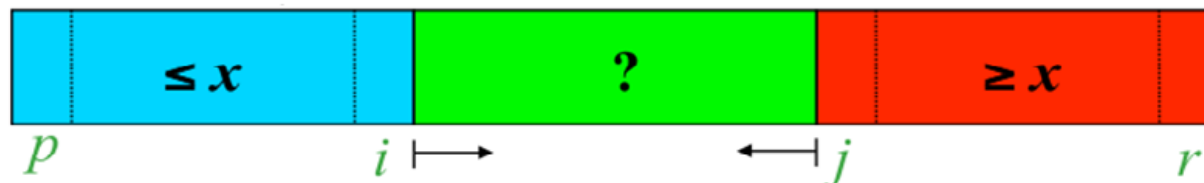


# HOARE PARTITIONING

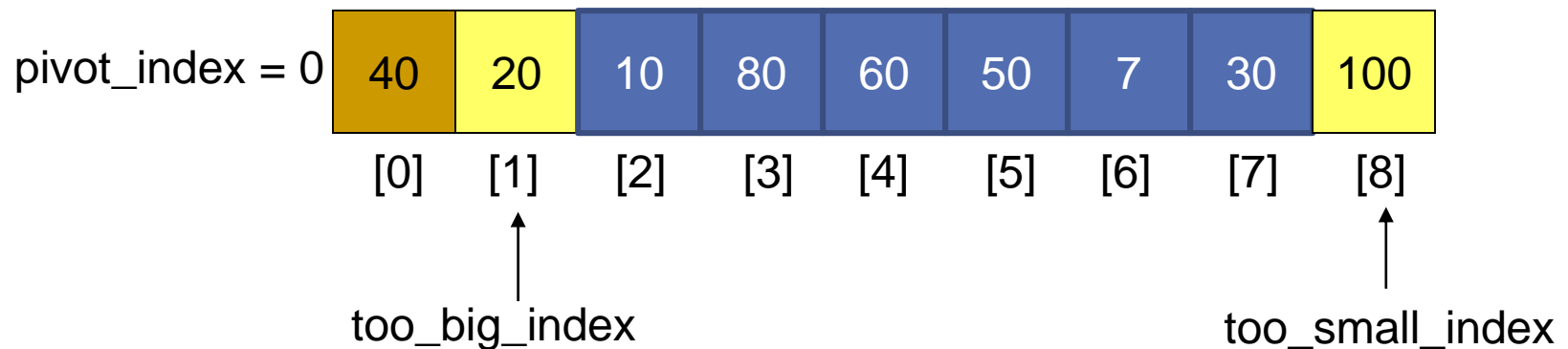
- Pick first element as pivot



- Partition array into sub-arrays:
  - Less than the pivot
  - Greater than the pivot
  - At the end, put pivot into the middle

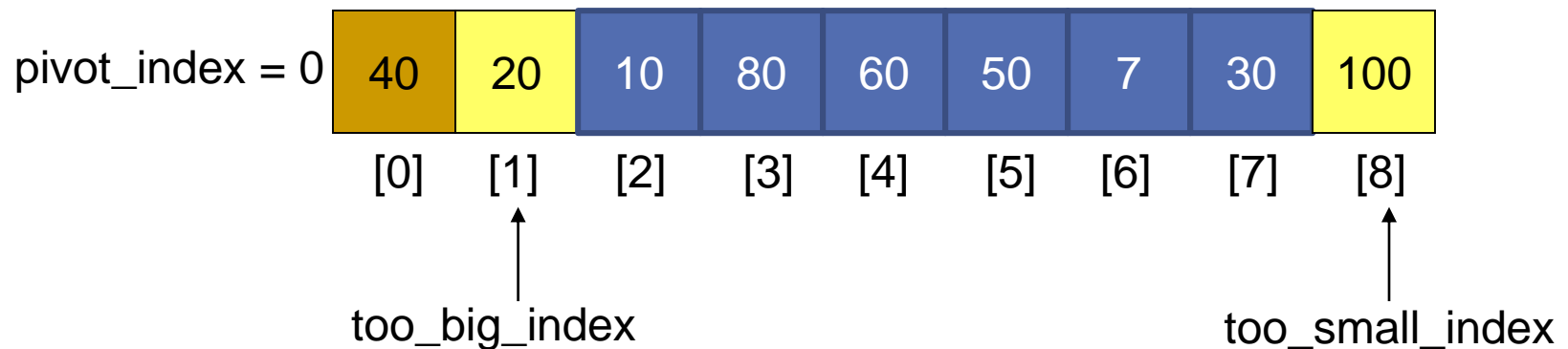


# PARTITIONING EXAMPLE



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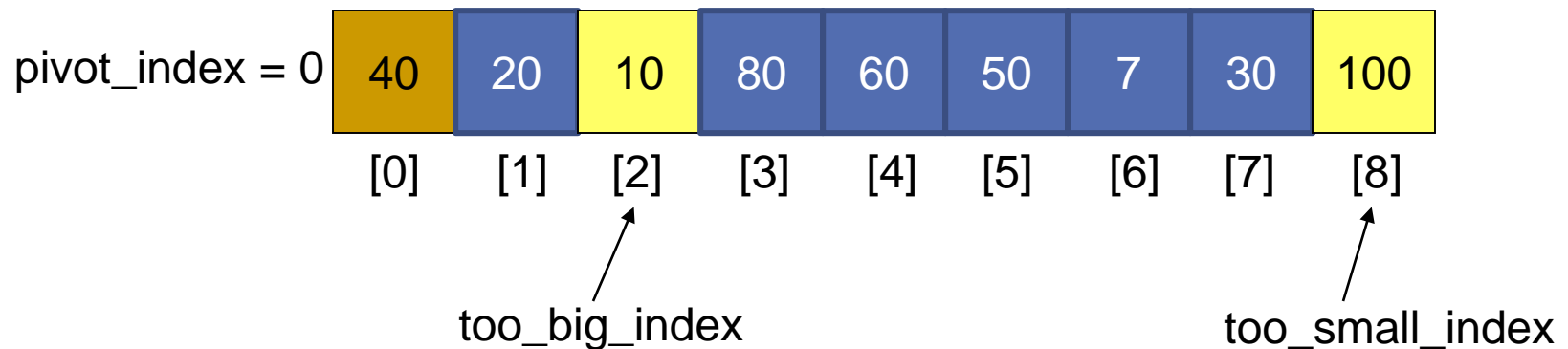
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     $++\text{too\_big\_index}$





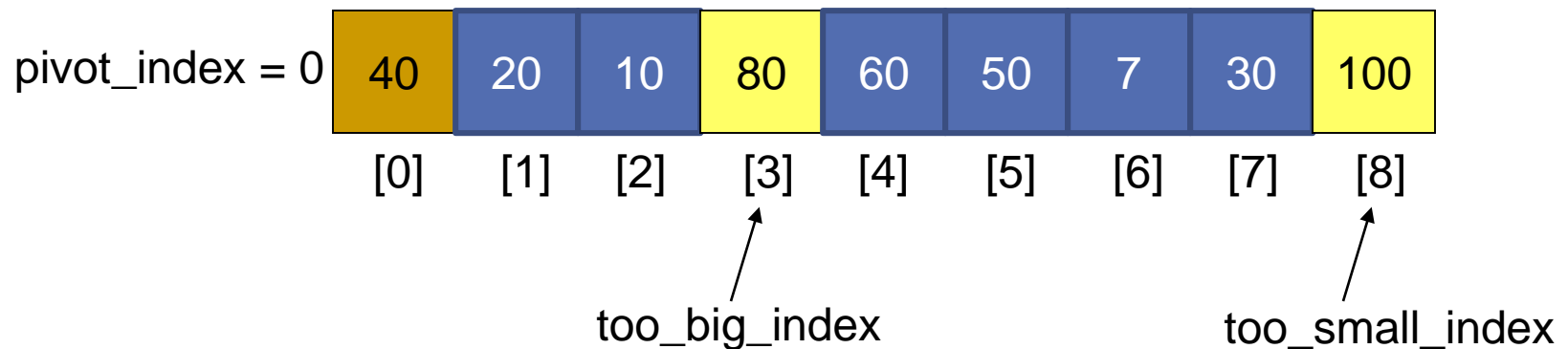
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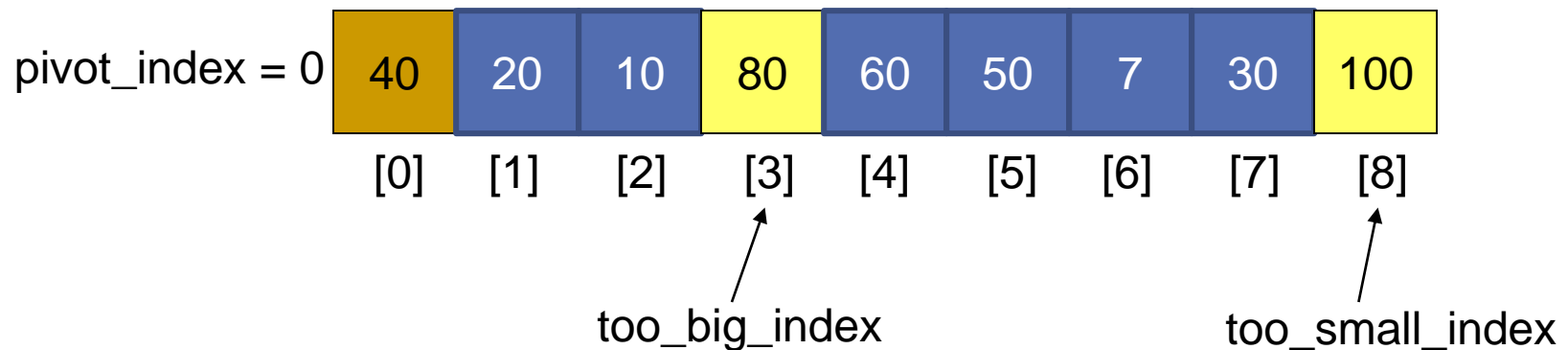
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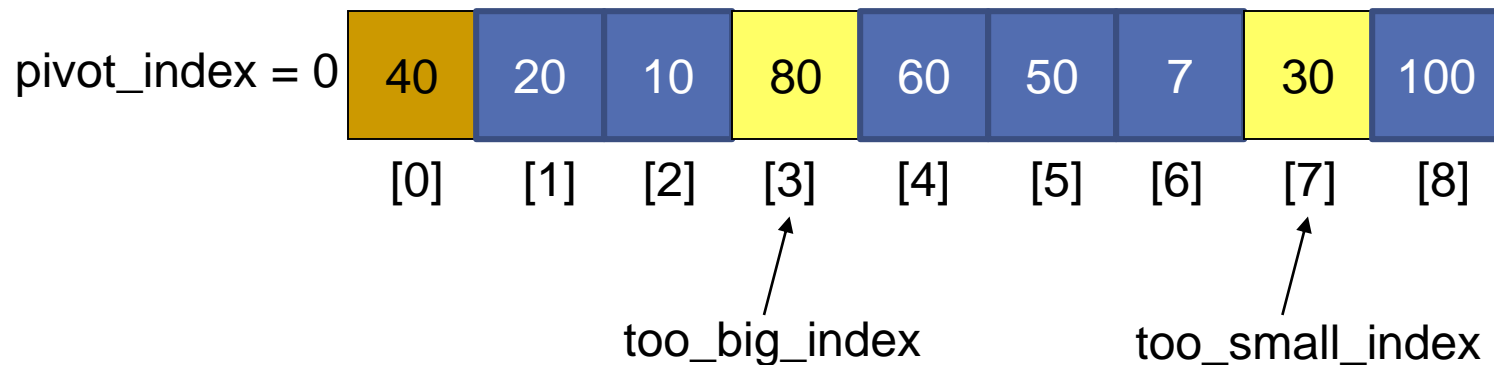
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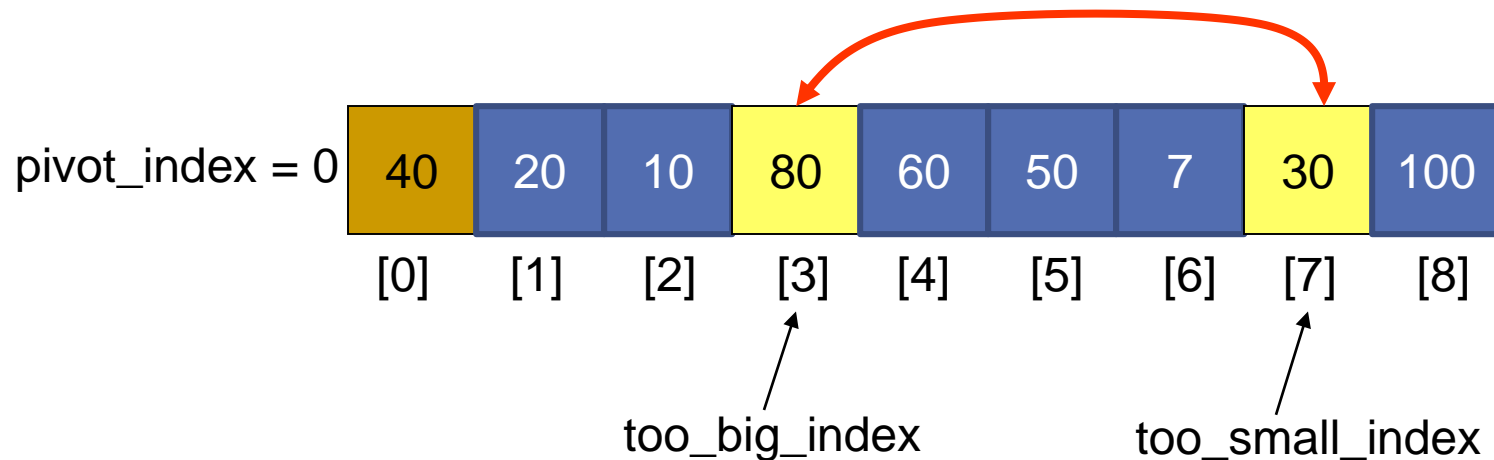
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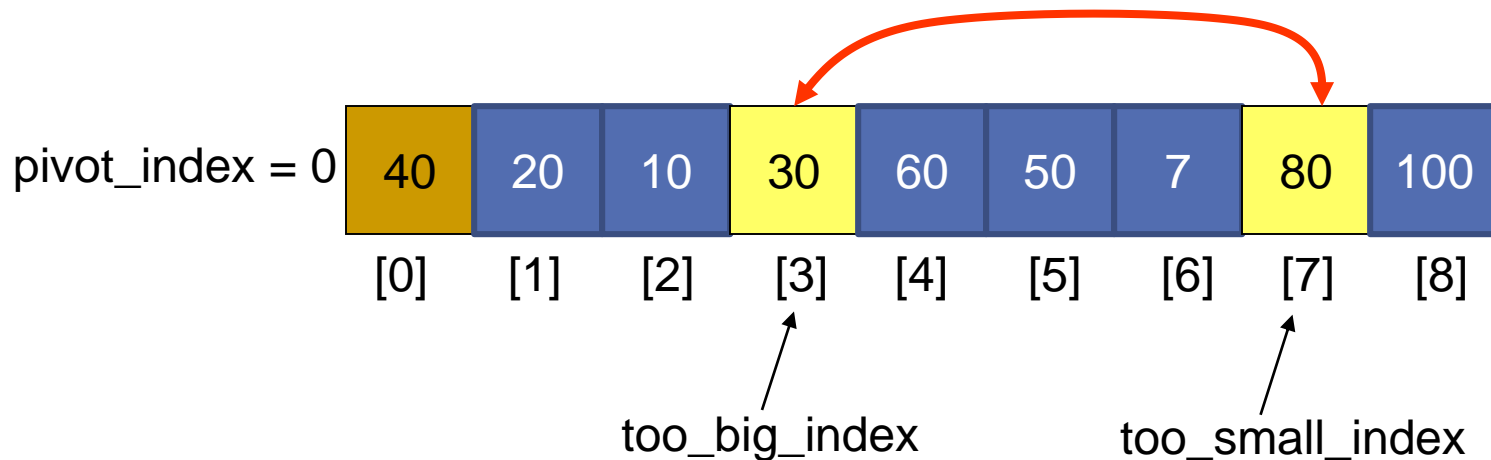
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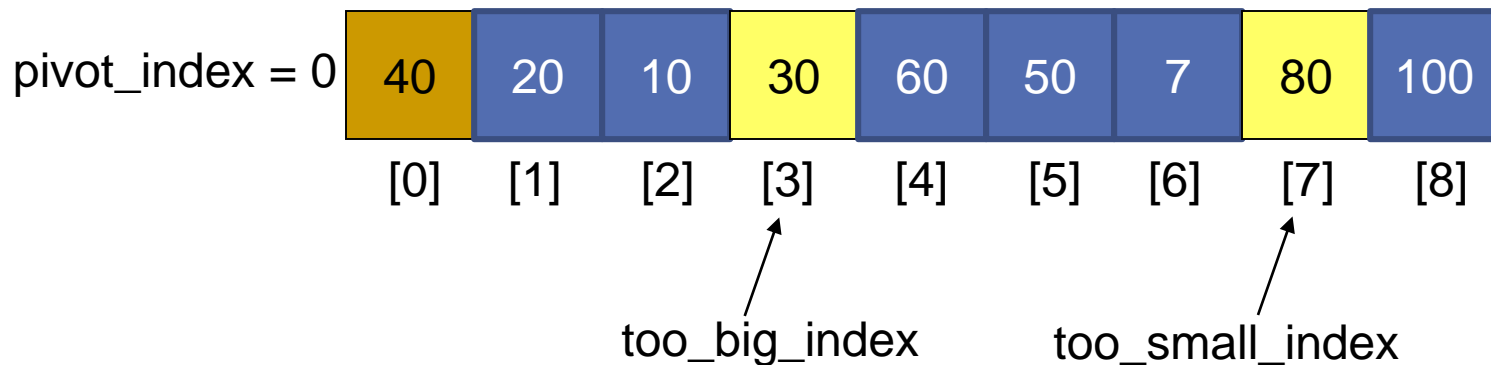
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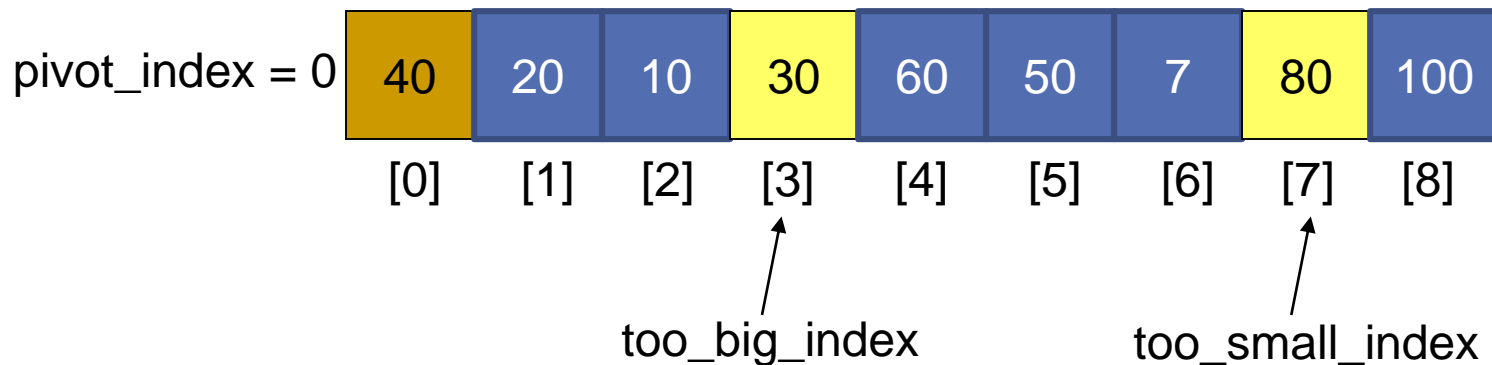
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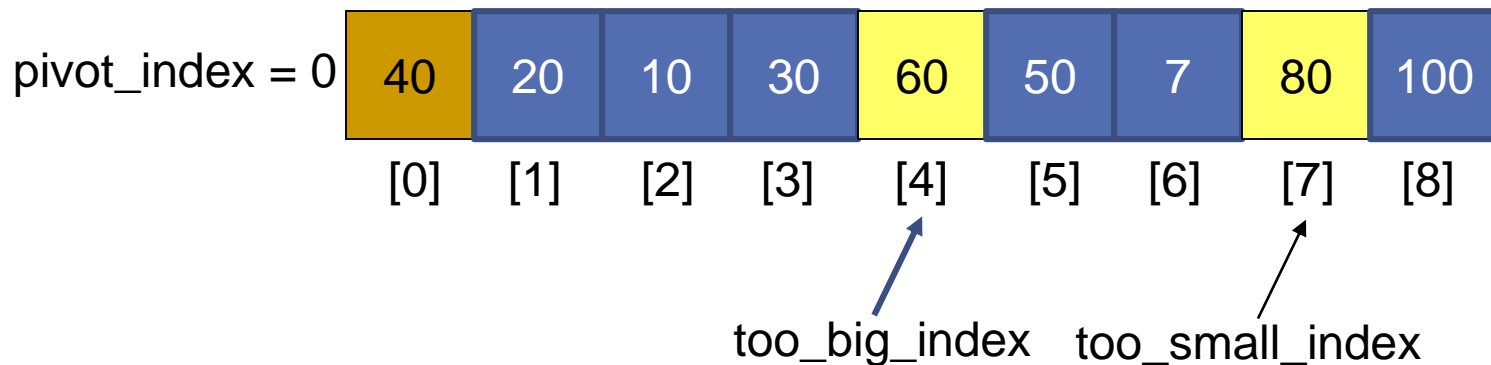
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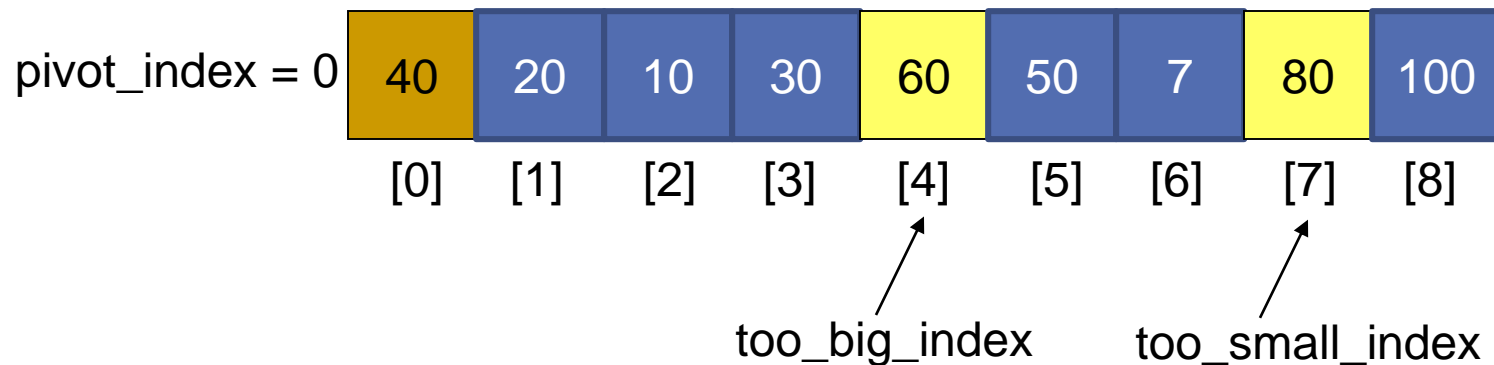
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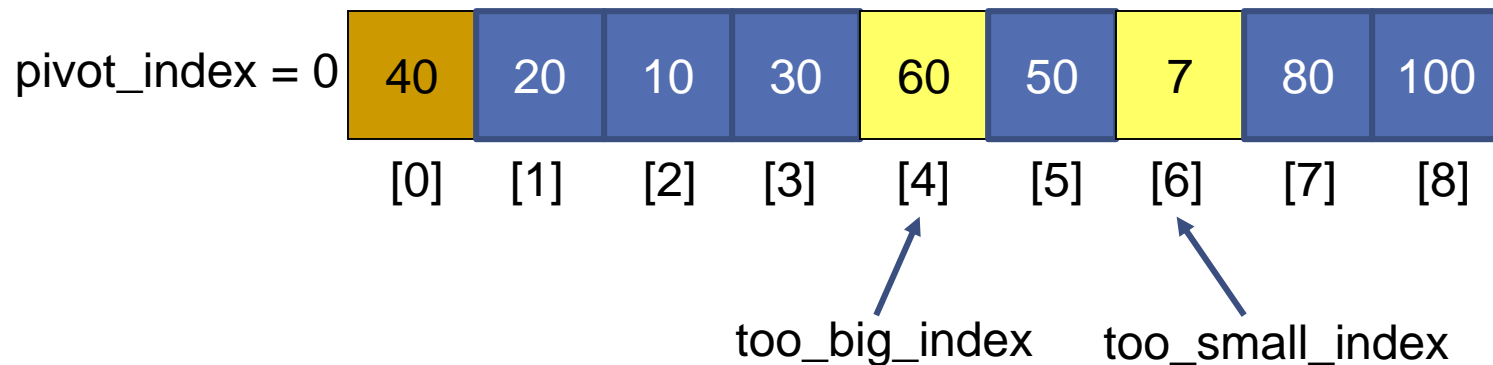
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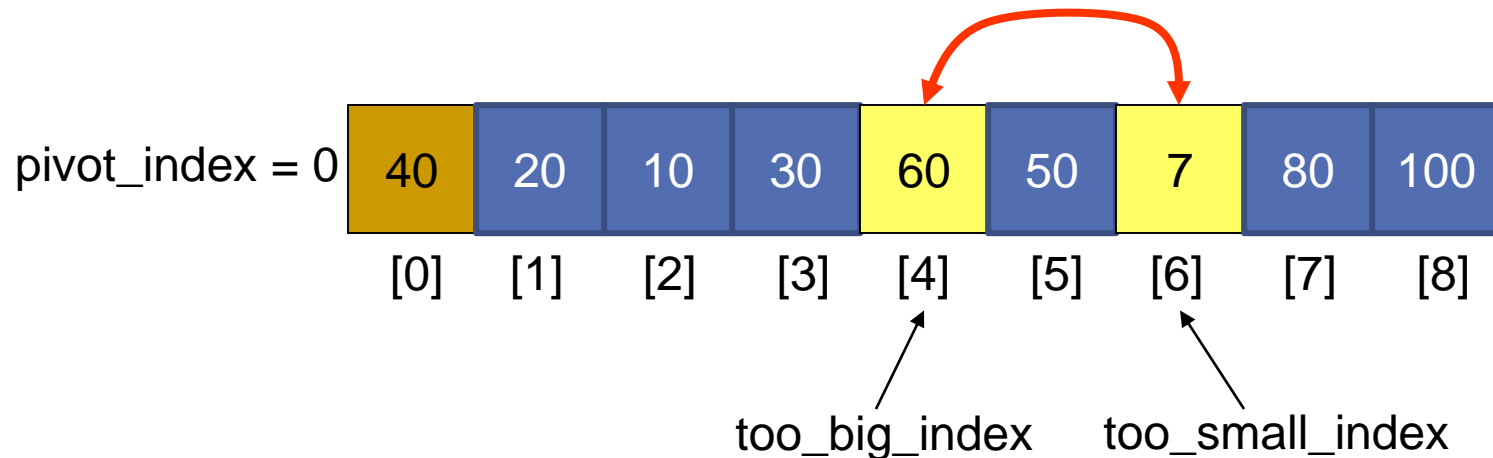
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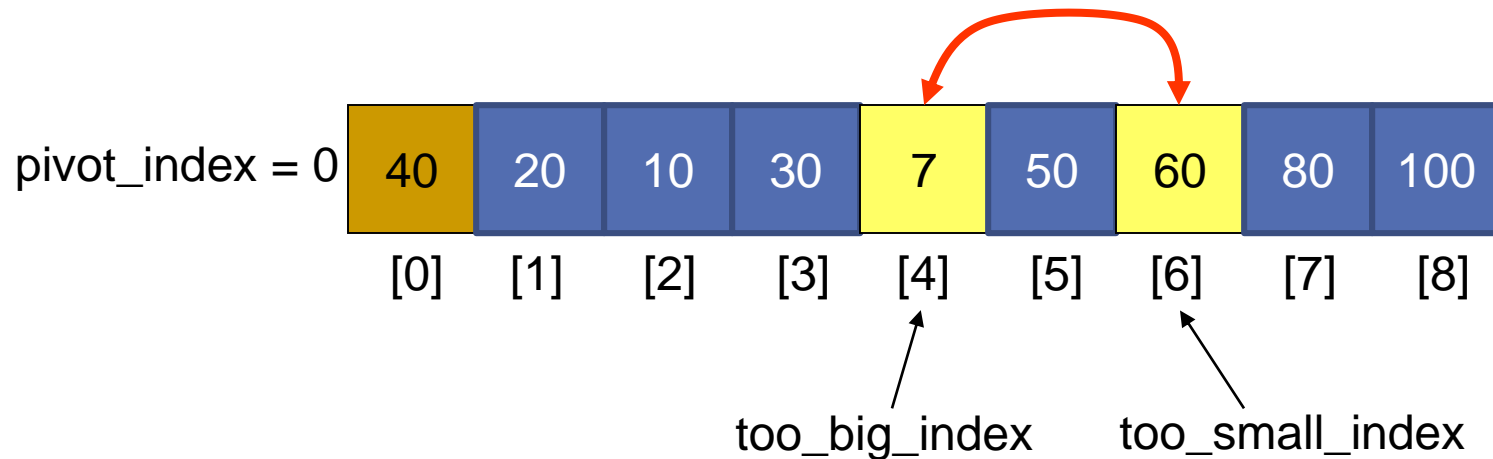
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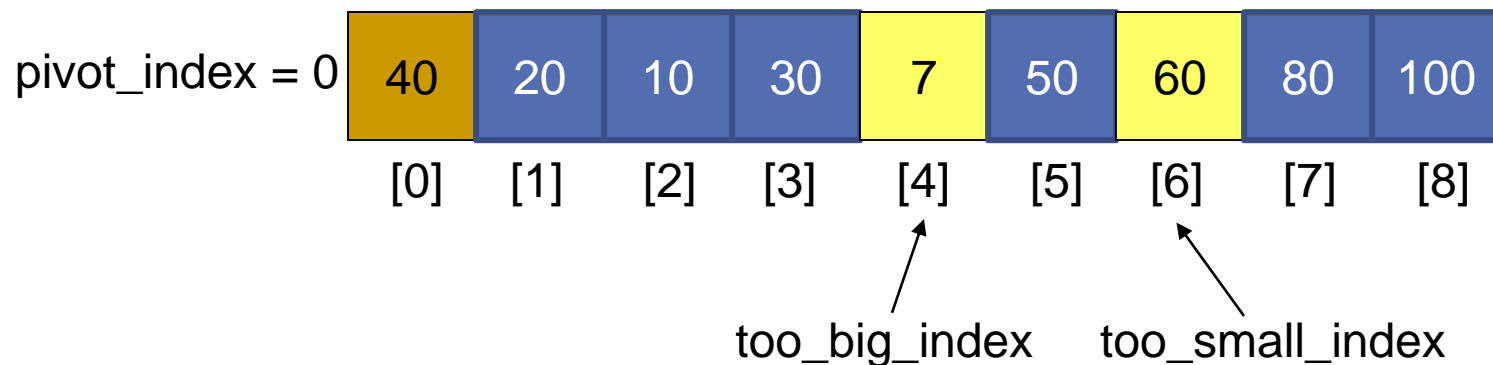
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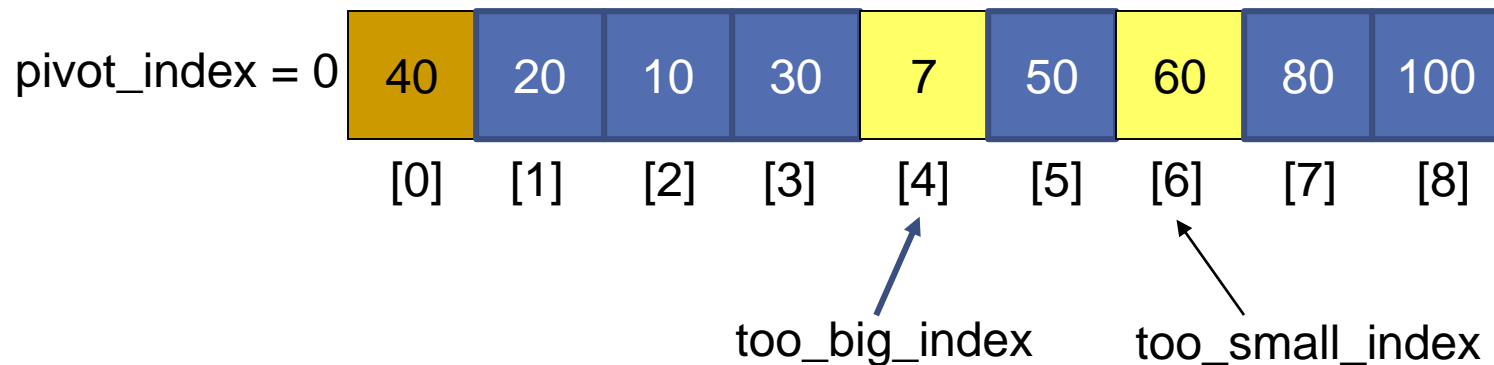
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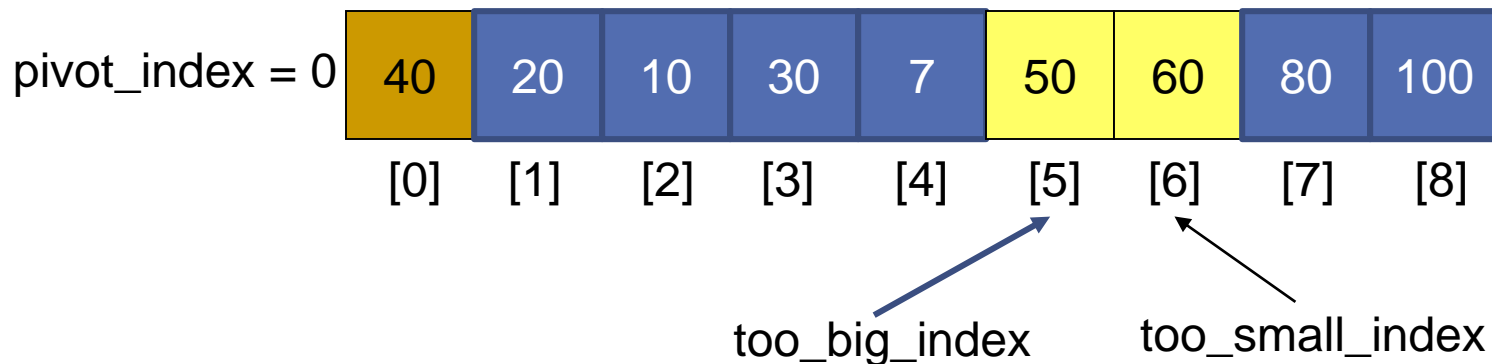
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- 4. While  $\text{too\_small\_index} > \text{too\_big\_index}$ , go to 1.



# PARTITIONING EXAMPLE

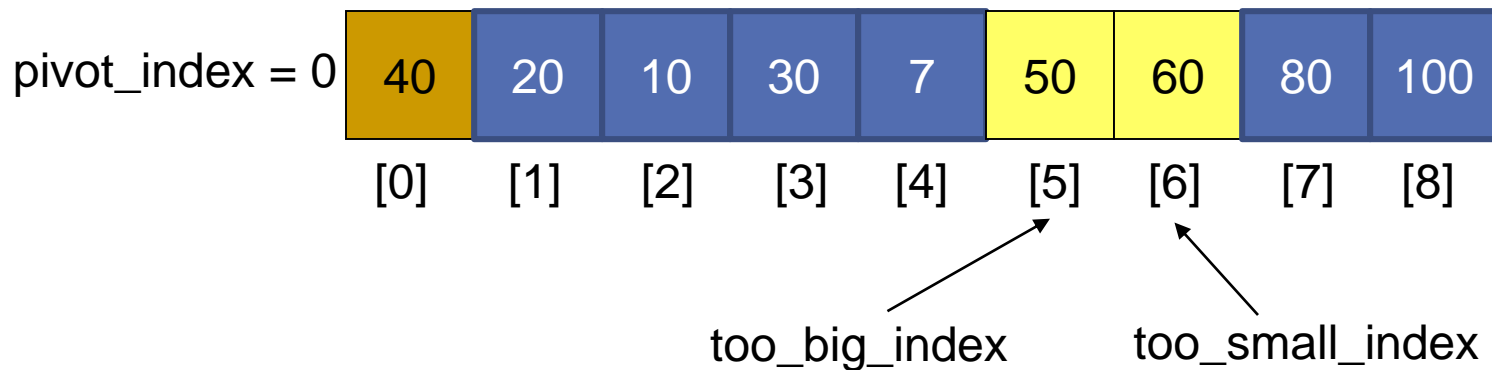
- 1. While  $\text{data}[\text{too\_big\_index}] \leq \text{data}[\text{pivot}]$   
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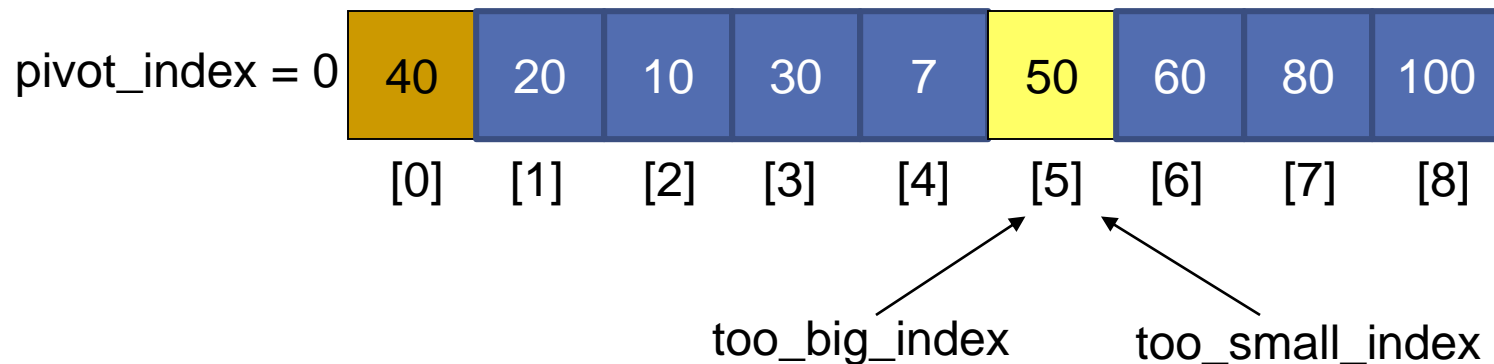
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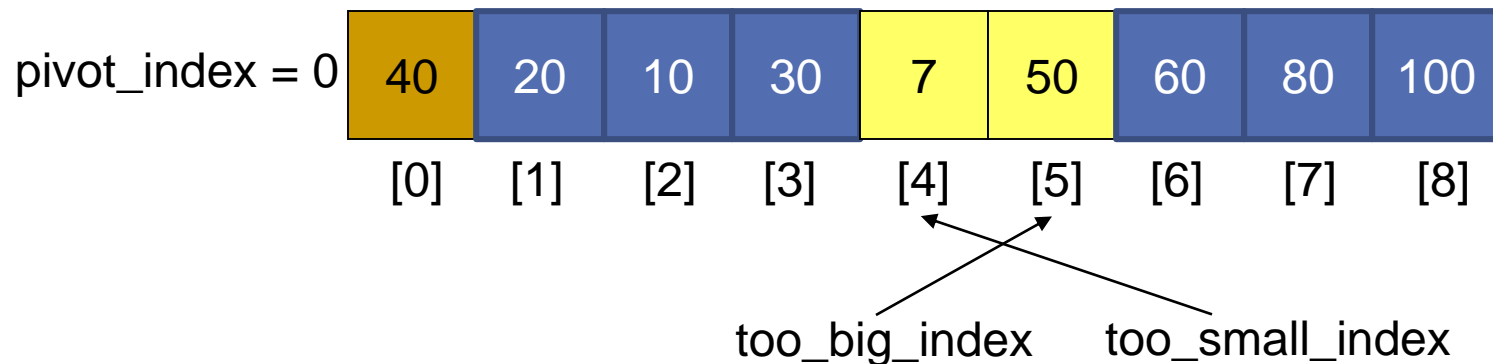
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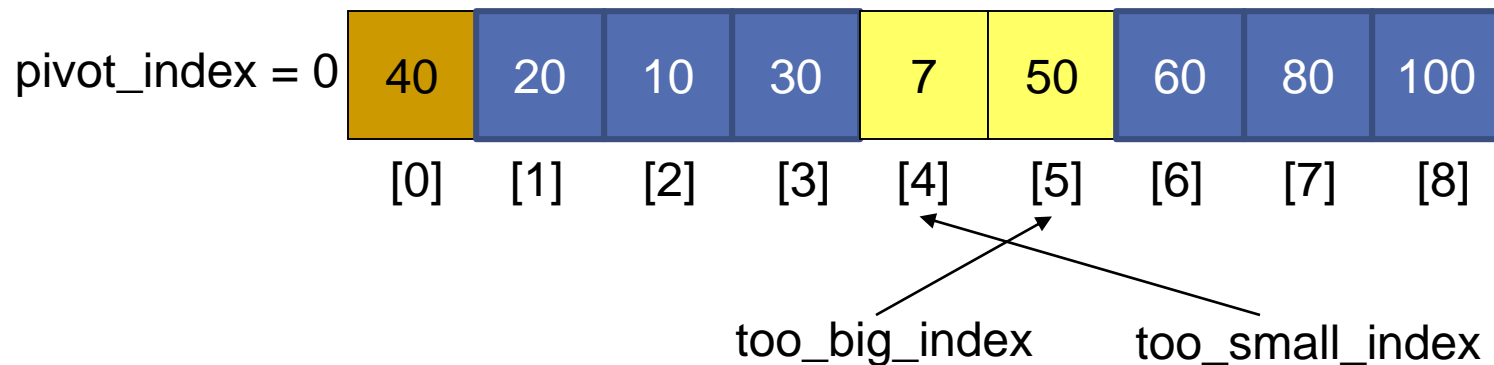
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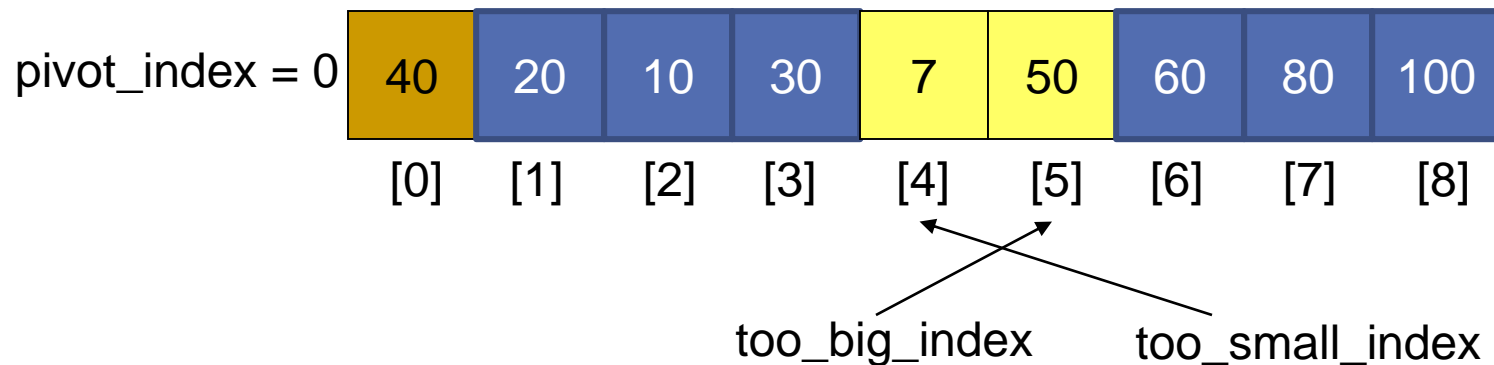
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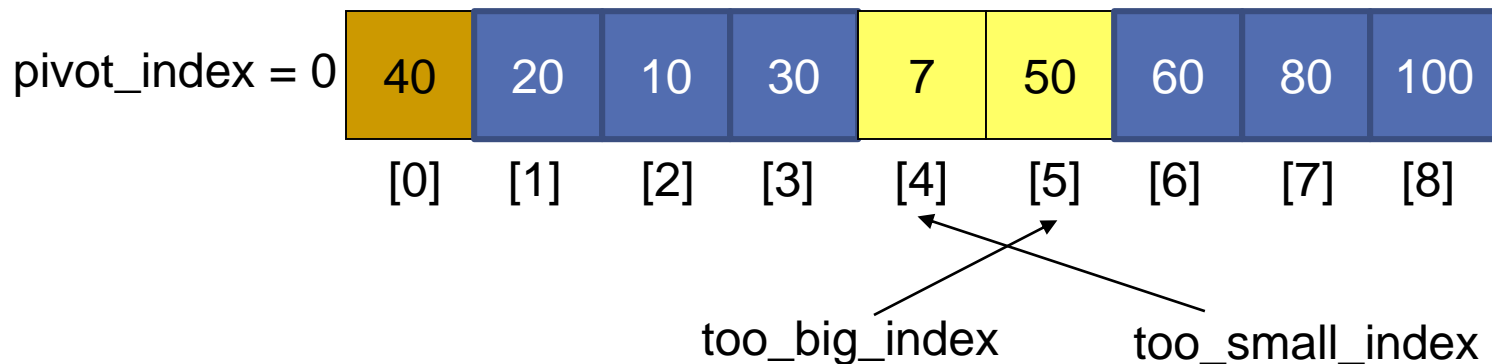
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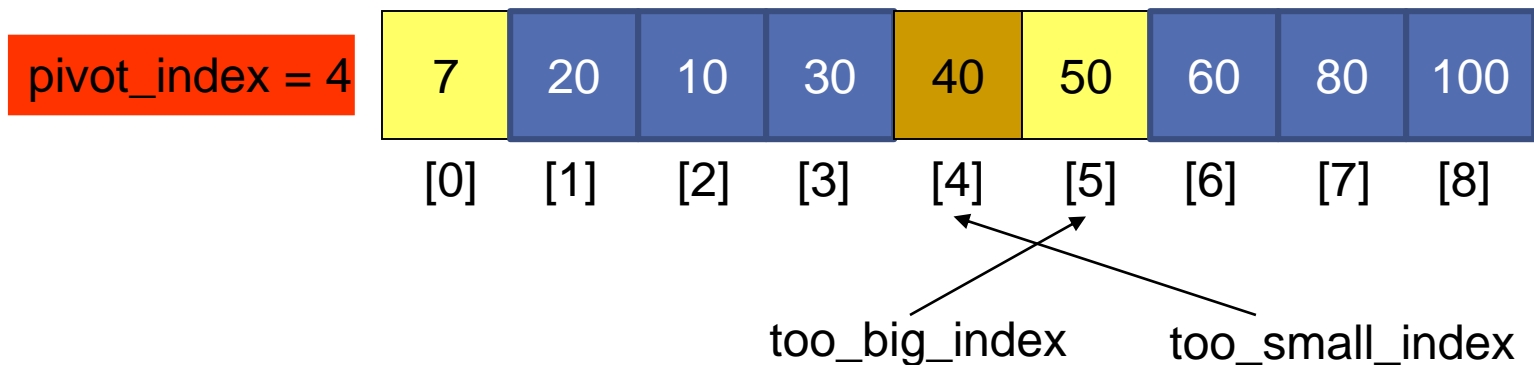
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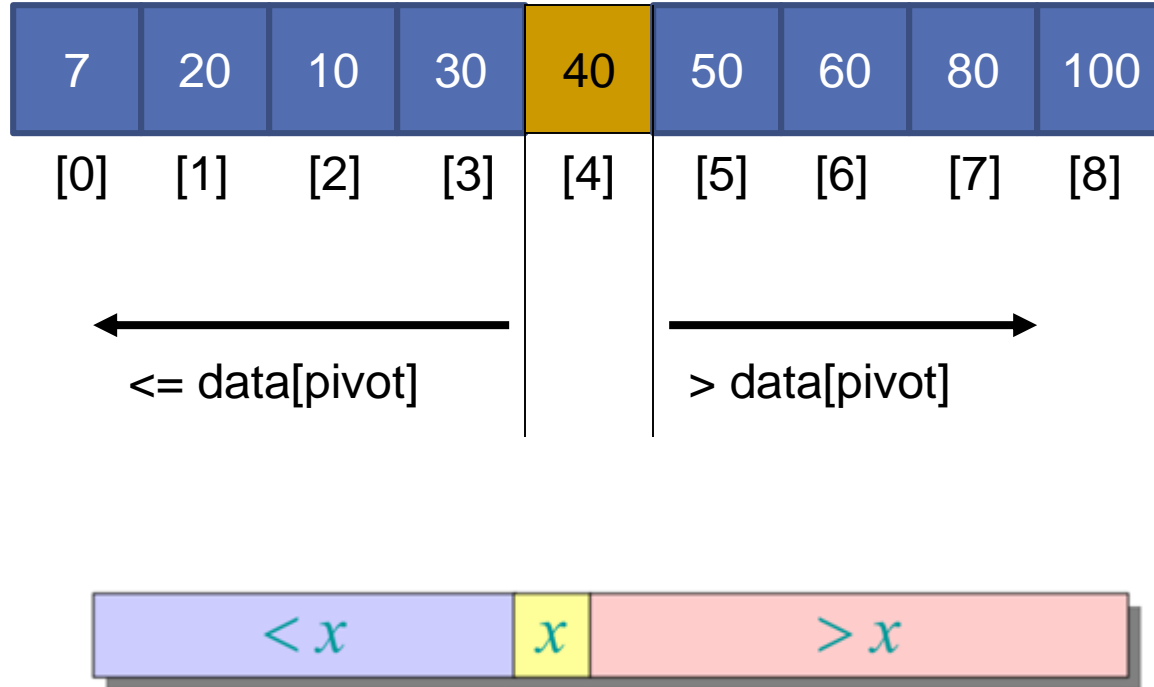


# PARTITIONING EXAMPLE

1. While  $\text{data}[\text{too\_big\_index}] \leq \text{data}[\text{pivot}]$   
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4. While  $\text{too\_small\_index} > \text{too\_big\_index}$ , go to 1.
- 5. Swap  $\text{data}[\text{too\_small\_index}]$  and  $\text{data}[\text{pivot\_index}]$



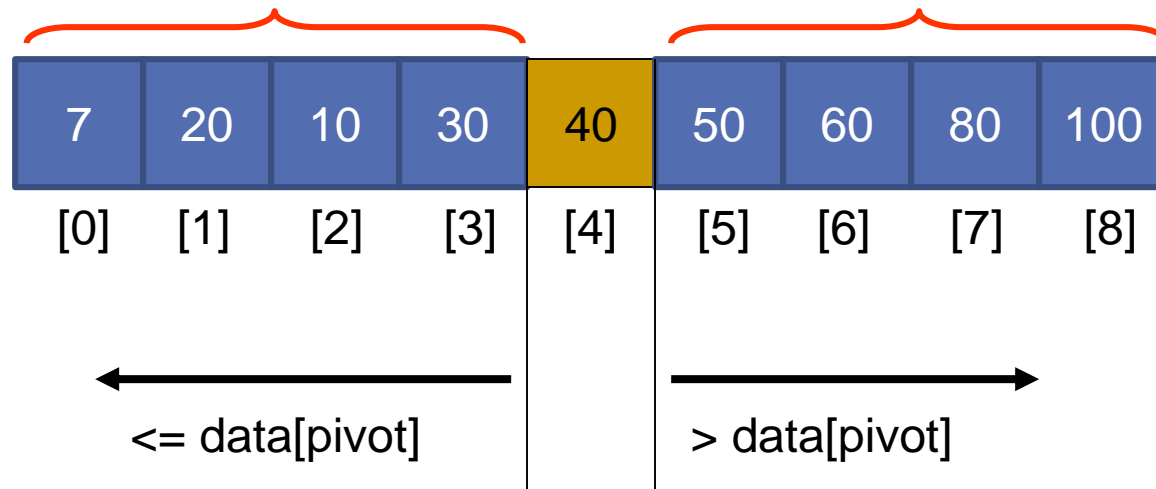
# PARTITION RESULT



**RUNTIME:  $O(n)$**



# RECURSION: QUICKSORT SUB-ARRAYS



# ANOTHER EXAMPLE OF PARTITIONING

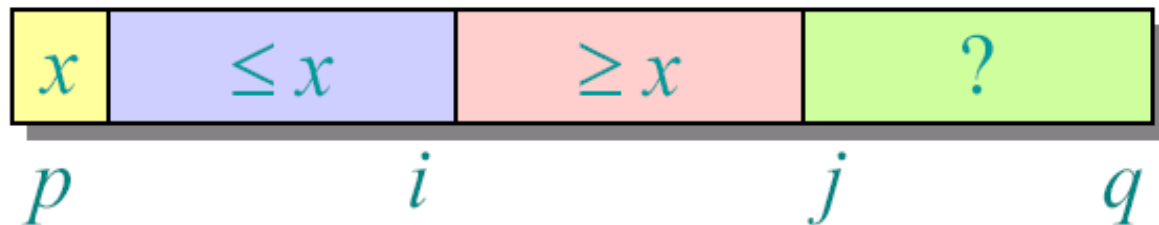
- choose pivot: 4 3 6 9 2 4 3 1 2 1 8 9 3 5 6
- search: 4 3 6 9 2 4 3 1 2 1 8 9 3 5 6
- swap: 4 3 3 9 2 4 3 1 2 1 8 9 6 5 6
- search: 4 3 3 9 2 4 3 1 2 1 8 9 6 5 6
- swap: 4 3 3 1 2 4 3 1 2 9 8 9 6 5 6
- search: 4 3 3 1 2 4 3 1 2 9 8 9 6 5 6
- swap: 4 3 3 1 2 2 3 1 4 9 8 9 6 5 6
- search: 4 3 3 1 2 2 3 1 4 9 8 9 6 5 6
- swap with pivot: 1 3 3 1 2 2 3 4 4 9 8 9 6 5 6

# ANOTHER PARTITIONING SUBROUTINE

```
PARTITION( $A, p, q$ )  $\triangleright A[p \dots q]$   
   $x \leftarrow A[p]$   $\triangleright$  pivot =  $A[p]$   
   $i \leftarrow p$   
  for  $j \leftarrow p + 1$  to  $q$   
    do if  $A[j] \leq x$   
      then  $i \leftarrow i + 1$   
           exchange  $A[i] \leftrightarrow A[j]$   
  exchange  $A[p] \leftrightarrow A[i]$   
  return  $i$ 
```

Running time  
=  $O(n)$  for  $n$   
elements.

***Invariant:***



# EXAMPLE OF PARTITIONING

6	10	13	5	8	3	2	11
i	j						

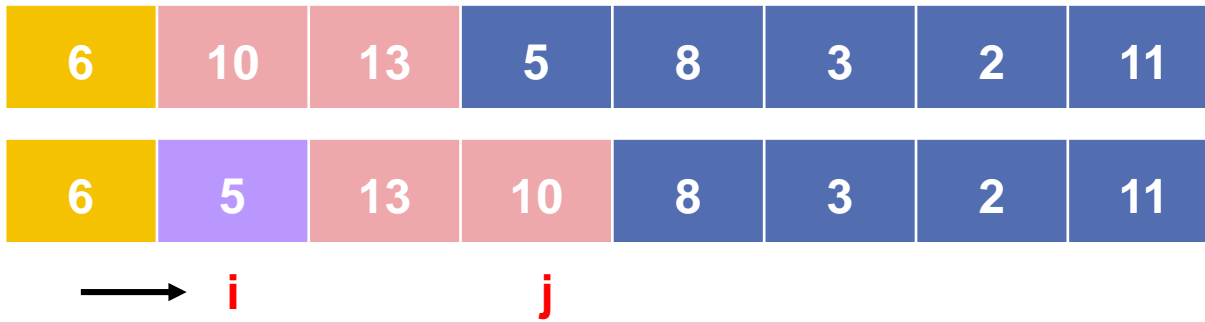
# EXAMPLE OF PARTITIONING



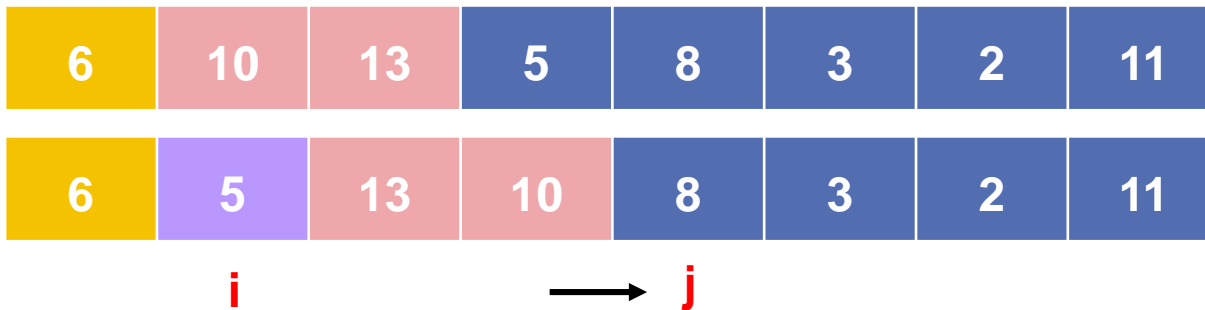
# EXAMPLE OF PARTITIONING



# EXAMPLE OF PARTITIONING

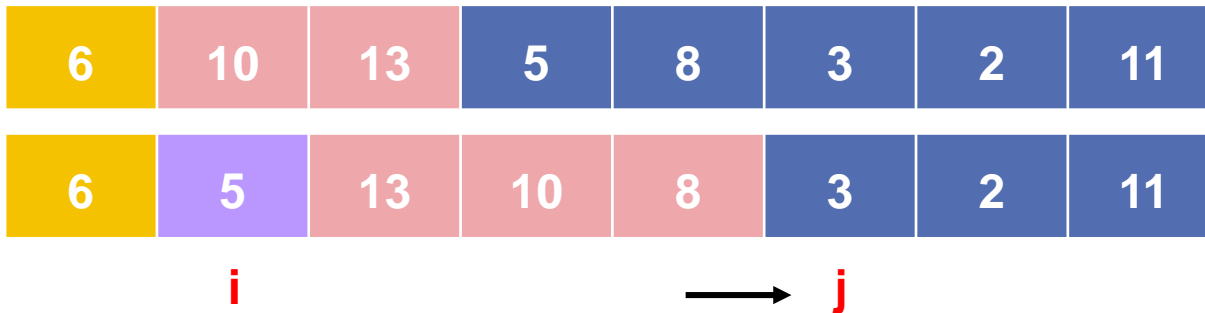


# EXAMPLE OF PARTITIONING

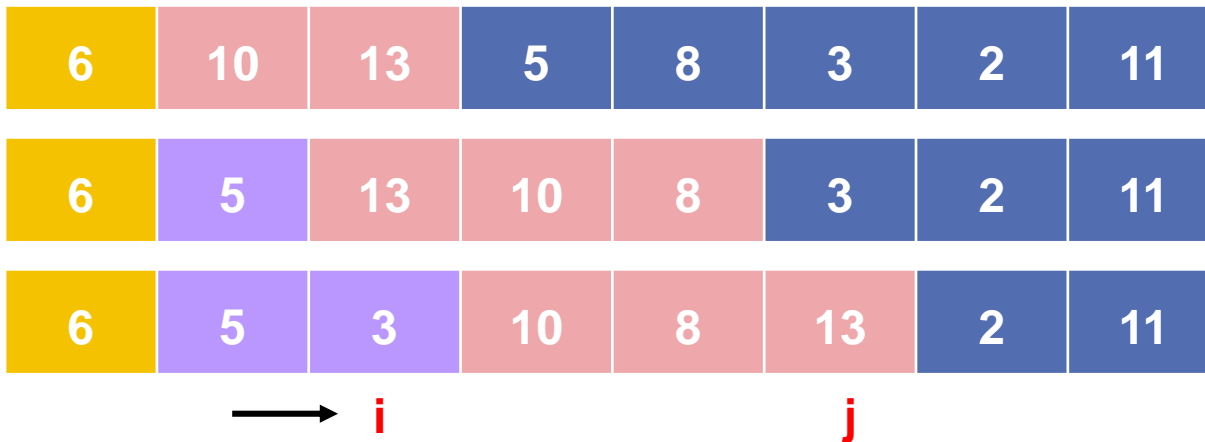




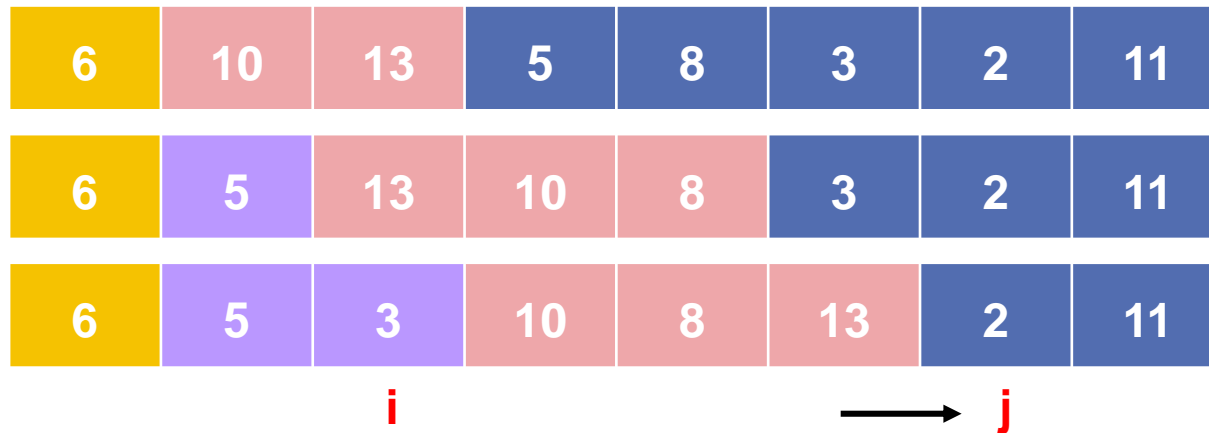
# EXAMPLE OF PARTITIONING



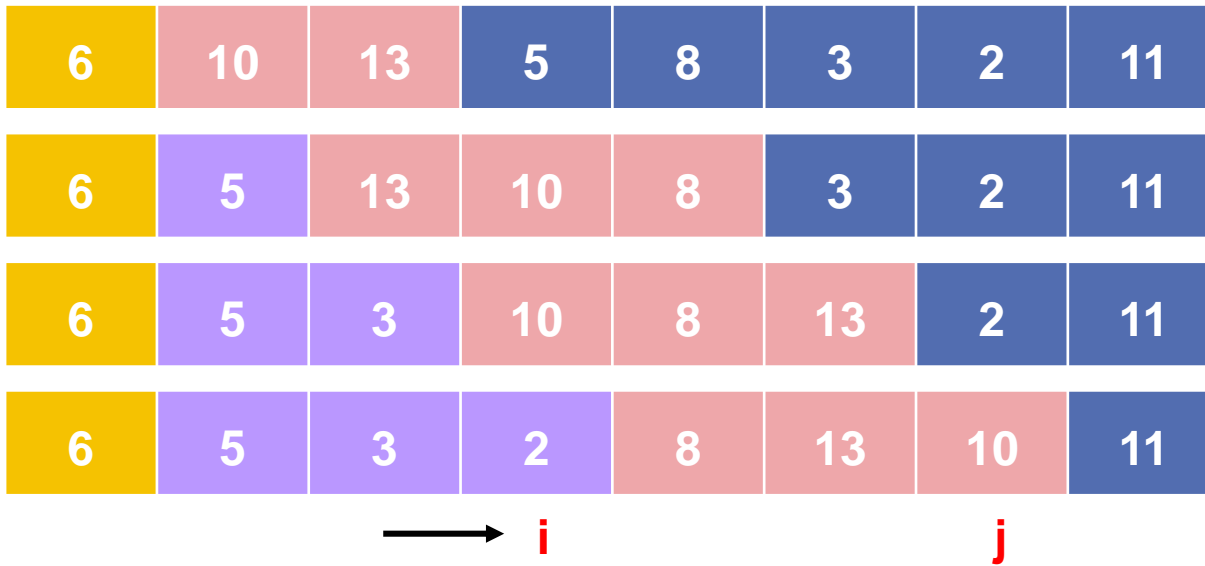
# EXAMPLE OF PARTITIONING



# EXAMPLE OF PARTITIONING



# EXAMPLE OF PARTITIONING

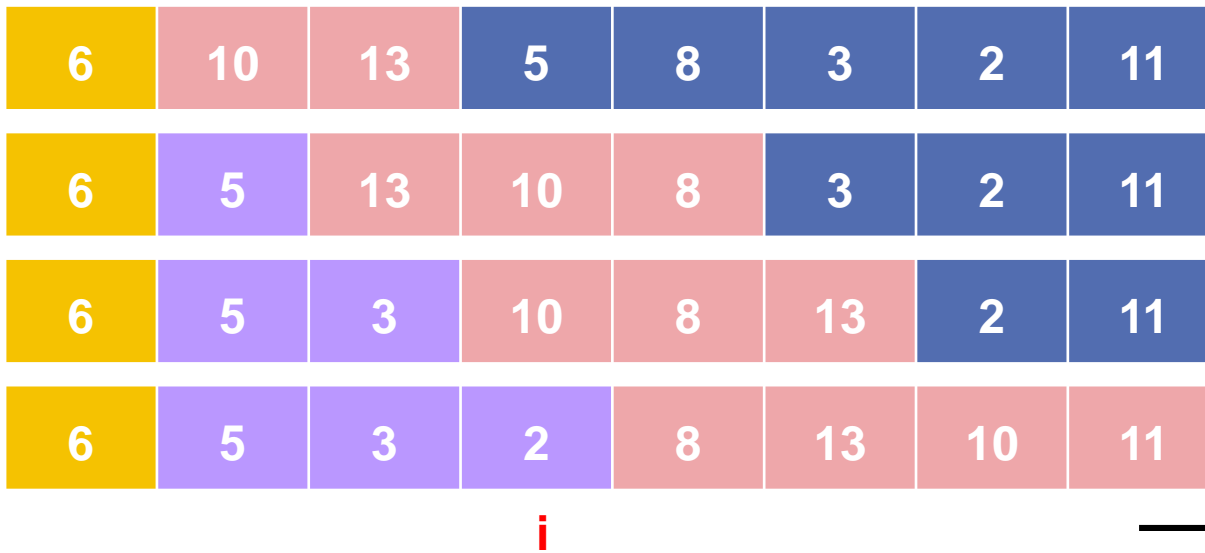


# EXAMPLE OF PARTITIONING

6	10	13	5	8	3	2	11
6	5	13	10	8	3	2	11
6	5	3	10	8	13	2	11
6	5	3	2	8	13	10	11

**i** → **j**

# EXAMPLE OF PARTITIONING



# EXAMPLE OF PARTITIONING

6	10	13	5	8	3	2	11
6	5	13	10	8	3	2	11
6	5	3	10	8	13	2	11
6	5	3	2	8	13	10	11
2	5	3	6	8	13	10	11

i

# LOMUTO PARTITIONING

- Select the **last element**  $A[r]$  in the subarray  $A[p..r]$  as the **pivot**.
- The array is partitioned into four (possibly empty) regions.
  1.  $A[p..i]$  — All entries in this region are  $< \text{pivot}$ .
  2.  $A[i+1..j-1]$  — All entries in this region are  $> \text{pivot}$ .
  3.  $A[r] = \text{pivot}$ .
  4.  $A[j..r-1]$  — Not known how they compare to  $\text{pivot}$ .
- These hold before each iteration of the *for* loop, and **constitute a loop invariant**.





# CORRECTNESS OF PARTITION

- Use loop invariant.

- Initialization:

- Before first iteration
  - $A[p..i]$  and  $A[i+1..j-1]$  are empty
  - $r$  is the index of the *pivot*

- Maintenance:

- Use inductive hypothesis

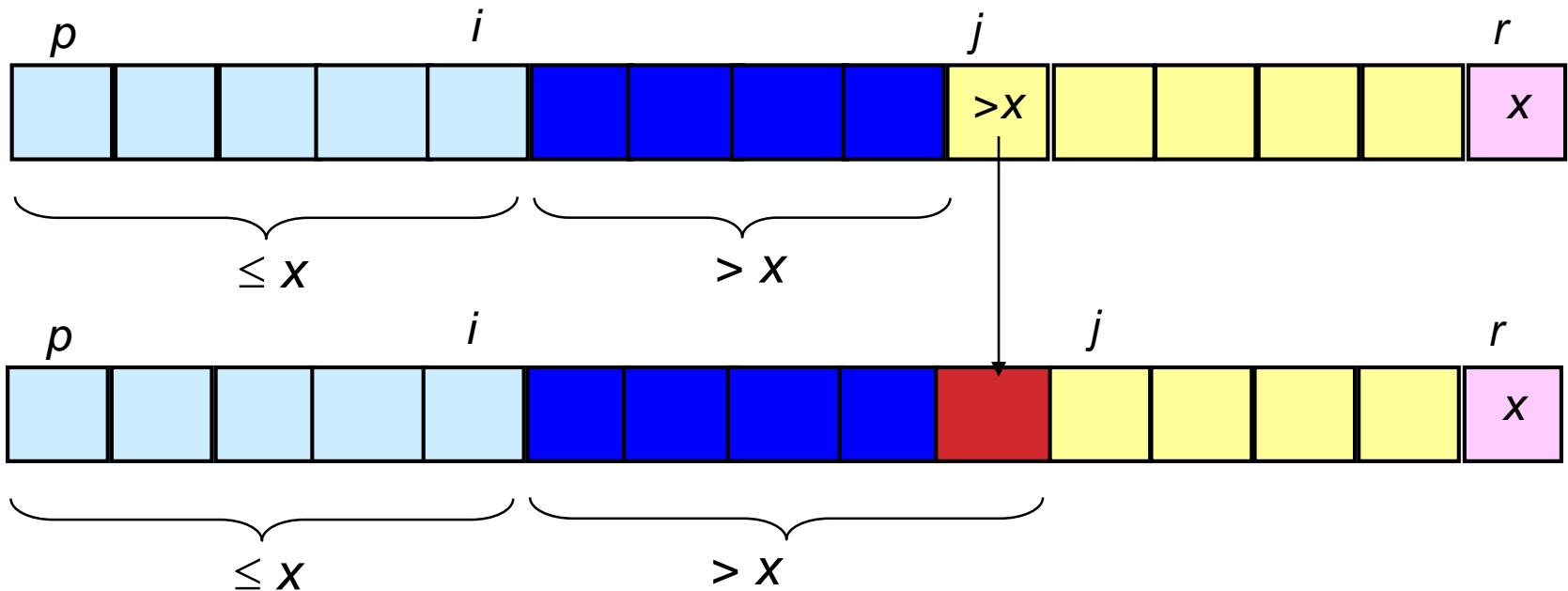
1.  $A[p..i] < \textit{pivot}$
2.  $A[i+1..j-1] > \textit{pivot}$
3.  $A[r] = \textit{pivot}$

Partition(A, p, r)

```
x := A[r], i := p - 1;  
for j := p to r - 1 do  
    if A[j] ≤ x then  
        i := i + 1;  
        A[i] ↔ A[j];  
A[i + 1] ↔ A[r];  
return i + 1;
```

# CORRECTNESS OF PARTITION

Case 1:  $A[j] > x$  Increment  $j$  only.



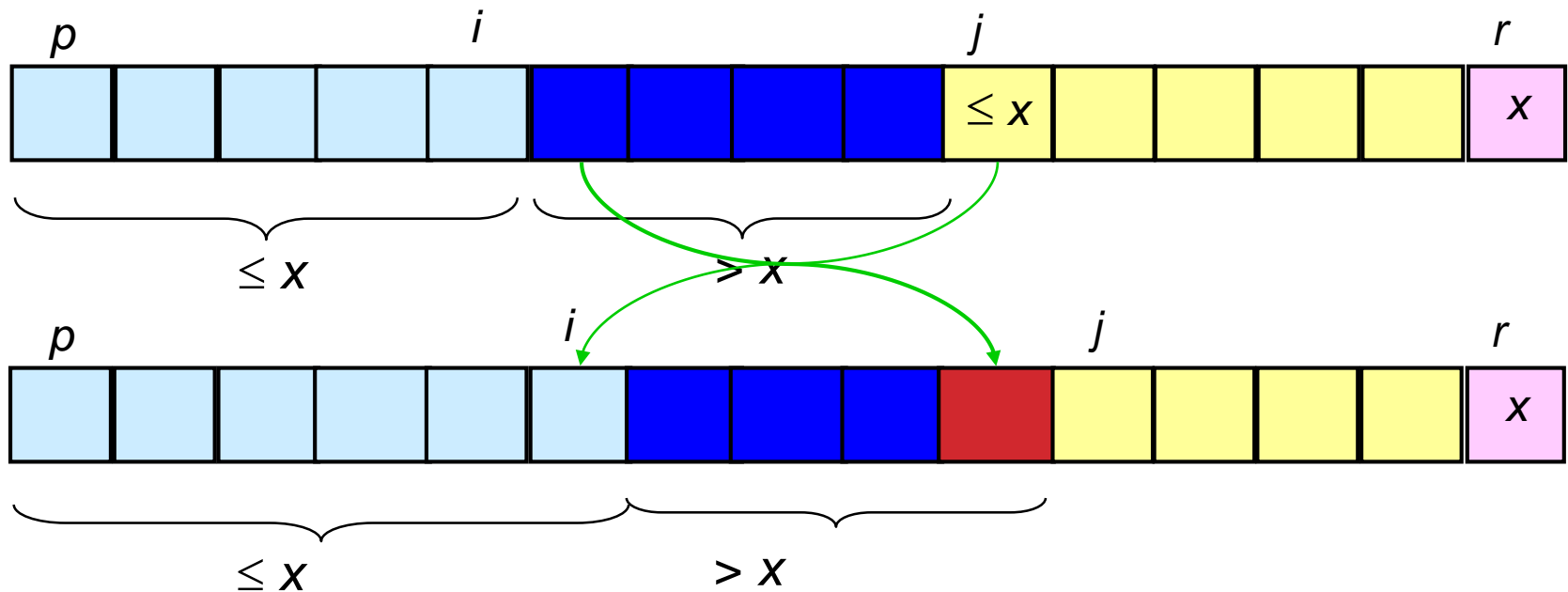
1.  $A[p..i] < \text{pivot}$
2.  $A[i+1..j-1] > \text{pivot}$
3.  $A[r] = \text{pivot}$

# CORRECTNESS OF PARTITION

## • Case 2: $A[j] \leq x$

- Increment  $i$
- Swap  $A[i]$  and  $A[j]$
- Increment  $j$

1.  $A[p..i] < \text{pivot}$
2.  $A[i+1..j-1] > \text{pivot}$
3.  $A[r] = \text{pivot}$



# CORRECTNESS OF PARTITION

- Termination:

- When the loop terminates,  $j = r$ , so all elements in  $A$  are partitioned into one of the three cases:

- $A[p..i] \leq \text{pivot}$
- $A[i+1..j-1] > \text{pivot}$
- $A[r] = \text{pivot}$

- At last, swap  $A[i+1]$  and  $A[r]$ .

- Before swap  $A[i+1] > \text{pivot}$
- After swap  $\text{pivot}$  moves from the end of the array to **between the two subarrays**.
- Thus, procedure *partition* correctly performs the divide step.



# ANALYZING QUICKSORT

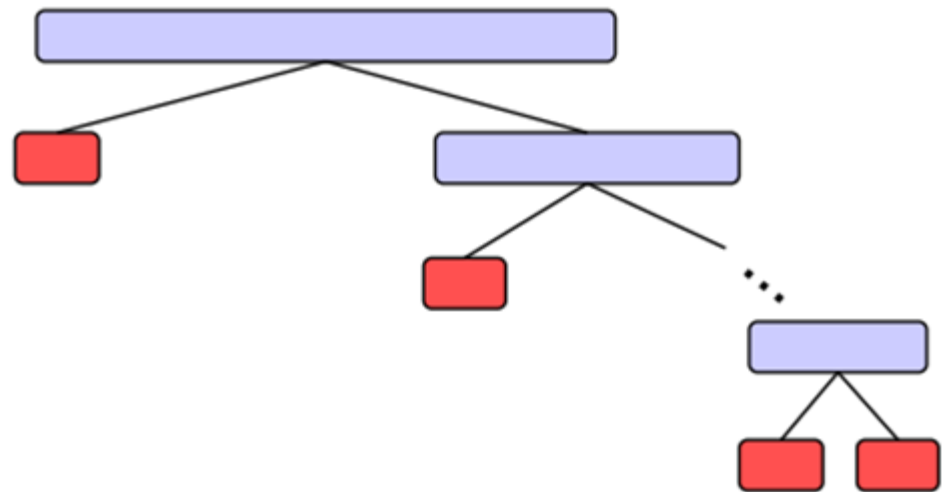
- *What will be the worst case for the algorithm?*
- *What will be the best case for the algorithm?*
- *Which one is more likely?*
- *Will any particular input cause the worst case?*

# ANALYZING QUICKSORT

- *What will be the worst case for the algorithm?*
  - Partition is always unbalanced
- *What will be the best case for the algorithm?*
  - Partition is perfectly balanced
- *Which one is more likely?*
  - Balanced, except...
- *Will any particular input cause the worst case?*
  - Yes: Already-sorted or reverse-sorted input

# WORST CASE

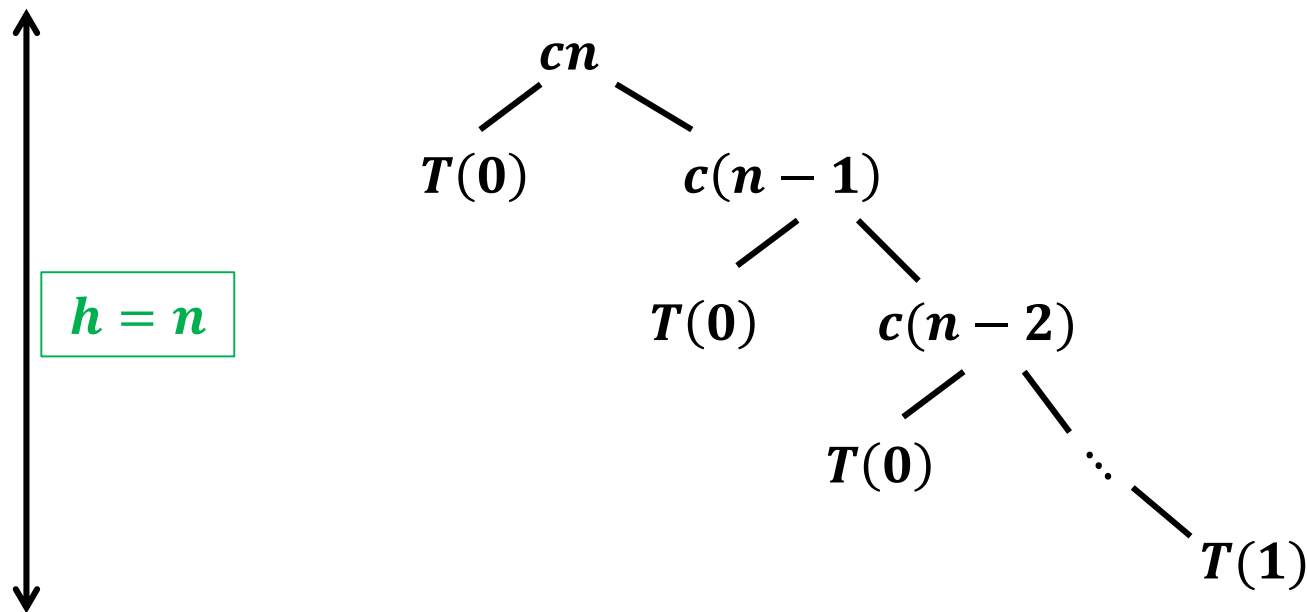
Depth	Partition Time
0	$n$
1	$n-1$
...	...
$n-1$	1



- Total:  $n + (n + 1) + \dots + 2 + 1$
- Thus, the worst-case running time of quicksort is  $O(n^2)$

# WORST-CASE RECURSION TREE

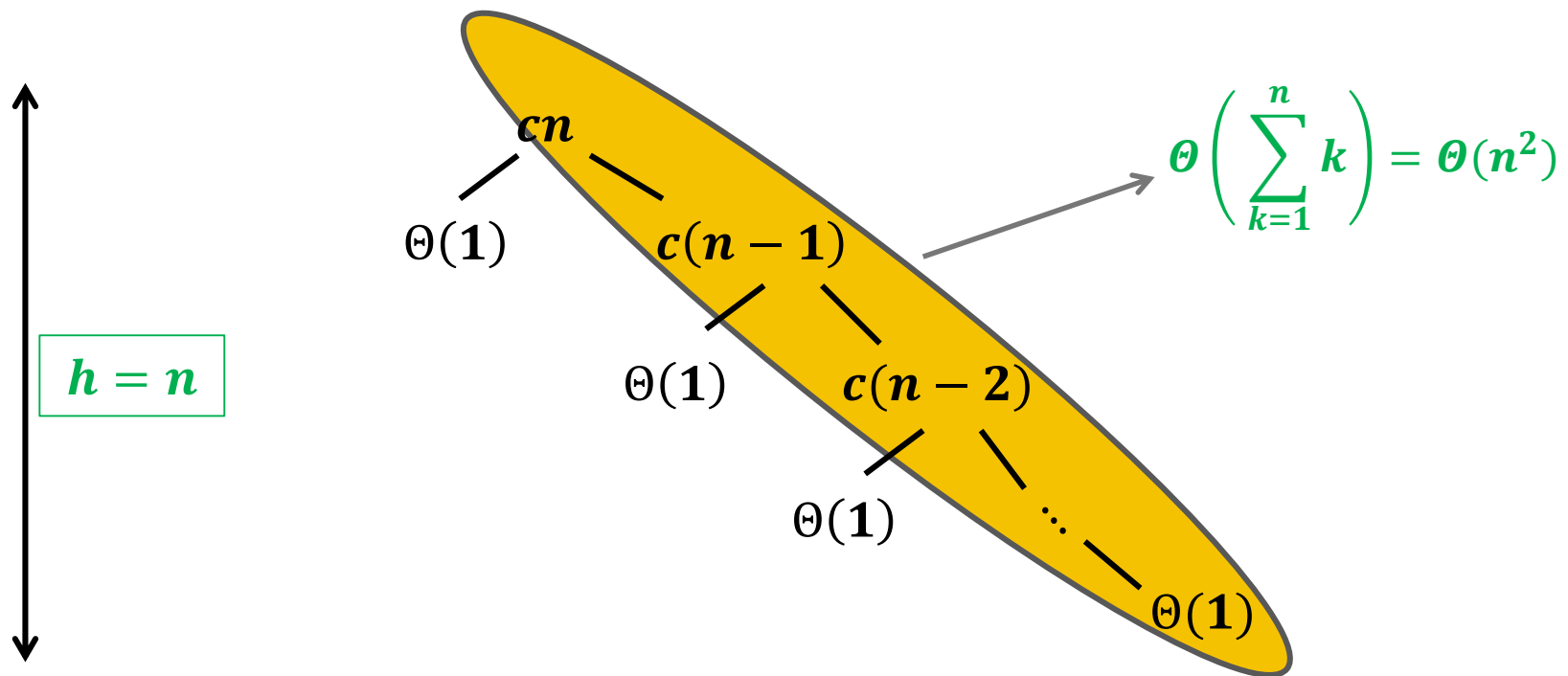
$$T(n) = T(0) + T(n - 1) + cn$$





# WORST-CASE RECURSION TREE

$$T(n) = T(1) + T(n-1) + cn$$



$$T(n) = \Theta(n) + \Theta(n^2) = \Theta(n^2)$$

# BEST-CASE

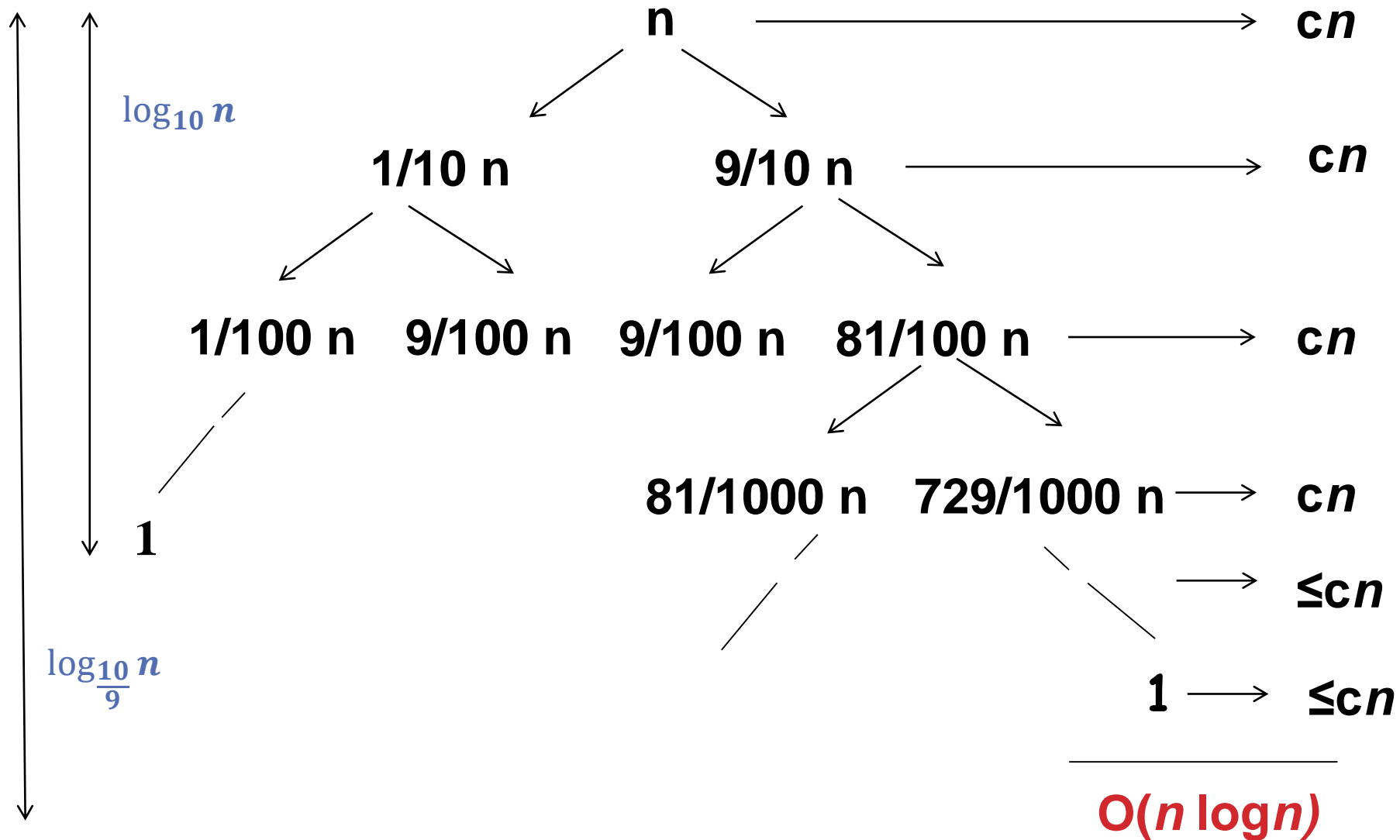
- Partition into two halves
  - $T(n) = 2 T(n/2) + cn$
  - $T(n) = \Theta(n \log n)$

# BEST-CASE

- Partition into two halves
  - $T(n) = 2 T(n/2) + cn$
  - $T(n) = \Theta(n \log n)$
- What if the split is always  $\frac{1}{10} : \frac{9}{10}$  ?
  - $T(n) = ?$

# BEST-CASE

- Partition into two halves
  - $T(n) = 2 T(n/2) + cn$
  - $T(n) = \Theta(n \log n)$
- What if the split is always  $\frac{1}{10} : \frac{9}{10}$  ?
  - $T(n) = T(\frac{1}{10}n) + T(\frac{9}{10}n) + cn$

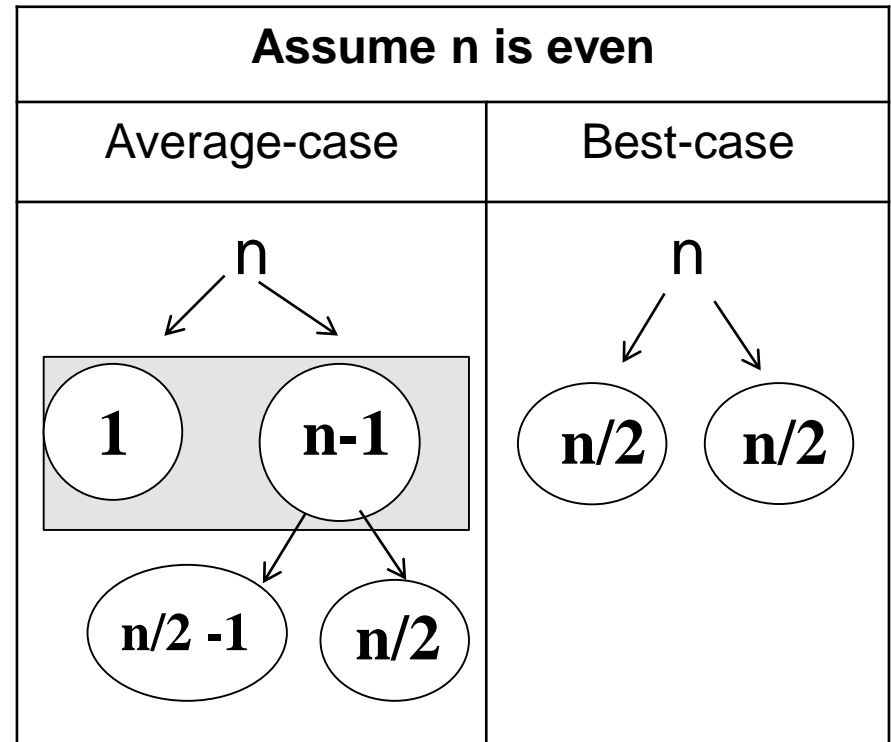


# INTUTION FOR AVERAGE CASE

- **Assumption:** All permutations equally likely (realistic??)
- **Unlikely:** Splits always the same way at every level
- **Expectation:** Some splits will be reasonably balanced.  
Some splits will be fairly unbalanced.
- **Average case:** A mix of good and bad splits.  
Good and bad splits distributed randomly through the tree.  
Good and bad splits occur in the alternate levels of the tree.
- **Good split:** Best-case split ( $n/2$  and  $n/2$ )
- **Bad split:** Worst-case split ( $1$  and  $n-1$ )

# INTUTITION FOR AVERAGE CASE

- Two successive levels of average-case produce a half-and-half split.
- Same result as a single level of the best case.
- Thus, after spending  $\Theta(n) + \Theta(n-1) = \Theta(n)$  partitioning cost, we reach the best case.
- Total tree height doubles ( $2 \log n$ ).
- Runtime still  $\Theta(n \log n)$



# CONCLUSIONS

- **Average-case analysis**

- Hard in general
- Need to make assumptions on the input distribution or workload
  - May not represent the real scenario
- Somewhere between best- and worst- cases
  - May be **as bad as the worst case** (e.g., insertion sort)
  - Or **as good as the best case** (e.g., quicksort)

- **Next: What if we can **enforce** input distribution?**