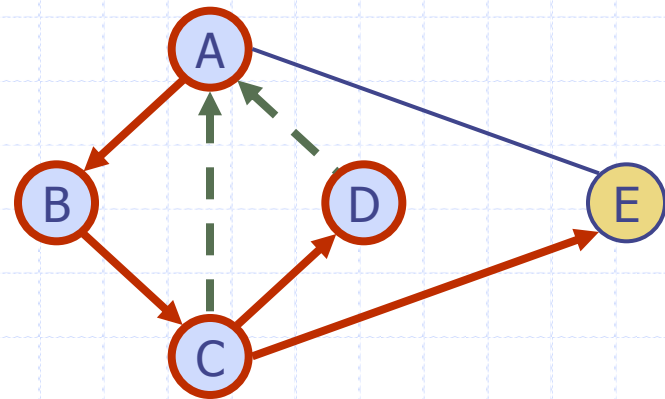
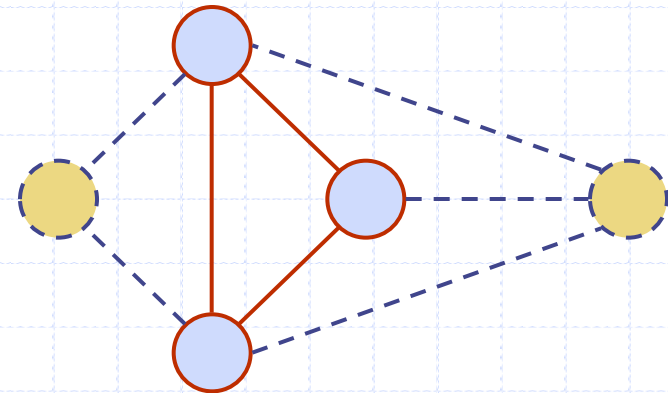


Depth-First Search

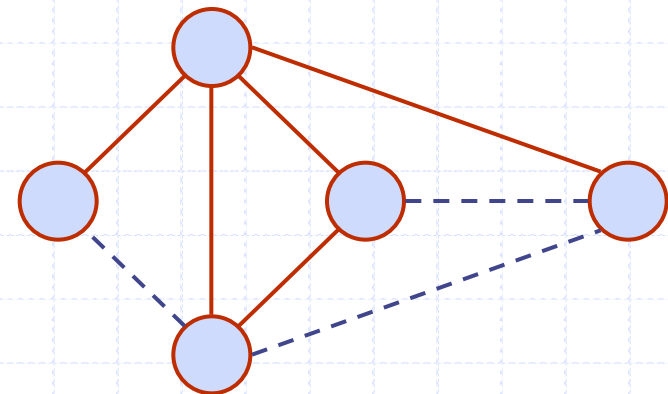


Subgraphs

- A **subgraph** S of a graph G is a graph such that
 - The vertices of S are a subset of the vertices of G
 - The edges of S are a subset of the edges of G
- A **spanning subgraph** of G is a subgraph that contains all the vertices of G



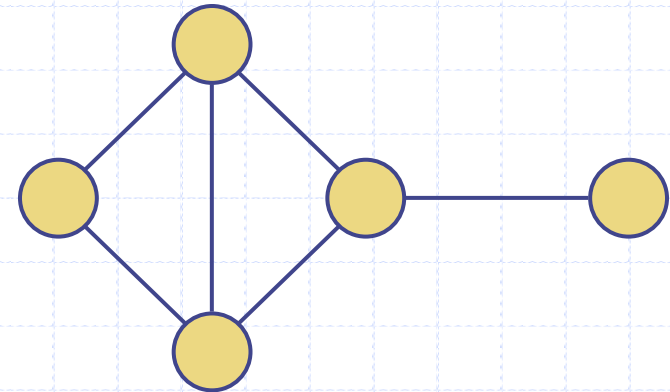
Subgraph



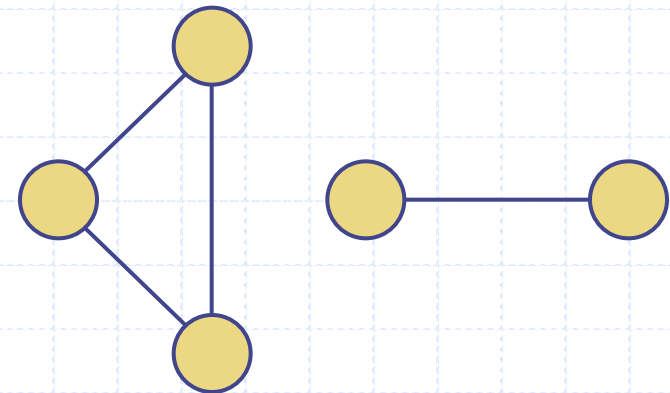
Spanning subgraph

Connectivity

- A graph is **connected** if there is a path between every pair of vertices
- A **connected component** of a graph G is a maximal connected subgraph of G



Connected graph



Non connected graph with two connected components

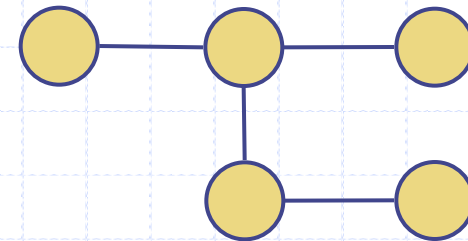
Trees and Forests

- A (free) **tree** is an undirected graph T such that

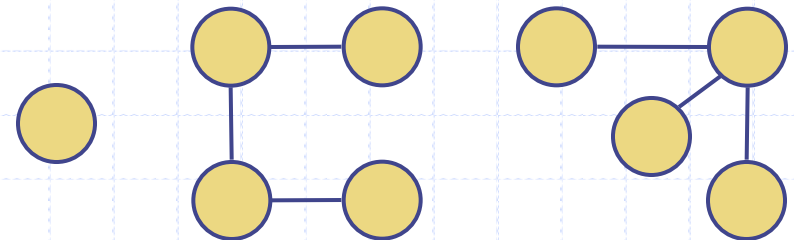
- T is connected
- T has no cycles

This definition of tree is different from the one of a rooted tree

- A **forest** is an undirected graph without cycles
- The connected components of a forest are trees



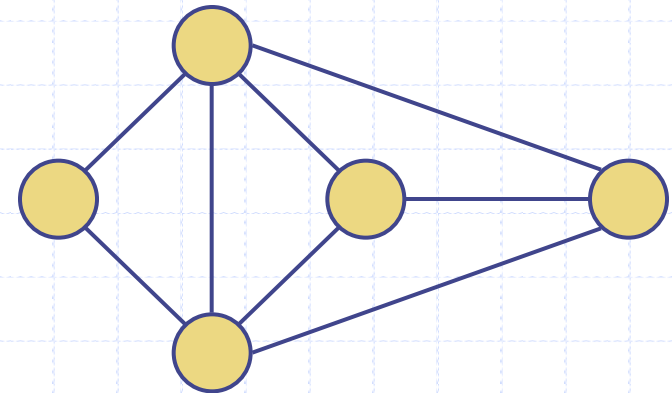
Tree



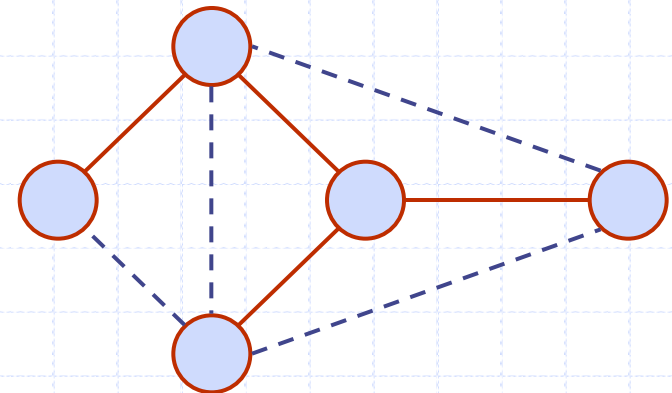
Forest

Spanning Trees and Forests

- ❑ A **spanning tree** of a connected graph is a spanning subgraph that is a tree
- ❑ A spanning tree is not unique unless the graph is a tree
- ❑ Spanning trees have applications to the design of communication networks
- ❑ A **spanning forest** of a graph is a spanning subgraph that is a forest



Graph



Spanning tree

Depth-First Search

- Depth-first search (**DFS**) is a general technique for traversing a graph
- A DFS traversal of a graph G
 - Visits all the vertices and edges of G
 - Determines whether G is connected
 - Computes the connected components of G
 - Computes a spanning forest of G
- DFS on a graph with n vertices and m edges takes $O(n + m)$ time
- DFS can be further extended to solve other graph problems
 - Find and report a path between two given vertices
 - Find a cycle in the graph
- Depth-first search is to graphs what Euler tour is to binary trees

DFS Algorithm

- The algorithm uses a mechanism for setting and getting “labels” of vertices and edges

Algorithm *DFS*(*G*)

Input graph *G*

Output labeling of the edges of *G*
as discovery edges and
back edges

```
for all  $u \in G.vertices()$ 
     $setLabel(u, UNEXPLORED)$ 
for all  $e \in G.edges()$ 
     $setLabel(e, UNEXPLORED)$ 
for all  $v \in G.vertices()$ 
    if  $getLabel(v) = UNEXPLORED$ 
         $DFS(G, v)$ 
```

Algorithm *DFS*(*G*, *v*)

Input graph *G* and a start vertex *v* of *G*
Output labeling of the edges of *G*
in the connected component of *v*
as discovery edges and back edges

```
 $setLabel(v, VISITED)$ 
for all  $e \in G.incidentEdges(v)$ 
    if  $getLabel(e) = UNEXPLORED$ 
         $w \leftarrow opposite(v, e)$ 
        if  $getLabel(w) = UNEXPLORED$ 
             $setLabel(e, DISCOVERY)$ 
             $DFS(G, w)$ 
        else
             $setLabel(e, BACK)$ 
```

Example

A

unexplored vertex

A

visited vertex

—

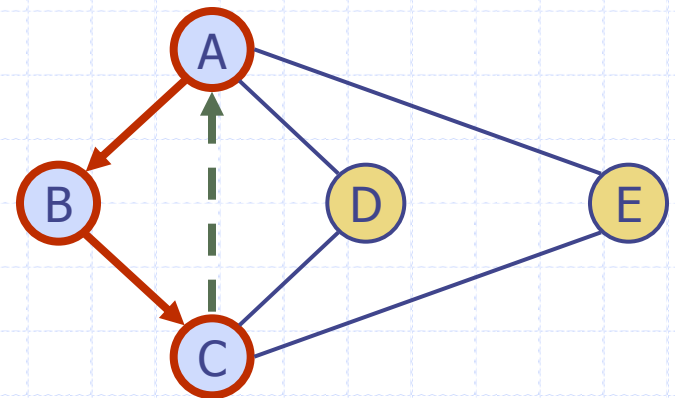
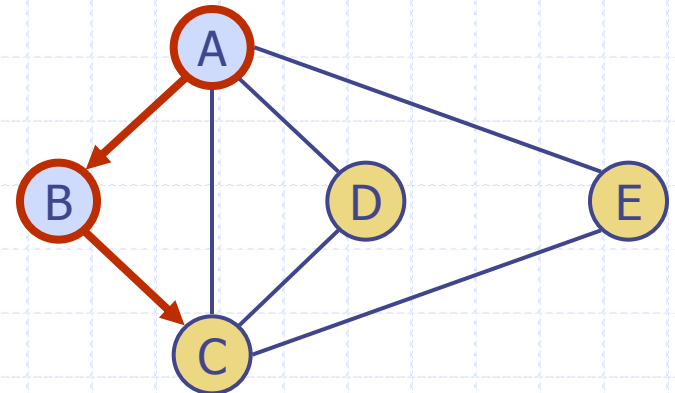
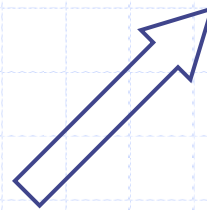
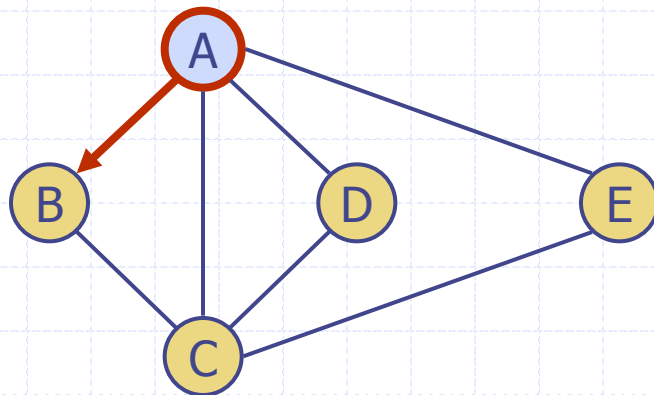
unexplored edge

→

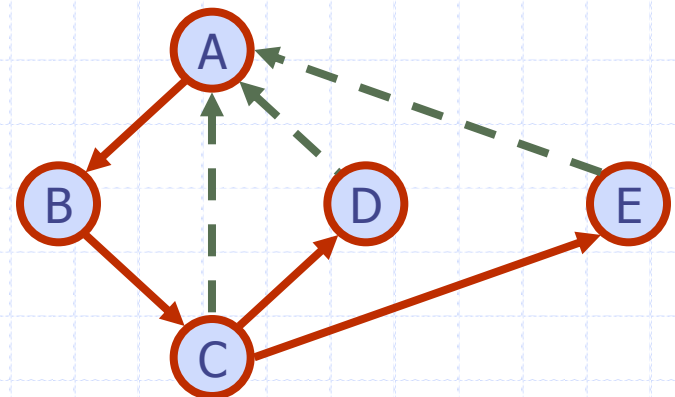
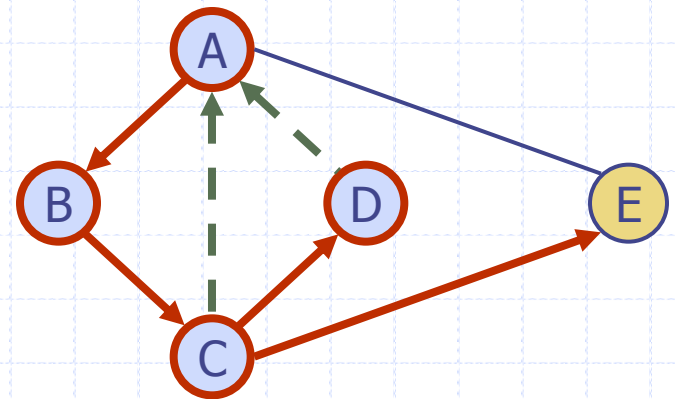
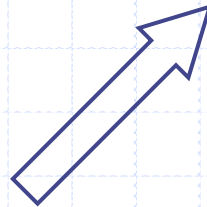
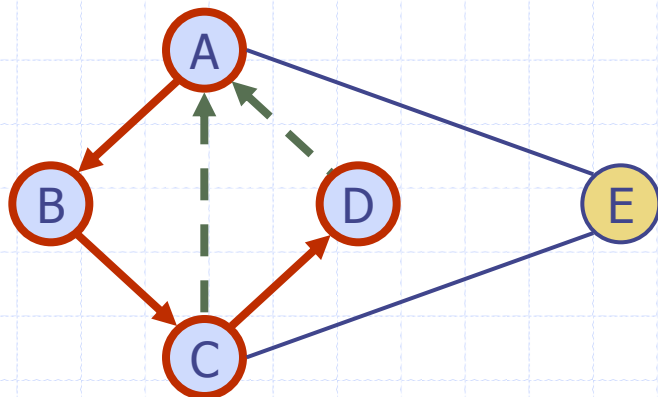
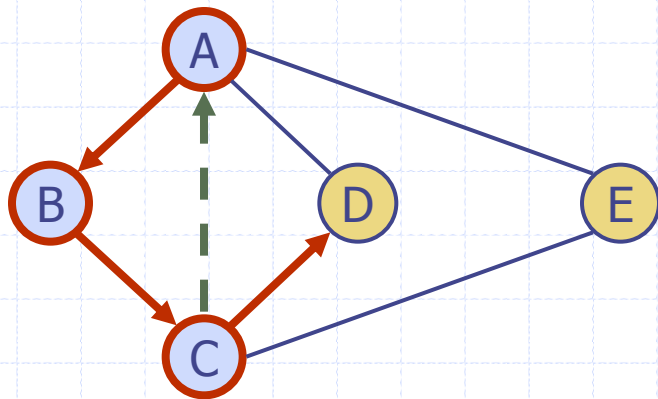
discovery edge

- - - →

back edge



Example (cont.)



-

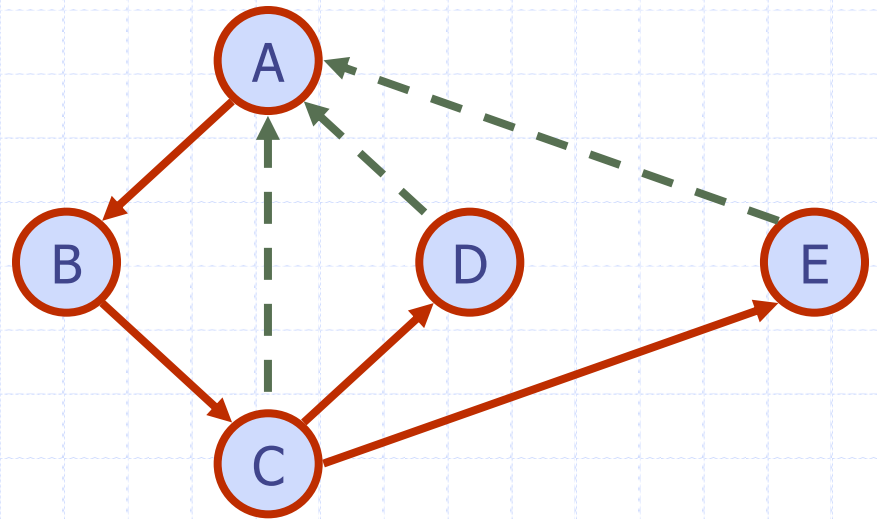
Properties of DFS

Property 1

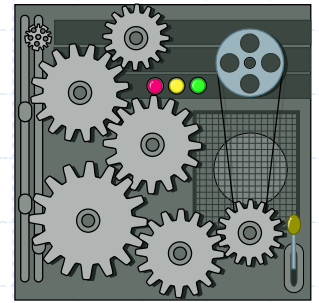
$DFS(G, v)$ visits all the vertices and edges in the connected component of v

Property 2

The discovery edges labeled by $DFS(G, v)$ form a spanning tree of the connected component of v



Analysis of DFS



- ❑ Setting/getting a vertex/edge label takes $O(1)$ time
- ❑ Each vertex is labeled twice
 - once as UNEXPLORED
 - once as **VISITED**
- ❑ Each edge is labeled twice
 - once as UNEXPLORED
 - once as **DISCOVERY** or **BACK**
- ❑ Method incidentEdges is called once for each vertex
- ❑ DFS runs in $O(n + m)$ time provided the graph is represented by the **adjacency list** structure
 - Recall that $\sum_v \deg(v) = 2m$

Path Finding



- We can specialize the DFS algorithm to find a path between two given vertices u and z using the template method pattern
- We call $DFS(G, u)$ with u as the start vertex
- We use a stack S to keep track of the path between the start vertex and the current vertex
- As soon as destination vertex z is encountered, we return the path as the contents of the stack

```
Algorithm pathDFS( $G, v, z$ )  
  setLabel( $v, VISITED$ )  
  S.push( $v$ )  
  if  $v = z$   
    return S.elements()  
  for all  $e \in G.incidentEdges(v)$   
    if getLabel( $e$ ) = UNEXPLORED  
       $w \leftarrow opposite(v, e)$   
      if getLabel( $w$ ) = UNEXPLORED  
        setLabel( $e, DISCOVERY$ )  
        S.push( $e$ )  
        pathDFS( $G, w, z$ )  
        S.pop( $e$ )  
      else  
        setLabel( $e, BACK$ )  
  S.pop( $v$ )
```

Cycle Finding



- We can specialize the DFS algorithm to find a simple cycle using the template method pattern
- We use a stack S to keep track of the path between the start vertex and the current vertex
- As soon as a back edge (v, w) is encountered, we return the cycle as the portion of the stack from the top to vertex w

```
Algorithm cycleDFS( $G, v, z$ )  
  setLabel( $v, VISITED$ )  
  S.push( $v$ )  
  for all  $e \in G.incidentEdges(v)$   
    if getLabel( $e$ ) = UNEXPLORED  
       $w \leftarrow opposite(v, e)$   
      S.push( $e$ )  
      if getLabel( $w$ ) = UNEXPLORED  
        setLabel( $e, DISCOVERY$ )  
        pathDFS( $G, w, z$ )  
        S.pop( $e$ )  
      else  
         $T \leftarrow$  new empty stack  
        repeat  
           $o \leftarrow S.pop()$   
          T.push( $o$ )  
        until  $o = w$   
        return T.elements()  
  S.pop( $v$ )
```