

Recap

- Revisiting %rip
- Calling Functions
 - The Stack
 - Passing Control
 - Passing Data
 - Local Storage
- Register Restrictions

Recap: Calling Functions In Assembly

To call a function in assembly, we must do a few things:

- Pass Control %rip must be adjusted to execute the callee's instructions, and then resume the caller's instructions afterwards.
- Pass Data we must pass any parameters and receive any return value.
- Manage Memory we must handle any space needs of the callee on the stack.

Terminology: caller function calls the callee function.

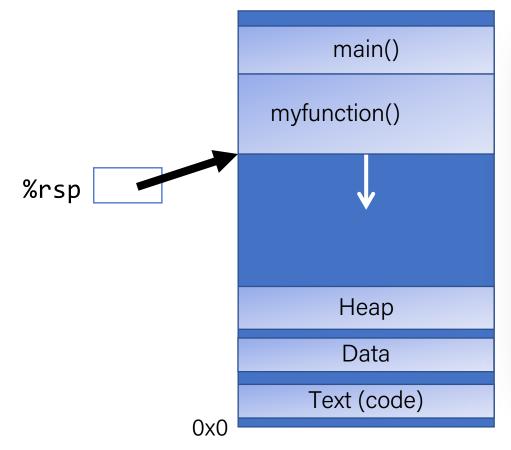
Recap: Instruction Pointer

- Machine code instructions live in main memory, just like stack and heap data.
- %rip is a register that stores a number (an address) of the next instruction to execute. It marks our place in the program's instructions.
- To advance to the next instruction, special hardware adds the size of the current instruction in bytes.
- jmp instructions work by adjusting %rip by a specified amount.

Recap: %rsp

• **%rsp** is a special register that stores the address of the current "top" of the stack (the bottom in our diagrams, since the stack grows downwards).

Main Memory



Key idea: %rsp must point to the same place before a function is called and after that function returns, since stack frames go away when a function finishes.

Recap: push and pop

Instruction	Effect	Instruction	Effect
	R[%rsp] ← R[%rsp] - 8; M[R[%rsp]] ← S		D ← M[R[%rsp]] R[%rsp] ← R[%rsp] + 8;

- The **push** instruction pushes the data at the specified source onto the top of the stack, adjusting **%rsp** accordingly.
- The pop instruction pops the topmost data from the stack and stores it in the specified destination, adjusting %rsp accordingly.
- **Note:** this <u>does not</u> remove/clear out the data! It just increments %rsp to indicate the next push can overwrite that location.

Recap: Call And Return

The **call** instruction pushes the address of the instruction immediately following the **call** instruction onto the stack and sets %rip to point to the beginning of the specified function's instructions.

call Label

call *Operand

The **ret** instruction pops this instruction address from the stack and stores it in %rip.

ret

The stored %rip value for a function is called its **return address**. It is the address of the instruction at which to resume the function's execution. (not to be confused with **return value**, which is the value returned from a function).

Recap: Local Storage

- So far, we've often seen local variables stored directly in registers, rather than on the stack as we'd expect. This is for optimization reasons.
- There are **three** common reasons that local data must be in memory:
 - We've run out of registers
 - The '&' operator is used on it, so we must generate an address for it
 - They are arrays or structs (need to use address arithmetic)

Recap: Register Restrictions

Caller-Owned (Callee Saved)

- Callee must *save* the existing value and *restore* it when done.
- Caller can store values and assume they will be preserved across function calls.

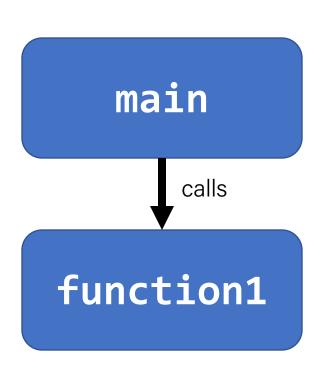
Callee-Owned (Caller Saved)

- Callee does not need to save the existing value.
- Caller's values could be overwritten by a callee! The caller may consider saving values elsewhere before calling functions.



Figure 3.2 Integer registers. The low-order portions of all 16 registers can be accessed as byte, word (16-bit), double word (32-bit), and quad word (64-bit) quantities.

Recap: Caller-Owned Registers



```
function1:

push %rbp

push %rbx

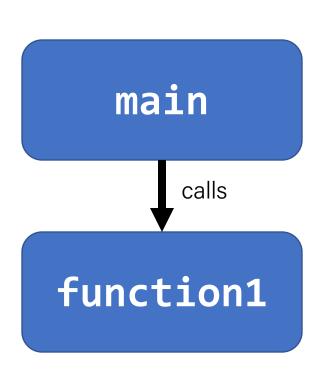
...

pop %rbx

pop %rbp

retq
```

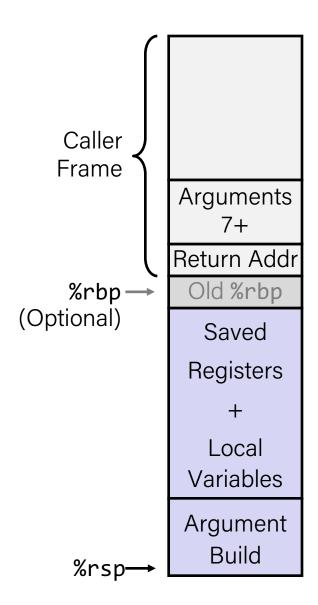
Recap: Callee-Owned Registers



```
main:
  push %r10
  push %r11
  callq function1
  pop %r11
  pop %r10
```

Recap: x86-64 Procedure Summary

- Important Points
 - Stack is the right data structure for procedure call/return
 - If P calls Q, then Q returns before P
- Recursion (& mutual recursion) handled by normal calling conventions
 - Can safely store values in local stack frame and in callee-saved registers
 - Put function arguments at top of stack
 - Result return in %rax
- Pointers are addresses of values
 - On stack or global



Plan for Today

- Arrays
- Structures
- Floating Point

Disclaimer: Slides for this lecture were borrowed from

—Randal E. Bryant and David R. O'Hallaroni's CMU 15-213 class

Lecture Plan

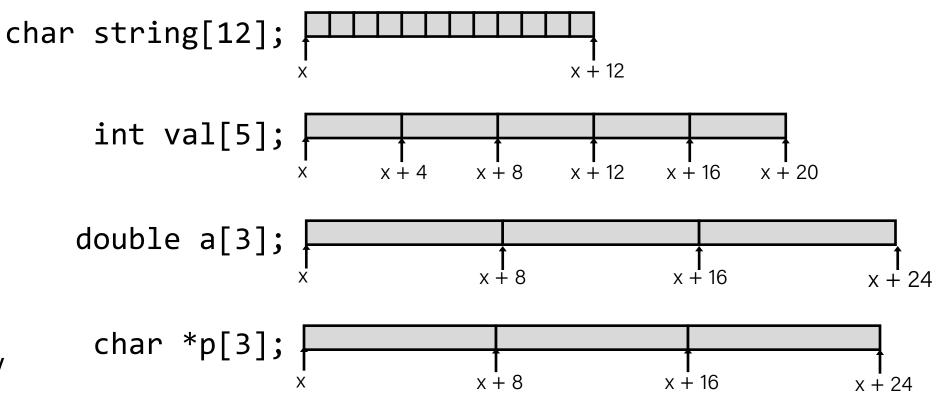
- Arrays
 - One-dimensional
 - Multi-dimensional (nested)
 - Multi-level
- Structures
- Floating Point

Array Allocation

Basic Principle

T A[L];

- Array of data type T and length L
- Contiguously allocated region of L*sizeof(T) bytes in memory



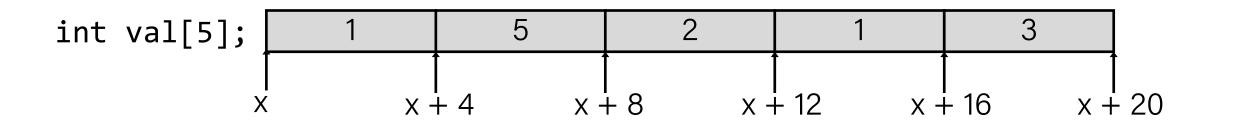
Array Access

Basic Principle

T A[L];

- Array of data type T and length L
- Identifier A can be used as a pointer to array element 0: Type T*

Reference	Type	Value
val[4]	int	3
val	int *	X
val+1	int *	x + 4
&val[2]	int *	x + 8
val[5]	int	??
*(val+1)	int	5
val + i	int *	x + 4 i



Array Example

```
5
#define ZLEN 5
                               zip_dig cmu;
typedef int zip_dig[ZLEN];
                                               16
                                                      20
                                                            24
                                                                   28
                                                                                36
zip_dig cmu = \{1,5,2,1,3\};
                                                                             9
                               zip_dig mit;
zip_dig mit = \{0,2,1,3,9\};
                                               36
                                                      40
                                                                   48
                                                                         52
zip_dig ku = \{3,4,4,5,0\};
                                                                                56
                                zip_dig ku;
```

56

- Declaration "zip_dig cmu" equivalent to "int cmu[5]"
- Example arrays were allocated in successive 20 byte blocks
 - Not guaranteed to happen in general

76

64

60

68

Array Accessing Example

```
int get_digit
  (zip_dig z, int digit)
{
  return z[digit];
}
```

```
zip_dig ku; 3 4 4 5 0
16 20 24 28 32 3

# %rdi = z
# %rsi = digit
movl (%rdi,%rsi,4), %eax # z[digit]
```

- Register %rdi contains starting address of array
- Register %rsi contains array index
- Desired digit at %rdi + 4*%rsi
- Use memory reference (%rdi,%rsi,4)

Array Loop Example

```
void zincr(zip_dig z) {
    size_t i;
    for (i=0; i<ZLEN; i++)
    z[i]++;
}</pre>
```

```
# %rdi = z
 movl $0, %eax
                       # i = 0
                        # goto middle
 jmp
        .L3
.L4:
                        # loop:
 addl $1, (%rdi,%rax,4) # z[i]++
 addq $1, %rax
                        # i++
.L3:
                        # middle
 cmpq $4, %rax
                        # i:4
                        # if <=, goto loop</pre>
 jbe .L4
 rep; ret
```

Multidimensional (Nested) Arrays

Declaration

T A[R][C];

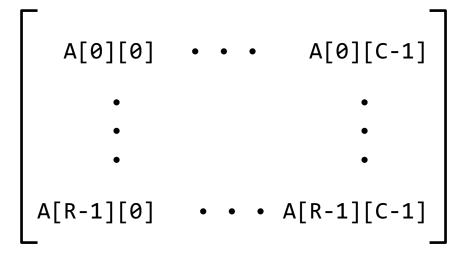
- 2D array of data type T
- R rows, C columns
- Type T element requires
 K bytes

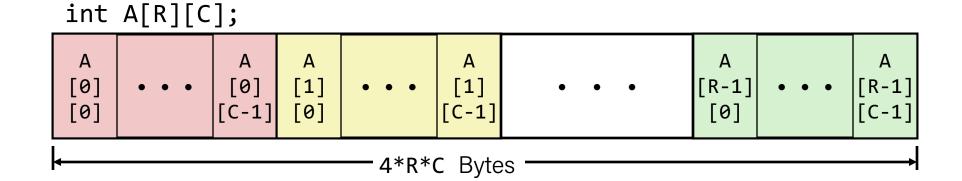
Array Size

• *R* * *C* * *K* bytes

Arrangement

Row-Major Ordering





Nested Array Example

```
#define PCOUNT 4
zip_dig pgh[PCOUNT] =
{{1, 5, 2, 0, 6},
{1, 5, 2, 1, 3},
{1, 5, 2, 1, 7},
{1, 5, 2, 2, 1 }};
```

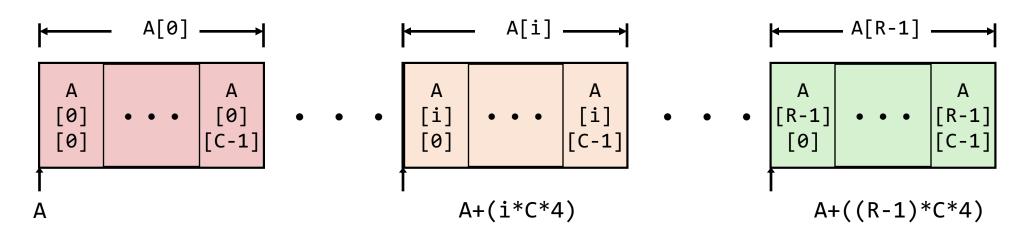
- "zip_dig pgh[4]" equivalent to "int pgh[4][5]"
 - Variable pgh: array of 4 elements, allocated contiguously
 - Each element is an array of 5 int's, allocated contiguously
- "Row-Major" ordering of all elements in memory

Nested Array Row Access

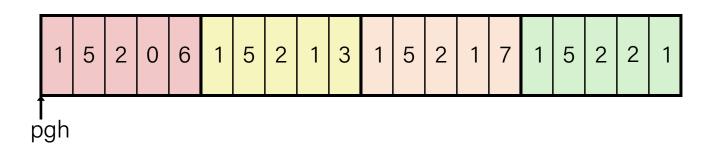
Row Vectors

- A[i] is array of C elements
- Each element of type *T* requires *K* bytes
- Starting address $\mathbf{A} + i * (C * K)$

int A[R][C];



Nested Array Row Access Code



Row Vector

- pgh[index] is array of 5 int's
- Starting address pgh+20*index

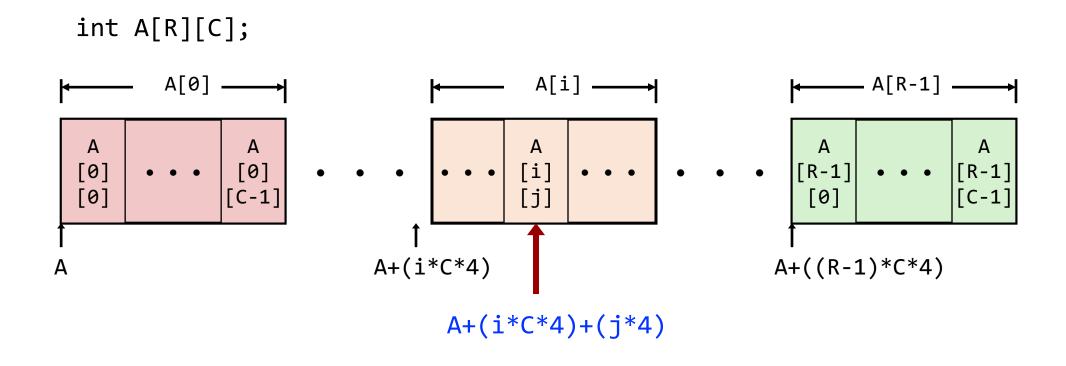
Machine Code

- Computes and returns address
- Compute as pgh+4*(index+4*index)

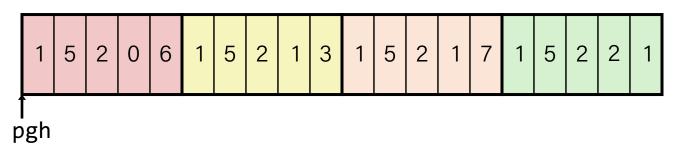
Nested Array Element Access

Array Elements

- A[i][j] is element of type T, which requires K bytes
- Address A + i * (C * K) + j * K = A + (i * C + j) * K



Nested Array Element Access Code



```
int get_pgh_digit
    (int index, int dig)
{
    movl pgh(,%rsi,4), %eax # 5*index
# 5*index+dig
movl pgh(,%rsi,4), %eax # M[pgh + 4*(5*index+dig)]
}
```

Array Elements

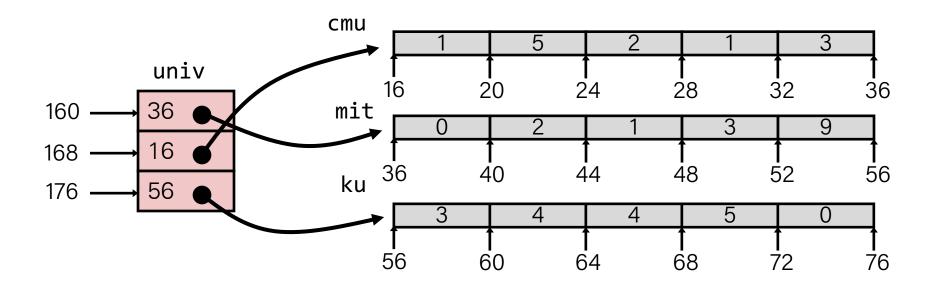
- pgh[index][dig] is int
- Address: pgh + 20*index + 4*dig = pgh + 4*(5*index + dig)

Multi-Level Array Example

```
zip_dig cmu = { 1, 5, 2, 1, 3 };
zip_dig mit = { 0, 2, 1, 3, 9 };
zip_dig ku = { 3, 4, 4, 5, 0 };

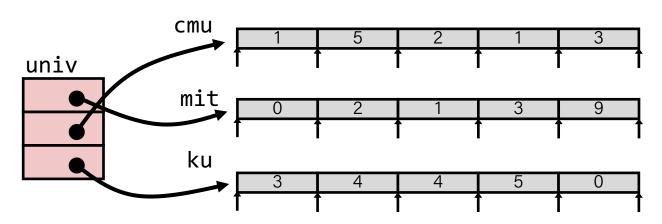
#define UCOUNT 3
int *univ[UCOUNT] = {mit, cmu, ku};
```

- Variable univ denotes array of 3 elements
- Each element is a pointer
 - 8 bytes
- Each pointer points to array of int's



Element Access in Multi-Level Array

```
int get_univ_digit
  (size_t index, size_t digit)
{
  return univ[index][digit];
}
```



```
salq $2, %rsi # 4*digit
addq univ(,%rdi,8), %rsi # p = univ[index] + 4*digit
movl (%rsi), %eax # return *p
ret
```

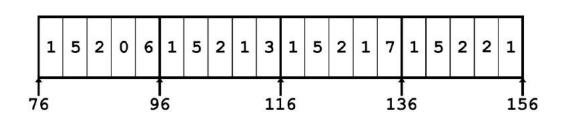
Computation

- Element access Mem[Mem[univ+8*index]+4*digit]
- Must do two memory reads
 - First get pointer to row array
 - Then access element within array

Array Element Accesses

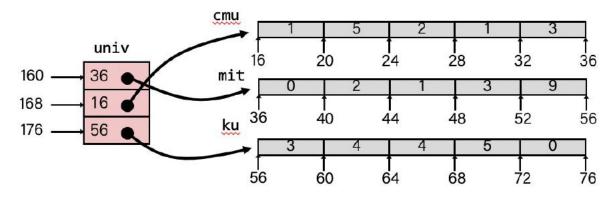
Nested array

```
int get_pgh_digit
  (size_t index, size_t digit)
{
  return pgh[index][digit];
}
```



Multi-level array

```
int get_univ_digit
   (size_t index, size_t digit)
{
   return univ[index][digit];
}
```



Accesses looks similar in C, but address computations very different:

```
Mem[pgh+20*index+4*digit]
```

Mem[Mem[univ+8*index]+4*digit]

N × N Matrix Code

Fixed dimensions

 Know value of N at compile time

Variable dimensions, explicit indexing

 Traditional way to implement dynamic arrays

Variable dimensions, implicit indexing

Now supported by gcc

16 × 16 Matrix Access

```
/* Get element a[i][j] */
int fix ele(fix matrix a, size_t i, size_t j) {
 return a[i][j];
# a in %rdi, i in %rsi, j in %rdx
salq $6, %rsi
                # 64*i
addq %rsi, %rdi # a + 64*i
movl (%rdi,%rdx,4), %eax # M[a + 64*i + 4*j]
ret
```

Array Elements

- Address A + i * (C * K) + j * K
- C = 16, K = 4

n x n Matrix Access

```
/* Get element a[i][j] */
int var_ele(size_t n, int a[n][n], size_t i, size_t j) {
  return a[i][j];
}
```

Array Elements

- Address A + i * (C * K) + j * K
- C = 16, K = 4
- Must perform integer multiplication

Practice 1: Reverse Engineering

```
#define M ??
#define N ??

long P[M][N];
long Q[N][M];
long sum_elem(long i, long j)
{
    return P[i][j] + Q[j][i];
}
```

```
# long sum_elem(long i, long j)
# in %rdi, j in %rsi
1 sum_element:
    leaq 0(,%rdi,8), %rdx
                               Compute 8*i
    subq %rdi, %rdx
                               Compute 7*i
    addq %rsi, %rdx
                               Compute 7*i+j
    leaq (%rsi,%rsi,4), %rax
5
                               Compute 5*j
    addq %rax, %rdi
                               Compute i+5*j
   movq Q(,%rdi,8), %rax
                               Retrieve M[Q+8*(5*j+i)]
                               Add M[P+8*(7*i+j)]
8
    add P(,%rdx,8), %rax
9
    ret
```

What is the value of M and N?

M = 5 and N = 7



Lecture Plan

- Arrays
- Structures
 - Allocation
 - Access
 - Alignment
- Floating Point

Structure Representation

- Structure represented as block of memory
 - Big enough to hold all of the fields
- Fields ordered according to declaration
 - Even if another ordering could yield a more compact representation
- Compiler determines overall size + positions of fields
 - Machine-level program has no understanding of the structures in the source code

Generating Pointer to Structure Member

```
struct rec {
    int a[4];
    int i;
    struct rec *next;
};
```

r r+4*idx a i next 0 16 20 28

Generating Pointer to Array Element

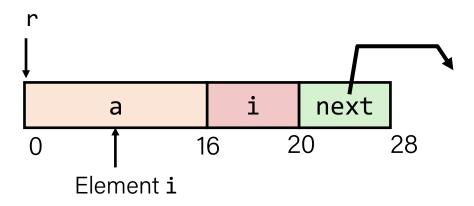
- Offset of each structure member determined at compile time
- Compute as r + 4*idx

```
int *get_ap
  (struct rec *r, size_t idx)
{
  return &r->a[idx];
}
```

```
# r in %rdi, idx in %rsi
leaq (%rdi,%rsi,4), %rax
ret
```

Following Linked List

```
struct rec {
    int a[4];
    int i;
    struct rec *next;
};
void set_val (struct rec *r, int val) {
  while (r) {
    int i = r \rightarrow i;
    r-a[i] = val;
    r = r \rightarrow next;
```



Register	Value
%rdi	r
%esi	val

```
.L11:
                               # loop:
                               # i = M[r+16]
 movslq 16(%rdi), %rax
         %esi, (%rdi,%rax,4)
                               \# M[r+4*i] = val
 movl
        20(%rdi), %rdi
                               # r = M[r+20]
 movq
 testq
         %rdi, %rdi
                               #
                                  Test r
 jne
         .L11
                                   if !=0 goto loop
```

Practice 2: Reverse Engineering

Fill in the blanks by inspecting the assembly code generated by gcc.



```
struct test {
   short *p;
   struct {
      short x;
      short y;
   } s;
   struct test *next;
void st init(struct test *st) {
   st->s.y = \underline{st->s.x};
   st->p = &(st->s.y);
   st->next = <u>st</u>
```

```
# void st_init(struct test *st)
# st in %rdi
1 st_init:
2   movl 8(%rdi), %eax   Get st->s.x
3   movl %eax, 10(%rdi)   Save in st->s.y
4   leaq 10(%rdi), %rax   Compute &(st->s.y)
5   movq %rax, (%rdi)   Store in st->p
6   movq %rdi, 12(%rdi)   Store st in st->next
7   ret
```

```
0 8 10 12 20 p s.x s.y next
```

Structures & Alignment

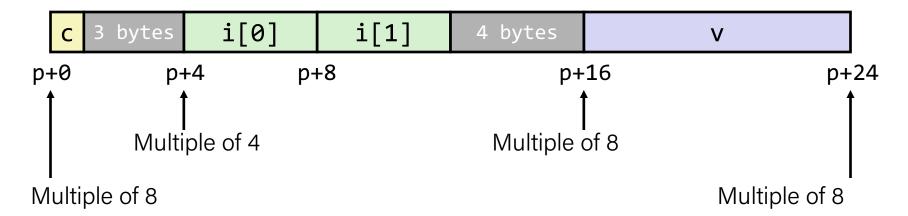
Unaligned Data

```
c i[0] i[1] v
p p+1 p+5 p+9 p+17
```

```
struct S1 {
  char c;
  int i[2];
  double v;
} *p;
```

Aligned Data

- Primitive data type requires K bytes
- Address must be multiple of K



Alignment Principles

Aligned Data

- Primitive data type requires K bytes
- Address must be multiple of K
- Required on some machines; advised on x86-64

Motivation for Aligning Data

- Memory accessed by (aligned) chunks of 4 or 8 bytes (system dependent)
 - Inefficient to load or store datum that spans quad word boundaries
 - Virtual memory trickier when datum spans 2 pages

Compiler

Inserts gaps in structure to ensure correct alignment of fields

Specific Cases of Alignment (x86-64)

- 1 byte: char, ...
 - no restrictions on address
- 2 bytes: short, ...
 - lowest 1 bit of address must be 02
- 4 bytes: int, float, ...
 - lowest 2 bits of address must be 002
- 8 bytes: double, long, char *, ...
 - lowest 3 bits of address must be 0002
- 16 bytes: long double (GCC on Linux)
 - lowest 4 bits of address must be 00002

Satisfying Alignment with Structures

Within structure:

Must satisfy each element's alignment requirement

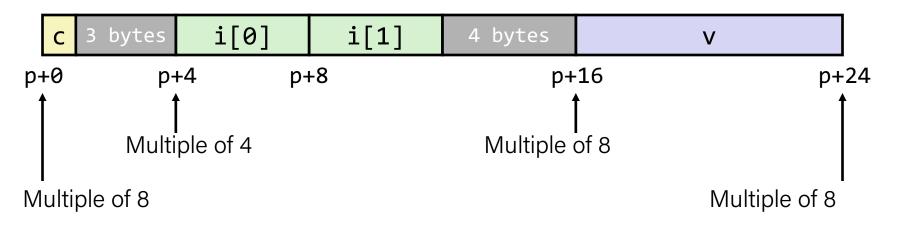
Overall structure placement

- Each structure has alignment requirement K
 - K = Largest alignment of any element
- Initial address & structure length must be multiples of K

Example:

• K = 8, due to **double** element

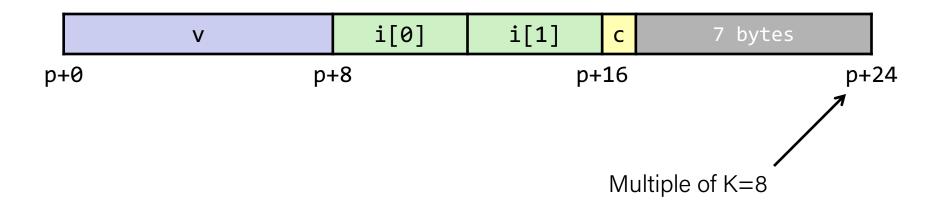
```
struct S1 {
  char c;
  int i[2];
  double v;
} *p;
```



Meeting Overall Alignment Requirement

- For largest alignment requirement K
- Overall structure must be multiple of K

```
struct S2 {
  double v;
  int i[2];
  char c;
} *p;
```

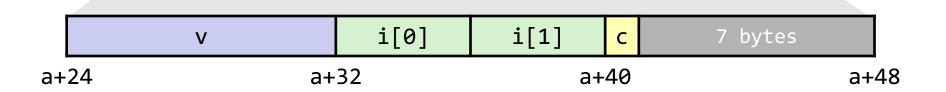


Arrays of Structures

- Overall structure length multiple of K
- Satisfy alignment requirement for every element

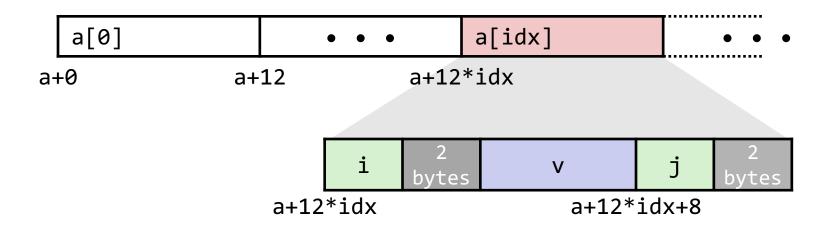
```
struct S2 {
  double v;
  int i[2];
  char c;
} a[10];
```





Accessing Array Elements

- Compute array offset 12*idx
 - sizeof(S3), including alignment spacers
- Element j is at offset 8 within structure
- Assembler gives offset a+8 (resolved during linking)



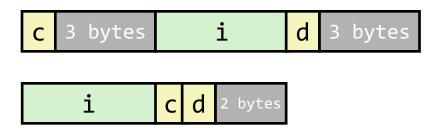
struct S3 {
 short i;
 float v;
 short j;
} a[10];

Saving Space

Put large data types first

```
struct S4 {
    char c;
    int i;
    char c;
    char d;
} *p;
struct S5 {
    int i;
    char c;
    char d;
} *p;
```

Effect (K=4)



Practice 3: Alignment



Determine the offset of each field, the total size of the structure, and its alignment requirement for x86-64.

```
struct mystruct {
   int *a;
   float b;
   char c;
   short d;
   float e;
   double f;
   int g;
   char *h;
```

Field	*a	b	C	d	e	f	g	*h	Total	Alignment
Size	8	4	1	2	4	8	4	8	40	8 padded to satisfyent requirement
Offset	0	8	12	14	16	24	32	36	•	

Rearranged structure with minimum wasted space:

Field	*a	f	h	b	e	g	d	C	Total	Alignment	
Size	8	8	8	4	4	4	2	1	40	0	
Offset	0	8	16	24	28	32	36	38	40	O naddad ta aatiaf (
									1 bytes padded to satisfy alignment requirement		

Lecture Plan

- Arrays
 - One-dimensional
 - Multi-dimensional (nested)
 - Multi-level
- Structures
- Floating Point

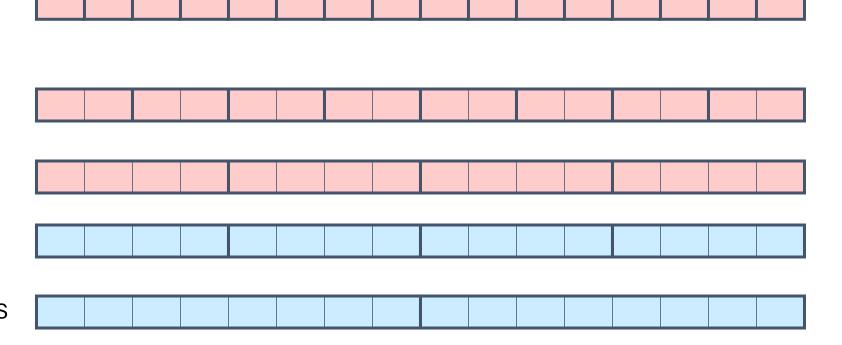
Background

- History
 - x87 FP
 - Legacy, very ugly
 - Streaming SIMD Extensions (SSE) FP
 - SIMD: single instruction, multiple data
 - Special case use of vector instructions
 - AVX FP
 - Newest version
 - Similar to SSE
 - Documented in book

Programming with SSE3

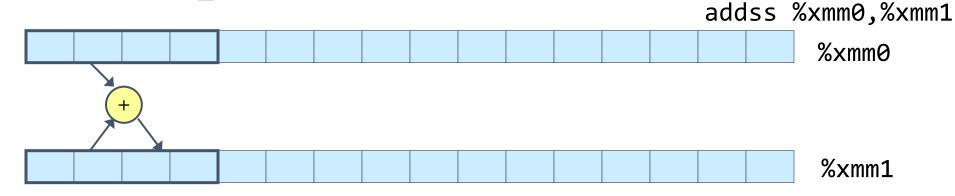
XMM Registers

- 16 total, each 16 bytes
- 16 single-byte integers
- 8 16-bit integers
- 4 32-bit integers
- 4 single-precision floats
- 2 double-precision floats
- 1 single-precision float
- 1 double-precision float

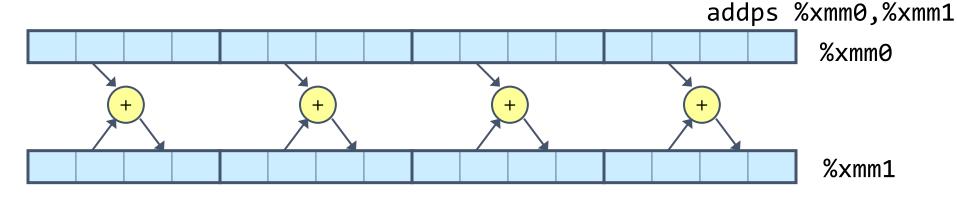


Scalar & SIMD Operations

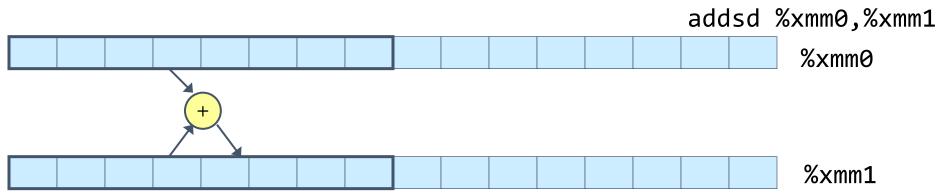
Scalar
 Operations:
 Single
 Precision



SIMD
 Operations:
 Single
 Precision



Scalar Operations: Double Precision



FP Basics

- Arguments passed in %xmm0, %xmm1, ...
- Result returned in %xmm0
- All XMM registers caller-saved

```
float fadd(float x, float y) {
    return x + y;
}
```

```
double dadd(double x, double y) {
    return x + y;
}
```

```
# x in %xmm0, y in %xmm1
addss %xmm1, %xmm0
ret
```

```
# x in %xmm0, y in %xmm1
addsd %xmm1, %xmm0
ret
```

FP Memory Referencing

- Integer (and pointer) arguments passed in regular registers
- FP values passed in XMM registers
- Different mov instructions to move between XMM registers, and between memory and XMM registers

Other Aspects of FP Code

- Lots of instructions
 - Different operations, different formats, ...
- Floating-point comparisons
 - Instructions ucomiss and ucomisd
 - Set condition codes CF, ZF, and PF
- Using constant values
 - Set XMM0 register to 0 with instruction xorpd %xmm0, %xmm0
 - Others loaded from memory

Recap

- Arrays
- Structures
- Floating Point

That's it for assembly!

Next time: security vulnerabilities, memory hierarchy