COMP 341 Intro to AI
Bayesian Networks – Exact Inference

How certain are we that the butler did it?

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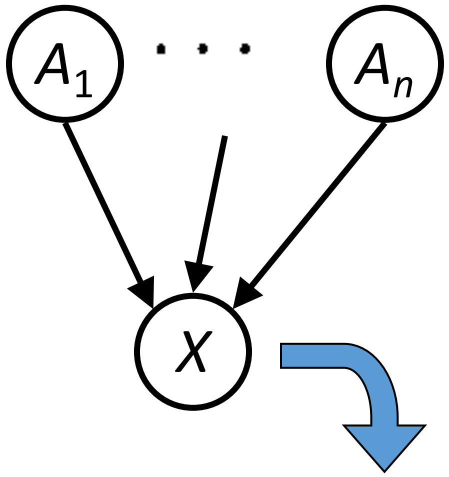
Bayesian Network Recap

- Represented as directed acyclic graphs
- A set of nodes, one per variable X
- Implicitly encode the joint probability distribution as a product of local conditional distributions

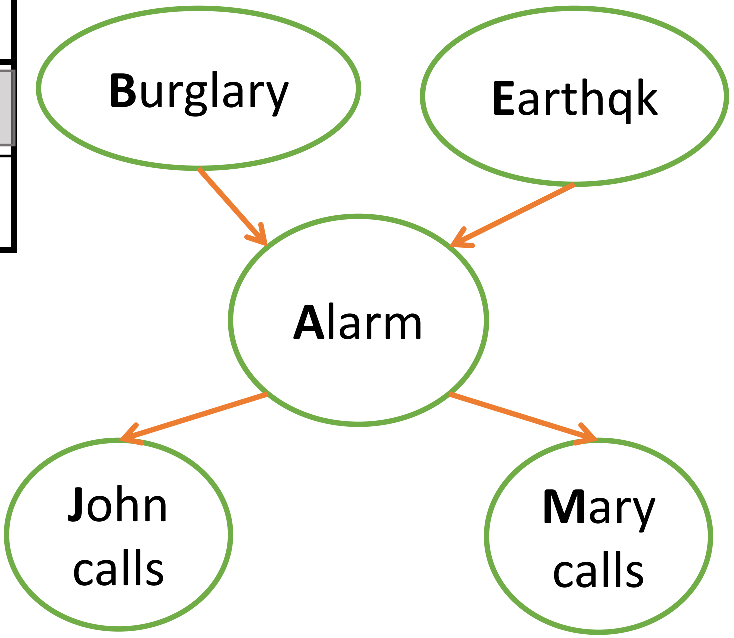
$$P(X_1, X_2, \dots, X_n) = \prod_{i=1}^{n} P\big(X_i | Parents(X_i)\big)$$



$$P(X|A_1 \dots A_n)$$

Example: Alarm Network

B	P(B)
+b	0.001
-b	0.999



E	P(E)
+e	0.002
-e	0.998

B	E	A	P(A|B,E)
+b	+e	+a	0.95
+b	+e	-a	0.05
+b	-e	+a	0.94
+b	-e	-a	0.06
-b	+e	+a	0.29
-b	+e	-a	0.71
-b	-e	+a	0.001
-b	-e	-a	0.999

A	J	P(J|A)
+a	+j	0.9
+a	-j	0.1
-a	+j	0.05
-a	-j	0.95

A	M	P(M|A)
+a	+m	0.7
+a	-m	0.3
-a	+m	0.01
-a	-m	0.99

$$P(+b, -e, +a, -j, +m) =$$
$$P(+b)P(-e)P(+a|+b,-e)P(-j|+a)P(+m|+a) =$$
$$0.001 \times 0.998 \times 0.94 \times 0.1 \times 0.7$$

Probabilistic Inference

- Inference: Calculating a useful quantity from a joint probability distribution
- We have seen “inference by enumeration”

- Posterior Probability: $\mathrm{P}(Q|E_1 = e_1, \ldots, E_k = e_k)$
- Most Likely Explanation: $\mathrm{argmax_q}\ \mathrm{P}(Q = q|E_1 = e_1, \ldots, E_k = e_k)$

- Mary called me to tell me that my house alarm was ringing. How likely is it that there is a burglar?
- Why did Mehmet get a medical report for the exam?

Probabilistic Inference Methods

- Enumeration (exact, exponential complexity)
- Variable elimination (exact, worst-case exponential complexity, often better)

- Exact Inference is NP-Hard

- Sampling (approximate)

Inference by Enumeration given the Joint Dist.

- General case:
  - Evidence variables: $E_1 \dots E_k = e_1 \dots e_k$
  - Query* variable: Q
  - Hidden variables: $H_1 \dots H_r$

$$\left.\begin{array}{l} E_1 \dots E_k = e_1 \dots e_k \\ Q \\ H_1 \dots H_r \end{array}\right\} X_1, X_2, \dots X_n$$

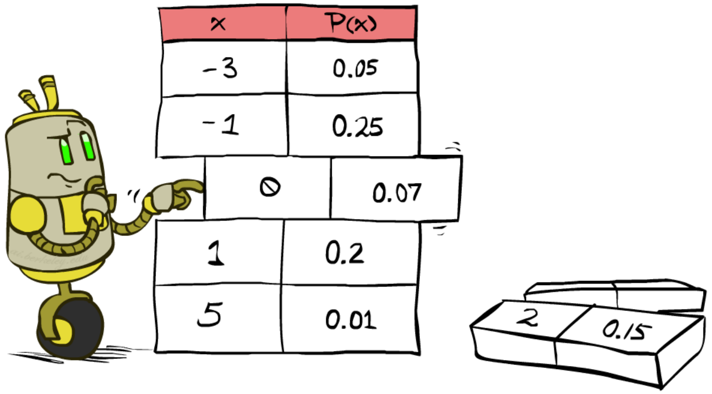
All variables

- We want:

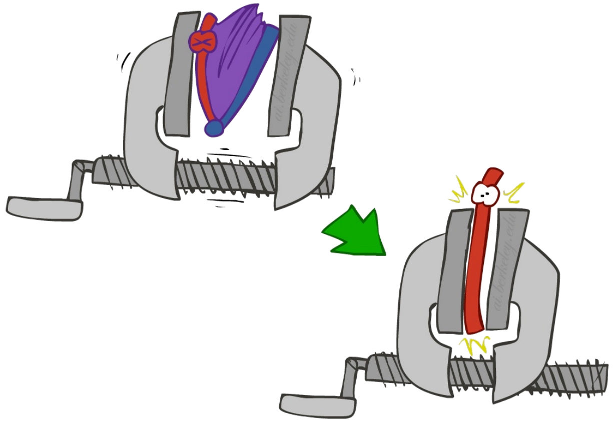
* *Works fine with multiple query variables, too*

$$P(Q|e_1 \dots e_k)$$

- Step 1: Select the entries consistent with the evidence



- Step 2: Sum out H to get joint of Query and evidence (marginalize)



$$P(Q, e_1 \dots e_k) = \sum_{h_1 \dots h_r} \underbrace{P(Q, h_1 \dots h_r, e_1 \dots e_k)}_{X_1, X_2, \dots X_n}$$

- Step 3: Normalize

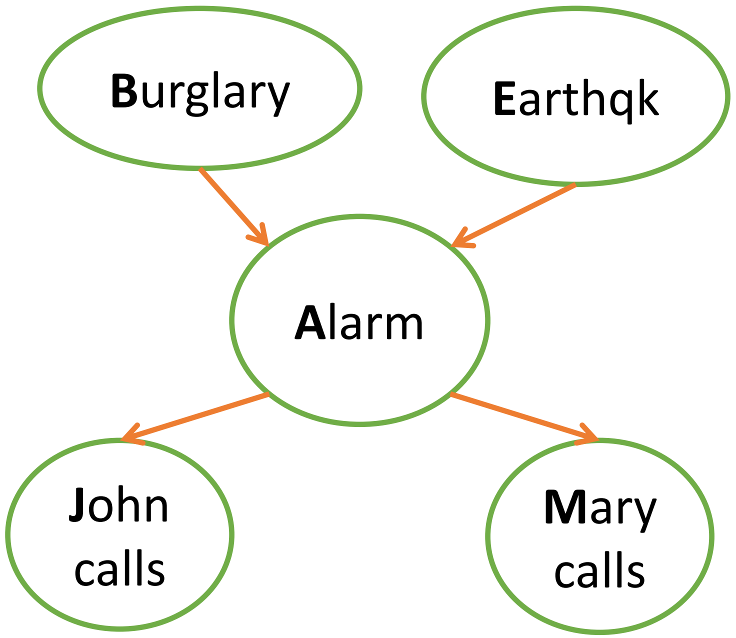
$$\times \frac{1}{Z}$$

$$Z = \sum_q P(Q, e_1 \cdots e_k)$$

$$P(Q|e_1 \cdots e_k) = \frac{1}{Z} P(Q, e_1 \cdots e_k)$$

Inference by Enumeration in BNs

- Easy! Just need lots of time
  - State all conditional probabilities needed
  - Figure out all atomic probabilities needed
  - Combine, marginalize and normalize



- E.g.

$\mathrm{P}(B, E, A, J, M) = P(B)P(E)P(A|B, E)P(J|A)P(M|A)$

$\mathrm{P}(B| +j, +m) = ?$

Inference Example

$$\mathrm{P}(B \mid +j, +m) = \frac{\mathrm{P}(B, +j, +m)}{\mathrm{P}(+j, +m)} = \alpha \mathrm{P}(B, +j, +m) = \alpha \sum_{e,a} \mathrm{P}\,(B, e, a, +j, +m)$$

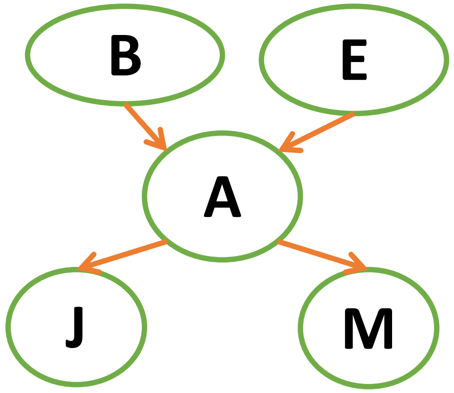
$$= \alpha \sum_{e,a} \mathrm{P}\,(B)\mathrm{P}(e)\mathrm{P}(a \mid B, e)\mathrm{P}(+j \mid a)\mathrm{P}(+m \mid a)$$

$$= \alpha(\mathrm{P}(B)P(+e)\mathrm{P}(+a \mid B, +e)P(+j \mid +a)P(+m \mid +a)$$

$$+ \quad \mathrm{P}(B)P(-e)\mathrm{P}(+a \mid B, -e)P(+j \mid +a)P(+m \mid +a)$$

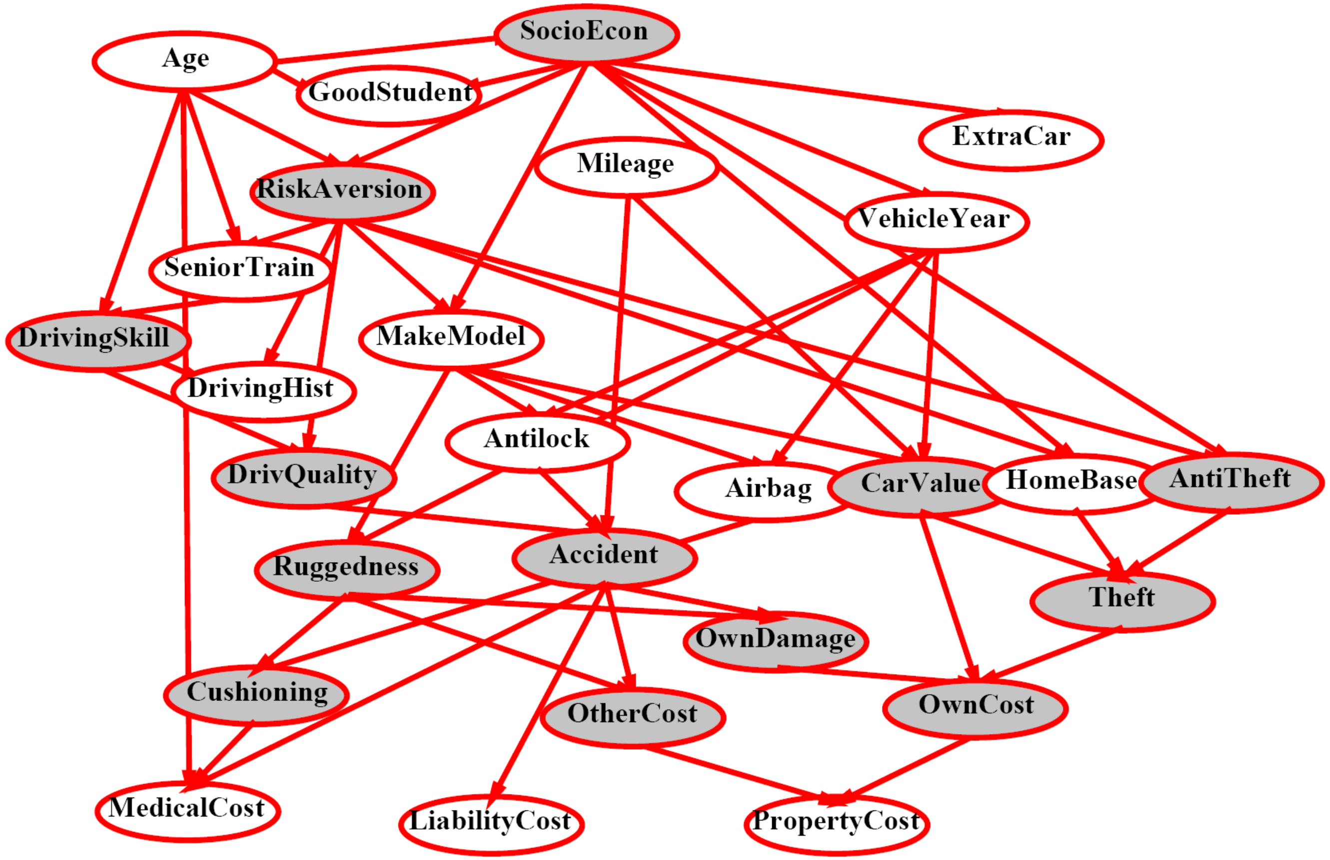
$$+ \quad \mathrm{P}(B)P(+e)\mathrm{P}(-a \mid B, +e)P(+j \mid -a)P(+m \mid -a)$$

$$+ \quad \mathrm{P}(B)P(-e)\mathrm{P}(-a \mid B, -e)P(+j \mid -a)P(+m \mid -a))$$



Calculate for both +b and –b. Then normalize to get rid of α

Another Example

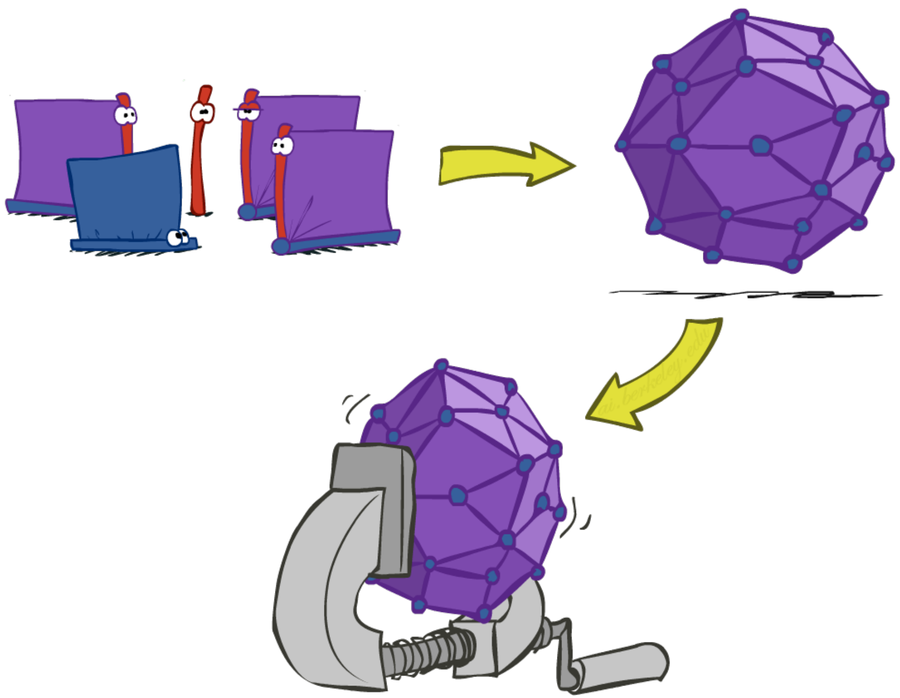


$$P(LiabilityCost|ShadedVariables) = ?$$

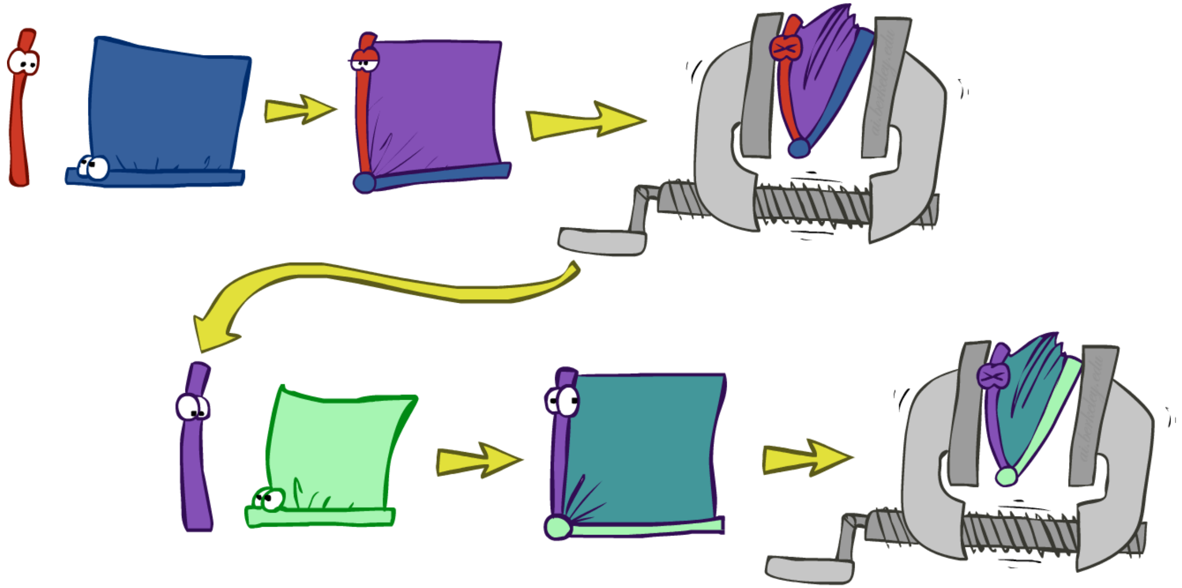
Would be cumbersome with enumeration (aka brute force), but there is a much easier way for this example

Variable Elimination

- Why is inference by enumeration so slow?
  - You join up the whole joint distribution before you sum out the hidden variables



- Idea: interleave joining and marginalizing!
  - Called “Variable Elimination”
  - Still NP-hard, but usually faster than inference by enumeration



- First we’ll need some new notation: factors

Factors

- **Factorization**: "Decomposition of an object into product of other objects or *factors*"

- Pointwise product of two factors:
$$f_1(x_1, \dots, x_n, \underline{y_1, \dots, y_k}) \cdot f_2(\underline{y_1, \dots, y_k}, z_1, \dots, z_l) = f(x_1, \dots, x_n, \underline{y_1, \dots, y_k}, z_1, \dots, z_l)$$

- What are some factors that we can use in BNs?

Factors I

- Joint distribution: P(X,Y)
  - Entries P(x,y) for all x, y
  - Sums to 1

$$P(T, W)$$

T	W	P
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3

- Selected joint: P(x,Y)
  - A slice of the joint distribution
  - Entries P(x,y) for fixed x, all y
  - Sums to P(x)

$$P(cold, W)$$

T	W	P
cold	sun	0.2
cold	rain	0.3

- Number of capitals (unobserved variables) affect dimensionality of the table

Factors II

- Single conditional: P(Y | x)
  - Entries P(y | x) for fixed x, all y
  - Sums to 1

$$P(W|cold)$$

T	W	P
cold	sun	0.4
cold	rain	0.6

- Family of conditionals:

  P(X |Y)
  - Multiple conditionals
  - Entries P(x | y) for all x, y
  - Sums to |Y|

$$P(W|T)$$

T	W	P
hot	sun	0.8
hot	rain	0.2
cold	sun	0.4
cold	rain	0.6

$P(W|hot)$

$P(W|cold)$

Factors III

- Specified family: P(y | X)
  - Entries P(y | x) for fixed y, but for all x
  - Sums to … who knows!

$$P(rain|T)$$

T	W	P
hot	rain	0.2
cold	rain	0.6

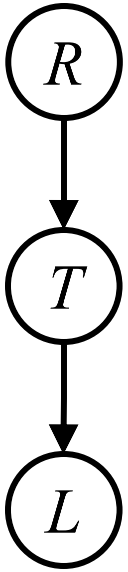
$P(rain|hot)$

$P(rain|cold)$

- In general, a factor is $P(Y_1, \ldots, Y_N | X_1, \ldots, X_M)$
  - Multi-dimensional array
  - Its values are $P(y_1 \ldots y_N \mid x_1 \ldots x_M)$
  - Any assigned (=lower-case) X or Y is a dimension missing (selected) from the array

Example: Traffic Domain

- Random Variables
  - R: Raining
  - T: Traffic
  - L: Late for class!



$$P(R)$$

+r	0.1
-r	0.9

$$P(T|R)$$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$$P(L|T)$$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

$$P(L) = \ ?$$

$$= \sum_{r,t} P(r,t,L)$$

$$= \sum_{r,t} P(r)P(t|r)P(L|t)$$

Inference by Enumeration: Procedural Outline

- Track objects called factors
- Initial factors are local CPTs (one per node)

$P(R)$

+r	0.1
-r	0.9

$P(T|R)$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

- Any known values are selected
  - E.g. if we know $L = +\ell$ the initial factors are

$P(R)$

+r	0.1
-r	0.9

$P(T|R)$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

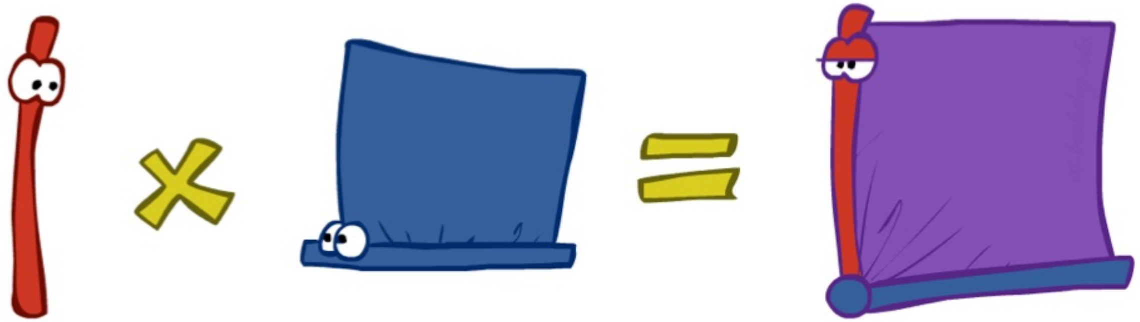
$P(+\ell|T)$

+t	+l	0.3
-t	+l	0.1

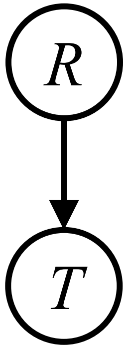
- Procedure: Join all factors, then eliminate all hidden variables

Operation 1: Join Factors

- First basic operation: joining factors
- Combining factors:
  - Get all factors over the joining variable
  - Build a new factor over the union of the variables involved



- Example: Join on R



$$P(R) \times P(T|R) \rightarrow P(R,T)$$

$P(R)$

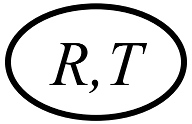
+r	0.1
-r	0.9

$P(T|R)$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

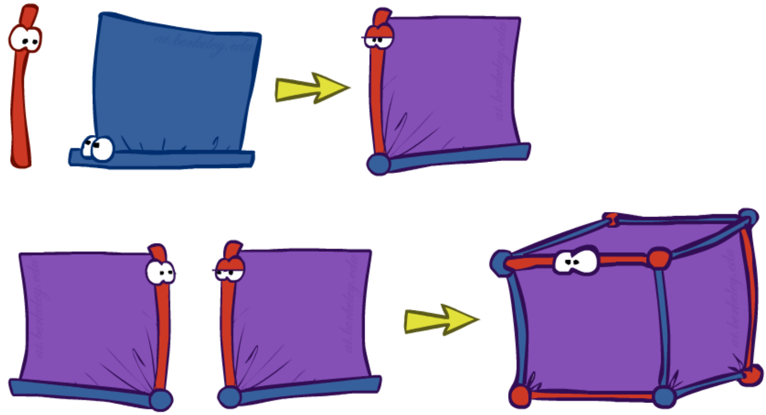
$P(R,T)$

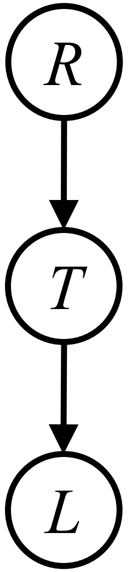
+r	+t	0.08
+r	-t	0.02
-r	+t	0.09
-r	-t	0.81



  - Computation for each entry: pointwise products $\forall r, t: \quad P(r,t) = P(r) \cdot P(t|r)$

Example: Multiple Joins





$P(R)$

+r	0.1
-r	0.9

$P(T|R)$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

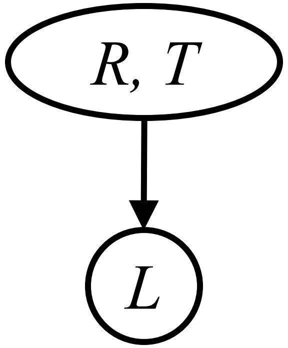
Join R

$P(R,T)$

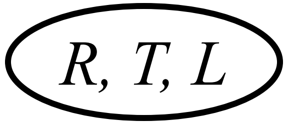
+r	+t	0.08
+r	-t	0.02
-r	+t	0.09
-r	-t	0.81

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9



Join T



$P(R,T,L)$

+r	+t	+l	0.024
+r	+t	-l	0.056
+r	-t	+l	0.002
+r	-t	-l	0.018
-r	+t	+l	0.027
-r	+t	-l	0.063
-r	-t	+l	0.081
-r	-t	-l	0.729

Operation 2: Eliminate

- Second basic operation: marginalization
- Take a factor and sum out a variable
  - Shrinks a factor to a smaller one
  - A projection operation
- Example:

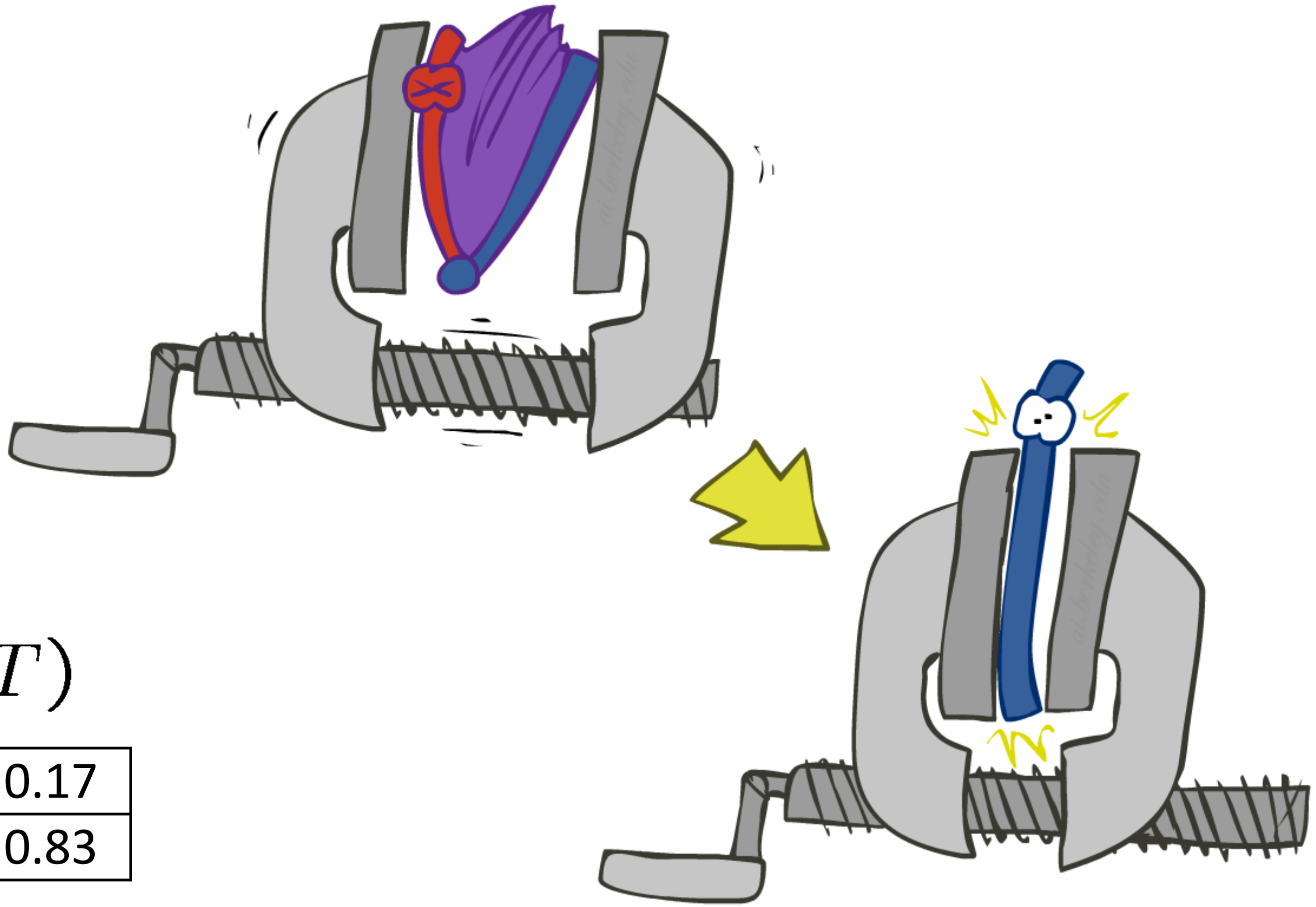
$P(R,T)$

+r	+t	0.08
+r	-t	0.02
-r	+t	0.09
-r	-t	0.81

sum R

$P(T)$

+t	0.17
-t	0.83



Multiple Elimination

R, T, L $\rightarrow$ T, L $\rightarrow$ L

$P(R,T,L)$

+r	+t	+l	0.024
+r	+t	-l	0.056
+r	-t	+l	0.002
+r	-t	-l	0.018
-r	+t	+l	0.027
-r	+t	-l	0.063
-r	-t	+l	0.081
-r	-t	-l	0.729

Sum out R

$P(T,L)$

+t	+l	0.051
+t	-l	0.119
-t	+l	0.083
-t	-l	0.747

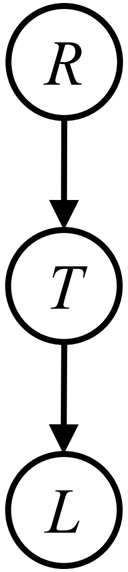
Sum out T

$P(L)$

+l	0.134
-l	0.886

Thus far, we have seen multiple-join and multiple-eliminate which is inference by enumeration!
Variable elimination is when we marginalize early

Traffic Domain



$$P(L) = \,?$$

- Inference by Enumeration

$$= \underbrace{\sum_t \underbrace{\sum_r \underbrace{P(L|t)\underbrace{P(r)P(t|r)}_{\text{Join on r}}}_{\text{Join on t}}}_{\text{Eliminate r}}}_{\text{Eliminate t}}$$

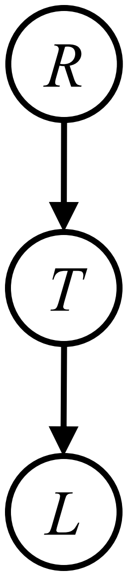
- Variable Elimination (VE)

$$= \underbrace{\sum_t \underbrace{P(L|t)\underbrace{\sum_r \underbrace{P(r)P(t|r)}_{\text{Join on r}}}_{\text{Eliminate r}}}_{\text{Join on t}}}_{\text{Eliminate t}}$$

Marginalizing Early! (aka VE)

$P(R)$

+r	0.1
-r	0.9



$P(T|R)$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

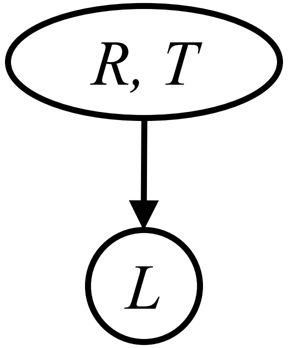
$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

Join R

$P(R,T)$

+r	+t	0.08
+r	-t	0.02
-r	+t	0.09
-r	-t	0.81



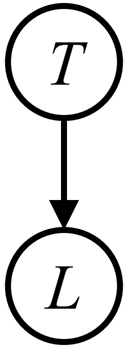
$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

Sum out R

$P(T)$

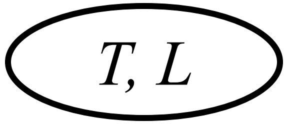
+t	0.17
-t	0.83



$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

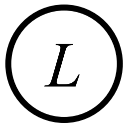
Join T



$P(T,L)$

+t	+l	0.051
+t	-l	0.119
-t	+l	0.083
-t	-l	0.747

Sum out T



$P(L)$

+l	0.134
-l	0.866

Evidence

- If you have evidence, start with factors that select that evidence
  - No evidence uses these initial factors:

$P(R)$

+r	0.1
-r	0.9

$P(T|R)$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

  - Computing $P(L|+r)$ the initial factors become:

$P(+r)$

+r	0.1

$P(T|+r)$

+r	+t	0.8
+r	-t	0.2

$P(L|T)$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

- We eliminate all vars other than query + evidence

Evidence II

- Result will be a selected joint of query and evidence
  - E.g. for P(L | +r), we would end up with:

$$P(+r, L)$$

+r	+l	0.026
+r	-l	0.074

Normalize

$$P(L|+r)$$

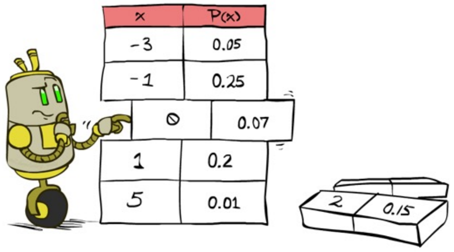
+l	0.26
-l	0.74

- To get our answer, just normalize this!

- That ’s it!

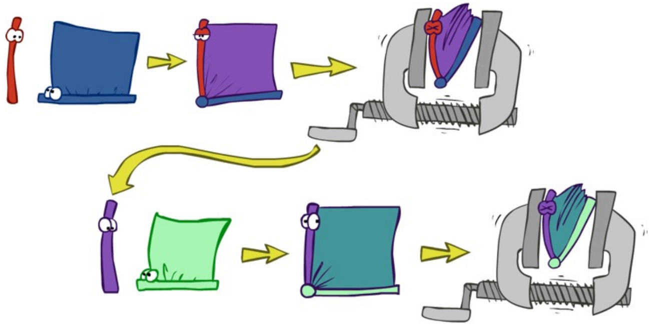
General Variable Elimination

- Query: $P(Q|E_1 = e_1, \dots E_k = e_k)$

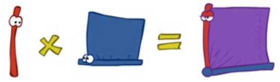


- Start with initial factors:
  - Local CPTs (but instantiated by evidence)

- While there are still hidden variables (not Q or evidence):
  - Pick a hidden variable H
  - Join all factors mentioning H
  - Eliminate (sum out) H



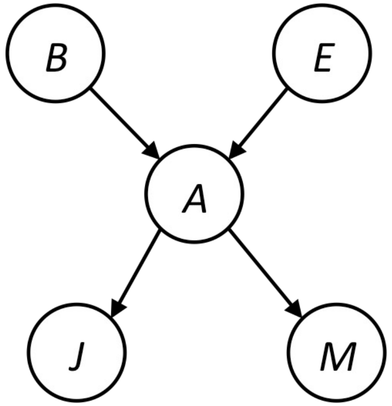
- Join all remaining factors and normalize



$$\times \frac{1}{Z}$$

Example

- What is the probability of a burglar being in my house if both John and Marry calls? OR $P(B|+j,+m) = ?$



Query Variables: B

Evidence Variables: $+j,+m$

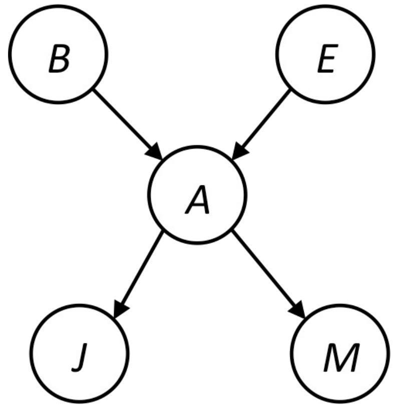
Hidden Variables: A, E

Example

$$P(B|j,m) \propto P(B,j,m)$$

Current factors

$$\boxed{P(B) \qquad P(E) \qquad P(A|B,E) \qquad P(j|A) \qquad P(m|A)}$$



Choose A

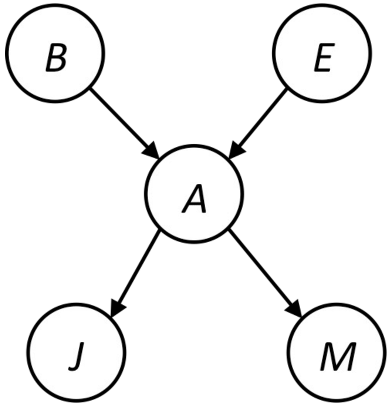
$$\begin{matrix} P(A|B,E) \\ P(j|A) \\ P(m|A) \end{matrix} \xrightarrow{\times} P(j,m,A|B,E) \xrightarrow{\sum} P(j,m|B,E)$$

$$\boxed{P(B) \qquad P(E) \qquad P(j,m|B,E)}$$

Factors after eliminating A

Example

$$P(B) \qquad P(E) \qquad P(j, m|B, E)$$



Choose E

$$\begin{matrix} P(E) \\ P(j, m|B, E) \end{matrix} \xrightarrow{\times} P(j, m, E|B) \xrightarrow{\sum} P(j, m|B)$$

$$P(B) \qquad P(j, m|B)$$

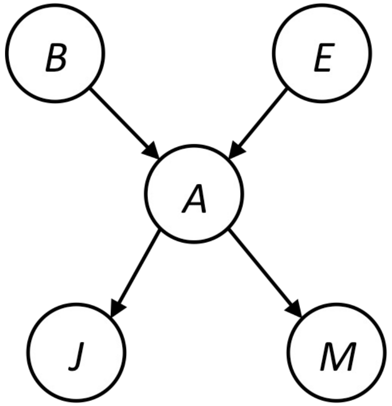
No more hidden vars, now what?
"Join all remaining and normalize"

Finish with B

$$\begin{matrix} P(B) \\ P(j, m|B) \end{matrix} \xrightarrow{\times} P(j, m, B) \xrightarrow{\text{Normalize}} P(B|j, m)$$

Same Example in Equations

$$P(B|j,m) \propto P(B,j,m)$$



$P(B)$	$P(E)$	$P(A\|B,E)$	$P(j\|A)$	$P(m\|A)$

$$\begin{aligned}
P(B|j,m) &\propto P(B,j,m) \\
&= \sum_{e,a} P(B,j,m,e,a) && \text{marginal can be obtained from joint by summing out} \\
&= \sum_{e,a} P(B)P(e)P(a|B,e)P(j|a)P(m|a) && \text{use Bayes' net joint distribution expression} \\
&= \sum_{e} P(B)P(e)\sum_{a} P(a|B,e)P(j|a)P(m|a) && \text{use } x*(y+z) = xy + xz \\
&= \sum_{e} P(B)P(e)f_1(B,e,j,m) && \text{joining on a, and then summing out gives } f_1 \\
&= P(B)\sum_{e} P(e)f_1(B,e,j,m) && \text{use } x*(y+z) = xy + xz \\
&= P(B)f_2(B,j,m) && \text{joining on e, and then summing out gives } f_2
\end{aligned}$$

All we are doing is exploiting uwy + uwz + uxy + uxz + vwy + vwz + vxy +vxz = (u+v)(w+x)(y+z) to improve computational efficiency!

Another Variable Elimination Example

Query: $P(X_3|Y_1 = y_1, Y_2 = y_2, Y_3 = y_3)$

Start by inserting evidence, which gives the following initial factors:

$$p(Z)p(X_1|Z)p(X_2|Z)p(X_3|Z)p(y_1|X_1)p(y_2|X_2)p(y_3|X_3)$$

Eliminate X_1, this introduces the factor $f_1(Z, y_1) = \sum_{x_1} p(x_1|Z)p(y_1|x_1)$, and we are left with:

$$p(Z)f_1(Z, y_1)p(X_2|Z)p(X_3|Z)p(y_2|X_2)p(y_3|X_3)$$

Eliminate X_2, this introduces the factor $f_2(Z, y_2) = \sum_{x_2} p(x_2|Z)p(y_2|x_2)$, and we are left with:

$$p(Z)f_1(Z, y_1)f_2(Z, y_2)p(X_3|Z)p(y_3|X_3)$$

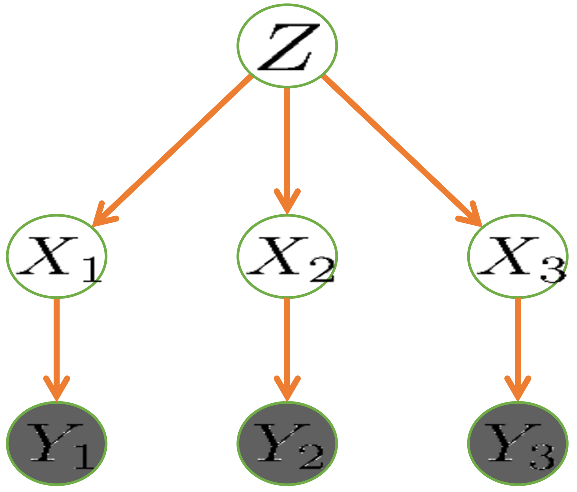
Eliminate Z, this introduces the factor $f_3(y_1, y_2, X_3) = \sum_z p(z)f_1(z, y_1)f_2(z, y_2)p(X_3|z)$, and we are left:

$$p(y_3|X_3), f_3(y_1, y_2, X_3)$$

No hidden variables left. Join the remaining factors to get:

$$f_4(y_1, y_2, y_3, X_3) = P(y_3|X_3)f_3(y_1, y_2, X_3).$$

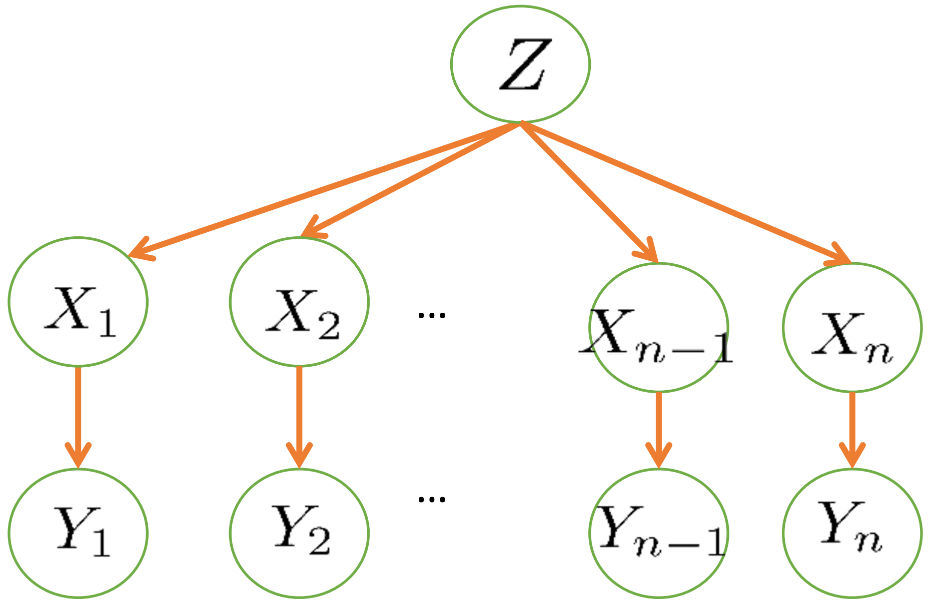
Normalizing over X_3 gives $P(X_3|y_1, y_2, y_3)$.



Computational complexity critically depends on the largest factor being generated in this process. Size of factor = number of entries in table. In example above (assuming binary) all factors generated are of size 2 --- as they all only have one parent.

Variable Elimination Ordering

- For the query $P(X_n|y_1,\ldots,y_n)$ work through the following two different orderings as done in previous slide: $Z, X_1, \ldots, X_{n-1}$ and $X_1, \ldots, X_{n-1}, Z$. What is the size of the maximum factor generated for each of the orderings?

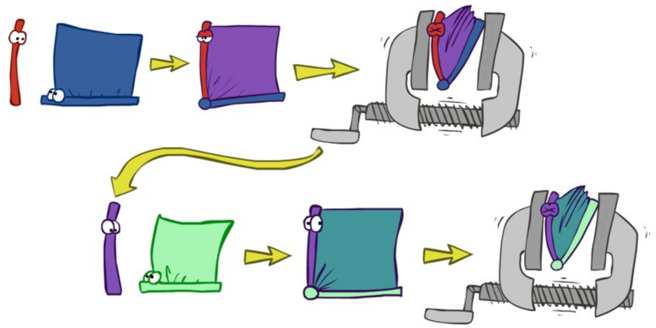


- Answer: 2^{n+1} versus 2^2 (assuming binary)
- In general: the ordering can greatly affect efficiency.

VE: Computational and Space Complexity

- The computational and space complexity of variable elimination is determined by the largest factor
- The elimination ordering can greatly affect the size of the largest factor.
  - E.g., previous slide’s example 2^n vs. 2^2
- Does there always exist an ordering that only results in small factors?
  - No!

Variable Elimination Summary



- Interleave joining and marginalizing
- d^k entries computed for a factor over k variables with domain sizes d
- Ordering of elimination of hidden variables can affect size of factors generated
- Worst case: running time exponential in the size of the Bayes' net
- Better than enumeration in practice, saves time by marginalizing variables as soon as possible rather than at the end

- Not efficient enough for big BNs, so next we'll talk about *Approximate Inference* techniques