## **Semantic Role Labeling**

## **Omar Bayoumi**

Sapienza University of Rome Natural Language Processing Homework 2

bayoumi.1747042@studenti.uniromal.it

#### 1 Introduction

In NLP, **Semantic Role Labeling** (**SRL**) is the ability to assign the semantic role that a single word plays within the sentence, such as agent, goal, or result, with the purpose of understanding the meaning of the sentence. Thus, the main goal is to associate word arguments for each predicate within a sentence. So the target tasks are: *Predicate Identification; Predicate Disambiguation; Argument Identification; Argument Classification* 

## 2 Preprocess

Reading an entry of the dataset we realize that there is a lot of information such as: *predicates*, *lemmas*, *words* and so on. We need a **preprocess**.

#### **2.1** Base

First, sentences are duplicated by creating copies as many as there are predicates, so that each copy specializes on the single predicate. Then each sentence is tokenized using the tokenizer offered by **HuggingFace** [0]. This tokenization assigns ids to words and, if necessary, divides uncommon words using as a prefix the part of the word that is very frequent in the corpus. Passing all sentences also adds padding at the end of the sentence to keep the same size as the longest sentence. In addition to this, an index array is created to identify the predicate position: if the word is a padding the index is 0; if its not a predicate the index is 1; if its a predicate the index is 2. The special sentence start/end character, padding, and the part after the first in the splitted word are considered as padding and therefore will not affect in the loss function.

## 2.2 Add the part of speech tagging (POS)

Taking all **pos\_tags** into consideration, an encoding was added to the input that tells for each word

which pos\_tag it has. For "padding" words, a special *PAD* tag was used so that it does not affect the loss function

# 2.3 Base exploiting part of speech tagging and VerbAtlas (Extra)

As an extra I integrated **VerbAtlas** within my preprocess improving the results. **VerbAtlas** is a handcrafted lexical-semantic resource whose goal is to bring together all verbal synsets from **BabelNet** into semantically-coherent frames [1].

#### 2.3.1 Add the VerbAtlas

Following the idea of *Jangseong bae and changki lee* [2], at the end of each sentence I added "[SEP]", the predicate lemma and the first two arguments of that type of predicate found in VerbAtlas. The reason why this method greatly improved the results [*Figure 1*] is mainly because at the end of the sentence there are the lemma of the predicate we are considering and more importantly the two probable roles that we will have to predict

### 3 Model

The models used are all based on a **transformer**. A transformer adopts the mechanism of **self-attention**, weighting the meaning of each part of the input. Thus, unlike a common RNN, the input is not passed one piece at a time but all at once, parallelizing and also greatly reducing the training time.

## 3.1 Base model

My basic model [Figure 6] consists of an Eembedding layer, a Transformer, a BLSTM and a Classifier. The Embedding layer aims to encode whether a given word is a predicate or not by using as input the index array described in the base preprocess [2.1 Base]. The Transformer encodes the sentence. The output of the Transformer and

**Embedding are concatenated** and passed to the BLSTM to perform further encoding of this sequence. The output of the BLSTM is passed to the classifier, which is responsible for predicting word roles for that predicate within the sentence.

## 3.2 Add the POS embedding

To the previous model, an additional Embedding layer has been added [Figure 7]. This Embedding is intended to encode the pos\_tag of each word within the sentence; the encoding at position 0 is the padding and will be ignored in the loss calculation. The idea behind it is to give additional information about the sentence to allow the model to understand the connections present in the sentence by the different pos\_tags. The output of this Embedding layer is concatenated together with the output of the Transformer and Embedding that identifies the predicate, and then everything is passed to the BLSTM and then classifier. This model was also used with the augmented input of VerbAtlas since the input is changed and not the model.

## 4 Experiments

The experiments were performed on Google Colab using the hyperparameters described in the Table 1 (step 3-4) for a specific model; looking for the best ones through a random search. The best results are reported in the various notebooks. One thing to mention is that the optimizer used was **Adam**, giving better results, most likely because Adam maintains a per-parameter learning rate that improves performances on problems with sparse gradients. Another hyperparameter I want to mention is the choice of Transformer type: tests were conducted using a case-sensitive and an uncase-sensitive version. The best results were obtained with the uncase version. Training was carried out for up to 100 epochs using the early stopping technique, and as a result training an average of 30 epochs. I also used the **dropout** with a value of, 0.5 for the BLSTM and 0.2 for the rest of the net, to try to reduce the overfitting. As loss function I used the Cross Entropy Loss. The plots Figure 8 Figure 9 Figure 10 show the loss function of the best checkpoints of the three types of models/precesses used. As can be seen, the use of VerbAtlas helped a lot in bringing down the loss function.

#### 4.1 Results

All results on the tests are shown in the evaluation.ipynb notebook. In Figure 1 are shown the results obtained from different models using different hyperparameters [Table 1] as well. As the loss function advised the model with best results is the one with VerbAtlas with a +2% for Argument Identification, but especially a +7% in Argument Classification w.r.t. the second best model. Most likely the addition at the end of the arguments recommended by VerbAtlas helped a lot to disambiguate them. Another thing to note is how the addition of POS embedding helped increase the results, even though slightly, by about 2%. Plotted in Figure 11 Figure 12 are the confusion matrices for the two tasks for the best model. One thing to note in the confusion matrix for Argument Classification is that roles such as: instrument, asset, material, time, purpose and so on, have bad results because there are few, or no, samples of that type in the train dataset. Instead, as can be seen in the confusion matrix for Argument Identification, the model was able to identify the arguments very well. Confusion matrix for Argument Identification and Argument Classification for models not using VerbAtlas are shown in Figure 13 Figure 14 (base model plus POS Embedding) Figure 15 Figure 16 (base model). As can be seen for Argument Identification, the arguments found are fewer than those found using VerbAtlas. Because of this, roles such as product and cause, with the use of VerbAtlas, go from being classified correctly almost never to being classified correctly almost always.

#### 5 Extras

As an extra, I transferred the knowledge learned from English into the other languages and implemented all four steps of the algorithm.

### 5.1 Training in other languages

First, I tried **three types** of approaches with the **Spanish dataset**; the results are shown in the *Figure 2*. The first approach was to use a model exactly identical to the one used for the English task, however, I got the worst results. This was most likely because the transformer used was specialized for the English language. Therefore, I replaced the "English" transformer with a **Multilingual** one. The results improved by about 8%. The best compromise in the end was to do **fine tuning** on the best English checkpoint, which even though it uses

an "English" transformer, is able to give the best results. This is certainly because it will split the Spanish words in such a way that the transformer will recognize them and use this information to give fairly acceptable predictions. Once I realized that the best technique is to do fine tuning from the best checkpoint, I applied this technique to all three types of models/preprocesses described earlier for both Spanish and French. All results in all languages for *Argument Identification* and *Argument Classification* are shown in *Figure 3*.

#### 5.2 The whole algorithm

The whole algorithm is based on **4 steps**: the first step deals with **finding the predicates** within the sentences; after that, knowing the position of the predicates, it is necessary to disambiguate them by making explicit what type of predicate it is; having obtained predicate position and type, we can move on to the third step in which for each predicate we have to find its arguments; and finally once the arguments have been found, we have to classify them. These steps were implemented considering the classifications made by VerbAtlas [1]. The purpose of the project was to carry out the sequences of steps 1-2-3-4, 2-3-4 and 3-4. The last one has already been described and the model used is one that exploits VerbAtlas. For the other two types of sequences it was necessary to make two models, one for step 1 and one for step 2. Since these sequences lack knowledge about predicates, it was necessary to remove from the model that realizes steps 3-4 the knowledge about pos\_tagging since at the predicates, for about 98% of the cases, there is the pos\_tag "VERB" which would be like using a ground truth.

#### 5.2.1 Model that implement step 1

The model is very similar to the others mentioned above [Figure 5]. A Transformer takes the tokenized sentence as input, without the addition of any extra structure, encoding the sentence. The output is passed to a BLSTM that encodes the sequence and then obtains a prediction through a Classifier layer. As can be seen from Figure 4, the results were excellent in all languages for the Predicate Identification task.

## 5.2.2 Model that implement step 2

The model for step two is the same as the base model [Figure 6] [3.1 Base model] since from step 1 the position of predicates is available. As can

be seen from the results in *Figure 4* the results were very good in English but not very good in the other languages. However, the results obtained in the other languages were even worse but were improved by **fine tuning from the English checkpoint**.

# 5.2.3 Results for the sequence 1-2-3-4, 2-3-4 and 3-4

Figure 4 shows the results of all sequences: 3-4, 2-3-4, 1-2-3-4. It can be seen how the influence of having predicted rather than "gold" information affects the final result. However, considering the final result I cannot say that I am not satisfied, especially for the English results to prove the fact that such an algorithm can generate excellent results for this kind of problem.

#### 6 Conclusion

In conclusion, from this project I learned how powerful the transformers tool is in terms of both efficiency and results, and how in general we train a network to analyse a sequence of data by decomposing the problem into multiple steps. By unfolding steps 1 and 2 of the algorithm, I also noticed that perhaps, making a model that realizes step 3, and later using the output of step 3 in a model that realizes only step 4, would bring better results. Considering step 1 that without any information can recognize predicates very well, there is nothing to prevent me from thinking that if I had made a network that only recognized arguments I would have gotten equally good results. Reading some papers I noticed that networks well or poorly have these structures but use very high hidden spaces with a much larger dataset. Most likely with more computing power and a dataset that explores more samples, simply increasing the number of neurons could have generated much better results.

#### References

- [0]. Hugging face community.
- [1]. Verbatlas.
- [2]. Jangseong bae and changki lee. 2022. korean semantic role labeling with bidirectional encoder representations from transformers and simple semantic information. *Applied Sciences*, 12(12).

LAWAJIACE: EN																	
	П	ARGUMENT_IDENTIFICATION								Ш	ARGUMENT_CLASSIFICATION						
														FALSE_NEGATIVES			
base_model_bert-base-cased	П	4068		499		945	e	9.8907	0.8115	0.8493		3643	924	1370	0.7977	0.7267	0.7605
base_model_bert-base-uncased	П	4120		564	I	893	e	3.8796	0.8219	0.8497	Ш	3678	1006	1335	0.7852	0.7337	0.7586
base_model_pos_hparams_1		4190		553		823	e	9.8834	0.8358	0.859		3747	996	1266		0.7475	0.7681
base_model_pos_hparams_2	Ш	3966		390		1047	e	9.9105	0.7911	0.8466	Ш	3546	810	1467	0.814	0.7074	0.757
base_model_pos_hparams_3	Ш	4280		562					0.8538				988	1159		0.7688	
base_model_pos_hparams_4	П	4212		636					0.8402			3827	1021	1186		0.7634	
base_model_pos_verbatlas	П	4378		536		635	e	8909	0.8733	0.882		4203	711	810	0.8553	0.8384	0.8468

Figure 1: Results of the three types of models/preprocesses. Highlighted in red is the **base model**, in yellow is the **base model + using pos**, in green is the **base model + using pos + VerbAtlas**. All hyperparameters are described in the Table 1.

LINEAUGE; ES																		
	Ш	ARGUMENT_IDENTIFICATION							П	ARGUMENT_CLASSIFICATION								
NAME		TRUE_POSITIVES	FALS	SE_POSITIVES	FALS	E_NEGATIVES	PRECISIO	I   RECA				TRUE_POSITIVES	FALS	E_POSITIVES	FALSE_NEGATIVES	PRECISION	RECALL	
base_model_pos_verbatlas_bert-base-multilingual-uncased		3488	ı	1288		1262	0.7303	0.73	13	0.7323		2485	I	2291	2265	0.5203	0.5232	0.5217
base_model_pos_verbatlas_bert-base-uncased		2900	ı	1314		1850	0.6882	0.61	95	0.647		2114	I	2100	2636	0.5017	0.4451	0.4717
base_model_pos_verbatlas_fine_tuning_from_english_chk		3363	ı	1026		1387	0.7662	0.7	8	<u>0.736</u>		3016	ı	1373	1734	0.6872	0.6349	0.66

Figure 2: Results in Spanish with the three different types of approaches.

				GUMENT_IDENTIFICAT					ARGUMENT_CLASSIFICATION					
NAME		TRUE_POSITIVES	FALSE_POSITIVES	FALSE_NEGATIVES				TRUE_POSITIVES	FALSE_POSITIVES	FALSE_NEGATIVES	PRECISION			
base_model_bert-base-cased		4068			0.8907	0.8115	0.8493							
base_model_bert-base-uncased					0.8796	0.8219	0.8497		1006					
base_model_pos_hparams_1					0.8834	0.8358	0.859							
base_model_pos_hparams_2				1047	0.9105	0.7911	0.8466	3546			0.814			
base_model_pos_hparams_3					0.8839	0.8538	0.8686							
base_model_pos_hparams_4					0.8688	0.8402	0.8543							
base_model_pos_verbatlas					0.8909	0.8733					0.8553	0.8384		
				GUMENT_IDENTIFICAT						ARGUMENT_CLASSIFICATION				
NAME										FALSE_NEGATIVES				
base_model_bert-base-uncased_fine_tuning_from_english_chk		2812	497	1938	0.8498		0.6979		1314	2755	0.6029		0.4951	
base_model_pos_fine_tuning_from_english_chk		2702	542	2048		0.5688			1456	2962		0.3764		
base_model_pos_verbatlas_bert-base-multilingual-uncased		3488	1288	1262		0.7343			2291	2265		0.5232		
base_model_pos_verbatlas_bert-base-uncased	Ш	2900	1314	1850	0.6882	0.6105		2114	2100	2636	0.5017	0.4451	0.4717	
base_model_pos_verbatlas_fine_tuning_from_english_chk					0.7662	0.708			1373	1734		0.6349		
				I ANGIJAGI										
	ABGIREN LIDENTIFICATION   ABGIREN CLASSIFICATION													
NAME														
base model bert-base-uncased fine tuning from english chk														
base model pos fine tuning from english chk														
base_model_pos_verbatlas_fine_tuning_from_english_chk														
base_model_pos_verbactas_tine_tuning_troil_english_chk		3336	1241	1 1408	0.7402	0.7000	0.723		1620	104/	0.0009	0.6309	0.0455	

Figure 3: Results of the three types of models/preprocesses in all language. Highlighted in red is the **base model**, in yellow is the **base model + using pos**, in green is the **base model + using pos + VerbAtlas**. All hyperparameters are described in the Table 1.

	W 11		7D 6 1	D . 1	TILL II DI CTL	B # / E 1 1# #	BOGE LIE E	m e					
Language	Model name	lr	Transformer lr	Batch	Hidden dim BLSTM	Predicate Embedding dim	POS Embedding dim	Transformer name					
	Step 1												
All	base model without predicate embedding	4e-4	4e-5	32	200	-	-	bert-base-uncased					
English	base model	1e-3	1e-4	32	200	200	•	bert-base-uncased					
Spanish/French	fine tune from english checkpoint	1e-3	1e-4	32	200	200	•	bert-base-uncased					
	Step 3-4												
English	base model hparams_1	1e-3	1e-4	80	200	128	•	bert-base-cased					
English	base model hparams_2	1e-3	1e-4	80	200	128	-	bert-base-uncased					
English	base model + POS hparams_1	1e-3	1e-4	32	200	128	128	bert-base-uncased					
English	base model + POS hparams_2	1e-3	1e-4	80	200	128	128	bert-base-uncased					
English	base model + POS hparams_3	1e-3	1e-4	32	200	200	200	bert-base-uncased					
English	base model + POS hparams_4	8e-4	1e-4	32	1600	200	200	bert-base-uncased					
English	base model + POS + VerbAtlas	1e-3	1e-4	32	200	128	128	bert-base-uncased					
Spanish/French	fine tune from base model	5e-4	5e-5	32	200	128	-	bert-base-uncased					
Spanish/French	fine tune from base model + POS hparams_3	5e-4	5e-5	32	200	200	200	bert-base-uncased					
Spanish	base model + POS + VerbAtlas hparams_1	1e-3	1e-4	32	200	128	128	bert-base-uncased					
Spanish	base model + POS + VerbAtlas hparams_2	1e-3	1e-4	32	200	128	128	bert-base-multilingual-uncased					
Spanish/French	fine tune from base model + POS + VerbAtlas	5e-4	5e-5	32	200	128	128	bert-base-uncased					

Table 1: All hparams for all models/preprocesses for all algorithm steps

		LANGUAGE: EN		
NAME	F1 SCORE PREDICATE_IDENTIFICATION	F1 SCORE PREDICATE_DISAMBIGUATION	F1 SCORE ARGUMENT_IDENTIFICATION	
Result_1234	0.9482	0.7943	0.8481	0.7808
Result_234		0.8309	0.8779	0.8072
Result_34			0.882	0.8468
		LANGUAGE: ES		
NAME	F1 SCORE PREDICATE_IDENTIFICATION	F1 SCORE PREDICATE_DISAMBIGUATION	F1 SCORE ARGUMENT_IDENTIFICATION	
Result_1234	0.9176	0.4465	0.6773	0.5078
Result_234		0.4661	0.7256	0.5422
Result_34			0.736	0.66
		LANGUAGE: FR		
NAME	F1 SCORE PREDICATE_IDENTIFICATION	F1 SCORE PREDICATE_DISAMBIGUATION	F1 SCORE ARGUMENT_IDENTIFICATION	
Result_1234	0.8821	0.4179	0.6586	0.4889
Result_234		0.4357	0.7099	0.5177
Result_34			0.723	0.6455

Figure 4: The results obtained in all languages for *Predicate Identification*, *Predicate Disambiguation*, *Argument Identification* and *Argument Classification* taking into consideration the sequences of **step 1-2-3-4**, **2-3-4 and 3-4**.

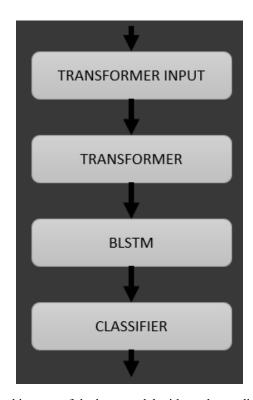


Figure 5: The architecture of the base model without the predicate Embedding.

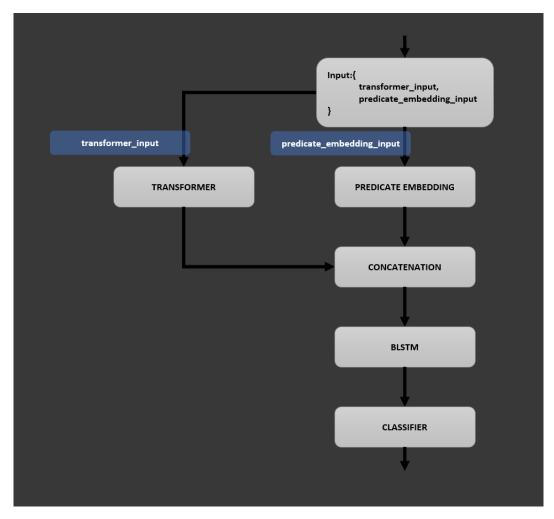


Figure 6: The architecture of the base model.

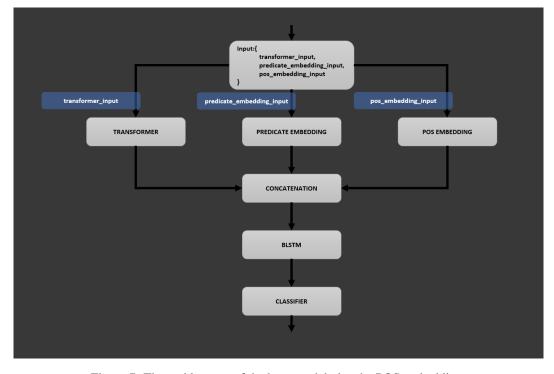


Figure 7: The architecture of the base model plus the POS embedding.

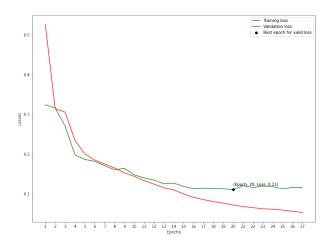


Figure 8: The loss function of the base model.

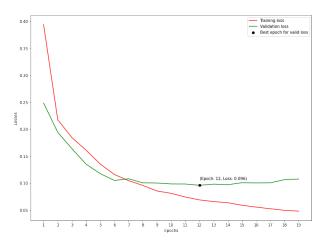


Figure 9: The loss function of the base model plus POS embedding.

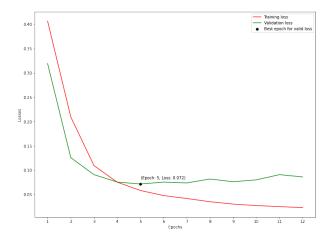


Figure 10: The loss function of the base model plus POS embedding exploiting VerbAtlas.

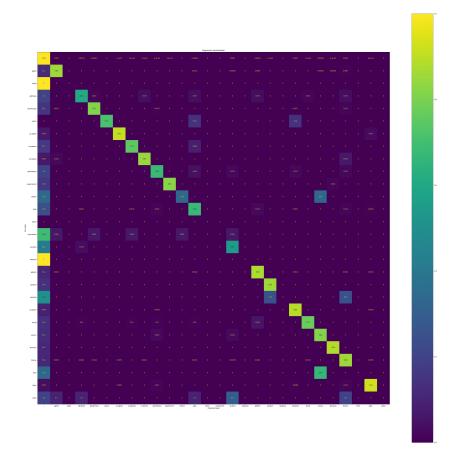


Figure 11: The confusion matrix for *Argument Classification* for the best checkpoint of the model base plus POS Embedding exploiting VerbAtlas.

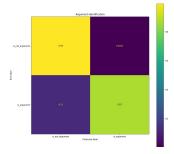


Figure 12: The confusion matrix for *Argument Identification* for the best checkpoint of the model base plus POS Embedding exploiting VerbAtlas.

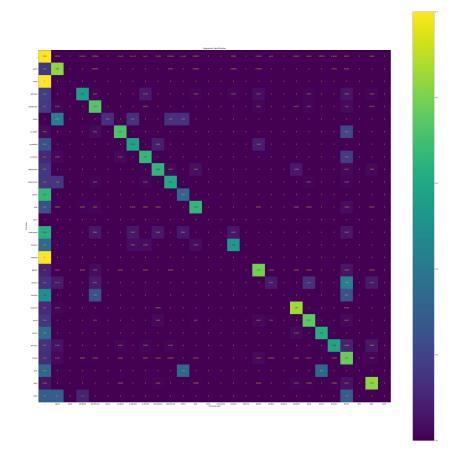


Figure 13: The confusion matrix for *Argument Classification* for the best checkpoint of the model base plus POS Embedding.

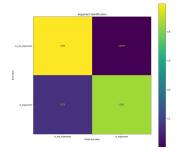


Figure 14: The confusion matrix for *Argument Identification* for the best checkpoint of the model base plus POS Embedding.

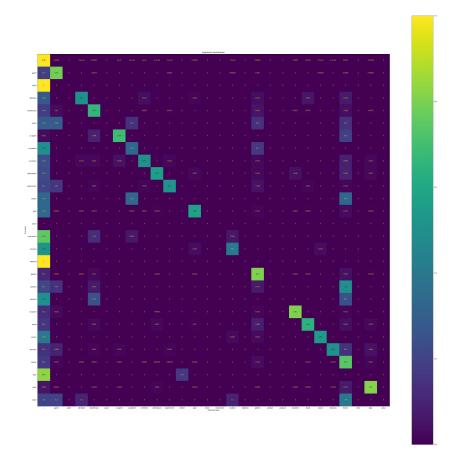


Figure 15: The confusion matrix for Argument Classification for the best checkpoint of the model base.

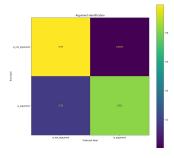


Figure 16: The confusion matrix for Argument Identification for the best checkpoint of the model base.