

# Jordan National Semiconductor Design Competition (JOSDC'2023)

MIPS single cycle 32 bit

By

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# MEET OUR TEAM



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Beyond the technical aspects, Professor Alshboul's dedication to nurturing creativity and fostering a spirit of inquiry has been truly inspirational. He has not only been a mentor but also a beacon of encouragement, instilling in me a passion for design and a commitment to excellence.

To Professor Alshboul, I extend my heartfelt appreciation for your invaluable support, guidance, and mentorship. Your influence on this project, and on my academic journey as a whole, cannot be overstated. Thank you for being the cornerstone of this achievement.

# Abstract

This project presents the design and implementation of a MIPS-based single-cycle Central Processing Unit (CPU) without branch functionality, utilizing Verilog as the primary hardware description language. The decision to exclude branch operations aims to simplify the architecture, providing an accessible model for educational purposes and foundational exploration into CPU design. The implementation focuses on core MIPS functionalities, such as arithmetic, logic, and memory operations. Through the use of Verilog, the project offers a clear and modular representation of the CPU components, facilitating understanding and potential scalability. Preliminary tests indicate that the design successfully emulates the expected operations of a MIPS single-cycle CPU, establishing it as a viable tool for educational demonstrations and further research into computer architecture. Future work may include the incorporation of the branch mechanism and the transition to a pipelined architecture for performance enhancement.

In the course of the project, special emphasis was placed on ensuring the accuracy and fidelity of the Verilog representations to the theoretical MIPS architecture. The CPU was systematically verified against a suite of benchmark programs to ensure its reliability and functionality. Additionally, the design prioritizes modularity, enabling easy future expansions or modifications. The project not only serves as a pedagogical tool but also as a foundation for more complex architectural explorations. Insights gained from this endeavor highlight the potential for creating more intricate designs, emphasizing the versatility and robustness of Verilog in modeling and simulating hardware systems.

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# Introduction

## 1.1 Introduction

In the ever-evolving landscape of computer science and engineering, the design and implementation of central processing units (CPUs) continue to be a focal point of innovation and exploration. Among the various CPU architectures, the development of a single-cycle CPU, akin to the revered MIPS (Microprocessor without Interlocked Pipeline Stages), stands as a compelling and vital undertaking. This project represents our endeavor to grasp and engineer a fundamental yet pivotal component of modern computing systems.

## 1.2 The Importance of the Design

The importance of designing and understanding single-cycle CPUs is multifaceted and integral to the field of computer science and engineering. In a world where processing power and efficiency are at the forefront of technological advancement, the design of CPUs becomes an arena where every microarchitectural decision counts. The single-cycle CPU, characterized by its simplicity and transparency, holds particular significance. It offers a clear and unambiguous model for comprehending the inner workings of a CPU. By its nature, it encapsulates the essence of instruction execution in a single clock cycle, thereby facilitating a straightforward understanding of processor operations. In this project, we dive into this simplicity to harness its educational and practical merits.

## 1.3 Motivation

The motivation behind this project stems from a shared passion for learning and a profound curiosity about the architecture of modern computers. Understanding the CPU, often referred to as the "brain" of a computer, is a fundamental step in comprehending how computers execute instructions, process data, and perform complex operations. As students in the field of computer science and engineering, our motivation is twofold. Firstly, we aim to deepen our knowledge of CPU design, enabling us to demystify the underlying mechanisms of computing systems. Secondly, we aspire to create a resource for students and enthusiasts alike to embark on a journey of discovery, employing our project as an educational tool.

## 1.4 Why This Topic is Important for Students

For students, the significance of exploring the design and implementation of a single-cycle CPU lies in the educational value it holds. It serves as a comprehensive learning experience, bridging theory and practice in the field of computer architecture. As an educational endeavor, our project offers students the opportunity to delve into the intricacies of CPU design, to comprehend the essence of instruction execution, and to witness the tangible results of their efforts. This not only enhances their academic knowledge but also fosters a deeper

appreciation for the technologies that underpin our modern world. By providing a practical and accessible entry point into CPU architecture, our project empowers students to become proficient problem solvers, critical thinkers, and innovative engineers.

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## 1.5 Objectives of the Project:

1. **Single-Cycle CPU Design:** The primary objective of this project is to design and implement a single-cycle CPU, heavily inspired by the MIPS architecture. This CPU will be capable of executing a set of fundamental instructions in a single clock cycle.
2. **Educational Resource:** We aim to create an educational resource that not only serves our learning goals but also benefits other students and enthusiasts in the field of computer science and engineering. The project aims to offer a clear, step-by-step insight into CPU design and facilitate a deeper understanding of the architectural choices involved.
3. **Comprehensive Understanding:** To achieve a comprehensive understanding of computer architecture, we will delve into the intricacies of various CPU components, including the control unit, ALU, registers, and memory hierarchy. This understanding will enable us to articulate the rationale behind design decisions.
4. **Performance Analysis:** The project seeks to analyze the performance of the single-cycle CPU in terms of execution speed, resource utilization, and comparison with other CPU architectures. This analysis will help in assessing the practical implications and limitations of the design.

## 1.6 Description of Design Achieved:

In pursuit of these objectives, we have successfully designed a single-cycle CPU model with the following characteristics:

- **MIPS-Inspired Architecture:** Our CPU design is heavily influenced by the MIPS architecture, renowned for its simplicity and elegance. This architecture served as a valuable reference point in shaping our CPU's instruction set, control unit, and data path.
- **RISC (Reduced Instruction Set Computer) Principles:** Our CPU follows the RISC principles by focusing on a limited set of simple and frequently used instructions. This design choice enhances the CPU's efficiency and ease of understanding.
- **Single-Cycle Execution:** Our CPU is designed to execute instructions in a single clock cycle. This efficient one-cycle process involves fetching instructions, decoding them, executing operations, and writing results back to registers.
- **Control Unit:** We have implemented a control unit that generates control signals to direct the CPU's operations based on the current instruction. This control unit is responsible for managing the flow of data within the CPU.

- **ALU and Registers:** The Arithmetic Logic Unit (ALU) performs arithmetic and logical operations, while the registers store data. Our CPU features a specific number of registers, and the ALU is capable of executing a variety of operations.
- **Memory Hierarchy:** We have incorporated a memory hierarchy with separate instruction and data memory. This design choice aligns with modern CPU architectures and offers an accurate representation of how instructions and data are stored and accessed.

## 1.7 Design Requirements:

Our CPU design adheres to the following key requirements:

- **Simplicity:** The design should prioritize simplicity and clarity to serve as an educational tool. It should be comprehensible to students and enthusiasts with a basic understanding of digital logic and computer architecture.
- **One-Cycle Execution:** All instructions should be executed in a single clock cycle, reflecting the core concept of a single-cycle CPU.
- **Instruction Set:** The CPU should support a defined instruction set, inspired by the MIPS architecture. This instruction set should include fundamental operations such as arithmetic, logic, and data movement instructions.
- **Efficiency:** The design should strive for efficiency by optimizing the use of resources and minimizing redundancy.

## 1.8 The team's member responsibility

# TIMELINE DIAGRAM

## week one



### Project Kickoff

In this phase, the project team convened for a crucial kickoff meeting to initiate the MIPS processor design project. The primary objective of the meeting was to define the project's scope, objectives, and requirements, and to assign specific tasks and responsibilities to each team member.

## week two



### Development Core Modules

In this phase, the project team focused on the creation of the essential core modules that make up the MIPS processor. These modules are the building blocks of the processor's functionality. The development and optimization of these core modules are crucial to the overall success of the MIPS processor design project.

## week three



### Integration The Modules

In this phase, the project team concentrated on the process of connecting and interconnecting the individual core modules designed for the MIPS processor. This stage involves integrating the ALU (Arithmetic Logic Unit), control unit, register file, and other essential modules to create a cohesive and functioning processor unit.

## week four



### Testing and Report Generation

This involved comprehensive testing, debugging, and verification of the functionality and performance of each module. Subsequently, the team compiled their findings and results into a detailed report. The report provides an assessment of the module performance, highlights any issues or improvements needed, and serves as a crucial document for tracking the progress and quality of the design project.

### 1.8.1 Omar AL-khasawneh (Leader)

- ALU design
- ALU control design
- PC design
- Writing report

### 1.8.2 Omar AL-salah

- Register file
- Control unit

### 1.8.3 Moayyad Abu Mallouh

- Instruction memory
- Data memory
- Mux between component

## 1.9 Organization of the rest of the documentation.

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- AluControl.v
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- 5bit\_Decoder.v
- 5bit\_Mux.v

## REFERENCES

- Instruction set Architecture.txt
- JoSDC\_CPU\_reference\_Design\_Guidelines.pdf

02

## TEST BENCHES

- PC\_tb.v
- ALU\_tb.v
- INS\_MEM\_tb.v
- RAM\_tb.v
- Control\_Unit\_tb.v
- Main\_tb.v
- AluControl\_tb.v
- SignExtend\_tb.v
- 5bit\_Decoder\_tb.v
- 5bit\_Mux\_tb.v

## SIMULATION

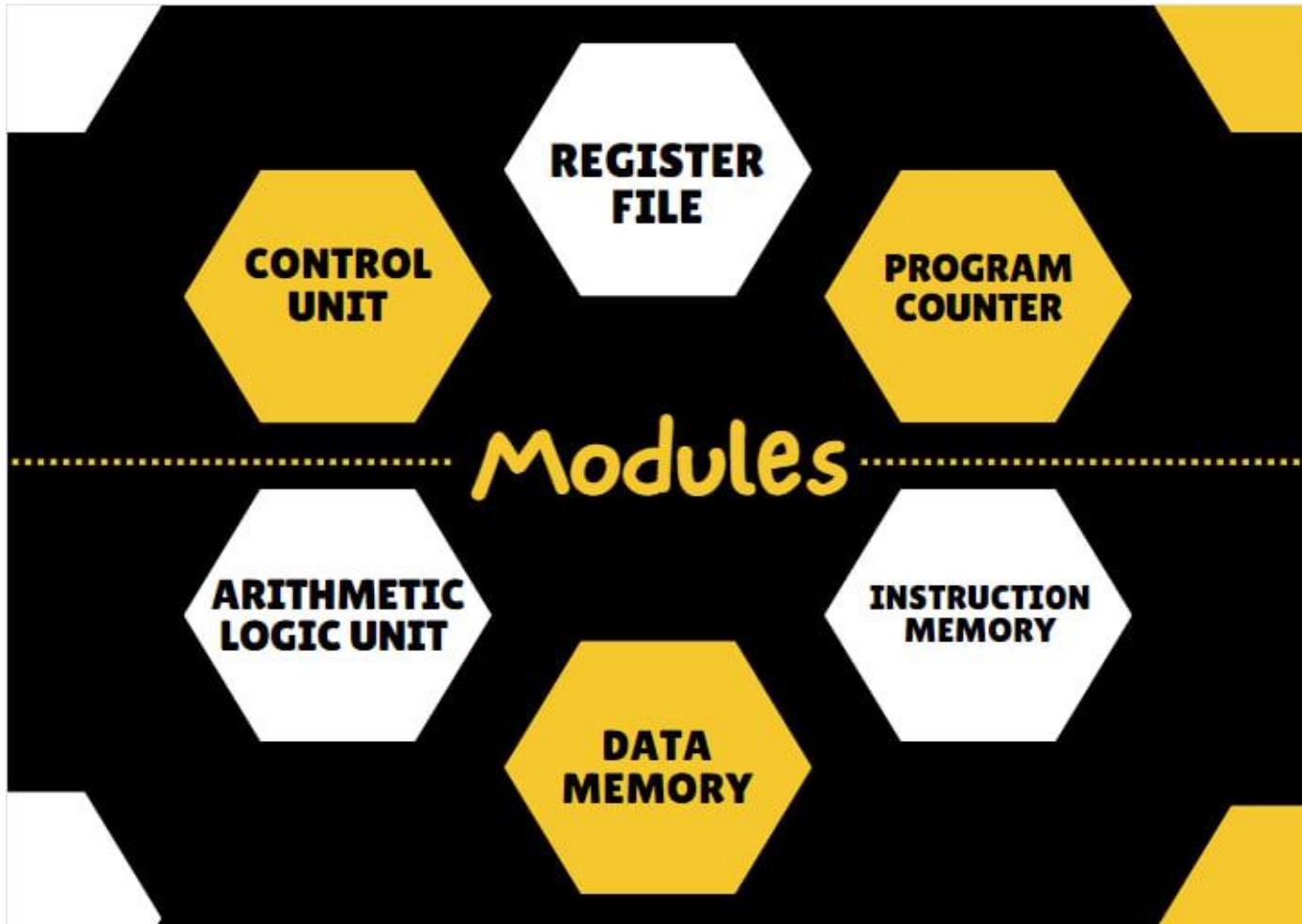
- Program Flow
- load Instruction Flow
- Graphs
- statistics

04

Design

## 1.10 Hardware Design and Implementation

We are used this component in our project:



- Describe the hardware design and components used.

### 1.10.1 Component

**Data Memory :** in the context of computer architecture and digital systems, is a component that stores and retrieves data during the execution of programs. It serves as a storage medium for variables, arrays, and other data structures used by a computer's central processing unit (CPU) to perform calculations and operations.

**Instruction memory:** also known as the Instruction Cache or Code Memory, is a component in a computer's architecture that stores the machine code instructions that the CPU (Central Processing Unit) fetches, decodes, and executes to perform various tasks and operations. These instructions are part of the computer program or software being run on the CPU. Instruction memory is essential for the operation of a computer because it holds the program's instructions in a format that the CPU can understand and execute sequentially.

**Arithmetic logic unit:** is a crucial component of a computer's central processing unit (CPU). It performs arithmetic and logic operations on data, such as addition, subtraction, multiplication, division, and comparisons.

The ALU is designed to perform a variety of arithmetic and logical operations, dictated by a 4-bit control signal (ALUControl). It processes 32-bit inputs (A and B), handling basic arithmetic operations like addition, subtraction, multiplication, and division, as well as logical operations including AND, OR, XOR, and NOR. Additionally, it supports shift operations (logical left and right shifts) which are controlled by a 5-bit shift amount.

One of the notable features of this ALU is its ability to respond to different branch types, determined by a 3-bit signal (branch\_type). This enables the ALU to participate in decision-making processes, fundamental in computational logic, by setting a Zero flag based on specific conditions (like equal, not equal, greater than, or less than comparisons).

Furthermore, the ALU includes an internal mechanism to handle overflow and carry-out scenarios, which are critical in signed arithmetic operations. These scenarios are managed through dedicated blocks that set the Overflow and CarryOut flags under specific conditions, like during addition or subtraction when the sign bit (most significant bit) might be incorrectly set or unset due to the arithmetic operation.

Overall, this ALU module illustrates the complexity and versatility of digital logic designs in performing essential computational tasks. It is a quintessential example of how various arithmetic and logical operations are implemented at a hardware level in computing systems.

**Program counter :** also known as the instruction pointer (IP) in some architectures, is a special-purpose register in a computer's central processing unit (CPU). It holds the memory address of the next instruction to be fetched and executed in a program. The PC is automatically incremented after each instruction is fetched, allowing the CPU to sequence through the program's instructions in order.

**we use state machine to make the design better and easy to upgrade .**

**Register file:** is a collection of registers that are used for temporary data storage and manipulation within a central processing unit (CPU). Registers are small, high-speed storage locations that are an integral part of the CPU. They store operands, intermediate results, and control information needed for executing instructions.

The Register File module stands as a cornerstone in the MIPS architecture, and in our CPU design, we have meticulously crafted a RegisterFile module to fulfill the essential role of managing registers efficiently. The module declaration encompasses standard signals, aligning with the MIPS

convention, including Clock, ReadReg1, ReadReg2, WriteReg, WriteData, Reg write Control, ReadData1, and ReadData2.

Our design extends beyond the conventional MIPS Register File by incorporating additional signals to tailor the functionality to our specific requirements:

### **Reset Signal:**

The Reset signal serves as a mechanism to reset all registers to a don't care (rubbish value) when activated. This feature ensures a clean and controlled initialization, contributing to the reliability and predictability of the system.

### **PC\_Store Signal:**

The PC\_Store signal is a custom addition to our Register File module, specifically designed to interact with register number 31. This signal, initiated by the control unit, enables register 31 to store a value from the write bus. The stored value represents the program counter value and plays a crucial role in the execution of instructions that involve branching, such as Jump And Link and Jump And Link Register.

In addition to these custom signals, we have implemented special-purpose registers to enhance the versatility and efficiency of the Register File:

### **First Register (Register Number 0):**

This register is designed to always maintain a value of zero. It serves as a constant reference point and is exclusively readable. No instruction is permitted to write to this register, ensuring its consistency as a zero value register.

### **Last Register (Register Number 31):**

Register 31 has been specially configured to serve a unique purpose in our design. It is enabled by the PC\_Store signal from the control unit, allowing it to store the program counter value. This functionality is essential for instructions like Jump And Link and Jump And Link Register, where the program counter value is stored in register 31, facilitating the management of subroutine calls and returns.

By incorporating these features, our Register File module not only adheres to MIPS standards but also offers enhanced functionality and customization tailored to the specific requirements of our CPU design

**Control unit:** is a crucial component of a computer's central processing unit (CPU) or any computational device. It coordinates the activities of all the other hardware components in the system. Essentially, the control unit fetches instructions from memory and decodes and executes them, sending signals to the other components of the computer to control data flow and processing operations. It acts as a central manager, directing the operation of the processor and its interaction with other hardware components.

The control unit serves as the central intelligence of our CPU design, acting as the pivotal module that orchestrates the various operations within the processor. At the core of this module lies the ControlUnit entity, taking essential input signals such as Clock, Reset, opcode, RegDst, ALUSrc, MemtoReg, MemWrite, MemRead, ALUOp, RegWrite, Branch, Jump, funct, pc\_load, and PC\_Store.

In aligning with the standard MIPS architecture, we have implemented familiar control signals such as Clock, RegDst, ALUSrc, MemtoReg, MemWrite, MemRead, ALUOp, RegWrite, Branch, Jump, and funct. These signals are crucial for directing the flow of data and control within the CPU.

Additionally, we have introduced new signals to tailor our design for specific functionalities:

### **Reset Signal:**

The Reset signal serves as a mechanism to reset the control unit, initiating a no-operation (nop) instruction. This feature ensures a controlled start or restart of the CPU, enhancing the robustness and reliability of the system.

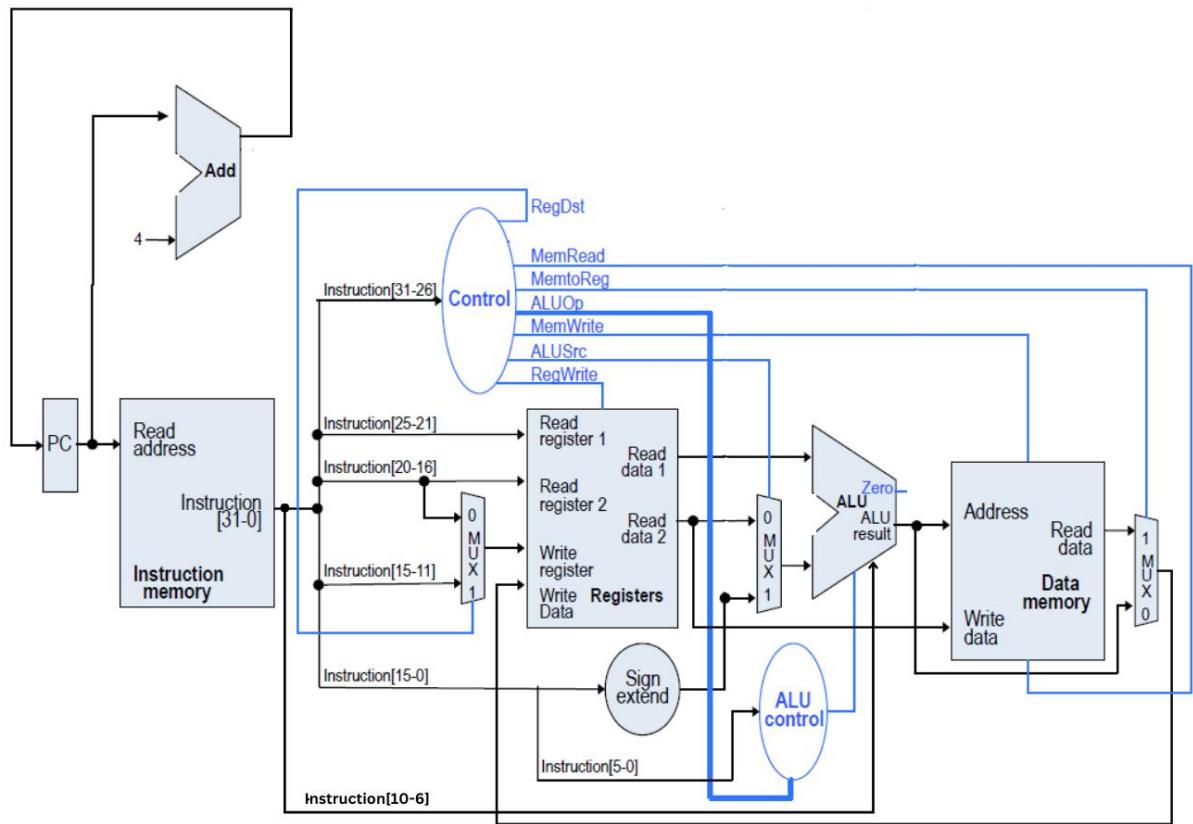
### **PC\_Store Signal:**

The PC\_Store signal is a unique addition designed to interact with the register file. Its purpose is to enable the register associated with register 31 to store a specific value. This value corresponds to the current program counter value that we intend to preserve. This feature allows for strategic storage of program counter values for future reference or manipulation.

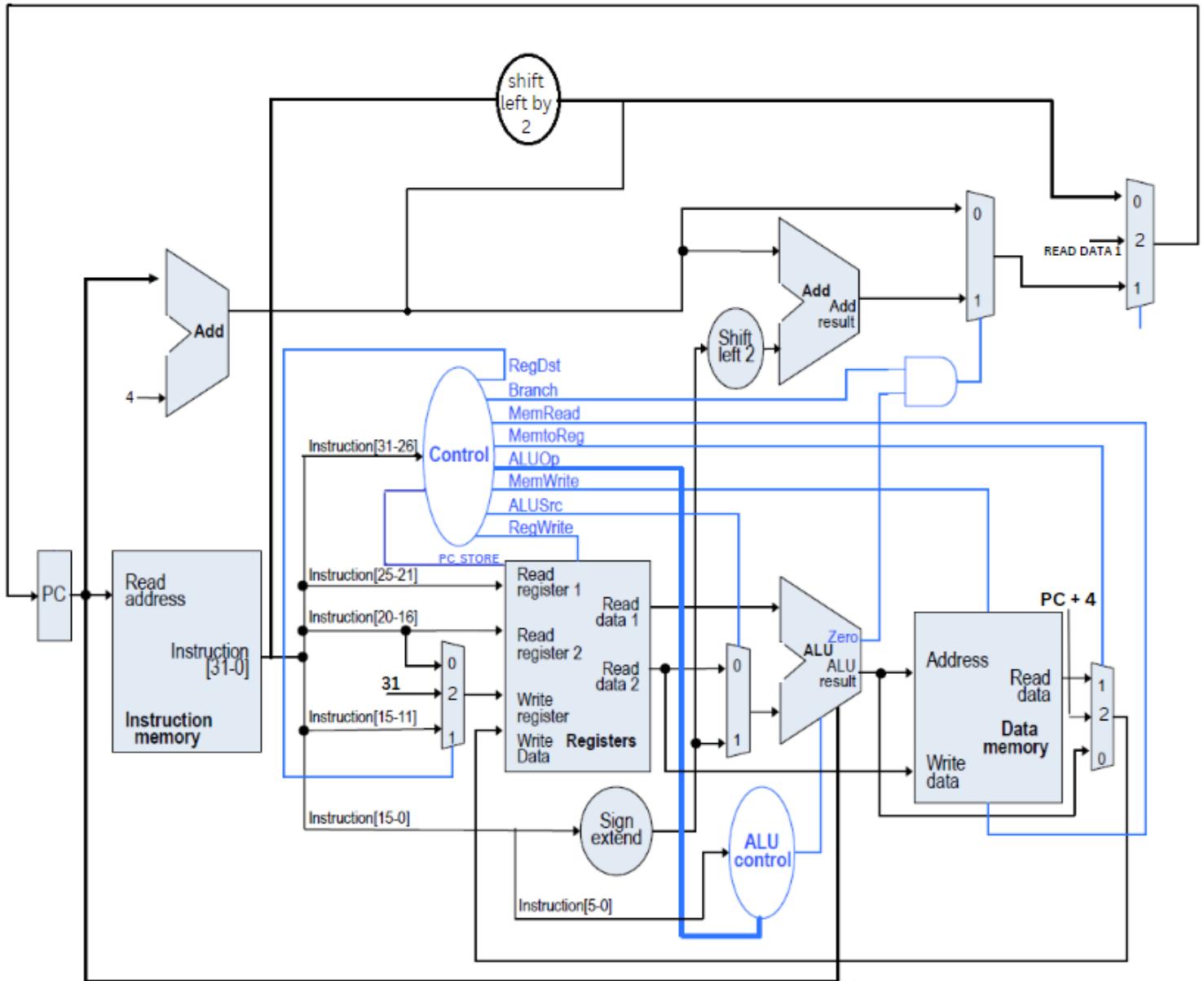
By incorporating these new signals, our control unit not only adheres to established MIPS standards but also offers a level of customization that enhances the adaptability and efficiency of our CPU design. The combination of standard and bespoke control signals ensures a versatile and finely-tuned control mechanism, making our CPU well-suited for a variety of computing tasks.

## 1.11 MIPS DATAPATH

### 1.11.1 Before – phase1



### 1.11.2 now



## 1.12 mips instruction execution phase

## MIPS INSTRUCTION EXECUTION PHASES

INSTRUCTION	IF	ID	EX	MEM	WB
ADD	✓	✓	✓		✓
SLL	✓	✓	✓		✓
SW	✓	✓	✓	✓	
LW	✓	✓	✓	✓	✓

### 1.13 Coding and Software Development

#### 1.13.1 Tools

In the development and verification of our single cycle CPU, we employed a combination of industry-standard tools to ensure accuracy, efficiency, and compatibility. We used **Verilog** as our hardware description language, a popular choice for its expressive syntax and powerful capabilities in modeling complex digital systems. Verilog facilitated a clear representation of our design, allowing for systematic testing and debugging of individual modules and their integration. Complementing this, **Quartus** served as our primary platform for synthesis, placement, routing, and simulation. Its comprehensive suite of tools enabled us to transform our Verilog code into gate-level representations, ensuring that our design meets the desired performance and resource criteria. Furthermore, Quartus provided a conducive environment for iterative design optimization, ensuring that our CPU design was not only functional but also efficient in terms of resource usage and speed. The synergy between Verilog and Quartus was instrumental in realizing a robust and reliable single cycle CPU.

#### 1.13.2 Challenging

1. We face challenges due to limited online learning resources and the complexities of optimization. To address this, we seek guidance from our university professors.
2. We improved the performance of our design by 1. increasing the clock speed and 2. minimizing the area.
3. Detecting overflow in the ALU and providing the correct overflow output, **Detection of Overflow in the ALU**:

- **For Addition:**
  - Overflow occurs if:
    - Both operands are positive, but the result is negative.
    - Both operands are negative, but the result is positive.
  - In terms of bit operations, consider the sign bits (most significant bit, MSB) of operands A and B and the result R. Overflow is detected if:
    - A's MSB is 0, B's MSB is 0, but R's MSB is 1.
    - A's MSB is 1, B's MSB is 1, but R's MSB is 0.
- **For Subtraction:** Since subtraction is the same as adding a negative number in two's complement arithmetic, the rules for addition apply here too.

### **Handling Overflow in the ALU:**

- **Overflow Flag:** The ALU can set an overflow flag (often denoted as the 'V' flag in many architectures) whenever overflow occurs. This flag can be checked by subsequent instructions, and based on its value, certain actions can be taken, such as branching to error-handling routines.

#### **1.13.3 Biggest challenge**

### **Timing Violation in MIPS 32-bit Architecture Single Cycle CPU**

A timing violation in a MIPS 32-bit architecture single cycle CPU occurs when a signal does not arrive at its destination within the required time window. This can happen for a number of reasons, including:

- Clock skew: Clock skew is the variation in the arrival time of the clock signal at different parts of the CPU. This can be caused by differences in the length of the clock wires or by variations in the manufacturing process.
- Hold time violation: A hold time violation occurs when a signal does not remain stable for the required amount of time before the clock edge. This can be caused by a slow signal driver or by a long signal path.
- Setup time violation: A setup time violation occurs when a signal does not arrive at its destination within the required amount of time before the clock edge. This can be caused by a fast signal driver or by a short signal path.
- Glitches: A glitch is a short-duration, spurious pulse that can occur on a signal line. Glitches can be caused by noise or by crosstalk between signal lines.

## Types of Timing Violations

There are two main types of timing violations:

1. Combinational timing violations: Combinational timing violations occur in combinational logic circuits, such as adders and multipliers. These circuits are designed to produce an output signal within a certain amount of time after the input signals arrive. If the input signals do not arrive within the required time window, or if the circuit is not designed properly, the output signal may not be correct.
2. Sequential timing violations: Sequential timing violations occur in sequential logic circuits, such as registers and flip-flops. These circuits are designed to store a state signal and then update it on the next clock edge. If the clock edge arrives before the state signal has settled, or if the circuit is not designed properly, the state signal may not be updated correctly.

## Consequences of Timing Violations

Timing violations can lead to a number of problems, including:

Incorrect results: Timing violations can cause the CPU to produce incorrect results. This can lead to errors in programs and data corruption.

System instability: Timing violations can cause the CPU to become unstable. This can lead to system crashes and other problems.

Increased power consumption: Timing violations can cause the CPU to consume more power. This can lead to overheating and reduced battery life.

### Preventing Timing Violations

There are a number of things that can be done to prevent timing violations, including:

Careful design: The CPU should be designed carefully to minimize clock skew and signal path delays.

Use of buffers: Buffers can be used to reduce signal path delays.

Use of clock gating: Clock gating can be used to disable the clock to unused circuits, which can reduce power consumption and improve timing performance.

Testing: The CPU should be thoroughly tested to ensure that it meets all timing requirements.

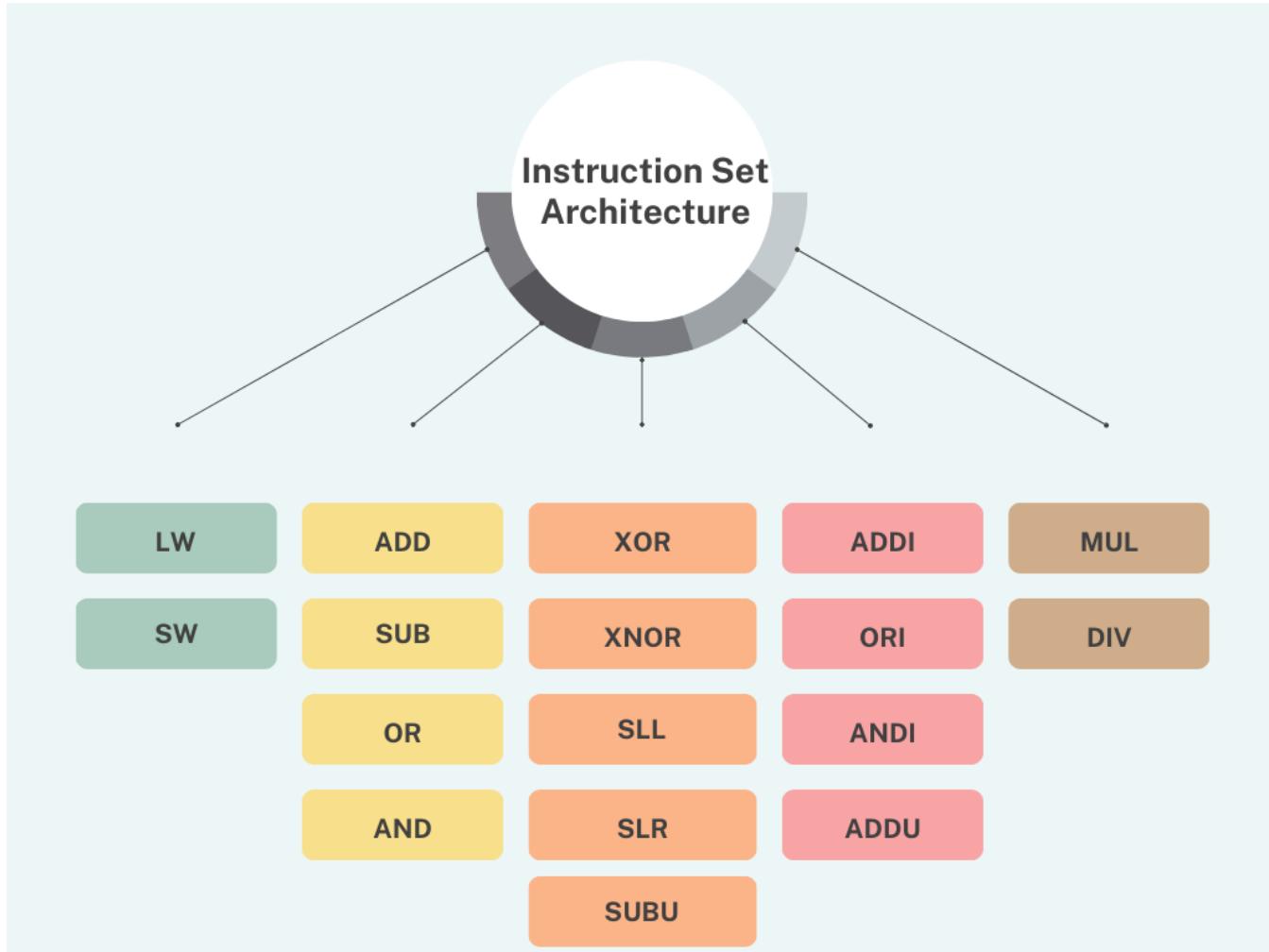
### Conclusion

Timing violations are a serious problem in MIPS 32-bit architecture single cycle CPUs. They can lead to incorrect results, system instability, and increased power consumption. There are a number of things that can be done to prevent timing violations, including careful design, the use of buffers, clock gating, and testing.

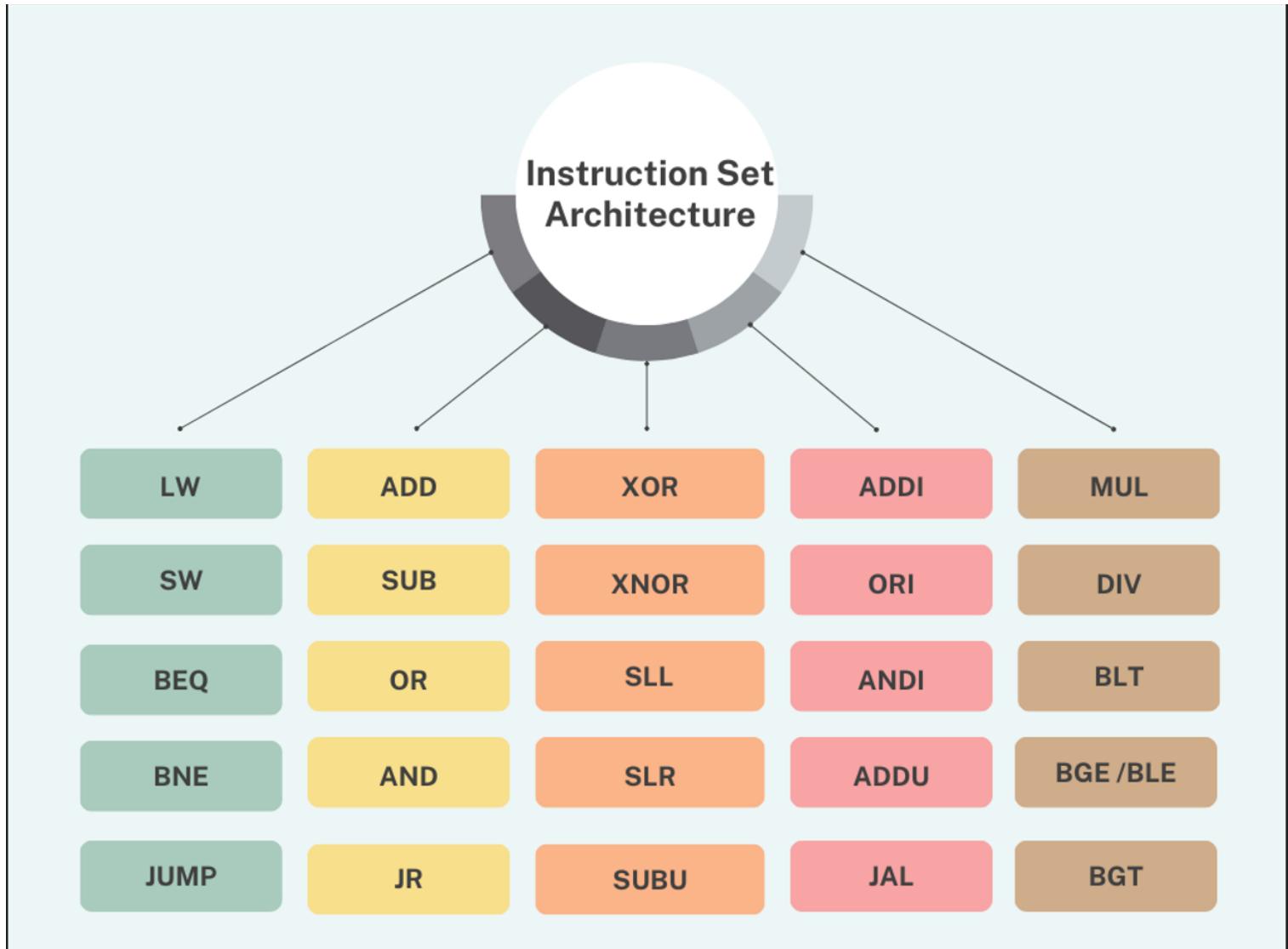
#### 1.13.4 Instruction set architecture

The our instruction set architecture, it will improve in the future.

#### 1.13.4.1 Before (phase one)



#### 1.13.4.2 Now -phase two



## Results

#### 1.14 Benchmark

### 1.14.1 Test case one

#### 1.14.1.1 Instruction memory and data memory

//-----

// testcase 1

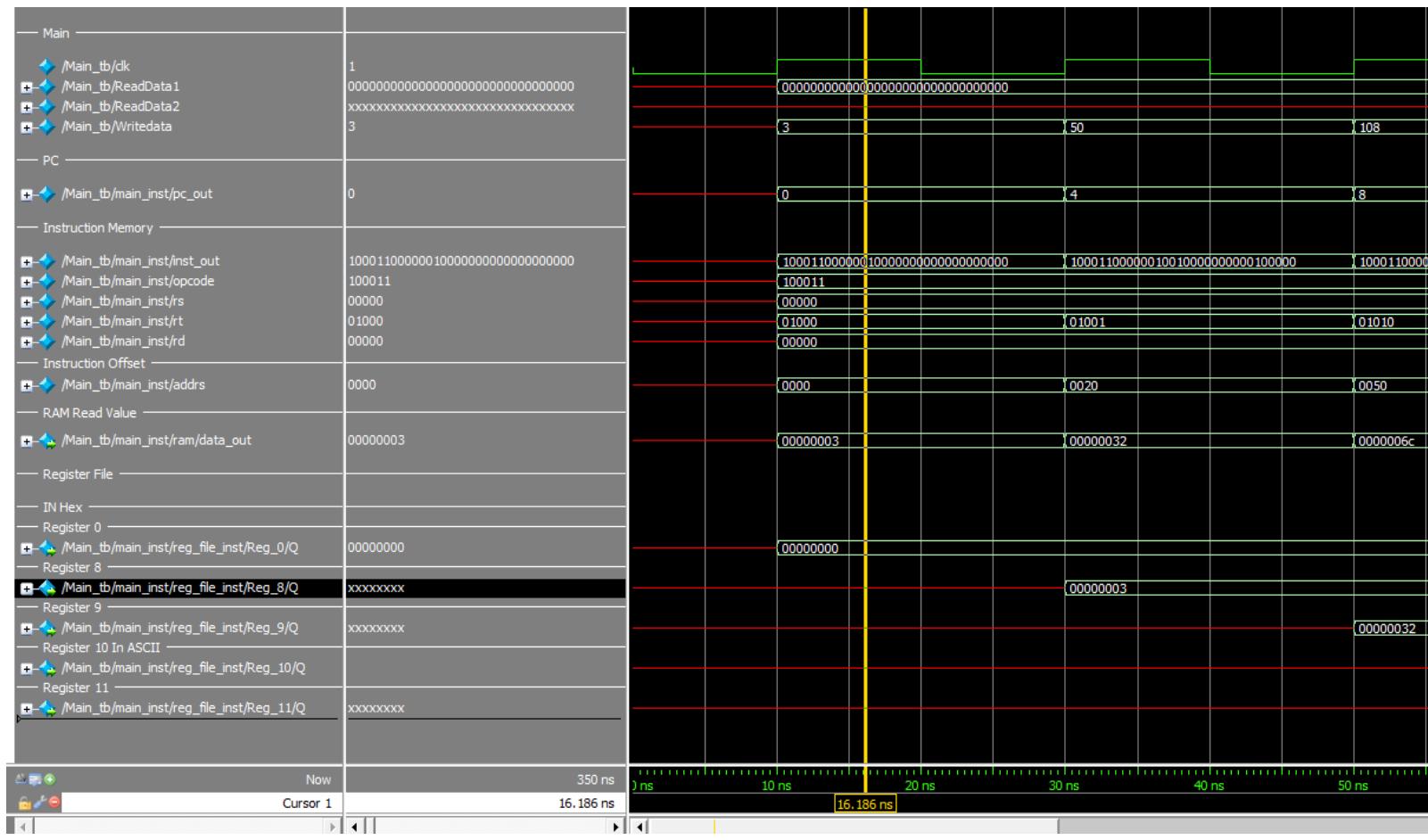
```
inst_mem[0] = 32'b10001100000010000000000000000000; //LW R8, 0(R0)
inst_mem[1] = 32'b10001100000010010000000000100000; //LW R9, 0x20(R0)
inst_mem[2] = 32'b100011000000101000000000001010000; //LW R10, 0x50(R0)
inst_mem[3] = 32'b10001100000010110000000000001000; //LW R11, 0x8(R0)
```

//-----

// testcase 1

```
mem[0] = 32'h00000003;
mem[1] = 32'h00000008;
mem[2] = 32'h00000005;
mem[3] = 32'h00000002;
mem[4] = 32'h00000032;
mem[5] = 32'h00000032;
mem[6] = 32'h00000032;
mem[7] = 32'h00000032;
mem[8] = 32'h00000032;
mem[9] = 32'h00000032;
mem[10] = 32'h00000032;
mem[11] = 32'h00000032;
mem[12] = 32'h00000032;
mem[13] = 32'h00000032;
mem[14] = 32'h00000032;
mem[15] = 32'h00000032;
mem[16] = 32'h00000032;
mem[17] = 32'h00000068;
mem[18] = 32'h00000065;
mem[19] = 32'h0000006C;
mem[20] = 32'h0000006C;
mem[21] = 32'h0000006F;
mem[22] = 32'h00000000;
```

### 1.14.1.2 First interaction *LW R8, 0(R0)* (CPU before execution)



pc\_out=> current value of pc

Pc\_next=> the next pc

Data\_out=> read data from RAM

We have 32 registers , we only show the register the related to instruction .

The value save in register or memory in next positive edge .

The image contains Verilog code that appears to be initializing an instruction memory array with a set of instructions, denoted as **inst\_mem**. Each line of the code assigns a 32-bit binary value to a different index in the **inst\_mem** array, which corresponds to a machine instruction. The comments at the end of each line provide a human-readable interpretation of each instruction.

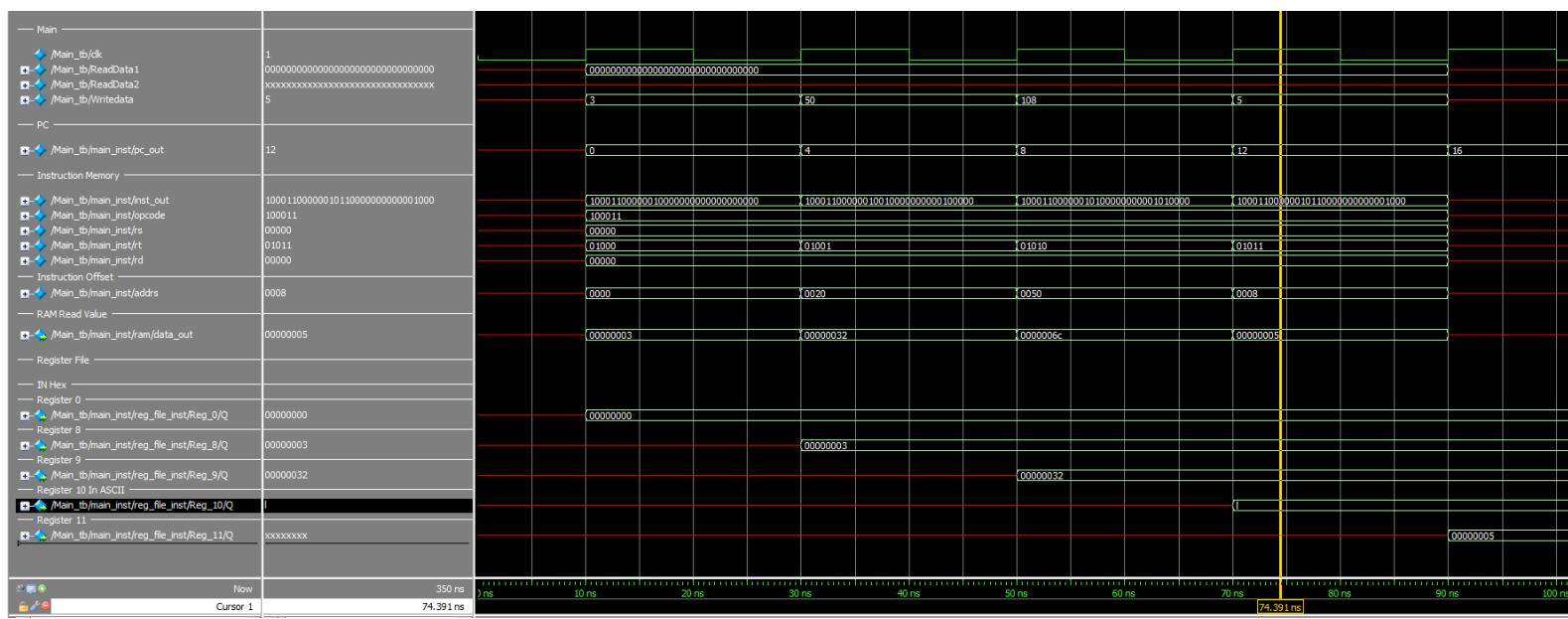
Here is a description of the instructions as per the comments:

- **inst\_mem[0]**: This instruction loads a word into register 8 from the memory address contained in register 0 (R0) with no offset. The comment **//LW R8, 0(R0)** stands for "Load Word" into R8 from the address **0 + (contents of R0)**.

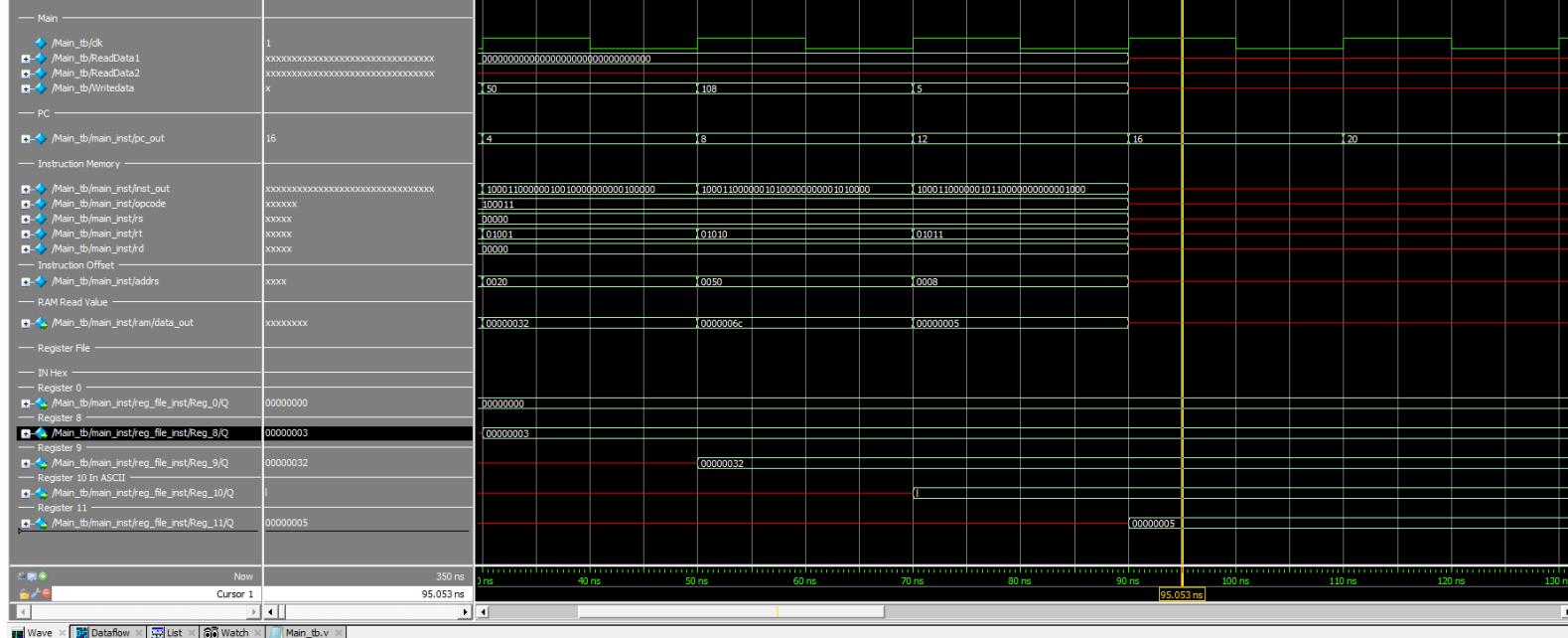
- **inst\_mem[1]**: This instruction loads a word into register 9 from the memory address contained in register 0 (R0) with an offset of 0x20. The comment **//LW R9, 0x20(R0)** means "Load Word" into R9 from the address **0x20 + (contents of R0)**.
- **inst\_mem[2]**: This line loads a word into register 10 from the memory address contained in register 0 (R0) with an offset of 0x50. The comment **//LW R10, 0x50(R0)** signifies "Load Word" into R10 from the address **0x50 + (contents of R0)**.
- **inst\_mem[3]**: This instruction loads a word into register 11 from the memory address contained in register 0 (R0) with an offset of 0x80. The comment **//LW R11, 0x80(R0)** indicates "Load Word" into R11 from the address **0x80 + (contents of R0)**.

Each **inst\_mem** entry is a 32-bit binary value representing the opcode and the operand(s) for the corresponding load instruction. The opcode determines the type of operation to be performed, and the operands specify the registers and memory addresses involved in the operation. The binary values are likely encoded according to a specific instruction set architecture, which dictates the format of the binary instruction (such as opcode, source register, destination register, and immediate values or offsets).

### 1.14.1.3 Third instruction LWR10, 0x50(r0)



after execution the final values



## 1.15 Test case 2

### 1.15.1 Data memory and instruction memory

// testcase 2

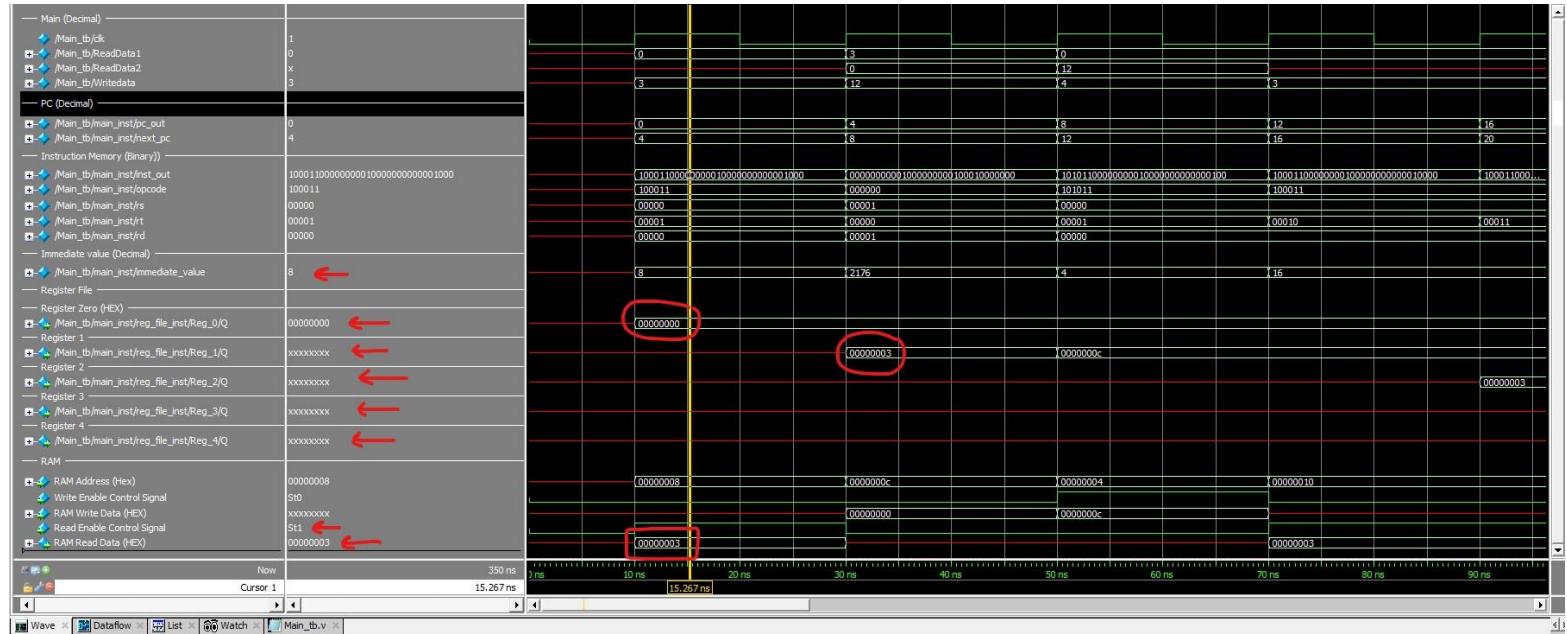
```
inst_mem[0] = 32'b100011000000000010000000000001000; //LW R1, 8(R0)
inst_mem[1] = 32'b00000000000100000000010001000000; //SLL R1, R1, 2
inst_mem[2] = 32'b10101100000000010000000000000100; //SW R1, 4(R0)
inst_mem[3] = 32'b10001100000000010000000000000100; //LW R2, 4(R0)
inst_mem[4] = 32'b100011000000000110000000000001000; //LW R3, 16(R0)
inst_mem[5] = 32'b00000000001000000000110000100000; //SLL R3, R2, 1
inst_mem[6] = 32'b101011000000000110000000000001100; //SW R3, 12(R0)
inst_mem[7] = 32'b100011000000000100000000000001100; //LW R4, 12(R0)
```

//-----

```
//testcase 2  
mem[0] = 32'b00000000000000000000000000000000; // 32'b00000000000000000000000000000000  
mem[1] = 32'b00000000000000000000000000000000; // 32'b00000000000000000000000000000000  
mem[2] = 32'b00000000000000000000000000000000; // 32'b00000000000000000000000000000000  
mem[3] = 32'b00000000000000000000000000000000; // 32'b00000000000000000000000000000000  
mem[4] = 32'b00000000000000000000000000000000; // 32'b00000000000000000000000000000000
```

/\*

### 1.15.2 First instruction LW R1 ,8(R0)



## Test Case 2: Array Operations on DATA Memory

This test case demonstrates how to manipulate array elements using data memory and instructions like LW, SLL, and SW

## Description/C Code:

**Declare an array a of size 5 → a[4] = a[3] = a[2] = a[1] = a[0] = 0x3**

execute  $a[1] = a[2] * 4$

execute  $a[3] = a[4] * 2$

DATA Memory is initialized with 5 words, each having a value of 0x3.

Instructions:

Instruction 1 (PC=0): LW R1, 8(R0)

Purpose: Load the value from memory location 8 ( $a[2]$ ) into register R1.

Result:  $R1 = a[2] = 0x3$ .

Instruction 2 (PC=4): SLL R1, R1, 2

Purpose: Multiply the value in register R1 by 4 (left shift by 2).

Result:  $R1 = 0xC$ .

Instruction 3 (PC=8): SW R1, 4(R0)

Purpose: Store the value in register R1 (0xC) into memory location 4 ( $a[1]$ ).

Result:  $a[1] = a[2] * 4$  is executed.

Instruction 4 (PC=12): LW R2, 16(R0)

Purpose: Load the value from memory location 16 ( $a[4]$ ) into register R2.

Result:  $R2 = a[4] = 0x3$ .

Instruction 5 (PC=16): LW R3, 16(R0)

Purpose: Load the value from memory location 16 ( $a[4]$ ) into register R3 (duplicated, no change).

Result:  $R3 = a[4] = 0x3$  (no change from the previous instruction).

## Instruction 6 (PC=20): SLL R3, R2, 1

Purpose: Multiply the value in register R2 by 2 (left shift by 1) and store it in R3.

Result:  $R3 = a[4] * 2$ .

## Instruction 7 (PC=24): SW R3, 12(R0)

Purpose: Store the value in register R3 into memory location 12 (a[3]).

Result:  $a[3] = a[4] * 2$  is executed.

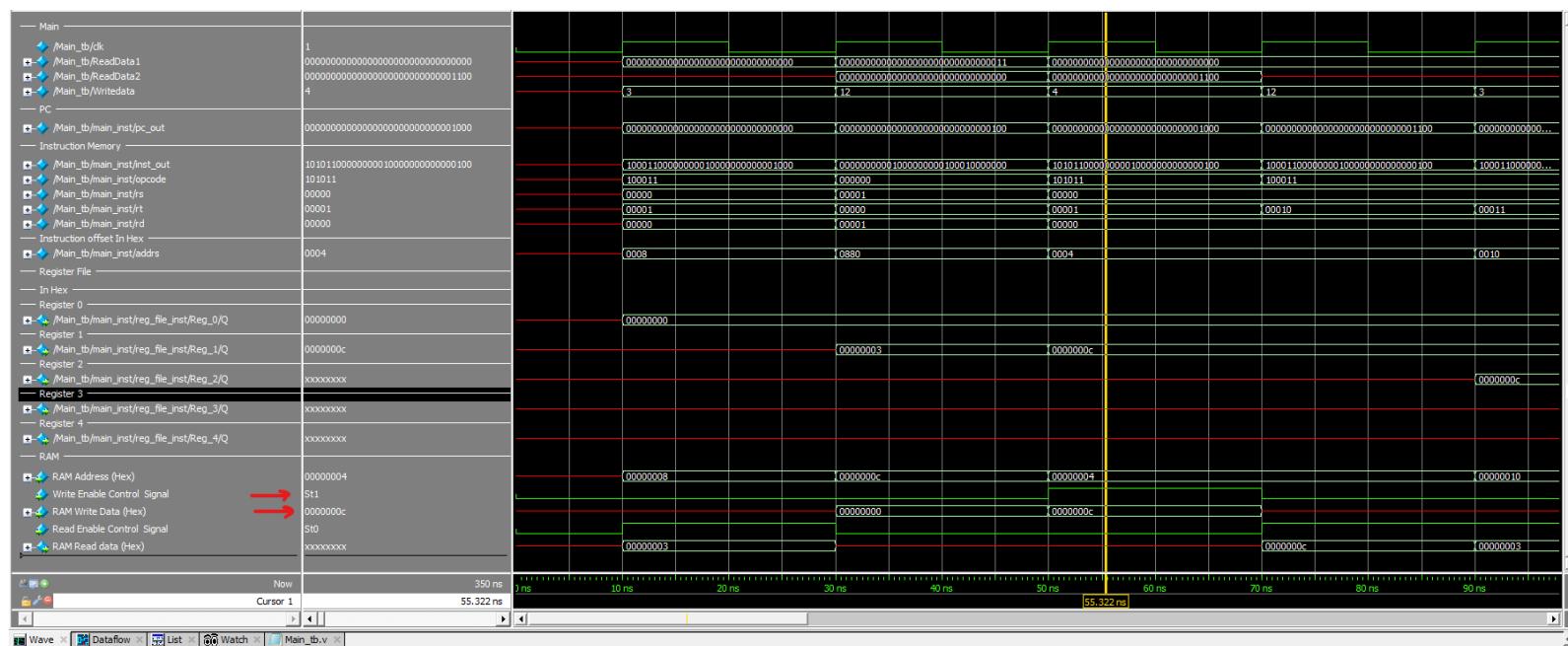
## Instruction 8 (PC=28): LW R4, 12(R0)

Purpose: Read from memory location 12 (a[3]) and store it in register R4.

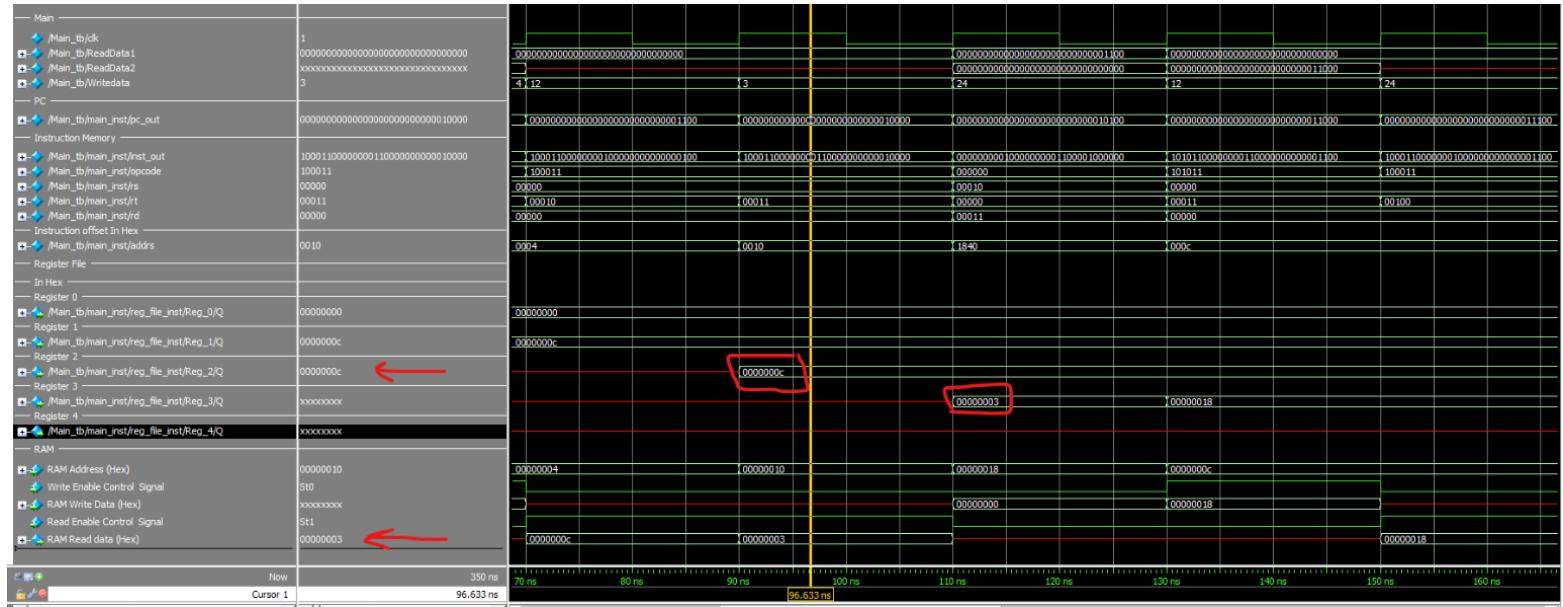
Result:  $R4 = a[3]$

### 1.15.3 Third instruction SW R1, 4(R0)

Please look careful for read color in the image

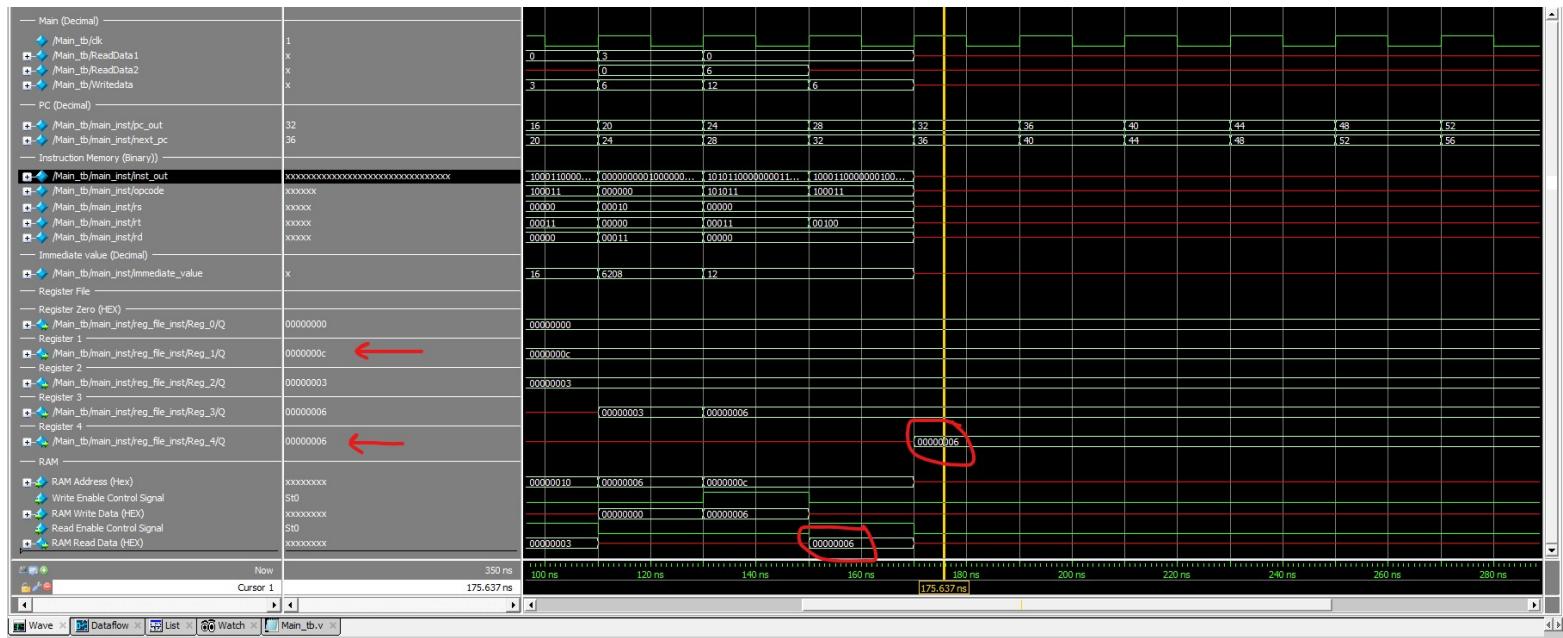


## 1.15.4 fifth Instruction LW R3, 16(R0) with the result of previous instruction in R2 LW R2, 4(R0)



Very important the change in the next positive edge

## 1.15.5 After execution final values



## 1.16 Test case 3

### 1.16.1 Instruction memory and data memory

// testcase 2

```
inst_mem[0] = 32'b100011000000000010000000000000001000; //LW R1, 8(R0)
inst_mem[1] = 32'b000000000000100000000010001000000; //SLL R1, R1, 2
inst_mem[2] = 32'b10101100000000001000000000000000100; //SW R1, 4(R0)
inst_mem[3] = 32'b10001100000000001000000000000000100; //LW R2, 16(R0)
inst_mem[4] = 32'b100011000000000011000000000000001000; //LW R3, 16(R0)
inst_mem[5] = 32'b000000000010000000001100001000000; //SLL R3, R2, 1
inst_mem[6] = 32'b101011000000000011000000000000001100; //SW R3, 12(R0)
inst_mem[7] = 32'b100011000000000010000000000000001100; //LW R4, 12(R0)
```

-----

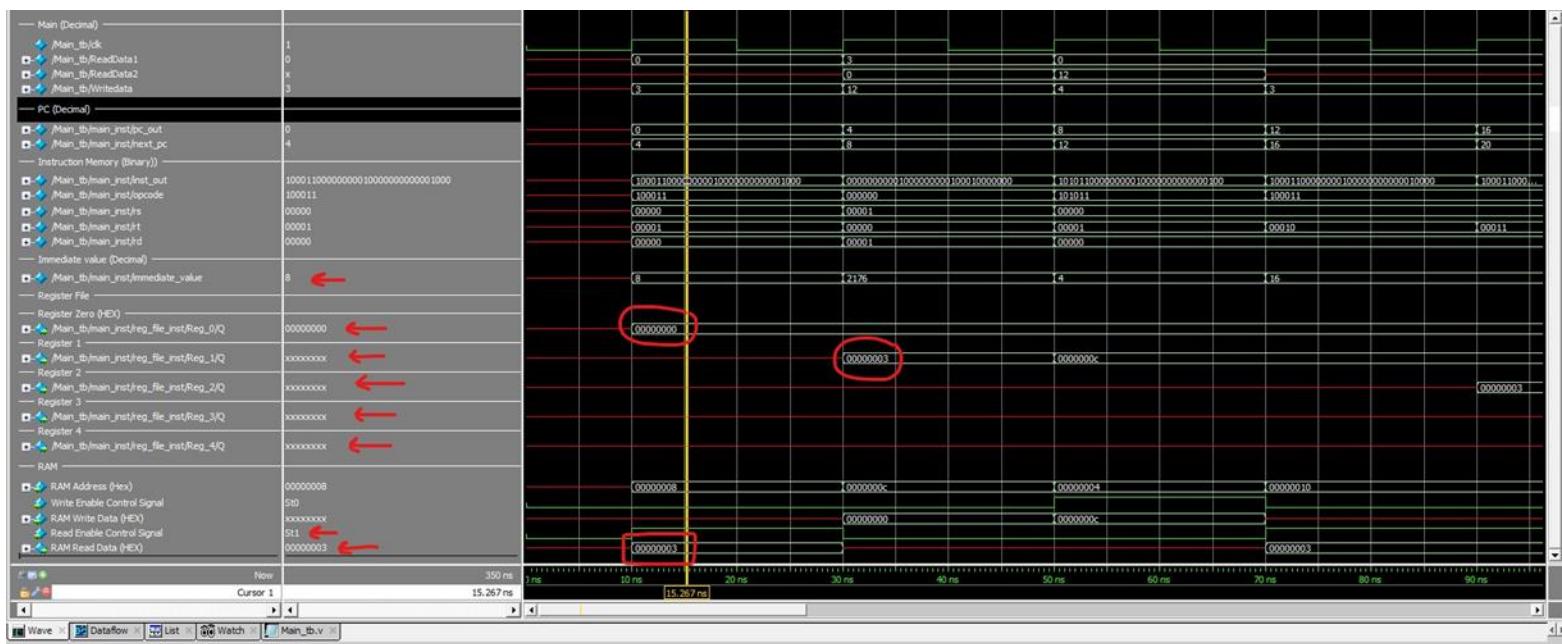
// testcase 3

```
mem[0] = 32'h00000023; // 0x23 (35)
mem[1] = 32'h0000002F; // 0x2F (47)
mem[2] = 32'h0000001A; // 0x1A (26)
```

/\*

-----

### 1.16.2 First Instruction (ADD R28,R0,R0)



The instructions in the image you've provided appear to represent a sequence of machine-level operations for a CPU. Here's a breakdown of each instruction and its likely purpose based on common assembly language syntax:

```
inst_mem[0] = 32'b00000000000001110000000000000000; //ADD R28, R0, R0
```

This instruction seems to perform an addition operation. It adds the value in register R0 to itself (which is likely zero at this point) and stores the result in register R28.

```
inst_mem[1] = 32'b1001111000100000000000000000000; //LW R8, 0(R28)
```

This is a load word (LW) instruction that loads data from memory into register R8. The address is calculated by adding the immediate value 0 to the contents of register R28.

```
inst_mem[2] = 32'b10011110001001000000000000000000; //LW R9, 4(R28)
```

Similar to the previous instruction, this loads data from memory into register R9. The address is the content of R28 plus an offset of 4, which typically means the next word in memory if we assume a 32-bit word size.

```
inst_mem[3] = 32'b00000001000100100100000000000000; //ADD R8, R8, R9
```

An addition operation that adds the contents of register R8 to the contents of register R9 and stores the result back into register R8.

```
inst_mem[4] = 32'b10011110001010000000000000000000; //LW R10, 8(R28)
```

This instruction loads the word from the memory address obtained by adding 8 to the contents of R28 into register R10.

```
inst_mem[5] = 32'b00000001000101010101000000000000; //ADD R10, R10, R10
```

This instruction doubles the value in R10 by adding it to itself and storing the result back in R10.

```
inst_mem[6] = 32'b00000001000101100101000000000000; //SUB R8, R8, R10
```

This instruction subtracts the value in register R10 from the value in register R8 and stores the result in register R8.

```
inst_mem[7] = 32'b00100001000100000000000000000001; //ADDI R8, R8, 1
```

An add immediate (ADDI) instruction that adds the immediate value 1 to the contents of register R8 and stores the result back into R8.

```
inst_mem[8] = 32'b00000000000010001000000000001000; //SUB R8, R0, R8
```

This instruction subtracts the value in register R8 from the value in register R0 (which is likely zero, as is common for R0 in many instruction sets) and stores the result in register R8.

## pc\_out=> current value of pc

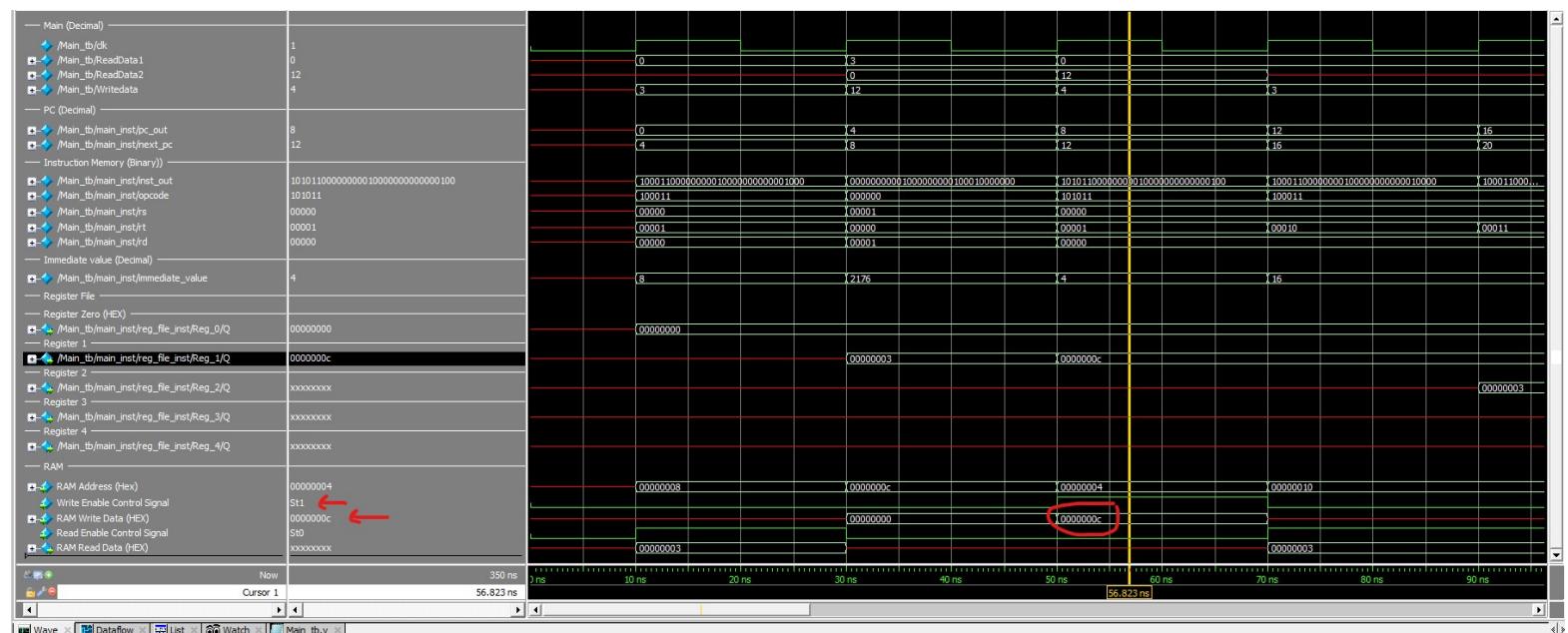
## Pc\_next=> the next pc

## Data\_out=> read data from RAM

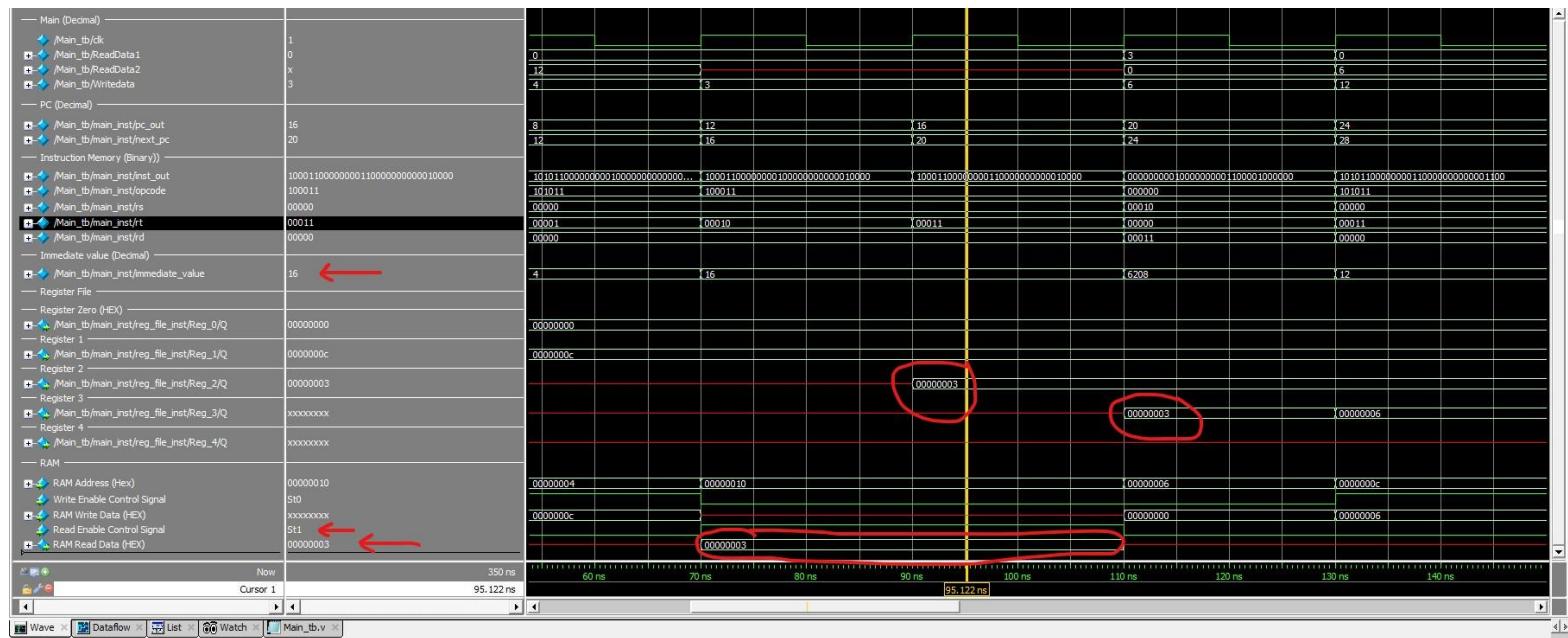
We have 32 registers , we only show the register the related to instruction .

The value save in register or memory in next positive edge .

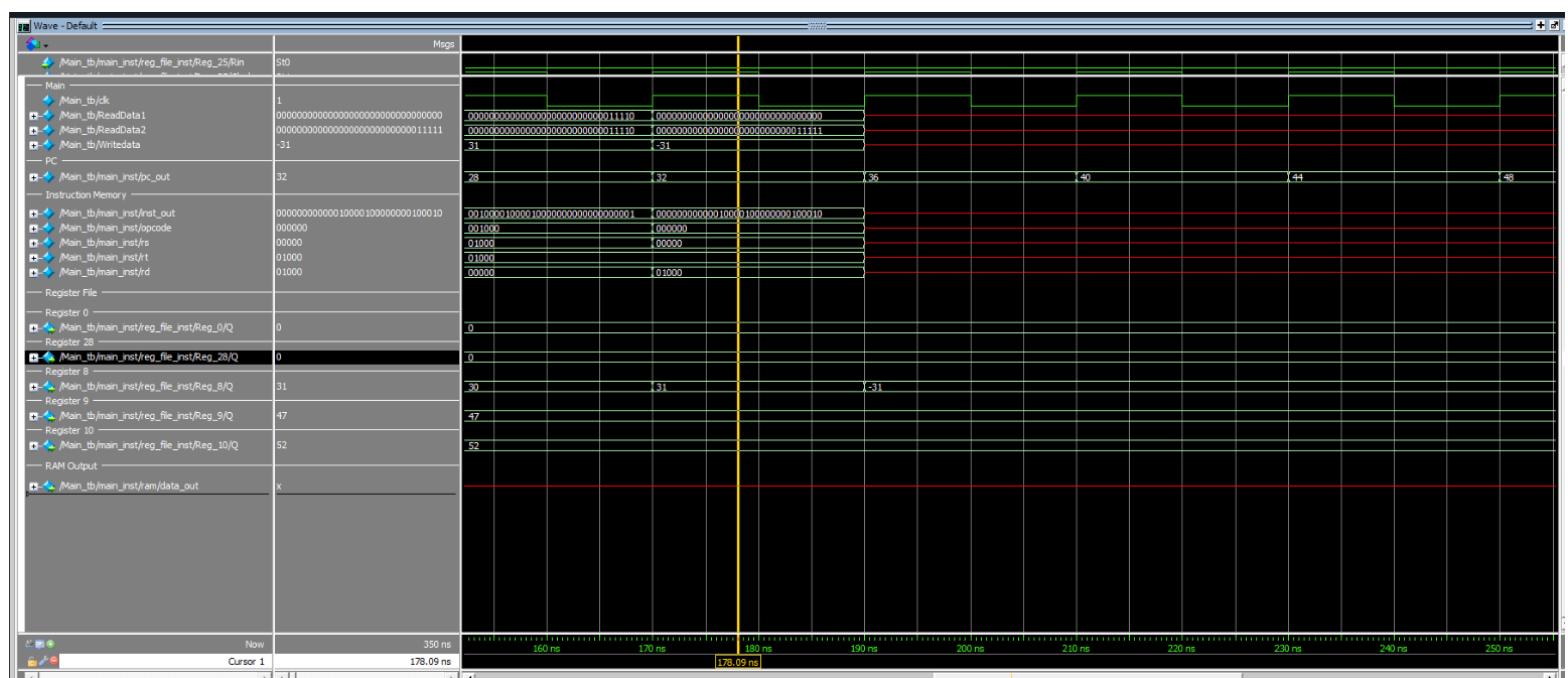
### 1.16.3 Third Instruction SW R1, 4(R0)



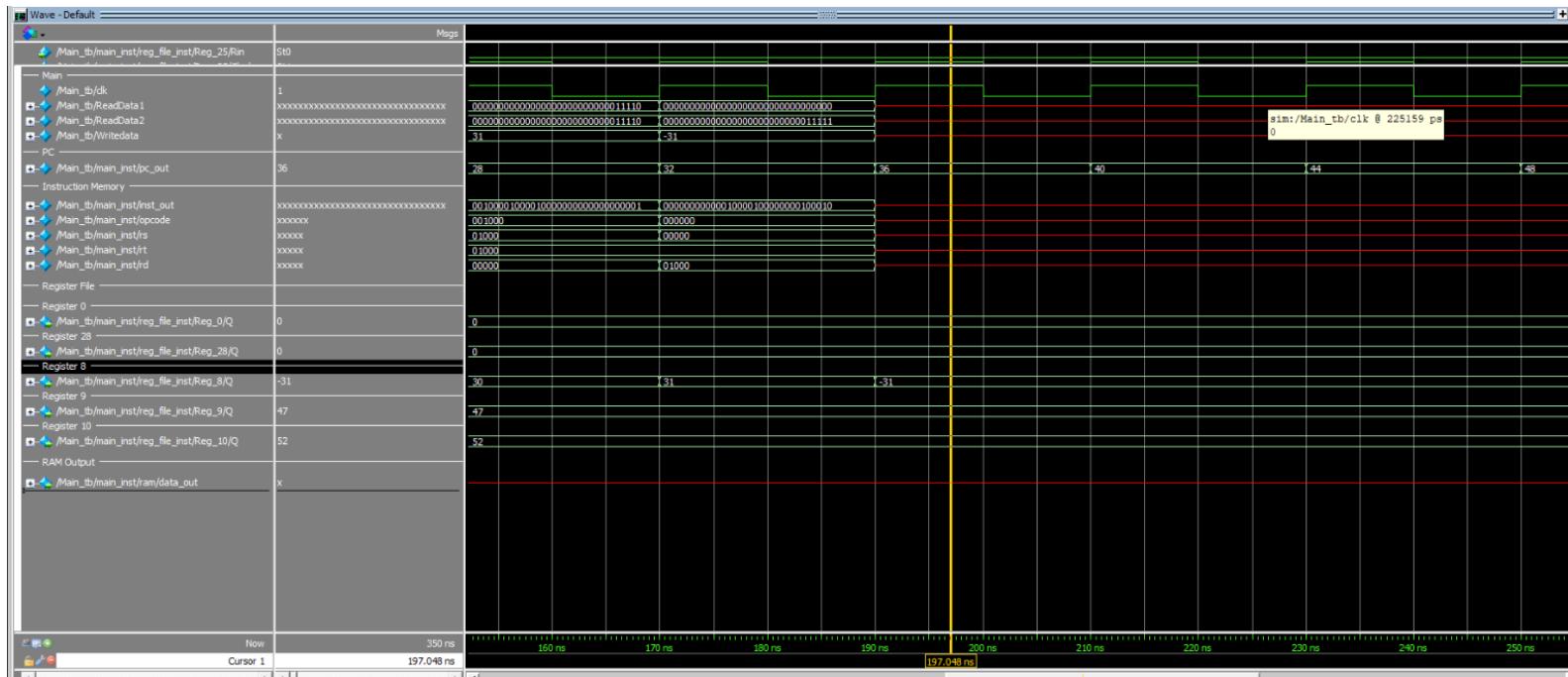
## 1.16.4 Fifth Instruction (LW R10, 8(R28)



## 1.16.5 the last Instruction (SUB R8 , R0 , R8)



## 1.16.6 the cpu after execution



## 1.17 Test case 4

### 1.17.1 Instruction memory and data memory

//-----  
//testcase 4

```
/*Address 0 */ inst_mem[0] = 32'b000000000000000010000000100000; //ADD R8, R0, R0
/*Address 4 */ inst_mem[1] = 32'b00100000000010010000000000001010; //ADDI R9, R9, 10
/*Address 8 */ inst_mem[2] = 32'b000000010000100101000000100010; //SUB R10, R8, R9 //Loop
/*Address 12 */ inst_mem[3] = 32'b001000000000110000000000000001; //ADDI R12, R0, 1
/*Address 16 */ inst_mem[4] = 32'b0001100100001001000000000000010; //BGT R8, R9, DONE
/*Address 20 */ inst_mem[5] = 32'b000100001000010000000000000001; //ADDI R8, R8, 1
/*Address 24 */ inst_mem[6] = 32'b0000010000000000000000000000010; //JUMP LOOP
/*Address 28 */ inst_mem[7] = 32'b000000001001000000110100000100000; //ADD R13, R9, R0 //DONE
/*Address 32 */ inst_mem[8] = 32'b0010000000001110000000000000011011; //ADDI R14, R0, 1B(27)
/*Address 36 */ inst_mem[9] = 32'b0011000111001110000000000000010111; //ANDI R14, R14, 17(23)
```

// testcase 4 & 5 & 6  
//no need for RAM

## 1.17.2 First Instruction ADD R8, R0, R0 CPU Status before execution

**pc\_out=> current value of pc**

**Pc\_next=> the next pc**

**Data\_out=> read data from RAM**

**We have 32 registers , we only show the register the related to instruction .**

**The value save in register or memory in next positive edge .**

Test Case 4: Conditional Sentences and Design Considerations

**Goal:** To comprehensively test our design's ability to handle conditional sentences while ensuring alignment with our default register initialization strategy. This test case will analyze the behavior of the code and the impact of design considerations on its execution.

**Description:** This test case compares two registers, R8 and R9, using a loop structure. Within the loop, the code continuously checks if R8 is greater than R9. Once this condition is met, the value of R9 is stored in R13. The test also involves additional instructions to evaluate the code's ability to perform logical operations after loops and jumps.

**Design Considerations:** Our design assumes that all registers are initialized with a "don't care" value by default. This requires careful analysis and modification of certain instructions to ensure proper functionality and alignment with our design.

Detailed Test Case Analysis:

Instructions:

PC=0:

Original instruction: ADD R8, R8, R0 (Assuming R0 = 0)

Modified instruction: ADD R8, R0, R0

Purpose: Explicitly initialize R8 with 0 to ensure proper loop behavior.

Result: R8 = 0 after execution.

PC=4:

Original instruction: ADDI R9, R9, 10

Modified instruction: ADDI R9, R0, 10

Purpose: Explicitly initialize R9 with 10 to ensure accurate comparison in the loop.

Result: R9 = 10 after execution.

PC=8 (LOOP TAG):

Instruction: SLT R11, R0, R10

Purpose: Set the Zero Flag (ZF) to indicate whether R10 is less than 0.

Purpose of Removal: In the context of our design and implementation strategy, the removal of this instruction, along with the subsequent replacement of BEQ with BGT, aims to streamline and optimize the code execution. The SLT instruction, while initially incorporated to assess the negativity of R10, is found to be extraneous to the core functionality of the test case. Its removal, coupled with the substitution of the conditional branch instruction, enhances the overall efficiency and clarity of the code, aligning it more closely with our design principles.

PC=16:

Original instruction: BEQ R11, R12, DONE

Modified instruction: BGT R8, R9, DONE

Purpose: Jump to the DONE tag if the Zero Flag (ZF) is set (originally) or if R8 is greater than R9 (modified).

Reason for modification: The removal of instruction 4 necessitates a change to the conditional jump instruction.

Result: The BGT instruction ensures the loop continues until R8 becomes greater than R9.

PC=20:

Instruction: ADDI R8, R8, 1

Purpose: Increment R8 by 1, aiming to eventually satisfy the loop condition.

Result: R8 increases by 1 with each loop iteration.

PC=24:

Instruction: JUMP LOOP

Purpose: Unconditionally jump back to the LOOP tag for further iterations.

Loop Analysis:

The code executes instructions 3 to 7 repeatedly, creating a loop that continues until the BGT condition is met.

R8 increments by 1 on each loop iteration, gradually approaching the value of R9.

On the 11th loop, R8 becomes equal to 11, exceeding the value of R9 (10).

PC=28 (DONE TAG):

Instruction: ADD R13, R9, R0

Purpose: Store the value of R9 (10) in R13.

PC=32:

Instruction: ADDI R14, R0, 1B

Purpose: Initialize R14 with the value 0x1B (27 in decimal).

PC=36:

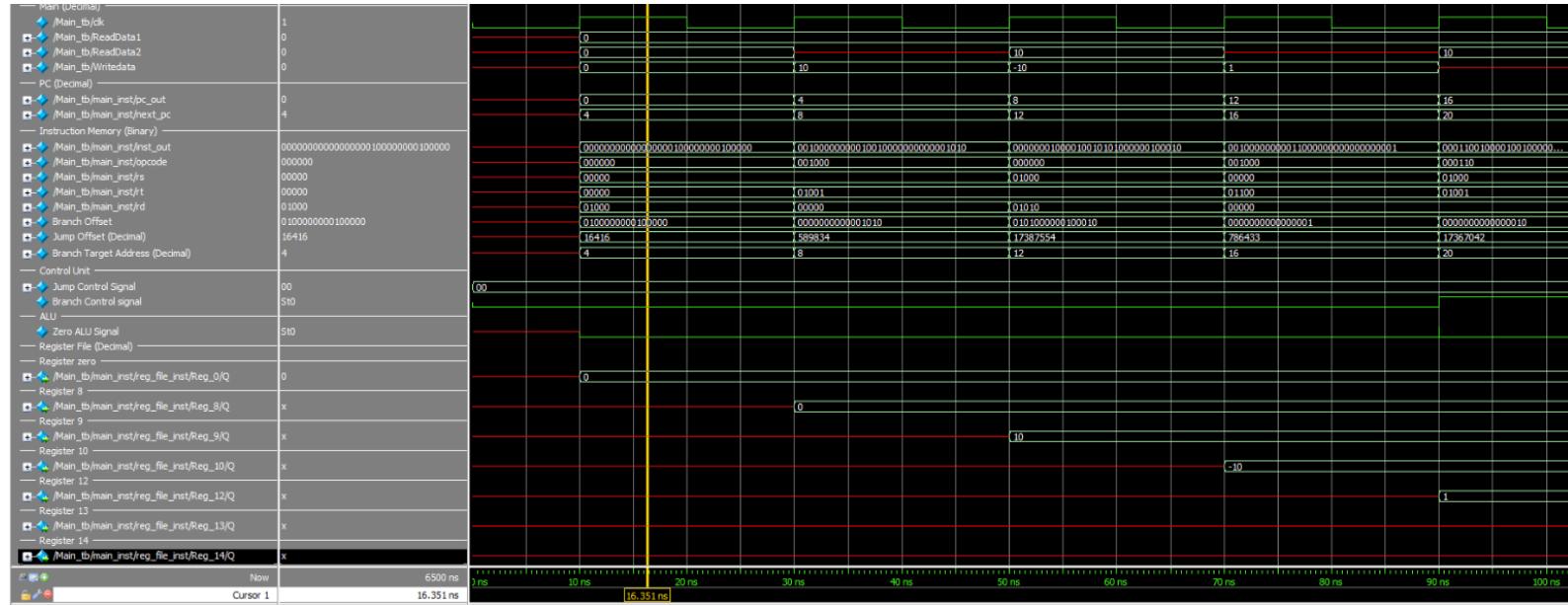
Instruction: ANDI R14, R14, 17

Purpose: Perform a bitwise AND operation between R14 (0x1B) and 0x17, storing the result in R14.

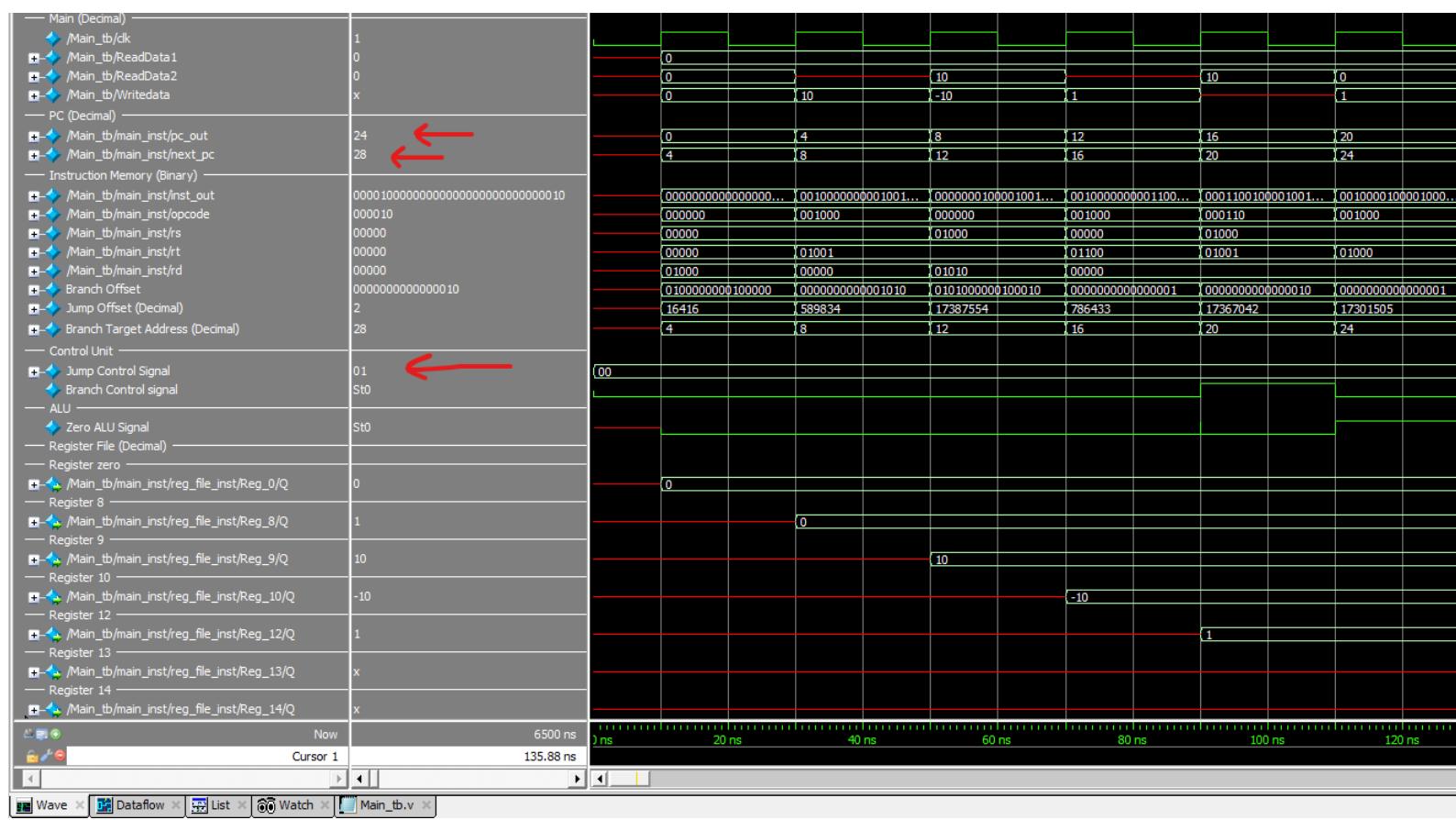
Results:

This test case successfully demonstrates how our design handles conditional sentences within a loop structure. Modifying instructions to align with our default register initialization strategy ensures proper loop behavior. The test confirms that the code correctly compares register values, executes the loop accordingly, and stores the desired value upon completion. Additional instructions verify the

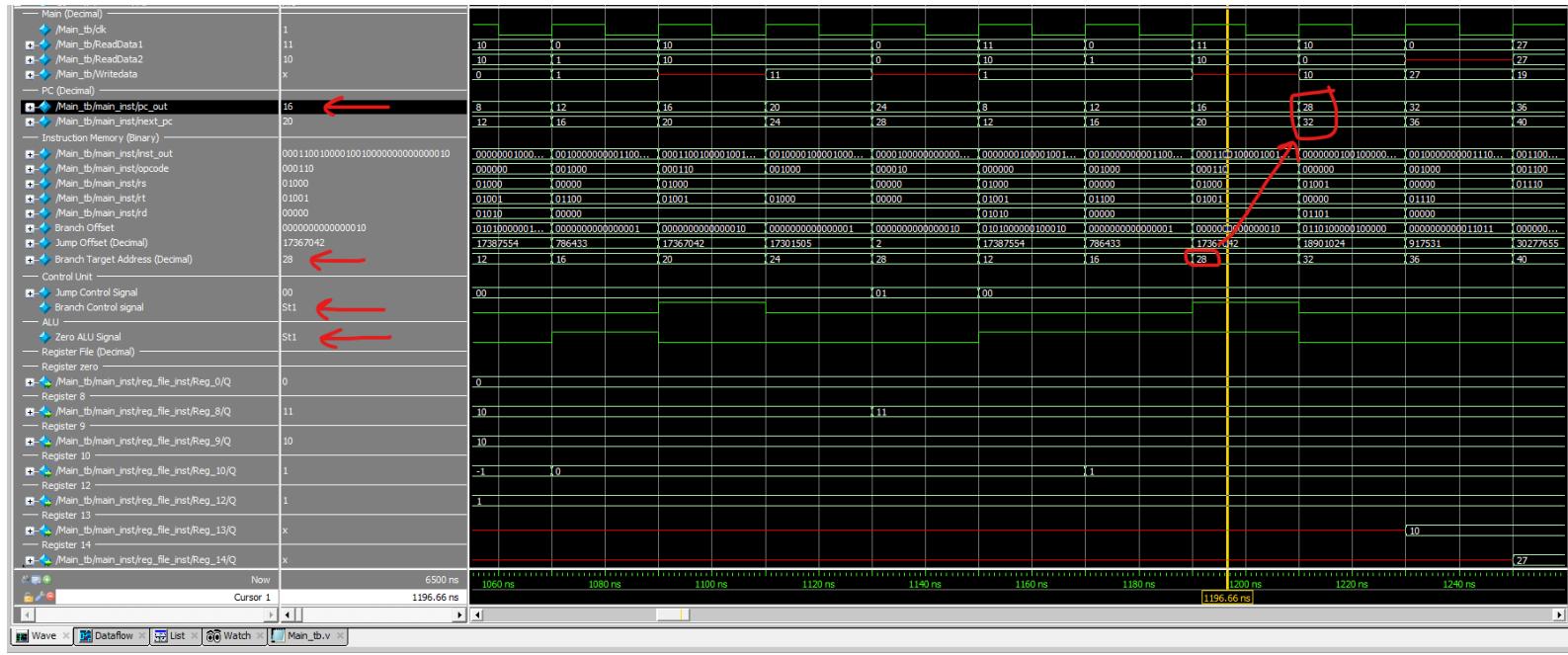
code's ability to perform logical operations after loops and jumps. Specifically, they demonstrate the code's capacity to handle hexadecimal values and perform bitwise AND operations, showcasing its versatility beyond the core functionality of the test case.



### 1.17.3 seventh Instruction JUMP LOOP First Iteration.



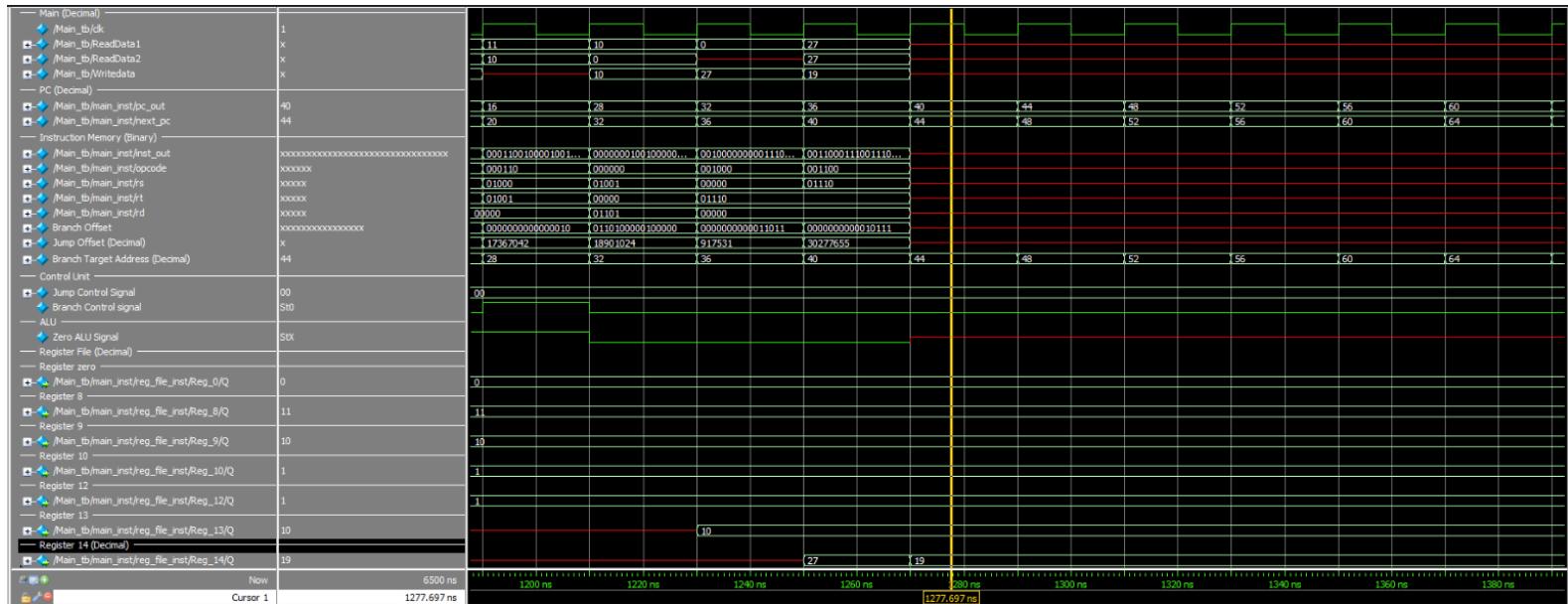
## 1.17.4 Branch Taken BGT R8, R9,



## 1.17.5 Instruction JUMP LOOP the Last Iteration



## 1.17.6 CPU Status after execution



## 1.18 Test case 5

**pc\_out=> current value of pc**

**Pc\_next=> the next pc**

**Data\_out=> read data from RAM**

**We have 32 registers, we only show the register the related to instruction.**

**The value save in register or memory in next positive edge .**

## 1.18.1 Instruction memory and data memory

### No need for RAM

```
// testcase 5

//a=2
/*Address 0 */ inst_mem[0] = 32'b0010000000000000100000000000000010; //ADDI R1, R0, 2 (a)
/*Address 4 */ inst_mem[1] = 32'b0010000000000000100000000000000010; //ADDI R2, R0, 2 (b)
/*Address 8 */ inst_mem[2] = 32'b0010000001000011000000000000000011; //ADDI R3, R2, 3 (b+3)
/*Address 12 */ inst_mem[3] = 32'b0010010000100011000000000000000010; //BGE R1, R3, THEN
/*Address 16 */ inst_mem[4] = 32'b001000000010000100000000000000001; //ADDI R1, R1, 1
/*Address 20 */ inst_mem[5] = 32'b0000010000000000000000000000000011; //JUMP END
/*Address 24 */ inst_mem[6] = 32'b0010000000100001000000000000000010; //ADDI R1, R1, 2 //THEN
/*Address 28 */ inst_mem[7] = 32'b000000000010000010001000000100000; //ADD R2, R2, R1 //END

//a=6
/*Address 0 */ inst_mem[0] = 32'b00100000000000001000000000000000110; //ADDI R1, R0, 6 (a)
/*Address 4 */ inst_mem[1] = 32'b0010000000000000100000000000000010; //ADDI R2, R0, 2 (b)
/*Address 8 */ inst_mem[2] = 32'b0010000001000011000000000000000011; //ADDI R3, R2, 3 (b+3)
/*Address 12 */ inst_mem[3] = 32'b0010010000100011000000000000000010; //BGE R1, R3, THEN
/*Address 16 */ inst_mem[4] = 32'b001000000010000100000000000000001; //ADDI R1, R1, 1
/*Address 20 */ inst_mem[5] = 32'b0000010000000000000000000000000011; //JUMP END
/*Address 24 */ inst_mem[6] = 32'b0010000000100001000000000000000010; //ADDI R1, R1, 2 //THEN
/*Address 28 */ inst_mem[7] = 32'b000000000010000010001000000100000; //ADD R2, R2, R1 //END

//-----.
```

### Test Case 5: Conditional Sentences and Design Considerations

Goal: This test case aims to analyze how our design handles conditional sentences and ensure its alignment with our design principles.

### Description/C Code:

```
if (a < b + 3)
```

```
a = a + 1;
```

```
else
```

```
a = a + 2;
```

```
b = b + a;
```

## A) Assuming a = 2:

Instruction 1 (PC=0): ADDI R1, R0, 2

Stores the value 2 in register R1 (representing variable a).

Instruction 2 (PC=4): ADDI R2, R0, 2

Stores the value 2 in register R2 (representing variable b).

Instruction 3 (PC=8): ADDI R3, R2, 3

Calculates b + 3 and stores the result in register R3 (representing the condition).

Instruction 4 (Removed)

This instruction was removed to comply with our design and replaced with BGE in instruction 5.

Instruction 5 (PC=12): BGE R1, R3, THEN

Replaces BEQ and performs the check  $a \geq b + 3$ .

If true, jumps to the THEN tag (else statement), incrementing a by 2.

In this case,  $a < b + 3$ , so the instruction is skipped.

Instruction 6 (PC=16): ADDI R1, R1, 1

Increments a by 1 since  $a < b + 3$ .

New value of a:  $2 + 1 = 3$ .

Instruction 7 (PC=20): JUMP END

Always jumps to the last instruction regardless of the conditional statement.

Instruction 8 (PC=24): ADD R2, R2, R1 (Modified)

This instruction is modified to align with the intended behavior.

Originally, it was ADD R1, R1, R0, which did not update b correctly.

The modified instruction adds a to b, resulting in  $b = b + a$ .

New value of b:  $2 + 3 = 5$ .

B) Assuming a = 6:

Instructions 1 to 4: Same as scenario A.

Instruction 5 (PC=12): BGE R1, R3, THEN

Checks if  $a \geq b + 3$ .

In this case,  $a \geq b + 3$  ( $6 \geq 5$ ), so the instruction jumps to the THEN tag.

Instruction 6 (PC=24): ADDI R1, R1, 2

Increments a by 2 since the condition is not met.

New value of a:  $6 + 2 = 8$ .

Instruction 7 (PC=28): ADD R2, R2, R1 (Modified)

Adds a to b, resulting in  $b = b + a$ .

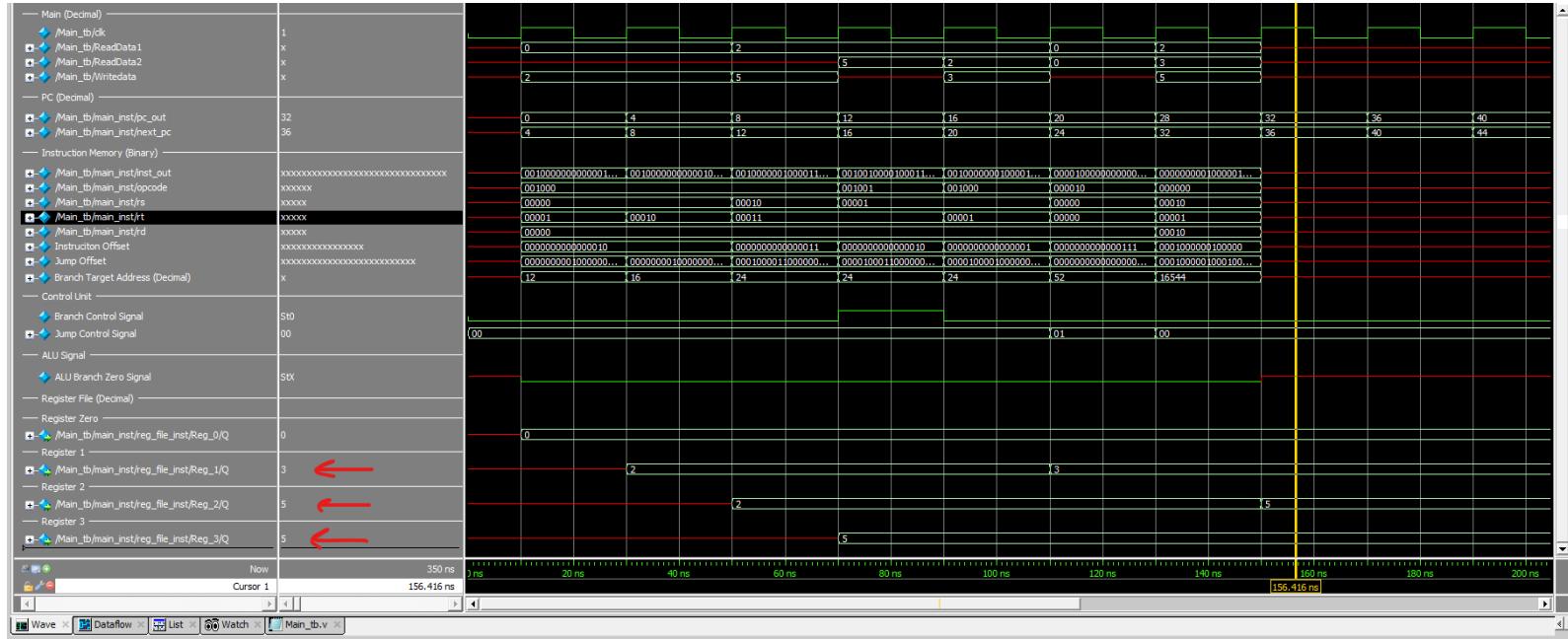
New value of b:  $2 + 8 = 10$ .

Summary:

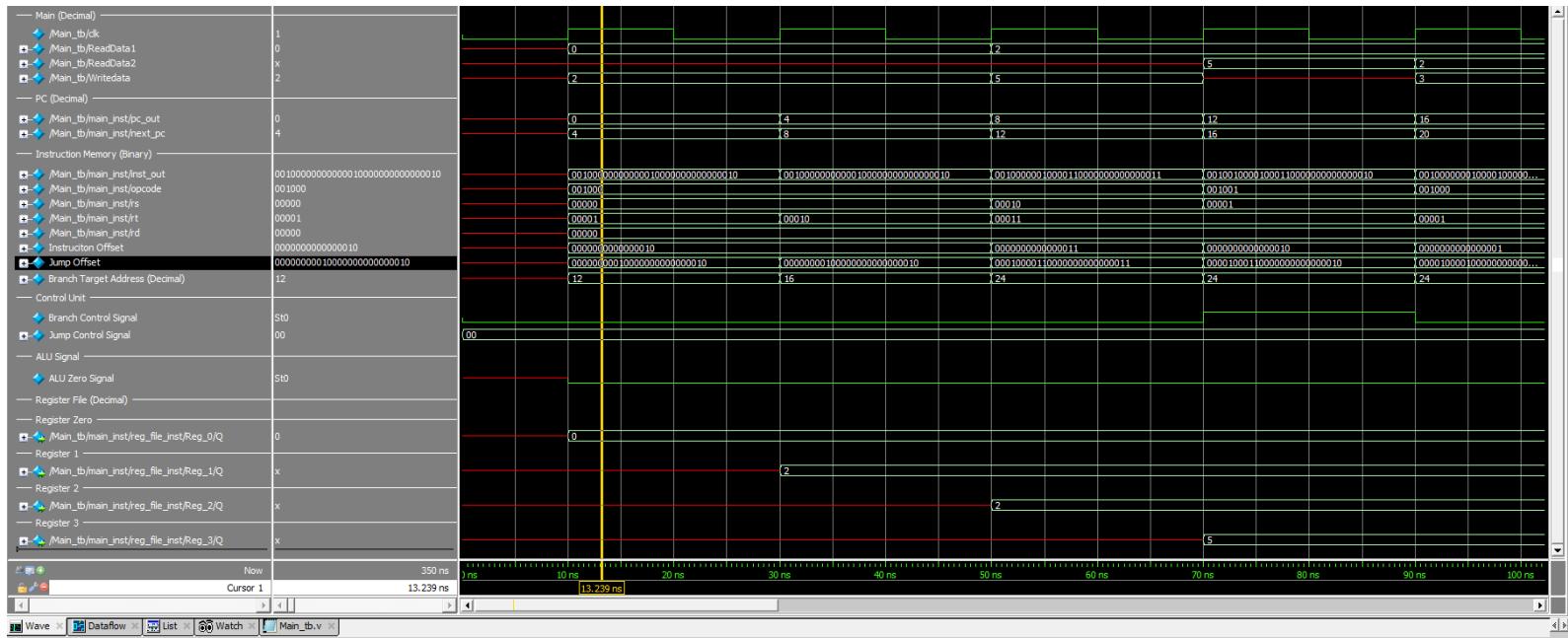
This test case demonstrates how our design handles conditional sentences and ensures proper execution for different input values. The modifications made to instructions align with our design principles and guarantee accurate results.

## 1.18.2 When a = 2

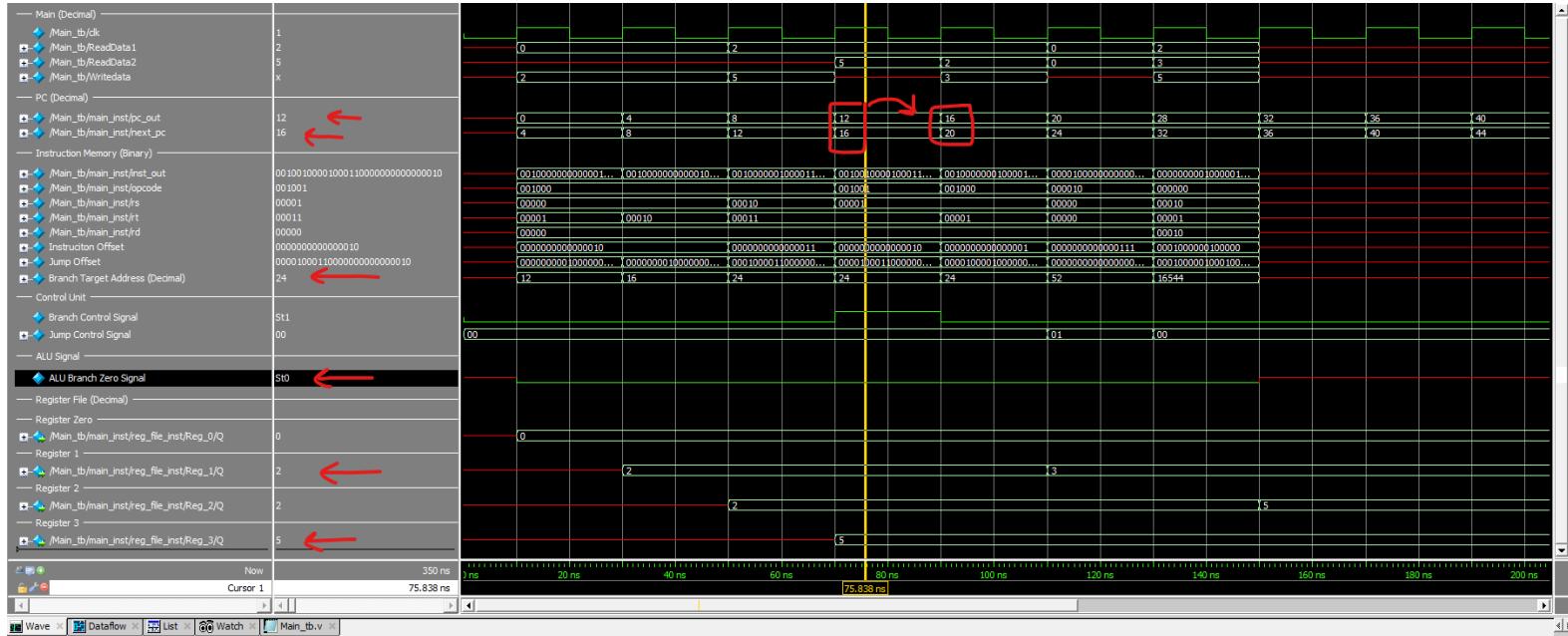
### 1.18.2.1 First Instruction ADDI R1, R0, 2 (a) CPU Status before execution



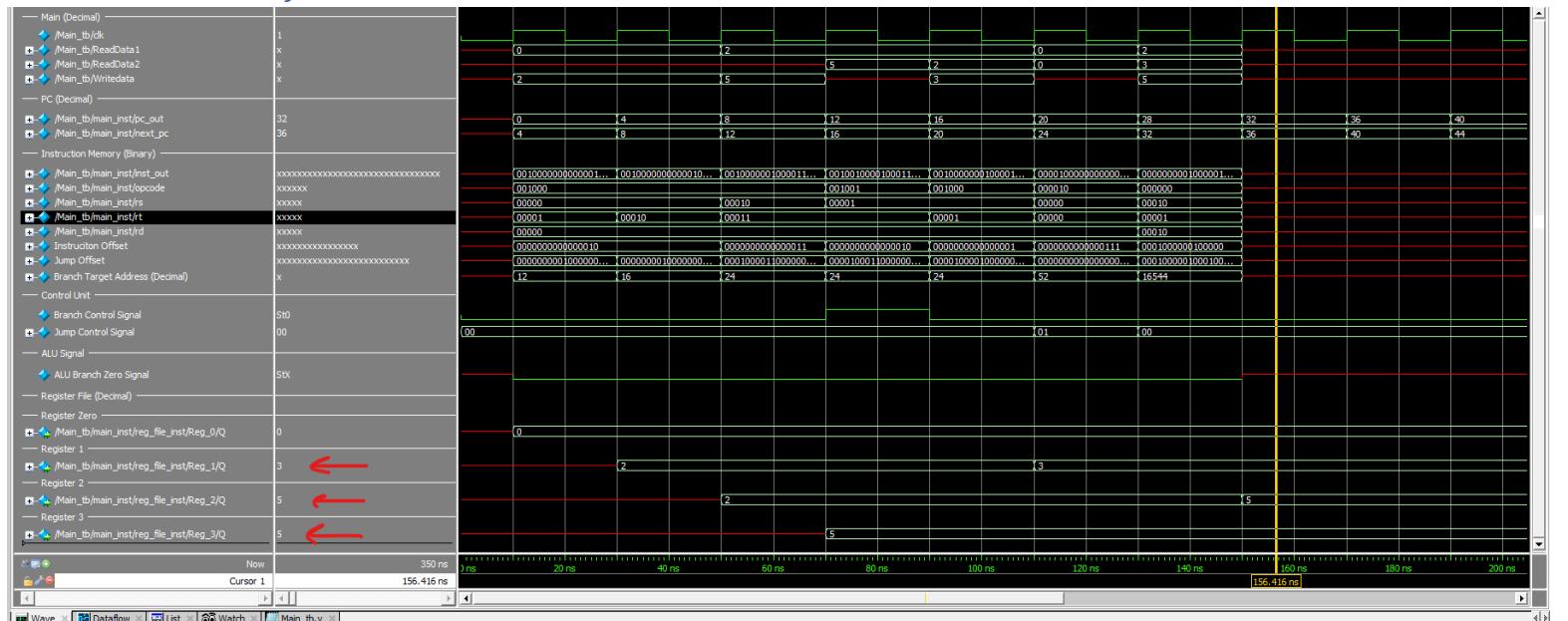
### 1.18.2.2 Fourth Instruction BGE R1, R3, THEN IF condition True the Branch Not Taken



### 1.18.2.3 Sixth Instruction JUMP

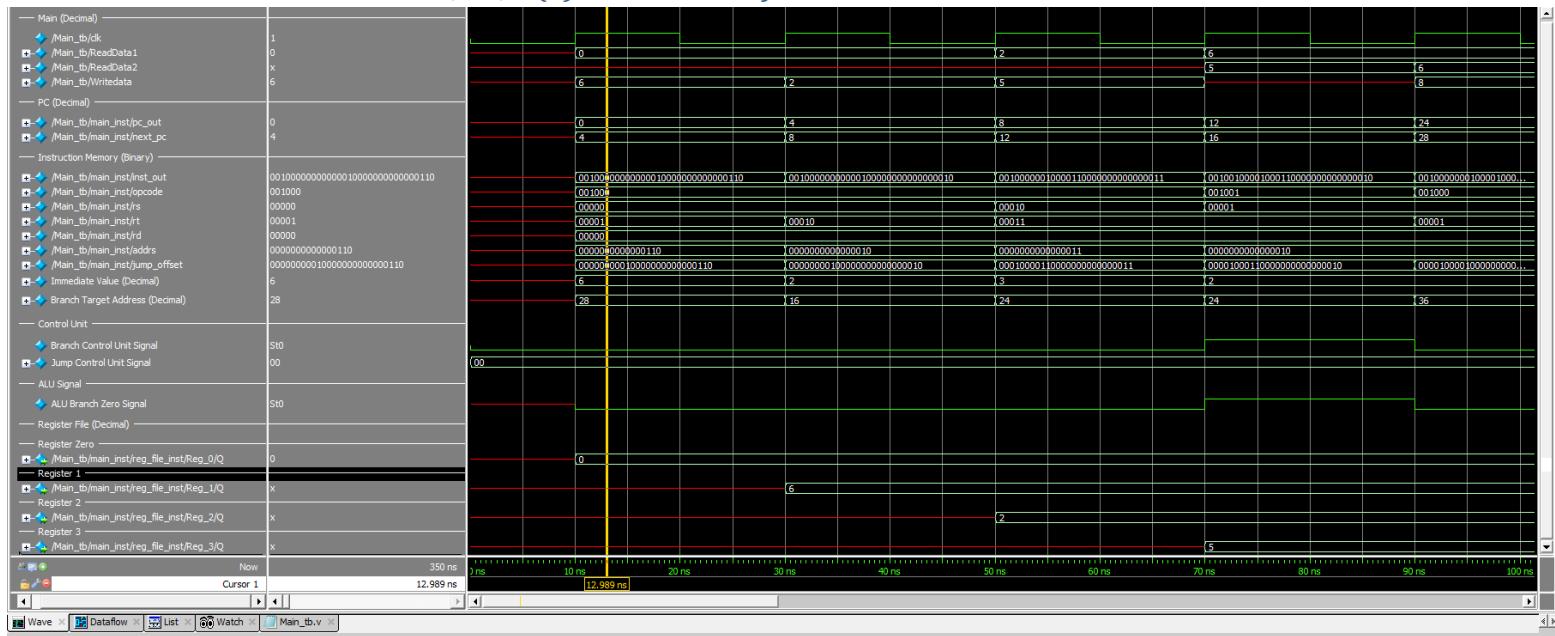


### 1.18.2.4 CPU Status After execution

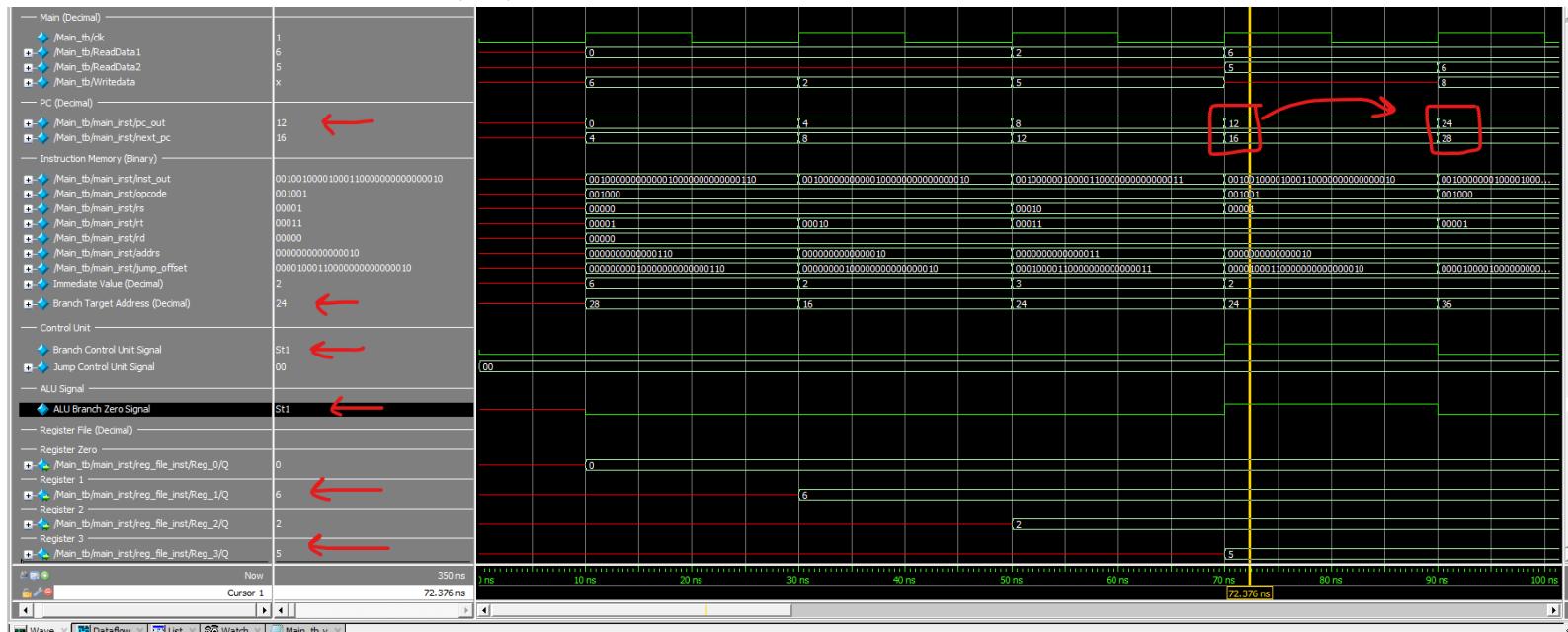


## 1.18.3 When a = 6

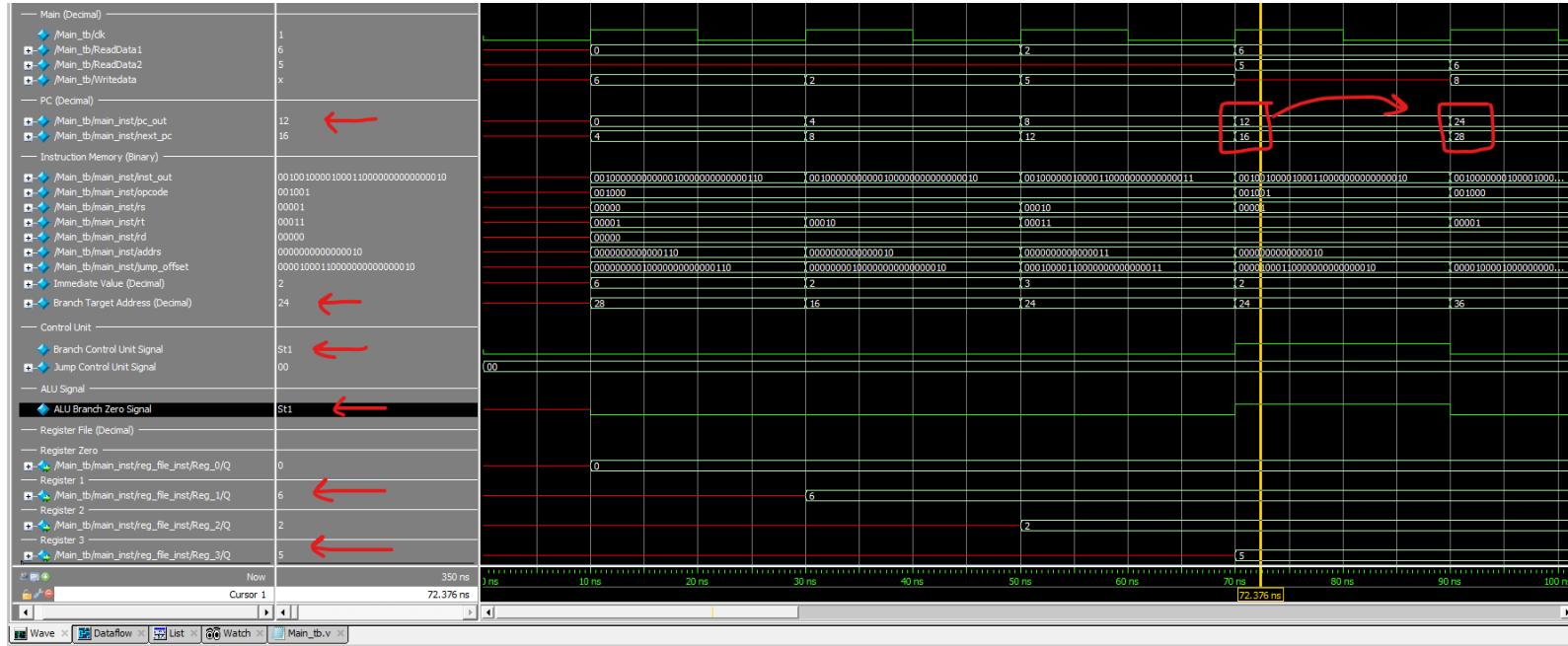
### 1.18.3.1 First Instruction ADDI R1, R0, 6 (a) CPU Status before execution.



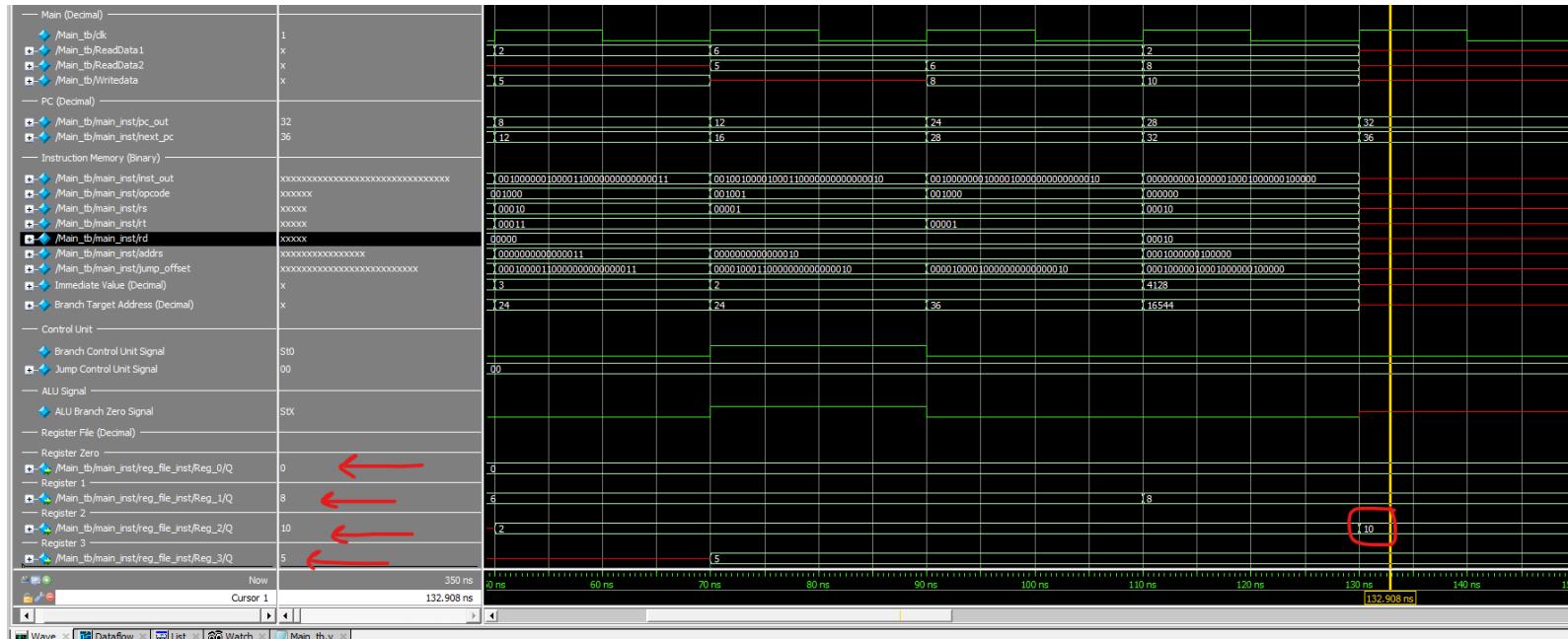
### 1.18.3.2 Fourth Instruction BGE R1, R3, THEN Branch Taken IF statement is False



### 1.18.3.3 seventh Instruction ADDI R1, R1, 2



### 1.18.3.4 CPU Status After execution



## 1.19 Test case 6

### 1.19.1 Instruction memory

#### No need for RAM

```
//-----  
//testcase 6  
  
/*Address 0 */ inst_mem[0] = 32'b000000000000000000000000000000010000001000000; //ADD R1, R0, R0  
/*Address 4 */ inst_mem[1] = 32'b000000000000000000000000000000010000001000000; //ADD R2, R0, R0  
/*Address 8 */ inst_mem[2] = 32'b001000000000000100100000000000001100100; //ADDI R9, R0, 100  
/*Address 12 */ inst_mem[3] = 32'b0001000000010100100000000000000000000010; //BEQ R1, R9, EXIT //START  
/*Address 16 */ inst_mem[4] = 32'b001000000010000100000000000000000000000001; //ADDI R1, R1, 1  
/*Address 20 */ inst_mem[5] = 32'b000010000000000000000000000000000000000011; //JUMP START  
/*Address 24 */ inst_mem[6] = 32'b00000000000010001000011000001000000; //ADD R3, R1, R2 //EXIT
```

### 1.19.2 First Instruction ADD R1, R0, R0 CPU Status before execution

#### Test Case 6: Counter Increment from 0 to 100

**Goal:** The objective of this test case is to implement a counter that increments from 0 to 100.

Instructions:

Instruction 1 (PC=0): ADD R1, R0, R0 (TAG START)

Purpose: Initialize register R1 with zero.

Instruction 2 (PC=4): ADD R2, R0, R0

Purpose: Initialize register R2 with zero.

Instruction 3 (PC=8): ADDI R9, R0, 100

Purpose: Initialize register R9 with the value 100.

Instruction 4 (PC=12): BEQ R1, R9, EXIT

Purpose: If R1 equals R9 (100), jump to the EXIT tag.

Note: This condition ensures the loop continues until R1 reaches 100.

Instruction 5 (PC=16): ADDI R1, R1, 1

Purpose: Increment the value in register R1 by 1 in each iteration of the loop.

Instruction 6 (PC=20): JUMP Loop (Modified from original description)

Purpose: Jump to the Loop tag, making PC=12, ensuring the loop continues until R1 = 100.

Note: This modification corrects the inaccuracies in the original description.

Instruction 7 (PC=24): ADD R3, R2, R1 (TAG EXIT - Modified from original description)

Purpose: After the BEQ condition is taken (R1=100), calculate the final value of R3.

Modification Rationale: We believe that R3 should be the sum of R2 and the final value of R1.

**Summary:** This test case aims to establish a counter that increments from 0 to 100. The instructions have been designed and modified to ensure accurate execution, with specific attention given to the loop condition and the calculation of the final result in R3. The modifications align with our understanding of the intended functionality.

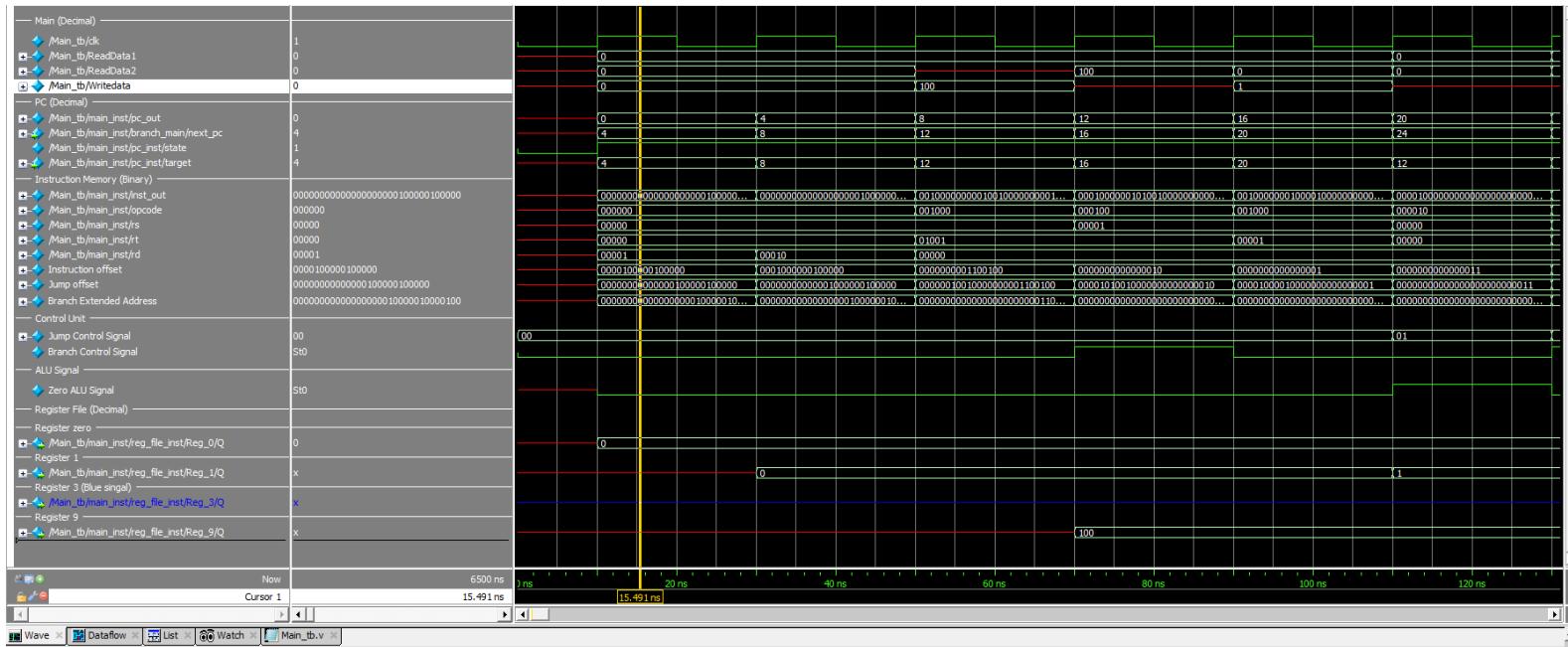
**pc\_out=> current value of pc**

**Pc\_next=> the next pc**

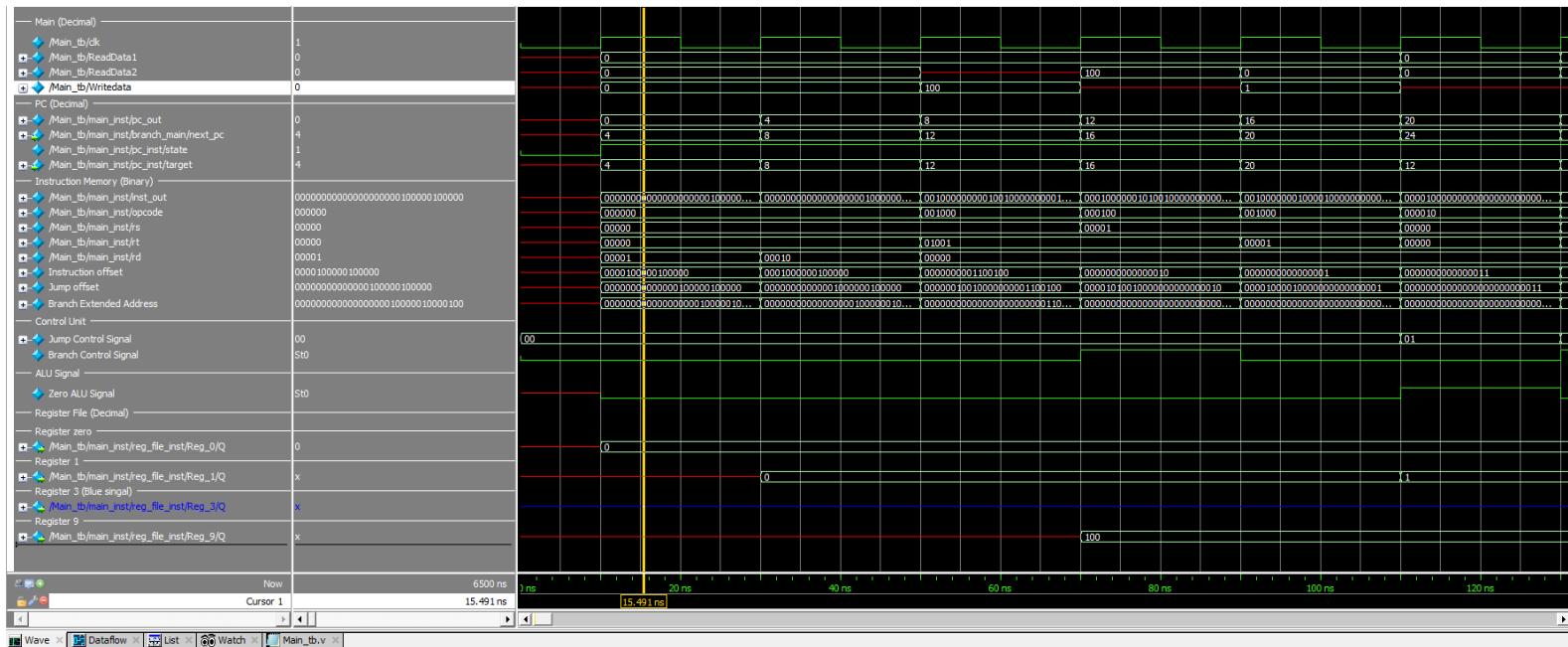
**Data\_out=> read data from RAM**

**We have 32 registers, we only show the register the related to instruction.**

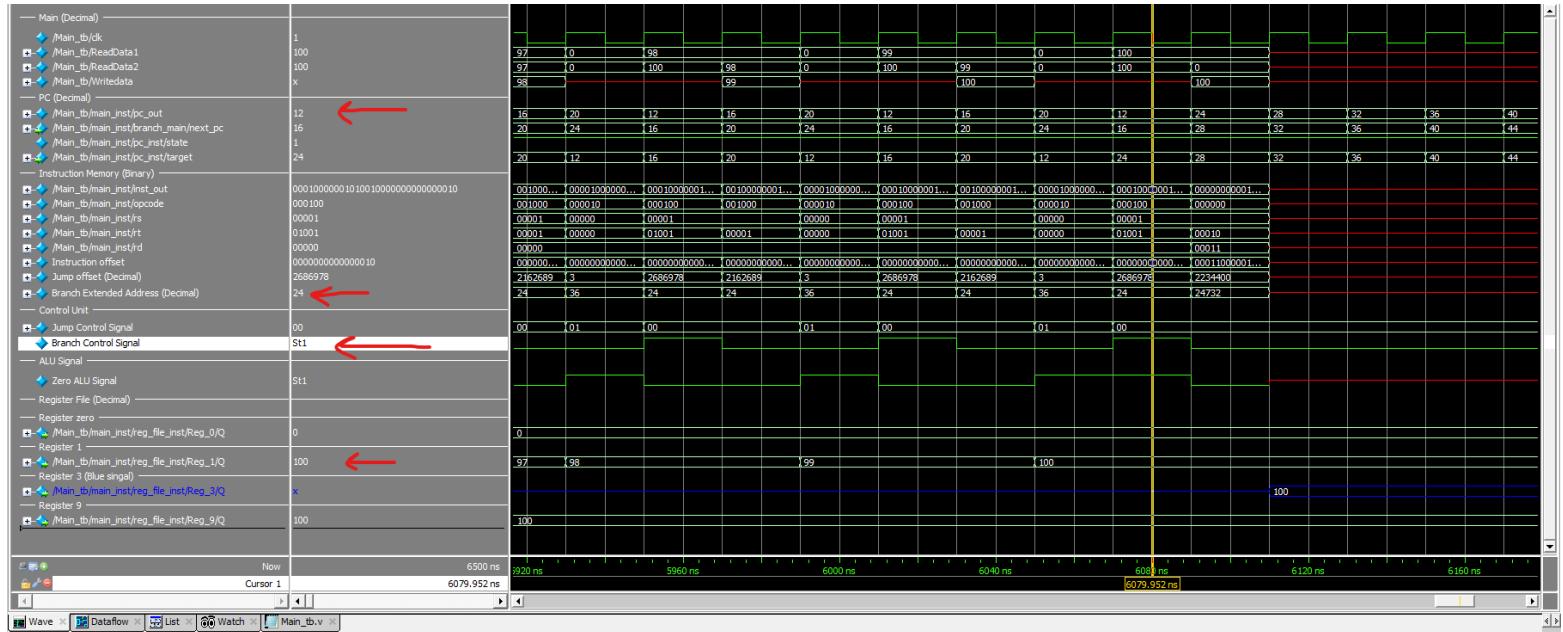
**The value save in register or memory in next positive edge**



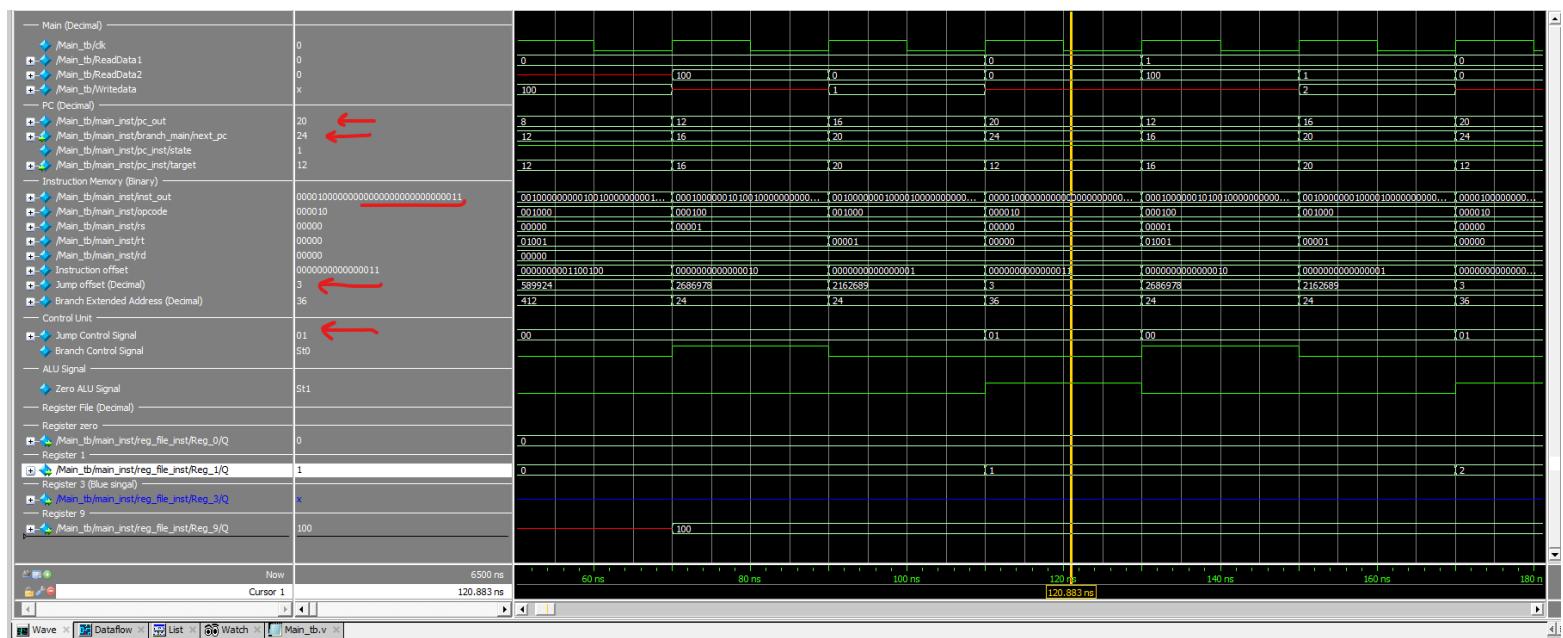
### 1.19.3 Fourth Instruction BEQ R1, R9, EXIT



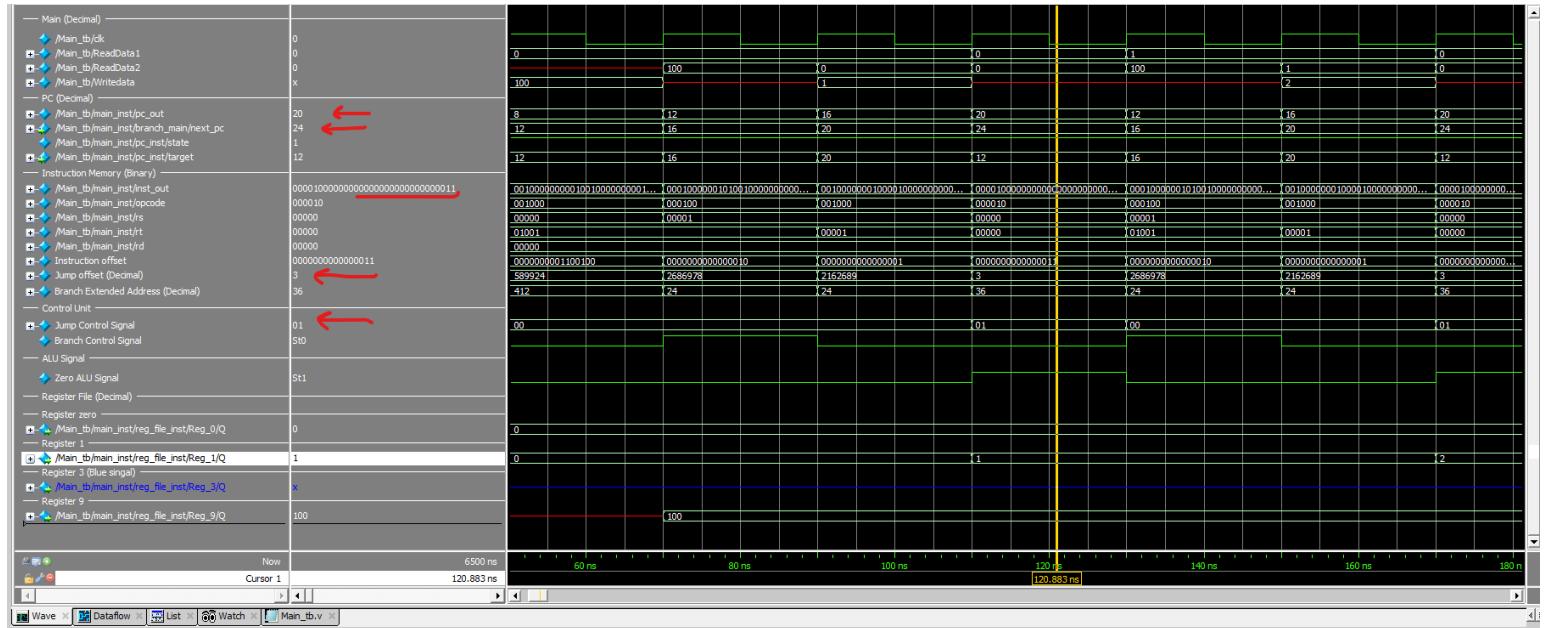
#### 1.19.4. Branch Taken to Instruction BEQ R1, R9, EXIT



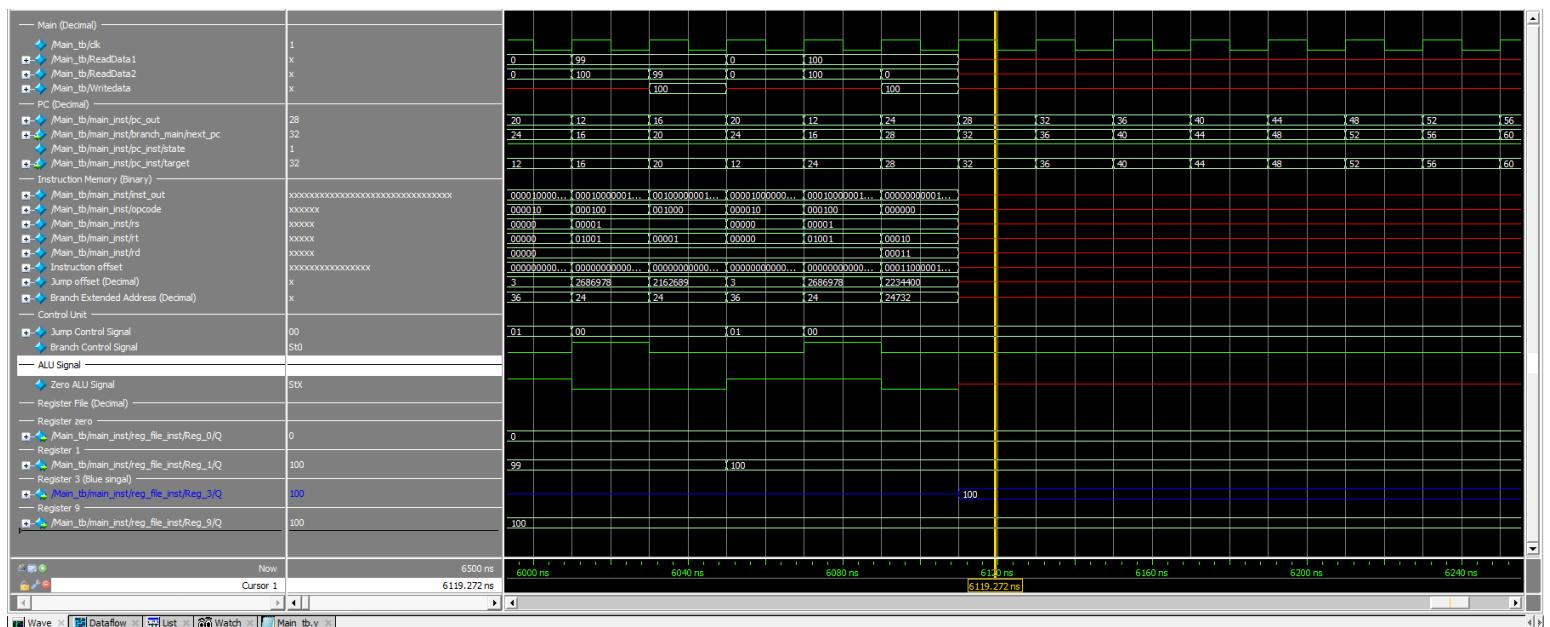
#### 1.19.5 Instruction JUMP START First turn.



## 1.19.6 The second Iteration first Instruction BEQ R1, R9, EXIT after the firt jump execute.



## 1.19.7 The CPU Status After execution



## 1.20Clock testing

As I mentioned earlier, this has been the most challenging part, but I'm proud that we've reached this point

### MIPS Processor Clock Testing and Optimal Cycle Time Evaluation

CLOCK	PERIOD	FREQUENCY	RAISE	FALL	SLACK	TNS	ACHIEVED
clk 1	2 ns	500 MHZ	0.00	1.00	- 2.00	-2.00	✗
clk 2	3.5 ns	285.71 MHZ	0.00	1.75	-0.50	-0.50	✗
clk 3	4 ns	250 MHZ	0.00	2.00	0.00	0.00	✓
clk4	5 ns	200 MHZ	0.00	2.50	1.00	0.00	✓

We have successfully finished the initial phase of constructing the single-cycle CPU. However, the branch component is still pending. We've complemented this phase with a robust testbench to ensure accuracy and functionality.

# Conclusion

The journey to design a single-cycle CPU, inspired by the venerable MIPS architecture, has led us to a comprehensive exploration of computer architecture, instruction execution, and the intricacies of CPU design. This endeavor has not only enriched our understanding of these fundamental concepts but has also yielded insights and a valuable educational resource for students and enthusiasts alike.

## 1.20.1 Key Findings and Implications

Through this project, we have made several key findings and drawn implications:

1. Educational Resource: We have successfully created an educational resource that unravels the intricacies of CPU design. The project offers a detailed, step-by-step account of how a single-cycle CPU operates, emphasizing simplicity and clarity, making it accessible to a broad audience.
2. Simplicity and Efficiency: The MIPS-inspired single-cycle design demonstrates the power of simplicity and efficiency in CPU architecture. We have observed that by adhering to a reduced instruction set and single-cycle execution, it is possible to achieve transparency in the execution of instructions.
3. Performance Analysis: Our performance analysis revealed that the single-cycle CPU's execution time is generally quicker compared to other designs. However, this speed comes at the expense of resource utilization, and it may not be the most efficient choice for all applications.

## 1.20.2 Project's objectives achieved.

While our project has achieved its primary objectives (**build single cycle cpu with good cycle time**), there are avenues for future work and exploration:

1. Pipeline CPU Design: Future projects could delve into the design of pipeline CPUs, which allow for a more balanced trade-off between execution speed and resource utilization. A pipeline design can be more efficient and is widely used in modern processors..
2. Advanced Instructions: Expanding the instruction set to include more complex operations, such as floating-point arithmetic or SIMD instructions, would further enrich the educational value of the CPU model.
3. Out of order processor: Out-of-order processors are often found in high-performance computing environments and modern microprocessors where speed and efficiency are paramount.
4. Exception handler

# Appendix A: CODE

## 1.21 PC (finite state machine)

```
module PC #(  
    parameter first_address = 0,  
    parameter pc_inc = 4  
)(  
    input wire clk,  
    input wire reset,  
    input wire [31:0] target,  
    input wire pc_load,  
    output reg [31:0] pc  
);
```

```
reg state = 1'b0;
```

```
always @(posedge clk or posedge reset) begin
```

```
    if (reset) begin  
        pc <= 32'bxxxxxxxxxxxxxxxxxxxxxxxxxxxxxx;  
        state=1'b0;
```

```
    end else begin
```

```
        case (state)
```

```
            1'b0: begin
```

```
                state <= 1'b1;
```

```

pc <= first_address;
end

1'b1: begin
    if (pc_load) begin
        pc <= target;
    end
end

default: begin
    state <= 1'b0;
    pc <= 32'h00000000;
end

endcase

end

endmodule

```

## 1.22 ALU

```

module ALU(
    input  clk,
    input [31:0] A, // 32-bit input A
    input [31:0] B, // 32-bit input B
    input [3:0] ALUControl, // 4-bit ALU control
    input [4:0] ShiftAmount, // 5-bit input for shift amount
    input [2:0] branch_type,
    output reg [31:0] ALUOut, // 32-bit output
    output reg Zero // Zero flag
    // output reg Overflow, // Overflow flag
    // output reg CarryOut // Carry-out flag
);

```

```

reg Overflow;
reg CarryOut;
//reg [31:0] ALUOut;
/*
addu
subu
*/
always @(*) begin
    case(ALUControl)
        4'b0000: ALUOut <= A + B; // Addition (signed)
        4'b0001: ALUOut <= A - B; // Subtraction (signed)
        4'b0010: ALUOut <= A * B; // Multiplication (signed)
        4'b0011: ALUOut <= A / B; // Division (signed/unsigned)
        4'b0100: ALUOut <= A << ShiftAmount; // Logical shift left
        4'b0101: ALUOut <= A >> ShiftAmount; // Logical shift right
        4'b0110: ALUOut <= A + B; // addu
        4'b0111: ALUOut <= A - B; // subu
        4'b1000: ALUOut <= A & B; // Logical AND
        4'b1001: ALUOut <= A | B; // Logical OR
        4'b1010: ALUOut <= A ^ B; // Logical XOR
        4'b1011: ALUOut <= ~(A | B); // Logical NOR
        4'b1100: ALUOut <= (branch_type == 3'b101) ? (A >= B) ? 32'b1 : 32'b0 :
            (branch_type == 3'b110) ? (A <= B) ? 32'b1 : 32'b0 : 32'b0;
        4'b1101: ALUOut <= (A < B) ? 32'b1 : 32'b0; // less than
        4'b1110: ALUOut <= (A > B) ? 32'b1 : 32'b0; // greater than
        // 4'b1111: ALUOut <= (A == B) ? 32'b1 : 32'b0; // Equal comparison ERROR
    endcase
end

```

```

default: ALUOut <= 32'b0; // Default operation

endcase

end

always @(*) begin

if (ALUControl == 4'b0000) begin // Addition (signed)

    Overflow <= (A[31] == B[31] && A[31] != ALUOut[31]);

    CarryOut <= (A[31] & B[31]) | (A[31] & ALUOut[31]) | (B[31] & ALUOut[31]);

end else if (ALUControl == 4'b0001) begin // Subtraction (signed)

    Overflow <= (A[31] != B[31] && A[31] != ALUOut[31]);

    CarryOut <= (A[31] & B[31]) | (A[31] & ALUOut[31]) | (B[31] & ALUOut[31]);

end else if (ALUControl == 4'b0010) begin // Multiplication (signed)

    Overflow <= (A[31] == B[31] && A[31] != ALUOut[31]);

    CarryOut <= 1'b0; // No carry-out for multiplication

end else if (ALUControl == 4'b0011) begin // Division (signed/unsigned)

    Overflow <= (B == 32'b0); // Detect division by zero

    CarryOut <= 1'b0;

    end else if ((ALUOut < A) && (ALUOut < B) && (ALUControl == 4'b0110)) begin

        Overflow <= 1'b0;

        CarryOut <= 1'b1;

    end else begin

        Overflow <= 1'b0;

        CarryOut <= 1'b0;

    end

end

/*
always @* begin

```

```

if (Overflow && (ALUControl != 0110) && (ALUControl != 0111)) begin //signed overflow check
    ALUOut = 32'bx;

end else if(CarryOut && ((ALUControl == 4'b0110) || (ALUControl == 4'b0111))) begin //unsigned overflow check
    ALUOut = 32'bx;
end
end*/



always @(*) begin
    case(branch_type)
        3'b001: Zero <= (ALUOut == 32'b0) ? 1'b1 : 1'b0; // beq
        3'b010: Zero <= (ALUOut != 32'b0) ? 1'b1 : 1'b0; // bne
        3'b011: Zero <= (ALUOut == 32'b1) ? 1'b1 : 1'b0; // bgt
        3'b100: Zero <= (ALUOut == 32'b1) ? 1'b1 : 1'b0; // blt
        3'b101: Zero <= (ALUOut == 32'b1) ? 1'b1 : 1'b0; // bge
        3'b110: Zero <= (ALUOut == 32'b1) ? 1'b1 : 1'b0; // ble
    endcase
end

endmodule

```

## 1.23 Control unit

```

module
ControlUnit(Clock,Reset,opcode,RegDst,ALUSrc,MemtoReg,MemWrite,MemRead,ALUOp,RegWrite,Branch,Jump,funct,pc_load,PC
_Store);
    input wire [5:0] opcode;

```

```

input Clock , Reset ; // Reset : 1 --> on | 0--> off

input wire [5:0] funct;

// wires

output wire ALUSrc,MemWrite,MemRead,RegWrite,Branch,PC_Store;

output wire [3:0] ALUOp;

output wire [1:0] Jump;

output wire [1:0] MemtoReg;

output wire [1:0] RegDst;

output wire pc_load;

// reg type

reg reg_ALUSrc,reg_MemWrite,reg_MemRead,reg_RegWrite,reg_Branch,reg_PC_Store;

reg [3:0] reg_ALUOp;

reg [1:0] reg_Jump;

reg [1:0] reg_MemtoReg;

reg [1:0] reg_RegDst;

reg reg_pc_load;

reg [5:0] reset_opcode ;

//      opcode, // 6-bit opcode from the instruction

//  RegDst,   // Control signal for selecting the destination register

//  ALUSrc,   // Control signal for ALU source selection (0 for register, 1 for immediate)

//  MemtoReg, // Control signal for selecting the source for register write data

//  MemWrite, // Control signal for memory write

//  MemRead,  // Control signal for memory read

//  Branch,   // Control signal for branching

//  ALUOp,    // Control signal for ALU operation

//  RegWrite  // Control signal for register write

//  reset_reg // will handle the default value if the reset is on

//      pc_load (0->stall),(1->load)

```

```
always @(*)
begin
    if(Reset==1'b1)
        reset_opcode <=6'b111000; // this bits will call the default value and make the control unit reset
    else
        reset_opcode <=opcode;
end
```

```
always @(*)
if(Reset==1'b1)begin
    // defualt value we can use it if we will implement reset or unsupported instructions
    reg_ALUSrc = 1'b0;
    reg_RegWrite = 1'b0;
    reg_MemtoReg = 2'b00;
    reg_MemWrite = 1'b0;
    reg_MemRead = 1'b0;
    reg_ALUOp = 4'b0000;
    reg_RegDst = 2'b00;
    reg_Branch = 1'b0;
    reg_Jump = 2'b00;
    reg_pc_load = 1'b0;
    reg_PC_Store = 1'b0;
end
```

```
else begin
    case(opcode)
        6'b000000:begin
            if(funct == 6'b001000)begin
                //Jump Register instruction
                reg_ALUSrc = 1'bx;
                reg_RegWrite = 1'b0;
                reg_MemtoReg = 2'bxx;
                reg_MemWrite = 1'b0;
                reg_MemRead = 1'bx;
                reg_ALUOp = 4'bxxxx;
                reg_RegDst = 2'bxx;
                reg_Branch = 1'bx;
                reg_Jump = 2'b10;
                reg_pc_load = 1'b1;//load
                reg_PC_Store = 1'b0;
            end
            else begin
                // R-type instruction
                reg_ALUSrc = 1'b0;
                reg_RegWrite = 1'b1;
                reg_MemtoReg = 2'b00;
                reg_MemWrite = 1'b0;
                reg_MemRead = 1'b0;
                reg_ALUOp = 4'b0010;
                reg_RegDst = 2'b01;
                reg_Branch = 1'b0;
```

```
    reg_Jump    = 2'b00;
    reg_pc_load = 1'b1;
    reg_PC_Store = 1'b0;
end
end
```

```
6'b100011:begin
    // load instruction
reg_ALUSrc  = 1'b1;
    reg_RegWrite = 1'b1;
reg_MemtoReg = 2'b01;
reg_MemWrite = 1'b0;
reg_MemRead  = 1'b1;
reg_ALUOp    = 4'b0000;
reg_RegDst   = 2'b00;
    reg_Branch  = 1'b0;
    reg_Jump    = 2'b00;
    reg_pc_load = 1'b1;
    reg_PC_Store = 1'b0;
end

6'b101011:begin
    // store instruction
reg_ALUSrc  = 1'b1;
    reg_RegWrite = 1'b0;
reg_MemtoReg = 2'b00; //error (should be 0 ) i am an idiot ...*****
reg_MemWrite = 1'b1;
reg_MemRead  = 1'b0;
```

```
reg_ALUOp = 4'b0000;  
reg_RegDst = 2'b00; //don't care  
    reg_Branch = 1'b0;  
    reg_Jump = 2'b00;  
    reg_pc_load = 1'b1;  
    reg_PC_Store = 1'b0;
```

```
end
```

```
6'b001000:begin  
//immediate instruction (addi)  
    reg_ALUSrc = 1'b1;  
    reg_RegWrite = 1'b1;  
  
reg_MemtoReg = 2'b00;  
  
reg_MemWrite = 1'b0;  
  
reg_MemRead = 1'b0;  
  
reg_ALUOp = 4'b0000;  
reg_RegDst = 2'b00;  
    reg_Branch = 1'b0;  
    reg_Jump = 2'b00;  
    reg_pc_load = 1'b1;  
    reg_PC_Store = 1'b0;
```

```
end
```

```
6'b001100:begin  
//immediate instruction (andi)  
    reg_ALUSrc = 1'b1;  
    reg_RegWrite = 1'b1;
```

```
reg_MemtoReg = 2'b00;  
reg_MemWrite = 1'b0;  
reg_MemRead = 1'b0;  
reg_ALUOp  = 4'b0001;  
reg_RegDst  = 2'b00;  
    reg_Branch  = 1'b0;  
    reg_Jump   = 2'b00;  
    reg_pc_load = 1'b1;  
    reg_PC_Store = 1'b0;
```

end

```
6'b001101:begin  
//immediate instruction (ori)  
    reg_ALUSrc  = 1'b1;  
    reg_RegWrite = 1'b1;  
reg_MemtoReg = 2'b00;  
reg_MemWrite = 1'b0;  
reg_MemRead = 1'b0;  
reg_ALUOp  = 4'b0011;  
reg_RegDst  = 2'b00;  
    reg_Branch  = 1'b0;  
    reg_Jump   = 2'b00;  
    reg_pc_load = 1'b1;  
    reg_PC_Store = 1'b0;
```

end

```
6'b000010:begin  
//Jump instruction (j)
```

```
reg_ALUSrc = 1'bx;  
reg_RegWrite = 1'b0;  
  
reg_MemtoReg = 2'bxx;  
  
reg_MemWrite = 1'b0;  
reg_MemRead = 1'bx;  
  
reg_ALUOp = 4'bxxxx;  
reg_RegDst = 2'bxx;  
  
    reg_Branch = 1'b0;  
  
    reg_Jump = 2'b01;  
  
    reg_pc_load = 1'b1;  
  
    reg_PC_Store = 1'b0;  
  
    reg_PC_Store = 1'b0;
```

end

```
6'b0000011:begin  
//Jump and link instruction (jal)  
  
    reg_ALUSrc = 1'bx;  
    reg_RegWrite = 1'b1;  
  
    reg_MemtoReg = 2'b10;  
  
    reg_MemWrite = 1'b0;  
    reg_MemRead = 1'bx;  
  
    reg_ALUOp = 4'bxxxx;  
    reg_RegDst = 2'b10;  
  
        reg_Branch = 1'bx;  
        reg_Jump = 2'b01;  
        reg_pc_load = 1'b1;  
        reg_PC_Store = 1'b1;
```

```
end
```

```
6'b000100:begin  
  //branch equal  
  reg_ALUSrc      = 1'b0;  
  reg_RegWrite   = 1'b0;  
  
  reg_MemtoReg    = 2'bxx;  
  reg_MemWrite     = 1'b0;  
  reg_MemRead     = 1'bx;  
  
  reg_ALUOp       = 4'b0100;  
  
  reg_RegDst      = 2'bxx;  
    reg_Branch      = 1'b1;  
    reg_Jump        = 2'b00;  
    reg_pc_load    = 1'b1;  
  reg_PC_Store = 1'b0;
```

```
end
```

```
6'b000101:begin  
  //branch not equal  
  reg_ALUSrc      = 1'b0;  
  reg_RegWrite   = 1'b0;  
  
  reg_MemtoReg    = 2'bxx;  
  reg_MemWrite     = 1'b0;  
  reg_MemRead     = 1'bx;  
  
  reg_ALUOp       = 4'b0101;  
  
  reg_RegDst      = 2'bxx;  
    reg_Branch      = 1'b1;  
    reg_Jump        = 2'b00;  
    reg_pc_load    = 1'b1;
```

```
reg_PC_Store = 1'b0;

end

6'b000110:begin
//branch greater than

reg_ALUSrc      = 1'b0;
reg_RegWrite   = 1'b0;

reg_MemtoReg    = 2'bxx;
reg_MemWrite     = 1'b0;
reg_MemRead     = 1'bx;
reg_ALUOp       = 4'b0110;
reg_RegDst      = 2'bxx;

reg_Branch      = 1'b1;
reg_Jump        = 2'b00;
reg_pc_load    = 1'b1;
reg_PC_Store = 1'b0;

end

6'b000111:begin
//branch less than

reg_ALUSrc      = 1'b0;
reg_RegWrite   = 1'b0;

reg_MemtoReg    = 2'bxx;
reg_MemWrite     = 1'b0;
reg_MemRead     = 1'bx;
reg_ALUOp       = 4'b0111;
reg_RegDst      = 2'bxx;
```

```
    reg_Branch      = 1'b1;  
    reg_Jump       = 2'b00;  
    reg_pc_load   = 1'b1;  
    reg_PC_Store = 1'b0;  
  
end
```

```
6'b001001:begin  
  //branch greater or equal  
  reg_ALUSrc      = 1'b0;  
  reg_RegWrite   = 1'b0;  
  
  reg_MemtoReg    = 2'bxx;  
  reg_MemWrite    = 1'b0;  
  reg_MemRead     = 1'bx;  
  reg_ALUOp       = 4'b1000;  
  reg_RegDst     = 2'bxx;  
  reg_Branch      = 1'b1;  
  reg_Jump       = 2'b00;  
  reg_pc_load   = 1'b1;  
  reg_PC_Store = 1'b0;
```

```
end
```

```
6'b001010:begin  
  //branch less or equal  
  reg_ALUSrc      = 1'b0;  
  reg_RegWrite   = 1'b0;  
  
  reg_MemtoReg    = 2'bxx;  
  reg_MemWrite    = 1'b0;  
  reg_MemRead     = 1'bx;  
  reg_ALUOp       = 4'b1001;
```

```
reg_RegDst      = 2'bxx;
```

```
reg_Branch      = 1'b1;
```

```
reg_Jump        = 2'b00;
```

```
reg_pc_load    = 1'b1;
```

```
reg_PC_Store   = 1'b0;
```

```
end
```

```
default : begin
```

```
// defualt value we can use it if we will implement reset or unsupported instructions
```

```
reg_ALUSrc   = 1'b0;
```

```
reg_RegWrite = 1'b0;
```

```
reg_MemtoReg = 2'b00;
```

```
reg_MemWrite = 1'b0;
```

```
reg_MemRead  = 1'b0;
```

```
reg_ALUOp    = 2'b00;
```

```
reg_RegDst   = 2'b00;
```

```
reg_Branch   = 1'b0;
```

```
reg_Jump     = 2'b00;
```

```
reg_pc_load = 1'b1;
```

```
reg_PC_Store = 1'b0;
```

```
end
```

```
endcase
```

```
end
```

```
// assign the output wires
```

```
assign RegDst = reg_RegDst;
```

```

assign ALUSrc = reg_ALUSrc;
assign MemtoReg = reg_MemtoReg;
assign MemWrite = reg_MemWrite;
assign MemRead = reg_MemRead;
assign RegWrite = reg_RegWrite;
assign ALUOp = reg_ALUOp;
assign Branch= reg_Branch;
assign Jump = reg_Jump;
assign pc_load = reg_pc_load;
assign PC_Store = reg_PC_Store;

```

endmodule

## 1.24 Register file

```

module
RegisterFile(Clock,Reset,ReadReg1,ReadReg2,WriteReg,WriteData,Reg_write_Control,ReadData1,ReadData2,PC_Store);
input Clock , Reset;
input [4:0] ReadReg1 , ReadReg2 , WriteReg;
input Reg_write_Control;
input PC_Store;
input [31:0] WriteData;
output [31:0] ReadData1;
output [31:0] ReadData2;
// define bus (wires)
wire [31:0] Reg_Enable;
wire [31:0] Registers_Read [31:0];
// to get the register enable we want to write on
RegFile_decoder dex(WriteReg,Reg_write_Control,Reg_Enable);

```

```
// we first write then we read from register file

//write on Register file

RegFile_regn Reg_0(WriteData, 1'b1, Reg_Enable[0], Clock,Registers_Read[0]);
RegFile_regn Reg_1(WriteData, Reset, Reg_Enable[1], Clock,Registers_Read[1]);
RegFile_regn Reg_2(WriteData, Reset, Reg_Enable[2], Clock,Registers_Read[2]);
RegFile_regn Reg_3(WriteData, Reset, Reg_Enable[3], Clock,Registers_Read[3]);
RegFile_regn Reg_4(WriteData, Reset, Reg_Enable[4], Clock,Registers_Read[4]);
RegFile_regn Reg_5(WriteData, Reset, Reg_Enable[5], Clock,Registers_Read[5]);
RegFile_regn Reg_6(WriteData, Reset, Reg_Enable[6], Clock,Registers_Read[6]);
RegFile_regn Reg_7(WriteData, Reset, Reg_Enable[7], Clock,Registers_Read[7]);
RegFile_regn Reg_8(WriteData, Reset, Reg_Enable[8], Clock,Registers_Read[8]);
RegFile_regn Reg_9(WriteData, Reset, Reg_Enable[9], Clock,Registers_Read[9]);

RegFile_regn Reg_10(WriteData, Reset, Reg_Enable[10], Clock,Registers_Read[10]);
RegFile_regn Reg_11(WriteData, Reset, Reg_Enable[11], Clock,Registers_Read[11]);
RegFile_regn Reg_12(WriteData, Reset, Reg_Enable[12], Clock,Registers_Read[12]);
RegFile_regn Reg_13(WriteData, Reset, Reg_Enable[13], Clock,Registers_Read[13]);
RegFile_regn Reg_14(WriteData, Reset, Reg_Enable[14], Clock,Registers_Read[14]);
RegFile_regn Reg_15(WriteData, Reset, Reg_Enable[15], Clock,Registers_Read[15]);
RegFile_regn Reg_16(WriteData, Reset, Reg_Enable[16], Clock,Registers_Read[16]);
RegFile_regn Reg_17(WriteData, Reset, Reg_Enable[17], Clock,Registers_Read[17]);
RegFile_regn Reg_18(WriteData, Reset, Reg_Enable[18], Clock,Registers_Read[18]);
RegFile_regn Reg_19(WriteData, Reset, Reg_Enable[19], Clock,Registers_Read[19]);

RegFile_regn Reg_20(WriteData, Reset, Reg_Enable[20], Clock,Registers_Read[20]);
RegFile_regn Reg_21(WriteData, Reset, Reg_Enable[21], Clock,Registers_Read[21]);
RegFile_regn Reg_22(WriteData, Reset, Reg_Enable[22], Clock,Registers_Read[22]);
RegFile_regn Reg_23(WriteData, Reset, Reg_Enable[23], Clock,Registers_Read[23]);
RegFile_regn Reg_24(WriteData, Reset, Reg_Enable[24], Clock,Registers_Read[24]);
RegFile_regn Reg_25(WriteData, Reset, Reg_Enable[25], Clock,Registers_Read[25]);
```

```

RegFile_regn Reg_26(WriteData, Reset, Reg_Enable[26], Clock,Registers_Read[26]);
RegFile_regn Reg_27(WriteData, Reset, Reg_Enable[27], Clock,Registers_Read[27]);
RegFile_regn Reg_28(WriteData, Reset, Reg_Enable[28], Clock,Registers_Read[28]);
RegFile_regn Reg_29(WriteData, Reset, Reg_Enable[29], Clock,Registers_Read[29]);
RegFile_regn Reg_30(WriteData, Reset, Reg_Enable[30], Clock,Registers_Read[30]);
RegFile_regn Reg_31(WriteData, Reset, PC_Store, Clock,Registers_Read[31]);

```

```

// Read from Register file
// MUX1: Read first operand
//always @(posedge Clock) begin
assign ReadData1= Registers_Read[ReadReg1];
//end
// MUX2: Read second operand
assign ReadData2= Registers_Read[ReadReg2];
endmodule
////////////////*****Register File Modules *****
//***** 1 - decoder 5 --> 32 bit*****////////////////

module RegFile_decoder(inputs,enable,outputs);
    input [4:0] inputs;
    input enable;
    output [31:0] outputs;

    reg [31:0] decoder_output;

    always @ (*) begin

```

```

if (enable == 1'b1) begin
    case (inputs)
        5'b00000: decoder_output = 32'b00000000000000000000000000000001;
        5'b00001: decoder_output = 32'b00000000000000000000000000000010;
        5'b00010: decoder_output = 32'b000000000000000000000000000000100;
        5'b00011: decoder_output = 32'b0000000000000000000000000000001000;
        5'b00100: decoder_output = 32'b00000000000000000000000000000010000;
        5'b00101: decoder_output = 32'b000000000000000000000000000000100000;
        5'b00110: decoder_output = 32'b0000000000000000000000000000001000000;
        5'b00111: decoder_output = 32'b00000000000000000000000000000010000000;
        5'b01000: decoder_output = 32'b00000000000000000000000000000010000000;
        5'b01001: decoder_output = 32'b000000000000000000000000000000100000000;
        5'b01010: decoder_output = 32'b000000000000000000000000000000100000000;
        5'b01011: decoder_output = 32'b000000000000000000000000000000100000000;
        5'b01100: decoder_output = 32'b000000000000000000000000000000100000000;
        5'b01101: decoder_output = 32'b000000000000000000000000000000100000000;
        5'b01110: decoder_output = 32'b000000000000000000000000000000100000000;
        5'b01111: decoder_output = 32'b000000000000000000000000000000100000000;
        5'b10000: decoder_output = 32'b000000000000000000000000000000100000000;
        5'b10001: decoder_output = 32'b000000000000000000000000000000100000000;
        5'b10010: decoder_output = 32'b000000000000000000000000000000100000000;
        5'b10011: decoder_output = 32'b000000000000000000000000000000100000000;
        5'b10100: decoder_output = 32'b000000000000000000000000000000100000000;
        5'b10101: decoder_output = 32'b000000000000000000000000000000100000000;
        5'b10110: decoder_output = 32'b000000000000000000000000000000100000000;
        5'b10111: decoder_output = 32'b000000000000000000000000000000100000000;
        5'b11000: decoder_output = 32'b0000000100000000000000000000000000000000;
        5'b11001: decoder_output = 32'b0000001000000000000000000000000000000000;
        5'b11010: decoder_output = 32'b0000010000000000000000000000000000000000;
        5'b11011: decoder_output = 32'b000010000000000000000000000000000000000000;
        5'b11100: decoder_output = 32'b000100000000000000000000000000000000000000;

```

```

5'b11101: decoder_output = 32'b00100000000000000000000000000000;
5'b11110: decoder_output = 32'b01000000000000000000000000000000;
5'b11111: decoder_output = 32'b10000000000000000000000000000000;
default: decoder_output = 32'b00000000000000000000000000000000;

endcase
end
else begin
    decoder_output = 32'b00000000000000000000000000000000;
end
end
assign outputs = decoder_output;
endmodule
////////*****3 - register 32-bit *****////////

// don't forget to change the parameter when you do not 32 bit register
module RegFile_regn(R, Resetn, Rin, Clock, Q);
    parameter n = 32;
    input [n-1:0] R;
    input Resetn, Rin, Clock;
    output [n-1:0] Q;
    reg [n-1:0] Q;

    always @(posedge Clock)
        if (Resetn)
            Q <= 0;
        else if (Rin)
            Q <= R;
Endmodule

```

## 1.25 Sign extend

```
module sign_extend (
    input wire [15:0] extend,
    output wire [31:0] extended
);
assign extended[15:0] = extend[15:0];
assign extended[31:16] = {16{extend[15]}};
endmodule
```

## 1.26 Main

```
module Main (
    input clk,
    input reset,
    output wire [31:0] ReadData1,
    output wire [31:0] ReadData2,
    output wire [31:0] Writedata
);

//PC

wire [31:0] pc_final;//input
wire [31:0] pc_out;//output
wire [31:0] next_pc;//pc+4
wire [31:0] pc_inc;//4
assign pc_inc = 32'b0000000000000000000000000000100;
wire pc_load;//control
```

```
PC #(first_address(0), .pc_inc(4))
```

```
pc_inst (
```

```
.clk(clk),
```

```
.reset(reset),  
.target(pc_final),  
.pc_load(pc_load),  
// .branch_condition(Branch&zero),  
.pc(pc_out)  
);
```

//end of PC

//-----

//inst\_mem

wire[31:0] inst\_out;

wire [5:0] opcode;

wire [4:0] rs;

wire [4:0] rt;

wire [4:0] rd;

wire [4:0] shamt;

wire [5:0] funct;

wire [15:0] addrs;

wire [25:0] jump\_offset;

INST\_MEM #(size(32),.data\_width(32) )

inst\_mem (

// .clk(clk),

.reset(reset),

.address(pc\_out),

.inst\_out(inst\_out),

.opcode(opcode),

.rs(rs),

.rt(rt),

.rd(rd),

```
.shamt(shamt),  
.funct(funct),  
.addr(addrs),  
.jump(jump_offset)  
);
```

```
//end of inst_mem
```

```
//-----
```

```
//sign extend
```

```
wire [31:0] immediate_value;
```

```
sign_extend extender (
```

```
.extend(addrs),  
.extended(immediate_value)
```

```
);
```

```
//end of sign extend
```

```
//-----
```

```
//ControlUnit
```

```
wire ALUSrc, MemWrite, MemRead, RegWrite, Branch;
```

```
wire [3:0] ALUOp;
```

```
wire [1:0] RegDst;
```

```
wire [1:0] MemtoReg;
```

```
wire [1:0] Jump_signal;
```

```
ControlUnit control_inst (
```

```
    .Clock(clk),
```

```
    .Reset(reset),
```

```
    .opcode(opcode),
```

```
    .RegDst(RegDst),
```

```
    .ALUSrc(ALUSrc),
```

```
    .MemtoReg(MemtoReg),
```

```
    .MemWrite(MemWrite),
```

```
    .MemRead(MemRead),
```

```
    .RegWrite(RegWrite),
```

```
    .ALUOp(ALUOp),
```

```
    .Branch/Branch),
```

```
    .Jump(Jump_signal),
```

```
    .funct(funct),
```

```
    .pc_load(pc_load)
```

```
);
```

```
//end of ControlUnit
```

```
//-----
```

```
// Reg_File
```

```
wire [4:0] write_reg_input;
```

```
MUX5bit mux_inst (
```

```
    .a(rt),
```

```
    .b(rd),
```

```
    .select(RegDst),
```

```
    .out(write_reg_input)
```

```
);
```

```

//reg [31:0] ReadData0;
/* output wire [31:0] ReadData1;
output wire [31:0] ReadData2;
output wire [31:0] Writedata;*/

RegisterFile reg_file_inst (
.Clock(clk),
.Reset(reset),
.ReadReg1(rs),
.ReadReg2(rt),
.WriteReg(write_reg_input),
.Reg_write_Control(RegWrite),
.WriteData(Writedata), //still error // Writedata
.ReadData1(ReadData1),
.ReadData2(ReadData2)
//.Reg_Enable(Reg_Enable), // Connect Reg_Enable signal
//.Registers_Read(Registers_Read) // Connect Registers_Read signals
);

/* always @(posedge clk) begin
assign ReadData0 = ReadData1 ;
end*/
//end of Reg_File*/
//-----
//alu_cntrl

wire [3:0] Operation;
wire [2:0] branch_type;

```

```
alu_control alu_ctrl (
    .clk(clk),
    .FuncField(func),
    .ALUOp(ALUOp),
    .Operation(Operation),
    .branch_type(branch_type)
);
```

```
//end of alu_cntrl
```

```
//-----
```

```
// MUX2_1 alu_sec_input
```

```
wire [31:0] alu_second_input;

MUX2_1 alu_sec_input (
    .a(ReadData2),
    .b(immediate_value),
    .select(ALUSrc),
    .out(alu_second_input)
);
```

```
//end of MUX2_1 alu_sec_input
```

```
//-----
```

```
//ALU
```

```
wire [31:0] alu_output;
wire zero ;
```

```
ALU alu (
```

```
    .clk(clk),
```

```
.A(ReadData1),  
.B(alu_second_input),  
.ALUControl(Operation),  
.ShiftAmount(shamt),  
.branch_type(branch_type),  
.ALUOut(alu_output),  
.Zero(zero)  
);
```

//end of ALU

//-----

// DATA MAM

```
wire [31:0] Read_data;
```

RAM #(

```
.size(32),  
.data_width(32)
```

) ram (

```
.clk(clk),  
.reset(reset),  
.address(alu_output),  
.data_write(ReadData2),  
.write_en(MemWrite),  
.read_en(MemRead),  
.data_out(Read_data)
```

```
);

//end of DATA_MEM

//-----
//Write back

MUX4_1 Write_back (
    .a(alu_output),
    .b(Read_data),
    .c(next_pc),
    .select(MemtoReg),
    .out(Writedata)
);
```

```
//-----
//handling jump instruction
```

```
adder add(
    .a(pc_inc),
    .b(pc_out),
    .c(next_pc)
);
```

```
wire [31:0] jump_target;
assign jump_target = {next_pc[31:28], jump_offset, 2'b00};

//-----
//branch

wire [31:0] branch;
```

```
branch_control branch_main(  
    .extended_address(immediate_value),  
    .next_pc(next_pc),  
    .branch(branch)  
);
```

//-----

```
wire [31:0] pc_branch;
```

```
MUX2_1 pc_target(  
    .a(next_pc),
```

```
    .b(branch),  
    .select((Branch & zero)),  
    .out(pc_branch)
```

```
);
```

```
MUX4_1 pc_final_main(  
    .a(pc_branch),
```

```
    .b(jump_target),  
    .c(ReadData1),  
    .select(Jump_signal),  
    .out(pc_final)
```

```
);
```

Endmodule

## 1.27 ALU control

```
module alu_control(
    input clk,
    input [5:0] FuncField,
    input [3:0] ALUOp,
    output reg [3:0] Operation,
    output reg [2:0] branch_type
);

always @(ALUOp , FuncField) begin
    if (ALUOp == 4'b0000) begin
        Operation = 4'b0000;
    end
    else if(ALUOp == 4'b0010) begin
        case (FuncField)
            6'b100000: Operation = 4'b0000; // add
            6'b100010: Operation = 4'b0001; // sub
                6'b011000: Operation = 4'b0010; //mul
                6'b011010: Operation = 4'b0011; //div
            6'b000000: Operation = 4'b0100; //sll
            6'b000010: Operation = 4'b0101; //srl
            6'b100100: Operation = 4'b1000; // and
            6'b100101: Operation = 4'b1001; // or
                6'b100110: Operation = 4'b1010; //xor
                6'b100111: Operation = 4'b1011; //nor
            6'b101010: Operation = 4'b1110; // SLT
        endcase
    end
end
```

```
6'b100001: Operation = 4'b0110;      //addu
6'b100011: Operation = 4'b0111; //subu

default: Operation <= 4'b0000; // Default add operation

endcase

end

else if(ALUOp == 4'b0001)begin
    Operation = 4'b1000; // andi
end

else if(ALUOp == 4'b0011)begin
    Operation = 4'b1001; // ori
end

else if(ALUOp == 4'b0100)begin
    Operation = 4'b0001; // beq
    branch_type = 3'b001;
end

else if(ALUOp == 4'b0101)begin
    Operation = 4'b0001; // bne
    branch_type = 3'b010;
end

else if(ALUOp == 4'b0110)begin
    Operation = 4'b1110; // bgt
    branch_type = 3'b011;
```

```

end

else if(ALUOp == 4'b0111)begin
    Operation = 4'b1101; // blt
    branch_type = 3'b100;
end

else if(ALUOp == 4'b1000)begin
    Operation = 4'b1100; // bge
    branch_type = 3'b101;
end

else if(ALUOp == 4'b1001)begin
    Operation = 4'b1100; // ble
    branch_type = 3'b110;
end

else begin Operation = 4'b1111;
end
end

```

endmodule

## 1.28 Adder

```

module adder (
    input wire [31:0] a,
    input wire [31:0] b,
    output wire [31:0] c
);
    assign c = a + b;
endmodule

```

## 1.29 Branch control

```
module branch_control(  
    input wire [31:0] extended_address,  
    input wire [31:0] next_pc,  
    output wire [31:0] branch  
);  
  
    assign branch = (extended_address << 2) + next_pc;  
  
endmodule
```

## 1.30 RAM

```
module RAM #(  
    parameter size = 32,  
    parameter data_width = 32  
    // parameter once=1  
)(  
  
    input clk,  
    input reset,          // Reset signal  
    input [31:0] address,  
    input [data_width-1:0] data_write,  
    input write_en,  
    input read_en,  
    output wire [data_width-1:0] data_out  
  
    // output reg error  
);  
  
    reg [31:0] mem [0:31];  
    reg error;  
    // reg first=once;
```

```
// Declare a memory array with parameterized size and data width.
```

```
// reg [data_width-1:0] mem [0:size - 1];
```

```
initial begin
```

```
    // testcase 1
```

```
    //     mem[0] = 32'h00000003;
```

```
    //     mem[1] = 32'h00000008;
```

```
    //     mem[2] = 32'h00000005;
```

```
    //     mem[3] = 32'h00000002;
```

```
    //     mem[4] = 32'h00000032;
```

```
    //     mem[5] = 32'h00000032;
```

```
    //     mem[6] = 32'h00000032;
```

```
    //     mem[7] = 32'h00000032;
```

```
    //     mem[8] = 32'h00000032;
```

```
    //     mem[9] = 32'h00000032;
```

```
    //     mem[10] = 32'h00000032;
```

```
    //     mem[11] = 32'h00000032;
```

```
    //     mem[12] = 32'h00000032;
```

```
    //     mem[13] = 32'h00000032;
```

```
    //     mem[14] = 32'h00000032;
```

```
    //     mem[15] = 32'h00000032;
```

```
    //     mem[16] = 32'h00000032;
```

```
    //     mem[17] = 32'h00000068;
```

```
    //     mem[18] = 32'h00000065;
```

```
    //     mem[19] = 32'h0000006C;
```

```
    //     mem[20] = 32'h0000006C;
```



```

mem[7] = 32'b000000000000000000000000000011100; // 28

mem[8] = 32'b0000000000000000000000000000100000; // 32

mem[9] = 32'b0000000000000000000000000000100100; // 36

//mem[10]= 32'b00000000000000000000000000001110; // from insrtuction sw =>14

mem[11]= 32'b01111111111111111111111111111111; // big number

mem[12]= 32'b0000000000000000000000000000111; // 7

mem[13]= 32'b00100000000000000000000000000000; // big number -for overflow check-
mem[14]= 32'b11110000000000000000000000000000; // big number -for overflow check-
*/



// $readmemh("data_memory_initialization", mem );

end

// assign data_out = mem[address >> 2];

// assign data_out = (reset)?8'h00000000:mem[address >> 2];
assign data_out=(read_en)? ((reset)?8'h00000000:mem[address >> 2]):32'bxxxxxxxxxxxxxxxxxxxxxxxxxxxxxx;

integer i;

always @(posedge clk) begin

if (reset) begin

for (i = 0; i < size; i = i + 1) begin

mem[i] <= 32'b0;

end

error <= 0;

end

```

```
else if (write_en) begin
    // Write data
    mem[address >> 2] <= data_write;
end

end
endmodule
```

### 1.31 instruction memory

```
module INST_MEM #(
    parameter size = 32,
    parameter data_width = 32
) (
    // input clk,
    input reset,
    input [31:0] address,
    output reg [31:0] inst_out,
    output reg [5:0] opcode,
    output reg [4:0] rs,
    output reg [4:0] rt,
    output reg [4:0] rd,
    output reg [4:0] shamt,
    output reg [5:0] funct,
    output reg [15:0] addr,
    output reg [25:0] jump
);
    reg [31:0] inst_mem [0:size - 1];
```

initial begin // this should be removed because it is NOT synthesizable

```
//-----
```

```
// testcase 6
```

```
// /*Address 0 */ inst_mem[0] = 32'b00000000000000000000000000000000; //ADD R1, R0, R0  
// /*Address 4 */ inst_mem[1] = 32'b00000000000000000000000000000000; //ADD R2, R0, R0  
// /*Address 8 */ inst_mem[2] = 32'b00100000000010010000000001100100; //ADDI R9, R0, 100  
// /*Address 12 */ inst_mem[3] = 32'b0001000000001010010000000000000010; //BEQ R1, R9, EXIT //START  
// /*Address 16 */ inst_mem[4] = 32'b001000000010000100000000000000001; //ADDI R1, R1, 1  
// /*Address 20 */ inst_mem[5] = 32'b0000100000000000000000000000000011; //JUMP START  
// /*Address 24 */ inst_mem[6] = 32'b000000000000000010001000011000001000000; //ADD R3, R1, R2 //EXIT
```

```
// testcase 5
```

```
//a=2
```

```
// /*Address 0 */ inst_mem[0] = 32'b0010000000000000100000000000000010; //ADDI R1, R0, 2 (a)  
// /*Address 4 */ inst_mem[1] = 32'b0010000000000000100000000000000010; //ADDI R2, R0, 2 (b)  
// /*Address 8 */ inst_mem[2] = 32'b0010000001000011000000000000000011; //ADDI R3, R2, 3 (b+3)  
// /*Address 12 */ inst_mem[3] = 32'b0010010000100011000000000000000010; //BGE R1, R3, THEN  
// /*Address 16 */ inst_mem[4] = 32'b001000000010000100000000000000001; //ADDI R1, R1, 1  
// /*Address 20 */ inst_mem[5] = 32'b0000100000000000000000000000000011; //JUMP END  
// /*Address 24 */ inst_mem[6] = 32'b0010000000100001000000000000000010; //ADDI R1, R1, 2 //THEN  
// /*Address 28 */ inst_mem[7] = 32'b0000000000100000100010000001000000; //ADD R2, R2, R1 //END
```

```
//a=6
```

```
// /*Address 0 */ inst_mem[0] = 32'b0010000000000000100000000000000010; //ADDI R1, R0, 6 (a)
```

```
// /*Address 4 */ inst_mem[1] = 32'b00100000000001000000000000000010; //ADDI R2, R0, 2 (b)
// /*Address 8 */ inst_mem[2] = 32'b001000001000110000000000000011; //ADDI R3, R2, 3 (b+3)
// /*Address 12 */ inst_mem[3] = 32'b001001000100011000000000000010; //BGE R1, R3, THEN
// /*Address 16 */ inst_mem[4] = 32'b00100000010000100000000000000001; //ADDI R1, R1, 1
// /*Address 20 */ inst_mem[5] = 32'b000010000000000000000000000011; //JUMP END
// /*Address 24 */ inst_mem[6] = 32'b001000000100001000000000000010; //ADDI R1, R1, 2 //THEN
// /*Address 28 */ inst_mem[7] = 32'b00000000010000100100000100000; //ADD R2, R2, R1 //END
//
```

```
//-----
```

```
// testcase 4
```

```
//
// /*Address 0 */ inst_mem[0] = 32'b000000000000000000001000000000100000; //ADD R8, R0, R0
// /*Address 4 */ inst_mem[1] = 32'b00100000000100100000000000001010; //ADDI R9, R9, 10
// /*Address 8 */ inst_mem[2] = 32'b00000001000010010101000000100010; //SUB R10, R8, R9 //Loop
// /*Address 12 */ inst_mem[3] = 32'b00100000000110000000000000000001; //ADDI R12, R0, 1
// /*Address 16 */ inst_mem[4] = 32'b00011001000100100000000000000001; //BGT R8, R9, DONE
// /*Address 20 */ inst_mem[5] = 32'b00100001000010000000000000000001; //ADDI R8, R8, 1
// /*Address 24 */ inst_mem[6] = 32'b000010000000000000000000000000010; //JUMP LOOP
// /*Address 28 */ inst_mem[7] = 32'b00000001001000000110100000100000; //ADD R13, R9, R0 //DONE
// /*Address 32 */ inst_mem[8] = 32'b001000000001110000000000000000011011; //ADDI R14, R0, 1B(27)
// /*Address 36 */ inst_mem[9] = 32'b001100011001110000000000000000010111; //ANDI R14, R14, 17(23)
```

```
//-----
```

```
// testcase 3
```

```
// inst_mem[0] = 32'b00000000000000001110000000000000; //ADD R28,R0,R0 (R28=0)
// inst_mem[1] = 32'b10001111000100000000000000000000; //LW R8, 0(R28)
// inst_mem[2] = 32'b1000111100010010000000000000100; //LW R9, 4(R28)
// inst_mem[3] = 32'b00000001000010010100000000000000; //ADD R8, R8, R9
// inst_mem[4] = 32'b10001111000101000000000000001000; //LW R10, 8(R28)
// inst_mem[5] = 32'b00000001010010010100000000000000; //ADD R10, R10, R10
// inst_mem[6] = 32'b00000001000010100100000000000000; //SUB R8, R8, R10
// inst_mem[7] = 32'b00100001000010000000000000000001; //ADDI R8, R8, 1
// inst_mem[8] = 32'b00000000000010000100000000000000; //SUB R8, R0, R8
//
//
```

```
//-----
```

```
// testcase 2
```

```
// inst_mem[0] = 32'b10001100000000010000000000000000; //LW R1, 8(R0)
// inst_mem[1] = 32'b00000000000100000000000000000000; //SLL R1, R1, 2
// inst_mem[2] = 32'b10101100000000010000000000000000; //SW R1, 4(R0)
// inst_mem[3] = 32'b10001100000000010000000000000000; //LW R2, 4(R0)
// inst_mem[4] = 32'b10001100000000011000000000000000; //LW R3, 16(R0)
// inst_mem[5] = 32'b000000000010000000001100001000000; //SLL R3, R2, 1
// inst_mem[6] = 32'b10101100000000011000000000000000; //SW R3, 12(R0)
// inst_mem[7] = 32'b10001100000000010000000000000000; //LW R4, 12(R0)
//
//-----
```

```
// testcase 1
```

```

// inst_mem[0] = 32'b10001100000010000000000000000000; //LW R8, 0(R0)
// inst_mem[1] = 32'b10001100000010010000000000100000; //LW R9, 0x20(R0)
// inst_mem[2] = 32'b10001100000010100000000001010000; //LW R10, 0x50(R0)
// inst_mem[3] = 32'b10001100000010110000000000001000; //LW R11, 0x8(R0)
//
//-----
//THIS TEST FOR BLT
/*
inst_mem[0] = 32'b1000110000000001000000000000000100;//lw reg1=3
inst_mem[1] = 32'b1000110000100010000000000000000101;//lw reg2=8
inst_mem[2] = 32'b0001110000100010000000000000000001;//blt address=16 -->4*1+12 **should work**
inst_mem[3] = 32'b100011000010001100000000000010001;//lw reg3=20 **should not work**
inst_mem[4] = 32'b1000110000100010000000000000000000100;//lw reg4=12 **should work**

*/
//THIS TEST FOR BLT not working
/*
inst_mem[0] = 32'b1000110000000001000000000000000100;//lw reg1=3
inst_mem[1] = 32'b1000110000100010000000000000000101;//lw reg2=8
inst_mem[2] = 32'b00011100001000010000000000000000001;//blt address=16 -->4*1+12 **should not work**
inst_mem[3] = 32'b100011000010001100000000000010001;//lw reg3=20 **should work**
inst_mem[4] = 32'b1000110000100010000000000000000000100;//lw reg4=12 **should work**

*/
//THIS TEST FOR BGT
/*

```

```
inst_mem[0] = 32'b1000110000000001000000000000000100;//lw reg1=3  
inst_mem[1] = 32'b1000110000100010000000000000000101;//lw reg2=8  
inst_mem[2] = 32'b00011000010000100000000000000001;//bgt address=16 -->4*1+12 **should work**  
inst_mem[3] = 32'b100011000010001100000000000000010001;//lw reg3=20 **should not work**  
inst_mem[4] = 32'b10001100010001000000000000000000100;//lw reg4=12 **should work**  
*/
```

//THIS TEST FOR BGT not working

```
/*  
inst_mem[0] = 32'b1000110000000001000000000000000100;//lw reg1=3  
inst_mem[1] = 32'b1000110000100010000000000000000101;//lw reg2=8  
inst_mem[2] = 32'b000110000010001000000000000000001;//bgt address=16 -->4*1+12 **should not work**  
inst_mem[3] = 32'b100011000010001100000000000000010001;//lw reg3=20 **should work**  
inst_mem[4] = 32'b10001100010001000000000000000000100;//lw reg4=12 **should work**  
*/
```

//THIS TEST FOR BNE

```
/*  
inst_mem[0] = 32'b1000110000000001000000000000000100;//lw reg1=3  
inst_mem[1] = 32'b1000110000100010000000000000000101;//lw reg2=8  
inst_mem[2] = 32'b0001010000100010000000000000000001;//bne address=16 -->4*1+12 **should not work**  
inst_mem[3] = 32'b100011000010001100000000000000010001;//lw reg3=20 **should not work**  
inst_mem[4] = 32'b10001100010001000000000000000000100;//lw reg4=12 **should work**  
*/
```

//THIS TEST FOR BNE not working

```
/*  
inst_mem[0] = 32'b1000110000000001000000000000000100;//lw reg1=3
```

```
inst_mem[1] = 32'b100011000000001000000000000000100;//lw reg2=3  
inst_mem[2] = 32'b00010100001000100000000000000001;//bne address=16 -->4*1+12  
inst_mem[3] = 32'b100011000010001100000000000010001;//lw reg3=20 **should work**  
inst_mem[4] = 32'b1000110001000100000000000000001001;//lw reg4=12 **should work**  
*/
```

```
//THIS TEST FOR BEQ  
/*  
inst_mem[0] = 32'b1000110000000001000000000000000100;//lw reg1=3  
inst_mem[1] = 32'b1000110000000010000000000000000100;//lw reg2=3  
inst_mem[2] = 32'b00010000001000100000000000000001;//beq address=16 -->4*1+12  
inst_mem[3] = 32'b1000110000100011000000000000010001;//lw reg3=20 **should not work**  
inst_mem[4] = 32'b1000110001000100000000000000001001;//lw reg4=12 **should work**  
*/
```

```
//THIS TEST FOR BEQ not working  
/*  
inst_mem[0] = 32'b1000110000000001000000000000000100;//lw reg1=3  
inst_mem[1] = 32'b100011000010001000000000000000101;//lw reg2=8  
inst_mem[2] = 32'b00010000001000100000000000000001;//beq address=16 -->4*1+12 **should not work**  
inst_mem[3] = 32'b1000110000100011000000000000010001;//lw reg3=20 **should work**  
inst_mem[4] = 32'b100011000100010000000000000000100;//lw reg4=12 **should work**  
*/
```

```
/* THIS TEST FOR JUMP INSTRUCTIONS  
inst_mem[0] = 32'b10001100000000010000000000001100;//load 12 in reg1  
inst_mem[1] = 32'b000011000000000000000000000000011;//jump to inst_mem[3] and save pc+1 in reg31 (jal)
```

```

// inst_mem[1] = 32'b0000000000100000000000000000001000;//jump to content of reg1 (pc=12)
//      inst_mem[1] = 32'b00001000000000000000000000000000100;//jump to inst_mem[4] and skip inst_mem[3]
inst_mem[2] = 32'b1000110000000100000000000000000010100;//load 20 in reg2

inst_mem[3] = 32'b100011000000011000000000000000001000;//load 8 in reg3

*/
/*



inst_mem[0] = 32'b10001100000000010000000000000000100;           //LW      $1 , $4(0) -> load the content of address
(content of reg 0 + 4=4) in ram to reg1 =3

inst_mem[1] = 32'b10001100001000100000000000000000101;           //LW  $2 , $5(1)      -> load the content of address
(content of reg 3 + 5=8) in ram to reg2 =8

inst_mem[2] = 32'b00000000001000100101000000100000;           //add  $10,$1,$2  -> add the content of reg 1 and 2
then store it in reg 10 = 11

inst_mem[3] = 32'b100011000010001100000000000010001;   //LW  $3 , $17(1) -> load the content of address (content of reg
1(3) + 17=20) in ram to reg3 =20

inst_mem[4] = 32'b001000000100010100000000000000110;          //addi $5,$2,6      -> add the content of reg2 to 6
(8+6 =14) then store it in reg5 =14

inst_mem[5] = 32'b10001100001000100000000000000000100;          //LW  $4 , $4(3) -> load the content of address (content
of reg2 (8) + 4=12) in ram to reg4 =12

inst_mem[6] = 32'b000000000101000010011000000100010;          //sub  $6,$5,$1      -> sub the content of
reg1 from reg5 (14-3=11) then store it in reg6=11

inst_mem[7] = 32'b000000000001000100011100000100010;          //sub  $7,$1,$2      -> sub the content of
reg10 from reg1 (3-8=-5) then store it in reg7=-5

inst_mem[8] = 32'b000000000001010100100000000100100;          //and  $8,$1,$10  -> and the content of reg10 with reg2
(ans:3) then store it in reg8=3

inst_mem[9] = 32'b000000000001010100100100000100101;          //or   $9,$1,$10  -> or the content of reg10 with
reg2 (ans:11) then store it in reg9=11

inst_mem[10] = 32'b000000000110001000101100000100110; //xor  $11,$4,$6      -> xor the content of reg15 with reg10
(ans:3) then store it in reg11=7

inst_mem[11] = 32'b0000000001000110011000000100111; //nor  $12,$2,$6      -> nor the content of reg15 with reg10
(ans:8) then store it in reg12=-12

inst_mem[12] = 32'b000000000001001110110100000011000; //mul  $13,$1,$7      -> mul the content of reg1 with reg7
(ans:-5*3=-15) then store it in reg13=-15

```

/\*

## checking LW muliable times

```
inst_mem[0] = 32'b100011000000000100000000000000100; //reg1=3  
  
inst_mem[1] = 32'b100011000010001000000000000000101; //reg2=8  
  
inst_mem[2] = 32'b100011000010001100000000000010001; //reg3=20  
  
inst_mem[3] = 32'b100011000000111100000000000101000; //reg15=14
```

```
inst_mem[4] = 32'b100011000001001000000000000101100; //reg18=big
inst_mem[5] = 32'b100011000001001100000000000101100; //reg19=big
inst_mem[6] = 32'b100011000001010100000000000101100; //reg21=big_num
inst_mem[7] = 32'b10101100000101010000000000000000000000000000; // m[0]=big_num
inst_mem[8] = 32'b10001100000101100000000000000000000000000000; //reg22=big*/
end
```

```
integer i;
```

```
always @(*) begin
    if (reset) begin
        for (i = 0; i < size; i = i + 1) begin
            inst_mem[i] <= 32'b0;
        end
    end
    else begin
        inst_out <= inst_mem[address >> 2];
        opcode <= inst_out[31:26];
        rs <= inst_out[25:21];
        rt <= inst_out[20:16];
        rd <= inst_out[15:11];
        shamt <= inst_out[10:6];
        funct <= inst_out[5:0];
        addr <= inst_out[15:0];
        jump <= inst_out[25:0];
    end
end
```

/\*

after doing this code the registers values are :

reg1	3
reg2	8
reg3	20
reg4	12
reg5	14
reg6	11
reg7	-5
reg8	3
reg9	11
reg10	11
reg11	7
reg12	-12
reg13	-15
reg14	4
reg15	14
reg16	13
reg17	4
reg18	$(2^{31})-1$
reg19	$(2^{31})-1$
reg20	don't care
reg21	big num -overflow check-
reg22	big num -overflow check-
reg23	don't care

```

*/



//          ((I type -> load and store))

//    Opcode | RS | RD | Offset/Immediate

//        6           5           5           16

//          (( R type))

//    Opcode | RS | RT | RD | Function Code

//        6           5           5           5           6

//          RAM :

//          add   data

//          0           2

//          4           3

//          8           8

//          12          12

//          16          6

//          20          20

//          24          24

//          28          28

//          32          32

//          36          36

//          40          14

//          44          (2^31-1)

```

```
//          48          8'h2000000
//          52          8'hF000000
```

```
//$readmemh("./memfile_text.hex",mem,0,63);
```

```
/* 'initial begin' should be removed because it is NOT synthesizable
```

```
status register must be added
```

```
initialize memories after reset
```

```
subu overflow check !!!
```

```
*/
```

```
endmodule
```