DSP Final Project Report

MATLAB®

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(1) Sampling and periodicity of sinusoidal signals :

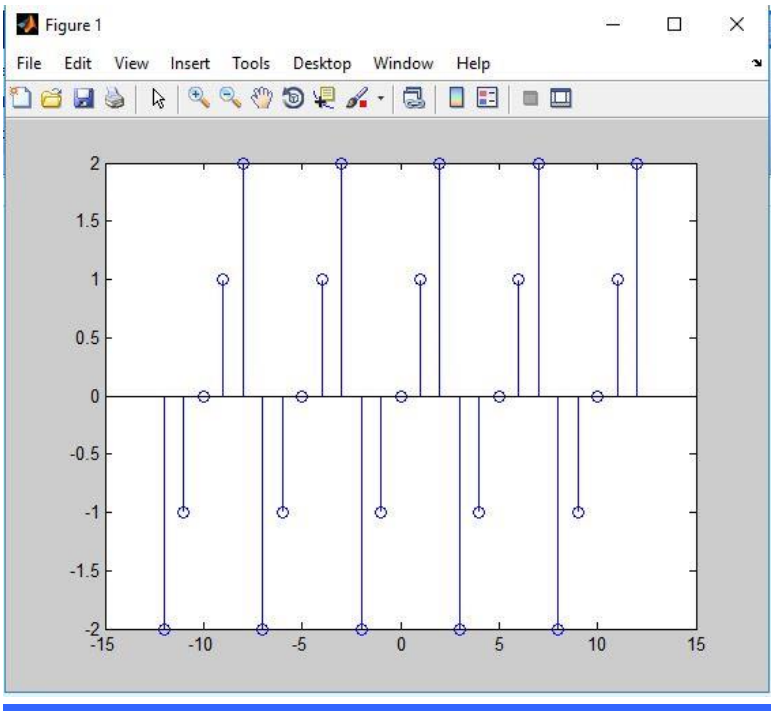
a-

1-

Code:

```
>> n=[-12:1:12];
>>x1n=[-2:1:2,-2:1:2,-2:1:2,-2:1:2,-2:1:2];
>> stem(n,x1n)
```

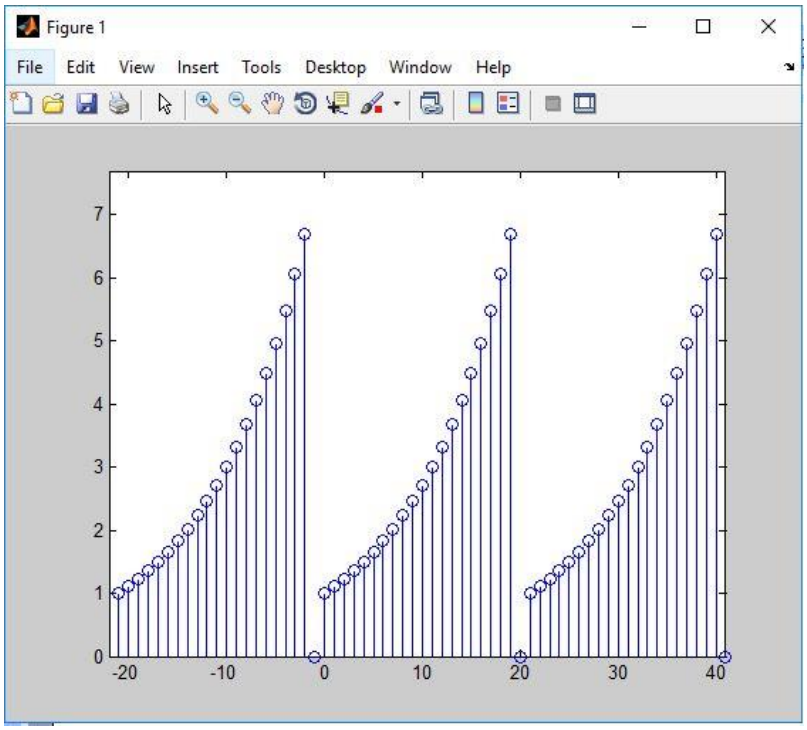
Output:



2-Code:

```
x2n=stepseq(0,0,20)-stepseq(20,0,20);
n=[0:20];
e=exp(0.1*n);
x2n=e.*x2n;
x2n=[x2n,x2n,x2n];
np=[-21:41];
stem(np,x2n);
axis([min(np)-2,max(np)+2,min(x2n),max(x2n)+2]);
```

Output:

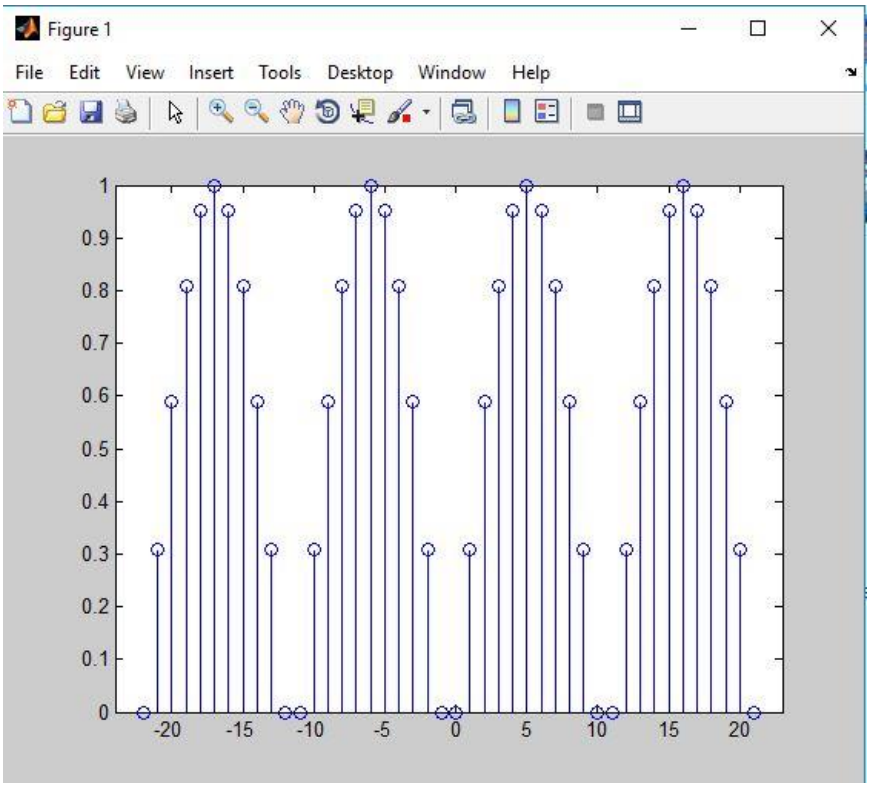


3-

Code:

```
x3n=stepseq(0,0,10)-stepseq(10,0,10);
n=[0:10];
s=sin(0.1*pi*n);
x3n=s.*(x3n);
x3n=[x3n,x3n,x3n,x3n];
n=[-21:22];
stem(n,x3n);
axis([min(n)-2,max(n)+2,min(x2n),max(x2n)])
```

Output:



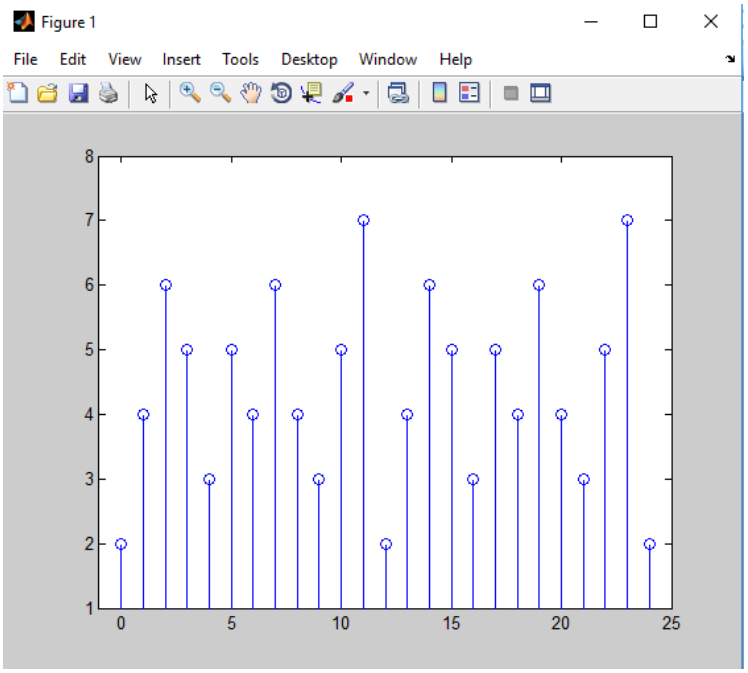
4-

Code:

```
>> n=[0:24];
>>x4a=[1 2 3];
>>x4a=repmat(x4a,[1 9]);
>>x4b=[1 2 3 4];
>>x4b=repmat(x4b,[1 7]);
>>x4=x4a(1:25)+x4b(1:25);
>>stem(n4,x4);
>>axis([min(n4)-1,max(n4)+1,min(x4)-1,max(x4)+1]);
```

Output:

The period of x4(n) is [2 3 4 6 3 5 4 5 4 3 5 7] and there is 2 periods from n = 0:24.



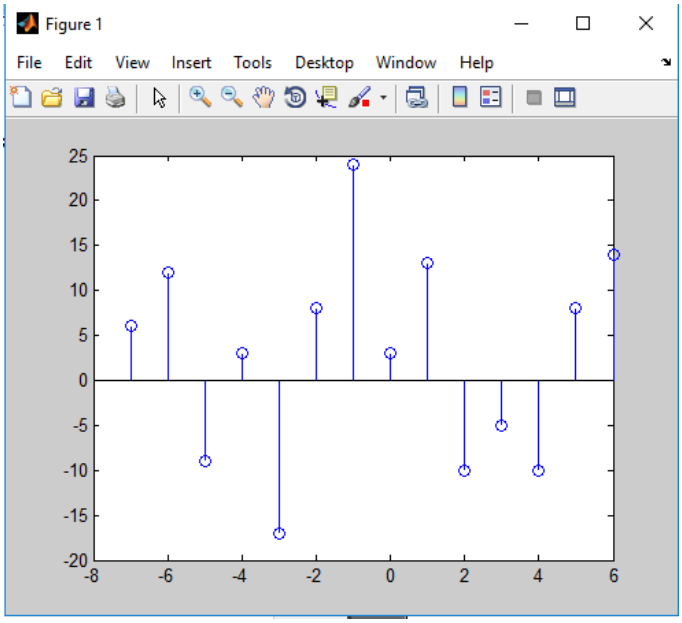
b-

```
>> x=[2 4 -3 1 -5 4 7];
>> n=[-3:3];
```

1) b-Code:

```
>> [x11,n11]=sigshift(x,n,3);
>> [x12,n12]=sigshift(x,n,-4);
>> [x1,n1]=sigadd(2*x11,n11,3*x12,n12);
>> [x1,n1]=sigadd(x1,n1,-x,n);
>> stem(n1,x1);
```

Output:

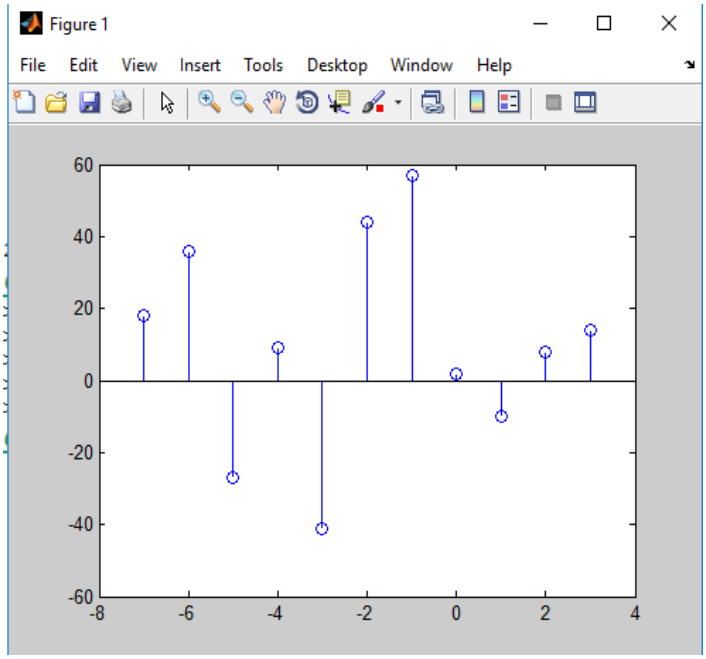


2) b-

Code:

```
>> [x21,n21]=sigshift(x,n,-4);
>> [x22,n22]=sigshift(x,n,-5);
>> [x2,n2]=sigadd(4*x11,n11,5*x12,n12);
>> [x2,n2]=sigadd(x2,n2,2*x,n);
>> stem(n2,x2);
```

Output:

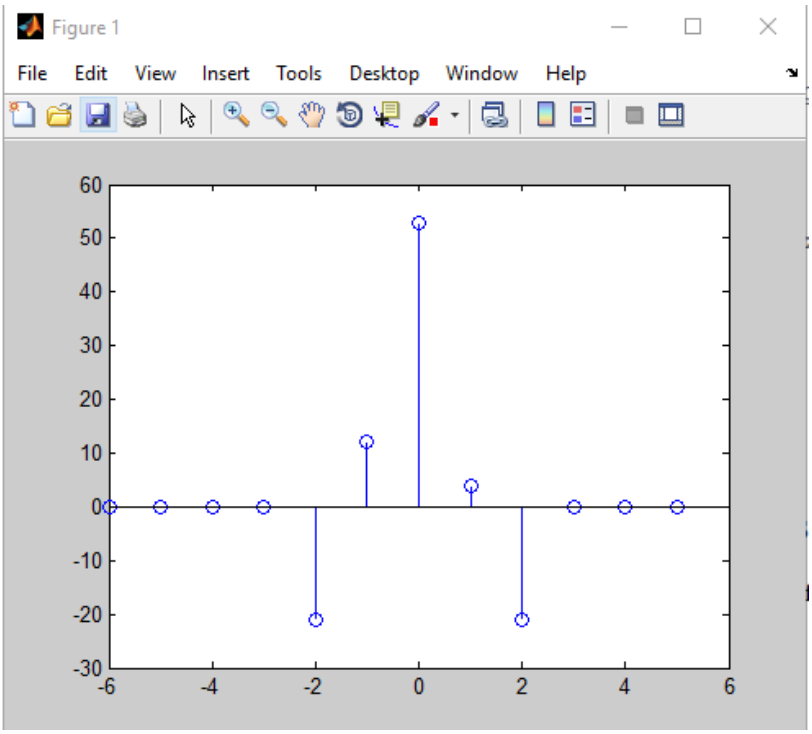


3) b-

Code:

```
>> x=[2 4 -3 1 -5 4 7];
>> n=[-3:3];
>> [x31,n31]=sigshift(x,n,-3);
>> [x32,n32]=sigshift(x,n,2);
>> [x32,n32]=sigmult(x31,n31,x32,n32);
>> [x33,n33]=sigfold(x,n);
>> [x33,n33]=sigshift(x33,n33,1);
>> [x34,n34]=sigshift(x,n,-1);
>> [x33,n33]=sigmult(x33,n33,x34,n34);
>> [x3,n3]=sigadd(x32,n32,x33,n33);
>> stem(n3,x3);
```

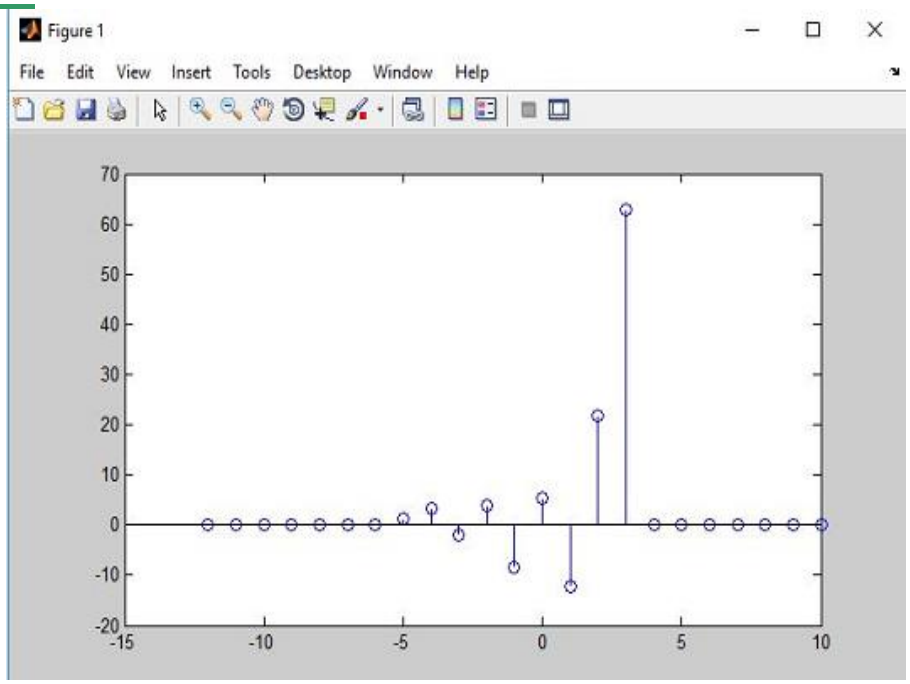
Output:



4) b-
Code:

```
>> x=[2 4 -3 1 -5 4 7];
>> n=[-3:3];
>> z=[zeros(1,7)];
>> xz = horzcat(z,x,z);
>> nz=[-10:10];
>> e=2*exp(0.5*nz);
>> c=cos(0.1*pi*nz);
>> [x41,n41]=sigshift(xz,nz,-2);
>> [x4,n4]=sigadd(e.*(xz),nz,c.*(x41),n41);
>> stem(n4,x4);
```

Output:



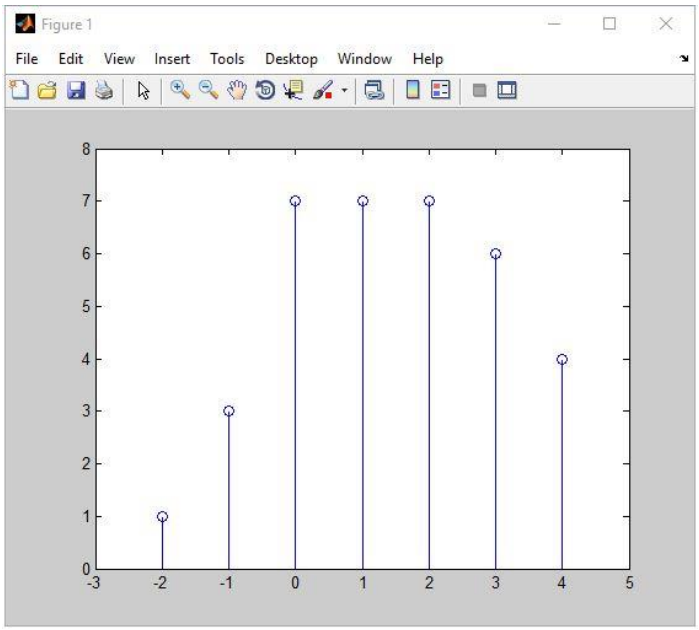
2)Time-Domain Analysis of LTI Systems

i-Code:

```
x1=[1,2,4];
nx=[0:2];
h1=[ones(1,5)];
nh=[-2:2];
[y,ny]=conv_m(x1,nx,h1,nh)
stem(ny,y)
axis([min(ny)-1,max(ny)+1,min(y)-1,max(y)+1])
```

Output:

```
y =

     1     3     7     7     7     6     4

ny =

    -2    -1     0     1     2     3     4
```

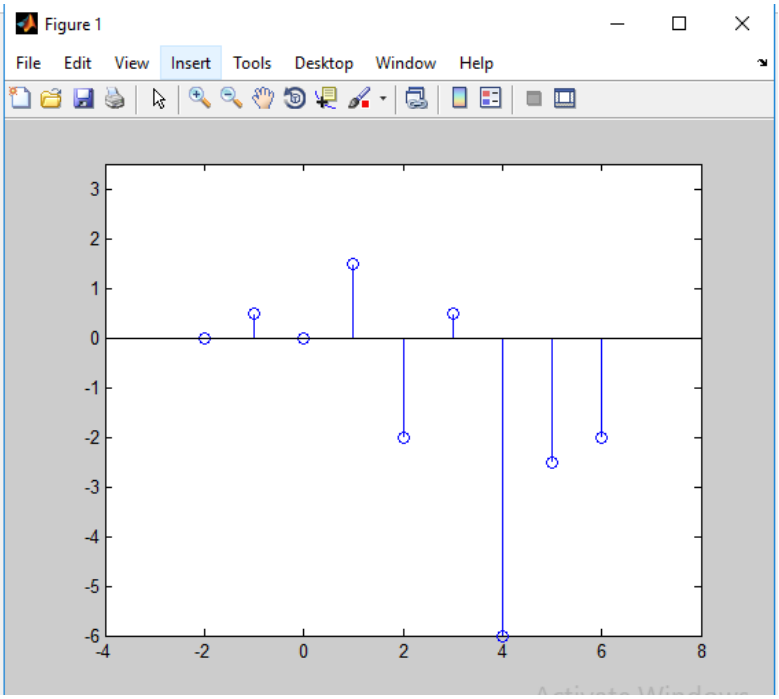


ii-Code:

```
>> x2=[0,1,-2,3,-4];
>> nx2=[0:4];
>> h2=[0.5,1,2,1,0.5];
>> nh2=[-2:2];
>>[y2,ny2]=conv_m(x2,nx2,h2,nh2);
```

Output:

```
y2 =

  Columns 1 through 5

         0    0.5000         0    1.5000   -2.0000

  Columns 6 through 9

    0.5000   -6.0000   -2.5000   -2.0000


ny2 =

    -2    -1     0     1     2     3     4     5     6
```



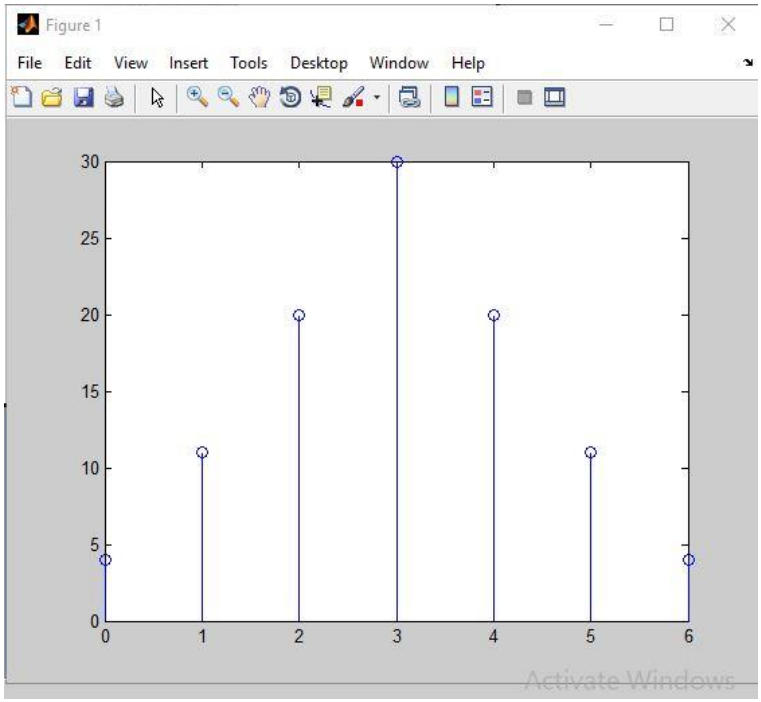
iii-

Code:

```
x3=[1,2,3,4];
nx3=[0:3];
h3=[4,3,2,1];
nh3=[0:3];
y3=conv(x3,h3);
ny3=[0:nx3(length(nx3))+nh3(length(nh3))];
stem(ny3,y3);
```

Output:

```
y3 =

     4    11    20    30    20    11     4

ny3 =

     0     1     2     3     4     5     6
```



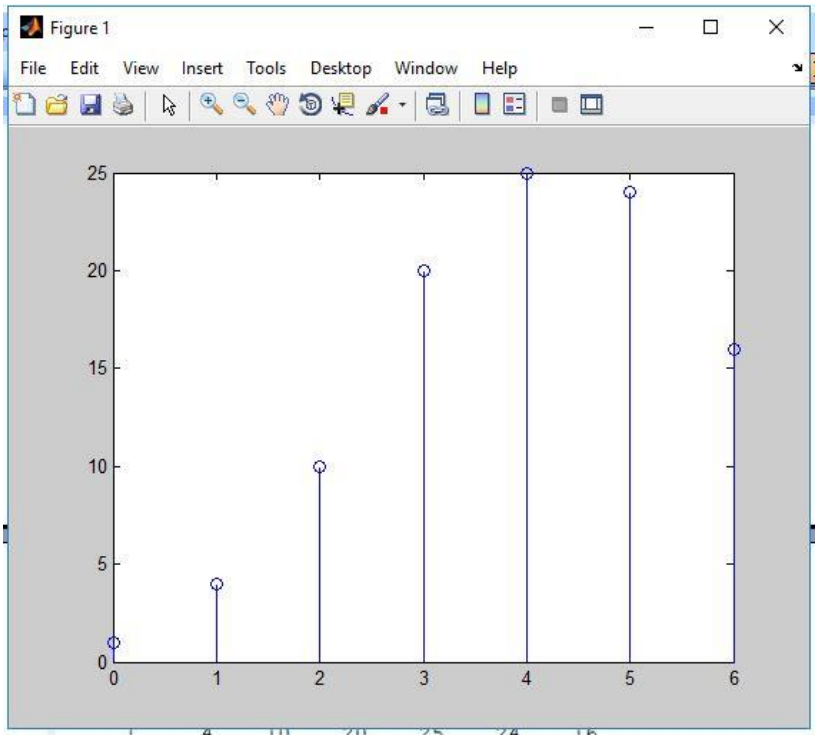
iiii-

Code:

```
>> x4=[1,2,3,4];
>> nx4=[0:3];
>> h4=[1,2,3,4];
>> nh4=[0:3];
>> y4=conv(x4,h4);
>> stem(ny4,y4);
```

Output:

```
y4 =

     1     4    10    20    25    24    16

ny4 =

     0     1     2     3     4     5     6
```



3-Z-Transform analysis of discrete-systems

(a)

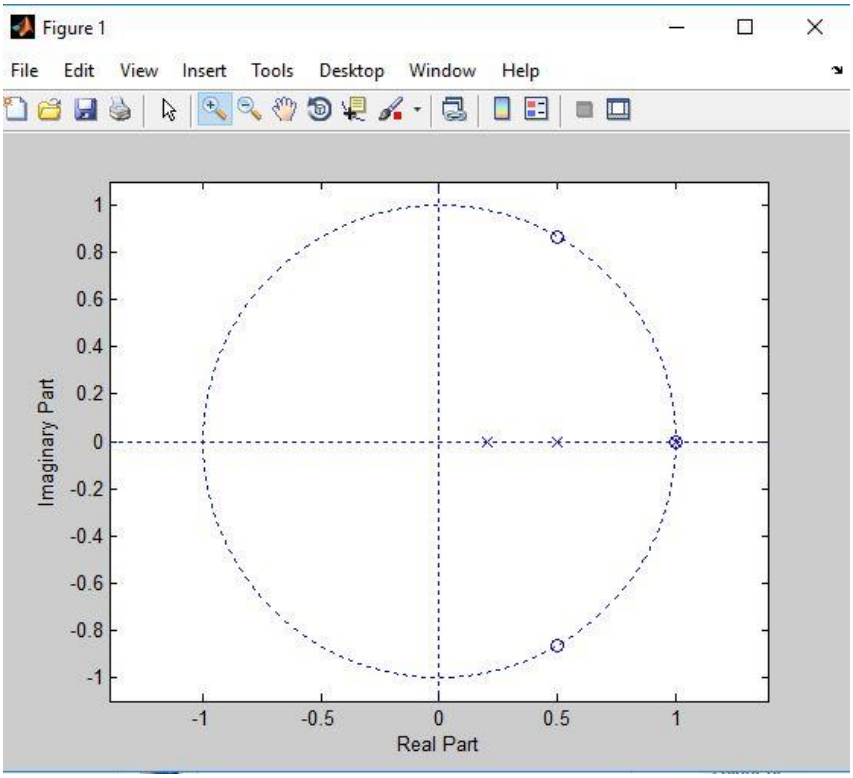
i.Code:

```
>> num=[1 -2 2 -1];
>> den=[1 -1.7 0.8 -0.1];
>> H=tf(num,den,0.1,'Variable','z^-1')
>> zplane(num,den)
```

Output:

```
H =

      1 - 2 z^-1 + 2 z^-2 - z^-3
  ---------------------------------
  1 - 1.7 z^-1 + 0.8 z^-2 - 0.1 z^-3

Sample time: 0.1 seconds
Discrete-time transfer function.
```

1st-Method to check Stability → zplane(num,den)



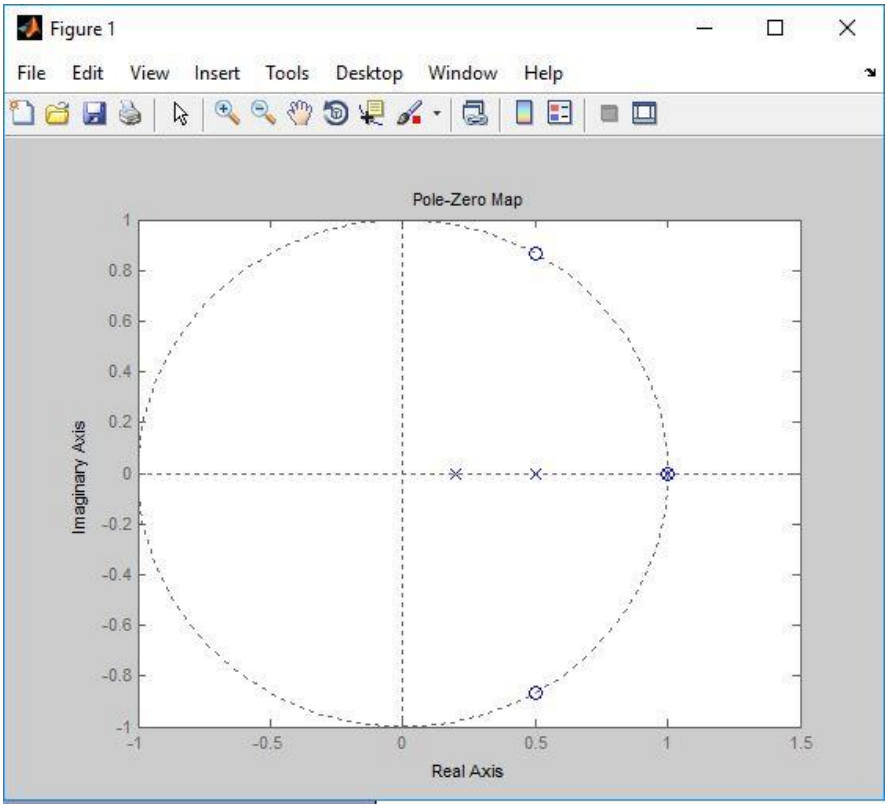
Marginally Stable → as there is one pole on the unit circle | P | =1

*2nd Method to check Stability → [p,z]=**pzmap(H)***

Code :

```
>>[p,z]=pzmap(H)
```

Output:



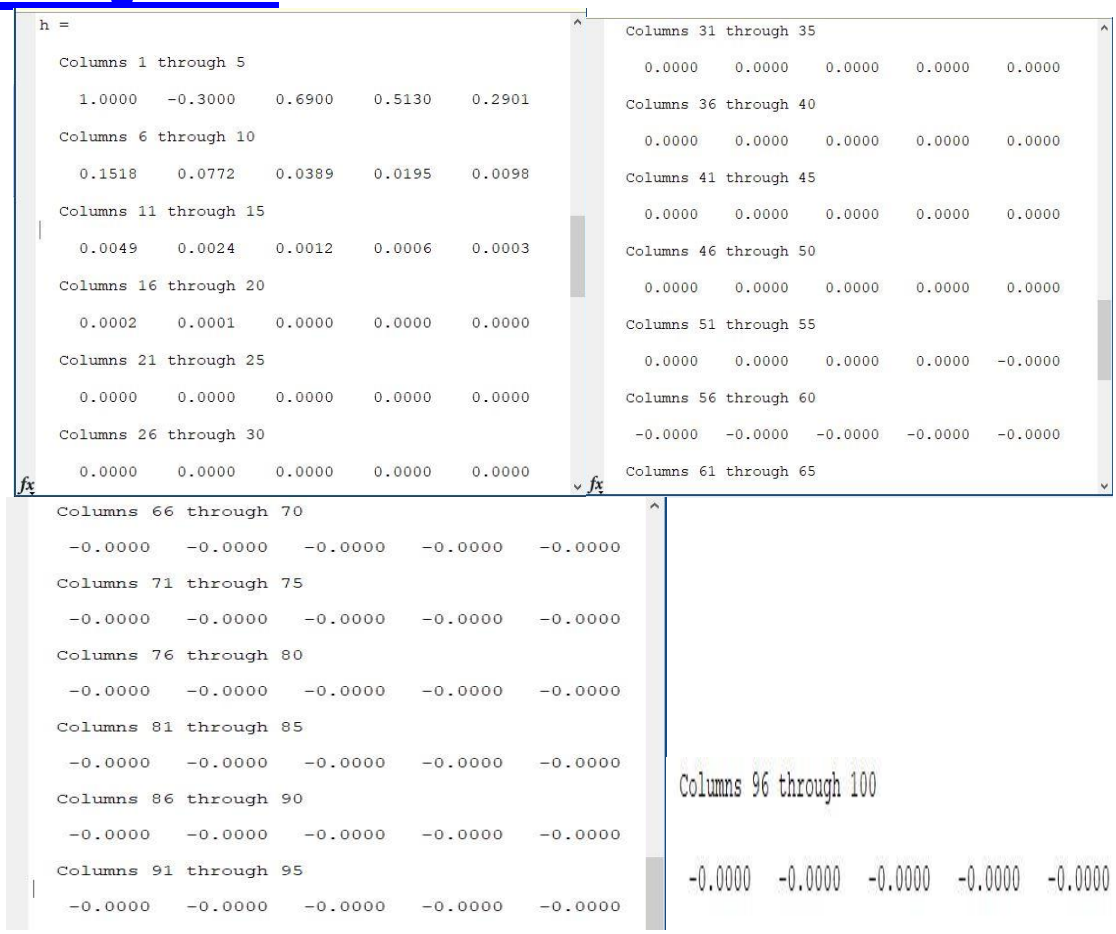
Marginally Stable → as there is one pole on the unit circle | P | =1

```
p =

    1.0000
    0.5000
    0.2000


z =

   1.0000 + 0.0000i
   0.5000 + 0.8660i
   0.5000 - 0.8660i

>> abs(p)

ans =

    1.0000
    0.5000
    0.2000
```

ii-Impulse Response

Code: >> h=filter(num,den,[1 zeros(1,N-1)])

Output:



(b).Code:

```
>> num=[0.03 -0.02 0.01];
>> den=[1 -2.8 3.02 -1.468 0.27];
>> H=tf(num,den,0.1,'Variable','z^-1')
```

Output:

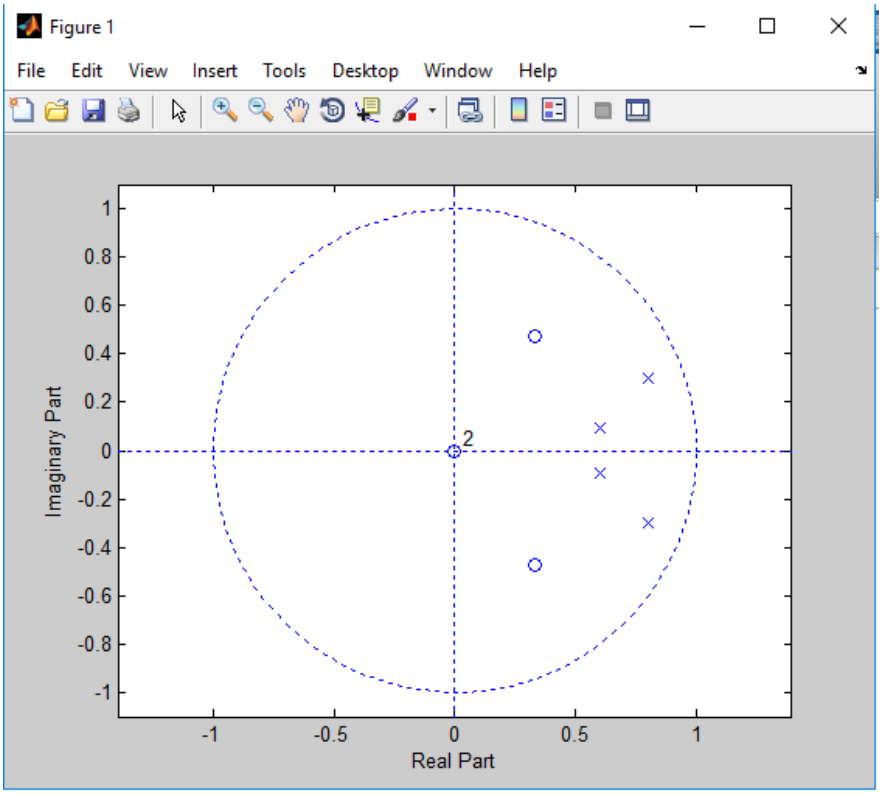
```
H =

            0.03 - 0.02 z^-1 + 0.01 z^-2
  ---------------------------------------------------
  1 - 2.8 z^-1 + 3.02 z^-2 - 1.468 z^-3 + 0.27 z^-4

Sample time: 0.1 seconds
Discrete-time transfer function.
```

Discussing Stability:

Code:

>> zplane(num,den)
[p,z]=pzmap(H)

Output:



Stable System since all the poles lies inside the unit circle.|P|<1

```
>> zplane(num,den)
>> [p,z]=pzmap(H)

p =

   0.7988 + 0.3004i
   0.7988 - 0.3004i
   0.6012 + 0.0962i
   0.6012 - 0.0962i


z =

   0.0000 + 0.0000i
   0.0000 + 0.0000i
   0.3333 + 0.4714i
   0.3333 - 0.4714i

>> abs(p)

ans =

    0.8534
    0.8534
    0.6089
    0.6089
```

Code: ″ x(n)=5u(n) ″

```
>> N=100;
>> x=5*ones(1,N)
>> y=filter(num,den,x)
```

Output:

```
y =
  Columns 1 through 6
    0.1500    0.4700    0.9630    1.5972    2.3134    3.0406
  Columns 7 through 12
    3.7121    4.2760    4.7012    4.9784    5.1165    5.1386
  Columns 13 through 18
    5.0750    4.9584    4.8190    4.6814    4.5634    4.4751
  Columns 19 through 24
    4.4200    4.3963    4.3986    4.4195    4.4512    4.4866
  Columns 25 through 30
    4.5201    4.5478    4.5677    4.5793    4.5833    4.5812
  Columns 31 through 36
    4.5751    4.5667    4.5579    4.5498    4.5433    4.5389
  Columns 37 through 42
    4.5365    4.5360    4.5368    4.5386    4.5407    4.5429
  Columns 43 through 48
    4.5448    4.5463    4.5473    4.5478    4.5478    4.5475
  Columns 49 through 54
    4.5470    4.5465    4.5460    4.5455    4.5452    4.5449
  Columns 55 through 60
    4.5449    4.5449    4.5450    4.5451    4.5452    4.5454
  Columns 61 through 66
    4.5455    4.5455    4.5456    4.5456    4.5456    4.5456
  Columns 67 through 72
    4.5455    4.5455    4.5455    4.5454    4.5454    4.5454
  Columns 73 through 78
    4.5454    4.5454    4.5454    4.5454    4.5454    4.5455
  Columns 79 through 84
    4.5455    4.5455    4.5455    4.5455    4.5455    4.5455
  Columns 85 through 90
    4.5455    4.5455    4.5455    4.5455    4.5455    4.5455
  Columns 91 through 96
    4.5455    4.5455    4.5455    4.5455    4.5455    4.5455
  Columns 97 through 100
    4.5455    4.5455    4.5455    4.5455
```

(4) Fourier-transform analysis of discrete systems

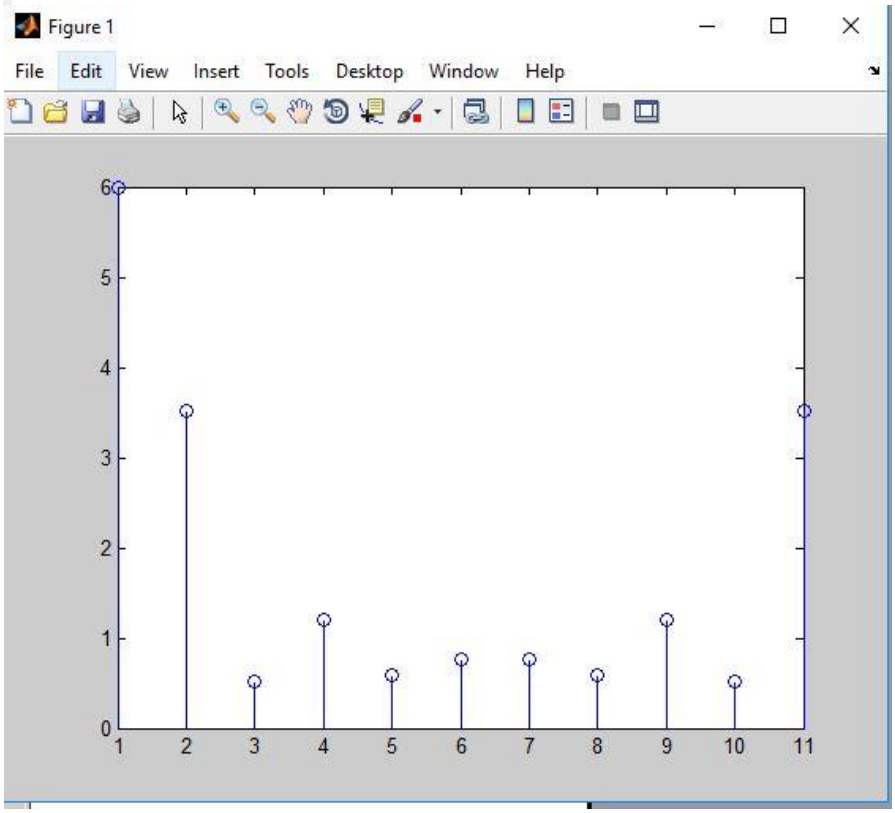
a. Code:

```
na=[0:10];
xa=stepseq(0,0,10)-stepseq(6,0,10);
xa=fft(xa);
xaMag=abs(xa);
stem(xaMag);
xaPhase=angle(xa);
stem(xaPhase);
```

Output:

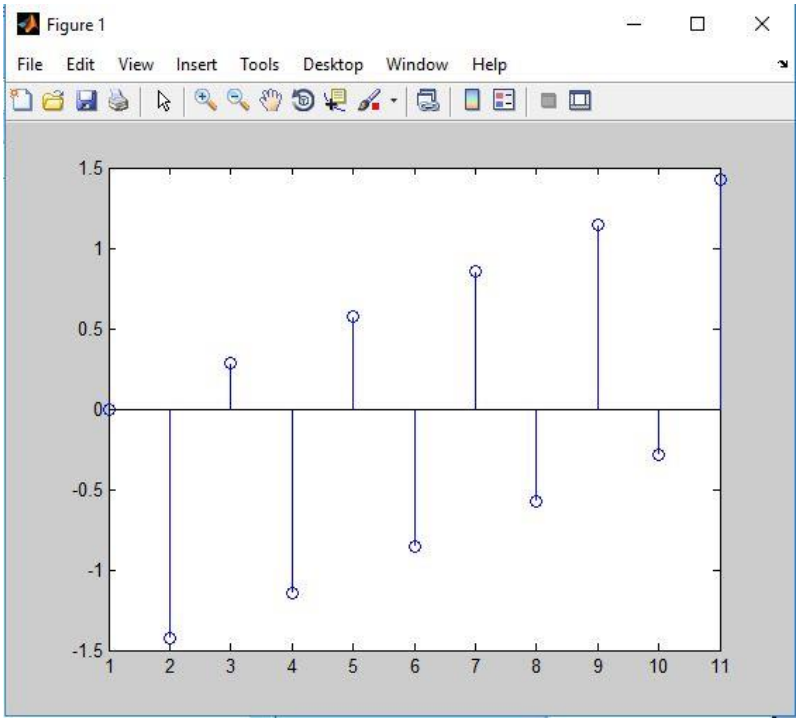
Magnitude:

```
xaMag =

  Columns 1 through 6

    6.0000    3.5133    0.5211    1.2036    0.5944    0.7635

  Columns 7 through 11

    0.7635    0.5944    1.2036    0.5211    3.5133
```



Phase:

```
xaPhase =

  Columns 1 through 6

         0   -1.4280    0.2856   -1.1424    0.5712   -0.8568

  Columns 7 through 11

    0.8568   -0.5712    1.1424   -0.2856    1.4280
```



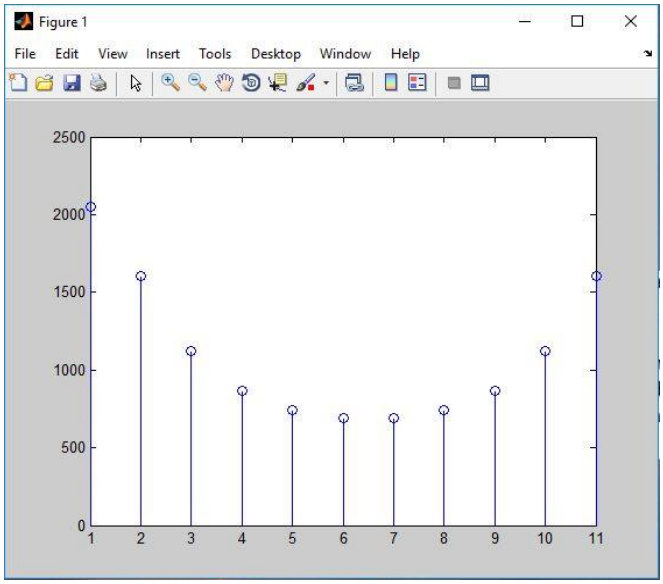
b-Code:

```
>> nb=[0:10];
>> cb=2.^nb;
>> xb=stepseq(0,0,10);
>> [xb,nb]=sigfold(cb.^(xb),nb);
>> xbF=fft(xb);
>> xbMag=abs(xbF);
>> xbPhase=phase(xbF);
```

Output:

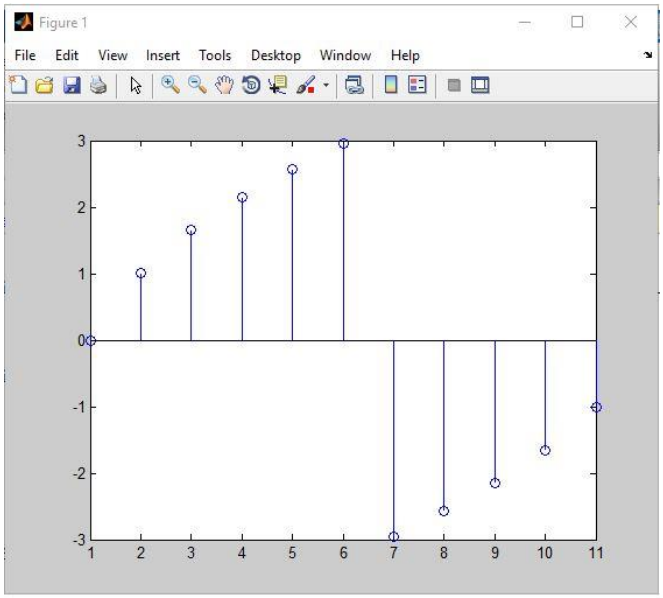
Magnitude:

```
xbMag =

   1.0e+03 *

    2.0470    1.6009    1.1203    0.8674    0.7416    0.6886    0.6886    0.7416    0.8674    1.1203    1.6009
```



Phase:

```
xbPhase =

         0    1.0077    1.6635    2.1464    2.5621    2.9509   -2.9509   -2.5621   -2.1464   -1.6635   -1.0077
```



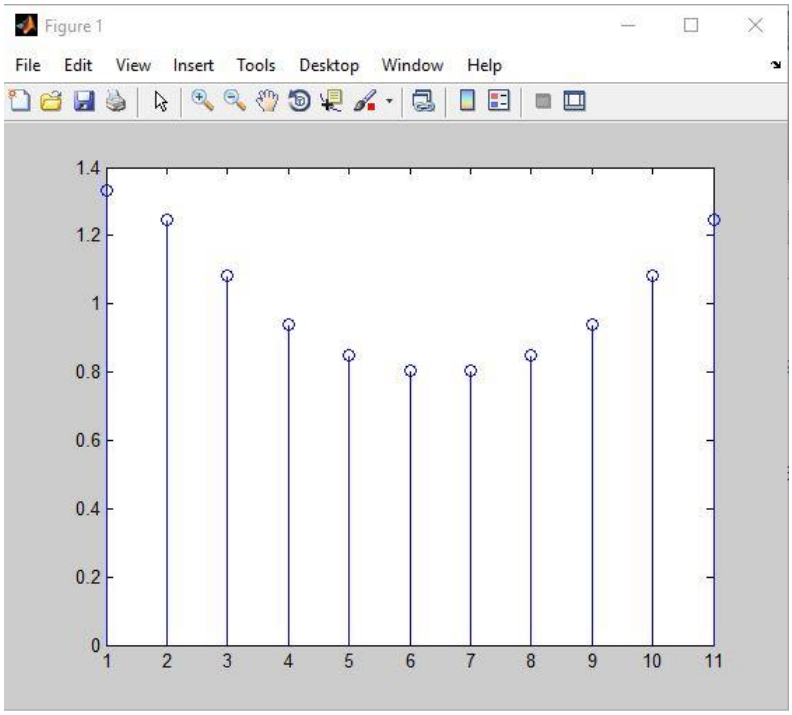
c-Code:

```
>> nc=[0:10];
>> cc=(1/4).^nc;
>> xc=stepseq(0,0,10);
>> xc=cc.^xc;
>> xcF=fft(xc);
>> stem(xcPhase);
>> stem(xcMag);
```

Output:

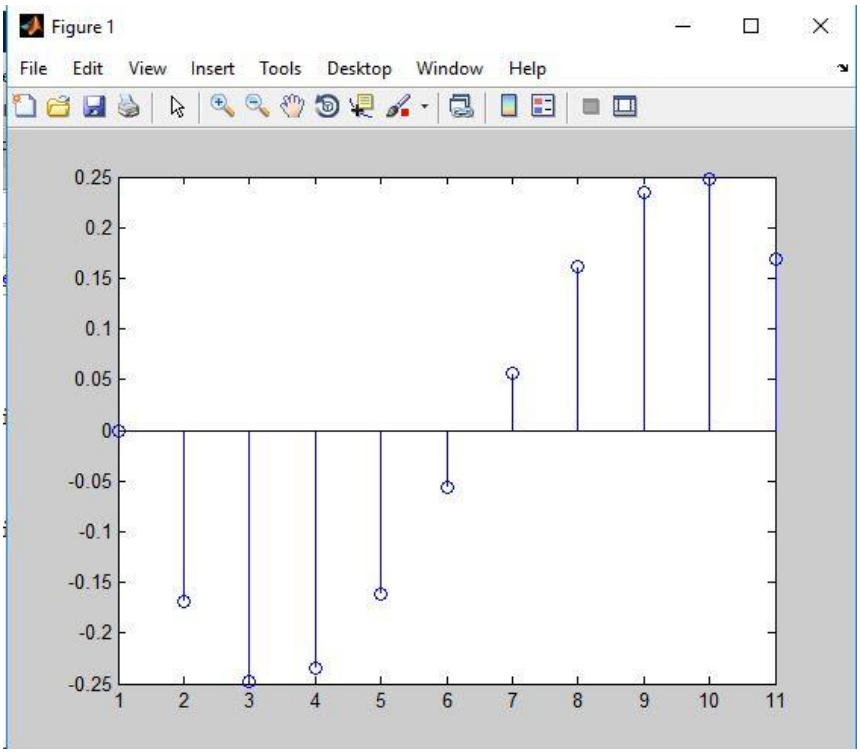
Magnitude:

```
xcMag =

    1.3333    1.2482    1.0816    0.9392    0.8482    0.8052    0.8052    0.8482    0.9392    1.0816    1.2482
```



Phase:

```
xcPhase =

         0   -0.1695   -0.2485   -0.2346   -0.1610   -0.0567    0.0567    0.1610    0.2346    0.2485    0.1695
```



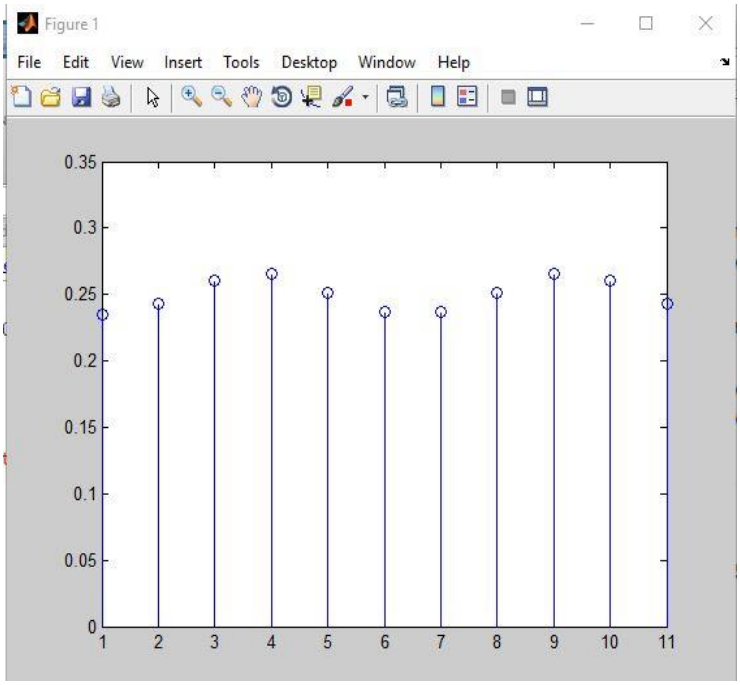
d-Code:

```
nd=[0:10];
cd= (0.25).^nd;
cs=cd.*sin(2*pi*0.25*nd);
xd=stepseq(0,0,10);
xd=cs.^xd;
xdF=fft(xd);
xdMag=abs(xdF);
xdPhase=phase(xdF);
```

Output:

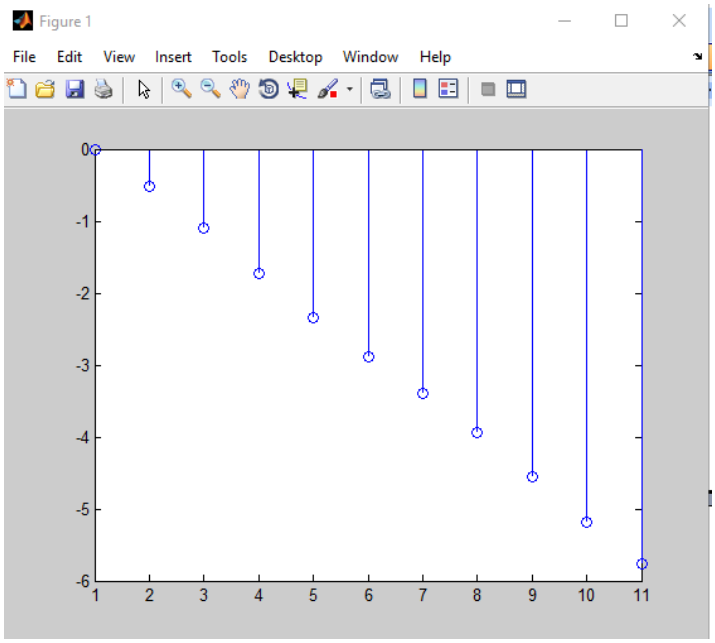
Magnitude

```
    Columns 1 through 6

      0.2353    0.2433    0.2604    0.2659    0.2518    0.2374

    Columns 7 through 11

      0.2374    0.2518    0.2659    0.2604    0.2433
```



Phase:

```
xdPhase =

  Columns 1 through 6

         0   -0.5158   -1.0932   -1.7323   -2.3471   -2.8881

  Columns 7 through 11

   -3.3951   -3.9361   -4.5509   -5.1900   -5.7673
```



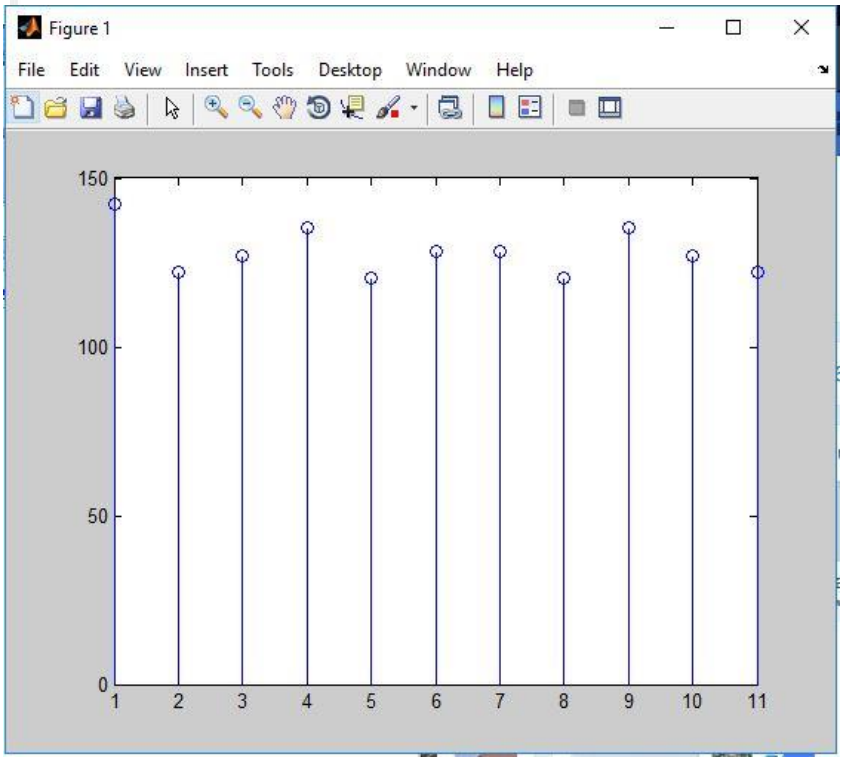
e-Code:

```
>> ne=[0:10];
>> ce=(0.5).^ne;
>> xe=sin(2*pi*0.25*ne) ;
>> xe=ce.^xe;
>> xeF=fft(xe);
>> xeMag=abs(xeF);
>> xePhase=angle(xeF);
>> stem(xeMag);
>> stem(xePhase);
```

Output:

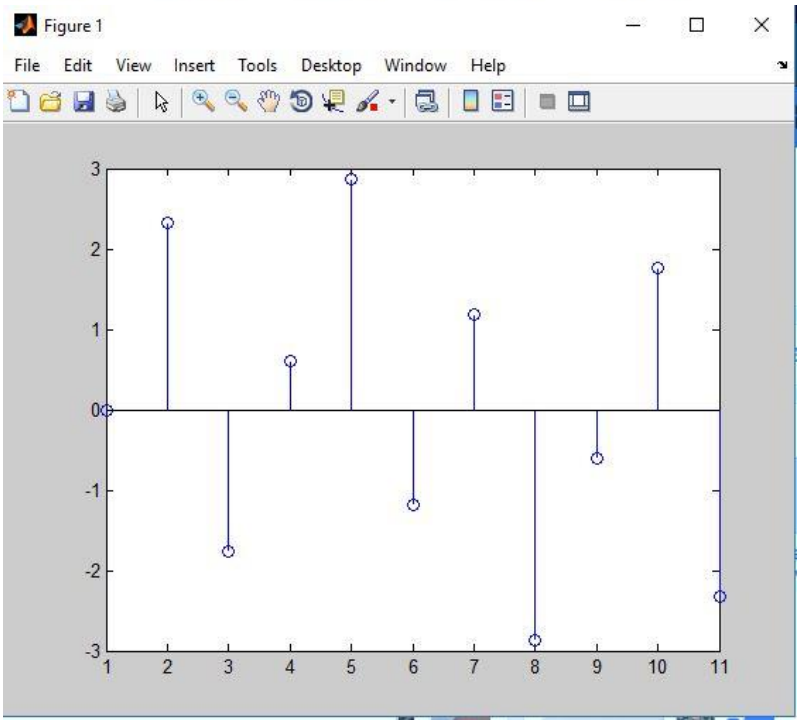
Magnitude:

```
xeMag =

  Columns 1 through 6

  142.5332  122.2006  127.0740  135.1672  120.3649  128.4595

  Columns 7 through 11

  128.4595  120.3649  135.1672  127.0740  122.2006
```



Phase:

```
xePhase =

  Columns 1 through 6

         0    2.3295   -1.7701    0.6019    2.8684   -1.1883

  Columns 7 through 11

    1.1883   -2.8684   -0.6019    1.7701   -2.3295
```



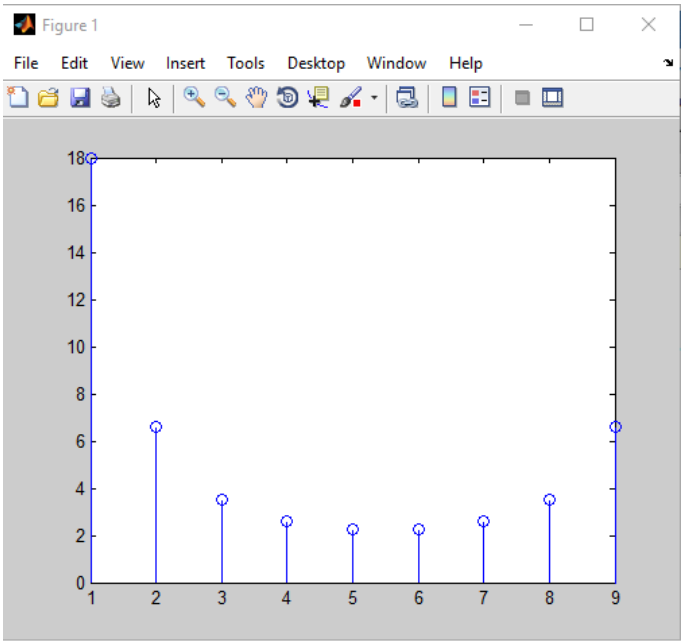
f-Code:

```
>> nf=[-4:4];
>> xf=2-(0.5*nf);
>> xfF=fft(xf);
>> xfMag=abs(xf);
>> xfMag=abs(xfF);
>> xfPhase=phase(xfF);
>> stem(xfMag);
```

Output:

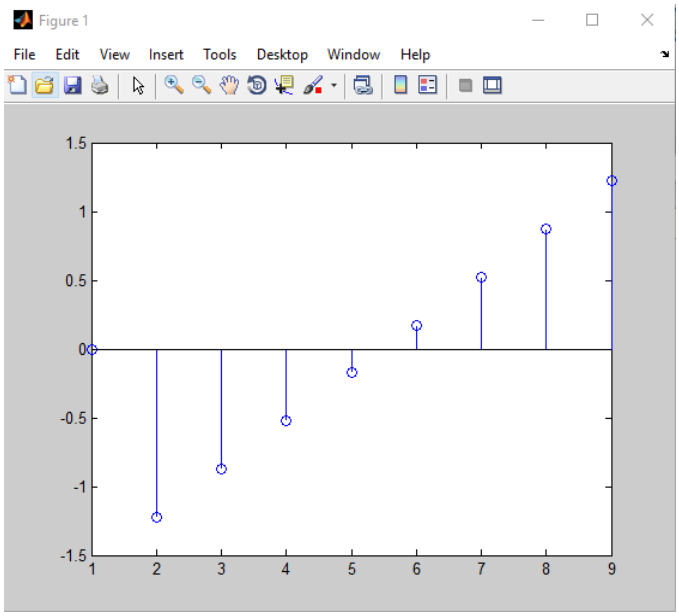
Magnitude:

```
xfMag =

   18.0000    6.5786    3.5004    2.5981    2.2847    2.2847    2.5981    3.5004    6.5786
```



Phase:

```
xfPhase =

         0   -1.2217   -0.8727   -0.5236   -0.1745    0.1745    0.5236    0.8727    1.2217
```



g.

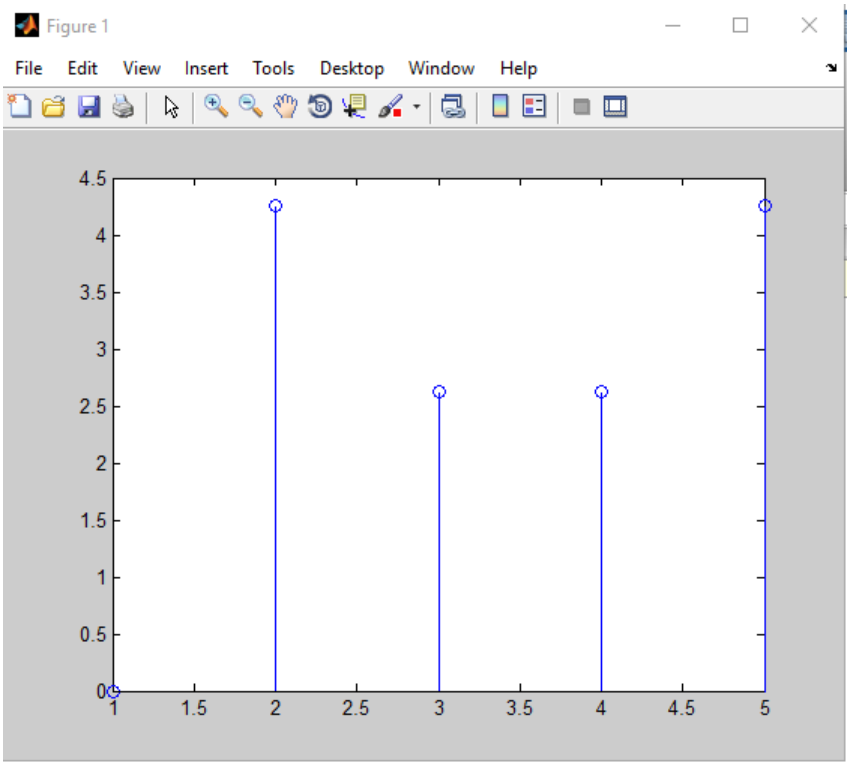
Code:

```
>> ng=[-2:2];
>> xg=[-2 -1 0 1 2];
>> xgF=fft(xg);
>> xgMag=abs(xgF);
>> xgPhase=phase(xgF);
>> stem(xgMag);
>> stem(xgPhase);
```

Output:

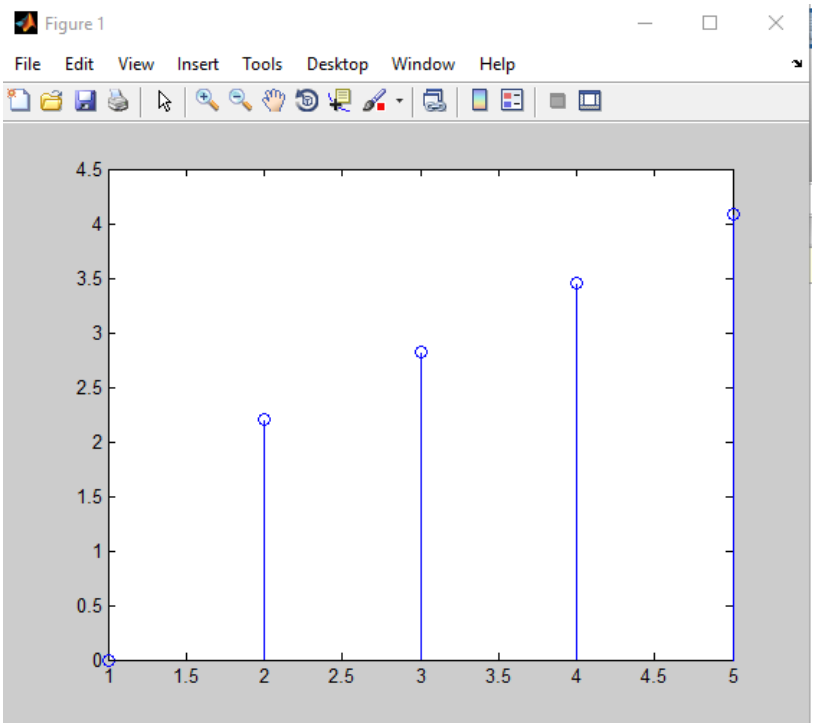
Magnitude:

```
xgMag =

         0    4.2533    2.6287    2.6287    4.2533
```

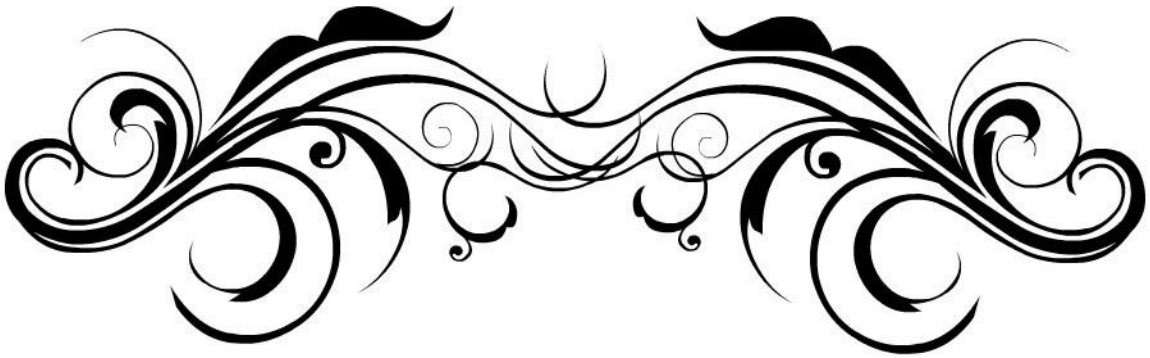


Phase :

```
xgPhase =

         0    2.1991    2.8274    3.4558    4.0841
```



End of Report



DSP Final MATLAB Project