


Sensor::run_hall



```
graph LR; A[Sensor::run_hall] --> B[SensorCallback::dataIn]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'Sensor::run_hall'. The right box is white and contains the text 'SensorCallback::dataIn'. A dark blue arrow points from the right side of the gray box to the left side of the white box.

SensorCallback::dataIn