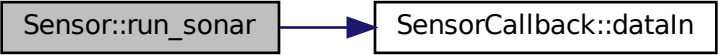


Sensor::run\_sonar



```
graph LR; A[Sensor::run_sonar] --> B[SensorCallback::dataIn]
```

A diagram showing a call from the function `Sensor::run_sonar` to the function `SensorCallback::dataIn`. The first box is shaded gray and the second is white. A blue arrow points from the right side of the first box to the left side of the second box.

SensorCallback::dataIn