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Numerical computing project

**CALCULATING THE ROOT OF EQUATION
WITH THE METHODS (BISECTION, FALSE-
POSITION, FIXED POINT, NEWTON-
RAPHSON, SECANT METHOD) WITH JAVA**

• DATA STRUCTURES

User defined data structure Point (x, y) which accepts x and y as floats or integers.

ArrayList: to store given equations

EQN: which is arraylist of equation members.

equation members: in which each coefficient is attached to its variable

for example: $2x+3y = 5$

EQN --> [(2, x), (3, y), (5, null)]

equation members --> (2, x), (3, y), (5, null)

• USER MANUAL

Zooming → user can zoom in by selecting the desired area using the mouse left click and zoom out by the same technique but in reverse direction, or simply right click on the desired place and select zoom in or zoom out (both axes, x axis, y axis) from the menu

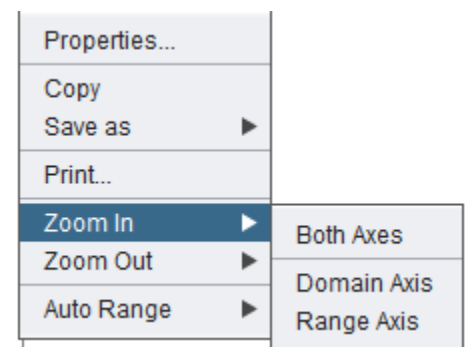
Saving → user should right click on the desired chart to be saved and select save as.

Coloring → Blue color indicates Xu

Red color indicates XI

Yellow color indicates final answer(root)

Syntax → e^x is written as exp(x)



• LIBRARIES

We used **JFreeChart** library to draw the graphs.

• DESIGN DECISIONS

Fixed point → there is no way to always guarantee convergence, we add x to both sides of the equation and it converges in most of the cases but diverges with bad initials

• PSEUDO CODE FOR EACH METHOD

False position

```
if substitute in function with (xl, A, y, x, p) * substitute in function with
(xu, A, y, x, p) > 0
    return wrong assumption
else if substitute in function with (xl, A, y, x, p) = 0
    return xl
else if substitute in function with (xu, A, y, x, p) = 0
    return xu
while ea >= epsilon and i < iterations
    add point (xl, 0) to points
    add point (xu, 0) to points
    fxl = substitute in function with (xl, A, Y, x, P)
    fxu = substitute in function with (xu, A, y, x, p)
    xr = (xl * fxu - xu * fxl) / (fxu - fxl)
    fxr = substitute in function with (xr, A, y, x, p)
    if fxr == 0
        break
    else if fxr < 0
        xu = xr
    else
        xl = xr
    ea = absolute ((xr - xrold) / xr) * 100
    xrold = xr
    i++
return root value
```

Bisection

```
if substitute in function with (xl, A, y, x, p) * substitute in function with
(xu, A, y, x, p) > 0
    return wrong assumption
else if substitute in function with (xl, A, y, x, p) = 0
    return xl
else if substitute in function with (xu, A, y, x, p) = 0
    return xu
while ea >= epsilon and i < iterations)
    add point (xl, 0) to points
    add point (xu, 0) to points
    xr = (xu + xl) / 2
    if substitute in function with (xr, A, y, x, p) = 0.0
        break
    else if substitute in function with (xr, A, y, x, p) * substitute in
function with (xl, A, y, x, p) < 0
        xu = xr
    else
        xl = xr
    ea = absolute ((xr - xrold) / xr) * 100;
    xrold = xr
    i++
return root value
```

FixedPoint

```
for i = 0 to A.length
  for j = 0 to A[0].length
    Ag[i][j] = A[i][j];

while ea >= epsilon and i < iterations
  xold = xc
  xc = substitute in function with (xc, Ag, y, xg, p)
  fxc = substitute in function with (xc, A, y, x, p)
  if fxc = 0
    break
  ea = Math.abs((xc[0] - xold) / xc[0]) * 100
  I++
return root value
```

Newton Raphson

```
if substitute in function with (xold, A, y, x, p) = 0
  return initial guess
while ea >= epsilon and i < iterations)
  fxold = substitute in function with (xold, A, y, x, p)
  fdxold = substitute in function with (xold, A, y, x, p)
  xnew = xold - (fxold / fdxold)

  if fxold = 0
    break

  ea = absolute ((xnew - xold) / xnew) * 100
  xold = xnew
  i++
return root value
```

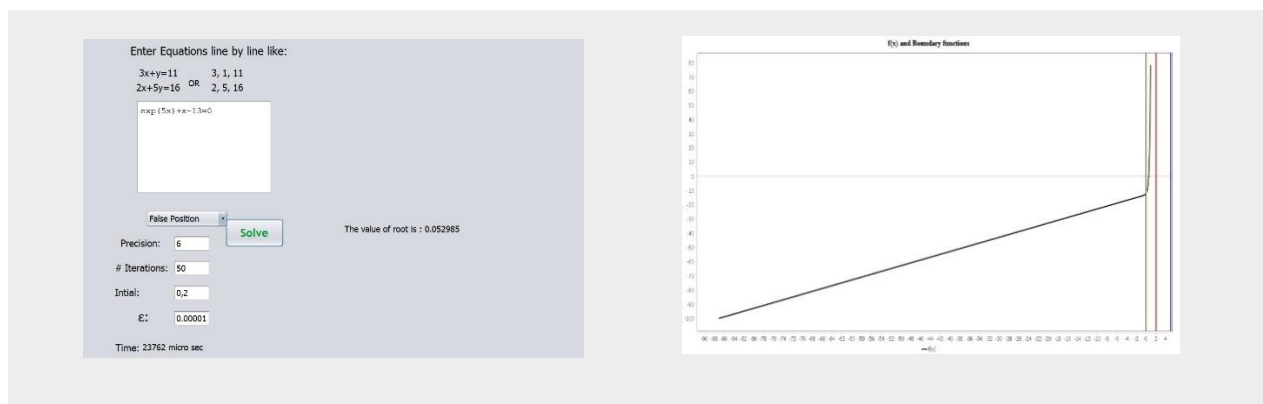
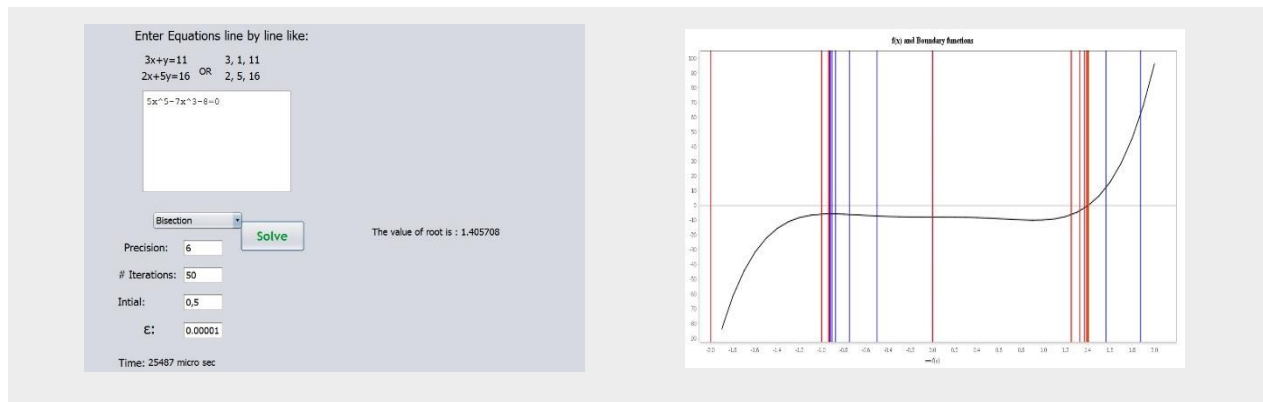
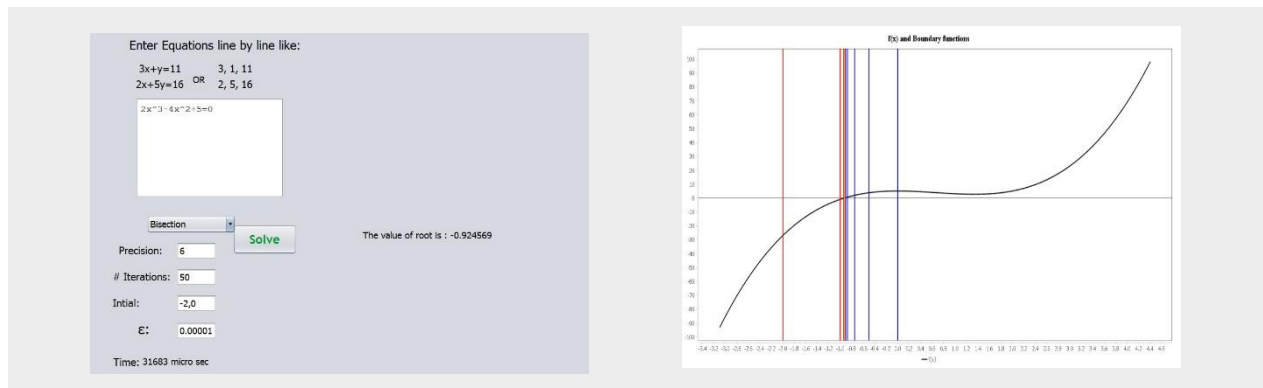
Secant

```
while ea >= epsilon and i < iterations
  fxp = substitute in function with(xp, A, y, x, p)
  fxc = substitute in function with(xc, A, y, x, p)
  xn = xc - (fxc * (xp - xc)) / (fxp - fxc)
  fxn = substitute in function with(xn, A, y, x, p)

  if fxn = 0
    break

  ea = absolute ((xn - xc) / xn) * 100
  xp = xc
  xc = xn
  i++
return root value
```

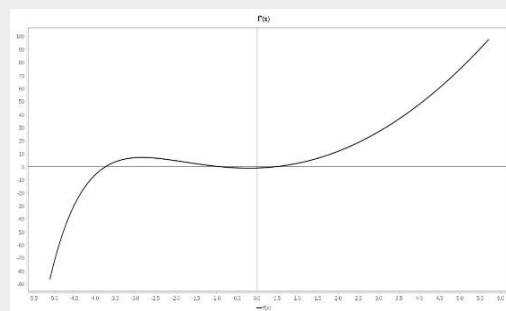
• TEST CASES



Enter Equations line by line like:

$3x+y=11$ 3, 1, 11
 $2x+5y=16$ OR 2, 5, 16

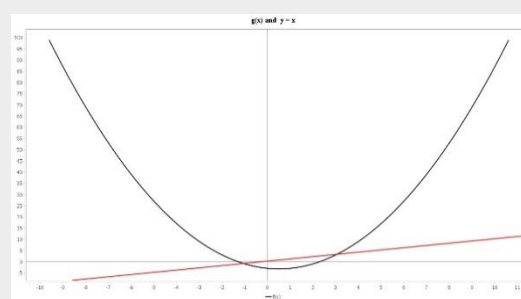
Newton Raphson
 Precision: The value of root is : -4.053957
 # Iterations:
 Intial:
 E:
 Time: 11770 micro sec



Enter Equations line by line like:

$3x+y=11$ 3, 1, 11
 $2x+5y=16$ OR 2, 5, 16

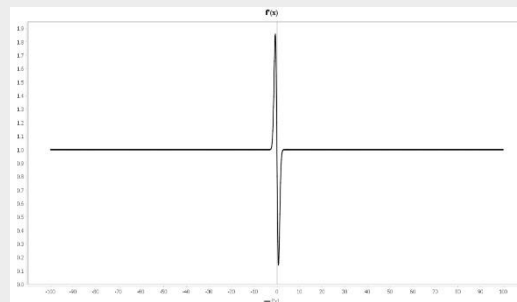
Fixed Point
 Precision: The value of root is : -1.0
 # Iterations:
 Intial:
 E:
 Time: 29200 micro sec



Enter Equations line by line like:

$3x+y=11$ 3, 1, 11
 $2x+5y=16$ OR 2, 5, 16

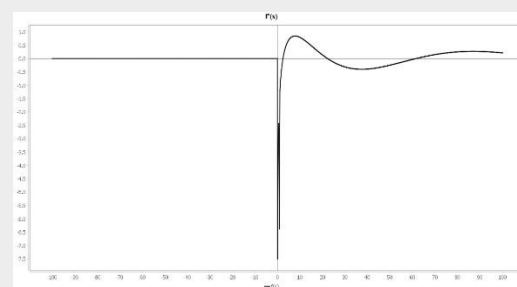
Secant
 Precision: The value of root is : 11.0
 # Iterations:
 Intial:
 E:
 Time: 32160 micro sec

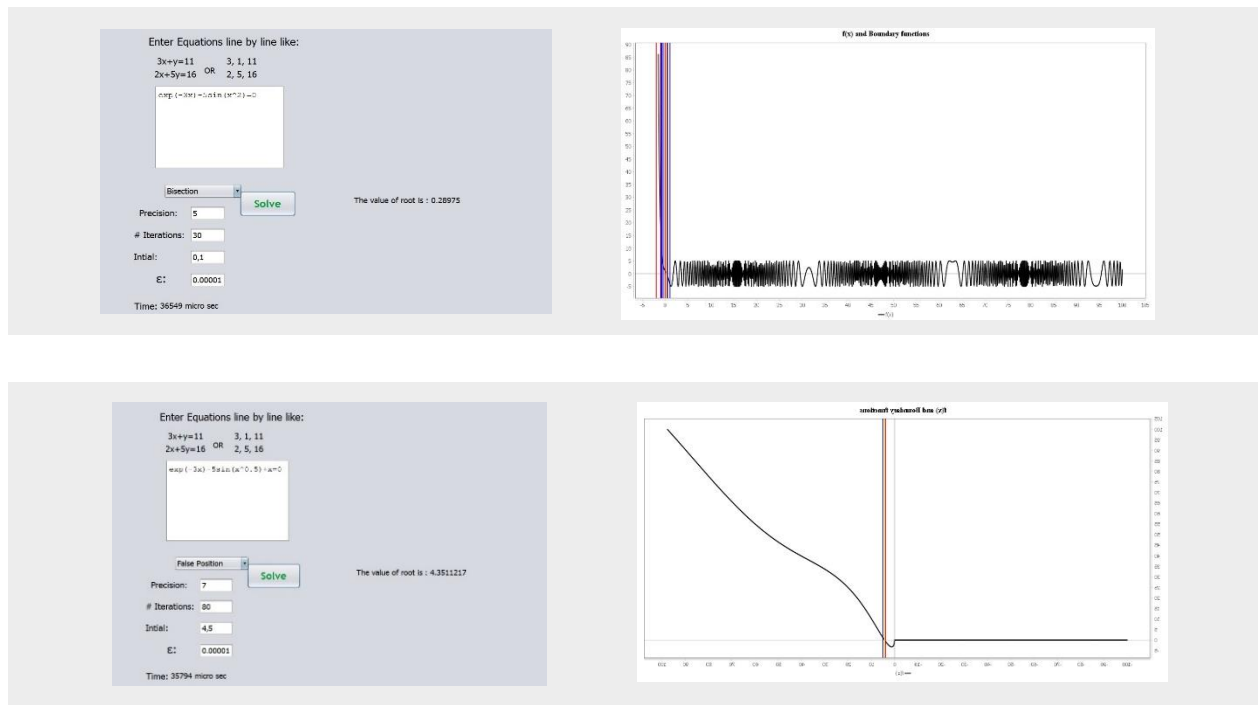


Enter Equations line by line like:

$3x+y=11$ 3, 1, 11
 $2x+5y=16$ OR 2, 5, 16

Newton Raphson
 Precision: The value of root is : 9.8696
 # Iterations:
 Intial:
 E:
 Time: 30068 micro sec





• COMPARISON BETWEEN DIFFERENT METHODS

we will compare between methods with **2** equations to get the roots

first equation: " $\exp(-3x)-5*\sin(x^{0.5}) +x=0$ "

second equation: " $2*x^3-4*x^2+5=0$ "

- HINT: we try a method 10 times and take the average off the time in microseconds to be more accurate because the time effects with the memory state and the processor.
**number of iterations:50 and precision: 6.

Methods	Average Time(μ s) first equations	Average Time(μ s) second equations
False-Position Method	32897	22248
Bisection Method	34583	26689
Fixed point Method	31787	21334
Newton-Raphson Method	26590	20236
Secant Method	22414	23365