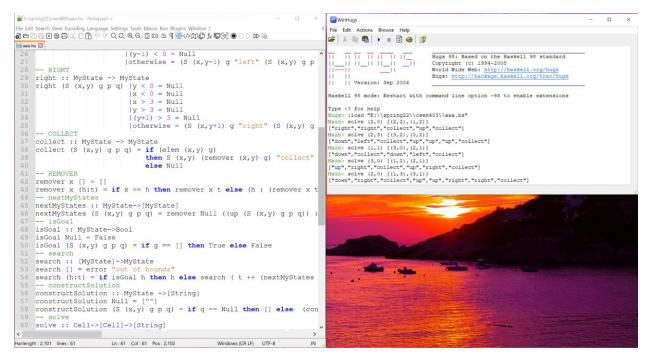
## Description of functions:

- 1- Up: the function takes a state and returns the result state after the minesweeper robot has moved up, note that that if the coordinates exceeds 3 or fall short of 0 Null is returned to keep the minesweeper robot inside the gird.
- 2- Down: the function takes a state and returns the result state after the minesweeper robot has moved down, note that that if the coordinates exceeds 3 or fall short of 0 Null is returned to keep the minesweeper robot inside the gird.
- 3- Left: the function takes a state and returns the result state after the minesweeper robot has moved left, note that that if the coordinates exceeds 3 or fall short of 0 Null is returned to keep the minesweeper robot inside the gird.
- 4- Right: the function takes a state and returns the result state after the minesweeper robot has moved right, note that that if the coordinates exceeds 3 or fall short of 0 Null is returned to keep the minesweeper robot inside the gird.
- 5- Collect: the function takes a state as input and preforms the action "collect" which, if the minesweeper robot is in the same cell as a mine, removes the mine from the list of mines and returns the resulting state, else the functions return Null.
- 6- Remover: the function the function takes an element x and a list and return a list without x elements
- 7- nextMyStates: the function returns a list of states after preforming the following operations: Up, Down , Left, Right and Collect on the state taken as input.
- 8- isGoal: the function checks whether the state taken as input has any mines left to collect, if there are still mines it returns false, otherwise it returns true.
- 9- Search: the function takes as an input a list of states and apply "isGoal"[7] function on the head of the list and returns the head if "isGoal"[7] is true otherwise, it applies "nextMyStates"[6] on the head and then append the result to the tail of the input list with the tail now being at the front.
- 10- constructSolution: the function returns a list of strings that acts as instructions for the robot to move from its current state to the input state.
- 11- Solve: the function takes as input the current cell of the robot and the cells of the mines and returns a list of strings that is basically the plan of action of the minesweeper robot to fully eradicate all the mines on the grid.

## Screenshot of multiple different grid configurations with the returned solutions:



## (Bonus) Screenshot of multiple different grid configurations with the returned solutions:

