

# CSE 312

# Microprocessor Based Systems

# Project 2 Report

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## Project’s Structure

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In this project, three subsystems –which can be used in a smart home- are implemented using two launch pads -Tm4c123gh6pm- commonly known as Tiva c, the two Tivas communicate together using UART communication protocol.

The 1st Tiva is connected to:

* A stepper motor which can rotate 30 degrees clock wise or anti clock wise according to the order sent to it from the 2nd Tiva when one of the switches are pressed, for example if the left switch is pressed, the motor will rotate 30 degrees anti clock wise and so on.
* A Temperature sensor that is built in the Tiva, which is used to measure the Tiva’s Processor temperature.
* An LED that changes its degree of illumination according to the PWM signal sent to it from the 2nd Tiva using a potentiometer.

The 2nd Tiva is connected to:

* Two switches that are used to rotate the stepper motor as mentioned before, using UART.
* An LCD that is used to display the temperature measured form the 1st Tiva’s temperature sensor.
* A potentiometer that is used to change the 1st Tiva’s LED light intensity.

## Used Perepherals

\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

The used protocols are:

* UART communication protocol that is used to establish communication between the two launch pads.
* Pulse width modulation (PWM) that is used to change the light intensity of the LED according to a certain voltage.
* Analog to digital convertor (ADC) ……………….?

## Mcal Layers

\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

## 

Mcal layers are divided into four basic groups:

* Microcontroller Driver
* PLL Driver
* Communication Drivers
* UART Driver
* I/O Drivers
  + DIO Driver
  + PORTS Driver
  + ADC Driver
  + PWM Driver
* Device Drivers
* LCD Driver
* Stepper Motor Driver
* Temperature Sensor

## Functions’ Description

\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

### Microcontroller Driver:

1. PLL Driver

|  |  |
| --- | --- |
| Function name | PLL\_Init() |
| Input | Void |
| Return | Void |
| Description | Initialize system’s clock according to predefined system Divisor |

### Communication Driver:

1. UART Driver

|  |  |
| --- | --- |
| Function name | UARTX\_Init() |
| Input | Void |
| Return | Void |
| Description | Enable UART Module by enabling the UART clock, set the baud rate and other UART properties. |

|  |  |
| --- | --- |
| Function name | Uint8\_t UARTX\_Available(void) |
| Input | Void |
| Return |  |
| Description |  |

|  |  |
| --- | --- |
| Function name | Uint8\_t UARTX\_Read(void) |
| Input | Void |
| Return |  |
| Description |  |

|  |  |
| --- | --- |
| Function name | void UARTX\_Write(Uint8\_t data) |
| Input | Void |
| Return |  |
| Description |  |

|  |  |
| --- | --- |
| Function name | void UARTX\_Write(Uint8\_t data) |
| Input | Void |
| Return |  |
| Description |  |

|  |  |
| --- | --- |
| Function name | void UARTX\_Read\_String(char c[]) |
| Input | Void |
| Return |  |
| Description |  |

### I/O Driver:

1. DIO Driver

// Copy bto3 el-mo3eed

1. PORTS Driver

// Copy bto3 el-mo3eed

1. ADC Driver

// Tiva 2

1. PWM Driver

|  |  |
| --- | --- |
| Function name | Blue\_PWM1\_Init() |
| Input | Void |
| Return |  |
| Description |  |

|  |  |
| --- | --- |
| Function name | BlueLED\_SetDutyCycle(uint8\_t duty\_cycle) |
| Input |  |
| Return | void |
| Description |  |

|  |  |
| --- | --- |
| Function name | void servo\_center(uint32\_t duty\_cycle) |
| Input |  |
| Return |  |
| Description |  |

### Device Drivers:

1. LCD Driver:

//Tiva 2

1. Stepper Motor Driver

|  |  |
| --- | --- |
| Function name | void STEPPER\_MOTOR\_voidInit(void); |
| Input |  |
| Return |  |
| Description |  |

|  |  |
| --- | --- |
| Function name | void STEPPER\_MOTOR\_MOVE\_30(int direction); |
| Input |  |
| Return |  |
| Description |  |

1. Temprature sensor Driver:

|  |  |
| --- | --- |
| Function name | void Temp\_Init(void) |
| Input |  |
| Return |  |
| Description |  |

|  |  |
| --- | --- |
| Function name | uint16\_t Temp\_Read(); |
| Input |  |
| Return |  |
| Description |  |

## Project’s Photo

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