

# **Computer System Architecture - CSEN 601**

**Module 4:** *Pipelining and Execution Techniques*

**Lecture 09:** *MIPS Single-Cycle Machines Datapath Implementation Scheme*

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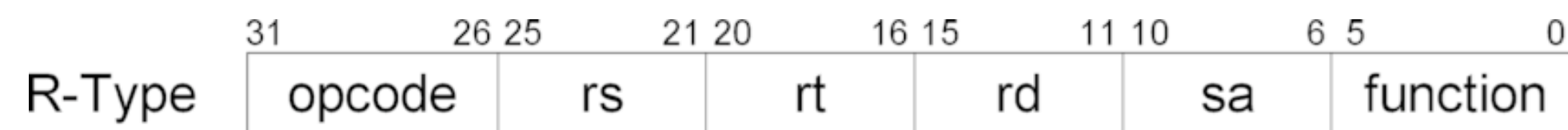
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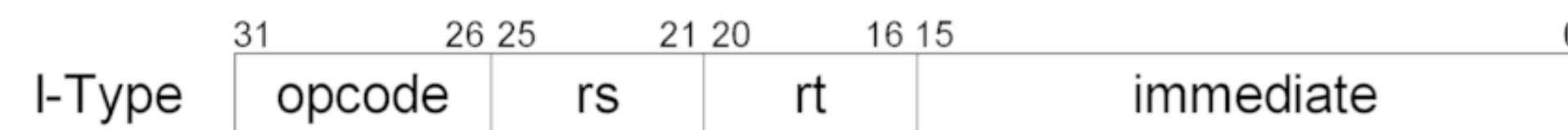
- The Datapath
- Building a MIPS Datapath

## *The MIPS Instructions **Format** Classification*

### R-Format Instructions



### I-Format Instructions



### J-Format Instructions



***It can be noticed from the illustrated formats that:***

- all instruction types have an opcode field, and
- they differ in terms of the other fields that include the needed registers to perform the required operation, immediate, or/and index.

## Some Observations!

- Much of what needs to be done to implement these instructions is the same, independent of the exact class of instruction. For every instruction, the first two steps are identical:
  1. Send the program counter (PC) to the memory that contains the code and fetch the instruction from that memory.
  2. Read one or two registers, using fields of the instruction to select the registers to read. For the load word instruction, we need to read only one register, but most other instructions require reading two registers.

## Some Observations!

- After these two steps, the actions required to complete the instruction depend on the instruction class.
- Fortunately, for each of the three instruction classes (memory-reference, arithmetic-logical, and branches), the actions are largely the same, independent of the exact instruction.
- The simplicity and regularity of the MIPS instruction set simplifies the implementation by making the execution of many of the instruction classes similar.
- For example, all instruction classes, *except jump*, use the arithmetic-logical unit (ALU) after reading the registers.
  - The memory-reference instructions use the ALU for an address calculation.
  - The arithmetic-logical instructions for the operation execution, and branches for comparison.



## Some Observations!

- After using the ALU, the actions required to complete various instruction classes differ.
  - A memory-reference instruction will need to access the memory either to read data for a load or write data for a store.
  - An arithmetic-logical or load instruction must write the data from the ALU or memory back into a register.
  - A branch instruction may need to change the next instruction address based on the comparison; otherwise, the PC should be incremented by 4 to get the address of the next instruction.

### **Very Important Note:**

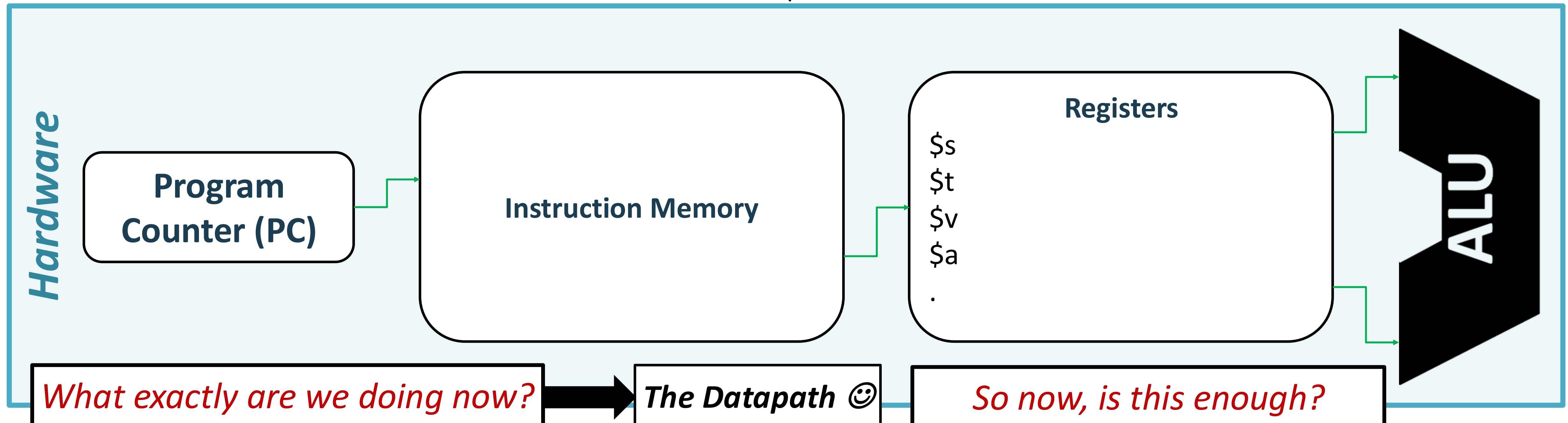
*When we design our computer architecture, think generically to fit all the instructions.*

## What are the steps when executing an instruction?

- Based on the previous observations, we can conclude the three basic execution stages:
  1. Use program counter (PC) to **Fetch** an instruction to execute it.
  2. **Decode** the needed registers to be selected and read using the proper fields
  3. **Execute** the action intended by the instruction

# Basic Instruction Execution Stages

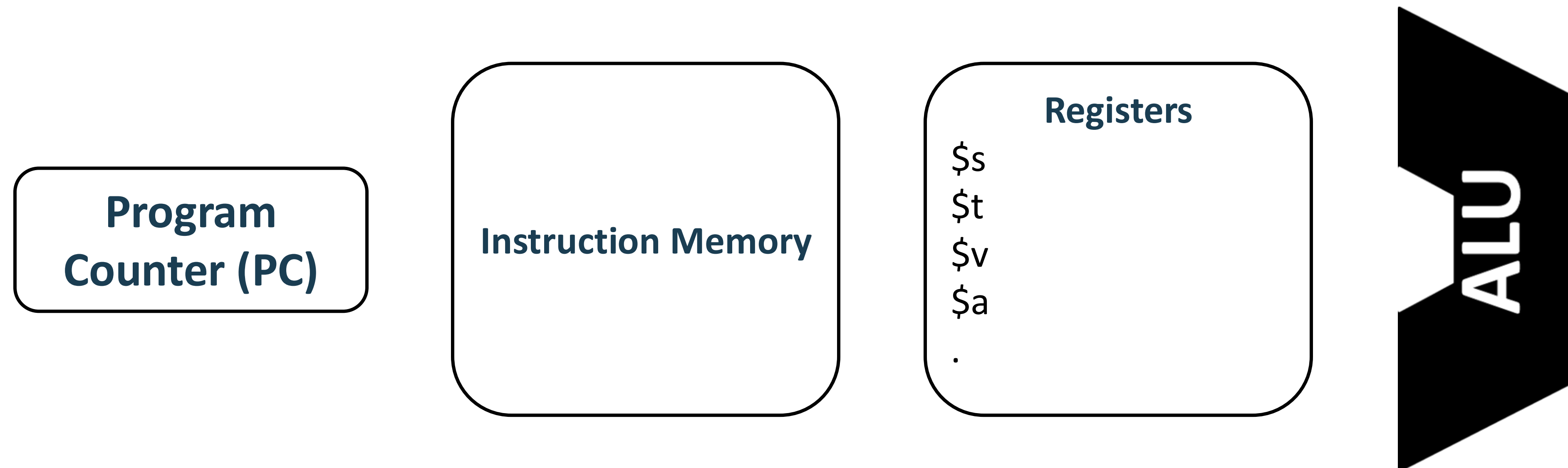
What are the steps when executing an instruction?





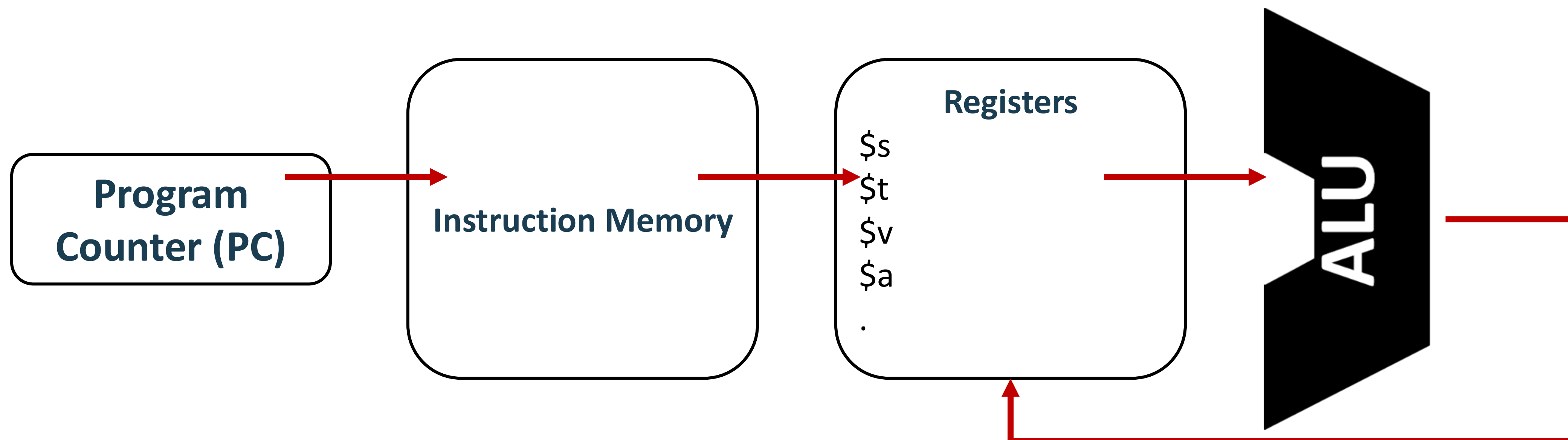
## How to build the datapath?

- Imagine the datapath as some pipes where the data flows.
- Therefore, you should consider where and in which direction the data will flow from the fetching till the end of the execution.
- Again, think generically when you design the datapath to fit all the instructions classes.
- In order to do that, we can start by drawing separate datapathes for each instruction class.



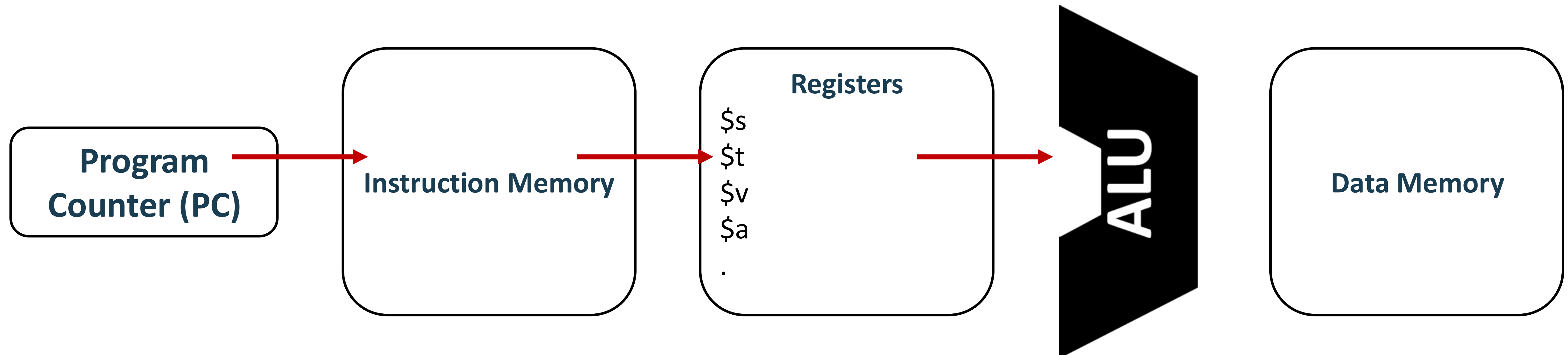
## The Arithmetic and Logical Instructions

- PC determines the instruction address to be fetched
- Decoded instruction determine the 2 source registers
- These registers are passed to the ALU where the function is executed.
- After finishing the execution, the results should be stored again in the registers (remember the Reg-Reg machine model)



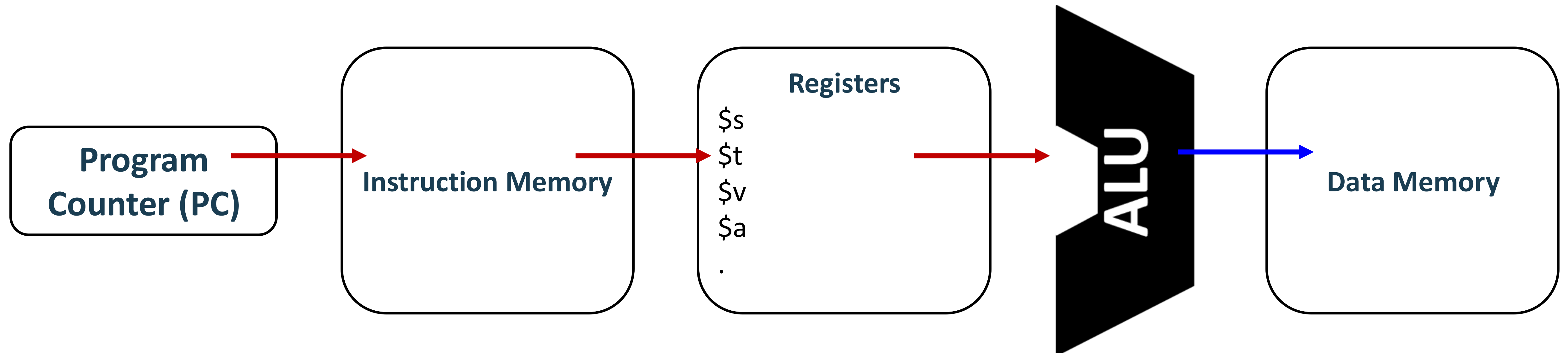
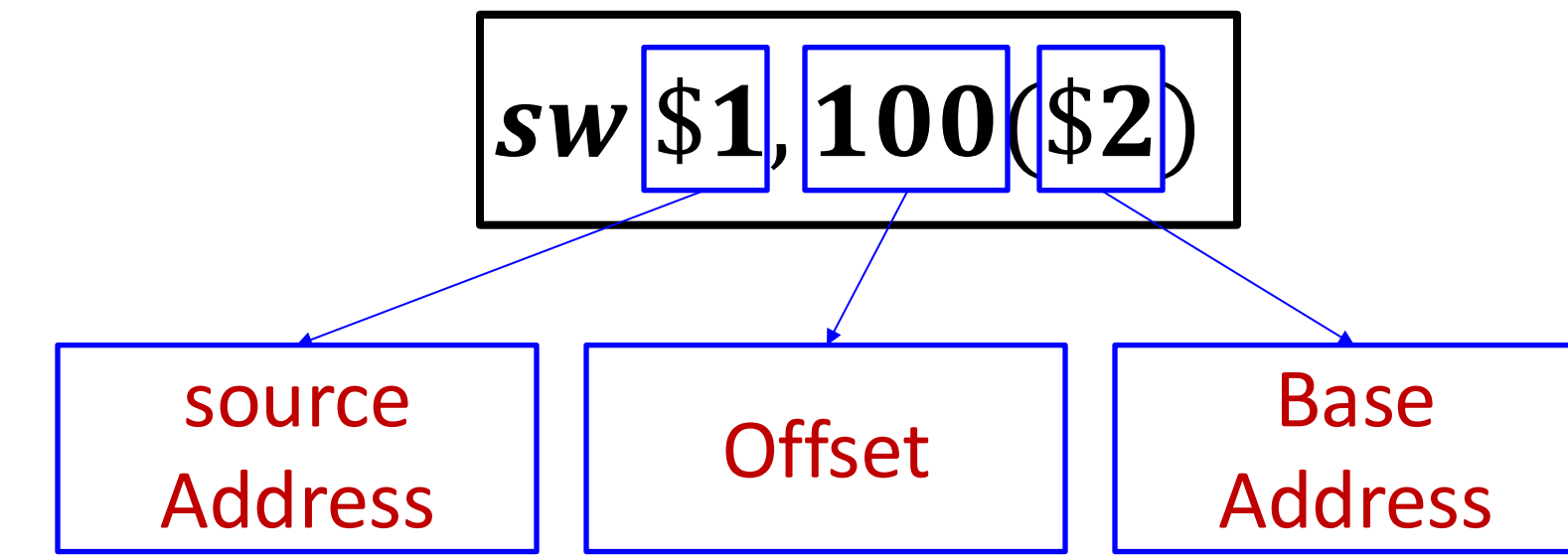
## Memory-Reference Instructions

- Here these components are not enough anymore, as we have to load/store our data in the data memory



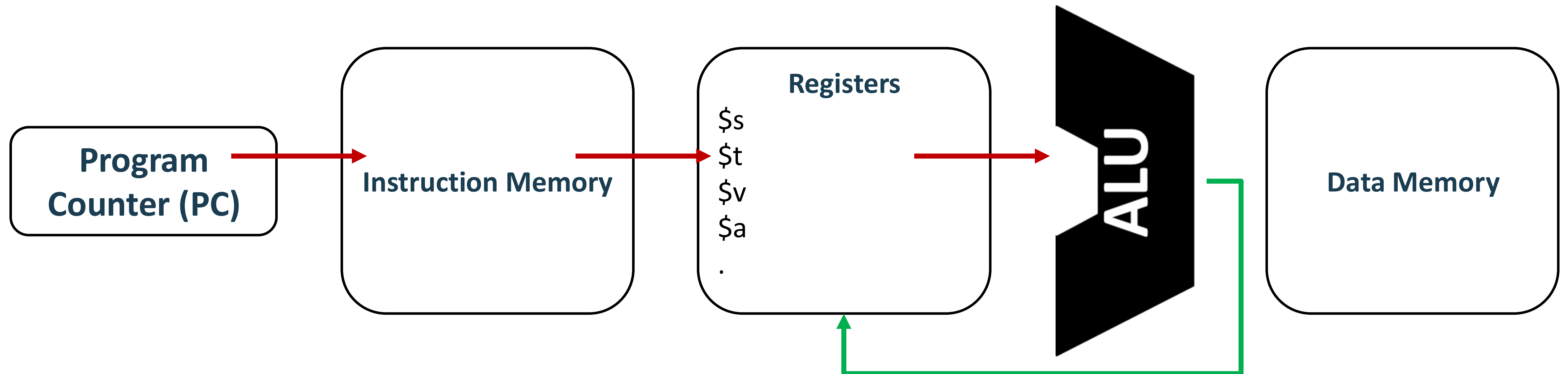
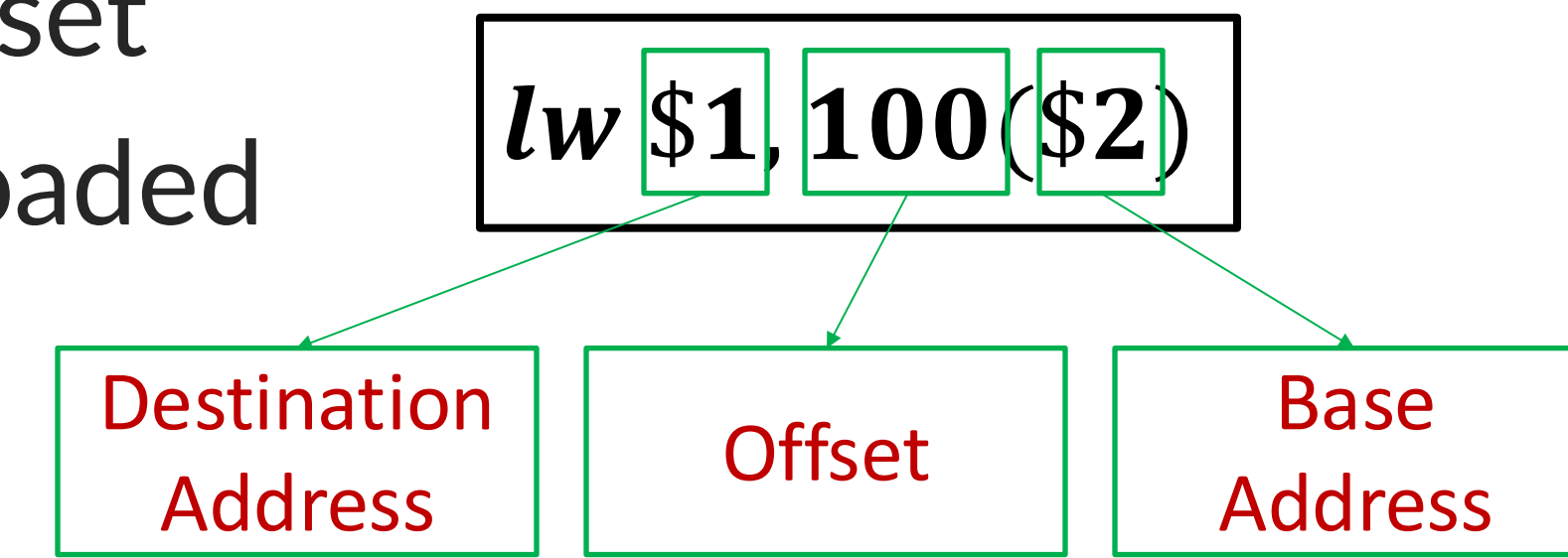
## Memory-Reference Instructions: *Store*

- PC determines the instruction address to be fetched
- Decoded instruction determine the 1 source address
- The ALU performs addition to get the new storage location (*base registers + the offset*)
- The results is stored in the data memory



## Memory-Reference Instructions: *Load*

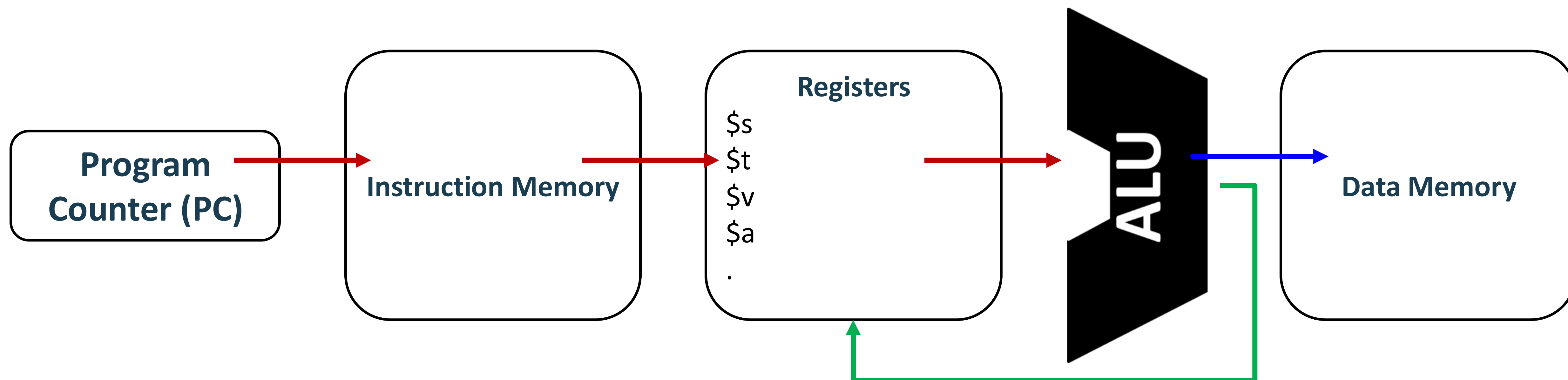
- PC determines the instruction address to be fetched
- Decoded instruction determine the 1 base registers and the offset
- The ALU performs addition to the address where data will be loaded
- The results is loaded in the destination register





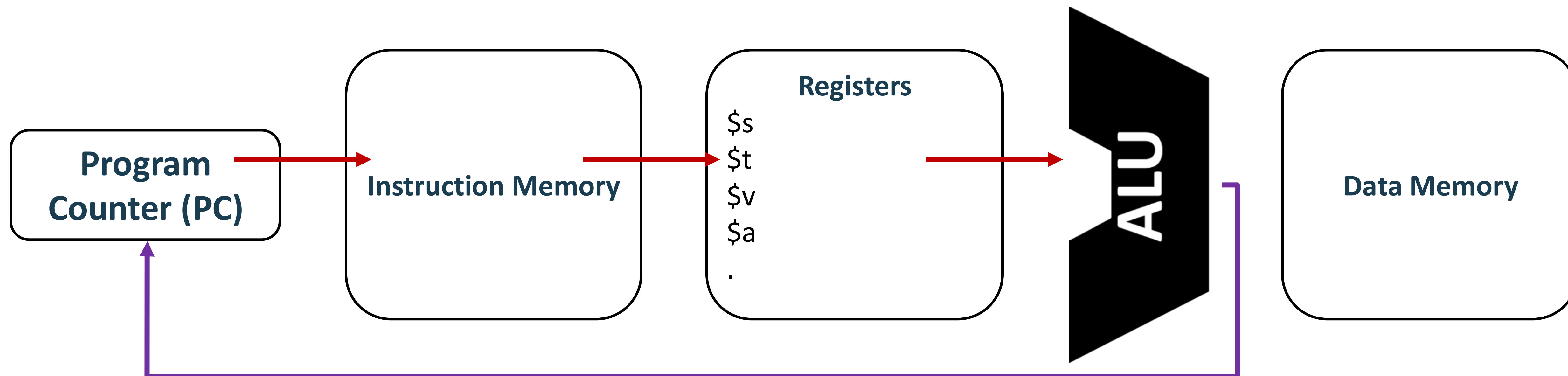
## Memory-Reference Instructions

- Combining both the load and store instructions, we will end up with:
  - Common datapath from PC till ALU
  - 2 possibilities depends on the operation itself



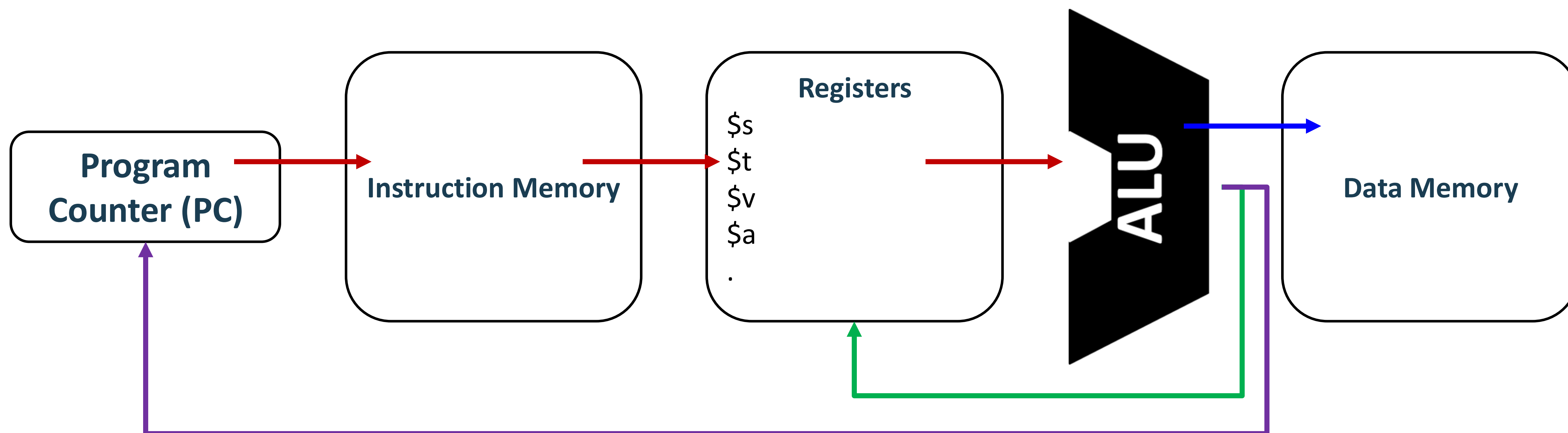
## Branches and Jumps Instructions

- PC determines the instruction address to be fetched
- Decoded instruction determine the offset of the jump or the registers to be compared in case of branching
- ALU executes the operation (addition of the offset for *jump* or subtraction in case of *beq*)
- Output is used to update the PC value



## The Abstracted Datapath

- Here is the big picture combining the 3 instructions classes of MIPS.



## Datapath Design

- A reasonable way to start a detailed datapath design is to examine **the major components** required to execute each class of MIPS instructions.
- That means we start at the top by looking at which datapath elements each instruction needs, and then work our way down through the levels of abstraction.

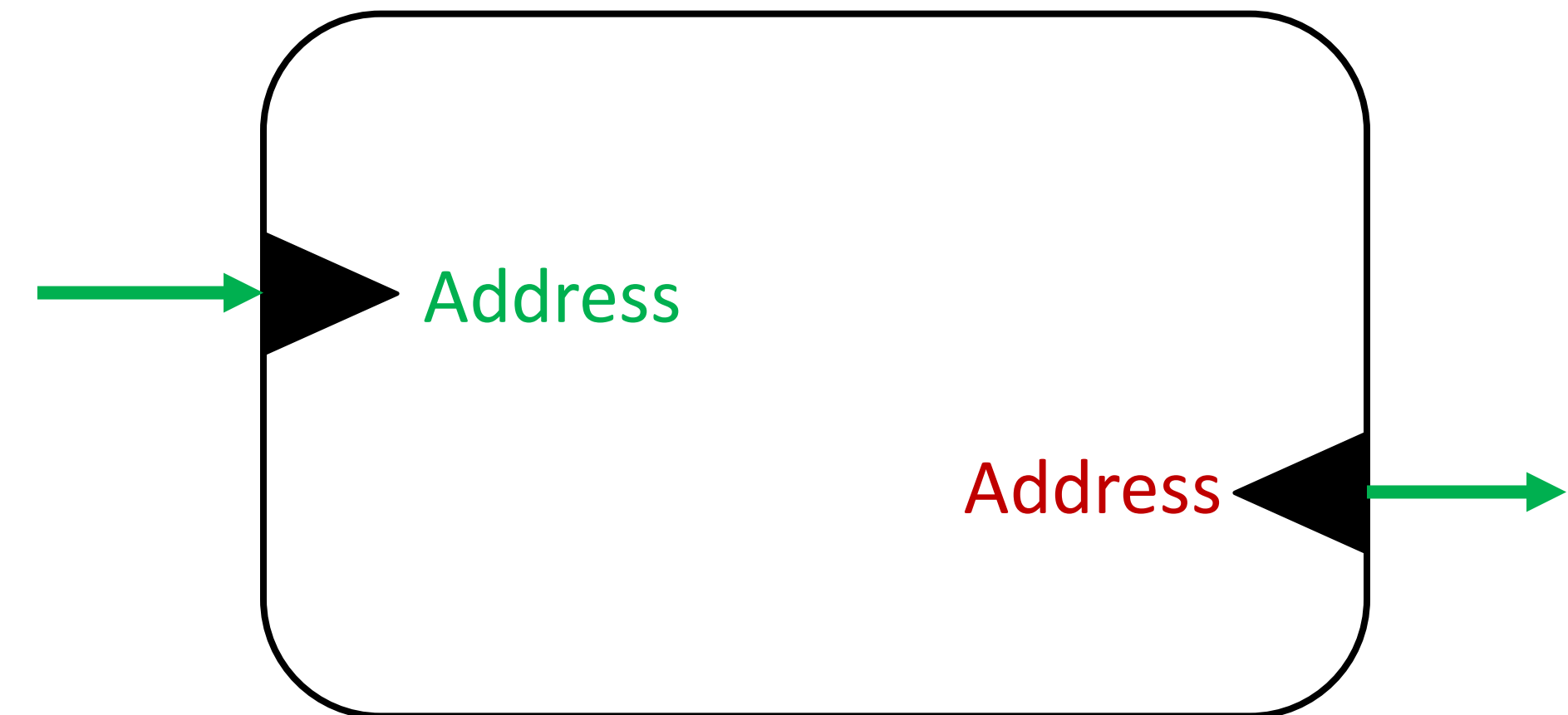
## The Datapath Elements

- Datapath element is a unit used to operate on or hold data within a processor.
- In the MIPS implementation, the datapath elements include **the instruction and data memories**, **the register file**, **the ALU**, and **adders**.



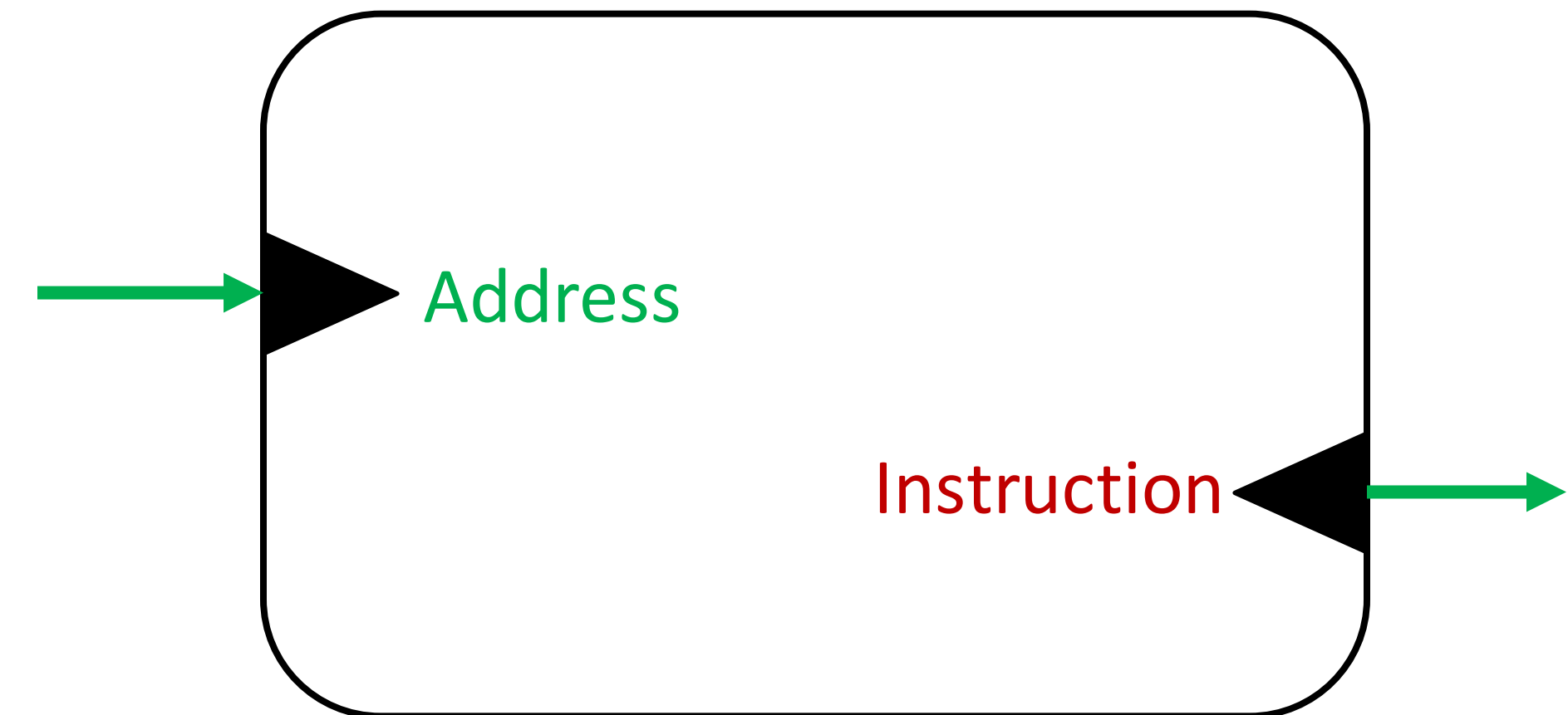
## The Program Counter

- The program counter is a 32-bit register that is written at the end of every clock cycle and thus does not need a write control signal.



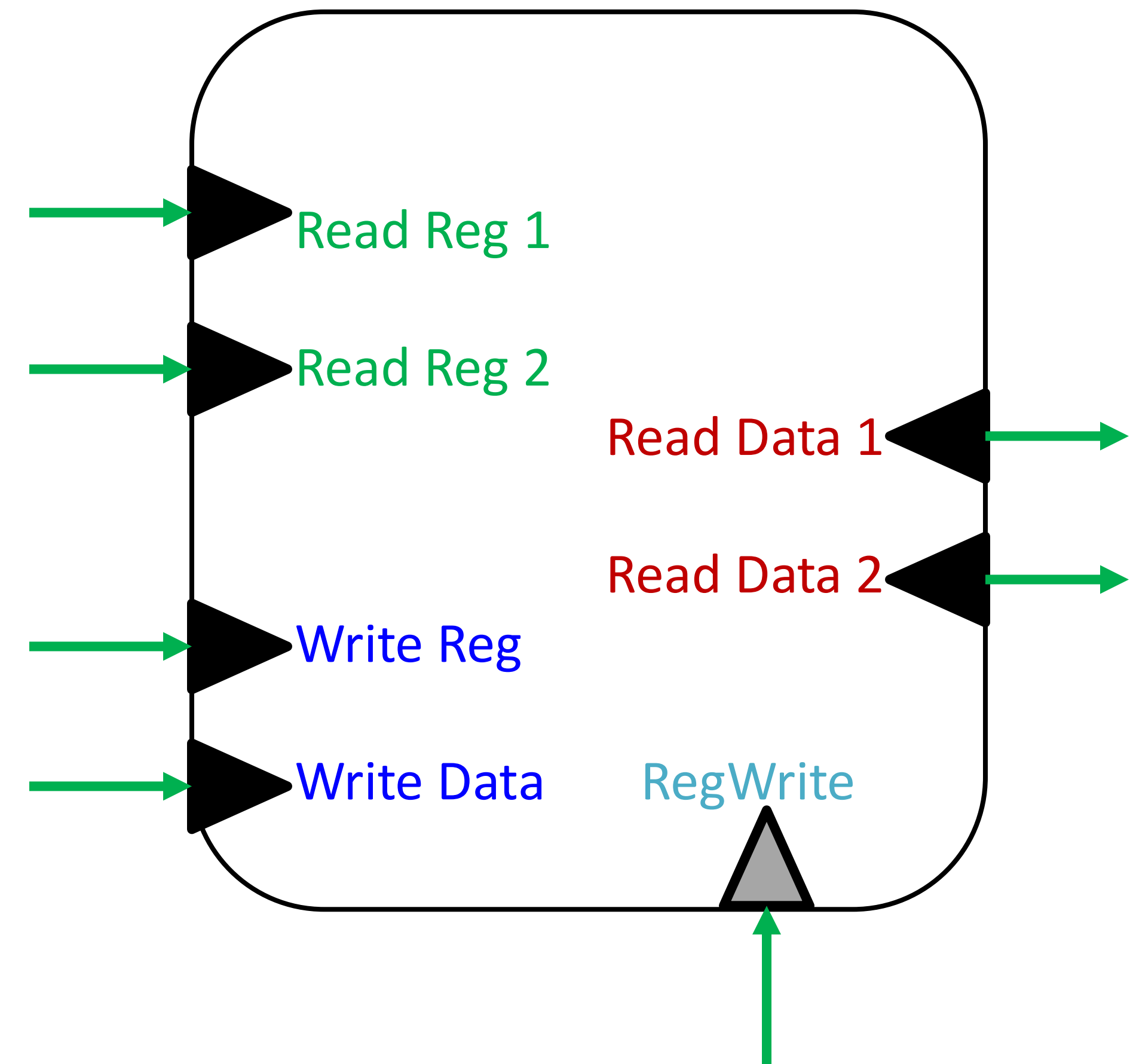
## The Instruction Memory

- The instruction memory need only provide read access because the datapath does not write instructions.
- Since the instruction memory only reads, we treat it as combinational logic:
  - the output at any time reflects the contents of the location specified by the address input, and no read control signal is needed.
  - Note that we will need to write the instruction memory when we load the program; this is not hard to add, and we ignore it for simplicity.



## The Register File

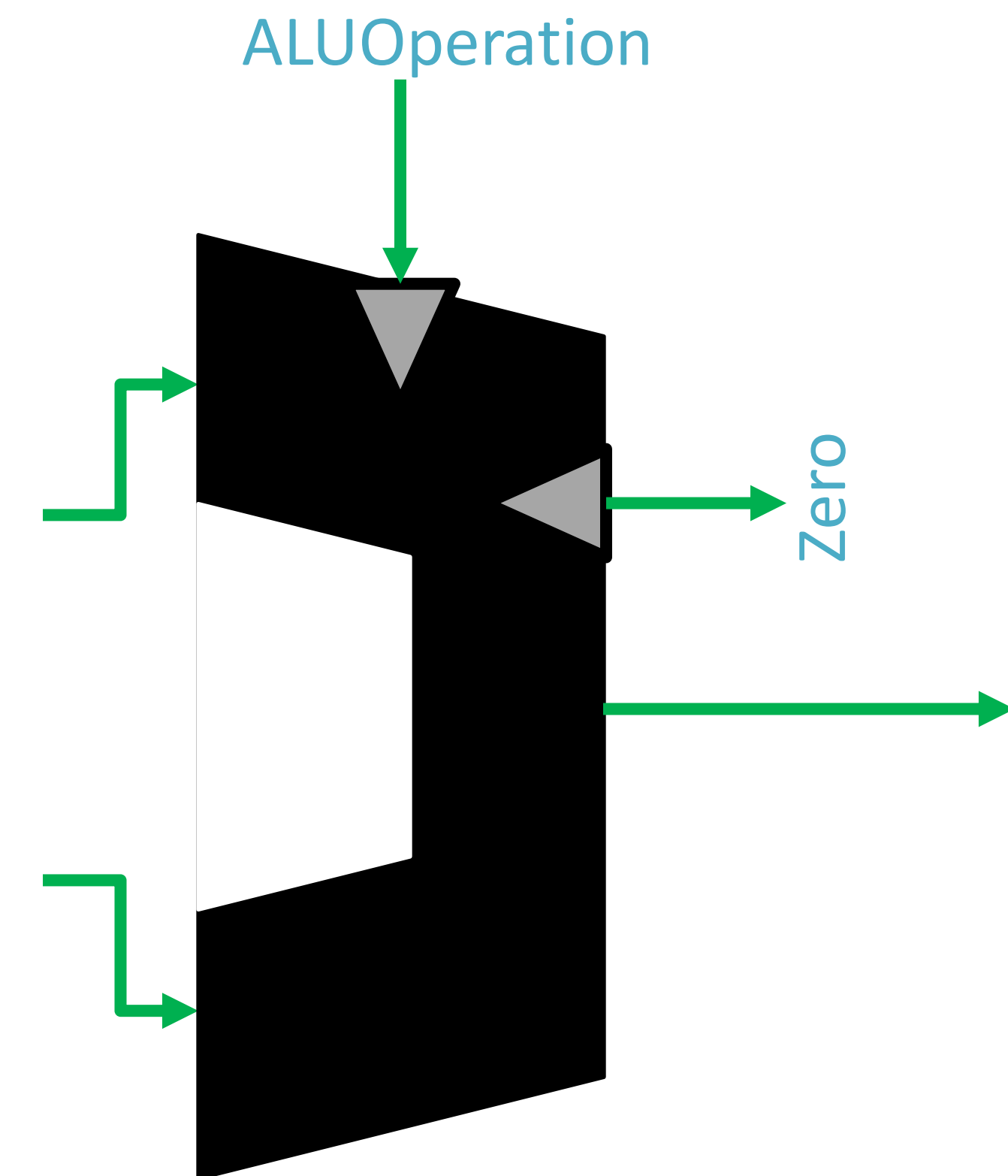
- The register file contains all the registers and has two read ports and one write port.
- The register file always outputs the contents of the registers corresponding to the Read register inputs on the outputs; no other control inputs are needed.
- In contrast, a register write must be explicitly indicated by asserting the write control signal.
- The inputs carrying the register number to the **register file are all 5 bits wide**, whereas the lines carrying **data values are 32 bits wide**. →Why?



## The ALU

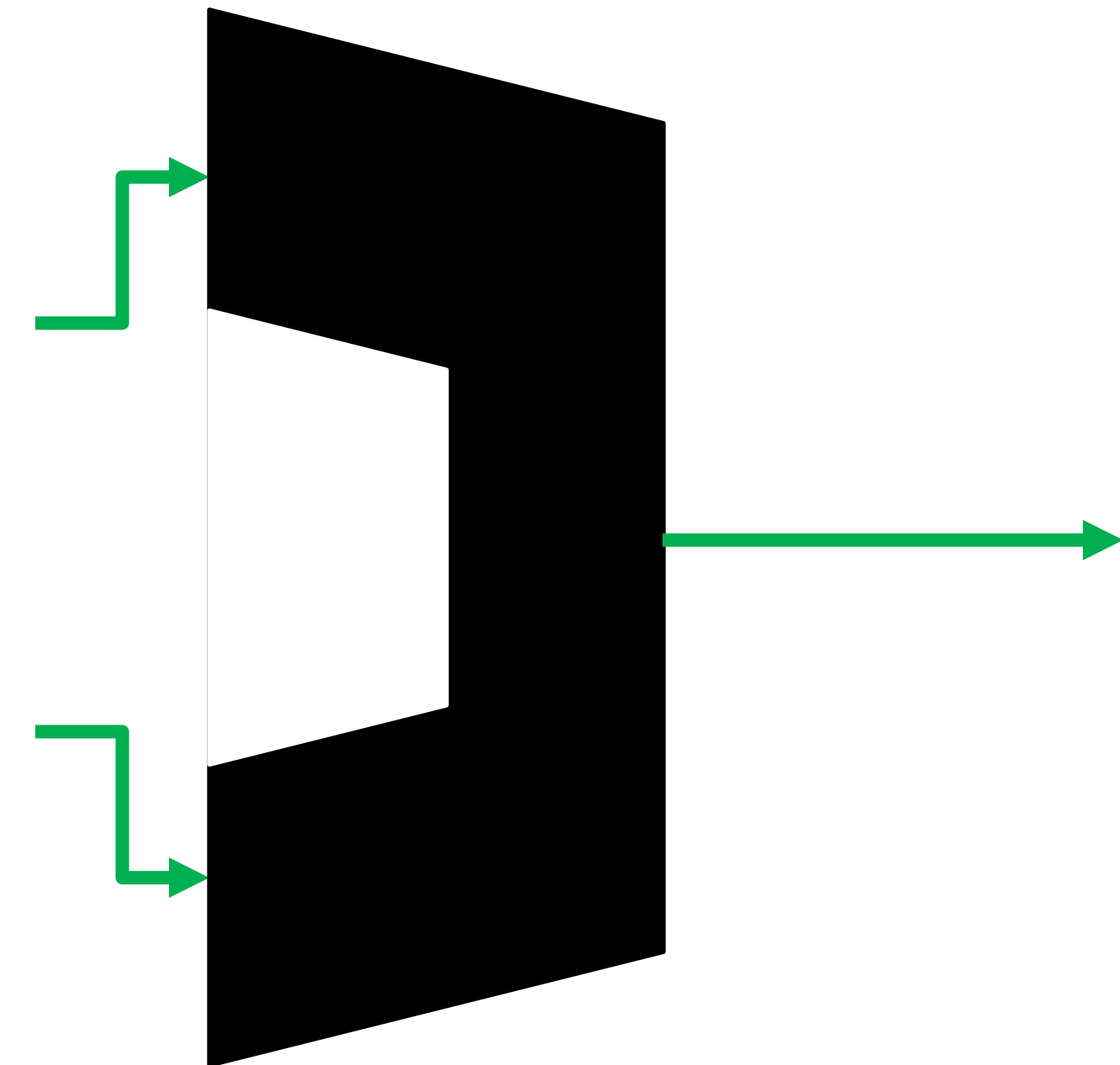
- The operation to be performed by the ALU is controlled with the ALU operation signal, which will be **4 bits wide**. *→What is that?*
- We will use the Zero detection output of the ALU shortly to implement branches.

ALU control lines	Function
0000	AND
0001	OR
0010	add
0110	subtract
0111	set on less than
1100	NOR



## The Adder

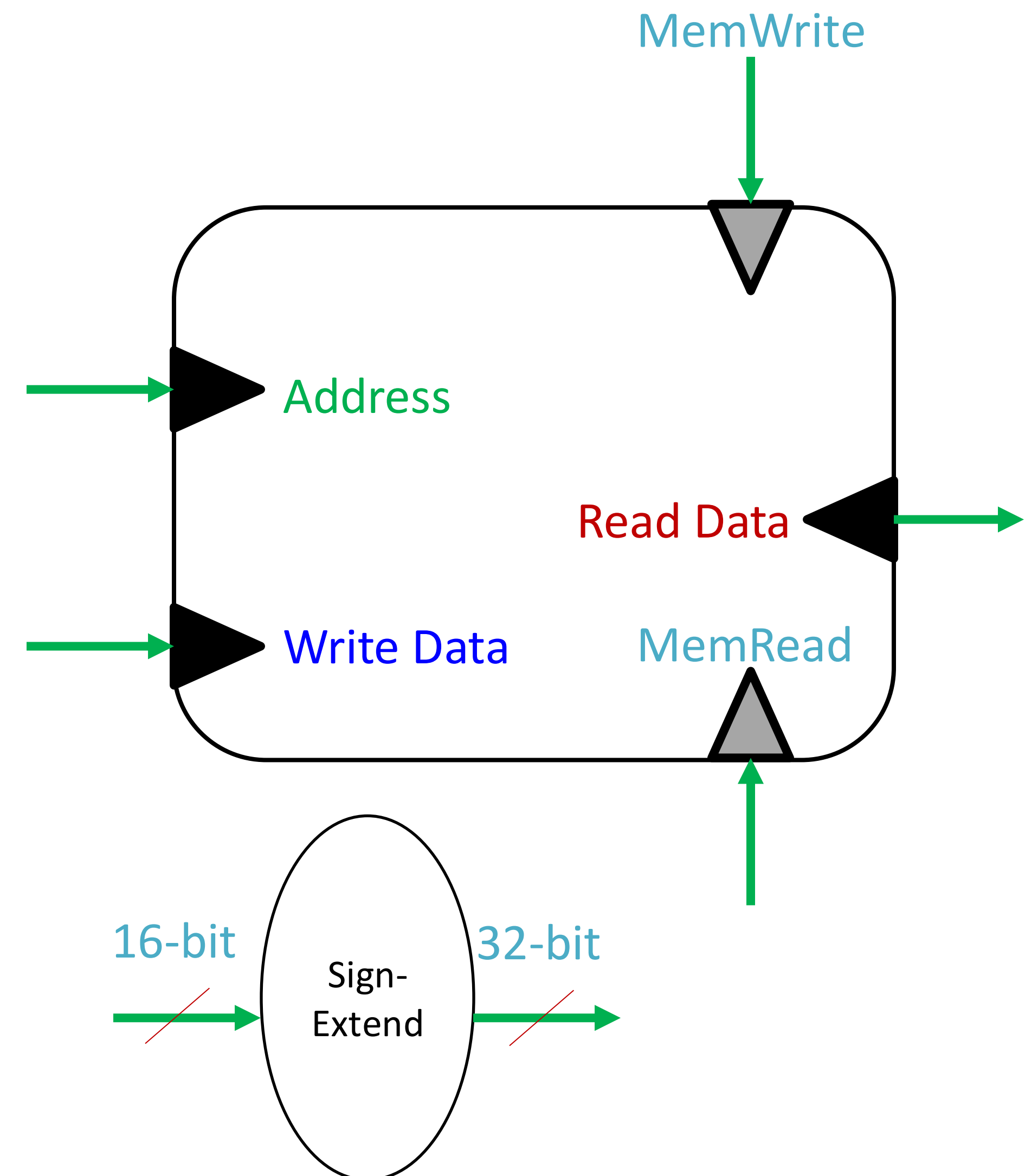
- The adder is an ALU wired to always add its two **32-bit inputs** and place the sum on its output. *→the ALU Operation is always set to add 0010*





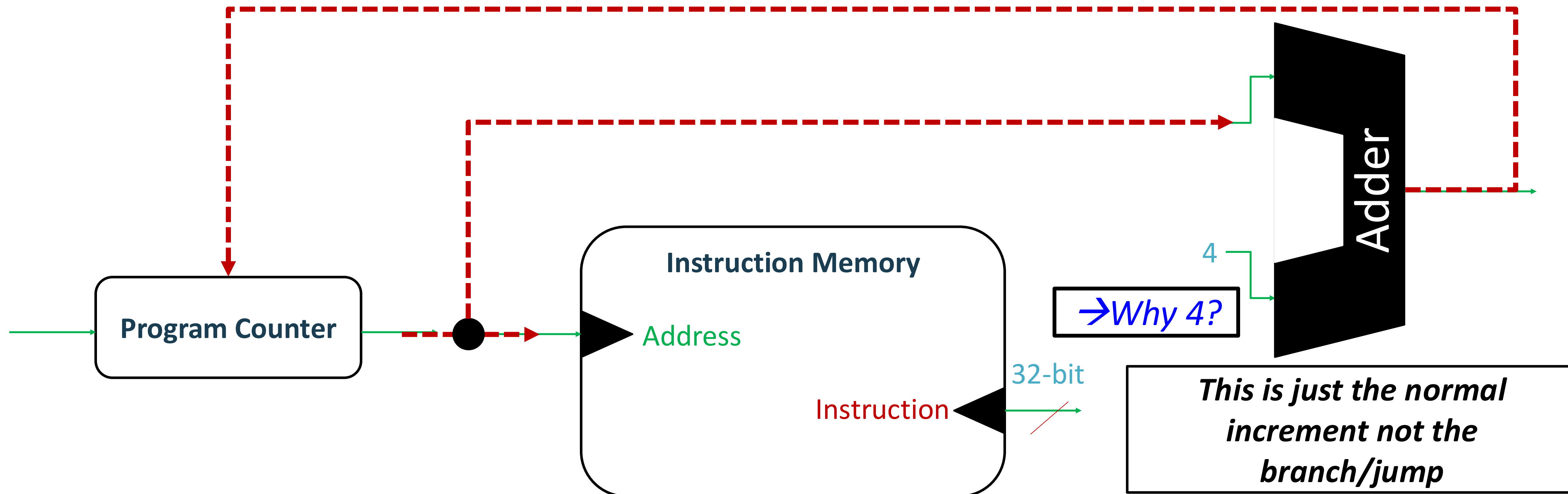
## The Data Memory

- The memory unit is a state element with inputs for the address and the write data, and a single output for the read result.
  - A sign extension unit is needed with a 16-bit input that is sign-extended into a 32-bit result appearing on the output.
  - The sign-extend unit extends the 16-bit offset field in the instruction to a 32-bit signed value, and a data memory unit to read from or write to. The data memory must be written on store instructions; hence, data memory has read and write control signals, an address input, and an input for the data to be written into memory.
- to balance the bits size for the ALU



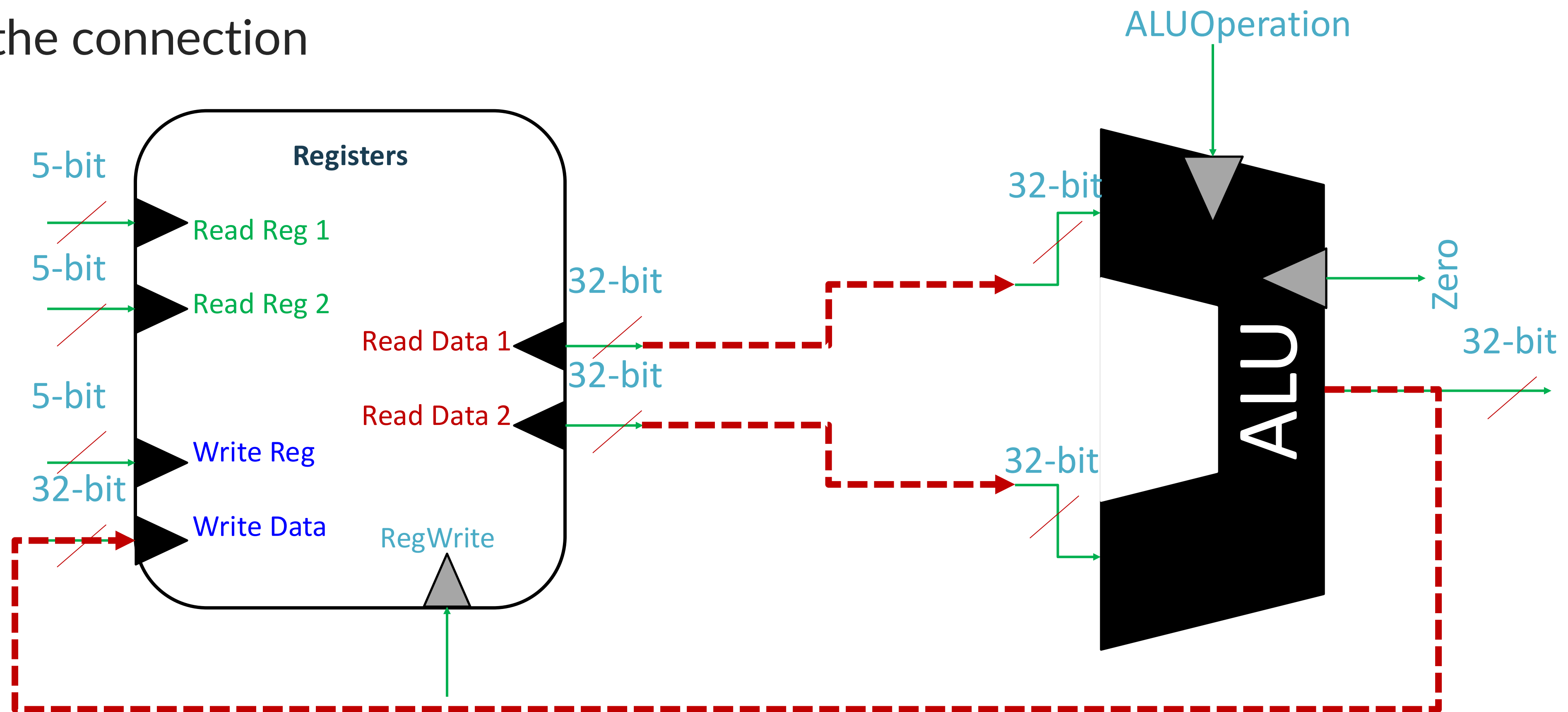
## Fetching instructions and incrementing the program counter

- Here we will need the program counter, the instruction memory, and an adder.
- Let's start the connection



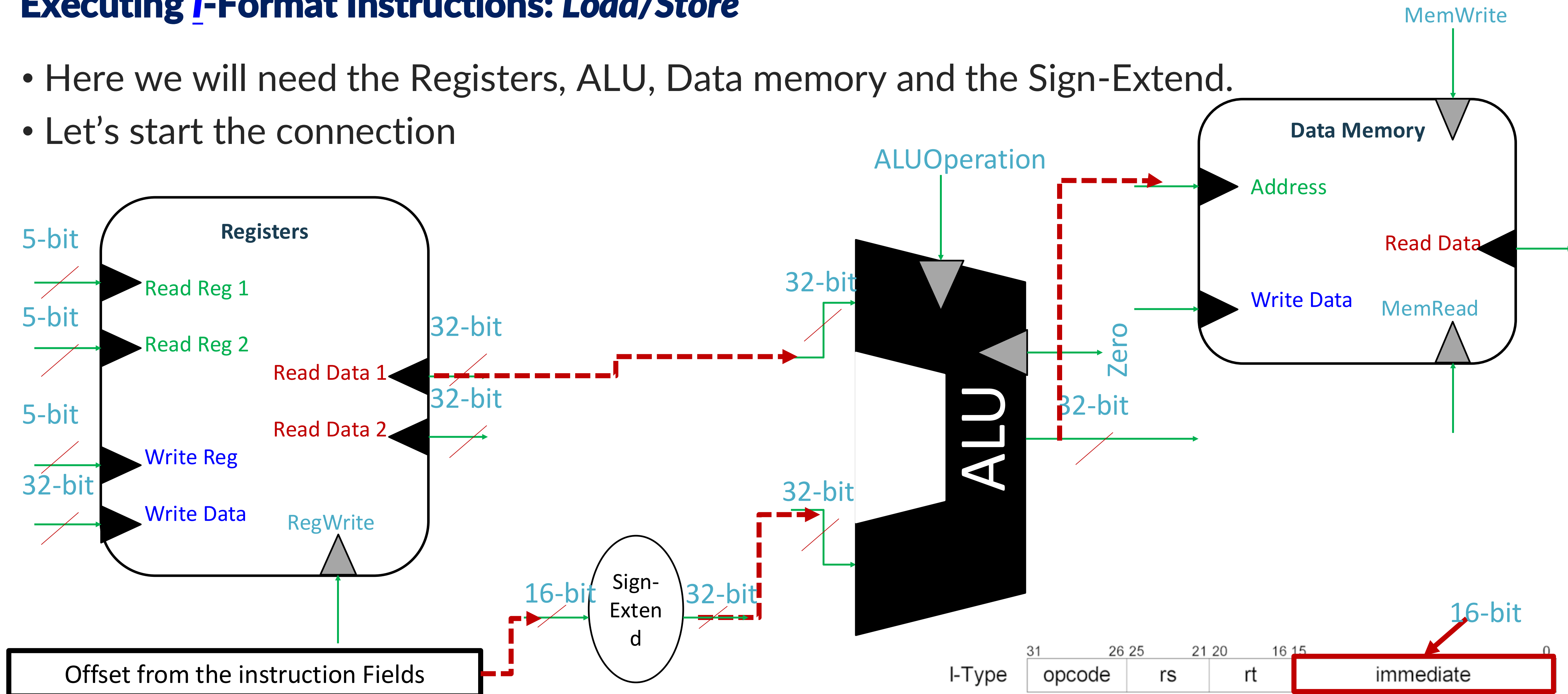
## Executing R-Format Instructions

- Here we will need the Registers and the ALU.
- Let's start the connection

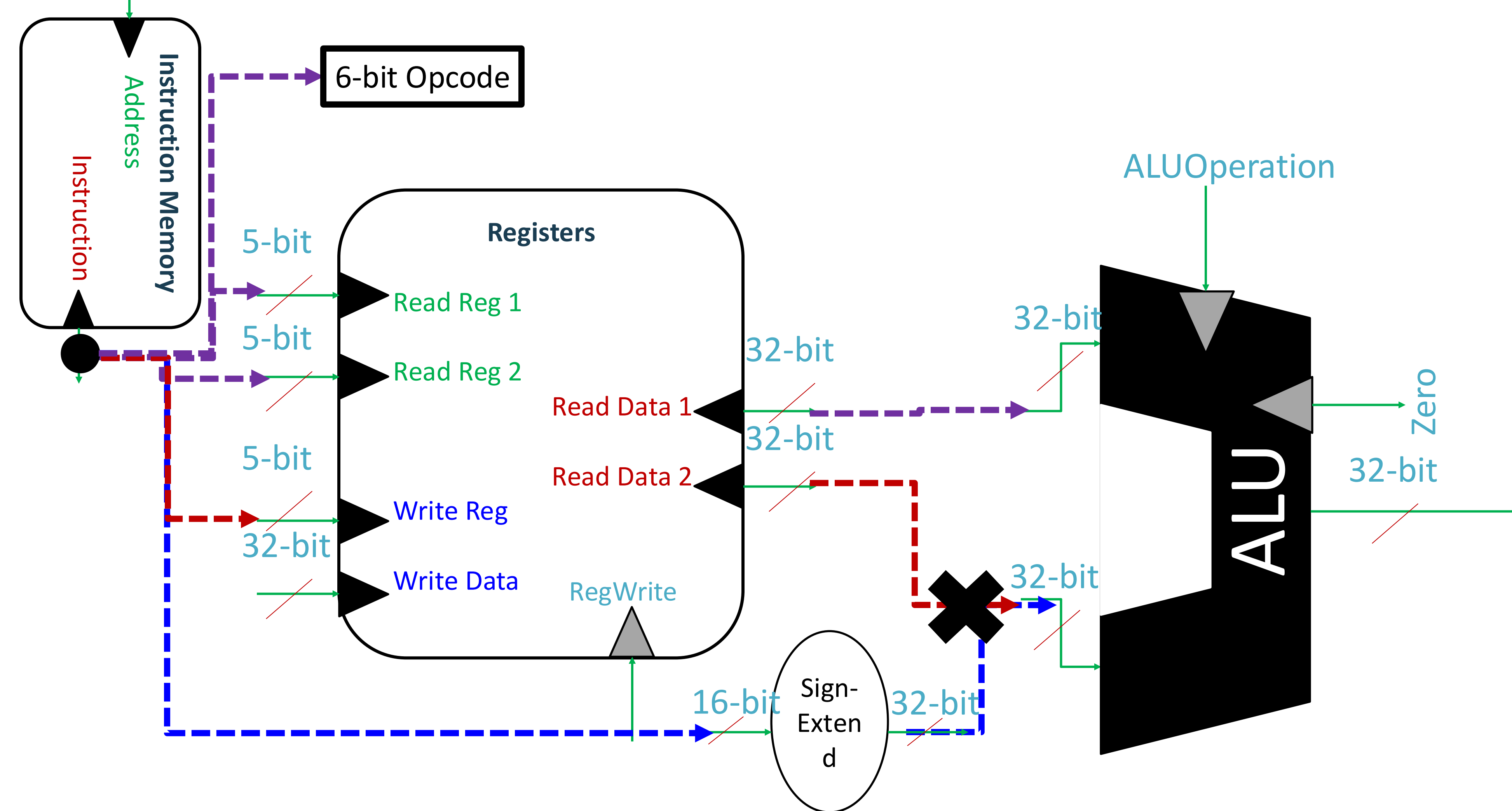


## Executing I-Format Instructions: *Load/Store*

- Here we will need the Registers, ALU, Data memory and the Sign-Extend.
- Let's start the connection

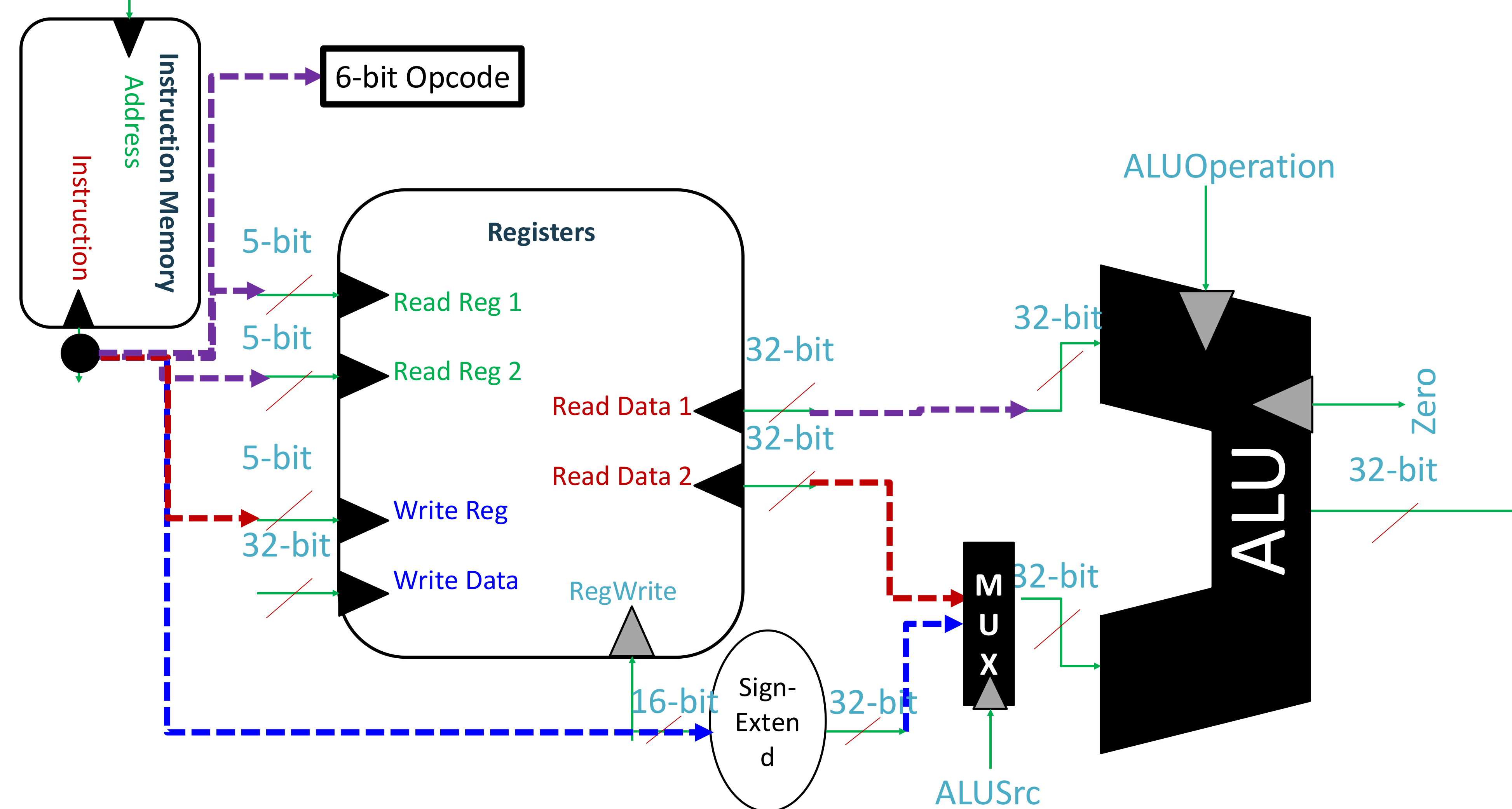


## Executing R&I-Format Instructions: *Load/Store*

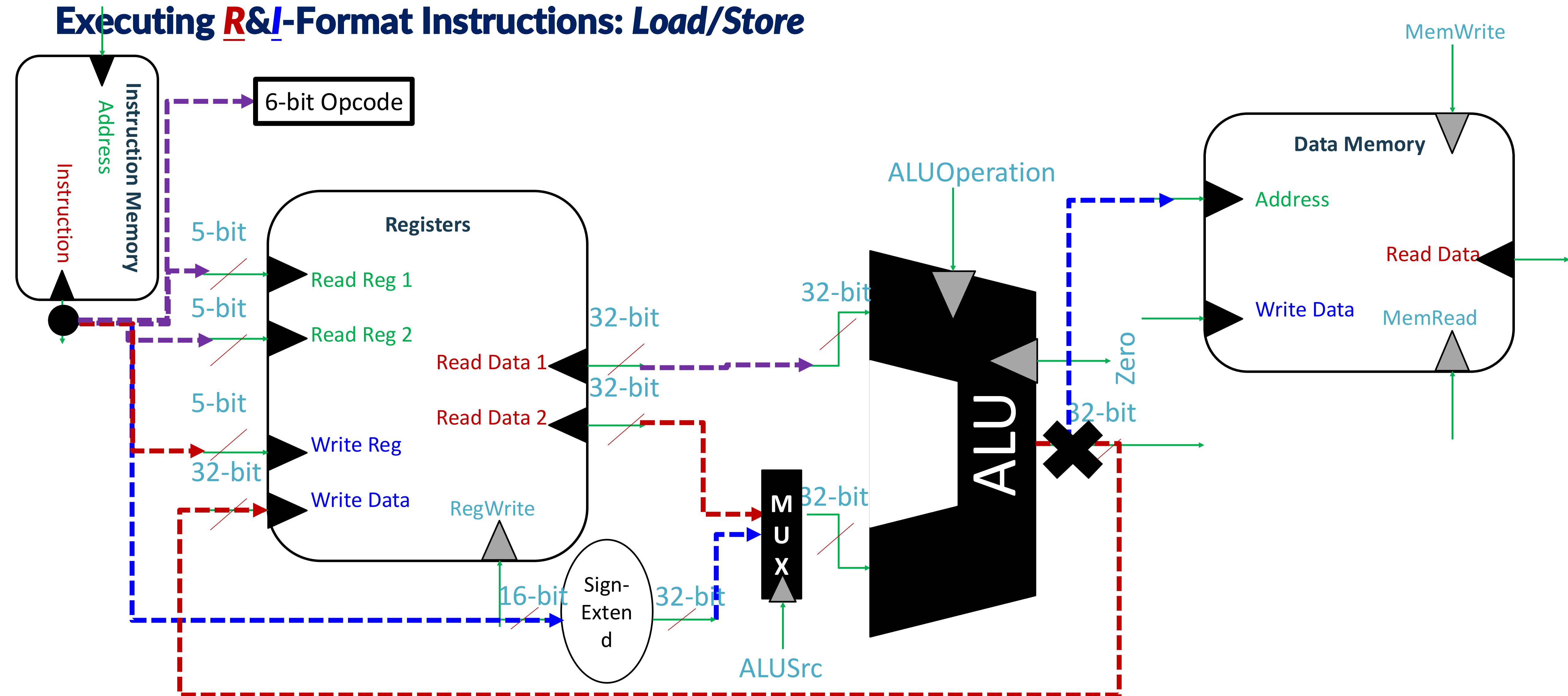




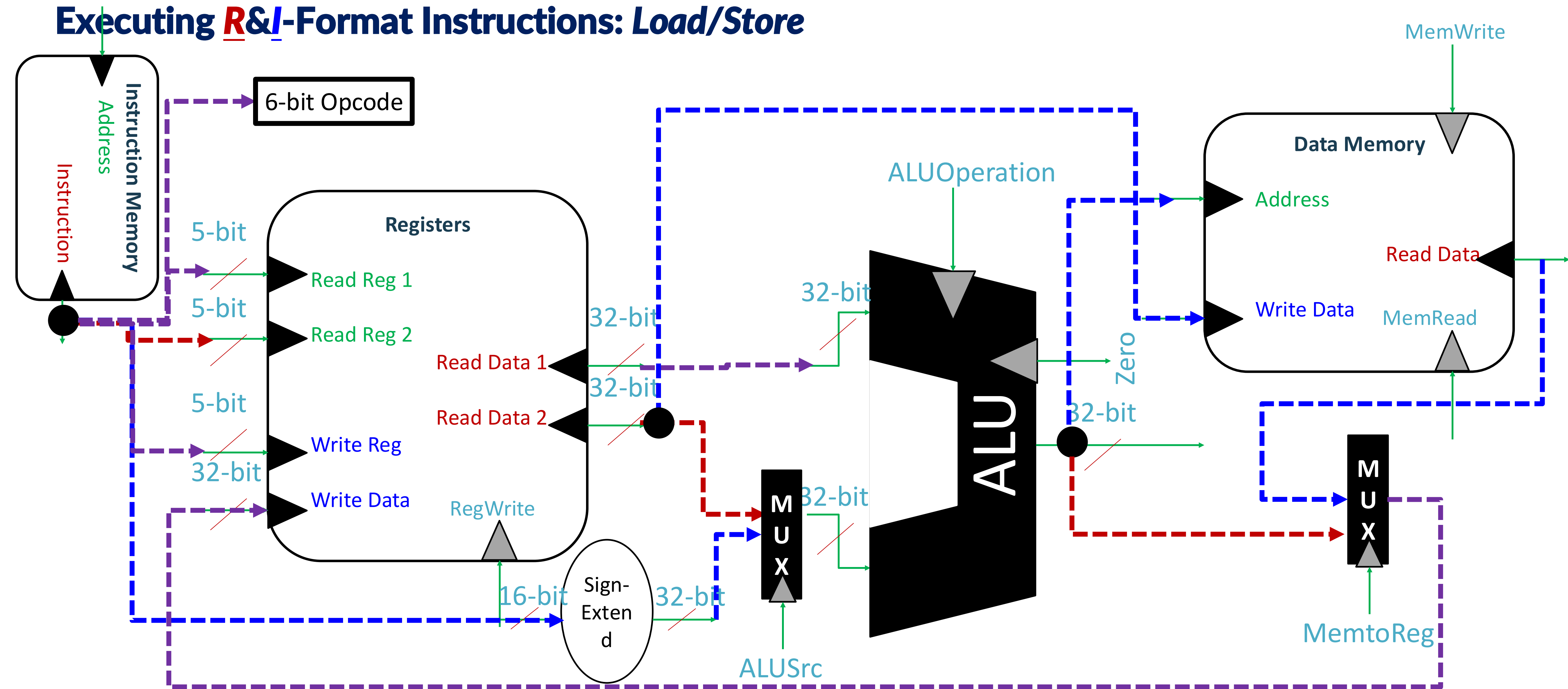
## Executing R&I-Format Instructions: *Load/Store*



## Executing R&I-Format Instructions: *Load/Store*

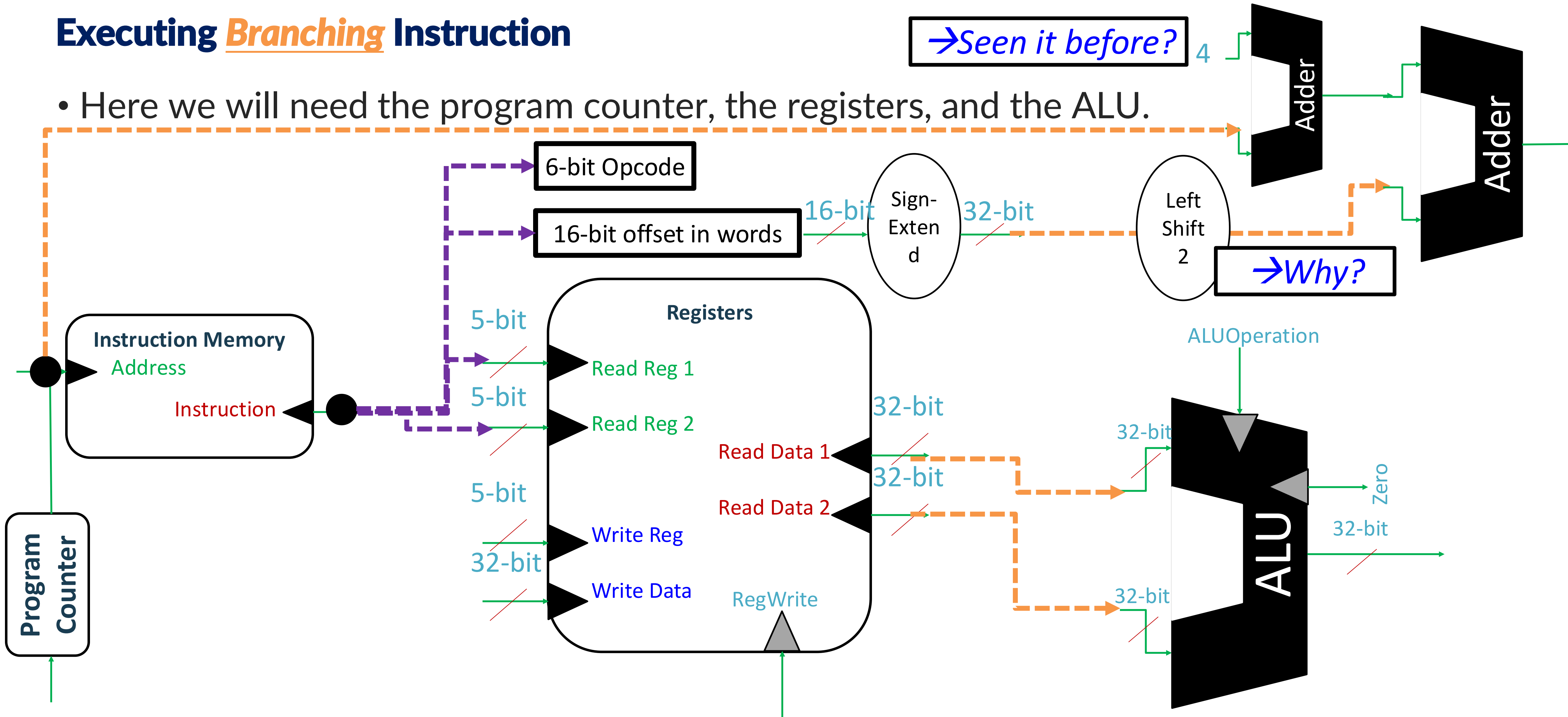


## Executing R&I-Format Instructions: *Load/Store*



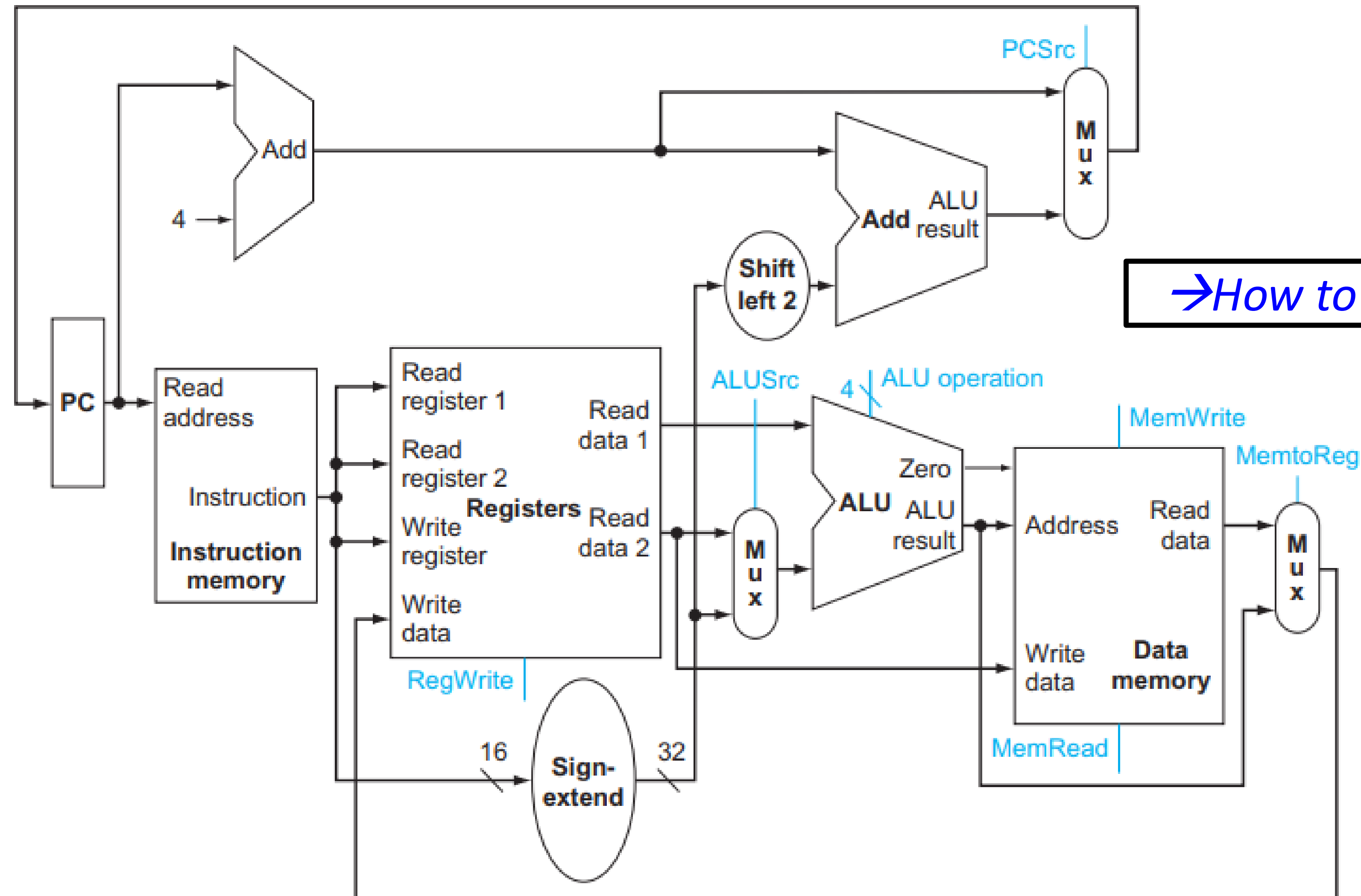
## Executing Branching Instruction

- Here we will need the program counter, the registers, and the ALU.



Let's put R/I/Branch/PC increment together

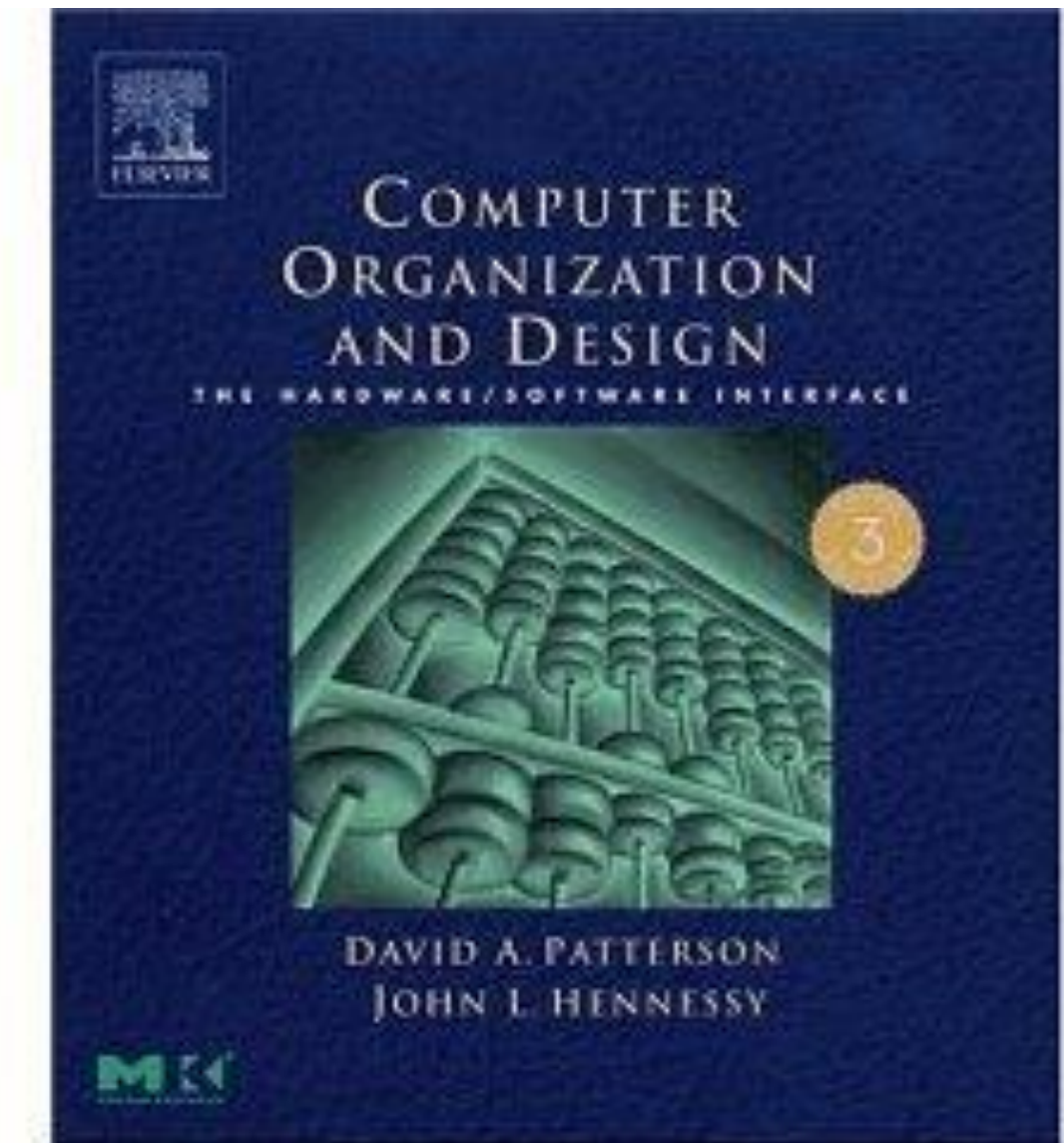
*This is called a single-cycle machine*




→How to control the ALU?



- Patterson, D. A., Hennessy, J. L. (2004). Computer Organization and Design: The Hardware/Software Interface. Netherlands: Morgan Kaufmann. (Chapter 4)





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***Thank you for your attention!***

***See you next time*** 😊