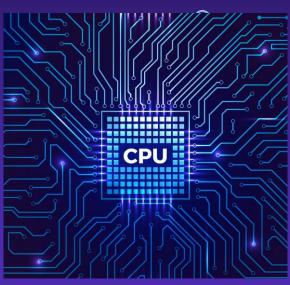
Single cycled mips •processor





Agenda

(01) What is MIPS?

(02) synthesis

02 Architecture.



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What is MIPS?





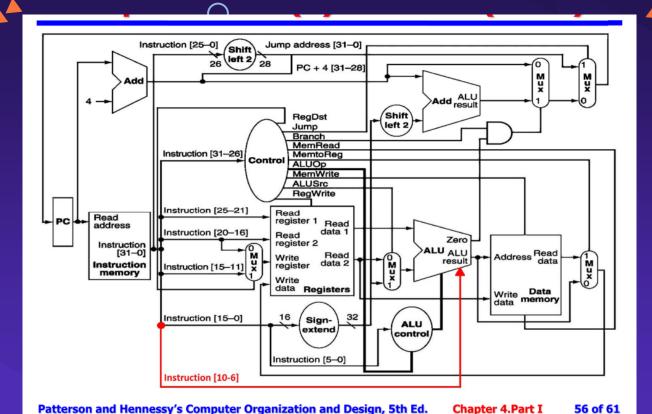


MIPS is a RISC (reduced instruction set computing) instruction set architecture developed by several Stanford researchers in the mid 1980s. Originally, the name was an acronym for Microprocessor without Interlocked Pipeline Stages, but interlocks between pipeline stages were eventually reintroduced, probably for performance reasons as other processors became more advanced. The decision for making a processor without interlocking pipeline stages was based on performance and simplicity of design. With interlocks, operations such as integer division, which is very time-consuming, would cause other pipeline phases to wait until the execute unit was done with the division. This defeats the purpose of pipelining because it causes sections of the processor to idle. Reducing all phases to one clock cycle removes idling (however it might force the clock to be slower).

MIPS follows the classic 5-stage RISC pipeline: Instruction Fetch (IF), Instruction Decode/Operand Fetch (ID), Execute (EX), Memory Access (MEM), and Write Back (WB). MIPS is a load-store architecture, which means that to do arithmetic on data, values must explicitly be read from memory with a special load instruction and written to memory with a store instruction; arithmetic instructions only operate on registers.

In my opinion, MIPS is a really great architecture if you're interested in learning about ISAs, computer architecture, and computer organization because it is straightforward and simple.

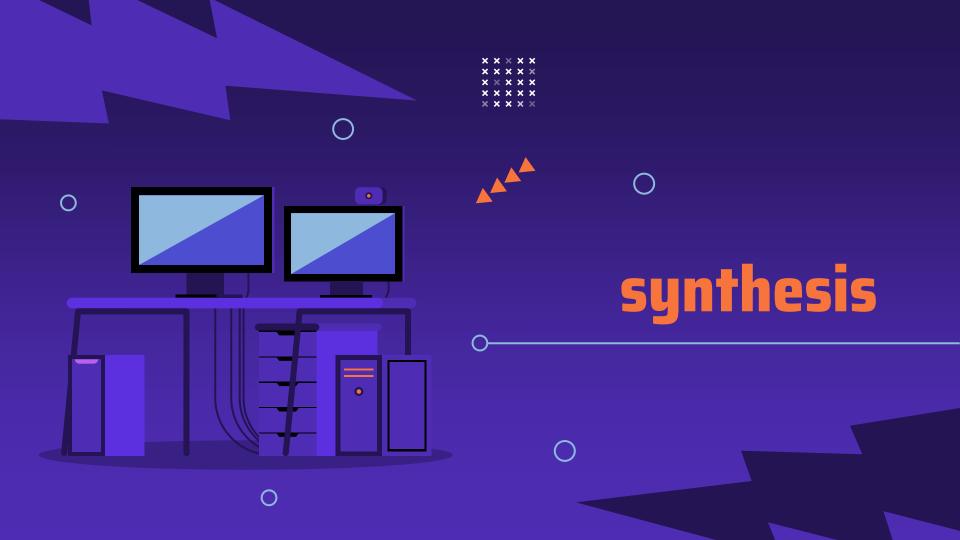




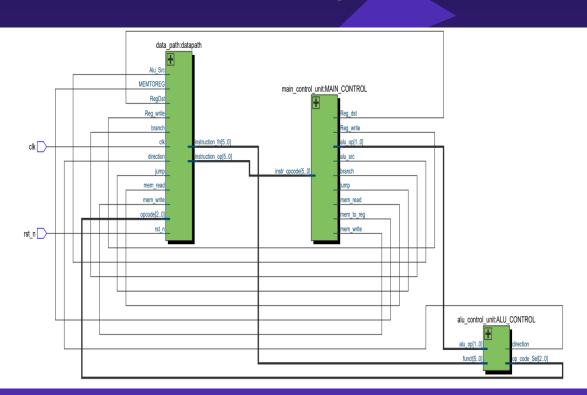
This MIPS support the following instructions:

							or	R	0	37	
Instruction		Form	nat	op	funct						
add		R		0 ₁₀	32 ₁₀						
	addi	I		8			sra	R	0	3	
	and	R		0	36	_	srl	R	0	2	
	lw		I		35		sub	R	0	34	
	nor		R		0	39	sw	I	43		
Ľ									•		
	j		J 2								
	beq		I		4		sll	R	0	0	Po
	_									_	

It also supports multiplication through the alu

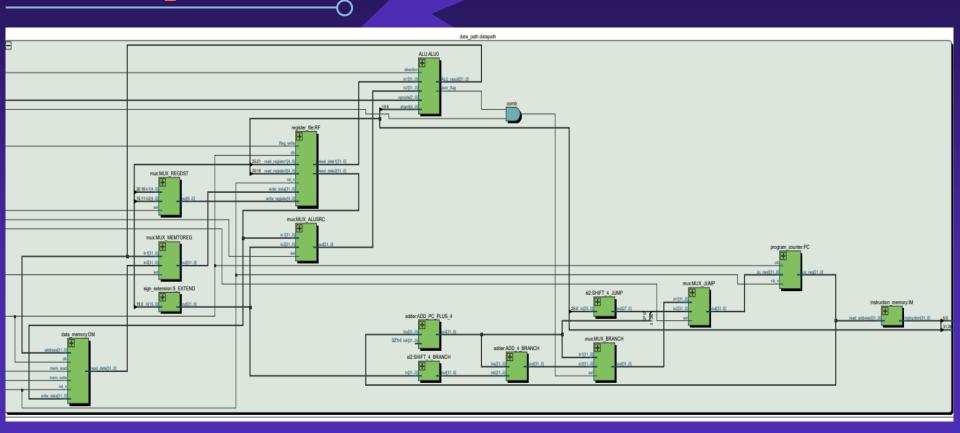


Top module

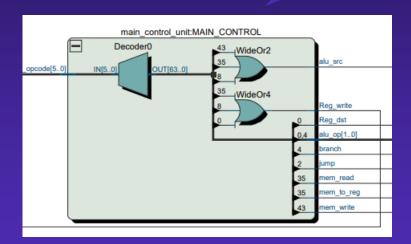




Data path



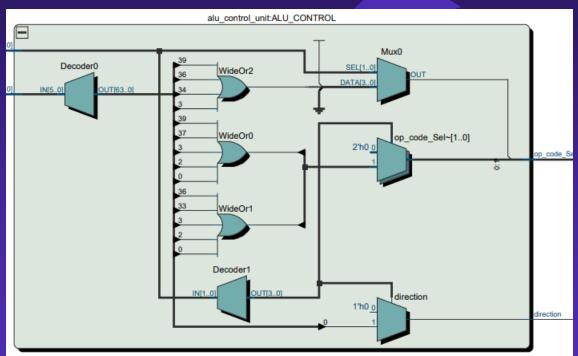
Main control unit







Alu control unit





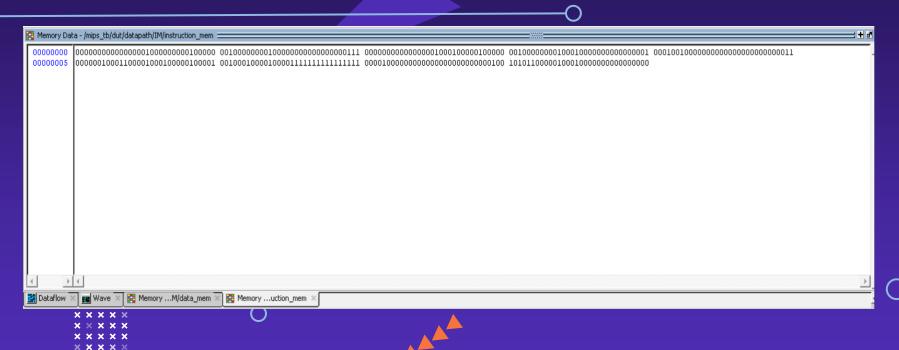




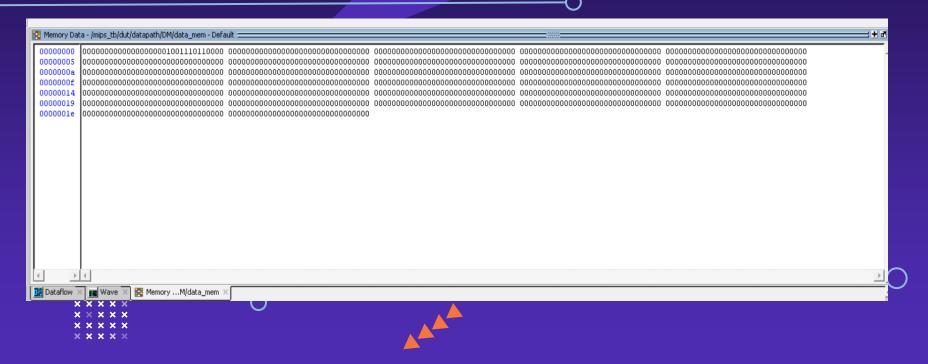
add \$s0, \$0, \$0 addi \$s0, \$0, 7 add \$s1, \$0, \$0 addi \$s1, \$0, 1 beq \$s1, \$0, 3 mul \$s1, \$s1, \$s0 addi \$s0, \$s0, -1 J 4 sw \$s1, 0(\$0)

This program 1 that I used to test the MIPS and it calculates the factorial of 7

Instruction memory



data memory



Snippet that shows how many cycles the program takes



ADDI \$t1 \$t0 0x1926

SLL \$t0 \$t1 1

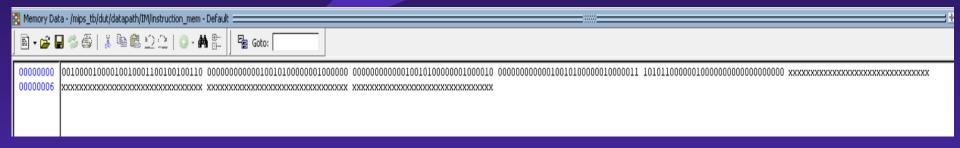
SRL \$t0 \$t1 1

SRA \$t0 \$t1 2

SW \$t0 0(\$zero)

This is program 2 that I used to test the MIPS and it tests the 3 shift instructions and sw

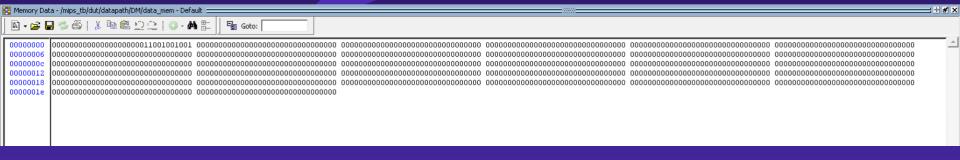
Instruction memory







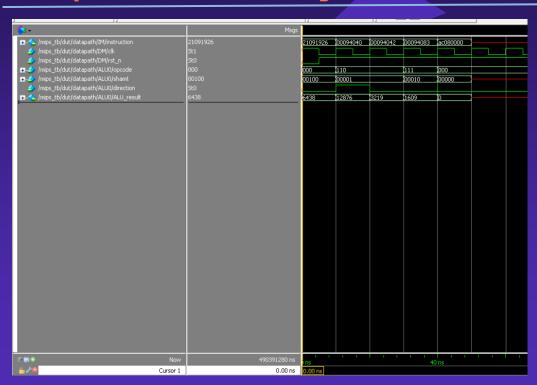
data memory







Snippet that shows how many cycles the program takes and the output of the Alu after every instruction



<u>Hint</u>: direction signal is high in SLL and low in SRL