

Collaborators:

Poole 6.6 #2 Find the matrix $[T]_{\mathcal{C} \leftarrow \mathcal{B}}$ of the linear transformation $T : V \rightarrow W$ with respect to the bases \mathcal{B} and \mathcal{C} of V and W , respectively. Verify Theorem 2.26 for the vector \mathbf{v} by computing $T(\vec{v})$ directly and using the theorem.

$T : \mathcal{P}_1 \rightarrow \mathcal{P}_1$ defined by $T(a + bx) = b - ax$, $\mathcal{B} = \{1 + x, 1 - x\}$, $\mathcal{C} = \{1, x\}$, $\mathbf{v} = p(x) = 4 + 2x$.

■

Poole 6.6 #4 Find the matrix $[T]_{\mathcal{C} \leftarrow \mathcal{B}}$ of the linear transformation $T : V \rightarrow W$ with respect to the bases \mathcal{B} and \mathcal{C} of V and W , respectively. Verify Theorem 2.26 for the vector \mathbf{v} by computing $T(\vec{v})$ directly and using the theorem.

$T : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ defined by $T(p(x)) = p(x+2)$, $\mathcal{B} = \{1, x+2, (x+2)^2\}$, $\mathcal{C} = \{1, x, x^2\}$, $\mathbf{v} = p(x) = a + bx + cx^2$.

■

Poole 6.6 #12 Find the matrix $[T]_{\mathcal{C} \leftarrow \mathcal{B}}$ of the linear transformation $T : V \rightarrow W$ with respect to the bases \mathcal{B} and \mathcal{C} of V and W , respectively. Verify Theorem 2.26 for the vector \mathbf{v} by computing $T(\vec{v})$ directly and using the theorem.

$T : M_{22} \rightarrow M_{22}$ defined by $T(A) = A - A^T$, $\mathcal{B} = \mathcal{C} = \{E_{11}, E_{12}, E_{21}, E_{22}\}$, $\mathbf{v} = A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$.

■

Poole 6.6 #14 Consider the subspace W of \mathcal{D} , given by $W = \text{span}(e^{2x}, e^{-2x})$.

- (a) Show that the differential operator D maps W into itself.
- (b) Find the matrix of D with respect to $\mathcal{B} = \{e^{2x}, e^{-2x}\}$.
- (c) Compute the derivative of $f(x) = e^{2x} - 3e^{-2x}$ indirectly, using Theorem 6.26, and verify that it agrees with $f'(x)$ as computed directly.

■

Poole 6.6 #18 $T : U \rightarrow V$ and $S : V \rightarrow W$ are linear transformation and \mathcal{B} , \mathcal{C} , and \mathcal{D} are bases for U , V , and W , respectively. Compute $[S \circ T]_{\mathcal{D} \leftarrow \mathcal{B}}$ in two ways:

- (a) By finding $S \circ T$ directly and then computing its matrix
- (b) by finding the matrices of S and T separately and using Theorem 6.27.

$T : \mathcal{P}_1 \rightarrow \mathcal{P}_2$ defined by $T(p(x)) = p(x + 1)$, $S : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ defined by $S(p(x)) = p(x + 1)$, $\mathcal{B} = \{1, x\}$, $\mathcal{C} = \mathcal{D} = \{1, x, x^2\}$.

■

Poole 6.6 #22 Determine whether the linear transformation T is invertible by considering its matrix with respect to the standard bases. If T is invertible, use Theorem 6.28 and the method of Example 6.82 to find T^{-1} .

$$T : \mathcal{P}_2 \rightarrow \mathcal{P}_2 \text{ defined by } T(p(x)) = p'(x).$$

■

Poole 6.6 #32 a linear transformation $T : V \rightarrow V$ is given. If possible, find a basis \mathcal{C} for V such that the matrix $[T]_{\mathcal{C}}$ of T with respect to \mathcal{C} is diagonal.

$$T : \mathbb{R}^2 \rightarrow \mathbb{R}^2 \text{ defined by } T \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} a - b \\ a + b \end{bmatrix}.$$

■

Poole 6.6 #34 a linear transformation $T : V \rightarrow V$ is given. If possible, find a basis \mathcal{C} for V such that the matrix $[T]_{\mathcal{C}}$ of T with respect to \mathcal{C} is diagonal.

$$T : \mathcal{P}_2 \rightarrow \mathcal{P}_2 \text{ defined by } T \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} a - b \\ a + b \end{bmatrix}.$$

■