

# Lecture Notes1: PDE

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# 1 Introduction

## 1.1 Mathematical model

The process of describing a real world problem in mathematical terms

## 1.2 differential equations

An equation that relates one or more unknown functions and their derivatives.

- **ODE:** An equation that contains one or several derivatives of unknown function and single variable.
- **PDE:** An equation that contains partial derivatives of unknown function of two or more variables

## 1.3 Common examples of PDEs

- $u_t + cu_x = 0$
- $u_{xx} + u_{yy} = f(x, y)$
- $a(x, y)u_{xx} + 2uxy + 3x^2u_{yy} = 4e^x$
- $u_x u_{xx} + (u_y)^2 = 0$
- $(u_{xx})^2 + u_{yy} + a(x, y)u_x + b(x, y)u = 0$

# 2 Basic concepts and definitions

## 2.1 Definition 1

The order of a PDE is the order of the highest order derivative in the equation.

### Examples

- **first order**

1.  $u_t + cu_x = 0$

- **second order**

1.  $u_{xx} + u_{yy} = f(x, y)$
2.  $u_x u_{xx} + (u_y)^2 = 0$

## 2.2 Definition 2

A PDE is linear if it's linear in the unknown function and all its derivatives with coefficients depending only on the independent variables.

### Examples

- **linear**

1.  $u_t + cu_x = 0$
2.  $u_{xx} + u_{yy} = f(x, y)$
3.  $a(x, y)u_{xx} + 2uxy + 3x^2u_{yy} = 4e^x$

- **Non-linear**

1.  $u_x u_{xx} + (uy)^2 = 0$
2.  $(u_{xx})^2 + u_{yy} + a(x, y)u_x + b(x, y)u = 0$

## 2.3 Definition 3

A PDE is homogeneous if the equation does not contain a term independent of the unknown function and its derivatives.

### Examples

- **linear**

1.  $u_t + cu_x = 0$
2.  $u_x u_{xx} + (uy)^2 = 0$
3.  $(u_{xx})^2 + u_{yy} + a(x, y)u_x + b(x, y)u = 0$

- **Non-linear**

1.  $u_{xx} + u_{yy} = f(x, y)$
2.  $a(x, y)u_{xx} + 2uxy + 3x^2u_{yy} = 4e^x$

### 3 Basic exercises

#### Example 1

Show that  $\mathbf{u}(\mathbf{x}, \mathbf{y}) = \mathbf{F}(\mathbf{xy}) + \mathbf{xG}(\frac{\mathbf{x}}{\mathbf{y}})$  is a general solution of the PDE  $\mathbf{x}^2\mathbf{u}_{\mathbf{xx}} - \mathbf{y}^2\mathbf{u}_{\mathbf{yy}} = 0$

$$\begin{aligned} \text{let } \alpha &= xy \text{ and } \beta = \frac{y}{x} \\ \alpha_x &= y \quad \alpha_y = x \quad \beta_x = \frac{-y}{x^2} \quad \beta_y = \frac{1}{x} \\ \therefore u &= F(\alpha) + xG(\beta) \\ \therefore u_x &= y\dot{F} + G(\beta) - \dot{G}\frac{y}{x} \\ \therefore u_{xx} &= y^2\ddot{F} + \frac{y^2}{x^3}\ddot{G} \\ \therefore u_y &= x\dot{F} + \dot{G} \\ \therefore u_{yy} &= x^2\dot{F} + \frac{1}{x}\ddot{G} \end{aligned}$$

$$\therefore x^2u_{xx} - y^2u_{yy} = x^2y^2\ddot{F} + \frac{y^2}{x}\ddot{G} - x^2y^2\dot{F} - \frac{y^2}{x}\ddot{G} = 0$$

#### Example 2: PDE can have many solutions

Find three possible solutions to any 2D Laplace Equation under specific initial conditions and boundary conditions  $\mathbf{u}_{\mathbf{xx}} + \mathbf{u}_{\mathbf{yy}} = 0$

$$\begin{aligned} \text{first sol: } u(x, y) &= x^2 - y^2 \\ \text{second sol: } u(x, y) &= \ln(x^2 + y^2) \\ \text{second sol: } e^x \cos(y) \end{aligned}$$

### 4 Fundamental Theorem (Superposition)

Let D be linear differential operators (in the variables  $x_1, x_2, \dots, x_n$ ), let f1 and f2 be functions (in the same variables), and let c1 and c2 be constants.

- If  $u_1$  solves the linear PDE  $Du = f_1$  and  $u_2$  solves  $Du = f_2$ , then  $u = c_1u_1 + c_2u_2$  solves  $Du = c_1f_1 + c_2f_2$ . In particular, if  $u_1$  and  $u_2$  both solve the same homogeneous linear PDE, so does  $u = c_1u_1 + c_2u_2$ .
- If  $u_1$  satisfies the linear boundary condition  $Du|_A = f_1|_A$  and  $u_2$  satisfies  $Du|_A = f_2|_A$ , then  $u = c_1u_1 + c_2u_2$  satisfies  $Du|_A = c_1f_1 + c_2f_2|_A$ . In particular, if  $u_1$  and  $u_2$  both satisfy the same homogeneous linear boundary conditions, so does  $u = c_1u_1 + c_2u_2$ .

## 5 Classification of linear 2nd order PDEs

- Linear Second order PDEs are used to model many systems in many different fields
- The general form of a linear 2nd order PDE in two variables  $x$  and  $y$  is given by:  $\mathbf{A}u_{xx} + \mathbf{B}u_{xy} + \mathbf{C}u_{yy} + \mathbf{D}u_x + \mathbf{E}u_y + \mathbf{F}u = \mathbf{G}$  , Where  $A, B, C, D, E, F$ , and  $G$  depend only on  $x$  and  $y$ .
- A discriminant at some point is defined as:  $\Delta = B^2 - 4AC$

The PDE is classified as follows:

- $\Delta > 0$ : Hyperbolic
- $\Delta = 0$ : Parabolic
- $\Delta < 0$ : Elliptic