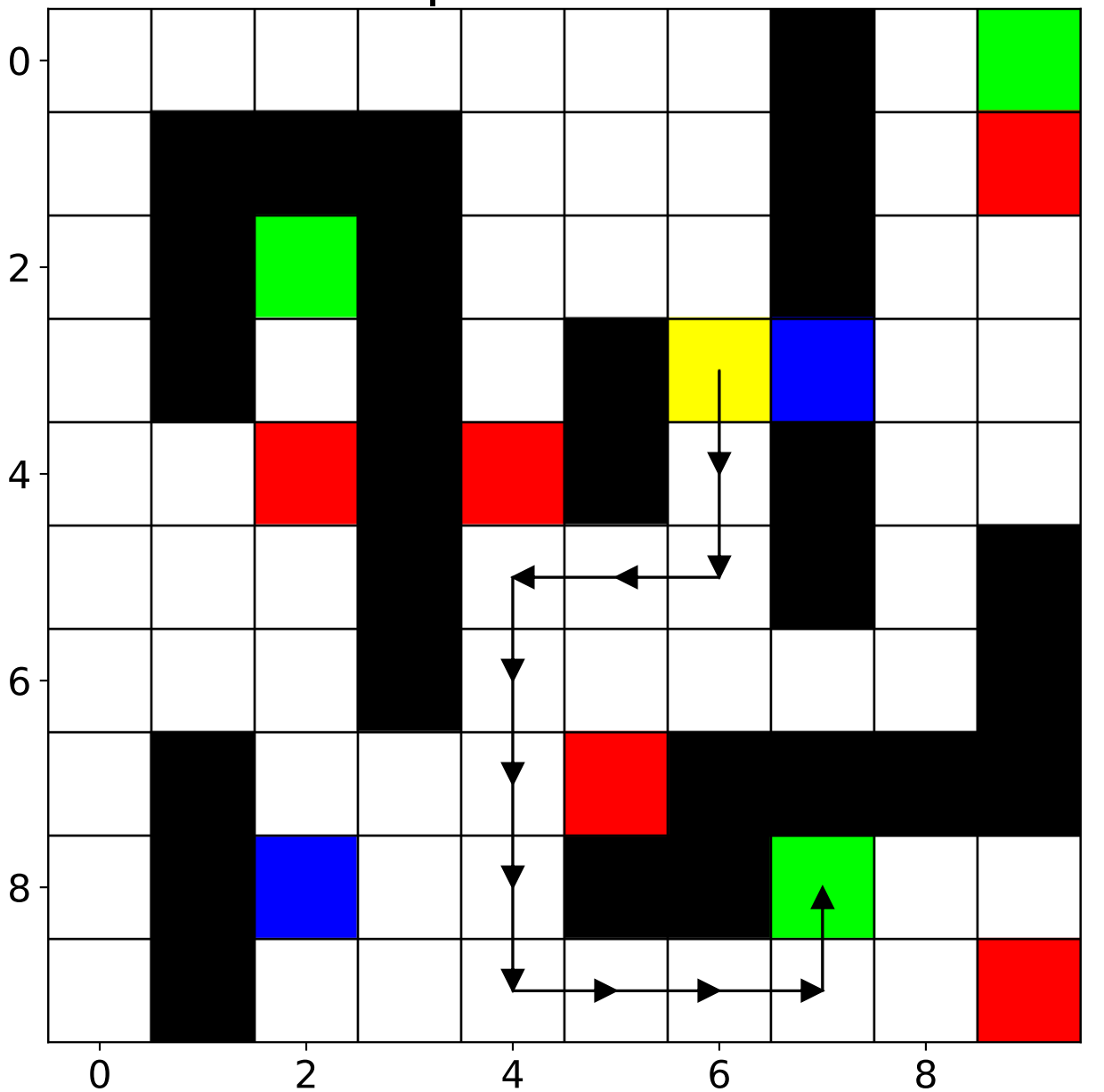


# Optimal Path



- |            |               |             |
|------------|---------------|-------------|
| Obstructed | Restart State | Start State |
| Bad State  | Goal State    |             |