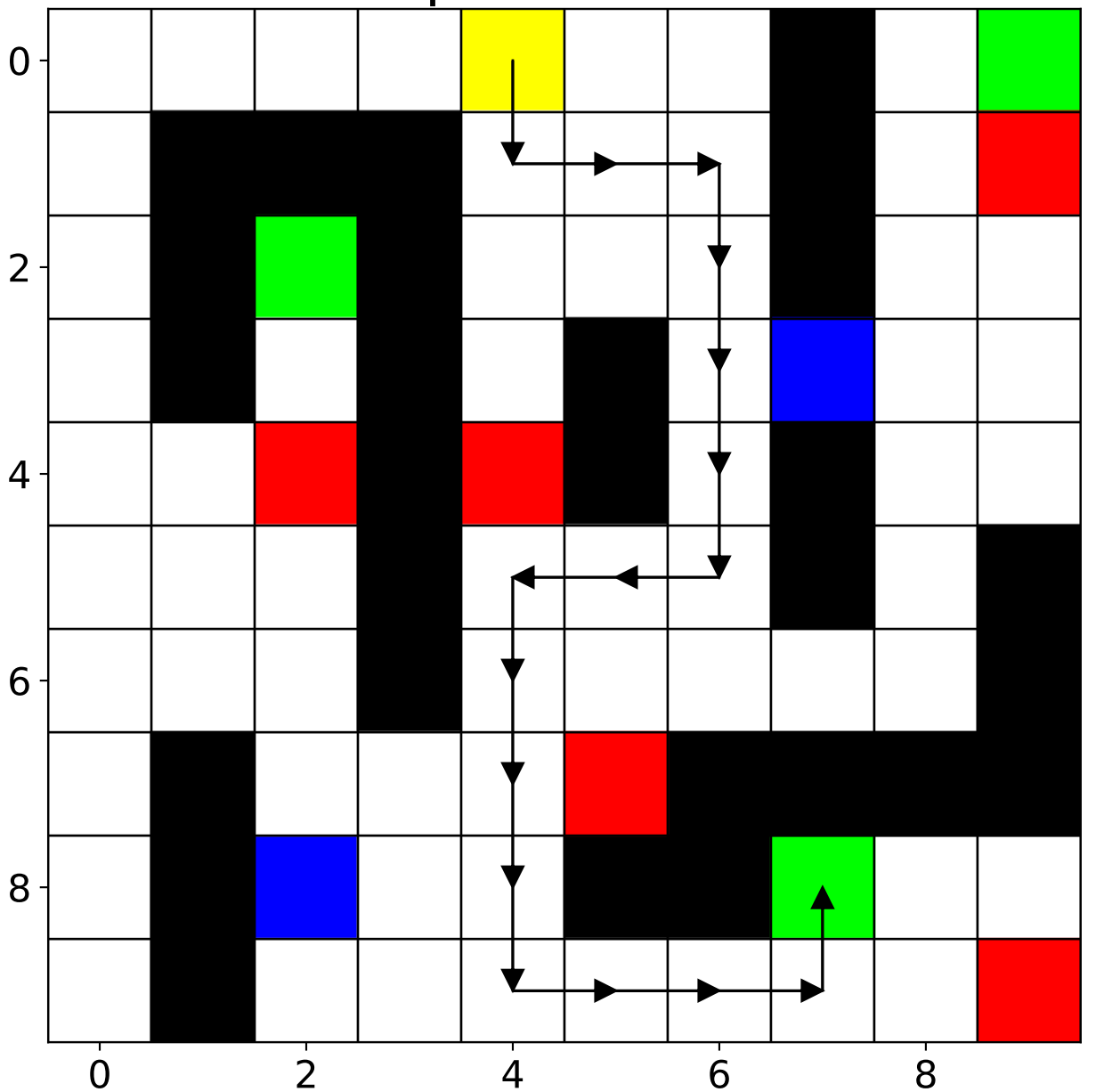


# Optimal Path



- |  |   |   |
|--|---|---|
|  Obstructed |  Restart State |  Start State |
|  Bad State  |  Goal State    |   |