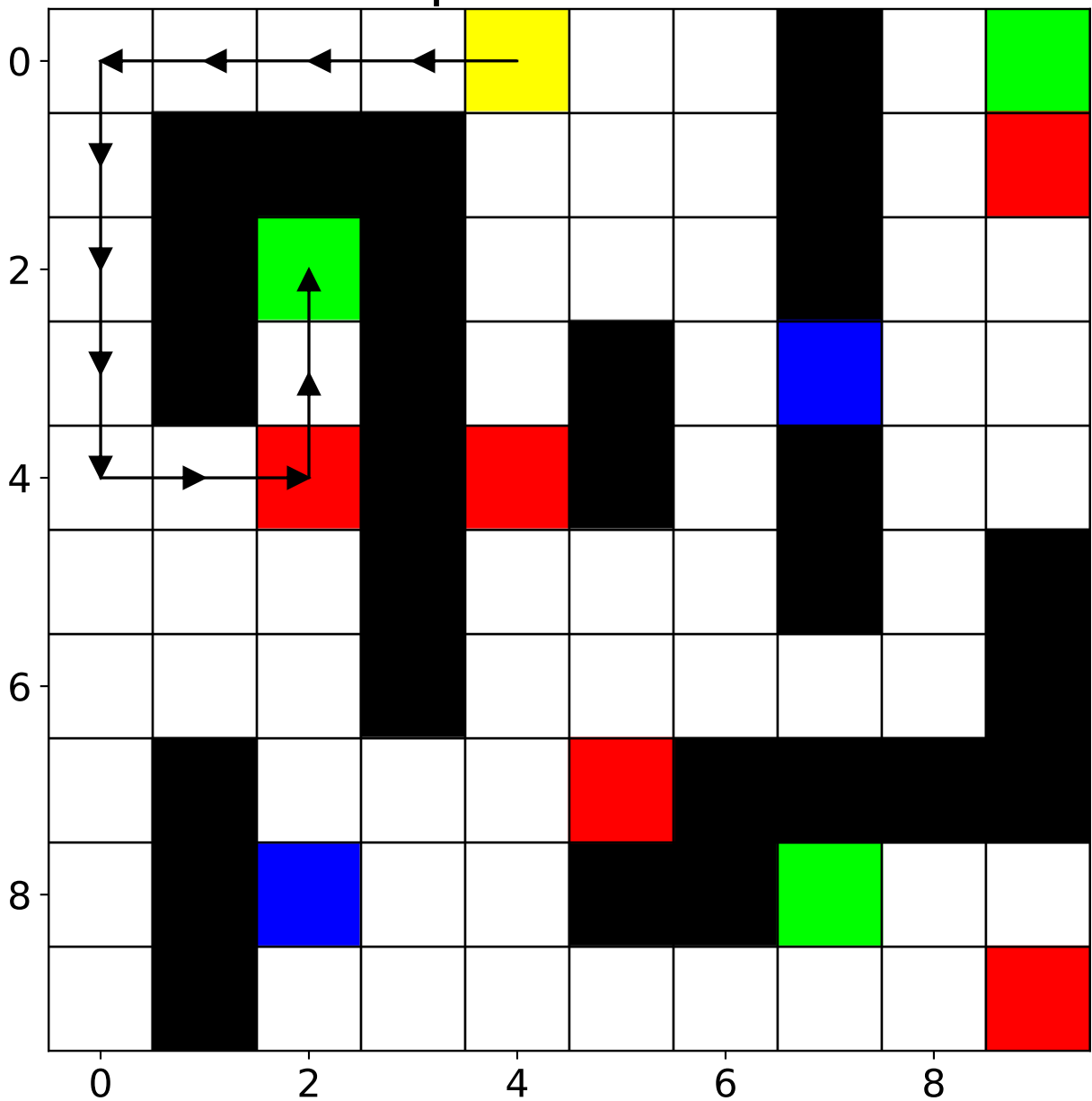


# Optimal Path



- |              |           |              |               |               |             |
|--------------|-----------|--------------|---------------|---------------|-------------|
| Black square | Obstruted | Blue square  | Restart State | Yellow square | Start State |
| Red square   | Bad State | Green square | Goal State    |               |             |