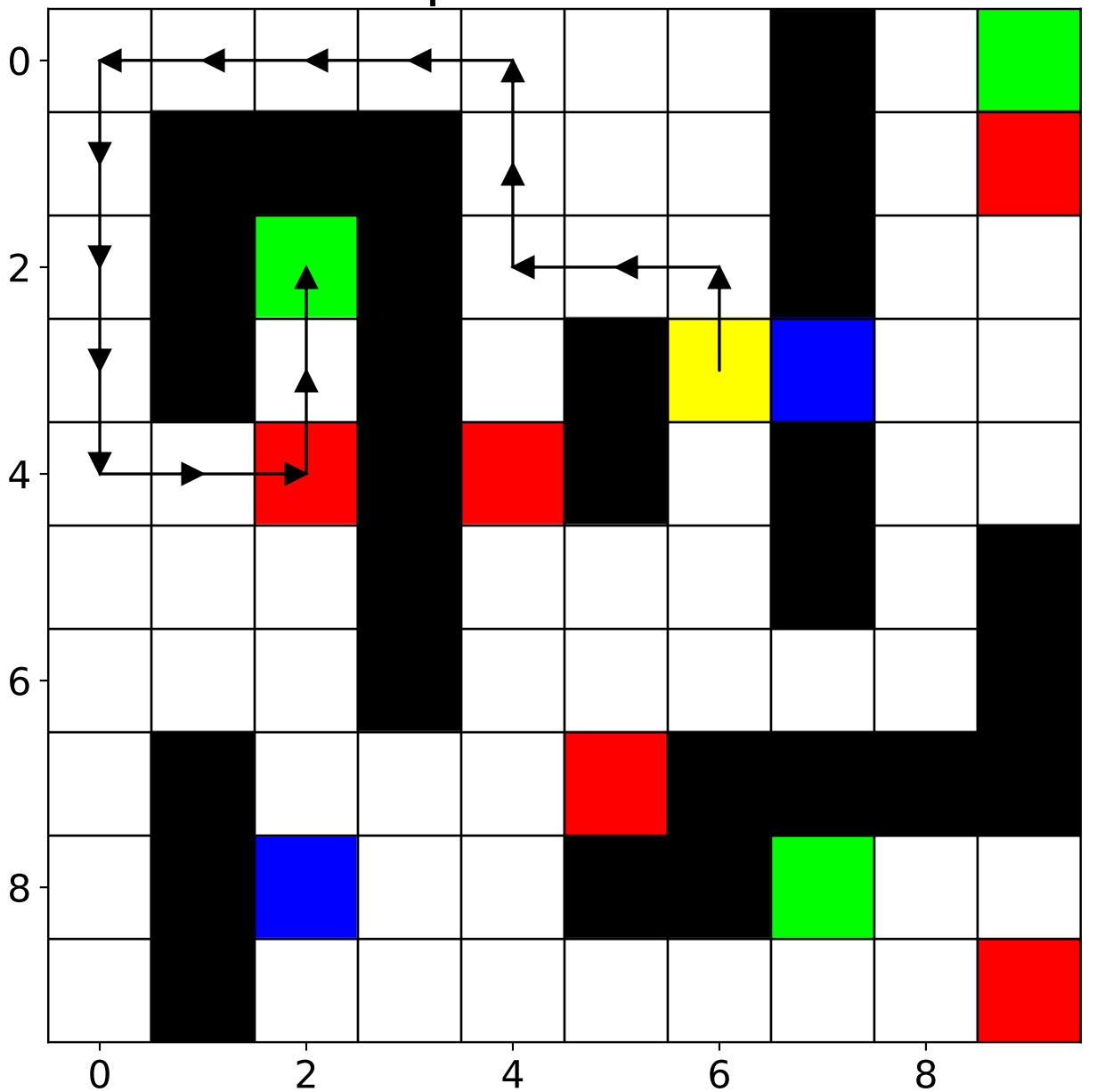


Optimal Path



Obstructed
 Restart State
 Start State

Bad State
 Goal State