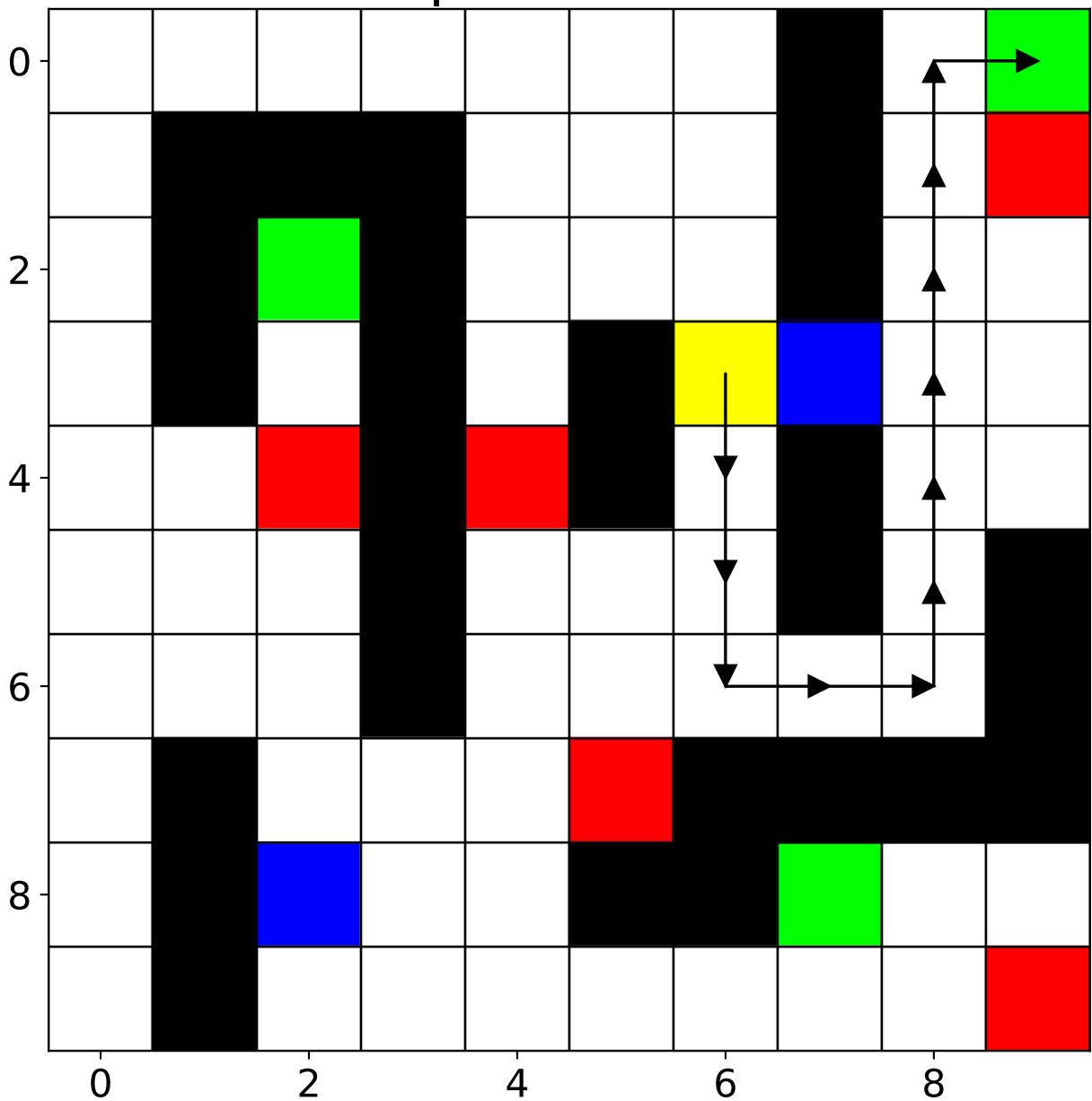


Optimal Path



- | | | |
|------------|---------------|-------------|
| Obstructed | Restart State | Start State |
| Bad State | Goal State | |