



Computer Vision

Lec 4 - RANSAC

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Robust Fitting using RANSAC

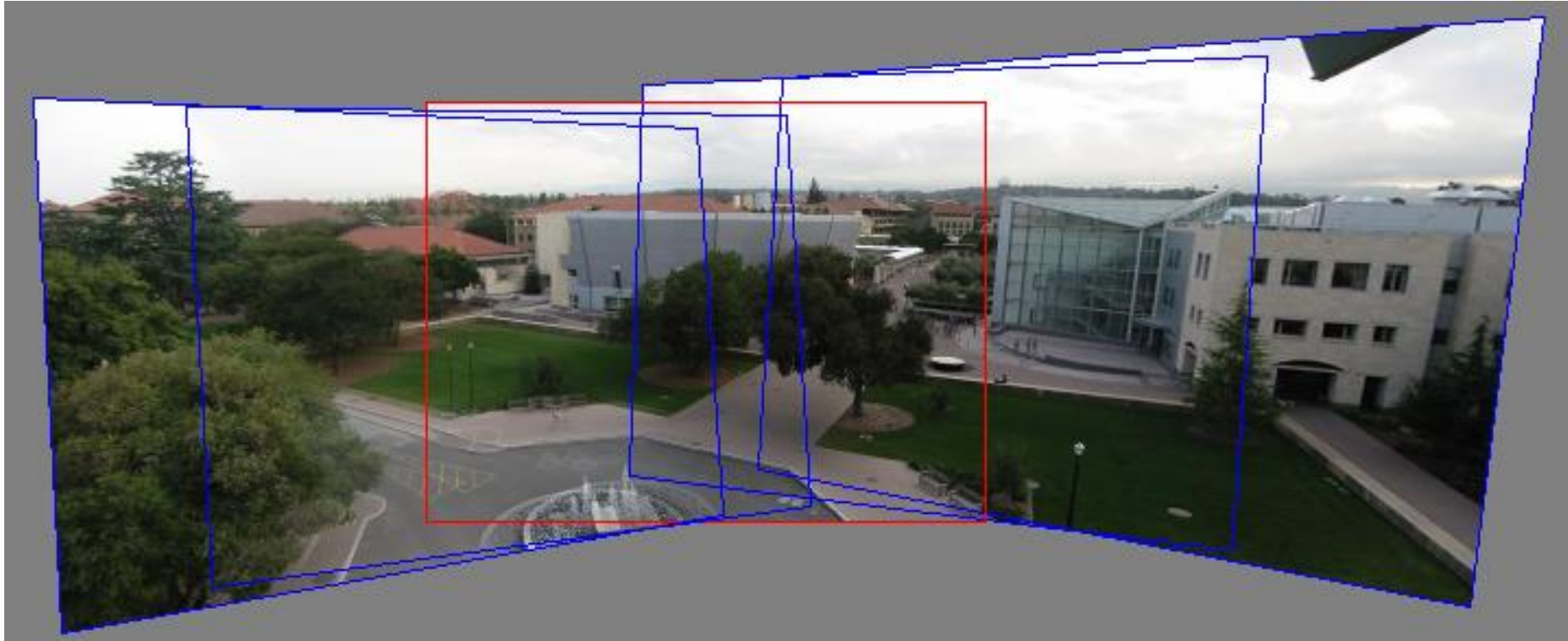
slide credit

- Svetlana Lazebnik, Sanja Fidler, Kristen Grauman, Ioannis Gkioulekas, Kris Kitani, James Hays, Fredo Durand, Rick Szeliski, Andrew Zisserman, Kyros Kutulakos

Overview

- Interest point detection
 - Harris, LoG, Scale space
- Invariant descriptors
 - SIFT
- Basic (nearest neighbor based) matching
 - ratio test, bidirectional criteria
- Fitting of 2D transformations (models)
 - affine, homography
- Today: RANSAC for *robust* fitting

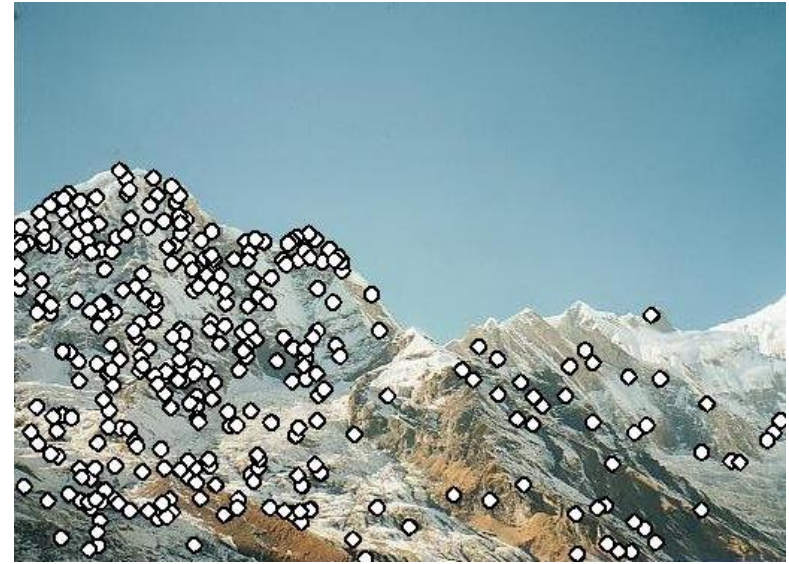
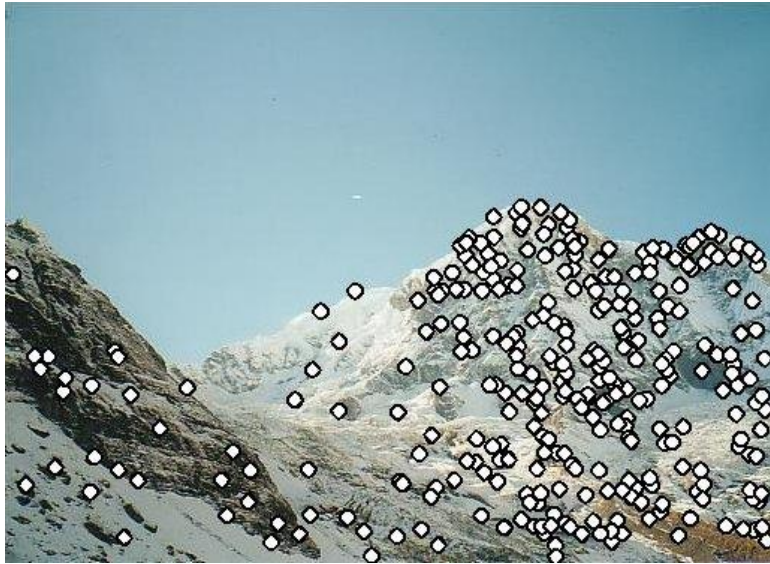
Motivation: mosaics



Robust feature-based alignment

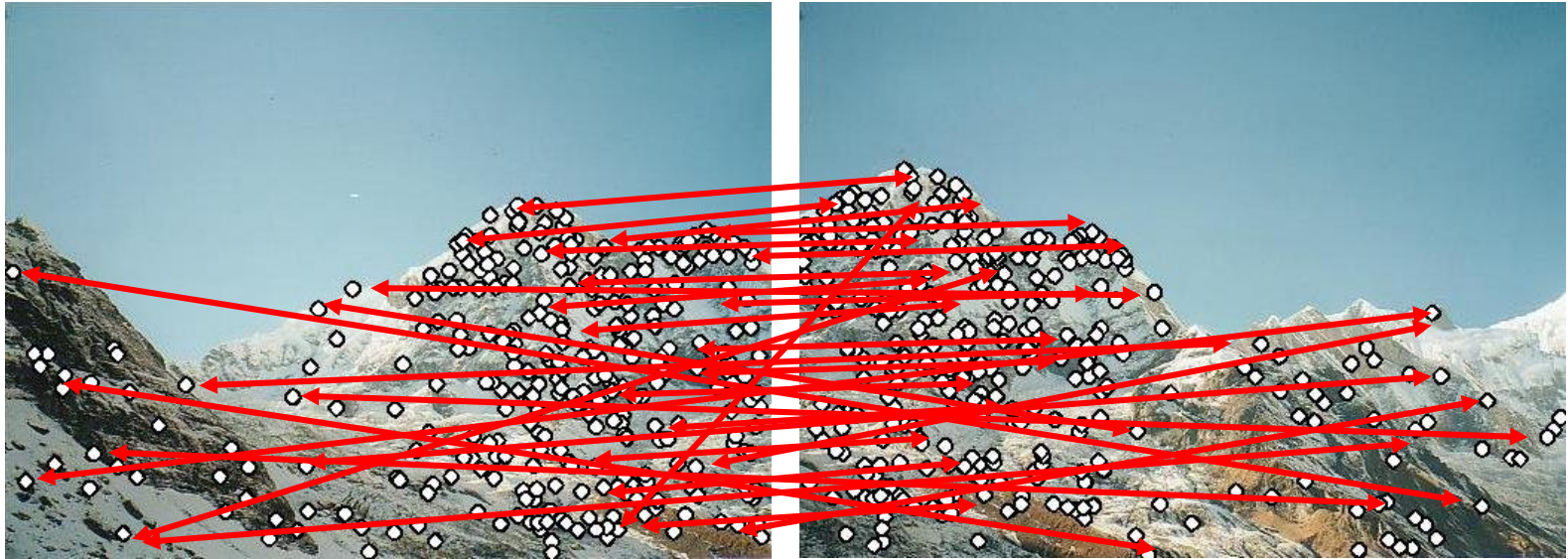


Robust feature-based alignment



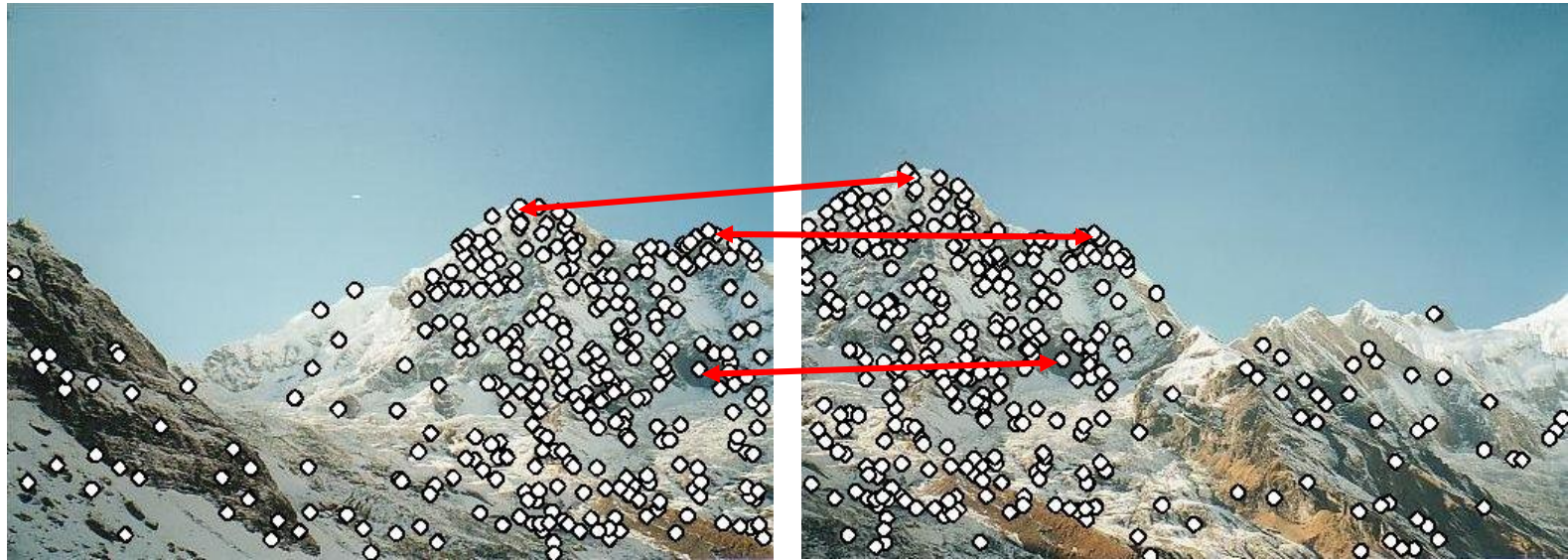
- Extract features

Robust feature-based alignment



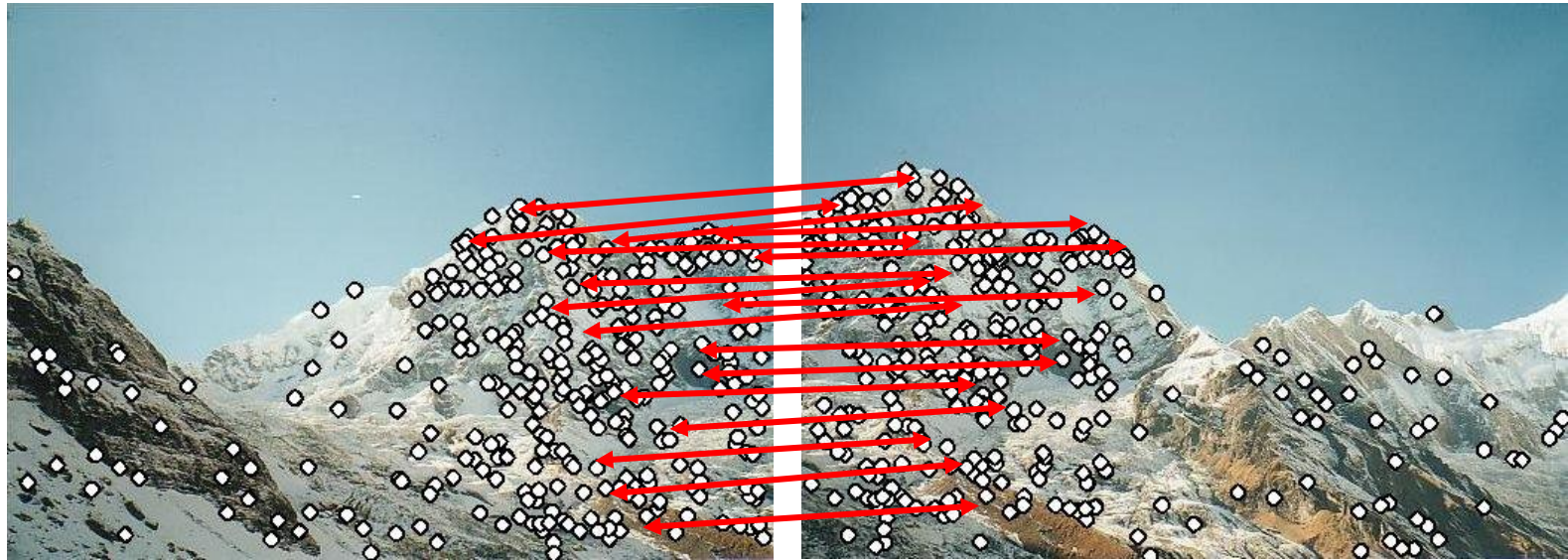
- Extract features
- Compute *putative matches*

Robust feature-based alignment



- Extract features
- Compute *putative matches*
- Loop:
 - *Hypothesize* transformation T (small group of putative matches that are related by T)

Robust feature-based alignment



- Extract features
- Compute *putative matches*
- Loop:
 - *Hypothesize* transformation T (small group of putative matches that are related by T)
 - *Verify* transformation (search for other matches consistent with T)

Robust feature-based alignment

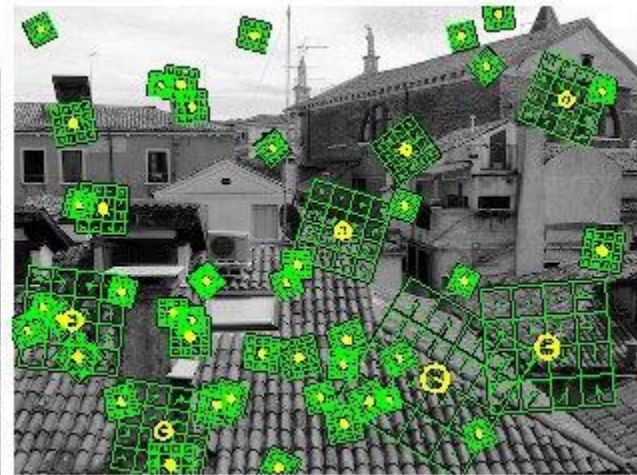


- Extract features
- Compute *putative matches*
- Loop:
 - *Hypothesize* transformation T (small group of putative matches that are related by T)
 - *Verify* transformation (search for other matches consistent with T)

Recall: Scale Invariant Feature Transform (SIFT) descriptor [Lowe 2004]

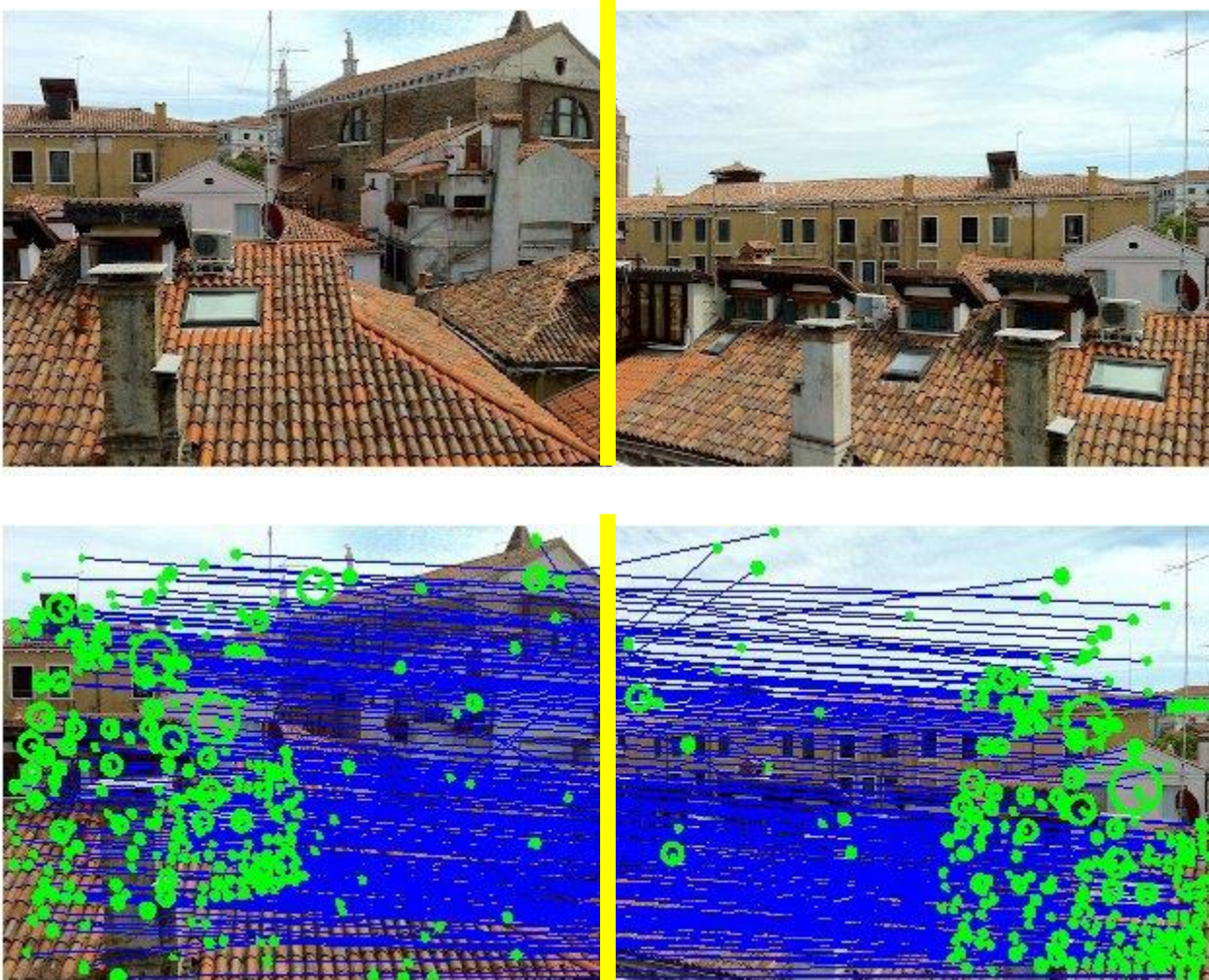


Interest points and
their scales and
orientations
(random subset of 50)



SIFT descriptors

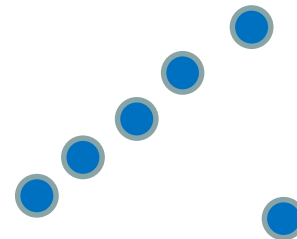
Recall: SIFT (preliminary) matches



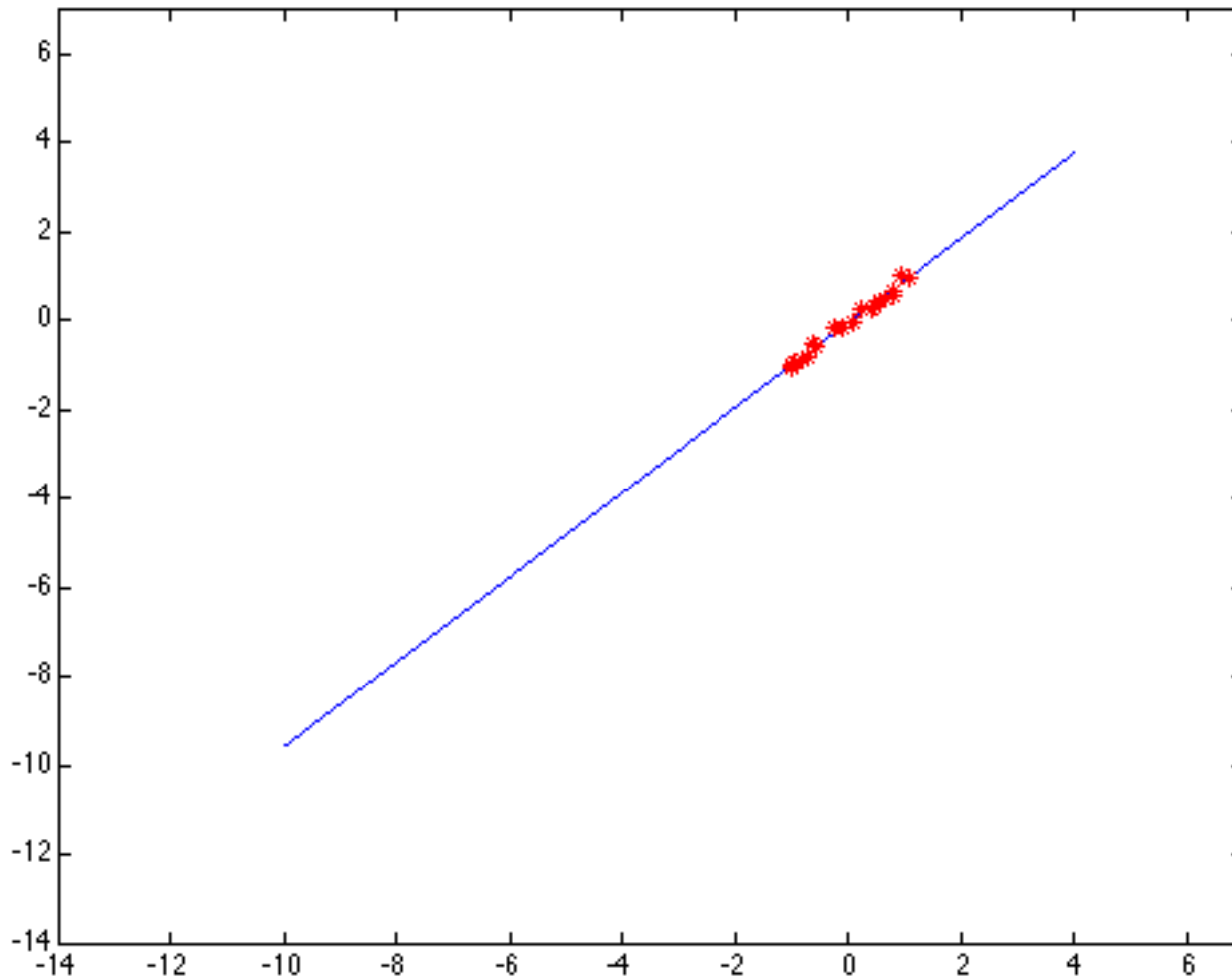
Not all of these
are valid
matches!

Outliers

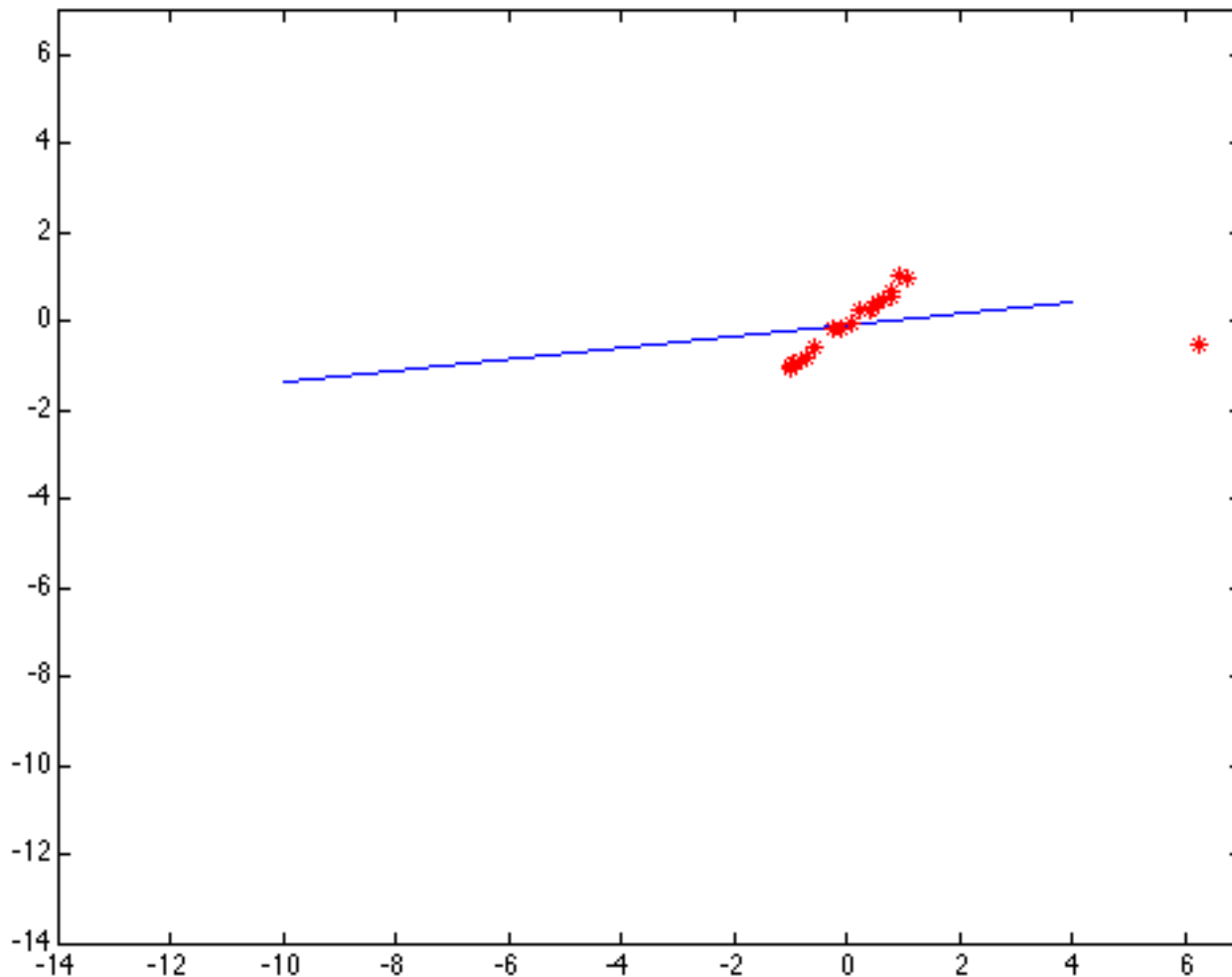
- **Outliers** can hurt the quality of our parameter estimates, e.g.,
 - an erroneous pair of **matching points** from two images
 - an **edge point** that is noise, or doesn't belong to the line we are fitting.



Outliers affect least squares fit



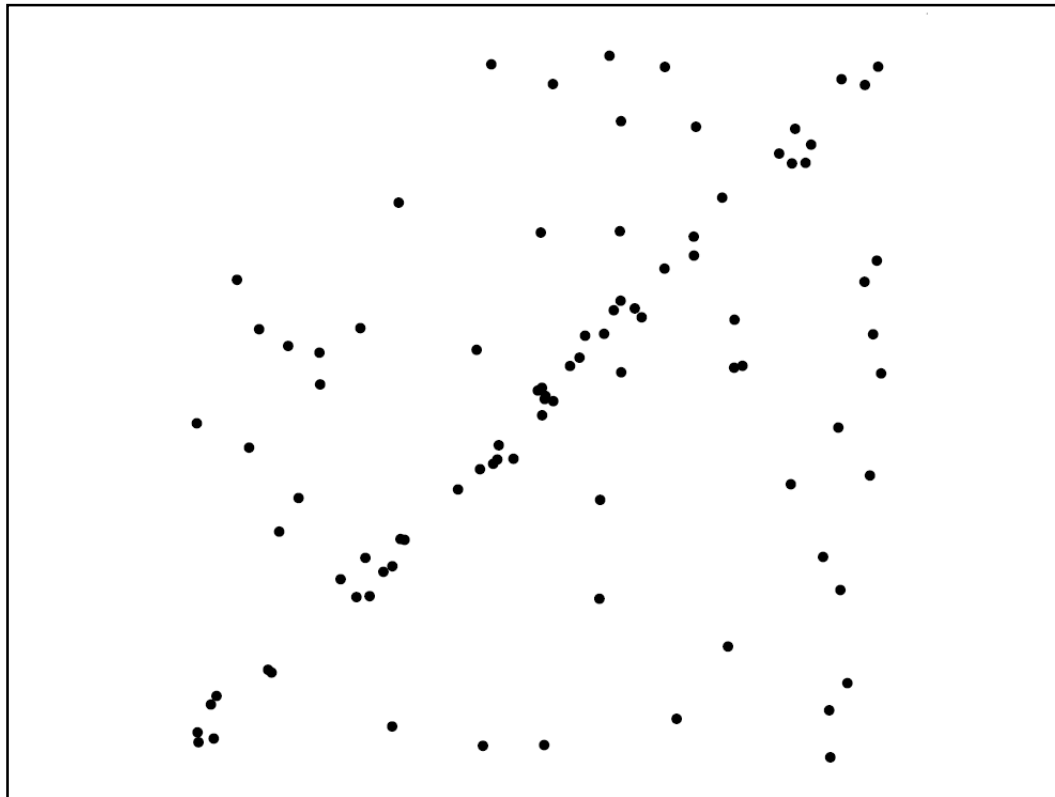
Outliers affect least squares fit



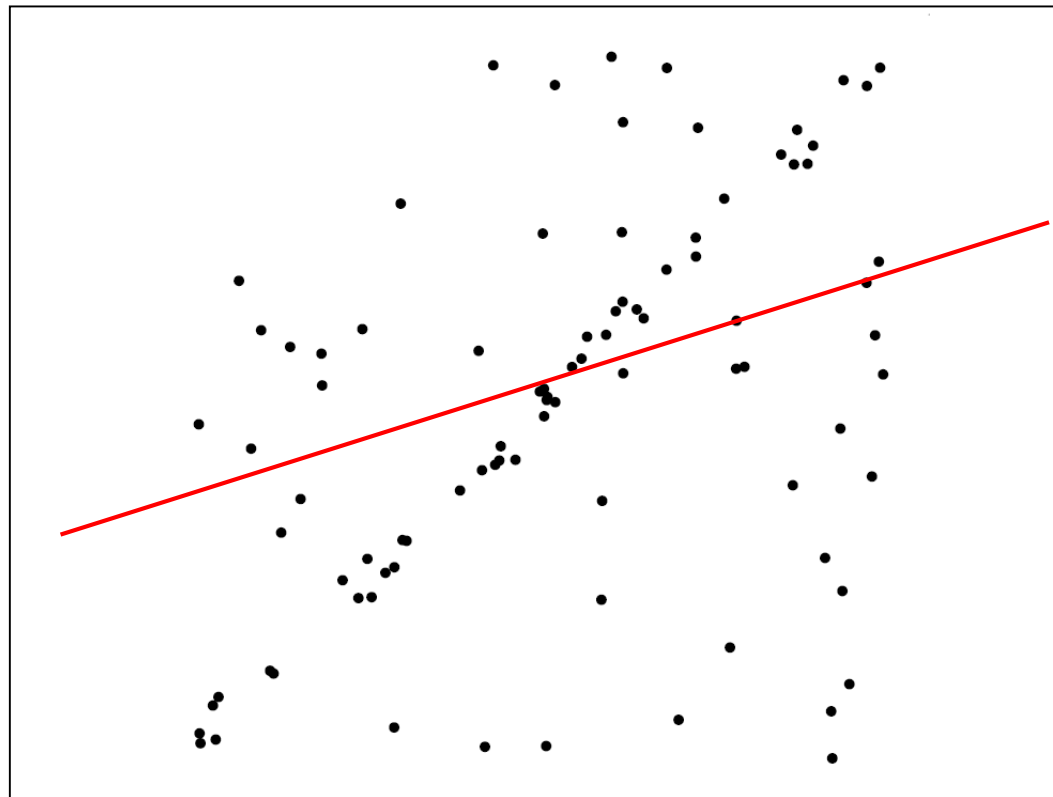
RANSAC

- RANdom SAmple Consensus (Fischler, Bolles 1981)
- **Approach:** we want to avoid the impact of outliers, so let's look for “inliers”, and use those only.
- **Intuition:** if an outlier is chosen to compute the current fit, then the resulting **line** (**transformation**) won't have much support from rest of the **points** (**matches**).

RANSAC for line fitting example

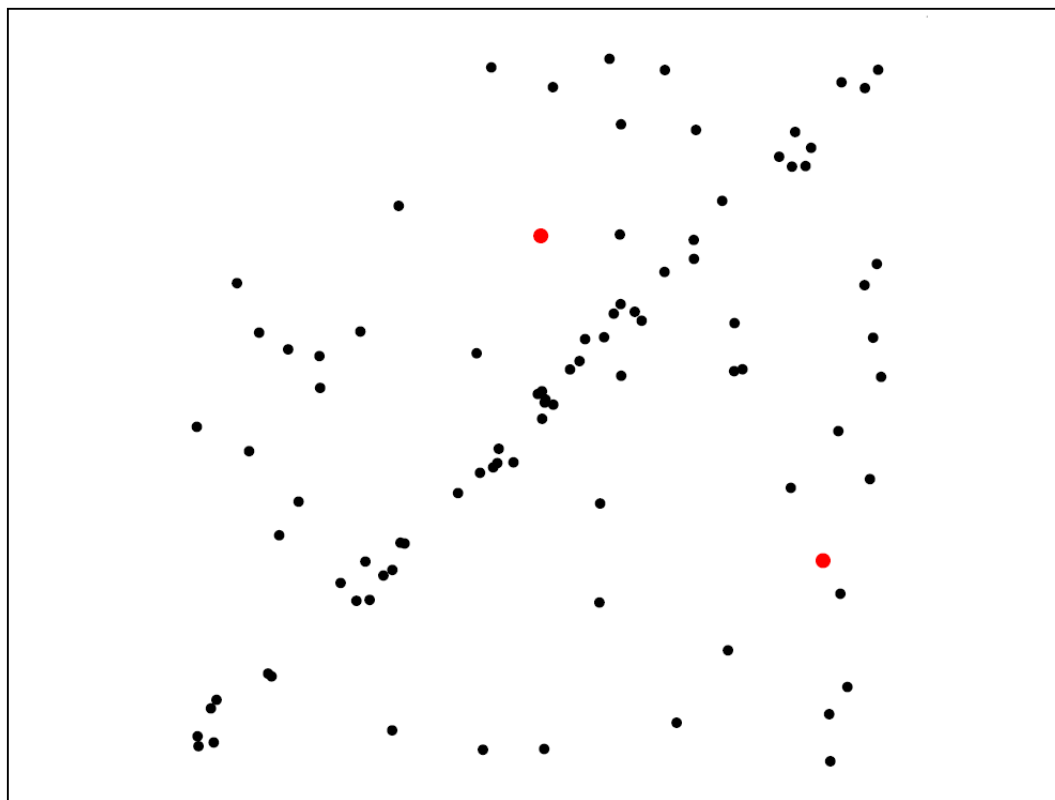


RANSAC for line fitting example



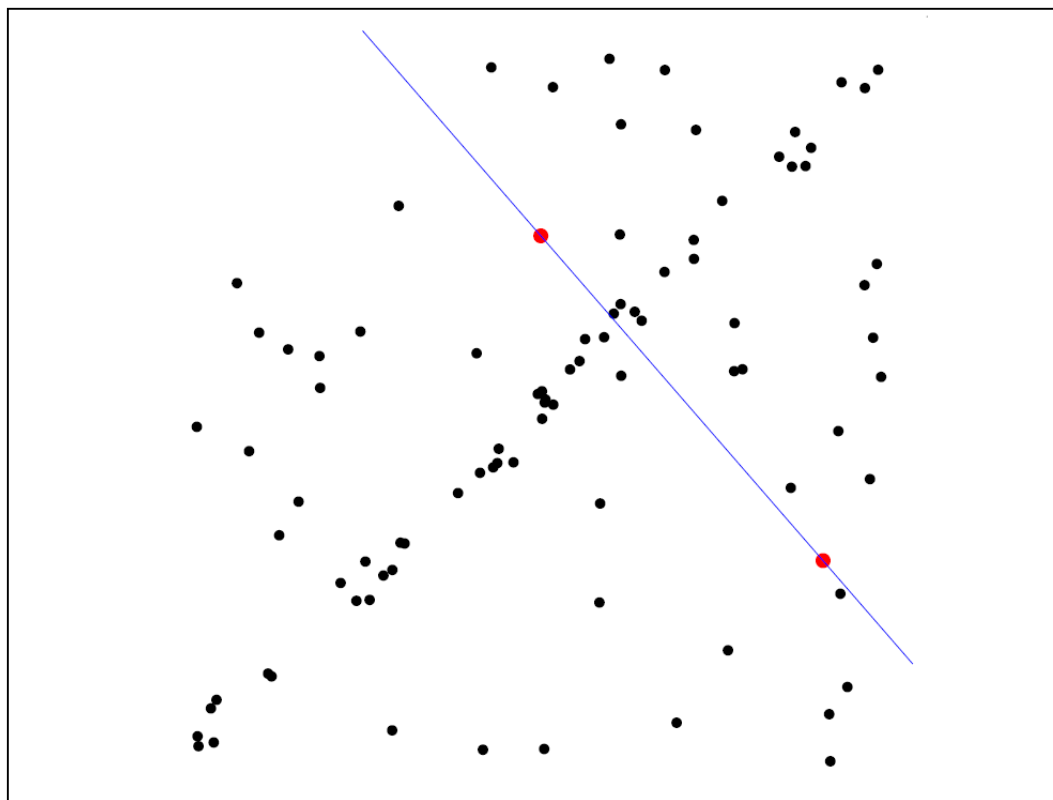
Least-squares fit

RANSAC for line fitting example



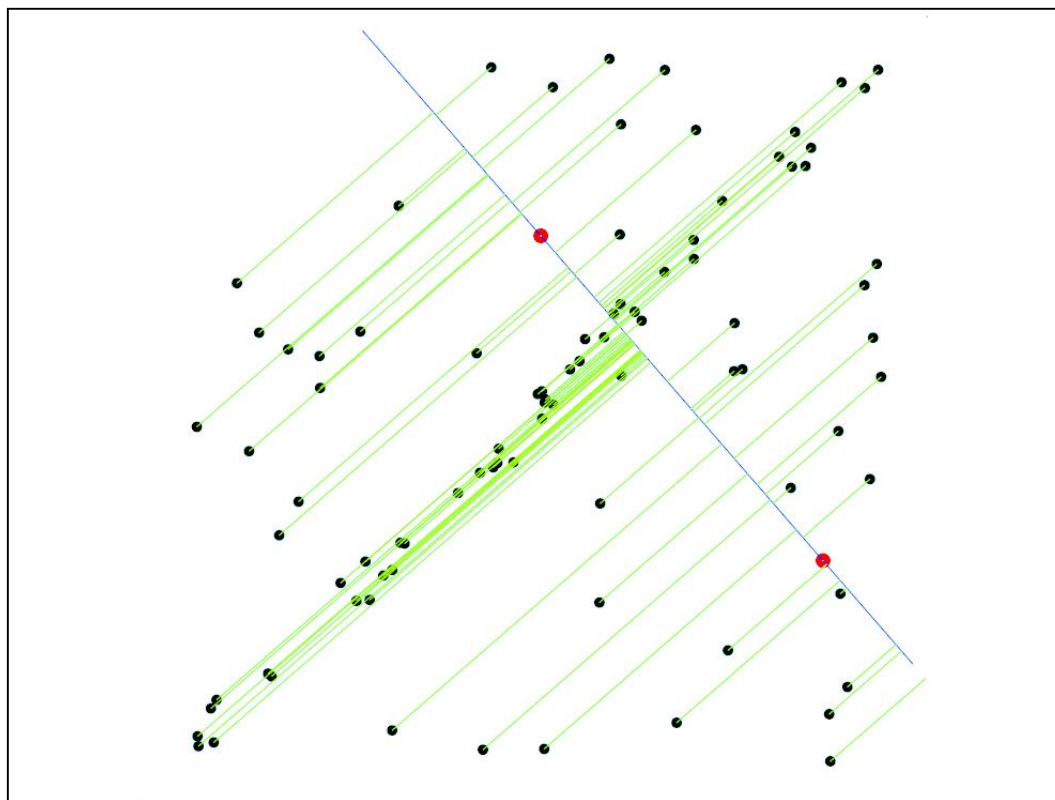
1. Randomly select *minimal* subset of points

RANSAC for line fitting example



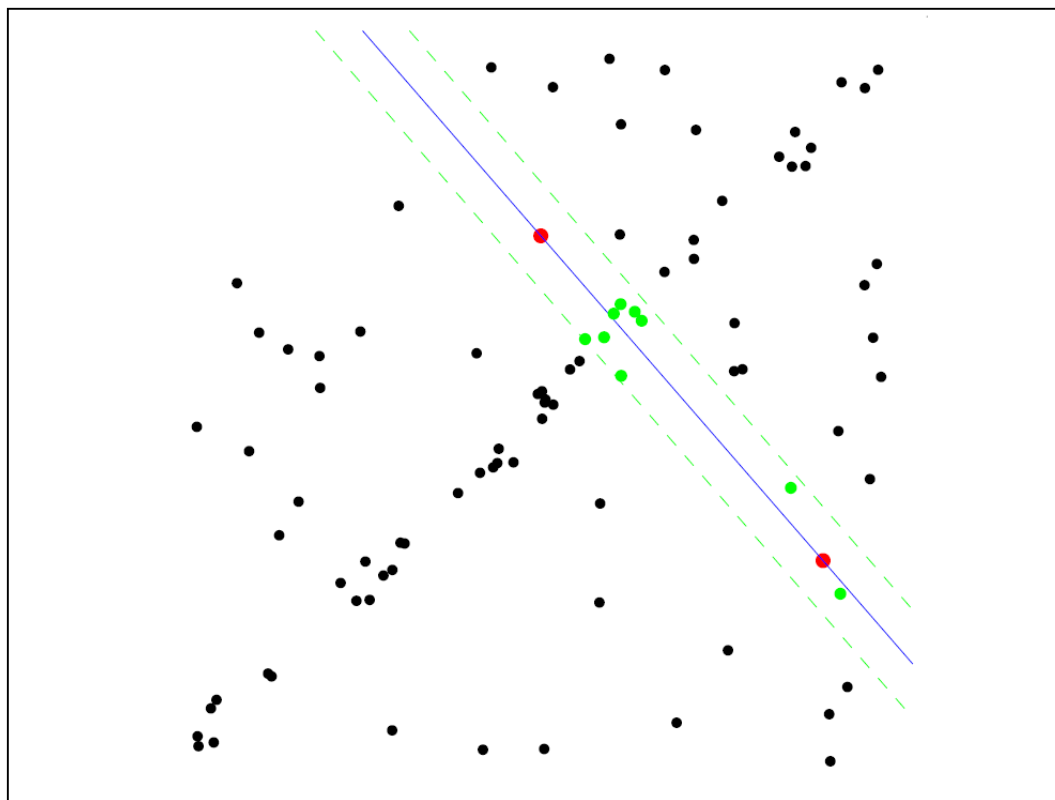
1. Randomly select *minimal* subset of points
2. Hypothesize a *model*

RANSAC for line fitting example



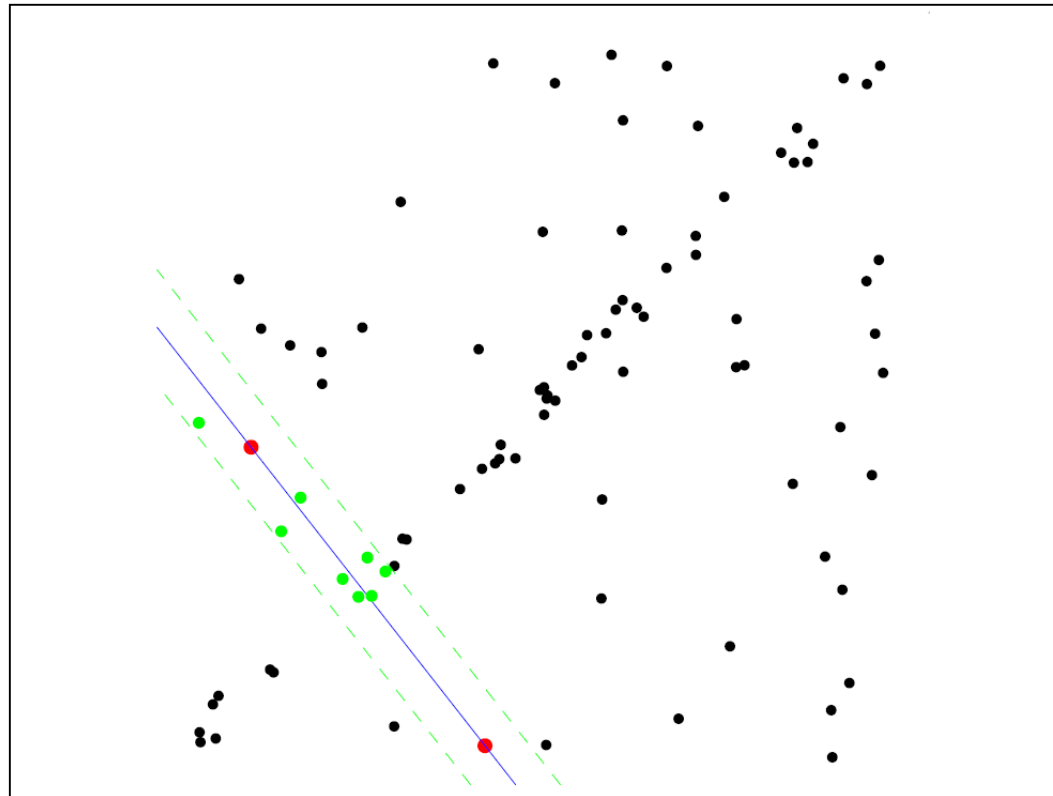
1. Randomly select *minimal* subset of points
2. Hypothesize a *model*
3. Compute *error* function

RANSAC for line fitting example



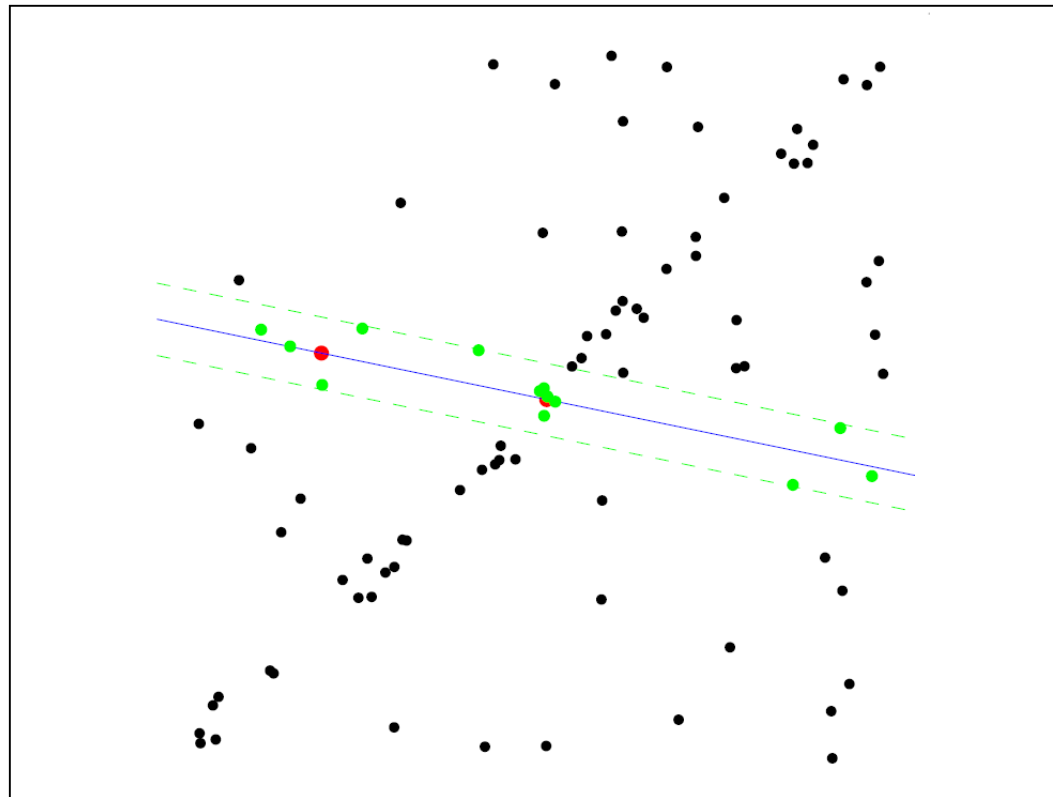
1. Randomly select *minimal* subset of points
2. Hypothesize a *model*
3. Compute *error* function
4. Select points consistent with model

RANSAC for line fitting example



1. Randomly select *minimal* subset of points
2. Hypothesize a *model*
3. Compute *error* function
4. Select points consistent with model
5. Repeat *hypothesize-and-verify* loop

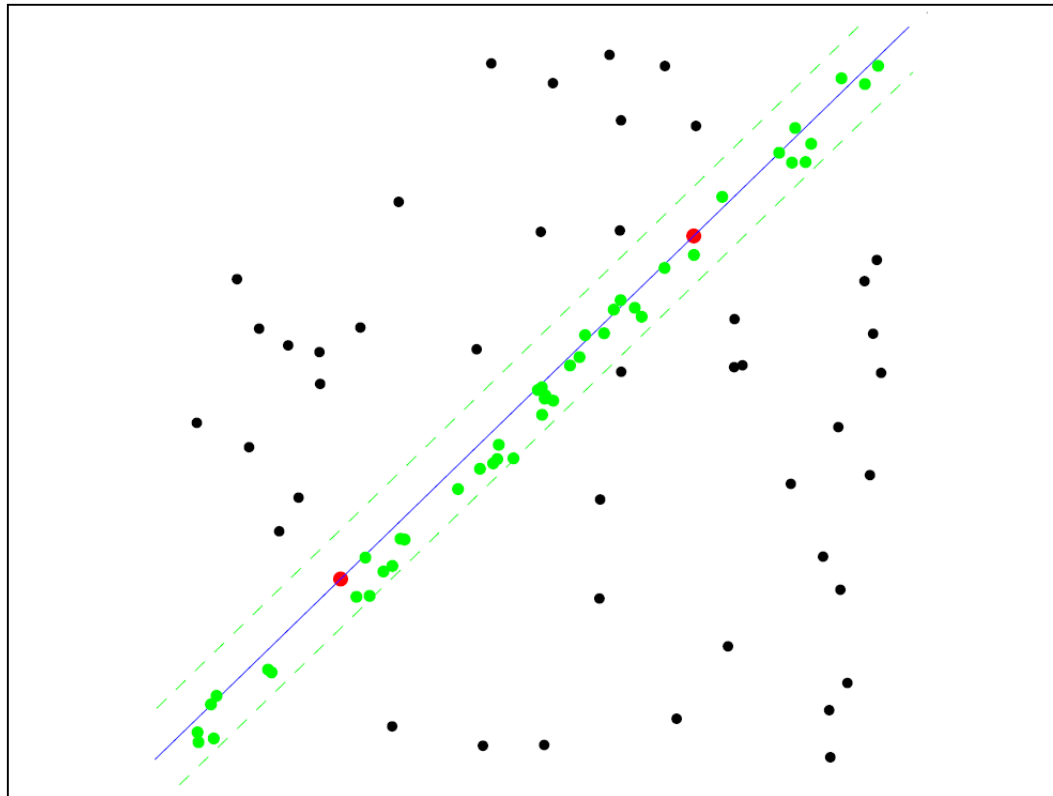
RANSAC for line fitting example



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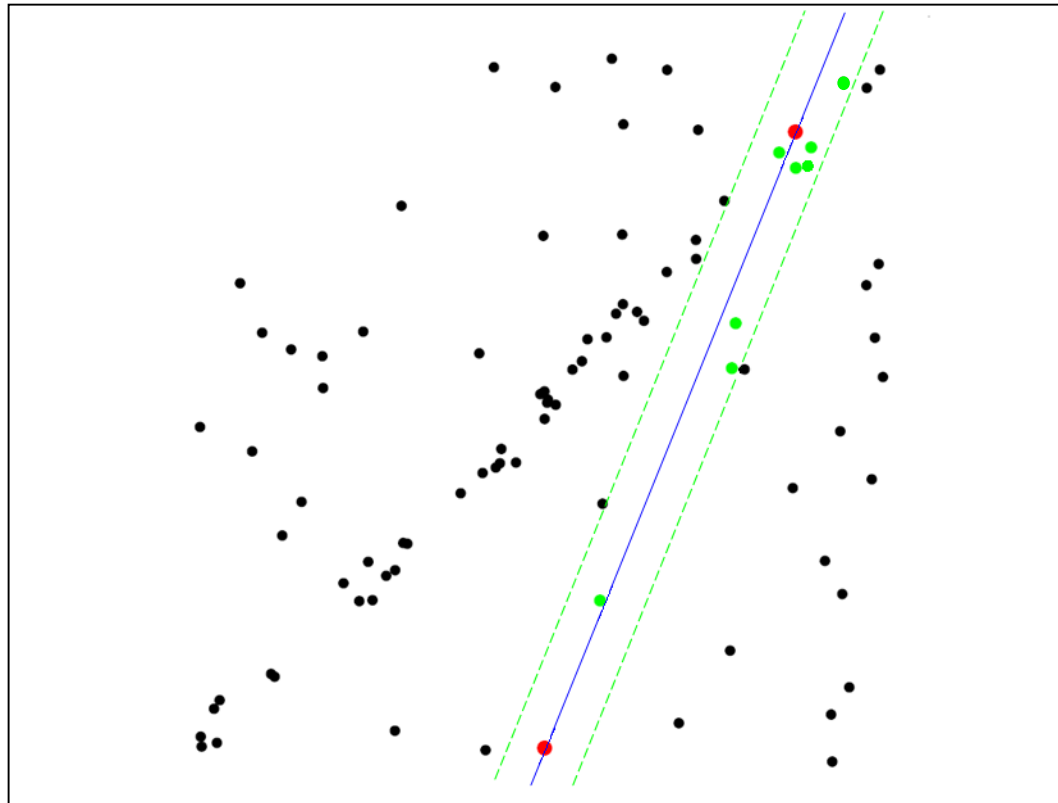
RANSAC for line fitting example

Uncontaminated sample



1. Randomly select *minimal* subset of points
2. Hypothesize a *model*
3. Compute *error* function
4. Select points consistent with model
5. Repeat *hypothesize-and-verify* loop

RANSAC for line fitting example



1. Randomly select *minimal* subset of points
2. Hypothesize a *model*
3. Compute *error* function
4. Select points consistent with model
5. Repeat *hypothesize-and-verify* loop

RANSAC for line fitting

Repeat (trials):

- Draw k points uniformly at random
- Fit line to these k points
- Find inliers to this line among the remaining points (i.e., points whose distance from the line is less than t)
- Stopping criterion - accept the line:
 - option 1: if there are d or more inliers
 - option 2: after n trials

Refit line using all inliers

How many trials for RANSAC?

To ensure good chance of finding true inliers, need sufficient number of trials, **S**.

- Let **P** be the total prob. of success after **S** trials.
- Let **p** be prob. that a given match is valid (*inlier rate*)
- Prob. that all **k** random samples in one trial are inliers: p^k
- Prob. that all **S** trials will fail:

$$1 - P = (1 - p^k)^S$$

- Required minimum number of trials:

$$S = \log(1 - P) / \log(1 - p^k)$$

for **P** = 0.99:

k	p	S
3	0.5	35
6	0.6	97
6	0.5	293
7	0.2	359776
7	0.1	46051700

RANSAC for line fitting

Repeat (trials):

- Draw k points uniformly at random
- Fit line to these k points
- Find inliers to this line among the remaining points (i.e., points whose distance from the line is less than t)
- Stopping criterion - accept the line:
 - option 1: if there are d or more inliers
 - option 2: after n trials
 - option 3 (dynamic): after $\sim \log(1-P) / \log(1-p^k)$ trials
 - » where p is the best found inlier rate

Refit using all inliers

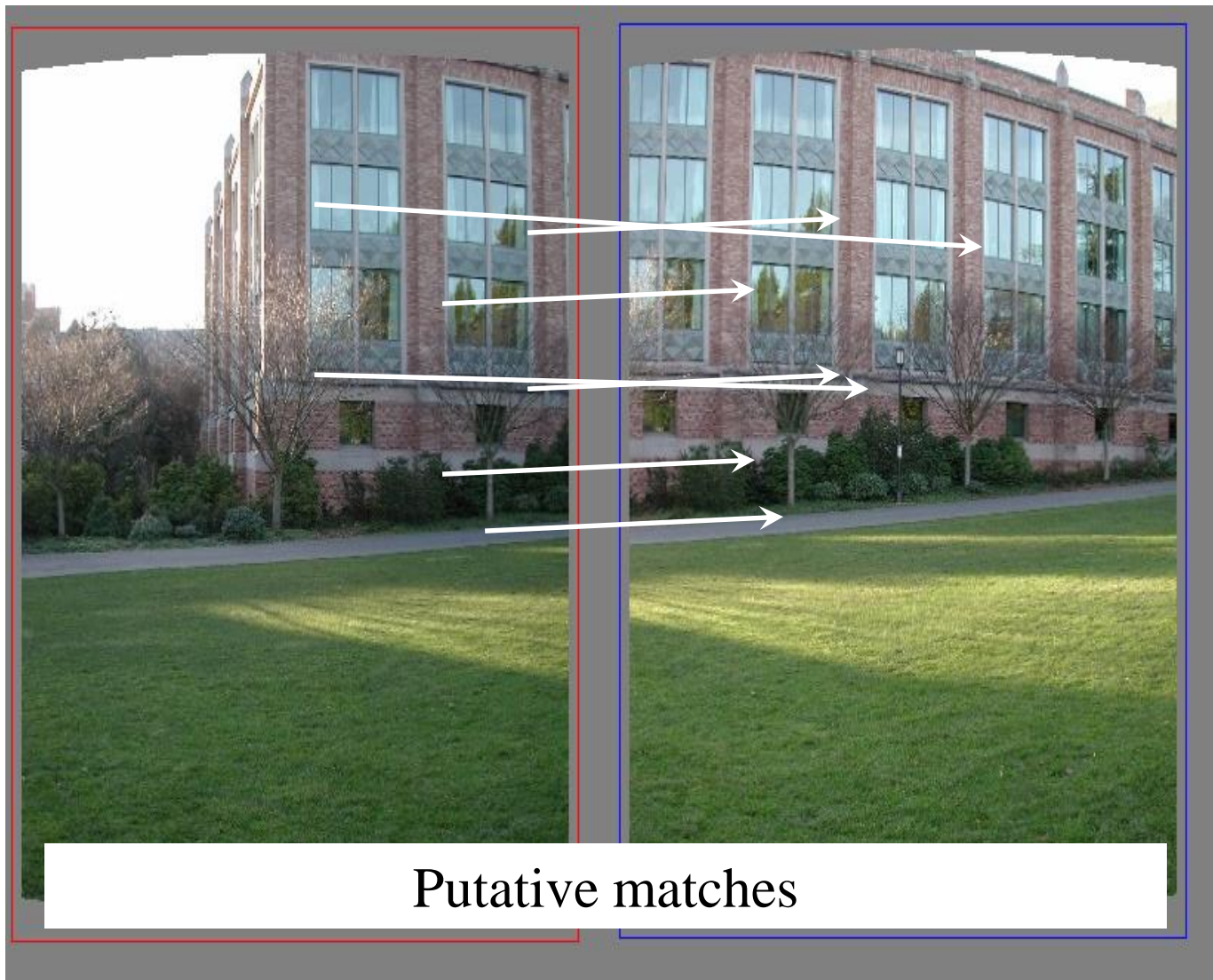
That is an example fitting a *model*
(line)...

What about fitting a *transformation*
(translation)?

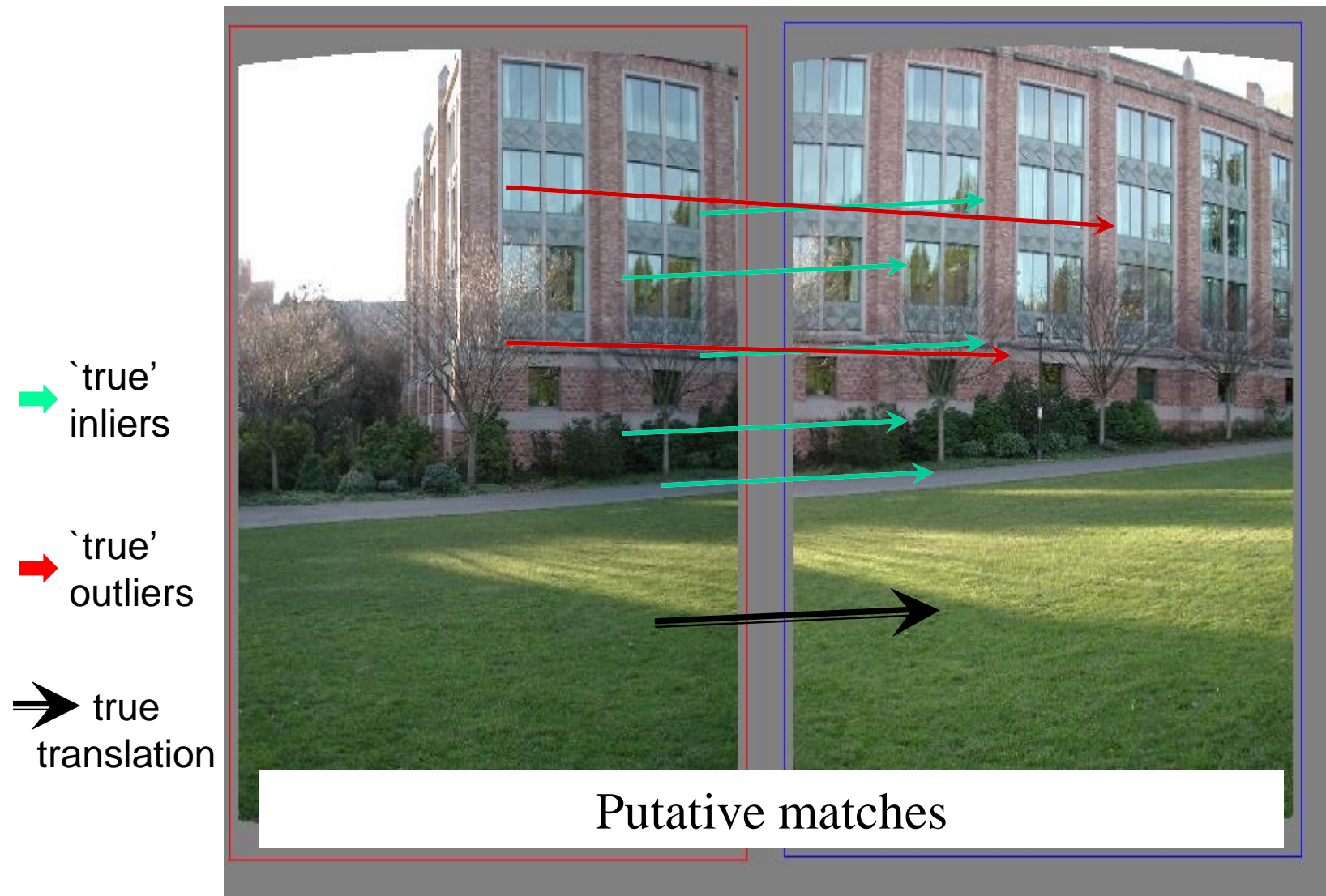
RANSAC: General form

- RANSAC loop:
 1. Randomly select a *seed group* on which to base transformation estimate (e.g., a group of matches)
 2. Compute transformation from seed group
 3. Find *inliers* to this transformation
 4. If the number of inliers is sufficiently large, re-compute estimate of transformation on all of the inliers
- Keep (and refine) the transformation with the largest number of inliers

RANSAC example: Translation

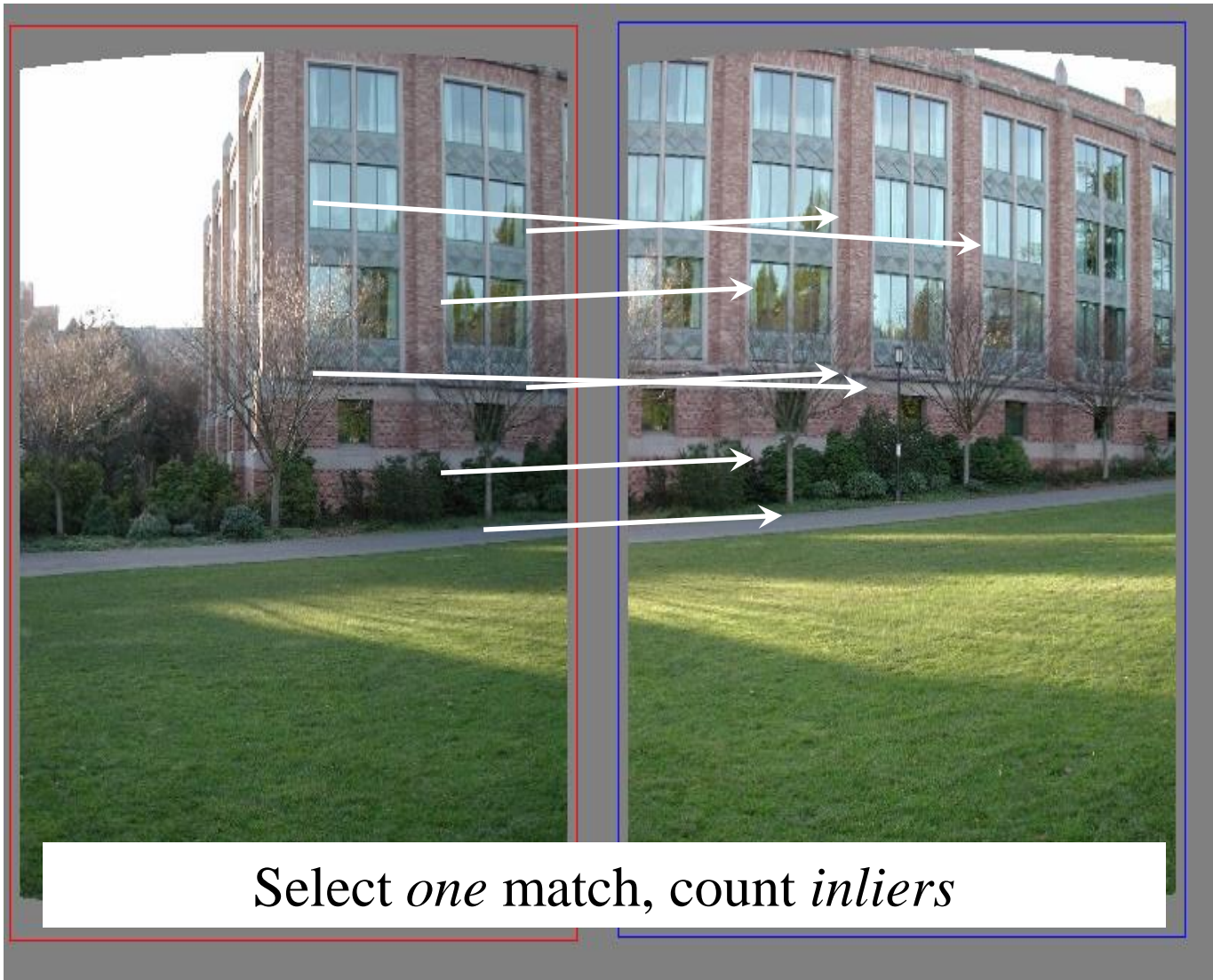


RANSAC example: Translation

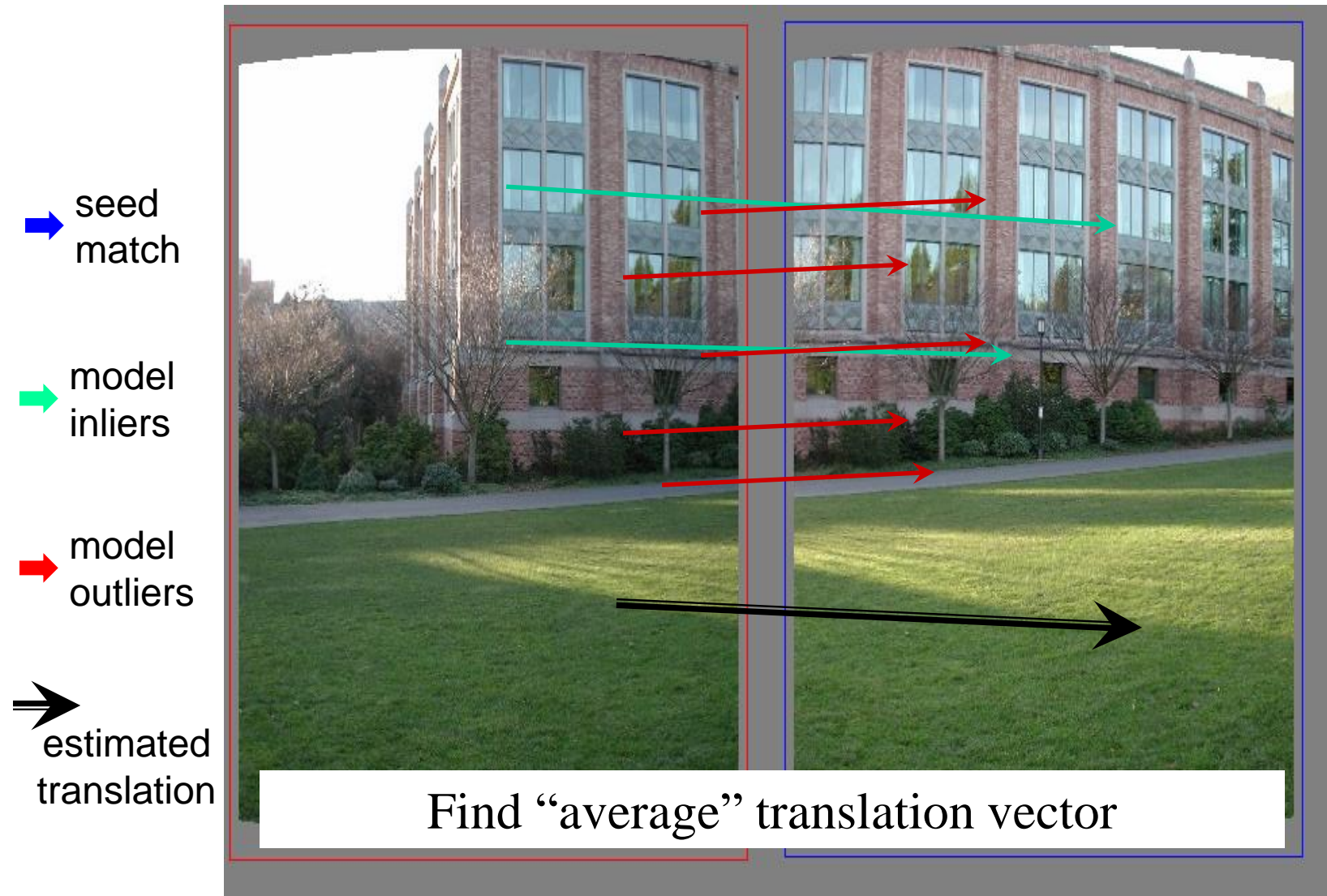


RANSAC example: Translation

- ➡ seed match
- ➡ model inliers
- ➡ model outliers

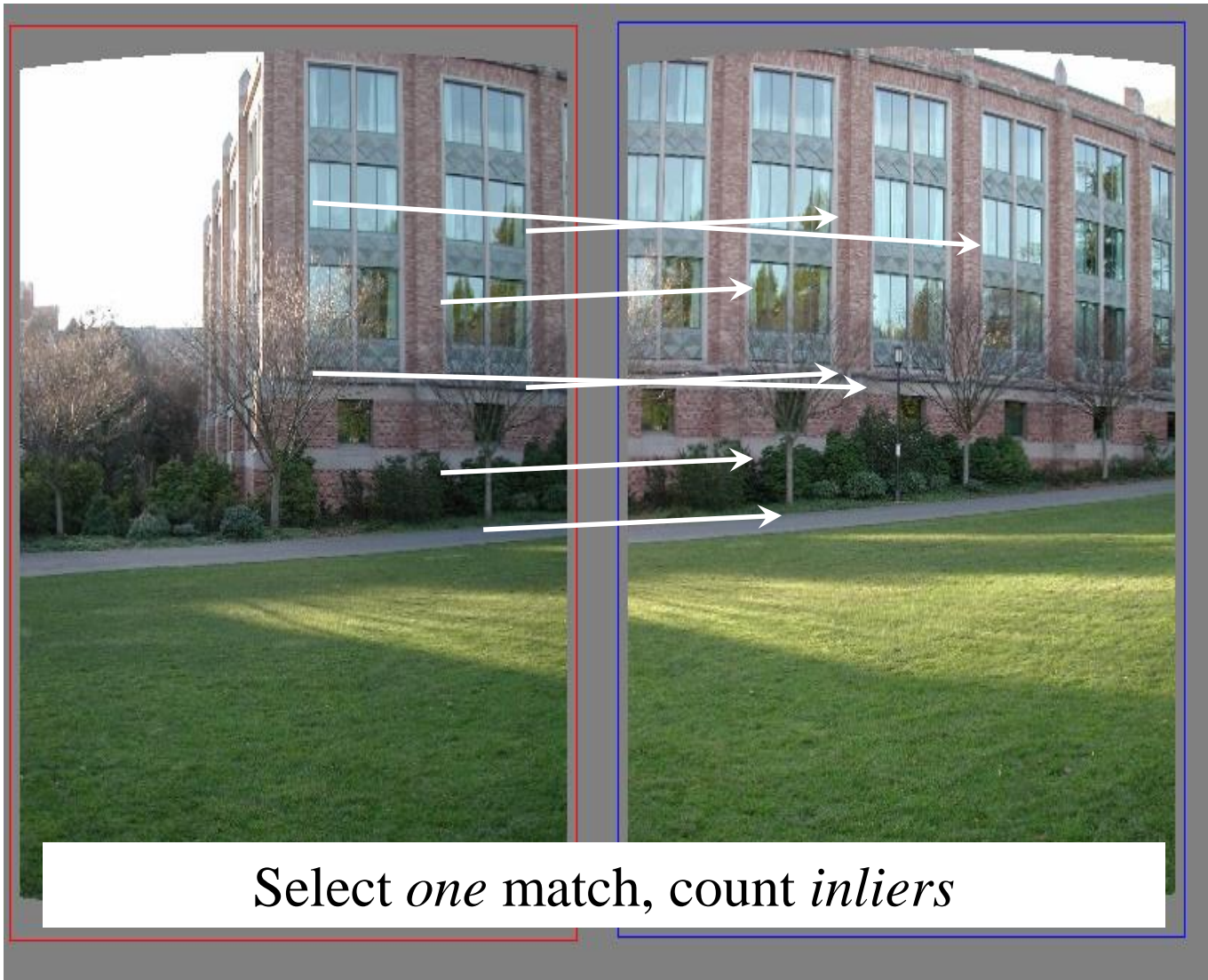


RANSAC example: Translation

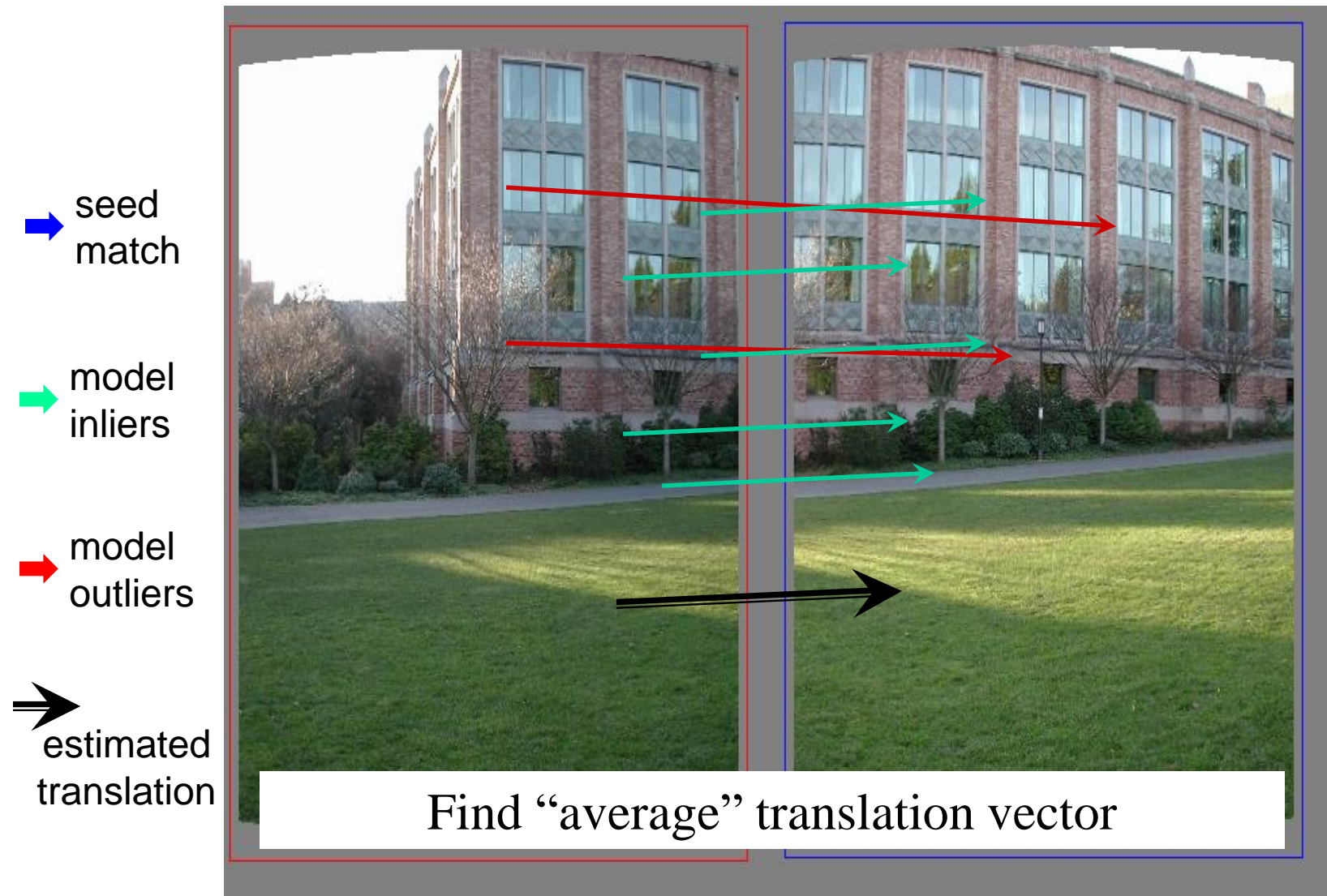


RANSAC example: Translation

- ➡ seed match
- ➡ model inliers
- ➡ model outliers

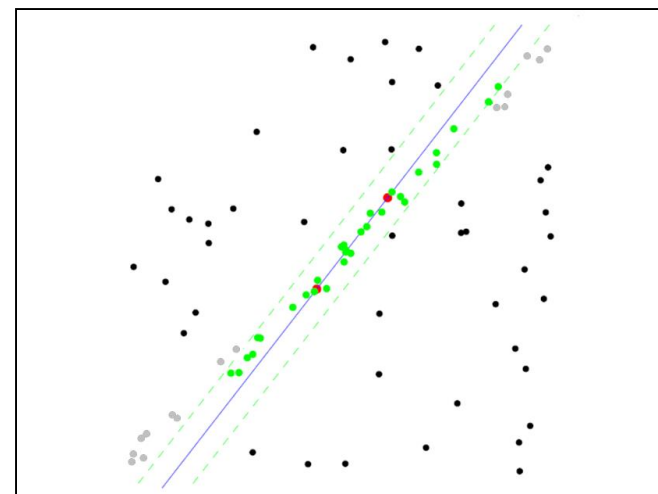


RANSAC example: Translation



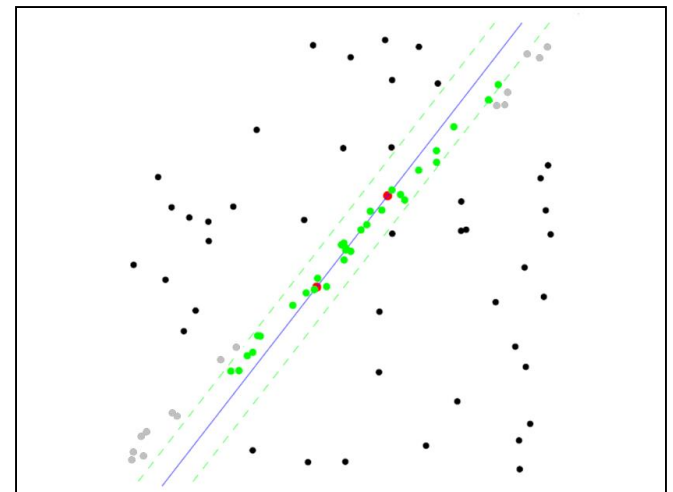
RANSAC pros and cons

- Pros
 - Simple and general
 - Applicable to many different problems
 - Often works well in practice
- Cons
 - Parameters to tune
 - Doesn't work well for low inlier ratios (too many iterations, or can fail completely)
 - Can't always get a good initialization of the model based on the minimum number of samples



RANSAC popular extensions

- Pro-SAC (speed)
 - Rank matches by their quality and sample with non-uniform distribution.
- LO-SAC (precision)
 - Perform local optimization on inliers of each promising model
- MLE-SAC (robustness)
 - Maximize the likelihood rather than the number of inliers
- many others...



Recap

- Feature-based alignment
 - 2D transformations
 - model fitting
 - RANSAC