

# Moonshot

## Goal

Demonstrate my skills by completing the mission

- Critical thinking
- Plan and design
- execution

## Mission

Electromagnetic gun simulation as described in the task doc

## Execution principles

- Everything always can be better, concentrate on a basic version that works as time is limited.
  - o basic V1 that works.
  - o Map gaps.
  - o Suggest improvements

## Design principles

- OOP
- AI to generate documentation
- AI to acquire the background knowledge
  - o Electromagnetic
  - o Python
  - o MATLAB
- AI wherever it can multiply my productivity.
  - o Code structure
  - o Coding
  - o Code review

## Design

Represent each component and each interaction between two components in the system as a class.

The benefits of this design are:

1. Easy to use, maintain and understand as it's structure is the same as the simulated setup. Important because this simulation serves other non-software engineers.
2. scalable:
  - Adding more objects i.e. connecting wires, power supplier, damping capacitor.
  - Adding objects characteristics i.e. conductance, capacitance.
  - Adding more interactions i.e. between the acceleration stages
  - Adding more types of interactions i.e. mechanical interactions such as heat, air resistance and such

V1 system components:

- Capsule
- Acceleration stage
- Acceleration tube

V1 parameters:

- Coil current

## Plan

V1

- ☒ Project template in PyCharm
- ☒ Upload to a GitHub repository
- ☒ Implement objects
- ☒ Implement Objects Interactions
- ☒ Run simulation
- ☒ Plots
- ☒ CLI

☒ Sample run configuration

☒ Documentation

## MATLAB

☒ Install

☒ Compile first task

☒ User interface

### **Execution summary:**

Current implementation fulfill all the system requirements.

The execution leveraged Gen AI Agents:

- ROO (VS Code extension) for designing and coding
- Bing MCP for acquiring the agent with physical background and best practices for Python and MATLAB coding, OOP and TTD.
- ChatGPT for self validation.

\*Roo tended to overdo, next time need to strain him better.

Main gaps:

- Physical understanding of the system can and should be deeper.
  - o The force is repulsing.
  - o The capsule doesn't move as expected (that's why `test_simulation_termination_conditions` is failing).
- More code cleaning iterations should be made.
- MATLAB integration can be simplified
- Output plots correctness should be verified i.e. final distance cant be 20mm