# Homework 2 Stat 215A, Fall 2021

Due: push a homework2.pdf file to your stat-215-a GitHub repo by Thursday, October 07 at 11:59pm

### 0 Linear Algebra Review

Recall that the SVD of  $\mathbf{X} \in \mathbb{R}^{n \times p}$  is a matrix decomposition such that  $\mathbf{X} = \mathbf{U} \mathbf{D} \mathbf{V}^{\top}$ , where  $\mathbf{U} = [\mathbf{u}_1, \dots, \mathbf{u}_n] \in \mathbb{R}^{n \times n}$ ,  $\mathbf{V} = [\mathbf{v}_1, \dots, \mathbf{v}_p] \in \mathbb{R}^{p \times p}$ , and  $\mathbf{D} = \operatorname{diag}(d_1, \dots, d_{\min\{n, p\}}) \in \mathbb{R}^{n \times p}$ . In addition,  $\mathbf{U}$  and  $\mathbf{V}$  are orthogonal matrices so that  $\mathbf{U}^{\top} \mathbf{U} = \mathbf{U} \mathbf{U}^{\top} = \mathbf{I}$  and  $\mathbf{V}^{\top} \mathbf{V} = \mathbf{V} \mathbf{V}^{\top} = \mathbf{I}$  (i.e.,  $\mathbf{u}_j^{\top} \mathbf{u}_i = \mathbf{v}_j^{\top} \mathbf{v}_i = 0$  for all  $i \neq j$  and  $\mathbf{u}_i^{\top} \mathbf{u}_j = \mathbf{v}_i^{\top} \mathbf{v}_j = 1$  for all i). Moreover,  $d_1 \geq \dots \geq d_{\min\{n, p\}} \geq 0$ .

Now, while the SVD can be used for any rectangular matrix, square matrices have an additional special property and can be decomposed via an eigendecomposition. Given a square matrix  $\mathbf{A} \in \mathbb{R}^{p \times p}$ , we say that  $\mathbf{v} \in \mathbb{R}^p$  is an eigenvector of  $\mathbf{A}$  if  $\mathbf{v} \neq \mathbf{0}$  and  $\mathbf{A} \mathbf{v} = \lambda \mathbf{v}$  for some  $\lambda \in \mathbb{R}$ . We also call  $\lambda$  the eigenvalue of  $\mathbf{A}$  corresponding to the eigenvector  $\mathbf{v}$ . For a more intuitive (geometric) interpretation of eigenvalues and eigenvectors, see this reference.

There is a close connection between the SVD and eigendecomposition. Namely, for any matrix  $\mathbf{X} \in \mathbb{R}^{n \times p}$ ,  $\mathbf{v} \in \mathbb{R}^p$  is a right singular vector of  $\mathbf{X}$  with singular value d if and only if  $\mathbf{v} \in \mathbb{R}^p$  is an eigenvector of  $\mathbf{X}^{\top} \mathbf{X}$  corresponding to the eigenvalue  $d^2$ . You may use this fact without proof.

### 1 Principal Components Analysis and SVD

Let **X** be an  $n \times p$  data matrix, where n is the number of observations and p is the number of features. For simplicity, we will assume that **X** has been mean-centered (i.e., each column of X has mean 0) and that  $n \le p$ . In the lab section, we used projections in order to introduce the population version of PCA as solving for each  $j = 1, \ldots, p$ 

$$\mathbf{v}_{j}^{*} = \underset{\mathbf{v} \in \mathbb{R}^{p}}{\operatorname{argmax}} \ \mathbf{v}^{\top} \operatorname{Var}(\mathbf{X}) \mathbf{v} \qquad \text{subject to} \quad \|\mathbf{v}\|_{2}^{2} = 1, \ \mathbf{v}^{\top} \mathbf{v}_{i}^{*} = 0 \ \forall i < j.$$
 (1.1)

However, since  $\operatorname{Var}(\mathbf{X})$  is almost always unknown in practice, we typically estimate  $\operatorname{Var}(\mathbf{X})$  with the sample covariance  $\frac{1}{n}\mathbf{X}^{\top}\mathbf{X}$ . Thus, in practice, the principal component (PC) directions,  $\hat{\mathbf{v}}_1, \dots, \hat{\mathbf{v}}_p$ , are the solution to the following system of optimization problems:

$$\hat{\mathbf{v}}_j = \underset{\mathbf{v} \in \mathbb{R}^p}{\operatorname{argmax}} \ \mathbf{v}^\top \mathbf{X}^\top \mathbf{X} \mathbf{v} \qquad \text{subject to} \quad \|\mathbf{v}\|_2^2 = 1, \ \mathbf{v}^\top \hat{\mathbf{v}}_i = 0 \ \forall i < j.$$
 (1.2)

In this problem, we will take small steps through the proof to show that the PC directions are precisely the right singular vectors of  $\mathbf{X}$ .

1. To begin, prove that the first PC direction  $\hat{\mathbf{v}}_1$  is equal to the first right singular vector  $\mathbf{v}_1$ . To show this, use Lagrange multipliers to solve the PC1 optimization problem:

$$\hat{\mathbf{v}}_1 = \underset{\mathbf{v} \in \mathbb{R}^p}{\operatorname{argmax}} \ \mathbf{v}^\top \mathbf{X}^\top \mathbf{X} \mathbf{v} \qquad \text{subject to} \quad \|\mathbf{v}\|_2^2 = 1.$$
 (1.3)

If you are not familiar with matrix calculus, Wikipedia is a convenient resource for common derivative identities, which you may find useful here.

2. Next, let  $j \in \{2, ..., p\}$  be given. Use the SVD and matrix multiplication to show that for all  $\mathbf{v} \in \mathbb{R}^p$  satisfying  $\mathbf{v}^\top \mathbf{v}_i = 0$  for each i < j, we have

$$\mathbf{v}^{\top} \mathbf{X}^{\top} \mathbf{X} \mathbf{v} = \sum_{k=j}^{p} \mathbf{v}^{\top} \left( d_k^2 \mathbf{v}_k \mathbf{v}_k^{\top} \right) \mathbf{v}, \tag{1.4}$$

where we define  $d_k = 0$  for  $k = n + 1, \dots, p$ .

3. Then, show that for each  $j=2,\ldots,p$ , the original (sample) PCA formulation in (1.2) is equivalent to

$$\hat{\mathbf{v}}_j = \underset{\mathbf{v} \in \mathbb{R}^p}{\operatorname{argmax}} \ \mathbf{v}^\top \left( \mathbf{X}_{(j)}^\top \mathbf{X}_{(j)} \right) \mathbf{v} \quad \text{subject to} \quad \|\mathbf{v}\|_2^2 = 1,$$
 (1.5)

where 
$$\mathbf{X}_{(j)} = \widetilde{\mathbf{U}}\widetilde{\mathbf{D}}\widetilde{\mathbf{V}}^{\top}$$
,  $\widetilde{\mathbf{U}} = [\mathbf{u}_j, \dots, \mathbf{u}_n, \mathbf{u}_1, \dots, \mathbf{u}_{j-1}] \in \mathbb{R}^{n \times n}$ ,  $\widetilde{\mathbf{D}} = \operatorname{diag}(d_j, \dots, d_n, 0, \dots, 0) \in \mathbb{R}^{n \times p}$ , and  $\widetilde{\mathbf{V}} = [\mathbf{v}_j, \dots, \mathbf{v}_p, \mathbf{v}_1, \dots, \mathbf{v}_{j-1}] \in \mathbb{R}^{p \times p}$ .

4. Conclude that for each j = 1, ..., p, the  $j^{th}$  PC direction,  $\hat{\mathbf{v}}_j$ , is equal to the  $j^{th}$  right singular vector  $\mathbf{v}_i$ . (Hint: Problem 1 may be useful).

### 2 Ordinary Least Squares

Suppose that we observe our usual data matrix  $\mathbf{X} \in \mathbb{R}^{n \times p}$  and response vector  $\mathbf{y} \in \mathbb{R}^n$ , where n is the number of samples/observations and p is the number of features. Suppose also that  $\mathbf{X}$  has rank p < n. Under this setting, the ordinary least squares (OLS) estimator is given by

$$\hat{\boldsymbol{\beta}}_{OLS} = \underset{\boldsymbol{\beta}}{\operatorname{argmin}} \|\mathbf{y} - \mathbf{X}\,\boldsymbol{\beta}\|_{2}^{2}.$$

- 1. Provide an expression for  $\hat{\boldsymbol{\beta}}_{OLS}$  in terms of **X** and **y** by solving the optimization problem above. Why do we require the assumption that rank(**X**) = p < n?
- 2. Show that the OLS predictions  $\hat{\mathbf{y}} = \mathbf{X} \hat{\boldsymbol{\beta}}_{OLS}$  can be written as  $\hat{\mathbf{y}} = \mathbf{H} \mathbf{y}$ , where  $\mathbf{H}^2 = \mathbf{H}$ .
- 3. Prove that the residuals  $\hat{\mathbf{r}} = \mathbf{y} \hat{\mathbf{y}}$  are orthogonal to the OLS predictions  $\hat{\mathbf{y}}$ . Draw a picture to show what this means geometrically.

## 3 Reading

Share your main takeaways from any of the following papers (in a few sentences):

- Strong Inference (Platt 64)
- Regularization and Variable Selection via the Elastic Net (Zou and Hastie 05)
- Co-clustering directed graphs to discover asymmetries and directional communities (Karl Rohea, Tai Qin, and Bin Yu, 16)
- Better Subset Regression Using the Nonnegative Garrote (Breiman 95)