### PEVA Cheat Sheet 1

#### Lecture 1 General

Amdahl's law:  $T(n) = (1 - \alpha) \cdot t + \alpha \cdot \frac{t}{n}$ ,  $\lim_{n \to \infty} S(n) = \frac{1}{1 - \alpha}$ 

Kendall notation for queues:

 $arrivals \mid service \mid servers \mid buffersize \mid population \mid scheduling$ 

Distribution of interarrival time arrival service Distribution of service time

Number of servers. servers

buffer size Maximum number of customers in queueing station (in-

cluding servers).

population Number of customers in and outside the queueing sta-

scheduling Employed scheduling strategy.

### Lecture 2 DTMCs

**Limiting distribution**:  $\underline{v}(P-I) = \underline{0}$  and  $\sum_i v_i = 1$ 

$$(P-I) = \begin{pmatrix} -0.1 & 0.1 \\ 0.4 & -0.4 \end{pmatrix} \implies \begin{matrix} -0.1v_0 + 0.4v_1 = 0 \\ 0.1v_0 - 0.4v_1 = 0 \end{matrix}$$

A state is recurrent if we return to it with probrecurrent

ability 1.

transient A state is transient (or nonrecurrent) if there

is a positive probability of not returning to this

positive recurrent A state is positive recurrent (or recurrent nonnull) if its mean recurrence time is finite.

A state is null recurrent if its mean recurrence null recurrent

time is infinite.

absorbing A state i is absorbing if and only if pi, i = 1.

The period  $d_i$  of state i is the greatest common period divisor of all the values n for which  $p_{i,i}(n) > 0$ .

irreducible A DTMC is called irreducible if every state can be reached from every other state in a finite number of steps. In an irreducible DTMC. all

states have the same period.

Future evolution (next state) only depends on Markov property

the current state, not on the past history! DTMCs are time-homogeneous: the matrix P time-homogeneous

does not change over time.

## Lecture 3 CTMCs

For each state i, introduce rate  $q_i$  for an exponentially distributed residence time; mean residence time is  $1/a_i$ .

Compute steady-state of CTMC by: 1. GBEs or "fluxin, fluxout". 2. Determine steady-state of embedded DTMC and renormalize  $\boldsymbol{v}$ with  $p_i = (\frac{v_i}{q_i}) \ div \ (\sum_j \frac{v_j}{q_i})$ , 3. Generator Matrix **Q** with  $q_{i,j} = q_i \cdot p_{i,j}, i \neq j \text{ and } -q_i, i = j. \text{ With } \mathbf{Q}, \text{ solve } p \cdot \mathbf{Q} = \underline{0}.$ 

## Lecture 4 M|M|1 queues

FCFS First come, first served. Round robin. R.R. PS Processor sharing. Shortest job next. SJNL.CFS Last come, first served. IS Infinite server. PRIO priority scheduling. PASTA Poisson Arrivals See Time Averages.

What is the expected number of jobs in the system in steady state? 1. compute steady-state probabilities using GBEs or something else, 2. use steady-state probabilities to compute expectation.

 $E[N] = \sum_{i=0}^{n} i \cdot p_i$ . If server is infinite (like with a M|M|1 queue), the expected number of customer:

In system,  $E[N] = \frac{\rho}{1-\rho}$ .

In queue,  $E[N_q] = \frac{\rho^2}{1-\rho}$ .

In server,  $E[N_s] = \rho$ .

Little's Law helps to go from system-oriented measures tot user-oriented measures.

Little's law for:

Utilization

 $E[N] = \lambda \cdot E[R]$ , with E[R] as the expected re-Full station sponse time, average time each customer spends in system.

 $E[N_a] = \lambda \cdot E[W]$ , with E[W] as average waiting Queue only

Server only  $\rho = \lambda \cdot E[S]$ , with E[S] as average service time.

For finite stations with one server: Little's law  $E[N] = X \cdot E[R]$ , with  $X = \mu$  if overloaded Loss prob p\_{m} probability that an arriving job has to leave because the buffer is full (PASTA)

Throughput  $X = \lambda \cdot (1 - p_m) = \mu \cdot (1 - p_0)$ , number of jobs

served per time unit  $X \cdot E[S] = 1 - p_0$ 

For infinite stations with m server:

For each individual server  $\rho = \frac{\lambda}{m \cdot \mu}$ Utilization Expected busy servers Number of busy servers  $m \cdot \rho = \frac{\lambda'}{n}$ 

#### Lecture 5 Simulation

Monte Carlo method:  $X_i$  and  $Y_i$  random variables, uniform on [0,1]= random points in a unit square. Define  $J_i$  if  $Y_i \leq X_i$  then 1 else 0. Estimate  $\widetilde{A} = \frac{1}{N} \sum_{i=1}^N J_i \approx \int_0^1 x^2 dx$ .

The estimate  $\tilde{a}$  is a realization of the random variable  $\tilde{A}$ . Random variable A is called an estimator of a. A should be unbiased, so  $E[\widetilde{A}] = a$  and  $\widetilde{A}$  should be consistent, so  $\lim_{n \to \infty} var[\widetilde{A}] = 0$ Different ways to classify simulation methods: 1. Stochastic vs. deterministic: usage of random numbers, 2. Discrete-event vs. continuous-event, 3. Steady-state vs. transient and 4. Time-based vs. event-based.

Time-based simulation: Also called synchronous simulation. Time proceeds in steps of size  $\Delta t$ . In each iteration all events are processed that happen in the interval  $[t, t + \Delta t]$ , System state is changed accordingly, Assumption: ordering of events in an interval is not important, events are independent and  $\Delta t$  has to be small.

Event-based simulation: Also called asynchronous simulation, Time 'jumps' from event to event. In each iteration: determine the next event, set simulation time to its occurrence time, process the event and generate new events.

**User-oriented measure:** Estimate of average response time from n jobs =  $\widetilde{r} = \frac{1}{n} \sum_{i=1}^{n} (t_i^{(d)} - t_i^{(a)})$ , with  $t_i^{(a)}$  arrival time of ith job and  $t_i^{(d)}$  departure time of ith job.

# Lecture 6 M|G|1 queues

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