## MA1522 Homework 2

AY 24/25 Sem 1 — github/omgeta

Q1. (a) Check V by substituting  $x_1 = 1, x_2 = 2, x_3 = 0, x_4 = 1$  into the equation of V:

$$2(1) + 1(2) - 3(1) = 1 \neq 0$$

 $\implies$  the vector does not satisfy the equation for V

$$\implies \begin{bmatrix} 1 \\ 2 \\ 0 \\ 1 \end{bmatrix} \not\in V$$

Check U by RREF:

$$\begin{bmatrix} 3 & 1 & 7 & 1 & | & 1 \\ 3 & 3 & 1 & 4 & | & 2 \\ -3 & -1 & -3 & -3 & | & 0 \\ 3 & 2 & 5 & 2 & | & 1 \end{bmatrix} \xrightarrow{RREF} \begin{bmatrix} 1 & 0 & 0 & 3/2 & | & 0 \\ 0 & 1 & 0 & 0 & | & 0 \\ 0 & 0 & 1 & -1/2 & | & 0 \\ 0 & 0 & 0 & 0 & | & 1 \end{bmatrix}$$

⇒ inconsistent equation in the last row

⇒ the vector is not in the column space

$$\implies \begin{bmatrix} 1 \\ 2 \\ 0 \\ 1 \end{bmatrix} \not\in U$$

Therefore,  $\begin{bmatrix} 1\\2\\0\\1 \end{bmatrix} \not\in V \land \begin{bmatrix} 1\\2\\0\\1 \end{bmatrix} \not\in U \quad \blacksquare$ 

(b) From the RREF of the matrix formed by the spanning set of U in (a), we can see the 4th column vector is a linear combination of the 1st and 3rd. By removing either the 1st, 3rd, or 4th vector, we can get a linearly independent set which also spans U.

Therefore, a possible basis is 
$$\left\{ \begin{bmatrix} 3\\3\\-3\\3 \end{bmatrix}, \begin{bmatrix} 1\\3\\-1\\2 \end{bmatrix}, \begin{bmatrix} 7\\1\\-3\\5 \end{bmatrix} \right\}$$

(c) Suppose there is a linear equation for  $U: a_1x_1 + a_2x_2 + a_3x_3 + a_4x_4 = \vec{b}$ , since  $\vec{0} \in U$ , the following equations must hold:

$$3a_1 + 3a_2 - 3a_3 + 3a_4 = 0$$
$$1a_1 + 3a_2 - 1a_3 + 2a_4 = 0$$
$$7a_1 + 1a_2 - 3a_3 + 5a_4 = 0$$

Reduce the corresponding matrix:

$$\begin{bmatrix} 3 & 3 & -3 & 3 & | & 0 \\ 1 & 3 & -1 & 2 & | & 0 \\ 7 & 1 & -3 & 5 & | & 0 \end{bmatrix} \xrightarrow{RREF} \begin{bmatrix} 1 & 0 & 0 & 3/4 & | & 0 \\ 0 & 1 & 0 & 1/2 & | & 0 \\ 0 & 0 & 1 & 1/4 & | & 0 \end{bmatrix}$$

$$\Longrightarrow \begin{bmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \end{bmatrix} = s \begin{bmatrix} 3 \\ 2 \\ 1 \\ -4 \end{bmatrix}, s \in \mathbb{R}$$

Therefore, a linear equation is  $3x_1 + 2x_2 + x_3 - 4x_4 = 0$ 

(d) Firstly, check if T is linearly independent:

$$\begin{bmatrix} 1 & 1 & 2 \\ 1 & 1 & -1 \\ -2 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \xrightarrow{RREF} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

 $\implies T$  is linearly independent

Secondly, check if  $Span(T) \subseteq V$ :

$$2(1) + 1(1) - 3(1) = 0$$

$$2(2) + 1(-1) - 3(1) = 0$$

$$\Rightarrow \begin{bmatrix} 1 \\ 1 \\ -2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -1 \\ 0 \\ 1 \end{bmatrix} \in V$$

 $\implies$  Span $(T) \subseteq V$ , by closure over addition and multiplication

Thirdly, check if  $V \subseteq \operatorname{Span}(T)$ :

$$\vec{v} \in V = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} x_1 \\ 3x_4 - 2x_1 \\ x_3 \\ x_4 \end{bmatrix}$$

$$= s \begin{bmatrix} 1 \\ -2 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} + u \begin{bmatrix} 0 \\ 3 \\ 0 \\ 1 \end{bmatrix}, \quad s, t, u \in \mathbb{R}$$

$$\therefore V = \text{Span} \left\{ \begin{bmatrix} 1 \\ -2 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 3 \\ 0 \\ 1 \end{bmatrix} \right\}$$

$$\begin{bmatrix} 1 & 1 & 2 & | & 1 & 0 & 0 \\ 1 & 1 & -1 & | & -2 & 0 & 3 \\ -2 & 1 & 0 & | & 0 & 1 & 0 \\ 1 & 1 & 1 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{RREF} \begin{bmatrix} 1 & 0 & 0 & | & -1/3 & -1/3 & 2/3 \\ 0 & 1 & 0 & | & -2/3 & 1/3 & 4/3 \\ 0 & 0 & 1 & | & 1 & 0 & -1 \\ 0 & 0 & 0 & | & 0 & 0 & 0 \end{bmatrix}$$

$$\implies V \subseteq \operatorname{Span}(T)$$

Since  $Span(T) \subseteq V$  and  $V \subseteq Span(T)$ , then Span(T) = V, by the definition of set equality. Therefore, Span(T) = V and T is linearly independent  $\implies T$  is a basis for V

(e) For a vector  $\vec{v} \in U \cap V$ :

$$2x_1 + x_2 + 0x_3 - 3x_4 = 0$$
$$3x_1 + 2x_2 + 1x_3 - 4x_3 = 0$$

Reduce the corresponding matrix:

$$\begin{bmatrix} 2 & 1 & 0 & -3 & | & 0 \\ 3 & 2 & 1 & -4 & | & 0 \end{bmatrix} \xrightarrow{RREF} \begin{bmatrix} 1 & 0 & -1 & -2 & | & 0 \\ 0 & 1 & 2 & 1 & | & 0 \end{bmatrix}$$
$$\therefore \vec{v} = s \begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 2 \\ -1 \\ 0 \\ 1 \end{bmatrix}, \quad s, t \in \mathbb{R}$$

Therefore, a basis for 
$$U \cap V$$
 is  $\left\{ \begin{bmatrix} 1\\-2\\1\\0 \end{bmatrix}, \begin{bmatrix} 2\\-1\\0\\1 \end{bmatrix} \right\}$ 

Q2. Yes.

Includes zero vector: when  $s_1 = -1, s_2 = 1, s_3 = 2, \vec{v} = \vec{0}$ Closure over addition:

$$\vec{u} + \vec{v} = \begin{bmatrix} 4 \\ -3 \\ 9 \\ 1 \end{bmatrix} + s_1 \begin{bmatrix} 6 \\ 6 \\ 8 \\ 2 \end{bmatrix} + s_2 \begin{bmatrix} 6 \\ 3 \\ 7 \\ 1 \end{bmatrix} + s_3 \begin{bmatrix} -2 \\ 3 \\ -4 \\ 0 \end{bmatrix}$$

$$+ \begin{bmatrix} 4 \\ -3 \\ 9 \\ 1 \end{bmatrix} + t_1 \begin{bmatrix} 6 \\ 6 \\ 8 \\ 2 \end{bmatrix} + t_2 \begin{bmatrix} 6 \\ 3 \\ 7 \\ 1 \end{bmatrix} + t_3 \begin{bmatrix} -2 \\ 3 \\ -4 \\ 0 \end{bmatrix}, \text{ where } \vec{u}, \vec{v} \in V$$

$$= \begin{bmatrix} 4 \\ -3 \\ 9 \\ 1 \end{bmatrix} + (s_1 + t_1 + 1) \begin{bmatrix} 6 \\ 6 \\ 8 \\ 2 \end{bmatrix} + (s_2 + t_2 - 1) \begin{bmatrix} 6 \\ 3 \\ 7 \\ 1 \end{bmatrix} + (s_3 + t_3 - 2) \begin{bmatrix} -2 \\ 3 \\ -4 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 4 \\ -3 \\ 9 \\ 1 \end{bmatrix} + s_1' \begin{bmatrix} 6 \\ 6 \\ 8 \\ 2 \end{bmatrix} + s_2' \begin{bmatrix} 6 \\ 3 \\ 7 \\ 1 \end{bmatrix} + s_3' \begin{bmatrix} -2 \\ 3 \\ -4 \\ 0 \end{bmatrix}$$
(\mathbb{R} \text{ closed over addition})

Closure over multiplication:

$$c \cdot \vec{v} = c \begin{bmatrix} 4 \\ -3 \\ 9 \\ 1 \end{bmatrix} + cs_1 \begin{bmatrix} 6 \\ 6 \\ 8 \\ 2 \end{bmatrix} + cs_2 \begin{bmatrix} 6 \\ 3 \\ 7 \\ 1 \end{bmatrix} + cs_3 \begin{bmatrix} -2 \\ 3 \\ -4 \\ 0 \end{bmatrix}, \text{ where } c \in \mathbb{R}, \vec{v} \in V$$

$$= \begin{bmatrix} 4 \\ -3 \\ 9 \\ 1 \end{bmatrix} + (cs_1 + c) \begin{bmatrix} 6 \\ 6 \\ 8 \\ 2 \end{bmatrix} + (cs_2 - c) \begin{bmatrix} 6 \\ 3 \\ 7 \\ 1 \end{bmatrix} + (cs_3 - 2c) \begin{bmatrix} -2 \\ 3 \\ -4 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 4 \\ -3 \\ 9 \\ 1 \end{bmatrix} + s'_1 \begin{bmatrix} 6 \\ 6 \\ 8 \\ 2 \end{bmatrix} + s'_2 \begin{bmatrix} 6 \\ 3 \\ 7 \\ 1 \end{bmatrix} + s'_3 \begin{bmatrix} -2 \\ 3 \\ -4 \\ 0 \end{bmatrix}$$

$$\implies c\vec{v} \in V$$

$$(\mathbb{R} \text{ closed over addition/multiplication})$$

$$\implies c\vec{v} \in V$$

To check if the spanning set is a basis, check for linearly independence:

$$\begin{bmatrix} 6 & 6 & -2 \\ 6 & 3 & 3 \\ 8 & 7 & -4 \\ 2 & 1 & 0 \end{bmatrix} \xrightarrow{RREF} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

⇒ all the vectors are linearly independent

Therefore, a basis for 
$$V$$
 is  $\left\{ \begin{bmatrix} 6\\6\\8\\2 \end{bmatrix}, \begin{bmatrix} 6\\3\\7\\1 \end{bmatrix}, \begin{bmatrix} -2\\3\\-4\\0 \end{bmatrix} \right\}$ 

Q3. (a) Reduce matrix A:

$$\begin{bmatrix} 2 & 4 & 3 \\ 9 & 6 & 3 \\ -1 & 3 & 4 \\ 1 & 1 & 1 \end{bmatrix} \xrightarrow{RREF} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

rank(A) = dim(Col(A)) = number of pivot columns of A = 3

(b) Yes; Suppose  $B = \begin{bmatrix} a & b & c & d \\ e & f & g & h \\ i & j & k & l \end{bmatrix}$ , then since  $BA = I_3 \iff A^TB^T = I_3$ , to solve, we reduce the system  $\begin{bmatrix} A^T \mid I_3 \end{bmatrix}$ :

$$\begin{bmatrix} 2 & 9 & -1 & 1 & | & 1 & 0 & 0 \\ 4 & 6 & 3 & 1 & | & 0 & 1 & 0 \\ 3 & 3 & 4 & 1 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{RREF} \begin{bmatrix} 1 & 0 & 0 & -1/3 & | & -5/9 & 13/9 & -11/9 \\ 0 & 1 & 0 & 2/9 & | & 7/27 & -11/27 & 10/27 \\ 0 & 0 & 1 & 1/3 & | & 2/9 & -7/9 & 8/9 \end{bmatrix}$$

Therefore, 
$$B = \begin{bmatrix} -5/9 + s/3 & 7/27 - 2s/9 & 2/9 - s/3 & s \\ 13/9 + t/3 & -11/27 - 2t/9 & -7/9 - t/3 & t \\ -11/9 + u/3 & 10/27 - 2u/9 & 8/9 - u/3 & u \end{bmatrix}, s, t, u \in \mathbb{R}$$

- (c) No;  $rank(A) \neq number$  of rows = 4  $\implies$  A has no right inverse.  $\blacksquare$  (Math Cafe 7, Slide 30)
- (d) No;  $\operatorname{Nul}(A) \perp \operatorname{Row}(A) \implies \operatorname{Nul}(A^T) \perp \operatorname{Col}(A) \implies \forall v \in \operatorname{Nul}(A^T), \ \vec{v} \not\in \operatorname{Col}(A)$

Alternatively, suppose nonzero  $\vec{v} \in \text{Nul}(A^T)$ , then  $A^T \vec{v} = \vec{0}$ :

$$\begin{bmatrix} 2 & 9 & -1 & 1 & | & 0 \\ 4 & 6 & 3 & 1 & | & 0 \\ 3 & 3 & 4 & 1 & | & 0 \end{bmatrix} \xrightarrow{RREF} \begin{bmatrix} 1 & 0 & 0 & -1/3 & | & 0 \\ 0 & 1 & 0 & 2/9 & | & 0 \\ 0 & 0 & 1 & -1/3 & | & 0 \end{bmatrix}$$
$$\therefore \vec{v} = s \begin{bmatrix} 3 \\ -2 \\ 3 \\ -9 \end{bmatrix}, \quad s \in \mathbb{R} \setminus \{0\}$$

However,  $A\vec{x} = \vec{v}$  will not be consistent as shown below:

$$\begin{bmatrix} 2 & 4 & 3 & | & 3 \\ 9 & 6 & 3 & | & -2 \\ -1 & 3 & 4 & | & 3 \\ 1 & 1 & 1 & | & -9 \end{bmatrix} \xrightarrow{RREF} \begin{bmatrix} 1 & 0 & 0 & | & 0 \\ 0 & 1 & 0 & | & 0 \\ 0 & 0 & 1 & | & 0 \\ 0 & 0 & 0 & | & 1 \end{bmatrix}$$

Therefore, there exists no nonzero vector  $\vec{v} \in \text{Nul}(A^T) \land A\vec{x} = \vec{v}$ 

Q4. (a) Find the transition matrix from S to T:

$$\begin{bmatrix} 1 & 1 & 0 & | & 1 & 0 & 0 \\ 3 & -3 & 6 & | & 0 & 3 & 0 \\ -1 & 3 & -1 & | & 1 & -2 & 3 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{RREF} \begin{bmatrix} 1 & 0 & 0 & | & 1/2 & 1/2 & -1 \\ 0 & 1 & 0 & | & 1/2 & -1/2 & 1 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \\ 0 & 0 & 0 & | & 0 & 0 & 0 \end{bmatrix}$$

Therefore 
$$[w]_T = \begin{bmatrix} 1/2 & 1/2 & -1 \\ 1/2 & -1/2 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \frac{x_1 + x_2}{2} - x_3 \\ \frac{x_1 - x_2}{2} + x_3 \\ x_3 \end{bmatrix} \blacksquare$$

(b) Find the transition matrix from B to the standard basis, using  $P_S$ , the transition matrix from S to the standard basis:

$$P_S P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 1 & -2 & 3 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 & 2 \\ -1 & 1 & 1 \\ 1 & 0 & 2 \end{bmatrix}$$
$$= \begin{bmatrix} 1 & -1 & 2 \\ -3 & 3 & 3 \\ 6 & -3 & 6 \\ 1 & 0 & 2 \end{bmatrix}$$

Therefore, a basis for 
$$B$$
 is  $\left\{ \begin{bmatrix} 1\\-3\\6\\1 \end{bmatrix}, \begin{bmatrix} -1\\3\\-3\\0 \end{bmatrix}, \begin{bmatrix} 2\\3\\6\\2 \end{bmatrix} \right\}$