

در این بخش از دو روش حلقه ای و پیدا کردن بزرگ اندازه ترین عنصر خارج قطر اصلی استفاده کردیم در ادامه کد و خروجی آنها آورده شده است.

```
%% Jacobi_eig
function [jV, jD] = Jacobi_eig(A)
```

```
    delta = eps * norm(A, 'fro');
```

```
    jV = eye(size(A, 1));
    jD = A;
```

```
    while (off(jD) > delta)
```

```
    % %    method 1
```

```
    %         for p = 1:size(A, 1) - 1
```

```
    %         for q = p+1:size(A, 1)
```

```
    %
```

```
    %             [c, s] = symSchur2(jD, p, q);
```

```
    %
```

```
    %             J = eye(size(A, 1));
```

```
    %             J(p,p) = c;
```

```
    %             J(p,q) = s;
```

```
    %             J(q,p) = -s;
```

```
    %             J(q,q) = c;
```

```
    %
```

```
    %             jV = jV*J;
```

```
    %             jD = J'*jD*J;
```

```
    %
```

```
    %         end
```

```
    %    end
```

```
    % method 2
```

```
    [p,q] = find(abs(jD) == max(abs(jD - diag(diag(jD)))), [], 'all'), 1);
```

```
    if (p > q)
```

```
        temp = p;
```

```
        p = q;
```

```
        q = temp;
```

```
    end
```

```
    [c, s] = symSchur2(jD, p, q);
```

```
    J = eye(size(A, 1));
```

```
    J(p,p) = c;
```

```
    J(p,q) = s;
```

```
    J(q,p) = -s;
```

```
    J(q,q) = c;
```

```
    jV = jV * J;
```

```
    jD = J' * jD * J;
```

```
end
```

```
% sort eigenvalues
```

```
jD = diag(jD);
```

```
for i=1:size(A, 1) - 1
```

```
    for j=1:size(A, 1) - i
```

```
        if jD(j) > jD(j+1)
```

```
            % change eigenvalues
```

```
            temp = jD(j);
```

```
            jD(j) = jD(j+1);
```

```
            jD(j+1) = temp;
```

```
            % change eigenvectors
```

```
            temp = jV(:, j);
```

```
            jV(:, j) = jV(:, j+1);
```

```
            jV(:, j+1) = temp;
```

```
        end
```

```
    end
```

```
end
```

```
jD = diag(jD);
```

```
end
```

```
%% off
```

```
function out = off(A)
```

```
    out = norm(A, 'fro') ^ 2;
```

```
    for i = 1:min(size(A))
```

```
        out = out - A(i, i) ^ 2;
```

```
    end
```

```
end
```

```
%% symSchur2
```

```
function [c, s] = symSchur2(A, p, q)
```

```
    if (A(p,q) == 0)
```

```
        c = 1;
```

```
        s = 0;
```

```
    else
```

```
        t = (A(q,q)-A(p,p))/(2*A(p,q));
```

```
        if (t >= 0)
```

```
            t_min = 1/(t+sqrt(1+t^2));
```

```
        else
```

```
            t_min = 1/(t-sqrt(1+t^2));
```

```
        end
```

```
        c = 1/(sqrt(1+t_min^2));
```

```
        s = t_min * c;
```

```
    end
```

```
end
```

خروجی روش بزرگترین یاب برای ماتریس رندوم متقارن ۶ در ۶ و مقایسه با دستور eig (مقدار ضریب دلتا eps در نظر گرفته شد)

A =

2.6162	1.0825	1.1256	1.7058	2.1824	2.1351
1.0825	0.8080	0.7335	0.7388	0.8688	0.7523
1.1256	0.7335	1.5408	0.8840	1.6291	1.5786
1.7058	0.7388	0.8840	1.5683	1.5897	1.4759
2.1824	0.8688	1.6291	1.5897	2.7579	2.7173
2.1351	0.7523	1.5786	1.4759	2.7173	2.7501

jV =

-0.1871	-0.4437	-0.4539	-0.1239	0.5717	0.4690
0.2711	0.6000	-0.2862	0.5992	0.2907	0.2027
-0.1071	-0.4764	0.1050	0.6790	-0.4346	0.3173
0.1252	0.0064	0.8284	0.0103	0.4268	0.3403
-0.6262	0.4649	0.0298	-0.2029	-0.2881	0.5165
0.6872	-0.0093	-0.1181	-0.3510	-0.3670	0.5058

jD =

0.0125	0	0	0	0	0
0	0.0945	0	0	0	0
0	0	0.3372	0	0	0
0	0	0	0.6932	0	0
0	0	0	0	1.1142	0
0	0	0	0	0	9.7896

Elapsed time is 0.003493 seconds.

V =

0.1871	0.4437	-0.4539	0.1239	-0.5717	0.4690
-0.2711	-0.6000	-0.2862	-0.5992	-0.2907	0.2027
0.1071	0.4764	0.1050	-0.6790	0.4346	0.3173
-0.1252	-0.0064	0.8284	-0.0103	-0.4268	0.3403
0.6262	-0.4649	0.0298	0.2029	0.2881	0.5165
-0.6872	0.0093	-0.1181	0.3510	0.3670	0.5058

D =

0.0125	0	0	0	0	0
0	0.0945	0	0	0	0
0	0	0.3372	0	0	0
0	0	0	0.6932	0	0
0	0	0	0	1.1142	0
0	0	0	0	0	9.7896

Elapsed time is 0.000318 seconds.

خروجی روش حلقه ای برای ماتریس رندوم متقارن ۶ در ۶ و مقایسه با دستور eig (مقدار ضریب دلتا اول eps در نظر گرفته شد و پایان نیافت و در نتیجه یک مقدار بزرگتر ده به توان منفی ۴ در نظر گرفته شد. چون روش حلقوی اجرا میشود معمولا پاسخ خوب به مقدار اصلی دستور eig نزدیک میشود اما چون ابعاد ماتریس کوچک است و جستجوی بزرگترین عنصر خارج قطر اصلی خیلی هزینه ندارد، این روش کندتر از روش قبل اجرا میشود)

A =

2.2410	1.7245	1.5584	1.4129	0.6724	1.0010
1.7245	1.7096	1.3474	1.4284	0.7754	0.8631
1.5584	1.3474	1.9175	1.1584	0.9844	1.2506
1.4129	1.4284	1.1584	1.6156	0.6436	0.8670
0.6724	0.7754	0.9844	0.6436	0.6170	0.6943
1.0010	0.8631	1.2506	0.8670	0.6943	1.3621

jV =

-0.3364	-0.1033	0.3508	-0.5857	-0.3985	0.5012
0.4373	0.6454	-0.2547	0.0984	-0.3395	0.4499
0.3462	-0.4509	-0.4325	-0.2843	0.4425	0.4617
-0.0928	-0.4622	0.0618	0.7216	-0.2976	0.4058
-0.7474	0.3039	-0.4333	0.1217	0.2964	0.2422
0.0926	0.2520	0.6583	0.1758	0.5947	0.3316

jD =

0.0039	0	0	0	0	0
0	0.1712	0	0	0	0
0	0	0.3643	0	0	0
0	0	0	0.5269	0	0
0	0	0	0	1.0412	0
0	0	0	0	0	7.3552

Elapsed time is 0.015757 seconds.

V =

-0.3365	0.1033	0.3508	0.5857	0.3985	0.5012
0.4373	-0.6454	-0.2547	-0.0984	0.3395	0.4499
0.3462	0.4509	-0.4325	0.2843	-0.4425	0.4617
-0.0928	0.4622	0.0618	-0.7216	0.2976	0.4058
-0.7474	-0.3039	-0.4333	-0.1217	-0.2964	0.2422
0.0926	-0.2520	0.6583	-0.1758	-0.5947	0.3316

D =

0.0039	0	0	0	0	0
0	0.1712	0	0	0	0
0	0	0.3643	0	0	0
0	0	0	0.5269	0	0
0	0	0	0	1.0412	0
0	0	0	0	0	7.3552

Elapsed time is 0.000269 seconds.

```

%% Jacobi_svd_2sided
function [jU2, jS2, jV2] = Jacobi_svd_2sided(A)

delta = 0.0001 * norm(A, 'fro');

[m, n] = size(A);
jS2 = A;
jU2 = eye(m);
jV2 = eye(n);

while (off(jS2) > delta)
    for p = 1:min(m, n)-1
        for q = p+1:min(m, n)

            [c1, s1, c2, s2] = asymSchur2(jS2, p, q);

            J1 = eye(m);
            J1(p,p) = c1;
            J1(p,q) = s1;
            J1(q,p) = -s1;
            J1(q,q) = c1;

            J2 = eye(n);
            J2(p,p) = c2;
            J2(p,q) = s2;
            J2(q,p) = -s2;
            J2(q,q) = c2;

            jS2 = J1' * jS2 * J2;
            jU2 = jU2 * J1;
            jV2 = jV2 * J2;

        end
    end
    if m < n
        % make all n-m end columns zero
        for p = 1:m
            for q = m+1:n

                if jS2(p, p) == 0
                    c2 = 0;
                    s2 = 1;
                else
                    t = -jS2(p, q)/jS2(p, p);
                    c2 = 1/sqrt(1+t^2);
                    s2 = t*c2;
                end

                J2 = eye(n);
                J2(p,p) = c2;
                J2(p,q) = s2;
                J2(q,p) = -s2;
                J2(q,q) = c2;

                jS2 = jS2 * J2;
                jV2 = jV2 * J2;

            end
        end
    elseif m > n
        % make all m-n end rows zero
        for p = n + 1:m
            for q = 1:n

                if jS2(q, q) == 0
                    c1 = 0;
                    s1 = 1;
                else
                    t = -jS2(p, q)/jS2(q, q);
                    c1 = 1/sqrt(1+t^2);
                    s1 = t*c1;
                end

                J1 = eye(m);
                J1(p,p) = c1;
                J1(p,q) = s1;
                J1(q,p) = -s1;
                J1(q,q) = c1;

                jS2 = J1' * jS2;
                jU2 = jU2 * J1;

            end
        end
    end
end

% make all coef positive
for i=1:min(m, n)
    if jS2(i, i) < 0
        jS2(i, i) = -jS2(i, i);
        jU2(:, i) = -jU2(:, i);
    end
end
end

```

```

%% asymSchur2
function [c1, s1, c2, s2] = asymSchur2(A, p, q)

    if (A(p, q) == A(q, p))
        c = 1;
        s = 0;
    else
        t = (A(q, p)-A(p, q))/(A(p, p)+A(q, q));
        c = 1/(sqrt(1+t^2));
        s = t*c;
    end

    temp = [c, s; -s, c] * A([p,q], [p,q]);
    [c2, s2] = symSchur2(temp, 1, 2);
    c1 = c * c2 + s * s2;
    s1 = c * s2 - s * c2;

end

```

```

% sort vectors
jS2 = diag(jS2);
for i = 1:min(m, n)-1
    for j = 1:min(m, n)-i

        if jS2(j) < jS2(j+1)
            % change coef
            temp = jS2(j);
            jS2(j) = jS2(j+1);
            jS2(j+1) = temp;

            % swap vectors
            temp = jU2(:, j);
            jU2(:, j) = jU2(:, j+1);
            jU2(:, j+1) = temp;
            temp = jV2(:, j);
            jV2(:, j) = jV2(:, j+1);
            jV2(:, j+1) = temp;
        end
    end
end

temp = jS2;
jS2 = zeros(m, n);
for i=1:min(m, n)
    jS2(i, i) = temp(i);
end
end

```

مقایسه روش با svd در ماتریس های رندوم با ابعاد مختلف :

A =

0.4231	0.5312	0.1265
0.6556	0.1088	0.1343
0.7229	0.6318	0.0986

jU1 =

0.5075	0.4677	0.7237
0.4581	-0.8578	0.2330
0.7297	0.2133	-0.6496

jS1 =

1.3173	0	0
0	0.3598	0
0	0	0.0598

jV1 =

0.7915	-0.5845	-0.1785
0.5925	0.8055	-0.0107
0.1501	-0.0973	0.9839

Elapsed time is 0.033298 seconds.

U =

-0.5075	0.4677	-0.7237
-0.4581	-0.8578	-0.2330
-0.7297	0.2133	0.6496

S =

1.3173	0	0
0	0.3598	0
0	0	0.0598

V =

-0.7915	-0.5845	0.1785
-0.5925	0.8055	0.0107
-0.1501	-0.0973	-0.9839

Elapsed time is 0.007665 seconds.

A =

0.5578	0.6225	0.2578	0.6841	0.4022
0.3134	0.9879	0.3968	0.4024	0.6207
0.1662	0.1704	0.0740	0.9828	0.1544

jU1 =

0.6163	0.0604	-0.7852
0.6619	-0.5801	0.4748
0.4268	0.8123	0.3975

jS1 =

1.8911	0	0	0	0
0	0.7704	0	0	0
0	0	0.2365	0	0

jV1 =

0.3290	-0.0170	-0.9434	0.0160	0.0344
0.5871	-0.5154	0.2032	0.3622	-0.4661
0.2396	-0.2005	0.0651	-0.9319	-0.1723
0.5856	0.7870	0.1883	0.0032	-0.0480
0.3831	-0.2730	0.1703	0.0091	0.8658

Elapsed time is 0.016157 seconds.

U =

-0.6163	0.0604	-0.7852
-0.6618	-0.5801	0.4748
-0.4268	0.8123	0.3975

S =

1.8911	0	0	0	0
0	0.7704	0	0	0
0	0	0.2365	0	0

V =

-0.3290	-0.0170	-0.9434	0.0139	0.0353
-0.5871	-0.5154	0.2032	0.3895	-0.4436
-0.2396	-0.2005	0.0651	-0.9199	-0.2278
-0.5856	0.7870	0.1883	0.0061	-0.0477
-0.3831	-0.2730	0.1703	-0.0428	0.8648

Elapsed time is 0.000210 seconds.

A =

0.5166	0.5409	0.7486
0.7027	0.6797	0.1202
0.1536	0.0366	0.5250
0.9535	0.8092	0.3258

jU1 =

0.5199	0.5731	0.6002	-0.2026
0.4977	-0.4200	0.2156	0.7276
0.1768	0.6365	-0.6161	0.4290
0.6714	-0.3000	-0.4623	-0.4954

jS1 =

1.8969	0	0
0	0.6718	0
0	0	0.1049
0	0	0

jV1 =

0.6777	-0.2783	-0.6806
0.6164	-0.2897	0.7322
0.4010	0.9158	0.0248

Elapsed time is 0.027613 seconds.

U =

-0.5185	0.5734	0.6017	-0.2007
-0.4973	-0.4202	0.2146	0.7280
-0.1777	0.6364	-0.6169	0.4277
-0.6725	-0.2995	-0.4597	-0.4968

S =

1.8969	0	0
0	0.6718	0
0	0	0.1049
0	0	0

V =

-0.6778	-0.2782	-0.6806
-0.6163	-0.2896	0.7323
-0.4008	0.9158	0.0248

Elapsed time is 0.000213 seconds.

```
%% Jacobi_svd_1sided
```

```
function [jU1, jS1, jV1] = Jacobi_svd_1sided(A)
```

```
[m, n] = size(A);
```

```
if m <= n
```

```
    delta = 0.0001 * norm(A*A', 'fro');
```

```
    D = A';
```

```
    jV1 = eye(m);
```

```
    % Just work on m columns
```

```
    while (off(D'*D) > delta)
```

```
        for p = 1:m-1
```

```
            for q = p+1:m
```

```
                [c, s] = orthogonalization(D(:, p), D(:, q));
```

```
                J = eye(m);
```

```
                J(p,p) = c;
```

```
                J(p,q) = s;
```

```
                J(q,p) = -s;
```

```
                J(q,q) = c;
```

```
                D = D * J;
```

```
                jV1 = jV1 * J;
```

```
            end
```

```
        end
```

```
    end
```

```
    % get out JU1 & JS1 from D
```

```
    jS1 = zeros(n, m);
```

```
    jU1 = zeros(n, m);
```

```
    for i = 1:m
```

```
        jS1(i, i) = norm(D(:, i));
```

```
        jU1(:, i) = D(:, i)/norm(D(:, i));
```

```
    end
```

```
    % Transpose everything to get final result
```

```
    temp = jU1;
```

```
    jU1 = jV1;
```

```
    jS1 = jS1';
```

```
    jV1 = temp;
```

```
else
```

```
    delta = 0.0001 * norm(A'*A, 'fro');
```

```
    D = A;
```

```
    jV1 = eye(n);
```

```
    % Just work on n columns
```

```
    while (off(D'*D) > delta)
```

```
        for p=1:n-1
```

```
            for q=p+1:n
```

```
                [c, s] = orthogonalization(D(:, p), D(:, q));
```

```
                J = eye(n);
```

```
                J(p,p) = c;
```

```
                J(p,q) = s;
```

```
                J(q,p) = -s;
```

```
                J(q,q) = c;
```

```
                D = D * J;
```

```
                jV1 = jV1 * J;
```

```
            end
```

```
        end
```

```
    end
```

```
    % get out JU1 & JS1 from D
```

```
    jS1 = zeros(m, n);
```

```
    jU1 = zeros(m, n);
```

```
    for i = 1:n
```

```
        jS1(i, i) = norm(D(:, i));
```

```
        jU1(:, i) = D(:, i)/norm(D(:, i));
```

```
    end
```

```
end
```

```
%% orthogonalization
```

```
function [c, s] = orthogonalization(x, y)
```

```
    if (norm(x) == norm(y))
```

```
        c = 1/sqrt(2);
```

```
        s = 1/sqrt(2);
```

```
    else
```

```
        t = 2*x'*y/(norm(y)^2-norm(x)^2);
```

```
        c = sqrt((1+1/sqrt(1+t^2))/2);
```

```
        s = sqrt((1-1/sqrt(1+t^2))/2);
```

```
    end
```

```
end
```

```
jS1 = diag(jS1);
```

```
for i = 1:min(m, n)-1
```

```
    for j = 1:min(m, n)-i
```

```
        if jS1(j) < jS1(j+1)
```

```
            % change coef
```

```
            temp = jS1(j);
```

```
            jS1(j) = jS1(j+1);
```

```
            jS1(j+1) = temp;
```

```
            % swap vectors
```

```
            temp = jU1(:, j);
```

```
            jU1(:, j) = jU1(:, j+1);
```

```
            jU1(:, j+1) = temp;
```

```
            temp = jV1(:, j);
```

```
            jV1(:, j) = jV1(:, j+1);
```

```
            jV1(:, j+1) = temp;
```

```
        end
```

```
    end
```

```
end
```

```
jS1 = diag(jS1);
```

```
end
```

مقایسه روش با svd در ماتریس های رندوم با ابعاد مختلف : (خروجی به فرمت Thin SVD میباشد)

```
A =  
0.7505 0.5836 0.7196  
0.5835 0.5118 0.9962  
0.5518 0.0826 0.3545
```

```
jU1 =  
0.6494 -0.1894 -0.7365  
0.6843 0.5682 0.4572  
0.3319 -0.8008 0.4985
```

```
jS1 =  
1.8223 0 0  
0 0.3131 0  
0 0 0.1857
```

```
jV1 =  
0.5870 -0.8065 -0.0588  
0.4152 0.3645 -0.8329  
0.6950 0.4655 0.5503
```

Elapsed time is 0.016255 seconds.

```
ans =  
0.7505 0.5836 0.7196  
0.5835 0.5118 0.9962  
0.5518 0.0826 0.3545
```

```
U =  
-0.6491 0.1896 -0.7367  
-0.6845 -0.5680 0.4570  
-0.3318 0.8009 0.4985
```

```
S =  
1.8223 0 0  
0 0.3131 0  
0 0 0.1857
```

```
V =  
-0.5870 0.8074 -0.0601  
-0.4152 -0.3639 -0.8338  
-0.6950 -0.4645 0.5488
```

Elapsed time is 0.000397 seconds.

```
A =  
0.8944 0.9274 0.6183 0.1248 0.8332  
0.1375 0.9175 0.3433 0.7306 0.3983  
0.3900 0.7136 0.9360 0.6465 0.7498
```

```
jU1 =  
0.6294 -0.7107 0.3143  
0.4689 0.6698 0.5757  
0.6197 0.2150 -0.7548
```

```
jS1 =  
2.4921 0 0  
0 0.7358 0  
0 0 0.4344
```

```
jV1 =  
0.3488 -0.6248 0.1518  
0.5843 0.1480 0.6471  
0.4535 -0.0113 -0.7241  
0.3297 0.7334 -0.0648  
0.4718 -0.2231 -0.1722
```

Elapsed time is 0.011936 seconds.

```
ans =  
0.8944 0.9274 0.6183 0.1248 0.8332  
0.1375 0.9175 0.3433 0.7306 0.3983  
0.3900 0.7136 0.9360 0.6465 0.7498
```

```
U =  
-0.6294 -0.7107 0.3143  
-0.4689 0.6698 0.5757  
-0.6197 0.2150 -0.7548
```

```
S =  
2.4921 0 0 0 0  
0 0.7358 0 0 0  
0 0 0.4344 0 0
```

```
V =  
-0.3488 -0.6248 0.1518 0.5542 -0.3973  
-0.5843 0.1480 0.6471 -0.4546 -0.1066  
-0.4535 -0.0113 -0.7241 -0.3648 -0.3698  
-0.3297 0.7334 -0.0648 0.5868 -0.0701  
-0.4718 -0.2231 -0.1722 0.0939 0.8301
```

Elapsed time is 0.000398 seconds.

```
A =  
0.7391 0.2815 0.6604  
0.9542 0.2304 0.0476  
0.0319 0.7111 0.3488  
0.3569 0.6246 0.4513  
0.6627 0.5906 0.2409
```

```
jU1 =  
-0.5239 -0.1513 -0.8027  
-0.4482 -0.6282 0.3881  
-0.3103 0.6710 0.2103  
-0.4328 0.3633 -0.0356  
-0.4910 -0.0145 0.3995
```

```
jS1 =  
1.8409 0 0  
0 0.8081 0  
0 0 0.4254
```

```
jV1 =  
-0.7079 -0.7011 0.0859  
-0.5612 0.6321 0.5343  
-0.4289 0.3301 -0.8409
```

Elapsed time is 0.013087 seconds.

```
ans =  
0.7391 0.2815 0.6604  
0.9542 0.2304 0.0476  
0.0319 0.7111 0.3488  
0.3569 0.6246 0.4513  
0.6627 0.5906 0.2409
```

```
U =  
-0.5240 0.1496 0.8024 -0.2433 -0.0073  
-0.4486 0.6268 -0.3883 0.0858 -0.4977  
-0.3099 -0.6720 -0.2105 -0.4258 -0.4762  
-0.4326 -0.3646 0.0353 0.8226 0.0449  
-0.4910 0.0130 -0.3998 -0.2748 0.7235
```

```
S =  
1.8409 0 0  
0 0.8081 0  
0 0 0.4254  
0 0 0  
0 0 0
```

```
V =  
-0.7088 0.7001 -0.0860  
-0.5602 -0.6329 -0.5344  
-0.4286 -0.3306 0.8408
```

Elapsed time is 0.000328 seconds.