



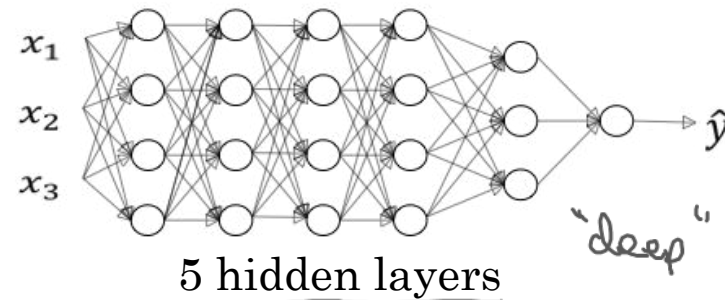
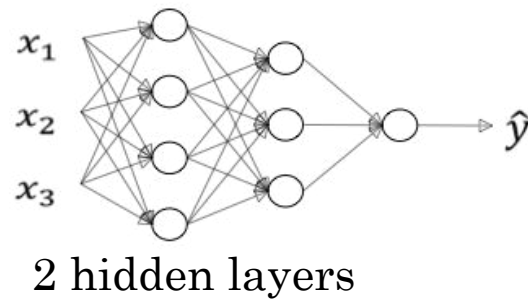
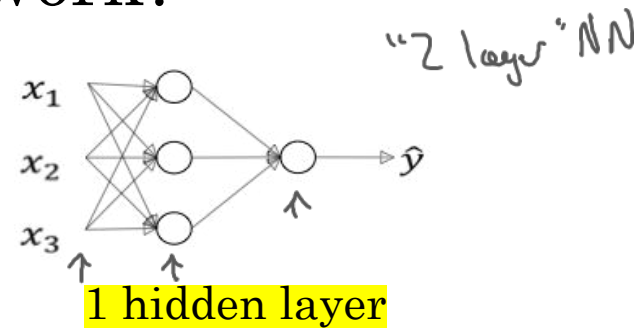
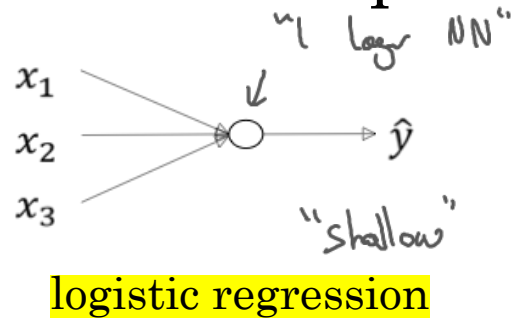
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Deep Neural Networks

Deep L-layer
Neural network

What is a deep neural network?

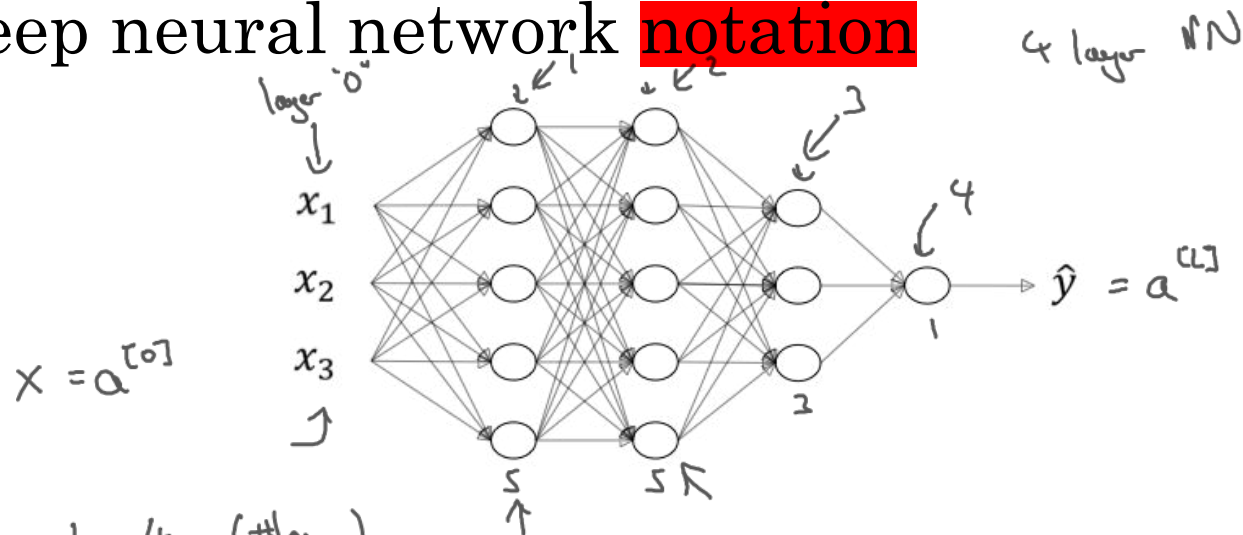
shallow
network



Deep Network

$$L, n^{[l]}, a^{[l]}, z^{[l]}, w^{[l]}, b^{[l]} \Rightarrow \begin{cases} x = a^{[0]} \\ \hat{y} = a^{[L]} \end{cases}$$

Deep neural network notation



$L \rightarrow L = 4$ (#layers)

$n^{[l]} \rightarrow n^{[l]} = \# \text{units in layer } l$

$a^{[l]} \rightarrow a^{[l]} = \text{activations in layer } l$

$a^{[l]} = g(z^{[l]})$, $w^{[l]} = \text{weights for } z^{[l]}$

$n^{[0]} = 3, n^{[1]} = 5, n^{[2]} = 5, n^{[3]} = 3, n^{[4]} = n^{[L]} = 1$

$n^{[0]} = n_x = 3$

$z^{[l]}$
 $w^{[l]}, b^{[l]}$



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Deep Neural Networks

Forward Propagation in a Deep Network

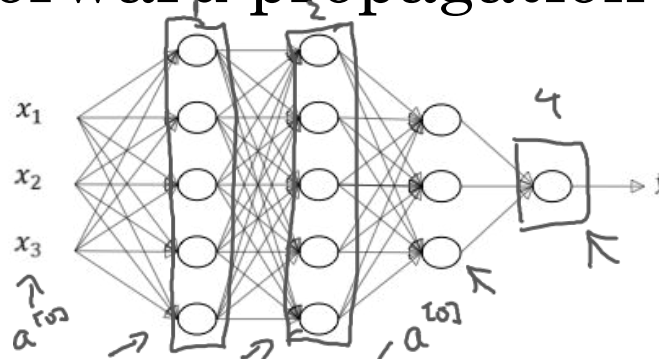
$$z^{[l]} = W^{[l]} A^{[l-1]} + b^{[l]}$$

$$A^{[l]} = g(z^{[l]})$$

$$\Rightarrow \begin{cases} X = A^{[0]} \\ \hat{Y} = A^{[L]} \end{cases}$$

for $l=1$ to $l=L$

Forward propagation in a deep network



$$X: z^{[1]} = W^{[1]} a^{[0]} + b^{[1]}$$

$$a^{[1]} = g(z^{[1]})$$

$$z^{[2]} = W^{[2]} a^{[1]} + b^{[2]}$$

$$a^{[2]} = g(z^{[2]})$$

$$z^{[4]} = W^{[4]} a^{[3]} + b^{[4]}, a^{[4]} = g(z^{[4]}) = \hat{y}$$

$$\begin{aligned} z^{[l]} &= W^{[l]} A^{[l-1]} + b^{[l]} \\ A^{[l]} &= g(z^{[l]}) \end{aligned}$$

$A^{[0]} = X$

Vertical:

$$\begin{aligned} z^{[1]} &= W^{[1]} A^{[0]} + b^{[1]} \\ A^{[1]} &= g(z^{[1]}) \\ z^{[2]} &= W^{[2]} A^{[1]} + b^{[2]} \\ A^{[2]} &= g(z^{[2]}) \\ &\vdots \\ z^{[L]} &= W^{[L]} A^{[L-1]} + b^{[L]} \\ \hat{Y} &= g(z^{[L]}) = A^{[L]} \end{aligned}$$

$\rightarrow X = A^{[0]}$
for $l=1 \dots L$



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Deep Neural Networks

Getting your matrix
dimensions right

Dimensions

non-vectorized (one sample)

$$w^{[l]} = (n^{[l]}, n^{[l-1]})$$

$$z^{[l]}, a^{[l]}, b^{[l]} = (n^{[l]}, 1)$$

Vectorized version (m samples)

$$Z^{[l]}, A^{[l]} = (n^{[l]}, m)$$

→ $n^{[l]}$ = number of units in layer l

→ $\dim(x) = \dim(dx) \Rightarrow dw^{[l]} = (n^{[l]}, n^{[l-1]})$, $db^{[l]} = (n^{[l]}, 1)$

→ $X = A^{[0]} \Rightarrow X = (n^{[0]}, m)$

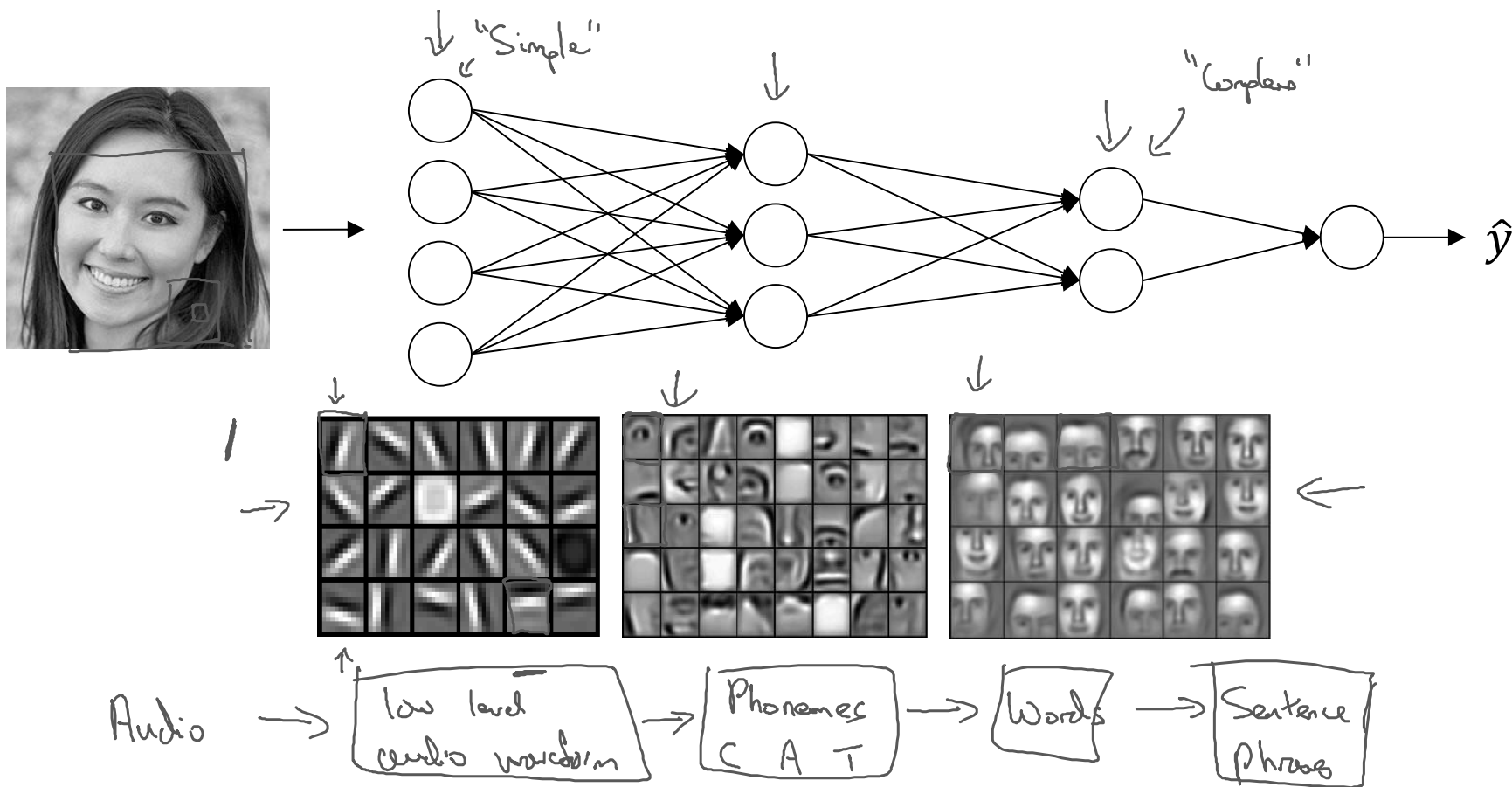


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Deep Neural Networks

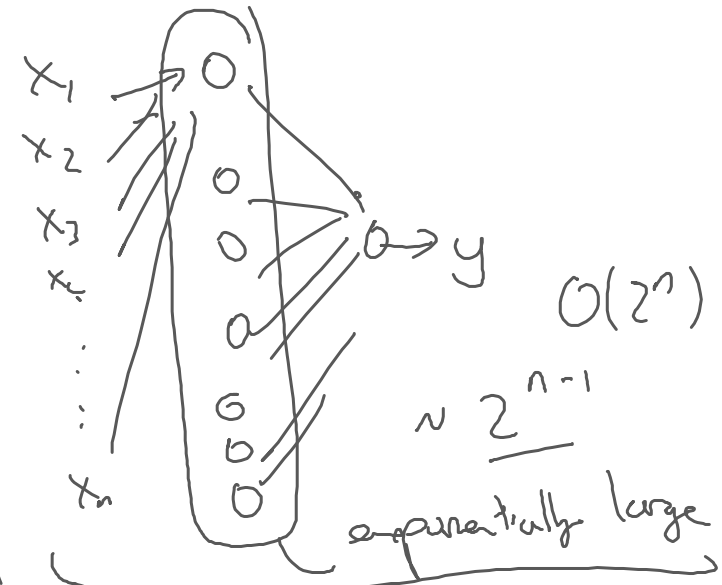
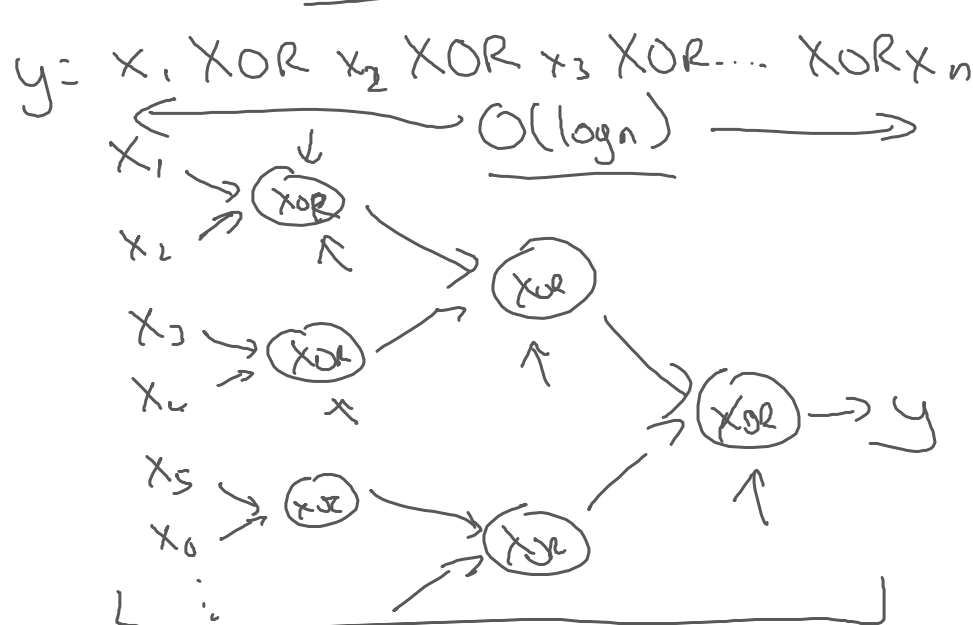
Why deep
representations?

Intuition about deep representation



Circuit theory and deep learning

Informally: There are functions you can compute with a “small” L-layer deep neural network that shallower networks require exponentially more hidden units to compute.



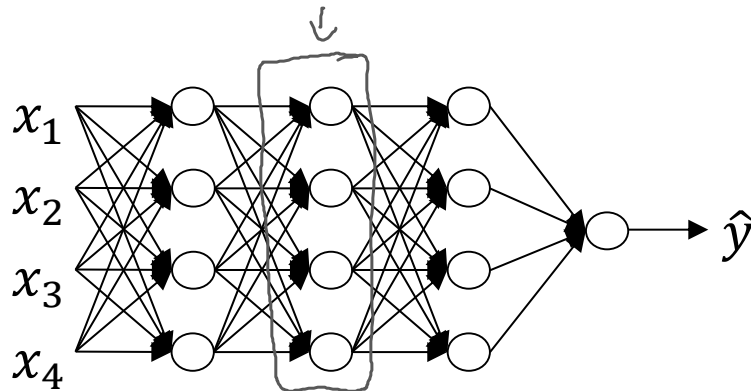


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Deep Neural Networks

Building blocks of
deep neural networks

Forward and backward functions



Layer l : $W^{[l]}, b^{[l]}$

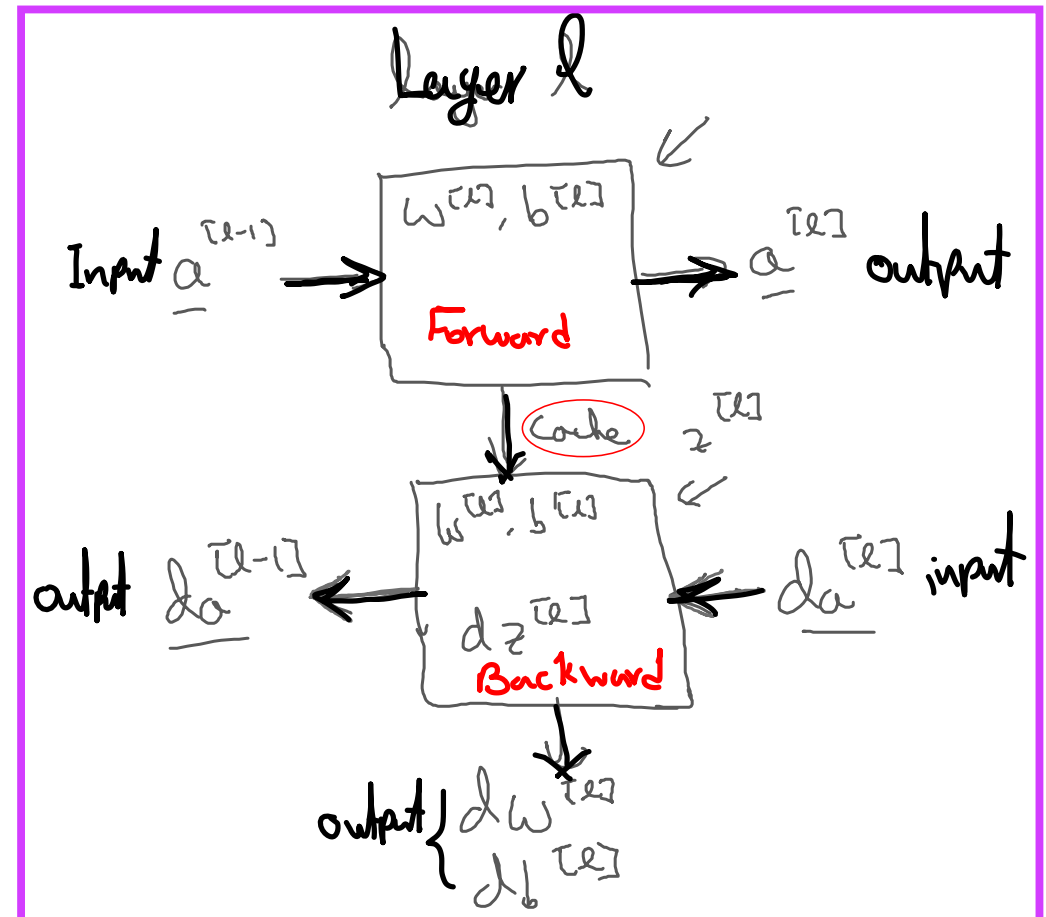
→ Forward: Input $a^{[l-1]}$, output $a^{[l]}$

$$z^{[l]} = W^{[l]} a^{[l-1]} + b^{[l]} \quad \text{cache } z^{[l]}$$

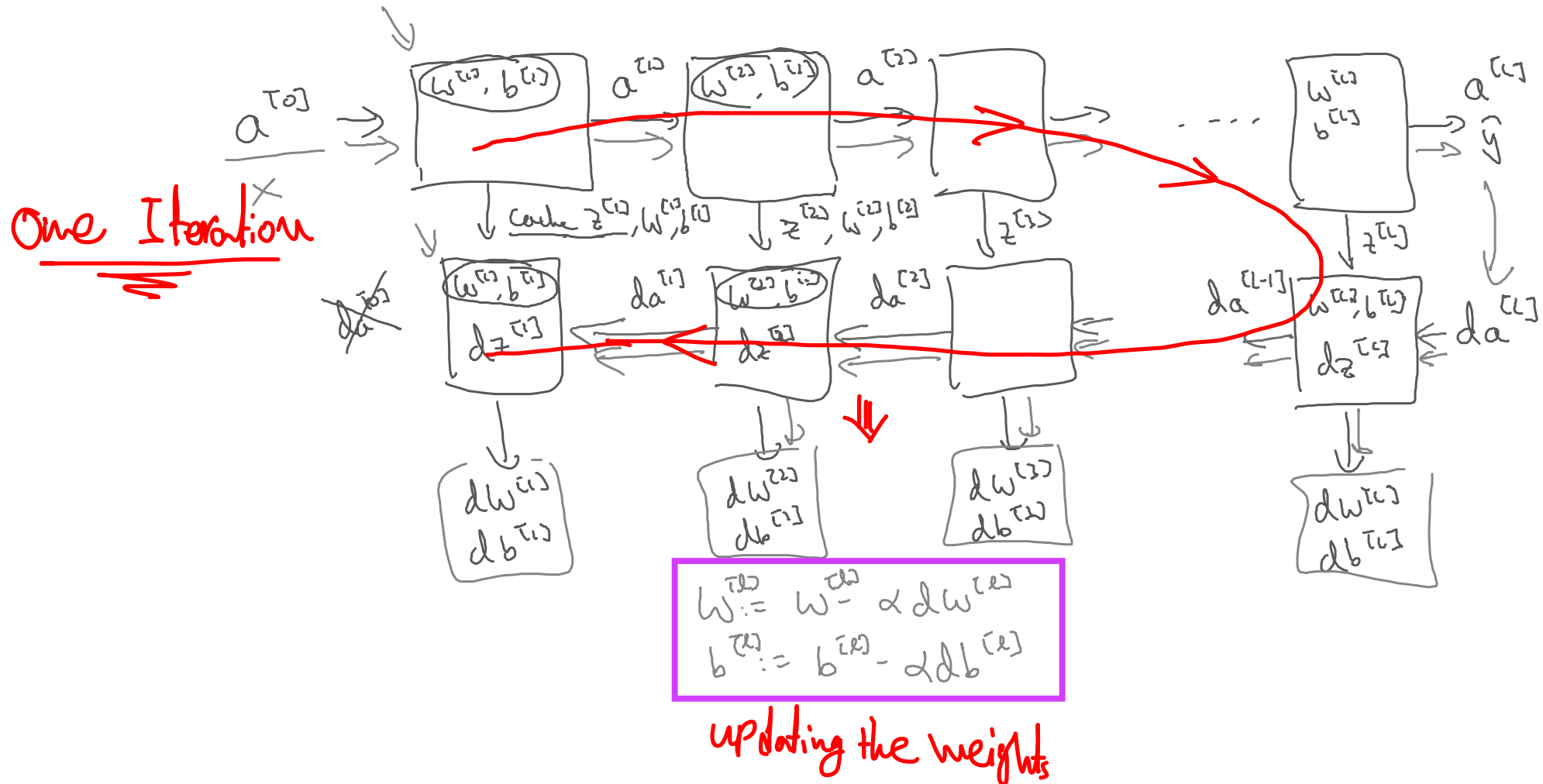
$$\underline{a}^{[l]} = g^{[l]}(z^{[l]})$$

→ Backward: Input $da^{[l]}$, output $da^{[l-1]}$

cache $(z^{[l]})$

$$\frac{dw^{[l]}}{db^{[l]}}$$


Forward and backward functions





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Deep Neural Networks

Forward and backward
propagation

Forward propagation for layer l

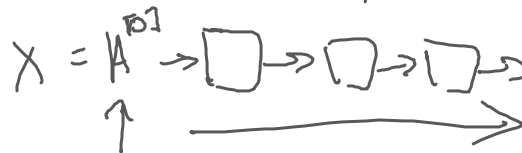
→ Input $a^{[l-1]} \leftarrow$

→ Output $a^{[l]}$, cache $(z^{[l]})$

$$z^{[l]} = W^{[l]} \cdot a^{[l-1]} + b^{[l]}$$

$$a^{[l]} = g^{[l]}(z^{[l]})$$

$a^{[0]}$
 $A^{[0]}$



vectorized Version

Vectorized:

$$Z^{[l]} = W^{[l]} \cdot A^{[l-1]} + b^{[l]}$$

$$A^{[l]} = g^{[l]}(Z^{[l]})$$

Backward propagation for layer l

→ Input $da^{[l]}$

→ Output $da^{[l-1]}, dW^{[l]}, db^{[l]}$

$$dz^{[l]} = da^{[l]} * g^{[l]'}(z^{[l]})$$

$$dw^{[l]} = dz^{[l]} \cdot a^{[l-1]}$$

$$db^{[l]} = dz^{[l]}$$

$$da^{[l-1]} = W^{[l]T} \cdot dz^{[l]}$$

$$dz^{[l+1]} = W^{[l+1]T} dz^{[l]} * g^{[l+1]'}(z^{[l+1]})$$

Vectorized version

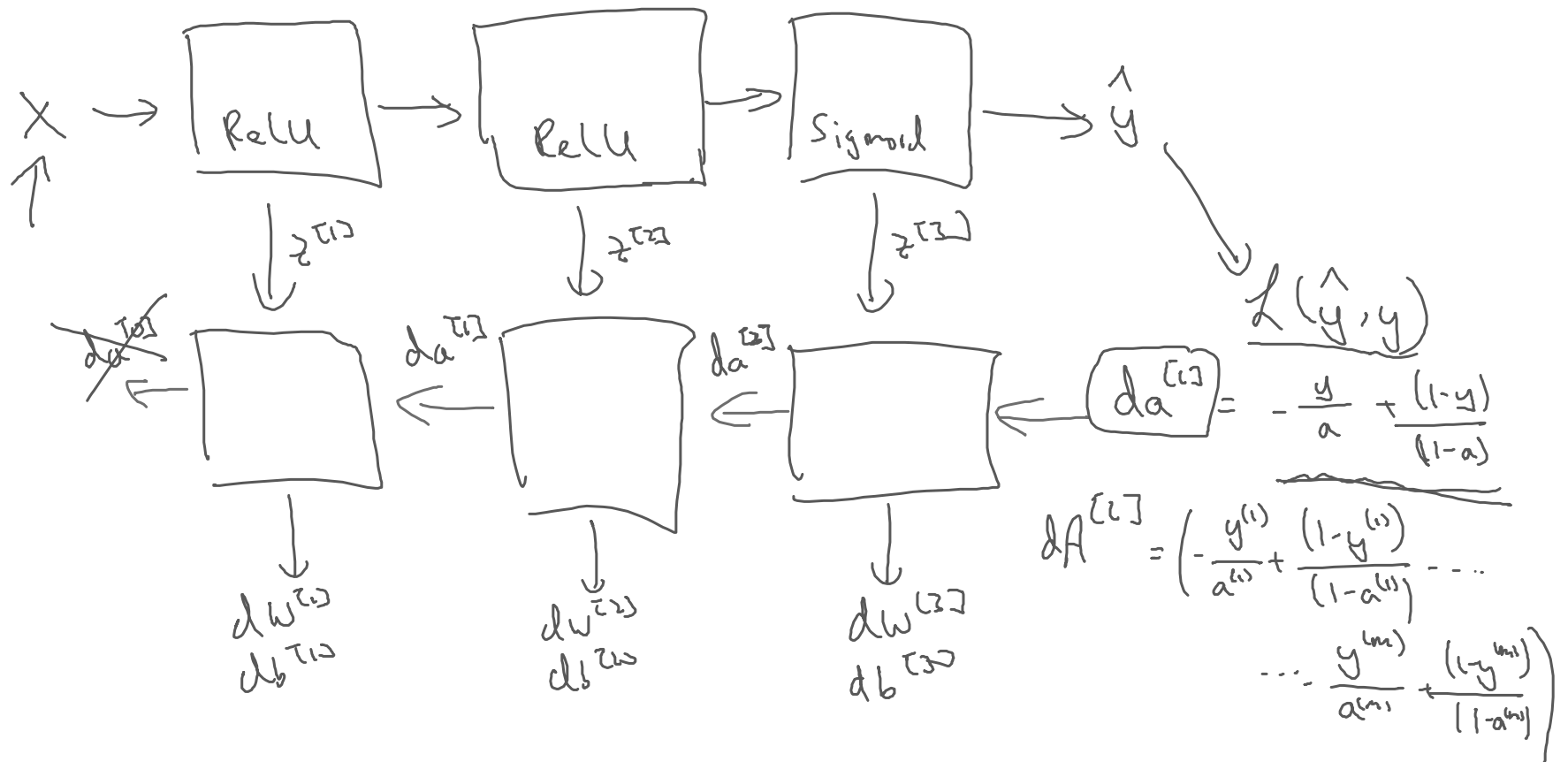
$$dz^{[l]} = dA^{[l]} * g^{[l]'}(z^{[l]})$$

$$dw^{[l]} = \frac{1}{n} dz^{[l]} \cdot A^{[l-1]T}$$

$$db^{[l]} = \frac{1}{n} \text{np.sum}(dz^{[l]}, \text{axis}=1, \text{keepdims}=\text{True})$$

$$dA^{[l-1]} = W^{[l]T} \cdot dz^{[l]}$$

Summary





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Deep Neural Networks

Parameters vs Hyperparameters

What are hyperparameters?

Parameters: $W^{[1]}, b^{[1]}, W^{[2]}, b^{[2]}, W^{[3]}, b^{[3]} \dots$

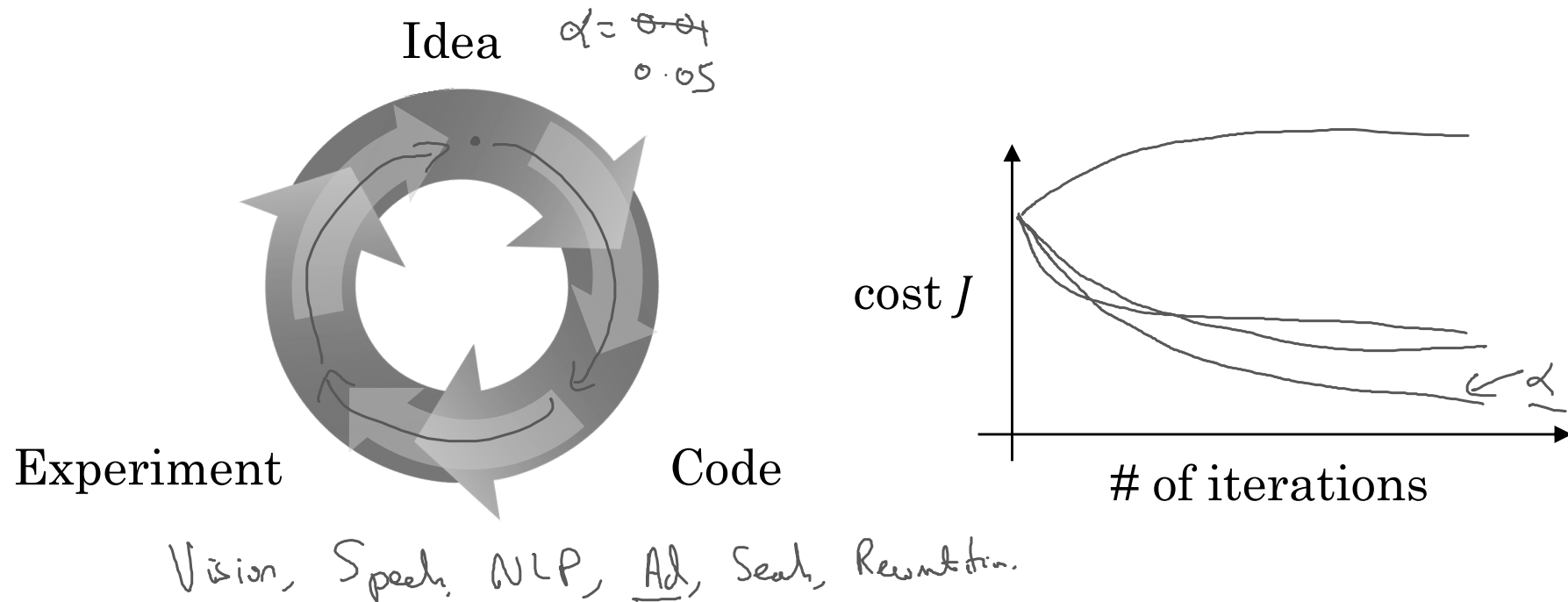
Hyperparameters: \rightarrow learning rate $\frac{\alpha}{\tau}$

Examples of Hyperparameters

- \rightarrow #iterations
- \rightarrow #hidden layers L
- \rightarrow #hidden units $n^{[1]}, n^{[2]}, \dots$
- \rightarrow choice of activation function

Later: Momentum, mini-batch size, regularizations, ...

Applied deep learning is a very empirical process





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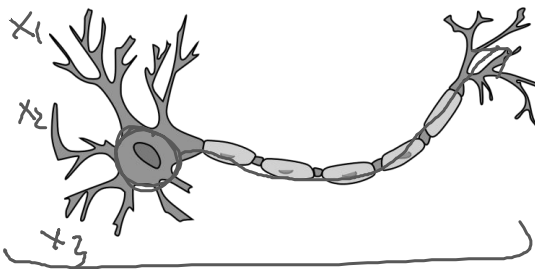
Deep Neural Networks

What does this
have to do with
the brain?

Forward and backward propagation

$$\begin{aligned} Z^{[1]} &= W^{[1]}X + b^{[1]} \\ A^{[1]} &= g^{[1]}(Z^{[1]}) \\ Z^{[2]} &= W^{[2]}A^{[1]} + b^{[2]} \\ A^{[2]} &= g^{[2]}(Z^{[2]}) \\ &\vdots \\ A^{[L]} &= g^{[L]}(Z^{[L]}) = \hat{Y} \end{aligned}$$

"It's like the brain"



$$\begin{aligned} dZ^{[L]} &= A^{[L]} - Y \\ dW^{[L]} &= \frac{1}{m} dZ^{[L]} A^{[L-1]T} \\ db^{[L]} &= \frac{1}{m} \text{np.sum}(dZ^{[L]}, \text{axis} = 1, \text{keepdims} = \text{True}) \\ dZ^{[L-1]} &= W^{[L]T} dZ^{[L]} * g'^{[L]}(Z^{[L-1]}) \\ &\vdots \\ dZ^{[1]} &= W^{[2]T} dZ^{[2]} g'^{[1]}(Z^{[1]}) \\ dW^{[1]} &= \frac{1}{m} dZ^{[1]} A^{[0]T} \\ db^{[1]} &= \frac{1}{m} \text{np.sum}(dZ^{[1]}, \text{axis} = 1, \text{keepdims} = \text{True}) \end{aligned}$$