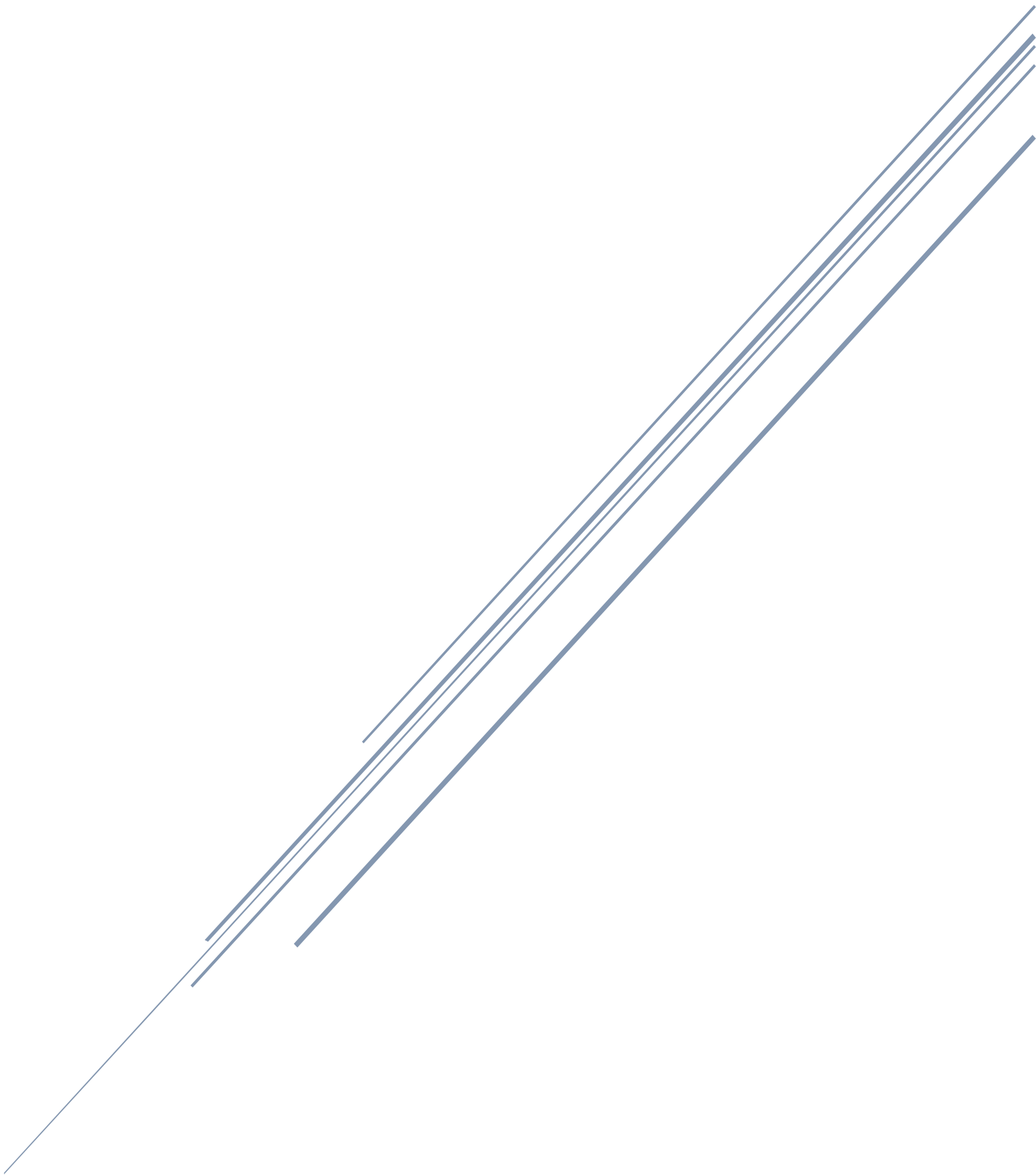


FS19CO042

MP MANUALS

Exp 1 to 10



Experiment No 1

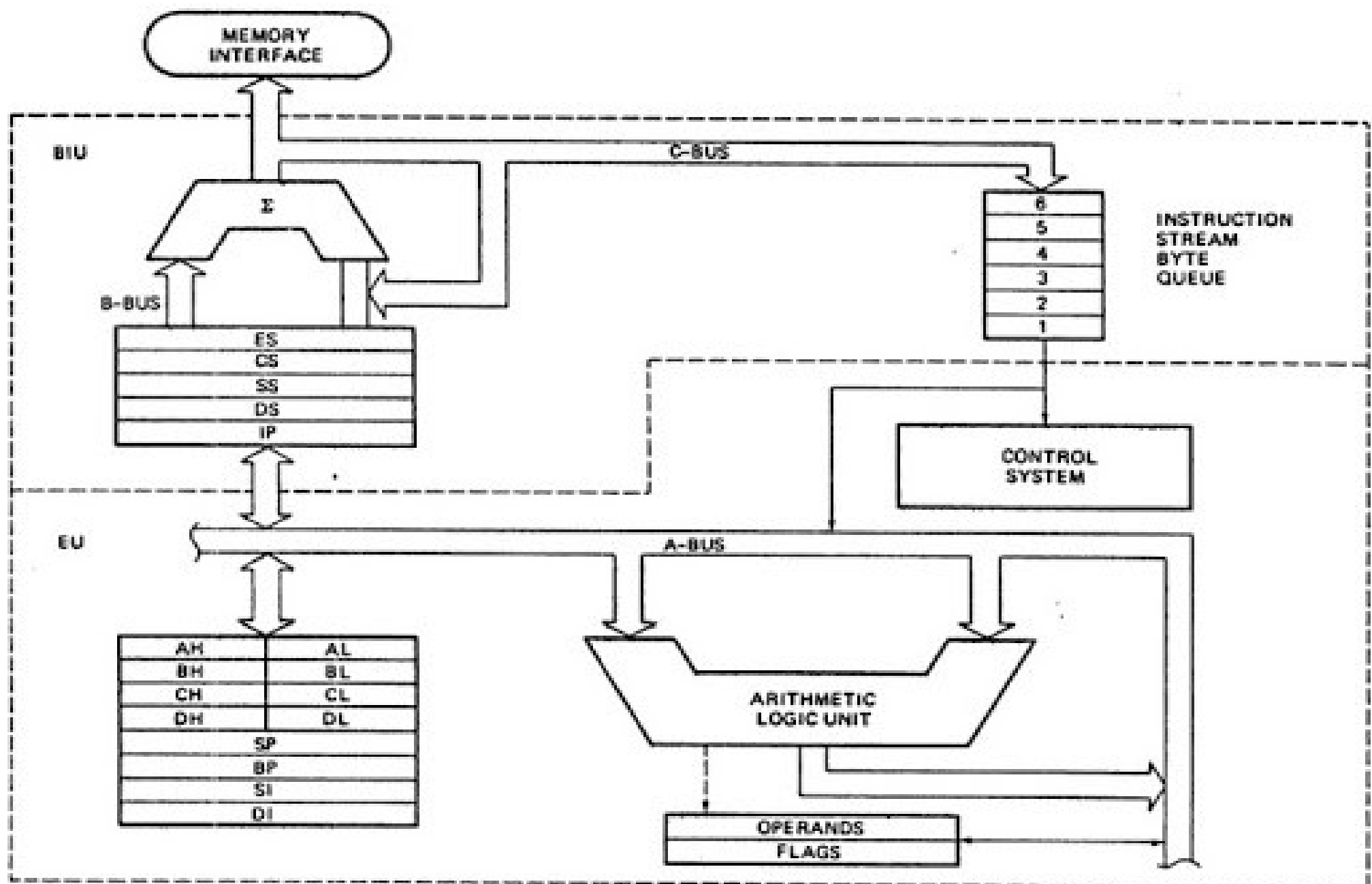
Aim : Understand 8086 Development Board and Simulation Software

Theory :

8086 Microprocessor is an enhanced version of 8085 Microprocessor that was designed by Intel in 1976. It is a 16-bit Microprocessor having 20 address lines and 16 data lines that provides up to 1MB storage. It consists of powerful instruction set, which provides operations like multiplication and division easily

EMU8086 - MICROPROCESSOR EMULATOR is a free emulator for multiple platforms. It provides its user with the ability to emulate old 8086 processors, which were used in Macintosh and Windows computers from the 1980s and early 1990s. It can emulate a large amount of software that was used on these microprocessors, but a savvy user can also program their own assembly code to run on it.

Block diagram of 8086:



BIU does the following:

- Fetch the instruction or data from memory.
- Write the data to the port.
- Read data from the port.
- Write the data to memory.

Execution unit does the following:

- To tell BIU where to fetch the instructions or data from.
- To decode the instructions.
- To execute the instructions.

Registers:

- **General Purpose register (Usable by programmer to store values i.e. variables)**

These are usable as whole for storing 16 bit data or their sub divisions, eg. AH,AL etc to store 8 bit data individually

1. **AX (AL,AH)** : Also used as accumulator in operations.
2. **BX (BL, BH)** : Generally used to store base locations
3. **CX (CL, CH)** : Acts as a counter in loops
4. **DX (DL, DH)** : Generally used to contain I/O port addresses

- **Segment registers**

The pointers will always store some address or memory location. In **8086 Microprocessor**, they usually store the offset through which the actual address is calculated.

1. **CS (Code Segment)**: The user cannot modify the content of these registers. Only the microprocessor's compiler can do this.
2. **DS (Data Segment)**: The user can modify the content of the data segment.
3. **SS (Stack Segment)**: The SS is used to store the information about the memory segment.

The operations of the SS are mainly Push and Pop.

4. **ES (Extra Segment)**: By default, the control of the compiler remains in the DS where the user can add and modify the instructions. If there is less space in that segment, then ES is used. ES is also used for copying purpose.

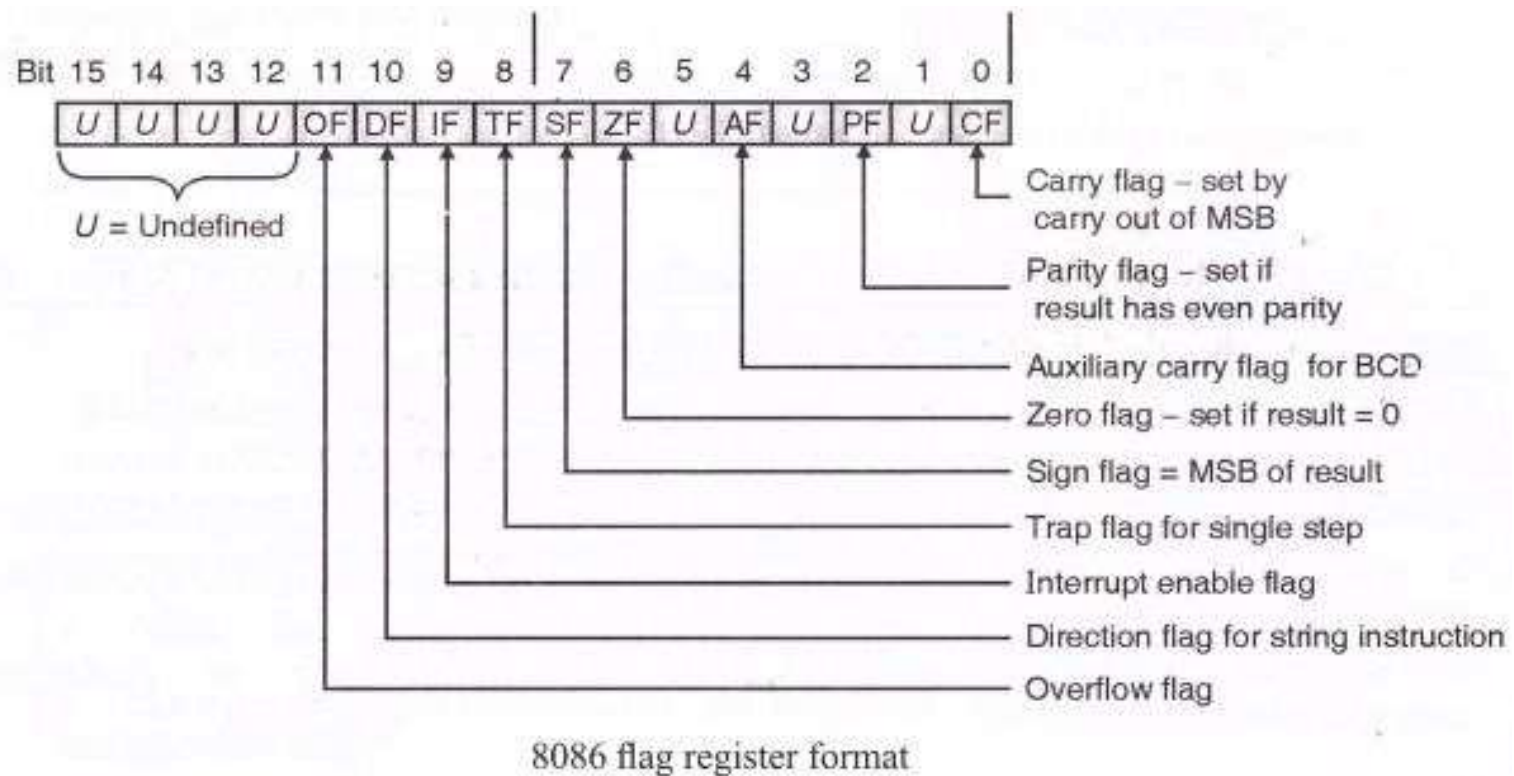
- **Pointers and Index Registers**

The pointers will always store some address or memory location. In **8086 Microprocessor**, they usually store the offset through which the actual address is calculated.

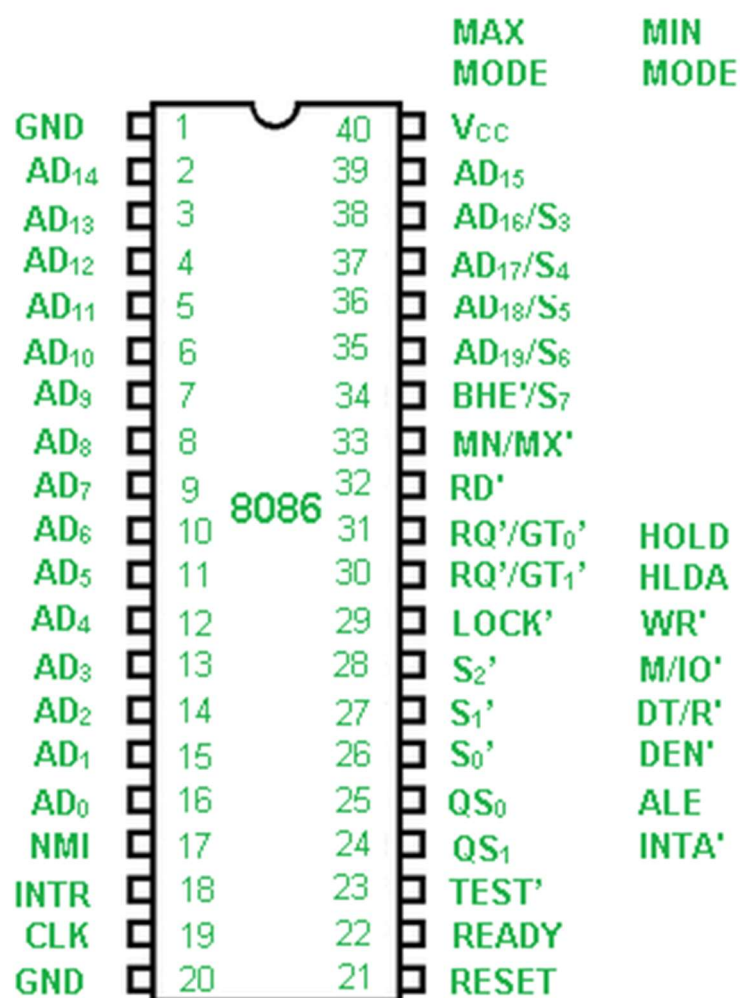
1. **SP**: This is the stack pointer. It is of 16 bits. It points to the topmost item of the stack. If the stack is empty the stack pointer will be (FFFE)H. It's offset address relative to stack segment
2. **BP**: This is the base pointer. It is of 16 bits. It is primary used in accessing parameters passed by the stack. It's offset address relative to stack segment.
3. **SI**: This is the source index register. It is of 16 bits. It is used in the pointer addressing of data and as a source in some string related operations. It's offset is relative to data segment.
4. **DI**: This is the destination index register. It is of 16 bits. It is used in the pointer addressing of data and as a destination in some string related operations. It's offset is relative to extra segment.

• Flag or Status Registers

The Flag or Status register is a 16-bit register which contains 9 flags, and the remaining 7 bits are idle in this register. These flags tell about the status of the processor after any arithmetic or logical operation. If the flag value is 1, the flag is set, and if it is 0, it is said to be reset.



Pin Diagram of 8086 Microprocessor:



Signals:

Power supply and frequency signals

It uses 5V DC supply at V_{CC} pin 40, and uses ground at V_{SS} pin 1 and 20 for its operation.

Clock signal

Clock signal is provided through Pin-19. It provides timing to the processor for operations. Its frequency is different for different versions, i.e. 5MHz, 8MHz and 10MHz.

Address/data bus

AD0-AD15. These are 16 address/data bus. AD0-AD7 carries low order byte data and AD8AD15 carries higher order byte data. During the first clock cycle, it carries 16-bit address and after that it carries 16-bit data.

Address/status bus

A16-A19/S3-S6. These are the 4 address/status buses. During the first clock cycle, it carries 4-bit address and later it carries status signals.

S7/BHE

BHE stands for Bus High Enable. It is available at pin 34 and used to indicate the transfer of data using data bus D8-D15. This signal is low during the first clock cycle, thereafter it is active.

Read (\$\overline{RD}\$)

It is available at pin 32 and is used to read signal for Read operation.

Ready

It is available at pin 22. It is an acknowledgement signal from I/O devices that data is transferred. It is an active high signal. When it is high, it indicates that the device is ready to transfer data. When it is low, it indicates wait state.

RESET

It is available at pin 21 and is used to restart the execution. It causes the processor to immediately terminate its present activity. This signal is active high for the first 4 clock cycles to RESET the microprocessor.

INTR

It is available at pin 18. It is an interrupt request signal, which is sampled during the last clock cycle of each instruction to determine if the processor considered this as an interrupt or not.

NMI

It stands for non-maskable interrupt and is available at pin 17. It is an edge triggered input, which causes an interrupt request to the microprocessor.

\$\overline{TEST}\$

This signal is like wait state and is available at pin 23. When this signal is high, then the processor has to wait for IDLE state, else the execution continues.

MN/\$\overline{MX}\$

It stands for Minimum/Maximum and is available at pin 33. It indicates what mode the processor is to operate in; when it is high, it works in the minimum mode and vice-versa.

INTA

It is an interrupt acknowledgement signal and id available at pin 24. When the microprocessor receives this signal, it acknowledges the interrupt.

ALE

It stands for address enable latch and is available at pin 25. A positive pulse is generated each time the processor begins any operation. This signal indicates the availability of a valid address on the address/data lines.

DEN

It stands for Data Enable and is available at pin 26. It is used to enable Trans receiver 8286. The trans receiver is a device used to separate data from the address/data bus.

DT/R

It stands for Data Transmit/Receive signal and is available at pin 27. It decides the direction of data flow through the trans receiver. When it is high, data is transmitted out and vice-a-versa.

M/IO

This signal is used to distinguish between memory and I/O operations. When it is high, it indicates I/O operation and when it is low indicates the memory operation. It is available at pin 28.

WR

It stands for write signal and is available at pin 29. It is used to write the data into the memory or the output device depending on the status of M/IO signal.

HLDA

It stands for Hold Acknowledgement signal and is available at pin 30. This signal acknowledges the HOLD signal.

HOLD

This signal indicates to the processor that external devices are requesting to access the address/data buses. It is available at pin 31.

QS₁ and QS₀

These are queue status signals and are available at pin 24 and 25. These signals provide the status of instruction queue. Their conditions are shown in the following table –

QS ₀	QS ₁	Status
0	0	No operation

0	1	First byte of opcode from the queue
1	0	Empty the queue
1	1	Subsequent byte from the queue

S₀, S₁, S₂

These are the status signals that provide the status of operation, which is used by the Bus Controller 8288 to generate memory & I/O control signals. These are available at pin 26, 27, and 28. Following is the table showing their status –

S ₂	S ₁	S ₀	Status
0	0	0	Interrupt acknowledgement
0	0	1	I/O Read
0	1	0	I/O Write
0	1	1	Halt
1	0	0	Opcode fetch
1	0	1	Memory read
1	1	0	Memory write
1	1	1	Passive

LOCK

When this signal is active, it indicates to the other processors not to ask the CPU to leave the system bus. It is activated using the LOCK prefix on any instruction and is available at pin 29.

RQ/GT₁ and RQ/GT₀

These are the Request/Grant signals used by the other processors requesting the CPU to release the system bus. When the signal is received by CPU, then it sends acknowledgment. RQ/GT₀ has a higher priority than RQ/GT₁.

Instruction Set Of 8086:

1. Data Transfer Instructions

These instructions are used to transfer the data from the source operand to the destination operand. List of data transfer instructions:

Instruction to transfer a word

- **MOV** – Used to copy the byte or word from the provided source to the provided destination.
- **PPUSH** – Used to put a word at the top of the stack.
- **POP** – Used to get a word from the top of the stack to the provided location.
- **PUSHA** – Used to put all the registers into the stack.
- **POPA** – Used to get words from the stack to all registers.
- **XCHG** – Used to exchange the data from two locations.
- **XLAT** – Used to translate a byte in AL using a table in the memory.

Instructions to transfer the address

- **LEA** – Used to load the address of operand into the provided register.
- **LDS** – Used to load DS register and other provided register from the memory
- **LES** – Used to load ES register and other provided register from the memory.

Instructions for input and output port transfer

- **IN** – Used to read a byte or word from the provided port to the accumulator.
- **OUT** – Used to send out a byte or word from the accumulator to the provided port.

Instructions to transfer flag registers

- **LAHF** – Used to load AH with the low byte of the flag register.
- **SAHF** – Used to store AH register to low byte of the flag register.
- **PUSHF** – Used to copy the flag register at the top of the stack.
- **POPF** – Used to copy a word at the top of the stack to the flag register.

2. Arithmetic Instructions

These instructions are used to perform arithmetic operations like addition, subtraction, multiplication, division, etc.

Following is the list of instructions under this group –

Instructions to perform addition

- **ADD** – Used to add the provided byte to byte/word to word.
- **ADC** – Used to add with carry.
- **INC** – Used to increment the provided byte/word by 1.
- **AAA** – Used to adjust ASCII after addition.
- **DAA** – Used to adjust the decimal after the addition/subtraction operation.

Instructions to perform subtraction

- **SUB** – Used to subtract the byte from byte/word from word.
- **SBB** – Used to perform subtraction with borrow.
- **DEC** – Used to decrement the provided byte/word by 1.
- **NPG** – Used to negate each bit of the provided byte/word and add 1/2's complement.
- **CMP** – Used to compare 2 provided byte/word.
- **AAS** – Used to adjust ASCII codes after subtraction.
- **DAS** – Used to adjust decimal after subtraction.

Instruction to perform multiplication

- **MUL** – Used to multiply unsigned byte by byte/word by word.
- **IMUL** – Used to multiply signed byte by byte/word by word.
- **AAM** – Used to adjust ASCII codes after multiplication.

Instructions to perform division

- **DIV** – Used to divide the unsigned word by byte or unsigned double word by word.
- **IDIV** – Used to divide the signed word by byte or signed double word by word.
- **AAD** – Used to adjust ASCII codes after division.
- **CBW** – Used to fill the upper byte of the word with the copies of sign bit of the lower byte.
- **CWD** – Used to fill the upper word of the double word with the sign bit of the lower word.

3. Bit Manipulation Instructions

These instructions are used to perform operations where data bits are involved, i.e. operations like logical, shift, etc.

Following is the list of instructions under this group –

Instructions to perform logical operation

- **NOT** – Used to invert each bit of a byte or word.
- **AND** – Used for adding each bit in a byte/word with the corresponding bit in another byte/word.
- **OR** – Used to multiply each bit in a byte/word with the corresponding bit in another byte/word.
- **XOR** – Used to perform Exclusive-OR operation over each bit in a byte/word with the corresponding bit in another byte/word.
- **TEST** – Used to add operands to update flags, without affecting operands.

Instructions to perform shift operations

- **SHL/SAL** – Used to shift bits of a byte/word towards left and put zero(S) in LSBs.

- **SHR** – Used to shift bits of a byte/word towards the right and put zero(S) in MSBs.
- **SAR** – Used to shift bits of a byte/word towards the right and copy the old MSB into the new MSB.

Instructions to perform rotate operations

- **ROL** – Used to rotate bits of byte/word towards the left, i.e. MSB to LSB and to Carry Flag [CF].
- **ROR** – Used to rotate bits of byte/word towards the right, i.e. LSB to MSB and to Carry Flag [CF].
- **RCR** – Used to rotate bits of byte/word towards the right, i.e. LSB to CF and CF to MSB.
- **RCL** – Used to rotate bits of byte/word towards the left, i.e. MSB to CF and CF to LSB.

4. String Instructions

String is a group of bytes/words and their memory is always allocated in a sequential order.

Following is the list of instructions under this group –

- **REP** – Used to repeat the given instruction till CX ≠ 0.
- **REPE/REPZ** – Used to repeat the given instruction until CX = 0 or zero flag ZF = 1.
- **REPNE/REPNZ** – Used to repeat the given instruction until CX = 0 or zero flag ZF = 1.
- **MOVS/MOVSb/MOVSW** – Used to move the byte/word from one string to another.
- **COMS/COMPSb/COMPSW** – Used to compare two string bytes/words.
- **INS/INSB/INSW** – Used as an input string/byte/word from the I/O port to the provided memory location.
- **OUTS/OUTSB/OUTSW** – Used as an output string/byte/word from the provided memory location to the I/O port.
- **SCAS/SCASb/SCASW** – Used to scan a string and compare its byte with a byte in AL or string word with a word in AX.
- **LODS/LODSb/LODSW** – Used to store the string byte into AL or string word into AX.

5. Program Execution Transfer Instructions (Branch and Loop Instructions)

These instructions are used to transfer/branch the instructions during an execution. It includes the following instructions –

Instructions to transfer the instruction during an execution without any condition –

- **CALL** – Used to call a procedure and save their return address to the stack.
- **RET** – Used to return from the procedure to the main program.
- **JMP** – Used to jump to the provided address to proceed to the next instruction.

Instructions to transfer the instruction during an execution with some conditions –

- **JA/JNBE** – Used to jump if above/not below/equal instruction satisfies.
- **JAE/JNB** – Used to jump if above/not below instruction satisfies.
- **JBE/JNA** – Used to jump if below/equal/ not above instruction satisfies.
- **JC** – Used to jump if carry flag CF = 1
- **JE/JZ** – Used to jump if equal/zero flag ZF = 1
- **JG/JNLE** – Used to jump if greater/not less than/equal instruction satisfies.
- **JGE/JNL** – Used to jump if greater than/equal/not less than instruction satisfies.
- **JL/JNGE** – Used to jump if less than/not greater than/equal instruction satisfies.
- **JLE/JNG** – Used to jump if less than/equal/if not greater than instruction satisfies.
- **JNC** – Used to jump if no carry flag (CF = 0)
- **JNE/JNZ** – Used to jump if not equal/zero flag ZF = 0
- **JNO** – Used to jump if no overflow flag OF = 0
- **JNP/JPO** – Used to jump if not parity/parity odd PF = 0
- **JNS** – Used to jump if not sign SF = 0
- **JO** – Used to jump if overflow flag OF = 1
- **JP/JPE** – Used to jump if parity/parity even PF = 1
- **JS** – Used to jump if sign flag SF = 1

6. Processor Control Instructions

These instructions are used to control the processor action by setting/resetting the flag values.

Following are the instructions under this group –

- **STC** – Used to set carry flag CF to 1

- **CLC** – Used to clear/reset carry flag CF to 0
- **CMC** – Used to put complement at the state of carry flag CF.
- **STD** – Used to set the direction flag DF to 1
- **CLD** – Used to clear/reset the direction flag DF to 0
- **STI** – Used to set the interrupt enable flag to 1, i.e., enable INTR input.
- **CLI** – Used to clear the interrupt enable flag to 0, i.e., disable INTR input.

7. Iteration Control Instructions

These instructions are used to execute the given instructions for number of times. Following is the list of instructions under this group –

- **LOOP** – Used to loop a group of instructions until the condition satisfies, i.e., CX = 0
- **LOOPE/LOOPZ** – Used to loop a group of instructions till it satisfies ZF = 1 & CX = 0
- **LOOPNE/LOOPNZ** – Used to loop a group of instructions till it satisfies ZF = 0 & CX = 0
- **JCXZ** – Used to jump to the provided address if CX = 0

8. Interrupt Instructions

These instructions are used to call the interrupt during program execution.

- **INT** – Used to interrupt the program during execution and calling service specified.
- **INTO** – Used to interrupt the program during execution if OF = 1
- **IRET** – Used to return from interrupt service to the main program

Conclusion: Thus, we understood working, construction and use of 8086 microprocessor development board and stimulation software

Experiment No 2

Aim : 8086 Assembly language programming for Addition and subtraction of two 16 bit numbers

Requirement : Emu8086 (Assembler and Microprocessor emulator)

Theory :

1. Data transfer instructions

Data transfer instructions are used to transfer data from source operand to destination operand

MOV instruction

MOV instruction moves data from one location to another. It also has the widest variety of parameters; so the assembler programmer can use MOV effectively, the rest of the commands are easier to understand.

Format: `MOV destination, source`

Eg. `MOV AX,6`

2. Arithmetic instructions

a. ADD instruction

ADD adds the contents of the source to the destination. The source and destination may be either bytes or words but both operands must be the same type or the assembler will generate an error.

If the sum of the two numbers cannot fit in the destination, an extra bit is required and this is signalled by the ADD operation setting the carry flags (CF) to 1. If the sum fits without spillage, CF=0. Other registers can be affected by addition operations as well; ZF=0 if the sum is zero, SF=1 if the sum is negative, etc. The logic of the basic addition command is:

Format: `ADD destination, source`

Logically, $\text{destination} = \text{destination} + \text{source}$

Eg. `ADD AX,BX`

b. SUB instruction

SUB subtracts the source value from the destination. Operation is almost identical to addition, except that the CF flag is used as a borrow in the case of the SBB (subtract with borrow) instruction.

Format: `SUB destination, source`

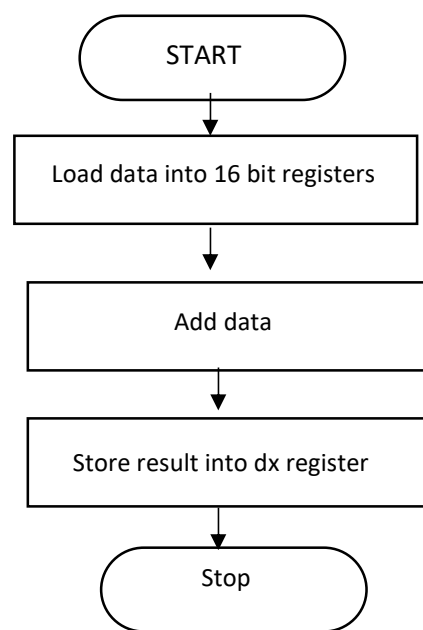
Logically, it is $\text{destination} = \text{destination} - \text{source}$

$\text{destination} = \text{destination} - \text{source} - \text{carry (if required)}$

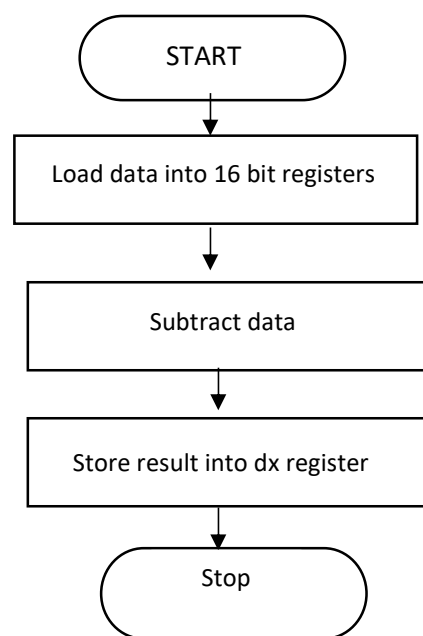
Eg. `SUB AX,BX`

Flowchart :

Flowchart for 16 bit numbers addition



Flowchart for 16 bit numbers subtraction



16 Bit Addition :

Program:

```
data segment
a dw 4121h
b dw 1742h
c dw ?
data ends

code segment
    assume cs:code,ds:data

start:
    mov ax,data
    mov ds,ax
    mov ax,a
    mov bx,b
    add ax,bx
    mov cx,ax
    mov c,cx
    int 3
    code ends

end start
```

MEMORY LOCATION	OP-CODE	LABEL	MNEMOIC
07110H	B8		mov ax,data
07111H	10		
07112H	07		
07113H	8E		mov ds,ax
07114H	D8		
07115H	A1		mov ax,a
07116H	00		
07117H	00		mov bx,b
07118H	8B		
07119H	1E		
0711AH	02		
0711BH	00		add ax,bx
0711CH	03		
0711DH	C3		
0711EH	8B		mov cx,ax
0711FH	C8		
07120H	89		mov c,cx
07121H	0E		
07122H	04		
07123H	00		
07124H	CC		int 3

16 Bit Subtraction :

Program:

```
data segment
    a dw 21A6h
    b dw 1022h
    c dw ?
data ends

code segment
    assume cs:code,ds:data

start:

    mov ax,data
    mov ds,ax

    mov ax,a
    mov bx,b

    sub ax,bx

    mov cx,ax
    mov c,cx

    int 3

    code ends

end start
```

MEMORY LOCATION	OP-CODE	LABEL	MNEMOIC
07110H	B8		mov ax,data
07111H	10		
07112H	07		

07113H	8E		mov ds,ax
07114H	D8		
07115H	A1		mov ax,a
07116H	00		
07117H	00		
07118H	8B		mov bx,b
07119H	1E		
0711AH	02		
0711BH	00		
0711CH	2B		sub ax,bx
0711DH	C3		
0711EH	8B		mov cx,ax
0711FH	C8		
07120H	89		mov c,cx
07121H	0E		
07122H	04		
07123H	00		
07124H	CC		int 3

Result :

Output OF 16 BIT ADDITION :

INPUT		OUTPUT	
REGISTER	DATA	REGISTER	DATA
AX	4121	CX	5863
BX	1742		

Affected flags: Parity flag

Output OF 16 BIT SUNTRACTION :

INPUT		OUTPUT	
REGISTER	DATA	REGISTER	DATA
AX	21A6	CX	1184
BX	1022		

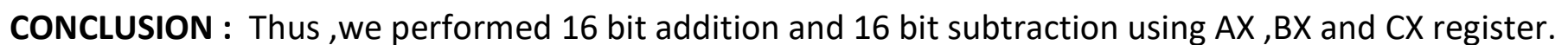
Affected flags: Parity flag

16 Bit Addition :

 emu8086 - assembler and microprocessor emulator 4.08



emu8086 - assembler and microprocessor emulator 4.08



CONCLUSION : Thus ,we performed 16 bit addition and 16 bit subtraction using AX ,BX and CX register.

Experiment No 3

Aim : 8086 Assembly language programming for Addition of series of 16 bit numbers

Requirement : Emu8086 (Assembler and Microprocessor emulator)

Theory :

1. Data transfer instructions

Data transfer instructions are used to transfer data from source operand to destination operand

a. MOV instruction

MOV instruction moves data from one location to another. It also has the widest variety of parameters; so if the assembler programmer can use MOV effectively, the rest of the commands are easier to understand.

Format: `MOV destination, source`

Eg. `MOV AX,6`

b. LEA instruction

LEA instruction determines the offset of the variable or memory location named as the source and puts this offset in the indicated 16-bit register. LEA does not affect any flag.

Syntax : `LEA Register, Source`

Example : `LEA AX,14`

2. Arithmetic instructions

a. ADD instruction

ADD adds the contents of the source to the destination. The source and destination may be either bytes or words but both operands must be the same type or the assembler will generate an error.

If the sum of the two numbers cannot fit in the destination, an extra bit is required and this is signalled by the ADD operation setting the carry flags (CF) to 1. If the sum fits without spillage, CF=0. Other registers can be affected by addition operations as well; ZF=0 if the sum is zero, SF=1 if the sum is negative, etc. The logic of the basic addition command is:

Format: **ADD** `destination, source`

Logically, $\text{destination} = \text{destination} + \text{source}$

Eg. `ADD AX,BX`

b. DEC instruction

DEC instruction subtracts 1 from the destination word or byte. The destination can be a register or a memory location. AF, OF, SF, PF, and ZF are updated, but CF is not affected. This means that if an 8-bit destination containing 00H or a 16-bit destination containing 0000H is decremented, the result will be FFH or FFFFH with no carry (borrow).

Syntax : `DEC Destination`

Example : `DEC AX`

3. Logical instructions

CMP instruction

This instruction comes under **Logical Instruction**. This instruction compares a byte / word in the specified source with a byte / word in the specified destination. The source can be an immediate number, a register, or a memory location. The destination can be a register or a memory location. However, the source and the destination cannot both be memory locations. The comparison is actually done by subtracting the source byte or word from the destination

byte or word. The source and the destination are not changed, but the flags are set to indicate the results of the comparison. AF, OF, SF, ZF, PF, and CF are updated by the CMP instruction. For the instruction CMP CX, BX, the values of CF, ZF, and SF will be as follows:

Syntax : CMP Destination, Source

Example : CMP AL, 01H

4. Transfer Of Control Instruction

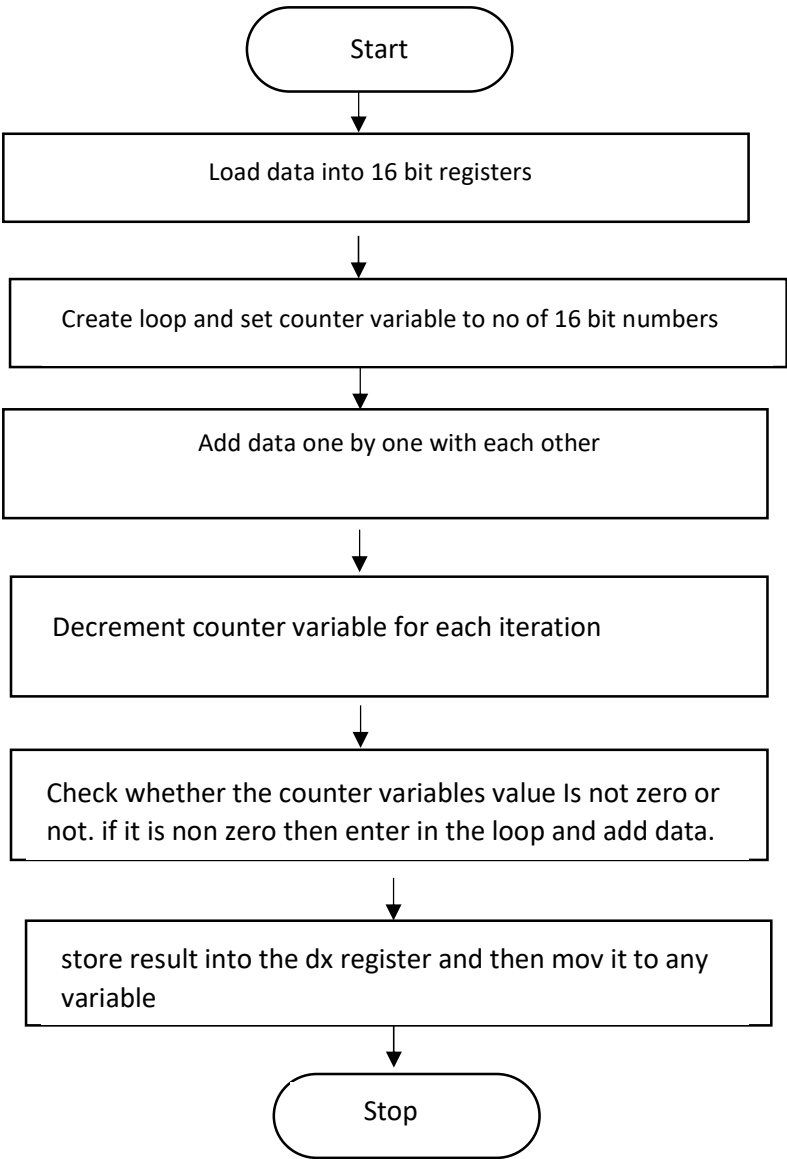
JNZ instruction

This instruction comes under **Transfer Of Control Instruction**. This instruction is usually used after a Compare instruction. If the zero flag is 0, then this instruction will cause a jump to the label given in the instruction.

Example :

```
ADD AX, 0002H
DEC BX
JNZ NEXT
```

Flowchart :



Program :

data segment

```
a dw 4200h, 5300h, 1600h, 8000h, 1900h
b dw ?
data ends
```

code segment

```
assume cs:code,ds:data

start:
mov ax,data
mov ds,ax
mov cl,5
lea bx,a
mov ax,00
```

```
OP: add ax,word ptr[bx]

add bx,02
dec cl
cmp cl,00
jnz OP
```

```
mov b,ax
int 3
code ends
```

end start

MEMORY LOCATION	OP-CODE	LABEL	MNEMOIC
07110h 07111h 07112h	B8		mov ax,data
07113h 07114h	8E D8		mov ds,ax
07115h 07116h	B1 05		mov cl,5
07117h 07118h 07119h	BB 00 00		lea bx,a
0711Ah 0711Bh 0711Ch	B8 00 00		mov ax,00
0711Dh 0711Eh	03 07	OP:	add ax,word ptr[bx]
0711Fh 07120h 07121h	83 C3 02		add bx,02
07122h 07123h	FE C9		dec cl
07124h 07125h 07126h	80 F9 00		cmp cl,00

07127h 07128h	75 F4		jnz OP
07129h 0712Ah 0712Bh	A3 0A 00		mov b,ax
0712Ch	CC		int 3

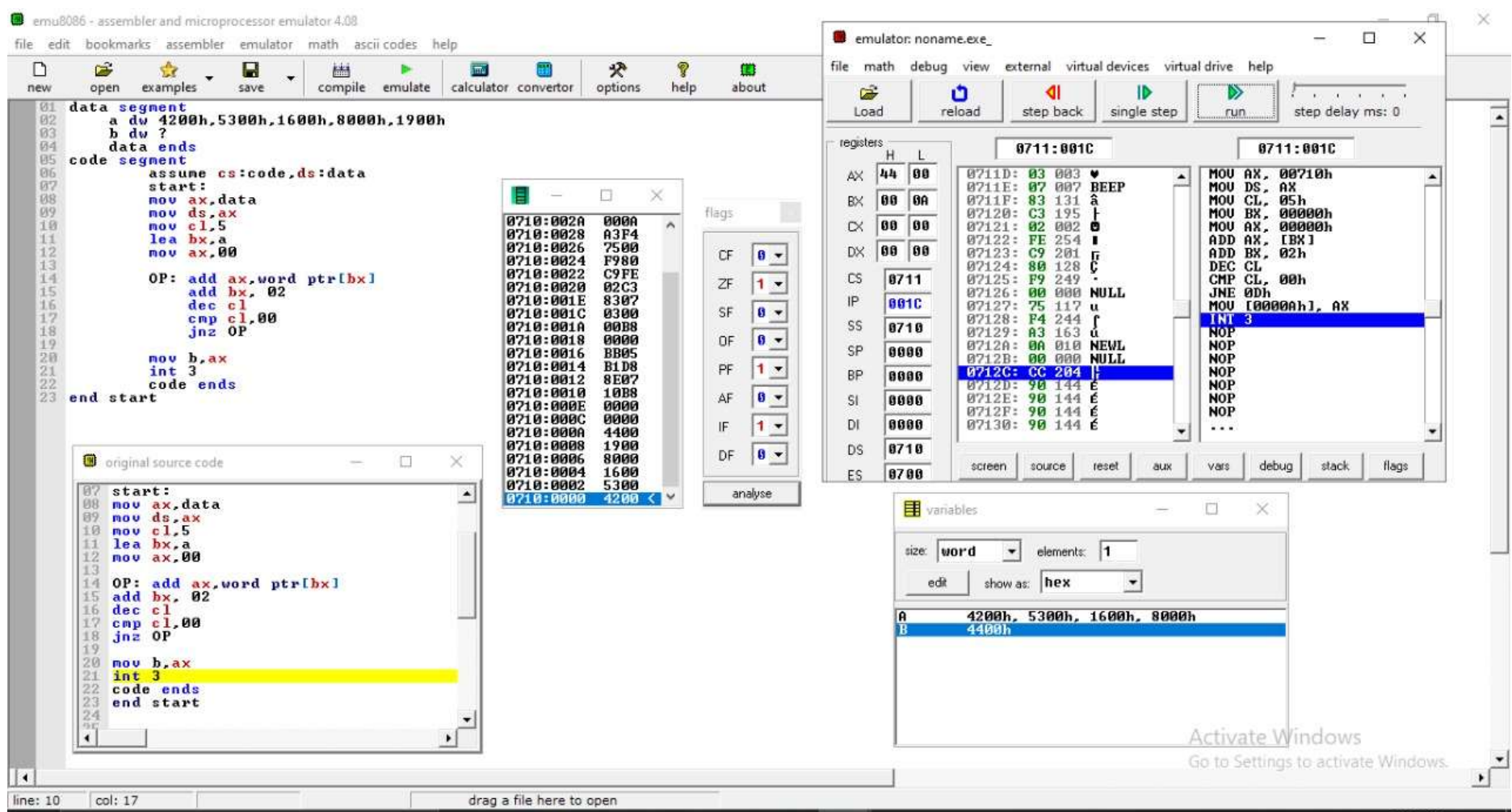
Result :

Output OF 16 BIT ADDITION :

INPUT		OUTPUT	
REGISTER	DATA	REGISTER	DATA
AX	4200h, 5300h, 1600h, 8000h, 1900h	AX	4400h

Affected flags: Parity flag, Zero flag, Interrupt enable flag

SCREENSHOT :



Conclusion: Thus, we understood and performed addition of series of 16 bit numbers.

Experiment No 4

Aim : 8086 Assembly language programming for multibyte addition of two numbers

Requirement : Emu8086 (Assembler and Microprocessor emulator)

Theory :

1. Data transfer instructions

Data transfer instructions are used to transfer data from source operand to destination operand

a. MOV instruction

MOV instruction moves data from one location to another. It also has the widest variety of parameters; so if the assembler programmer can use MOV effectively, the rest of the commands are easier to understand.

Format: `MOV destination, source`

Eg. `MOV AX,6`

2. Arithmetic instructions

a. ADD instruction

ADD adds the contents of the source to the destination. The source and destination may be either bytes or words but both operands must be the same type or the assembler will generate an error.

If the sum of the two numbers cannot fit in the destination, an extra bit is required and this is signalled by the ADD operation setting the carry flags (CF) to 1. If the sum fits without spillage, CF=0. Other registers can be affected by addition operations as well; ZF=0 if the sum is zero, SF=1 if the sum is negative, etc. The logic of the basic addition command is:

Format: **ADD** `destination, source`

Logically, $\text{destination} = \text{destination} + \text{source}$

Eg. `ADD AX,BX`

b. ADC instruction

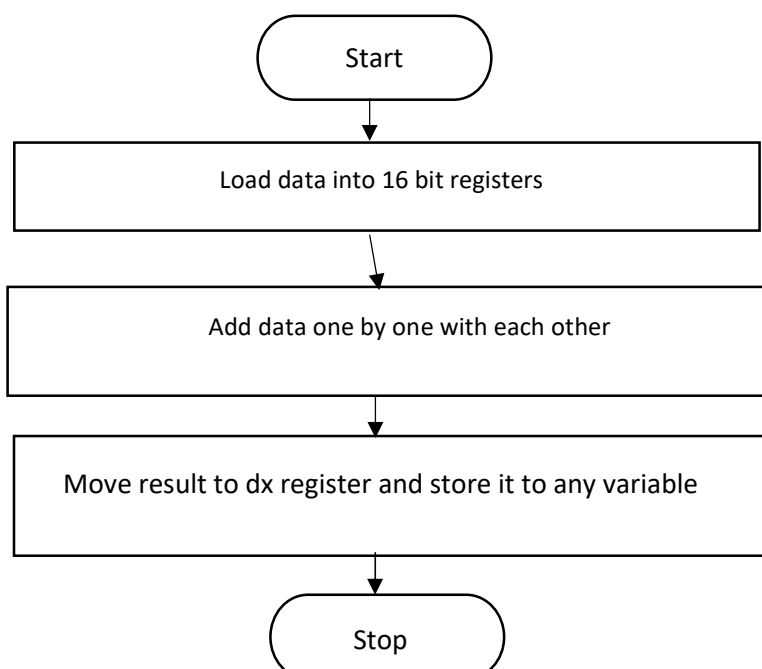
ADC instructions add a number from some source to a number in specified destination and put result in destination like ADD instruction. It also adds the carry flag value 0 or 1 to the result, hence called Add with carry

Syntax : `ADC Destination, Source`

Logically, $\text{destination} = \text{destination} + \text{source} + \text{CF}$

Example : `ADC BX, AX`

Flowchart:



Program:

data segment

a dw 4200h

b dw 5300h

c dw 1600h

d dw 8000h

p dw ?

data ends

code segment

assume cs:code,ds:data

start:

mov ax,data

mov ds,ax

mov ax,a

mov bx,b

mov cx,c

mov dx,d

add ax,bx

adc ax,cx

adc ax,dx

mov p,ax

int 3

code ends

end start

MEMORY LOCATION	OP-CODE	LABEL	MNEMOIC
7110h 7111h 7112h	B8 10 07		mov ax,data
7113h 7114h	8E D8		mov ds,ax
7115h 7116h 7117h	A1 00 00		mov ax,a
7118h 7119h 711Ah 711Bh	8B 1E 02 00		mov bx,b

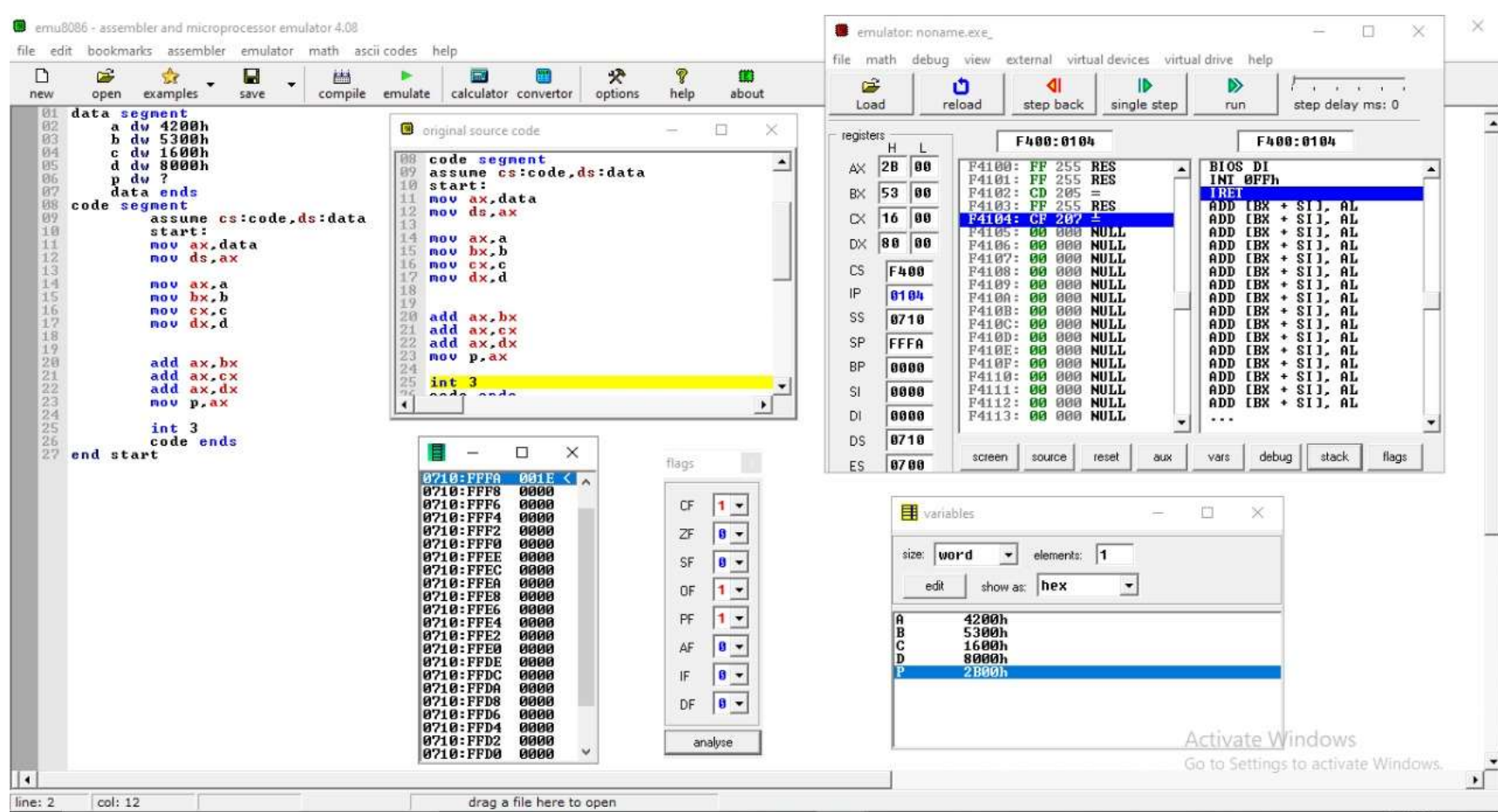
711Ch 711Dh 711Eh 711Fh	8B 0E 04 00		mov cx,c
7120h 7121h 7122h 7123h	8B 16 06 00		mov dx,d
7124h	03		add ax,bx
7126h 7127h	13 C1		adc ax,cx
7128h 7129h	13 C2		adc ax,dx
712Ah 712Bh 712Ch	A3 08 00		mov p, ax
712Dh	CC		int 3

Result:

INPUT		OUTPUT	
REGISTER	DATA	REGISTER	DATA
AX	4200h	AX	2B00h
BX	5300h		
CX	1600h		
DX	0000h		

Affected flag : Parity flag, Carry flag, Overflow flag

Output:



Conclusion: Thus, we performed and understood multibyte addition of 2 numbers.

Experiment No 5

Aim : 8086 Assembly language programming for multiplication of two 16 bit signed and unsigned numbers

Requirement : Emu8086 (Assembler and Microprocessor emulator)

Theory :

1. Data transfer instructions

Data transfer instructions are used to transfer data from source operand to destination operand

a. MOV instruction

MOV instruction moves data from one location to another. It also has the widest variety of parameters; so if the assembler programmer can use MOV effectively, the rest of the commands are easier to understand.

Format: MOV destination, source

Eg. MOV AX,6

2. Arithmetic instructions

- a. **MUL :** - MUL is used to multiply an unsigned byte in some source with an unsigned byte in AL register or an unsigned word in some source with an unsigned word in AX register.

Flags affected : CF, OF

Syntax : - MUL source

Example : - MUL BH

- b. **IMUL :** - IMUL is used to multiply a signed byte from source with a signed byte in AL or a signed word from some source with a signed word in AX.

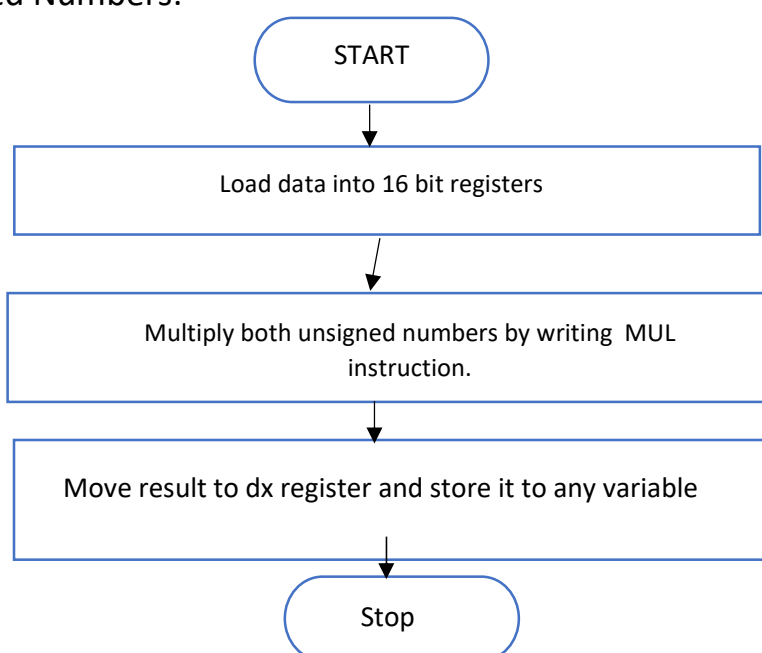
Flags affected : CF, OF

Syntax : - MUL source

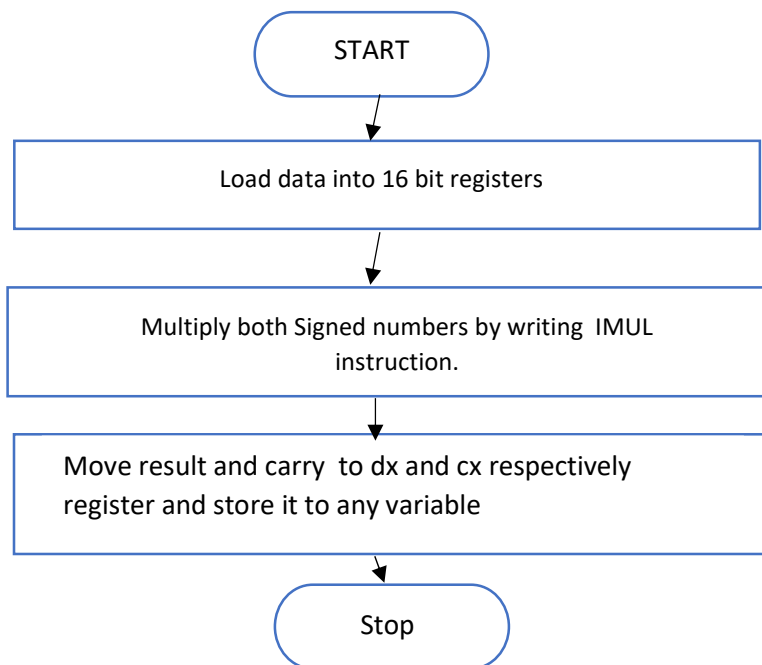
Example : - IMUL BH

Flowchart:

1. Unsigned Numbers:



2. Signed Numbers:



Programs:

Unsigned multiplication

data segment

a dw 2342h

b dw 3312h

c dw ?

d dw ?

data ends

code segment

assume cs: code, ds:data

start:

mov ax, data

mov ds, ax

mov ax, a

mov bx, b

mul bx

mov c, dx

mov d, ax

int 3

code ends

end start

MEMORY LOCATION	OP-CODE	LABEL	MNEMONIC
07110h 07111h 07112h	B8 10 07	-	MOV AX, DATA
07113h 07114h	8E D8	-	MOV DS, AX
07115h 07116h 07117h	A1 00 00	-	MOV AX, A
07118h 07119h 0711Ah 0711Bh	8B 1E 02 00	-	MOV BX, B
0711Ch 0711Dh	F7 E3	-	MUL BX
0711E 0711Fh 07120h 07121h	89 16 04 00	-	MOV C, DX
07122h 07123h 07124h	A3 06 00	-	MOV D, AX
07125h	CC		INT 3

Input		Output	
Register	Data	Register	Data
AX	2342h	DX	0A04h
BX	3312h	AX	0708h

Flags Affected : Carry Flag, Overflow flag, Interrupt Flag

Signed multiplication

data segment

a dw 2342h

b dw 00d2h

c dw ?

d dw ?

data ends

code segment

assume cs: code, ds:data

start:

mov ax, data

mov ds, ax

mov ax, a

mov bx, b

imul bx


```

mov c, dx
mov d, ax
int 3
code ends
end start

```

MEMORY LOCATION	OP-CODE	LABEL	MNEMONIC
07110h 07111h 07112h	B8 10 07	-	MOV AX, DATA
07113h 07114h	8E D8	-	MOV DS, AX
07115h 07116h 07117h	A1 00 00	-	MOV AX, A
07118h 07119h 0711Ah 0711Bh	8B 1E 02 00	-	MOV BX, B
0711Ch 0711Dh	F7 EB	-	IMUL BX
0711Eh 0711Fh 07120h 07121h	89 16 04 00	-	MOV C, DX
07122h 07123h 07124h	A3 06 00	-	MOV D, AX
07125h	CC	-	Int 3

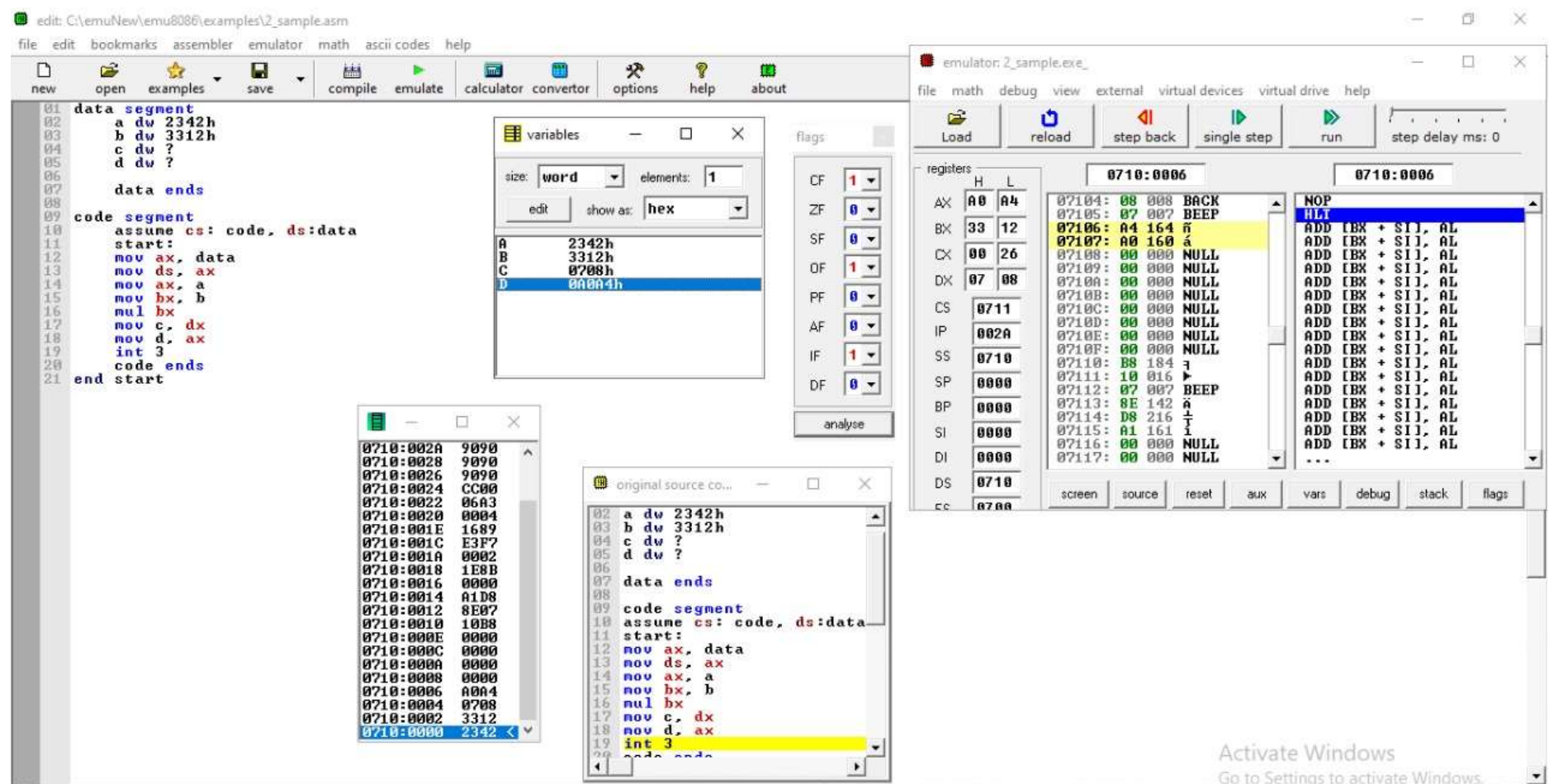
Result:

Input		Output	
Register	Data	Register	Data
AX	2342h	DX	001Ch
BX	00D2h	AX	EC24h

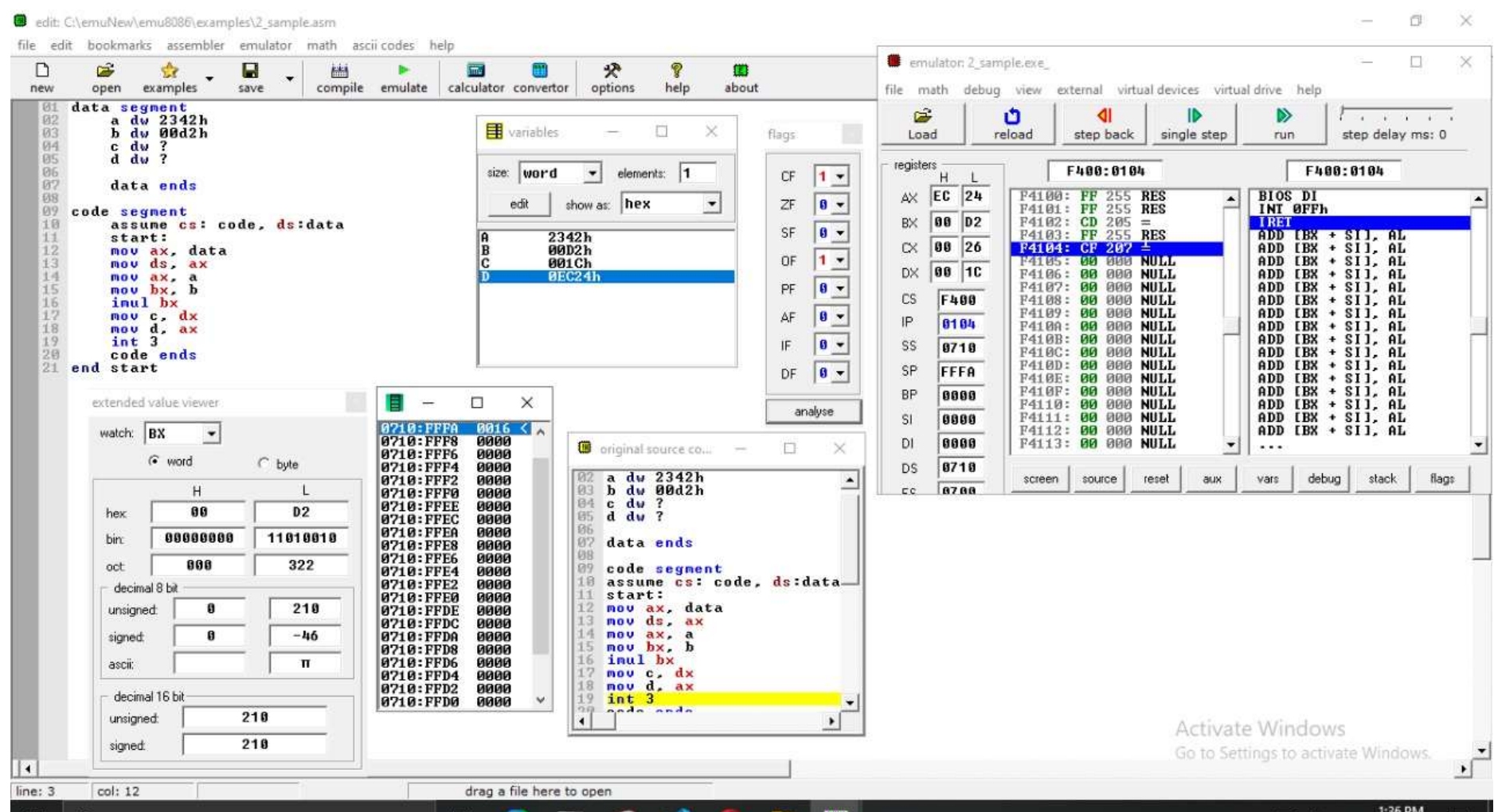
Flags Affected : Carry flag, Overflow flag

Screenshots:

Unsigned multiplication:



Signed multiplication:



Conclusion: Thus we performed and understood multiplication of signed and unsigned 16 bit numbers

Experiment No 6

Aim : 8086 Assembly language programming for multiplication of two 16 bit signed and unsigned numbers

Requirement : Emu8086 (Assembler and Microprocessor emulator)

Theory :

1. Data transfer instructions

Data transfer instructions are used to transfer data from source operand to destination operand

a. MOV instruction

MOV instruction moves data from one location to another. It also has the widest variety of parameters; so if the assembler programmer can use MOV effectively, the rest of the commands are easier to understand.

Format: MOV destination, source

Eg. MOV AX,6

2. Arithmetic instructions

- a. **DIV :** - DIV instruction is used to divide an *unsigned* word by a byte or to divide an *unsigned* double word (32 bits) by a word. When a word is divided by a byte, the word must be in the AX register.

Flags affected :- All of the arithmetic status flags are undefined after the operation.

Syntax : - MUL source

Example : - MUL BH

- b. **IDIV:-** This instruction is used to divide a *signed* word by a *signed* byte, or to divide a *signed* double word by a *signed* word. When dividing a signed word by a signed byte, the word must be in the AX register

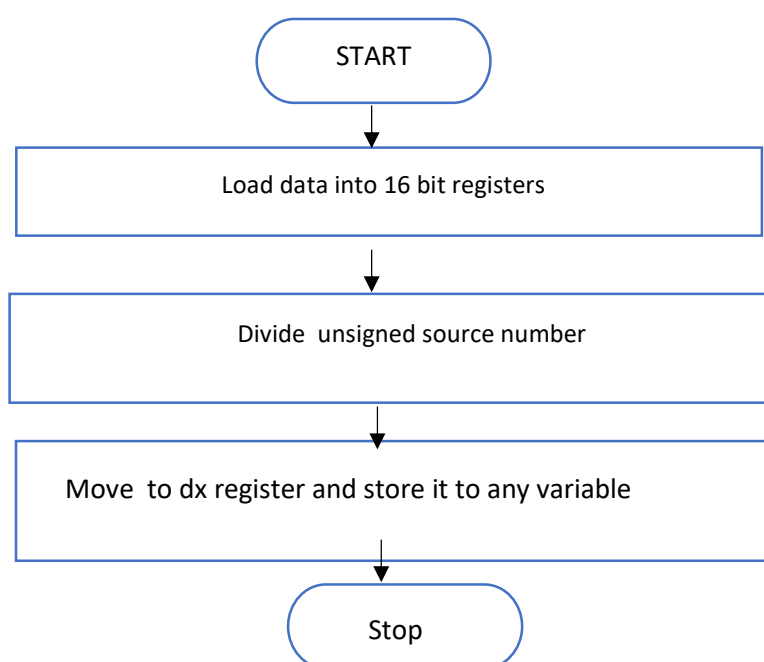
Flags affected :- All of the arithmetic status flags are undefined after the operation.

Syntax :- IDIV source

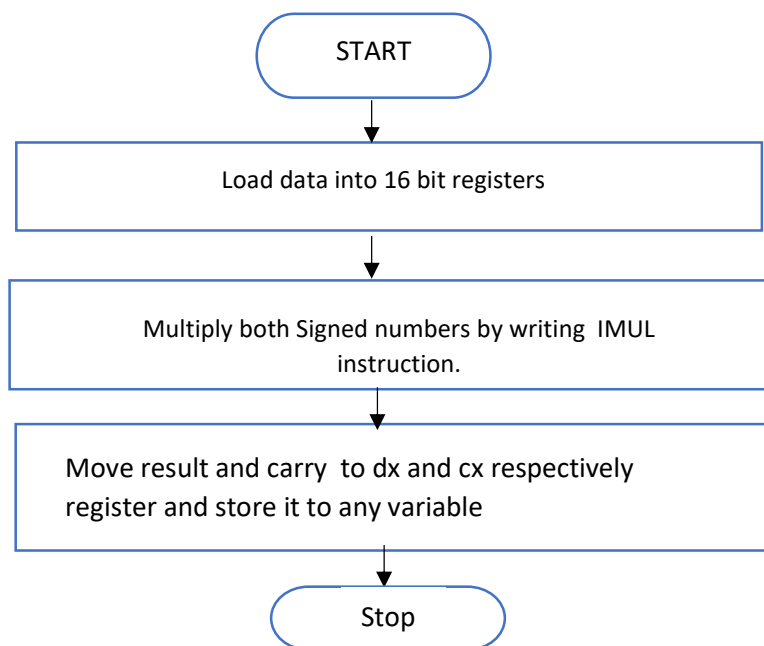
Example:- IDIV BL

Flowchart:

Unsigned division



Signed division:



Program:

data segment

a dw 4235h

b dw 2264h

c dw ?

d dw ?

data ends

code segment

assume cs:code ds:data

start:

mov ax,data

mov ds,ax

mov ax,a

mov bx,b

div bx

mov cx,ax

mov c,cx

mov d,dx

int 3

code ends

end start

Unsigned division

MEMORY LOCATION	OP-CODE	LABEL	MNEMONIC
7110h 7111h 7112h	B8 10 07	-	MOV AX, DATA
7113h 7114h	8E D8	-	MOV DS, AX
7115h 7116hh 7117h	A1 00 00	-	MOV AX, A
7118h 7119h 711Ah 711Bh	8B 1E 02 00	-	MOV BX, B
711Ch 711Dh	F7 FB	-	DIV BX
711Eh 711Fh	8B C8	-	MOV CX, AX
7120hh 7121h 7122h 7123h	89 0E 04 00	-	MOV C, CX
7124h 7125h 7126h 7127h	89 16 06 00	-	MOV D, DX
7128h	CC		Int 3

Result:

Input		Output	
Register	Data	Register	Data
AX	000Ah	CX	0003h
BX	0003h	DX	0001h

Flags Affected : Interrupt Flag

Signed division

MEMORY LOCATION	OP-CODE	LABEL	MNEMONIC
7110h 7111h 7112h	B8 10 07	-	MOV AX, DATA
7113h 7114h	8E D8	-	MOV DS, AX
7115h 7116h 7117h	A1 00 00	-	MOV AX, A
7118h 7119h 711Ah 711Bh	8B 1E 02 00	-	MOV BX, B
711Ch 711Dh	F7 FB	-	IDIV BX
711Eh 711Fhh	8B C8	-	MOV CX, AX
7120h 7121h 7122h 7123h	89 0E 04 00	-	MOV C, CX
7124h 7125h 7126h 7127h	89 16 06 00	-	MOV D, DX

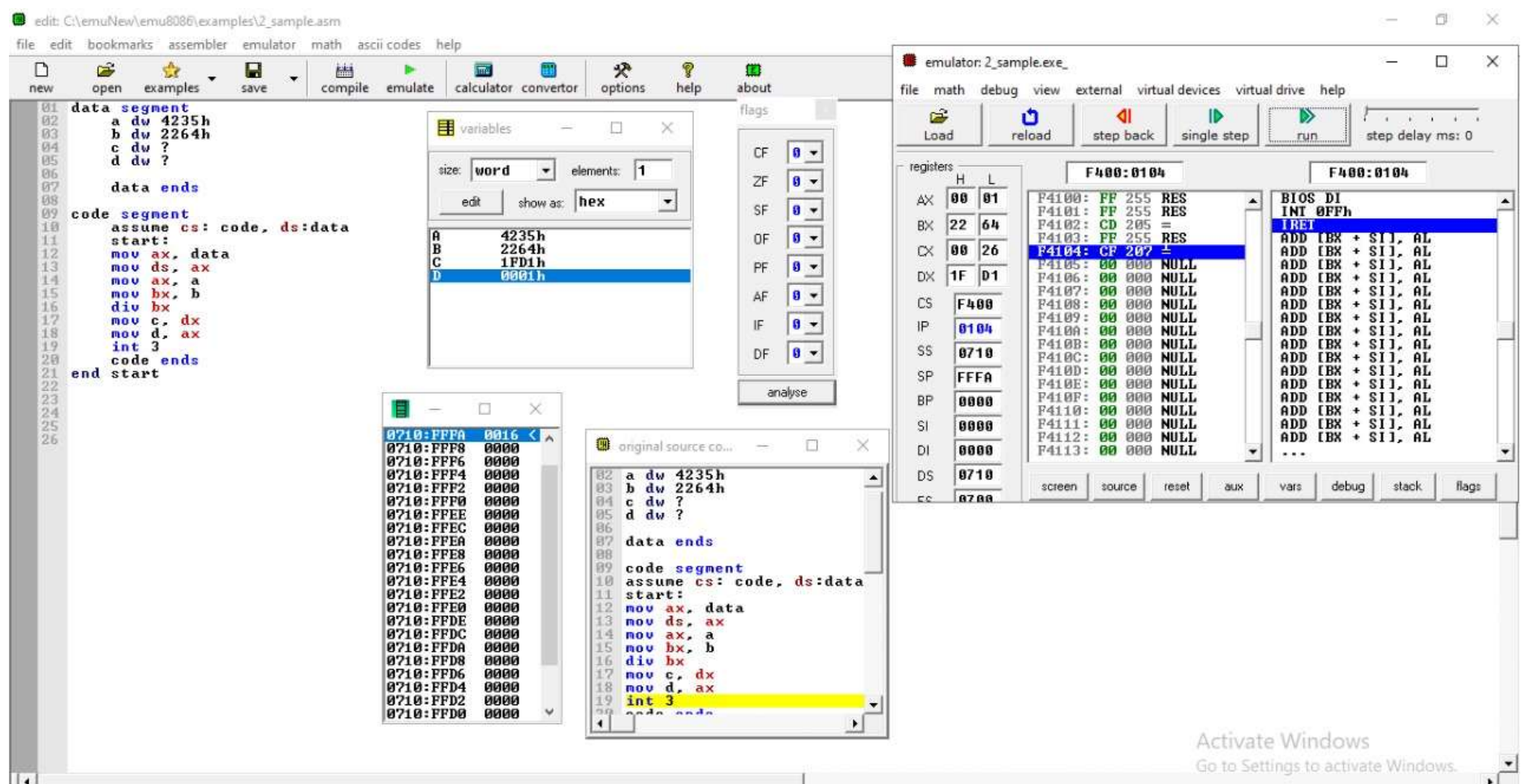
Result :

Input		Output	
Register	Data	Register	Data
AX	00F6h	CX	0052h
BX	0003h	DX	0000h

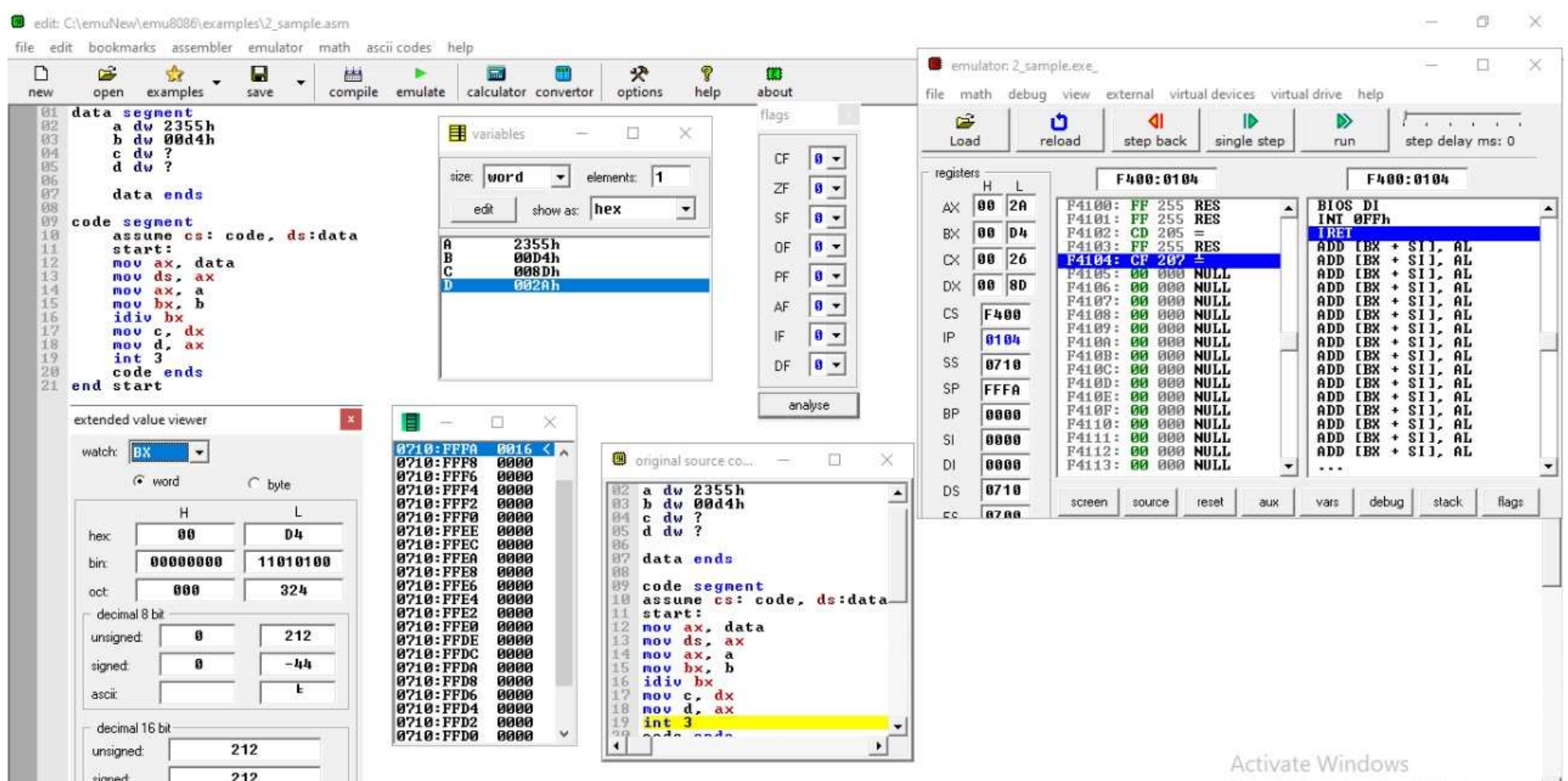
Flags Affected : Interrupt Flag

Output:

Unsigned division:



Signed division:



Conclusion: - Thus we have understood 8086 Assembly language programming for division of two 16 bit signed and unsigned numbers.

Experiment no. 7

Aim: 8086 Assembly language programming for arranging 16 bit numbers in ascending order.

Requirements: 8086 microprocessor kit/MASM ----1 2.RPS (+5V) ----1,]and Emu8086 Emulator

Theory:

Data Transfer Instructions : -

- 1) **MOV** :- MOV instruction is used to transfer byte or word from register to register, memory to register, register to memory or with immediate addressing.
Flags affected :- None
Syntax :- MOV destination, source
Example :- MOV AX,00F4H
- 2) **XCHG** :- The XCHG instruction exchanges the content of a register with the content of another register. It cannot directly exchange the content of two memory locations.
Flags affected :- None
Syntax :- XCHG Destination, Source
Example :- XCHG AX, DX
- 3) **LEA** :- LEA instruction computes the effective address of the second operand (source operand) and stores it in the first operand (destination operand).
Flags affected :- None
Syntax :- LEA destination, source
Example :- LEA AX, BX

Arithmetic Instructions : -

- 4) **ADD** :- ADD instruction is used to add the current contents of destination with that of source and store the result in destination.
Flags affected :- AF, CF, OF, PF, SF and ZF
Syntax :- ADD destination, source
Example :- ADD AL,0FH
- 5) **DEC** :- DEC instruction is used to decrement the content of the specified destination by one.
Flags affected :- AF, CF, OF, PF, SF and ZF
Syntax :- DEC destination, source
Example :- DEC AX
- 6) **CMP** :- CMP instruction is used to compare the source operand, which maybe a register or an immediate data or a memory location, with a destination operand that may be a register or a memory location. For comparison, it subtracts the source operand from the destination operand but does not store the result anywhere.
Flags affected :- The flags are affected depending upon the result of the subtraction.
If both of the operands are equal, then zero flag is affected.
If the source operand is greater than the destination operand, then carry flag is set or else, carry flag is reset.
Syntax :- CMP destination, source
Example :- CMP AX,BX

Transfer-Of-Control Instructions : -

- 7) **JC (JUMP IF CARRY)**:- If, after a compare or some other instructions which affect flags, the carry flag is a 1, this instruction will cause execution to jump to a label given in the instruction. If CF is 0, the instruction will have no effect on program execution.
Flags affected :- None

Syntax : - LOOP label

Example:- ADD BX, CX
JC NEXT
- 8) **JNZ** :- JNZ instruction is a conditional jump that follows a test. It jumps to the specified location if the Zero flag is cleared (0).

Flags affected :- None

Syntax :- JNZ location

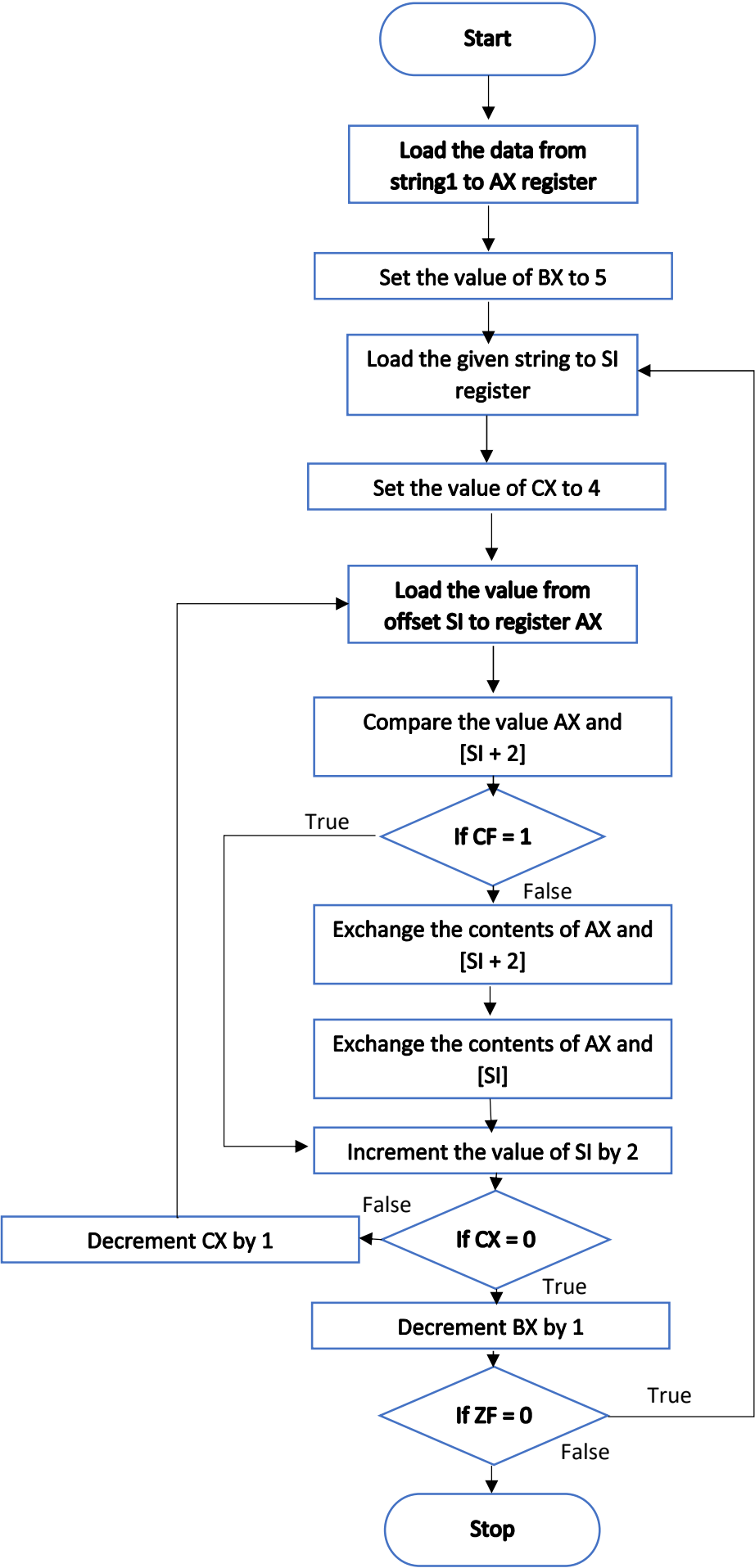
Example :- JNZ 4000

9) **LOOP** :- This instruction is used to repeat a series of instructions some number of time.Loops through a sequence of instructions until CX=0
Flags affected :- None

Syntax : - LOOP label

Example :-
MOV BX, OFFSET PRICES
MOV CX, 40
NEXT: MOV AL, [BX]
INC AL
MOV [BX], AL
INC BX
LOOP NEXT

➤ **Flowchart :**



Code :

```
data segment
    string1 dw 14h,10h,5h,15h,21h
data ends

code segment
    assume cs:code,ds:data

    start:

    mov ax,data
    mov ds,ax

    mov bx,5

    up1: lea si,string1

    mov cx,4

    up: mov ax,[si]

    cmp ax,[si+2]

    jc down


    xchg ax,[si+2]

    xchg ax,[si]

    down: add si,2

    loop up

    dec bx

    jnz up1

    int 3

    code ends

end start
```

Program:

MEMORY LOCATION	OP-CODE	LABEL	MNEMONIC
07110h	B8		MOV AX, DATA
07111h	10		
07112hh	07		
07113h	8E		MOV DS, AX
07114h	D8		
07115h	BB		MOV BX, 5
07116h	05		
07117h	00		
07118h	BE	UP1	LEA SI, STRING1
07119h	00		
0711Ah	00		
0711Bh	B9		MOV CX, 4
0711Ch	04		
0711Dh	00		
0711Eh	8B	UP	MOV AX, [SI]
0711Fh	04		
07120h	3B		CMP AX, [SI + 2]
07121h	44		
07122h	02		
07123h	72		JC DOWN
07124h	05		

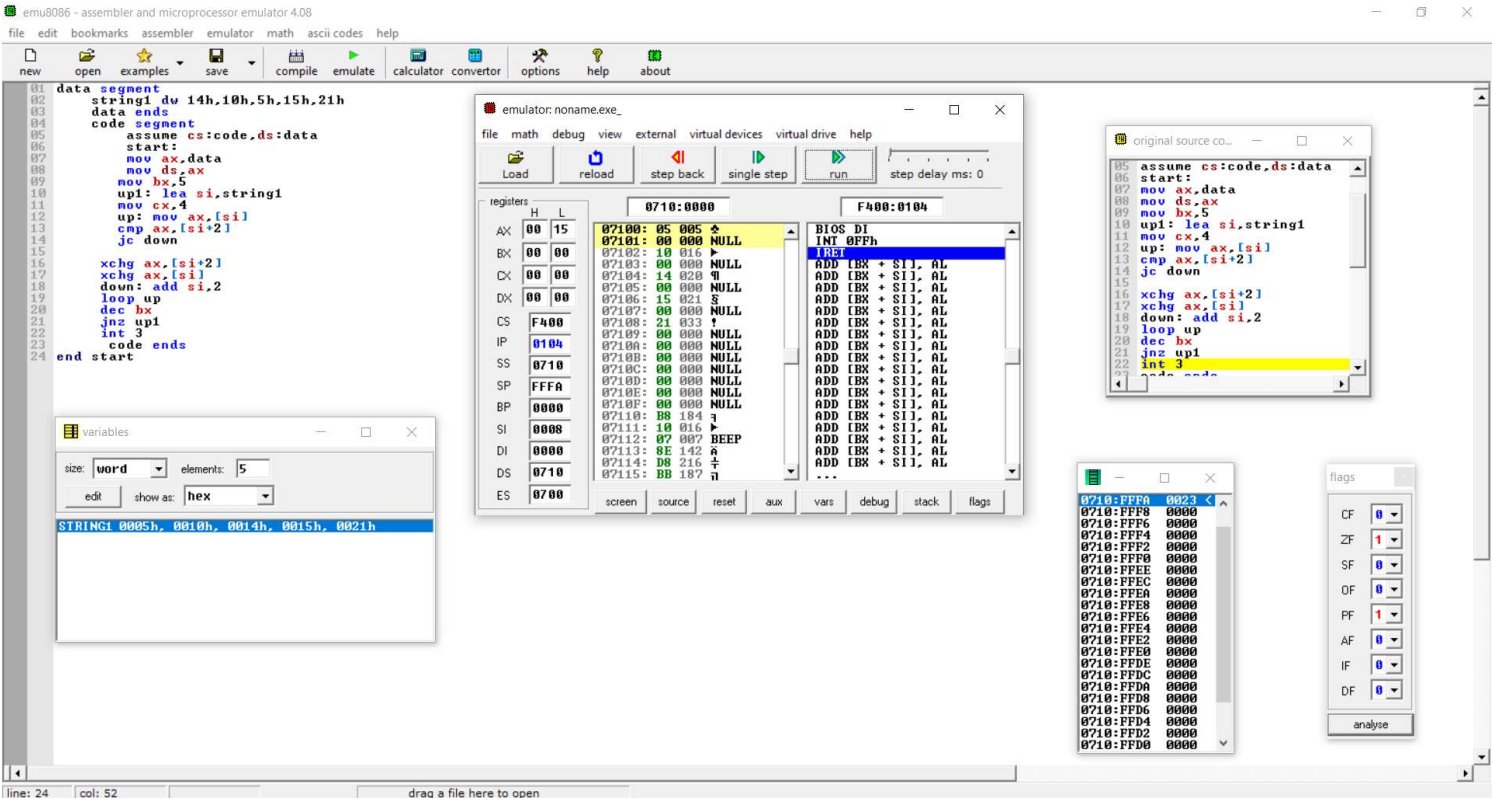
07125h	87		XCHG AX,
07126hh	44		[SI + 2]
07127h	02		
07128h	87		XCHG AX, [SI]
07129h	04		
0712Ah	83	DOWN	ADD SI, 2
0712Bh	C6		
0712Chh	02		
0712Dh	E2		LOOP UP
0712Eh	EF		
0712Fh	4B		DEC BX
07130h	75		JNZ UP1
07131h	E6		
07132h	CC		INT 3

Result:

Input		Output	
Register	Data	Register	Data
AX	0014h,0010h,0005h, 0015h,0021h	AX	0005h, 0010h, 0014h, 0015h, 0021h

Flag Affected : Parity flag, Zero flag

Screenshot:



Conclusion: Thus we have understood 8086 Assembly language programming for arranging 16 bit numbers in ascending order.

Experiment no. 8

Aim: 8086 Assembly language programming for arranging 16 bit numbers in descending order.

Requirements: 8086 microprocessor kit/MASM ----1 2.RPS (+5V) ----1,]and Emu8086 Emulator

Theory:

Data Transfer Instructions : -

- 1) **MOV** :- MOV instruction is used to transfer byte or word from register to register, memory to register, register to memory or with immediate addressing.
Flags affected :- None

Syntax :- MOV destination, source

Example :- MOV AX,BX
- 2) **LEA** :- LEA instruction computes the effective address of the second operand (source operand) and stores it in the first operand (destination operand).
Flags affected :- None

Syntax :- LEA destination, source

Example :- LEA AX, BX
- 3) **XCHG** :- The XCHG instruction exchanges the content of a register with the content of another register. It cannot directly exchange the content of two memory locations.
Flags affected :- None

Syntax :- XCHG Destination, Source

Example :- XCHG AX, DX

Arithmetic Instructions : -

- 4) **CMP** - CMP instruction is used to compare the source operand, which maybe a register or an immediate data or a memory location, with a destination operand that may be a register or a memory location. For comparison, it subtracts the source operand from the destination operand but does not store the result anywhere.
Flags affected :- The flags are affected depending upon the result of the subtraction.
If both of the operands are equal, then zero flag is affected.
If the source operand is greater than the destination operand, then carry flag is set or else, carry flag is reset.

Syntax :- CMP destination, source

Example :- CMP AX,B
- 5) **DEC** :- DEC instruction is used to decrement the content of the specified destination by one.
Flags affected :- AF, CF, OF, PF, SF and ZF

Syntax :- DEC destination

Example :- DEC AX
- 6) **ADD** :- ADD instruction is used to add the current contents of destination with that of source and store the result in destination.
Flags affected :- AF, CF, OF, PF, SF and ZF

Syntax :- ADD destination, source

Example :- ADD AL,0FH

Program Execution Transfer Instructions : -

- 7) **JNC** :- The JNC (Jump if No Carry) instruction transfers program control to the specified address if the carry flag is 0.
Flags affected :- None

Syntax :-

Example :- ADD AL, BL
JNC NEXT

- 8) **JNZ** :- JNZ instruction is a conditional jump that follows a test. It jumps to the specified location if the Zero flag is cleared (0).
Flags affected :- None

Syntax :- JNZ location

Example :- JNZ 4000

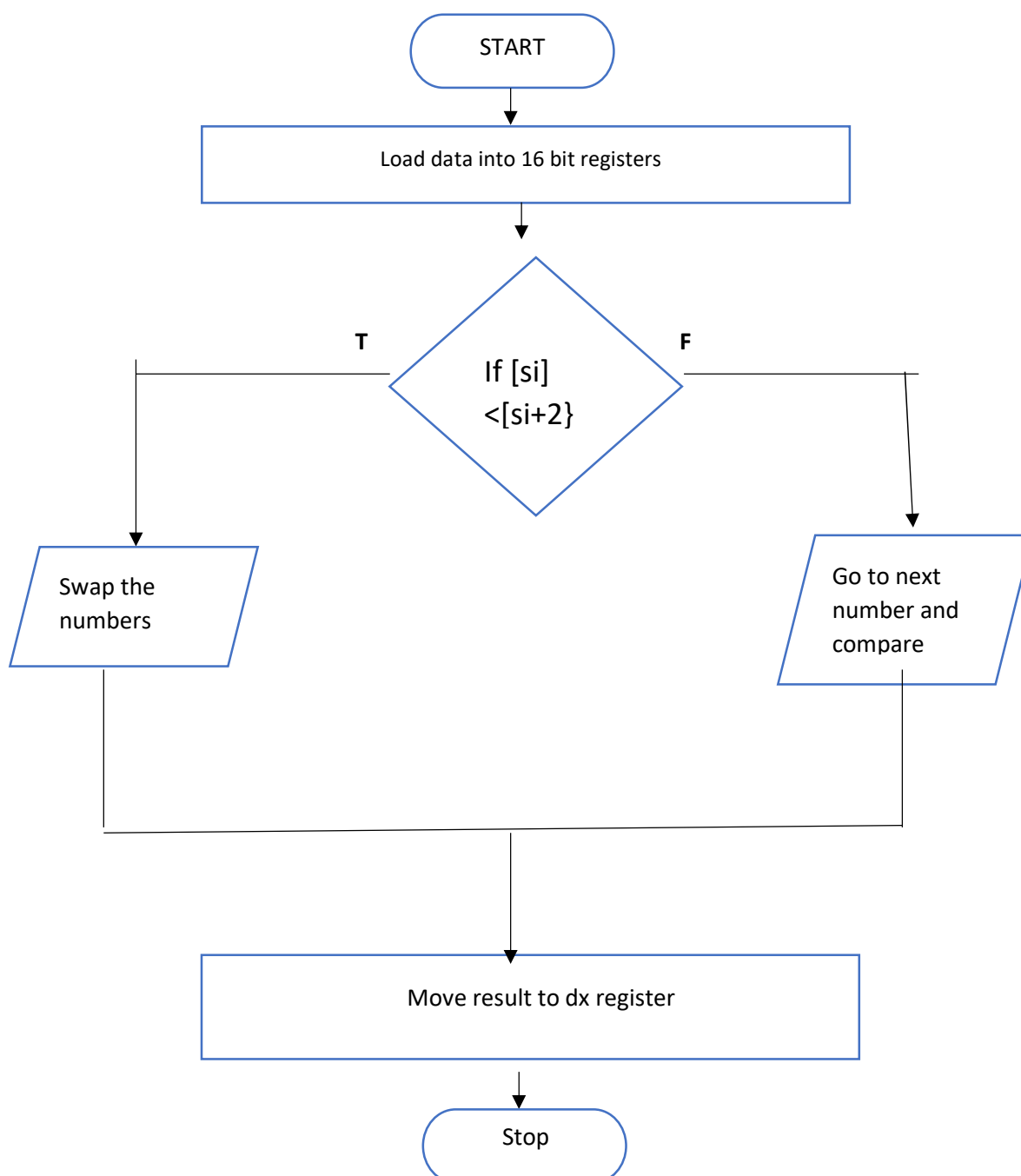
Transfer-Of-Control Instructions :-

- 9) **LOOP** :- The Loop instruction provides a simple way to repeat a block of statements a specific number of times. The Loop instructions use the CX register to indicate the loop count.
Flags affected :- None

Syntax :- LOOP label

Example :- LOOP 2050

Flowchart:



Code:

data segment

```
string1 dw 14h,10h,5h,15h,21h
```

data ends

code segment

```
assume cs:code,ds:data
```

start:

```

mov ax,data
mov ds,ax
mov bx,5
up1: lea si,string1
mov cx,4
up: mov ax,[si]
cmp ax,[si+2]
jnc down

xchg ax,[si+2]
xchg ax,[si]
down: add si,2
loop up
dec bx
jnz up1
int 3
code ends
end start

```

Program:

MEMORY LOCATION	OP-CODE	LABEL	MNEMONIC
07110h 07111h 07112h	B8 10 07		MOV AX, DATA
07113h 07114hh	8E D8		MOV DS, AX
07115h 07116h 07117h	BB 05 00		MOV BX, 5
07118h 07119hh 0711Ah	BE 00 00	UP1	LEA SI, STRING1
0711Bh 0711Ch 0711Dh	B9 04 00		MOV CX, 4
0711Ehh 0711Fh	8B 04	UP	MOV AX, [SI]
07120h 07121h 07122h	3B 44 02		CMP AX, [SI + 2]
07123h 07124h	72 05		JNC DOWN

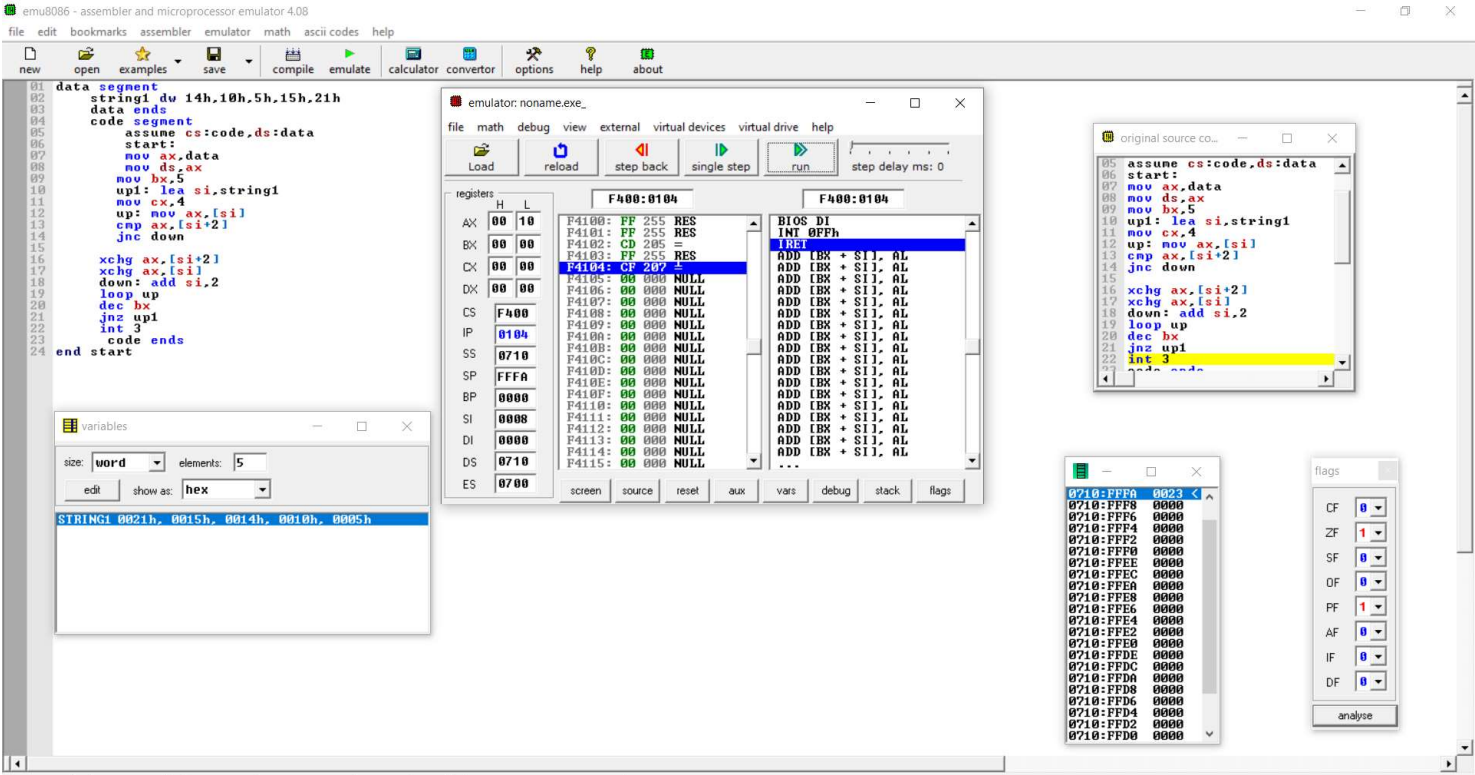
0712Ah	83	DOWN	ADD SI, 2
0712Bh	C6		
0712Ch	02		
0712Dh	E2		LOOP UP
0712Eh	EF		
07125h	87		XCHG AX, [SI + 2]
07126h	44		
07127h	02		
07128h	87		XCHG AX, [SI]
07129h	04		
0712Fh	4B		DEC BX
07130h	75		JNZ UP1
07131h	E6		
07132h	CC		INT 3

Result:

Input		Output	
Register	Data	Register	Data
AX	0014h, 0010h, 0005h, 0015h, 0021h	AX	0021h, 0015h, 0014h, 0010h, 0005h

Flags Affected : Zero flag, Parity flag

Screenshot:



Conclusion : - Thus we have understood 8086 Assembly language programming for arranging 16 bit numbers in descending order.

Experiment no. 9

Aim: 8086 Assembly language programming for block transfer of 16 bit data.

Requirements: 8086 microprocessor kit/MASM ----1 2.RPS (+5V) ----1,]and Emu8086 Emulator

Theory:

Data Transfer Instructions : -

- 1) **MOV** :- MOV instruction is used to transfer byte or word from register to register, memory to register, register to memory or with immediate addressing.
Flags affected :- None

Syntax :- MOV destination, source

Example :- MOV AX,BX

- 2) **LEA** :- LEA instruction computes the effective address of the second operand (source operand) and stores it in the first operand (destination operand).
Flags affected :- None

Syntax :- LEA destination, source

Example :- LEA AX, BX

Transfer-Of-Control Instructions : -

- 3) **LOOP** :- The Loop instruction provides a simple way to repeat a block of statements a specific number of times. The Loop instructions use the CX register to indicate the loop count.
Flags affected :- None

Syntax :- LOOP label

Example :- LOOP 2050

String Instructions : -

- 4) **MOVSB** :- The MOVSB (move string, byte) instruction fetches the byte at address SI, stores it at address DI and then increments or decrements the SI & DI registers by 1.
Flags affected :- None

Syntax :- LEA destination, source

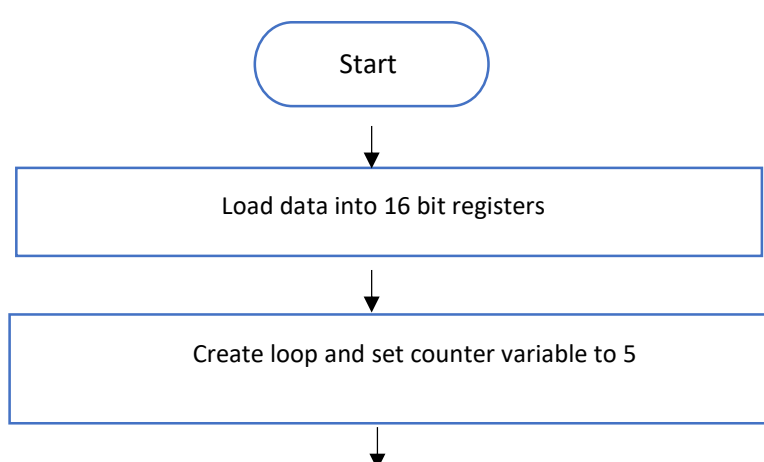
Example :- MOV SI, OFFSET SOURCE
MOV DI, OFFSET DESTINATION
CLD
MOV CX, 04H
REP MOVSB

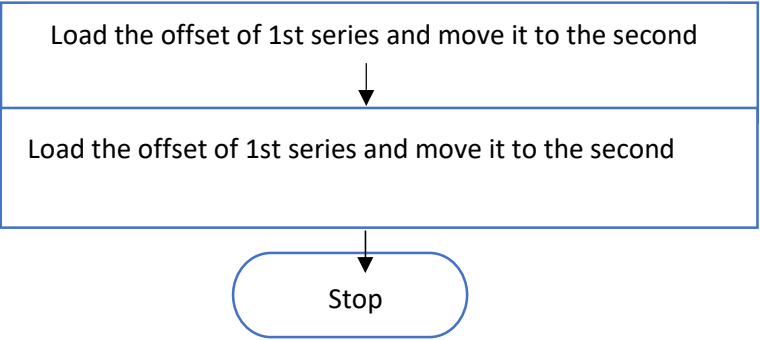
Miscellaneous Instructions : -

- 5) **INT** :- Used to interrupt the program during execution and calling service specified.

Example:- INT 3 -> This is a special form, which has the single-byte code of CCH;

Flowchart:





Code:

```
data segment
    string1 dw 0101h,0303h,0505h,0707h,0909h
    string2 dw 5DUP<0>
data ends

code segment
    assume cs:code ds:data

start:
    mov ax,data
    mov ds,ax
    mov es,ax
    mov cx,5
    lea si,string1
    lea di,string2

    up: movsw
    loop up
    int 3
code ends
```

end start

Program :

MEMORY LOCATION	OP-CODE	LABEL	MNEMONIC
07110h 07111h 07112hh	B8 10 07		MOV AX, DATA
07113h 07114h	8E D8		MOV DX, AX
07115h 07116h	8E C0		MOV ES, AX
07118h 07119h	B1 05		MOV CX, 5
07110h 0711Ah 0711Bh	BE 00 00		LEA SI, STRING1
0711Ch 0711Dh 0711Eh	BF 05 00		LEA DI, STRING2
0711Fh	A4	UP	MOVSW
07120h 07121h	E2 FD		LOOP UP
07122h	CC		INT 3

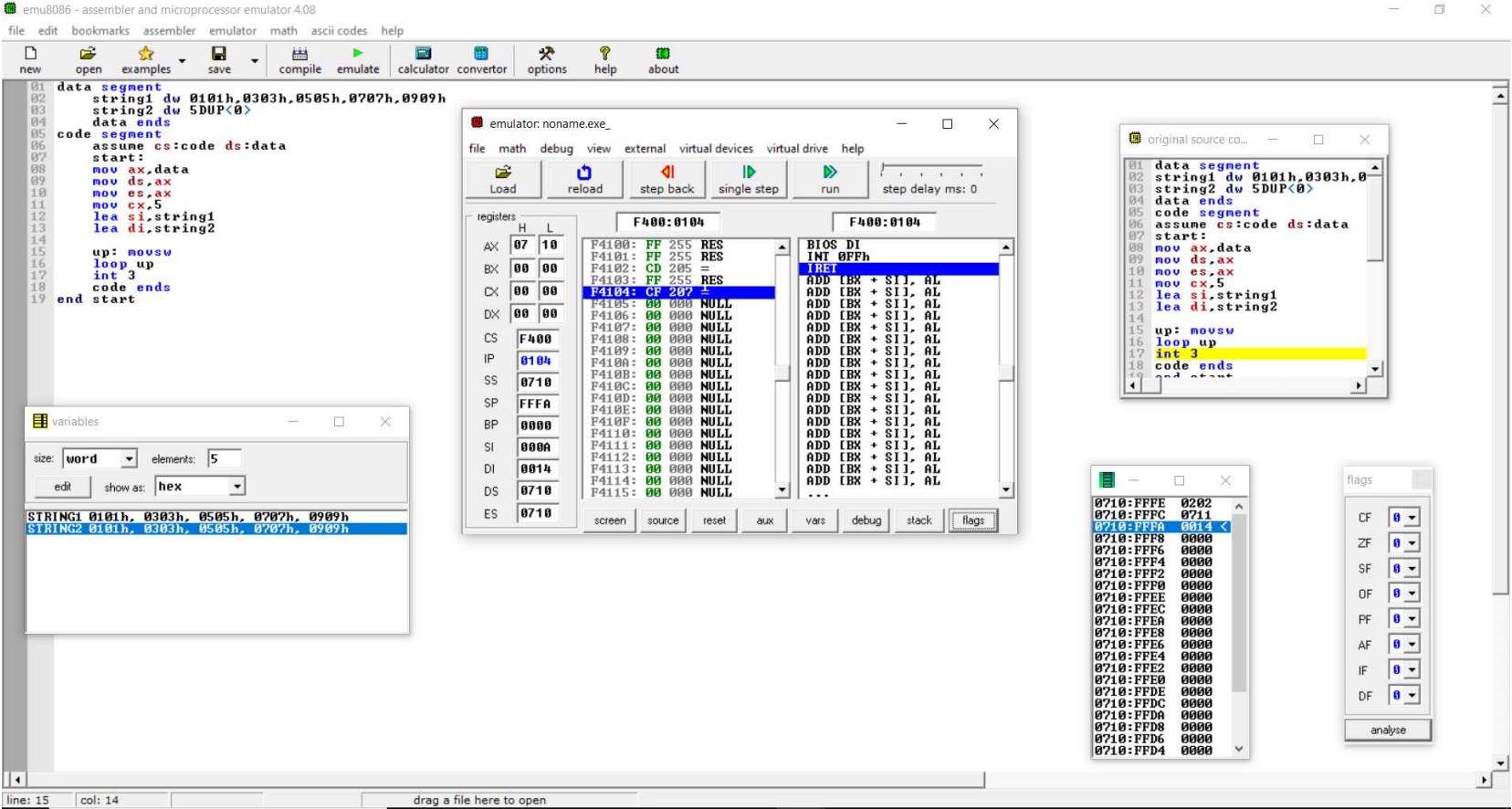
Result:

INPUT		OUTPUT	
REGISTER	DATA	REGISTER	DATA

SI	0101h,0303h,0505h,0707h,0909h	DI	0101h,0303h,0505h,0707h,0909h
----	-------------------------------	----	-------------------------------

Flag Affected : No flags affected

Screenshot :



Conclusion : - Thus we have understood 8086 Assembly language programming for block transfer of 16 bit data.

Experiment no. 10

Aim: Write a program in assembly language to find cube of any 16 bit number.

Requirements: 8086 microprocessor kit/MASM ----1 2.RPS (+5V) ----1,]and Emu8086 Emulator

Theory:

Data Transfer Instruction:

Mov Instruction:

This instruction comes under **Data Transfer Instruction**. The MOV instruction copies a word or byte of data from a specified source to a specified destination. MOV instruction does not affect any flag

Syntax: MOV Destination, Source

Example: MOV AX,6

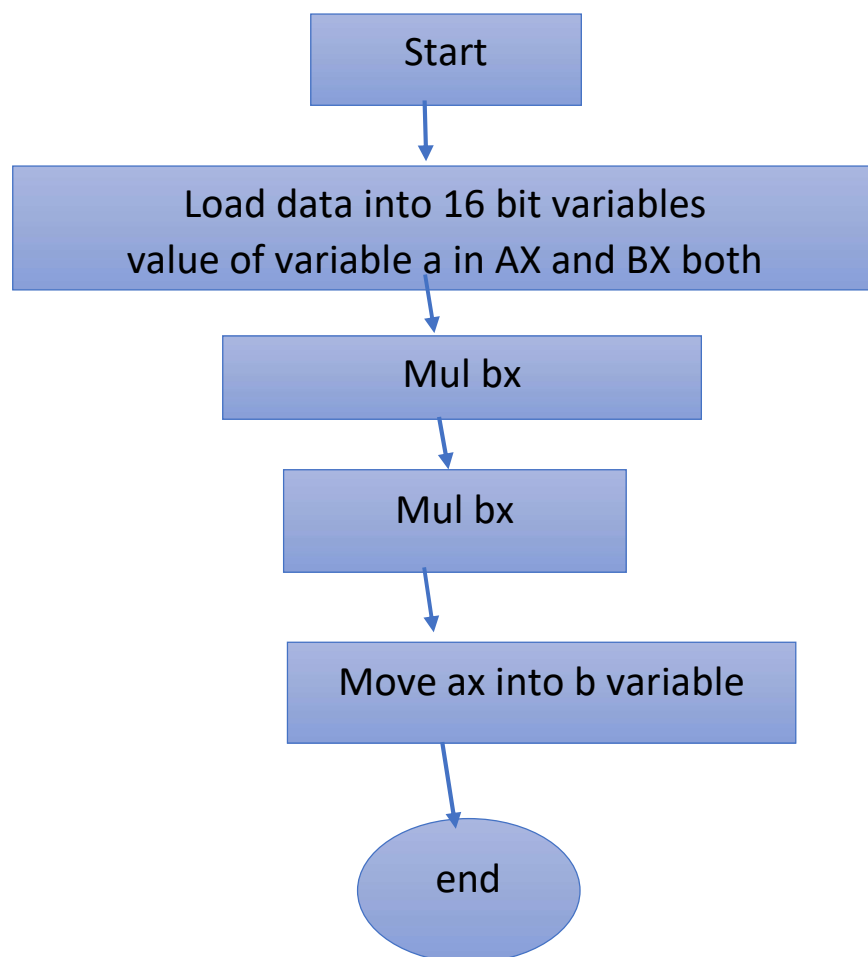
Arithmetic Instructions : -

MUL : - MUL is used to multiply an unsigned byte in some source with an unsigned byte in AL register or an unsigned word in some source with an unsigned word in AX register.

Syntax : - MUL source

Example : - MUL BH

FlowChart :



Code :

data segment

 a dw 0005h

 b dw ?

data ends

code segment

 assume cs: code, ds:data

```
start:

mov ax, data

mov ds, ax

mov ax, a

mov bx, a

mul bx

mul bx

mov b,ax

int 3

code ends

end start
```

Program:

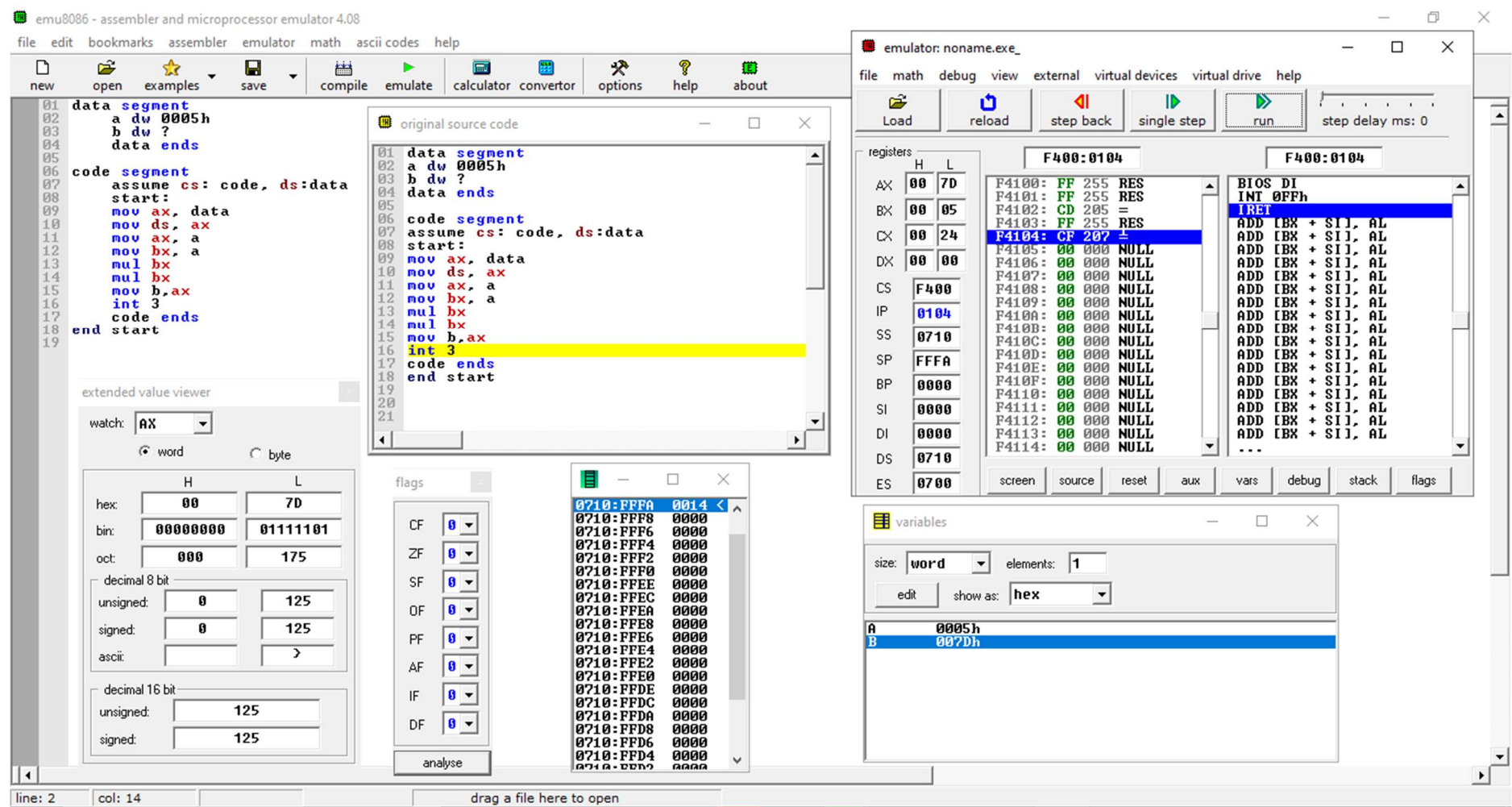
MEMORY LOCATION	OP-CODE	LABEL	MNEMONIC
07110h	B8		mov ax, data
07111h	10		
07112h	07		
07113h	8E		mov ds, ax
07114h	D8		
07115h	A1		mov ax, a
07116h	00		
07117h	00		
07118h	8B		mov bx, a
07119h	1E		
0711Ah	00		
0711Bh	00		
0711Ch	F7		mul bx
0711Dh	E3		
0711Eh	F7		mul bx
0711Fh	E3		
07120h	A3		mov b, ax
07121h	02		
07122h	00		
07123h	CC		int 3

Output:

INPUT		OUTPUT	
REGISTER	DATA	REGISTER	DATA
AX	0002H	AX	0008h
BX	0002H		

FLAG AFFECTED : --None--

Screenshot:



Conclusion: Thus we understood and executed assembly program to find cube of numbers