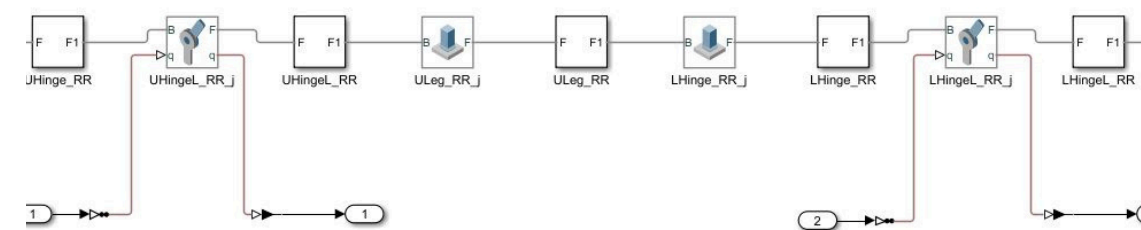


Multibody Model of Hexapod Leg



Gravity
Inertia
Friction