view_frames Result Recorded at time: 1529522031.931 map Broadcaster: /amcl Average rate: 15.227 Hz Most recent transform: 1529522031.909 (0.022 sec old) Buffer length: 4.400 sec odom Broadcaster: /movo/movo_driver Average rate: 15.291 Hz Most recent transform: 1529522031.849 (0.083 sec old) Buffer length: 4.839 sec base_link Broadcaster: /robot_state_publisher Average rate: 100.212 Hz Most recent transform: 1529522031.925 (0.006 sec old) Buffer length: 4.920 sec base_chassis_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 100.212 Hz Most recent transform: 1529522031.925 (0.006 sec old) \ Most recent transform: 1529522031.925 (0.006 sec old) Most recent transform: 1529522031.925 (0.006 sec old) Buffer length: 4.920 sec linear_actuator_fixed_link mid_body_link rear_laser_link lower_body_link sic_imu_frame front_laser_link Broadcaster: /robot_state_publisher Average rate: 100.212 Hz Most recent transform: 1529522031.925 (0.006 sec old) Buffer length: 4.920 sec linear_actuator_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 100.212 Hz Average rate: 100.212 Hz Average rate: 100.212 Hz Average rate: 100.212 Hz Most recent transform: 1529522031.925 (0.006 sec old) | Most recent transform: 1529522031.925 (0.006 sec old) | Most recent transform: 1529522031.925 (0.006 sec old) | Most recent transform: 1529522031.925 (0.006 sec old) | Most recent transform: 1529522031.925 (0.006 sec old) | Most recent transform: 1529522031.925 (0.006 sec old) | Most recent transform: 1529522031.925 (0.006 sec old) | Most recent transform: 1529522031.925 (0.006 sec old) | Most recent transform: 1529522031.925 (0.006 sec old) | Most recent transform: 1529522031.925 (0.006 sec old) | Most 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