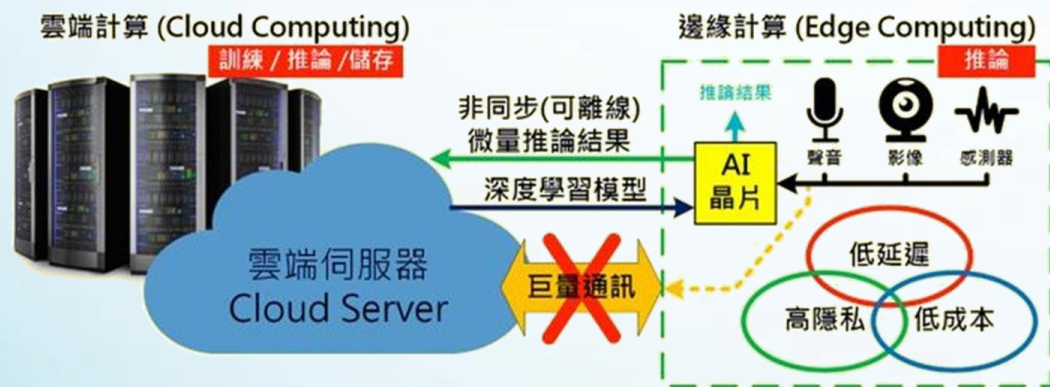


# OmniXRI's Edge AI & TinyML 小學堂



沒有最邊



只有更邊

歡迎加入  
邊緣人俱樂部



【第11講】

案例實作 — 姿態估測



歐尼克斯實境互動工作室 (OmniXRI Studio)  
許哲豪 (Jack Hsu)

# 簡報大綱



- 11.1. 姿態估測簡介
- 11.2. 姿態估測模型
- 11.3. 姿態估測評量
- 11.4. 姿態估測實作

**本課程完全免費，請勿移作商業用途！**  
**歡迎留言、訂閱、點讚、轉發，讓更多需要的朋友也能一起學習。**

完整課程大綱：<https://omnixri.blogspot.com/2024/02/omnixris-edge-ai-tinymml-0.html>  
課程直播清單：<https://www.youtube.com/@omnixri1784/streams>

# 姿態估測(Pose Estimation)

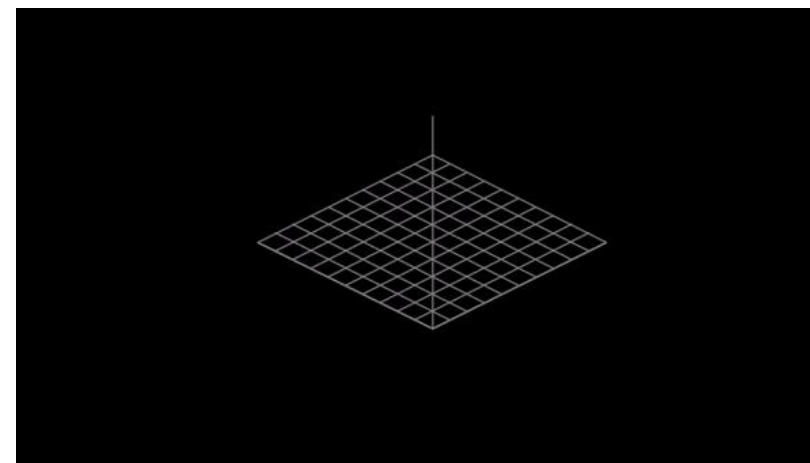
## 主要部位

- 頭部
- 注視點
- 手部
- 全身



## 估測方式

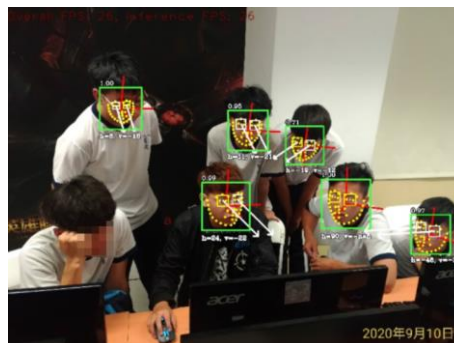
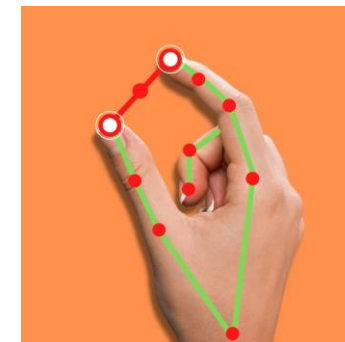
- 2D ( 照片、攝影機 )
- 3D ( 深度攝影機 )
- 2.5D ( 假3D，輸入2D，輸出3D，以平面估測立體深度 )



# 姿態估測常見用途

## 常見用途

- 人機互動
- 運動分析
- 組裝確認
- 智慧零售
- 智慧安防
- 智慧教室
- 安全駕駛
- ...

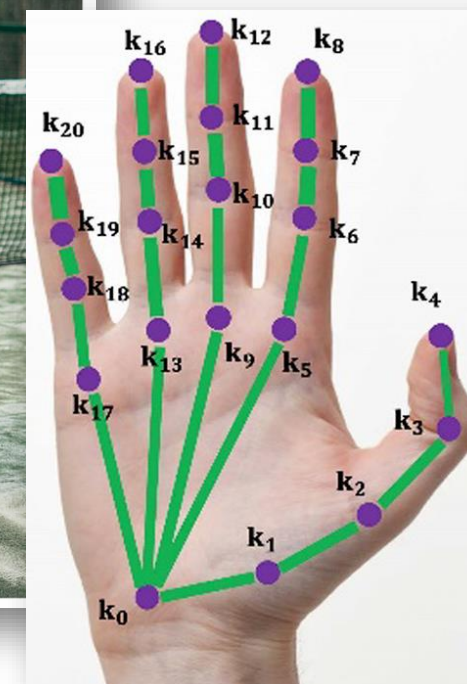
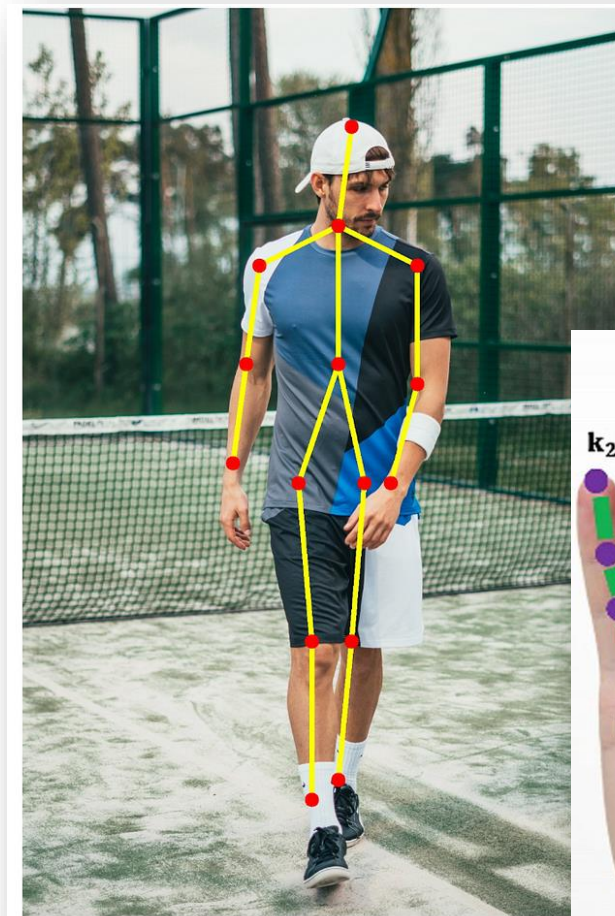




# 姿態估測 ( 人體關鍵點 ) 資料集

## 常見的2D關鍵點開放資料集

- 微軟COCO (17點)
- CMU OpenPose (18/25點)
  - 人體骨架 (18/25點)
  - 臉部動作 (70點)
  - 手部動作 (22點)
- MPII (16點)
- AI Challenge (14點)
- LSP (14點)
- FLIC (9點)



# 姿態估測標註比較



資料來源：<https://arxiv.org/abs/2204.07370>



# MS COCO 關鍵點資料集

## Person\_keypoints\_val2017 範例 (JSON)



```

annotation{
  "keypoints": [x1,y1,v1,...],
  "num_keypoints": int,
  "id": int,
  "image_id": int,
  "category_id": int,
  "segmentation": RLE or [polygon],
  "area": float,
  "bbox": [x,y,width,height],
  "iscrowd": 0 or 1,
}

```

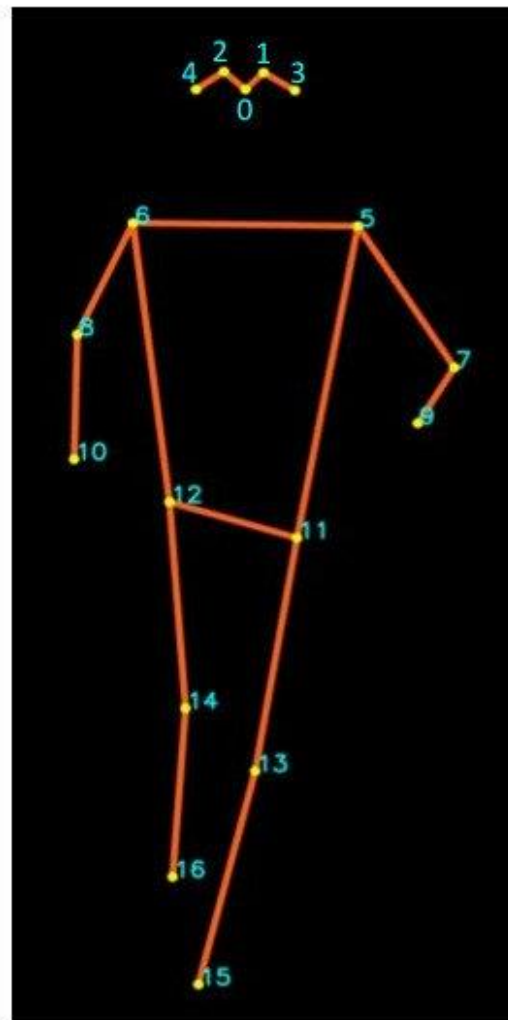
v=0 未標註, xy須為0  
 v=1 已標註但不可見  
 v=2 標註且可見

資料來源：<https://cocodataset.org/#keypoints-2020>, <https://cocodataset.org/#keypoints-eval>

# MS COCO 關鍵點定義



Index	Key point
0	Nose
1	Left-eye
2	Right-eye
3	Left-ear
4	Right-ear
5	Left-shoulder
6	Right-shoulder
7	Left-elbow
8	Right-elbow
9	Left-wrist
10	Right-wrist
11	Left-hip
12	Right-hip
13	Left-knee
14	Right-knee
15	Left-ankle
16	Right-ankle



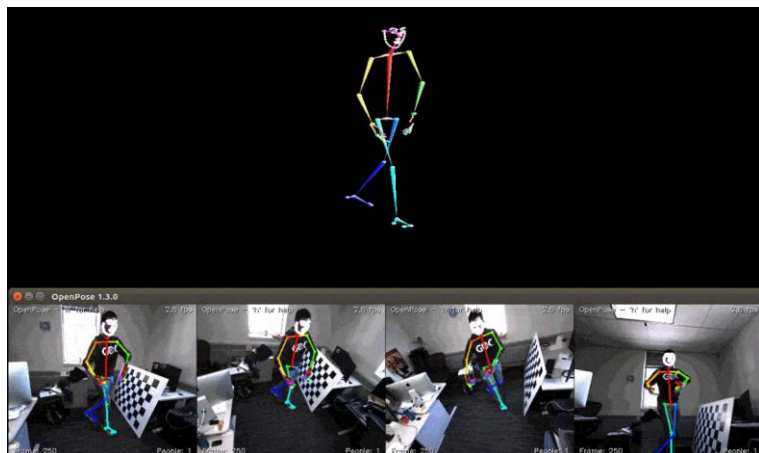
## Categories字串

```
{
  "id": int,
  "name": str,
  "supercategory": str,
  "keypoints": [str],
  "skeleton": [edge]
}
```

關鍵點名稱 (17)  
骨架連結



# OpenPose 基本介紹



卡內基美濃大學(CMU) 2017年提出。

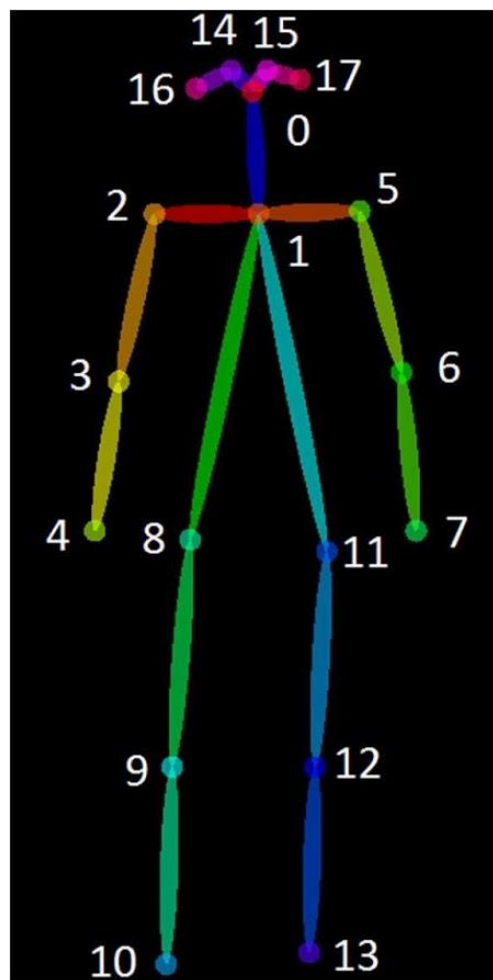
開源人體姿態專案，包含即時人體動作(2D/3D)、面部表情及手指運動偵測等。

支援Windows, Linux(Ubuntu), Mac OS。支援CPU及GPU(CUDA, OpenCL)加速。

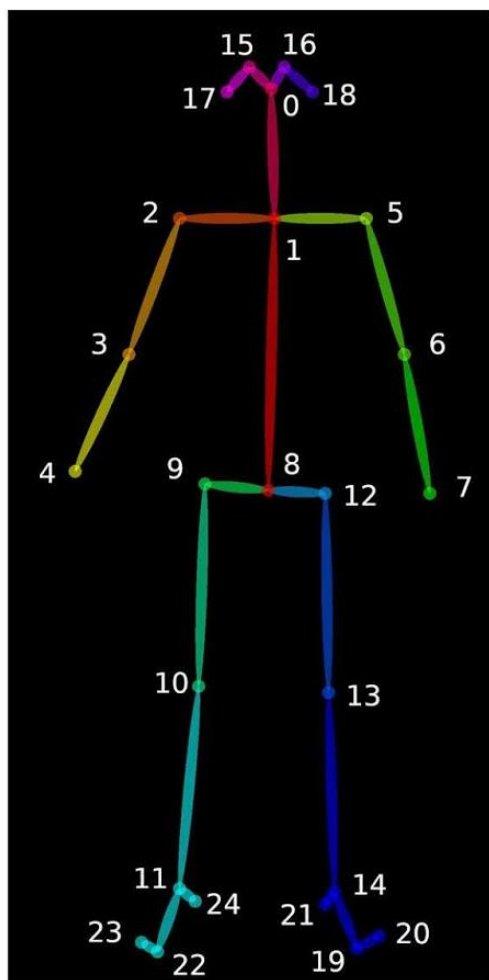


<https://github.com/CMU-Perceptual-Computing-Lab/openpose>

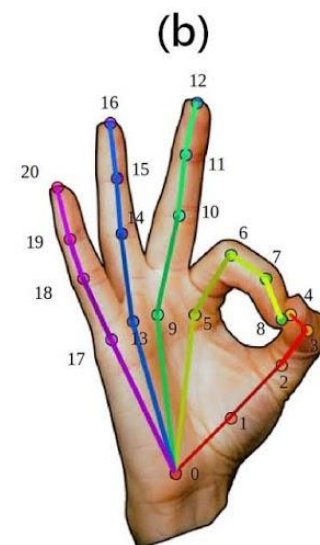
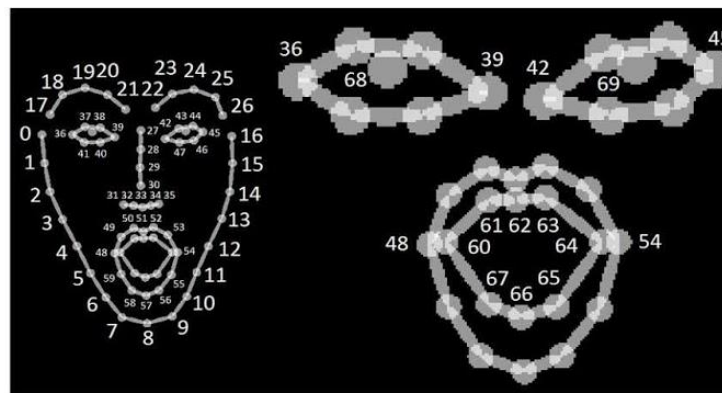
# OpenPose 關鍵點定義



(a)



(b)



(d)

## OpenPose

### 支援輸出格式：

(a) 類COCO 18點

(b) BODY 25點

(c) 臉部70點

(d) 手部22點

# 姿態關鍵點轉換

## MS COCO: (17點)

{0:鼻子, 1:左眼, 2:右眼, 3:左耳, 4:右耳, 5:左肩, 6:右肩, 7:左肘, 8:右肘, 9:左腕, 10:右腕, 11:左臀 (腰), 12:右臀 (腰), 13:左膝, 14:右膝, 15:左踝, 16:右踝 }

## CMU OpenPose: (18點)

{0:鼻子, 1:脖子, 2:右肩, 3:右肘, 4:右腕, 5:左肩, 6:左肘, 7:左腕, 8:右臀 (腰), 9:右膝, 10:右踝, 11:左臀 (腰), 12:左膝, 13:左踝, 14:左眼, 15:右眼, 16:左耳, 17:右耳 }



# 人體姿態估測模型(OpenVINO OMZ)

## Legacy Features\ Open Model Zoo\

## Intel's Pre-Trained Model

Model Name ↕	Complexity (GFLOPs) ↕	Size (Mp) ↕
<a href="#">human-pose-estimation-0001</a>	15.435	4.099
<a href="#">human-pose-estimation-0005</a>	5.9393	8.1504
<a href="#">human-pose-estimation-0006</a>	8.8720	8.1504
<a href="#">human-pose-estimation-0007</a>	14.3707	8.1504

OpenPose

EfficientHRNet

[https://docs.openvino.ai/2024/omz\\_models\\_group\\_intel.html#human-pose-estimation-models](https://docs.openvino.ai/2024/omz_models_group_intel.html#human-pose-estimation-models)

## Public Pre-Trained Model

Model Name ↕	Implementation ↕	OMZ Model Name ↕	Accuracy ↕	GFlops ↕	mParams ↕
human-pose-estimation-3d-0001	PyTorch*	<a href="#">human-pose-estimation-3d-0001</a>	100.44437mm	18.998	5.074
single-human-pose-estimation-0001	PyTorch*	<a href="#">single-human-pose-estimation-0001</a>	69.0491%	60.125	33.165
higher-hrnet-w32-human-pose-estimation	PyTorch*	<a href="#">higher-hrnet-w32-human-pose-estimation</a>	64.64%	92.8364	28.6180

Lightweight OpenPose

Convolutional Pose Machines

HigherHRNet

[https://docs.openvino.ai/2024/omz\\_models\\_group\\_public.html#human-pose-estimation-models](https://docs.openvino.ai/2024/omz_models_group_public.html#human-pose-estimation-models)

# 人體姿態估測模型(OpenVINO Notebooks)

OpenVINO<sup>™</sup> Notebooks

Categories AI Tasks<sup>1</sup> Ecosystem

Filter AI Tasks by name

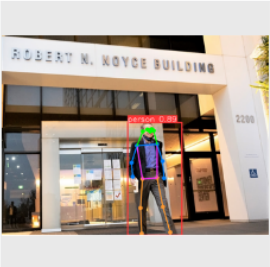
Computer Vision

- Image Classification
- Image Segmentation
- Image Inpainting
- Image-to-Image
- Object Detection
- Salient Object Detection
- Depth Estimation
- Super Resolution
- Style Transfer
- Pose Estimation**
- Zero-Shot Image Classification
- Text Detection


Notebooks 3 of 143 Reset Filters

Filter notebooks by name

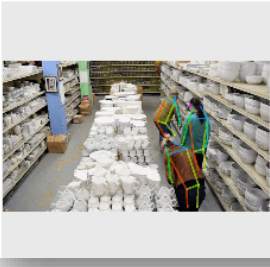
Sort: Recently Added



AI Trends Convert and Optimize YOLOv8 keypoint detection model with OpenVINO<sup>™</sup>  
Model Demos • Pose Estimation  
View on GitHub Open in Colab



Inference time: 60.9ms (18.7 FPS)  
Live 3D Human Pose Estimation with OpenVINO  
Live Demos • Pose Estimation  
View on GitHub Launch in Binder



Live Human Pose Estimation with OpenVINO<sup>™</sup>  
Live Demos • Pose Estimation  
View on GitHub Launch in Binder

[https://openvinotoolkit.github.io/openvino\\_notebooks/](https://openvinotoolkit.github.io/openvino_notebooks/)

2024/05/14

OmniXRI's Edge AI & TinyML 小學堂\_【第11講】實作案例－姿態估測\_OmniXRI\_JackHsu

13

# YOLOv8 姿態估測模型及資料格式

Model	size (pixels)	mAP <sup>pose</sup> <sub>50-95</sub>	mAP <sup>pose</sup> <sub>50</sub>	Speed CPU ONNX (ms)	Speed A100 TensorRT (ms)	params (M)	FLOPs (B)
<a href="#">YOLOv8n-pose</a>	640	50.4	80.1	131.8	1.18	3.3	9.2
<a href="#">YOLOv8s-pose</a>	640	60.0	86.2	233.2	1.42	11.6	30.2
<a href="#">YOLOv8m-pose</a>	640	65.0	88.8	456.3	2.00	26.4	81.0
<a href="#">YOLOv8l-pose</a>	640	67.6	90.0	784.5	2.59	44.4	168.6
<a href="#">YOLOv8x-pose</a>	640	69.2	90.2	1607.1	3.73	69.4	263.2
<a href="#">YOLOv8x-pose-p6</a>	1280	71.6	91.2	4088.7	10.04	99.1	1066.4

Format with Dim = 2

```
<class-index> <x> <y> <width> <height> <px1> <py1> <px2> <py2> ... <pxn> <pyn>
```

Format with Dim = 3

```
<class-index> <x> <y> <width> <height> <px1> <py1> <p1-visibility> <px2> <py2> <p2-visibility> <pxn> <pyn>
```

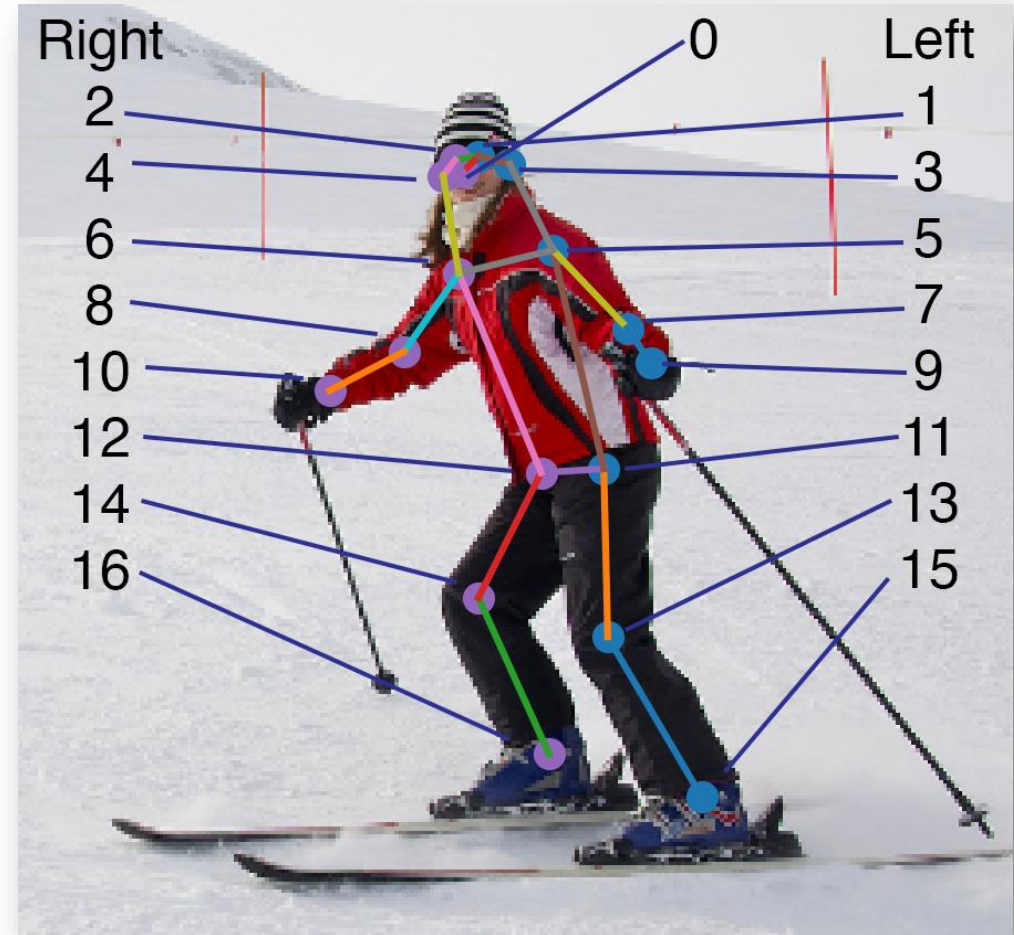
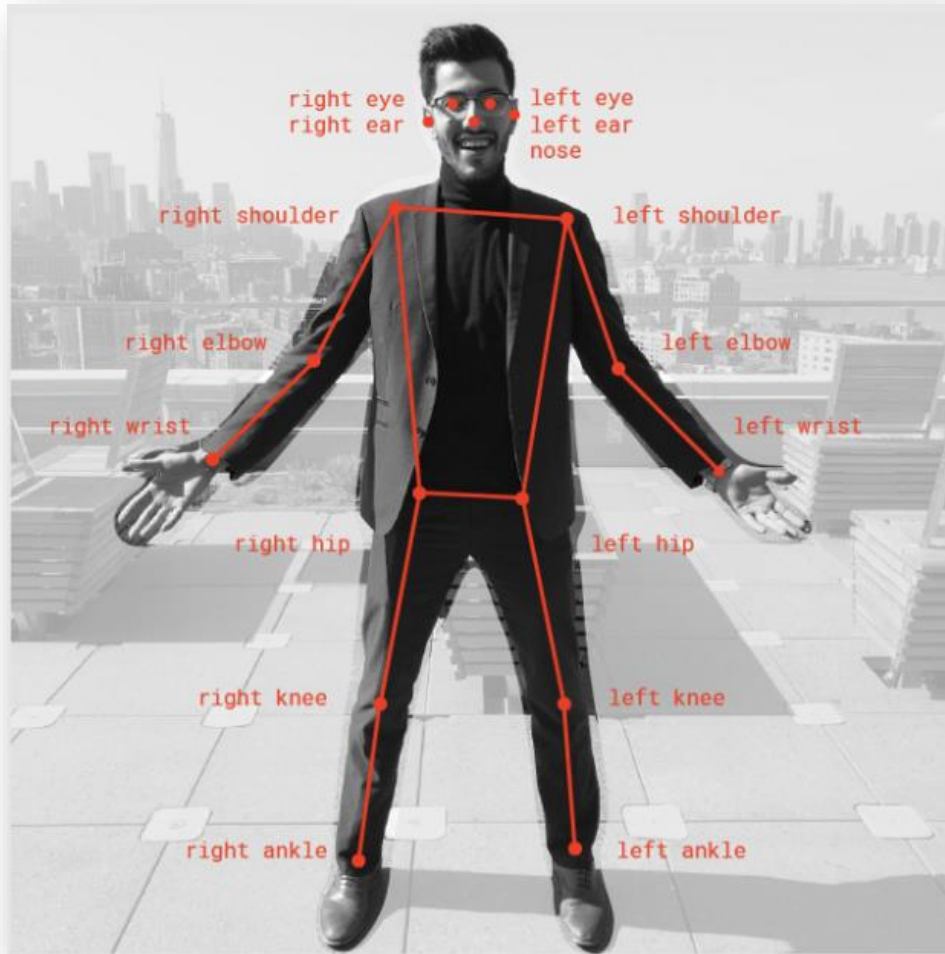
和 MS COCO  
Keypoints 定義類似

資料來源：<https://docs.ultralytics.com/tasks/pose/>

<https://docs.ultralytics.com/datasets/pose/>



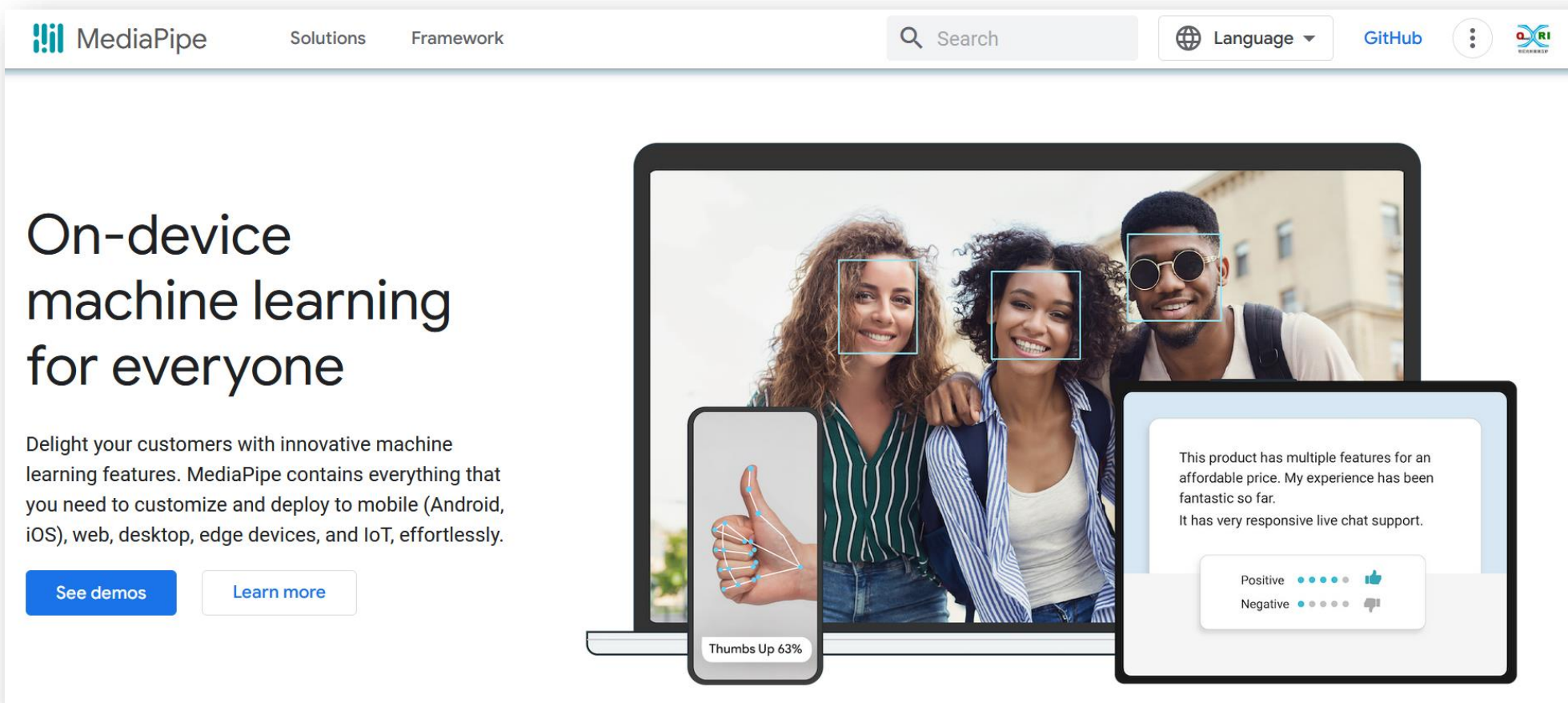
# Yolov8 關鍵點定義



和 MS COCO Keypoints 定義類似

資料來源：<https://chtseng.wordpress.com/2023/07/14/yolov8-pose-estimation/>

# Google MediPipe



**2019/6** 首次於**CVPR**  
展示預覽版本

**2023/4/3** 起由 <https://google.github.io/mediapipe/>  
遷移至 <https://developers.google.com/mediapipe>

# MediaPipe 主要特色



免費及開源  
支援CPU, GPU加速計算

多種解決方案

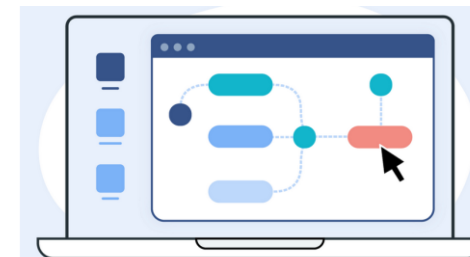
- 視覺
- 文字
- 聲音
- 生成式

多種開發框架

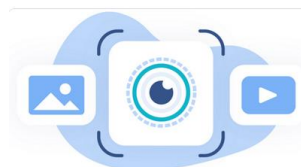
- Android
- iOS
- Python
- Web



Low-Code APIs

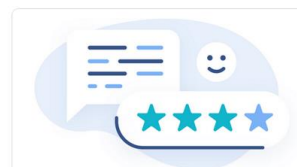


No-Code Studio



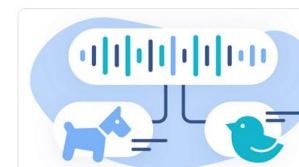
Vision

Analyze things in images and videos.



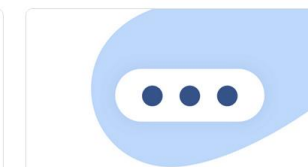
Natural language

Understand meanings behind text.



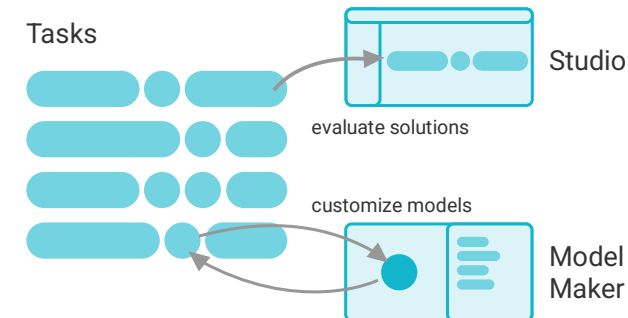
Audio

Listen and recognize sounds.



Others

More solutions coming soon.



<https://github.com/google/mediapipe>



# MediaPipe 解決方案



影像辨識



物件偵測



手勢辨識



人臉偵測



影像相似度



影像分割



交互式分割



手部特徵點



臉部特徵點



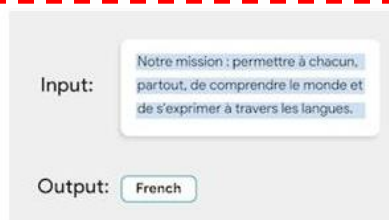
姿態特徵點



文字情緒



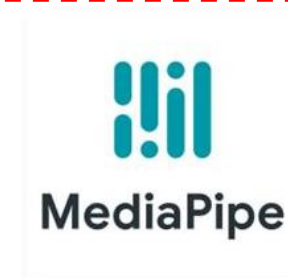
文字相似度



語系辨識



語音辨識



**DEMO:** <https://mediapipe-studio.webapps.google.com/home>

# 姿態估測指標

## Object Keypoint Similarity (OKS) 關鍵點相似度 (COCO)

$$OKS_p = \frac{\sum_i \exp\{-d_{pi}^2 / 2S_p^2\sigma_i^2\} \delta(v_{pi} > 0)}{\sum_i \delta(v_{pi} > 0)}$$

## Average Precision (AP) 平均精準度

(單人、多人)

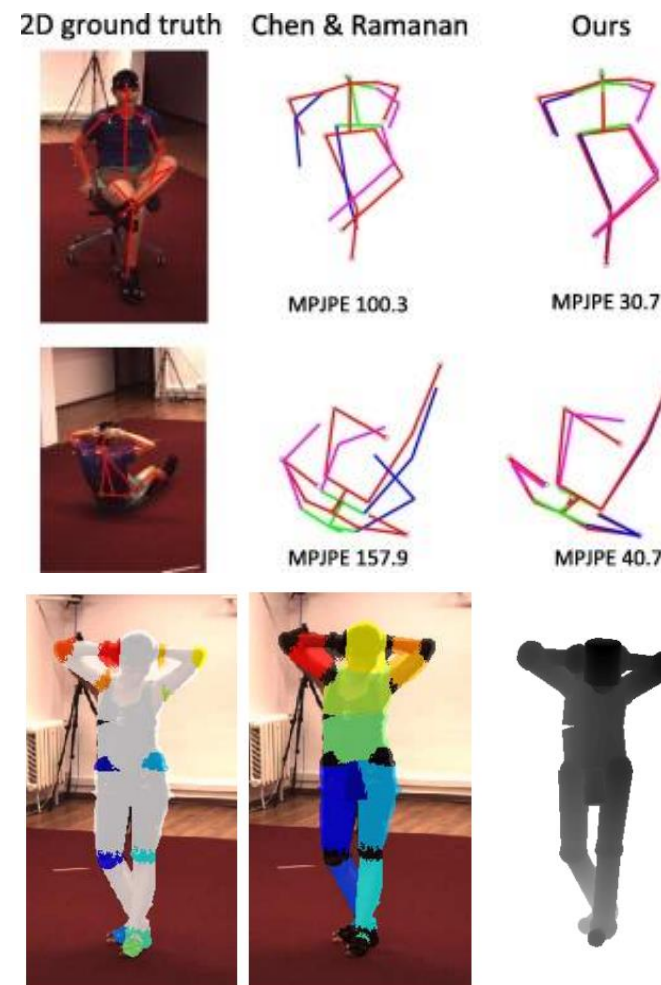
$$AP = \frac{\sum_p \delta(oks_p > T)}{\sum_p 1}$$

## Mean Per Joint Position Error (MPJPE)

每個關節位置誤差。

$$E_{MPJPE}(f, \mathcal{S}) = \frac{1}{N_S} \sum_{i=1}^{N_S} \|m_{f, \mathcal{S}}^{(f)}(i) - m_{gt, \mathcal{S}}^{(f)}(i)\|_2$$

資料來源：<http://vision.imar.ro/human3.6m/pami-h36m.pdf>



# 實作範例1 — YOLOv8 姿態估測 (OpenVINO Colab)

## Convert and Optimize YOLOv8 keypoint detection model with OpenVINO



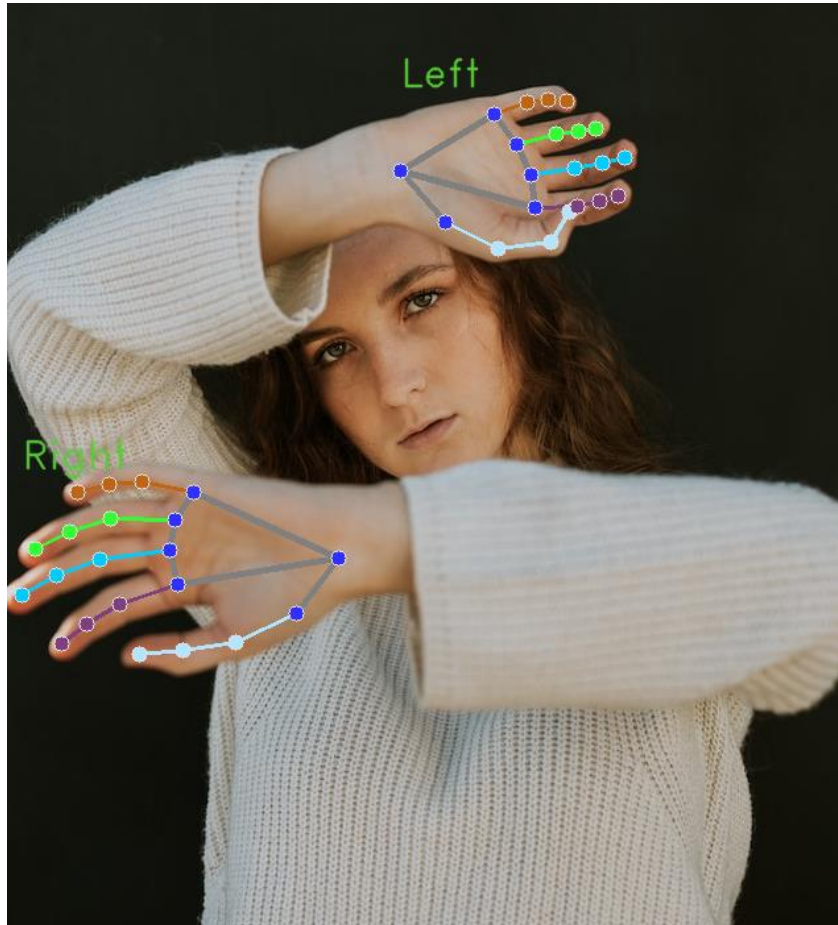
### 程式導讀：

- Prepare the PyTorch model.
- Download and prepare a dataset.
- Validate the original model.
- Convert the PyTorch model to OpenVINO IR.
- Validate the converted model.
- Prepare and run optimization pipeline.
- Compare performance of the FP32 and quantized models.
- Compare accuracy of the FP32 and quantized models.
- Live demo

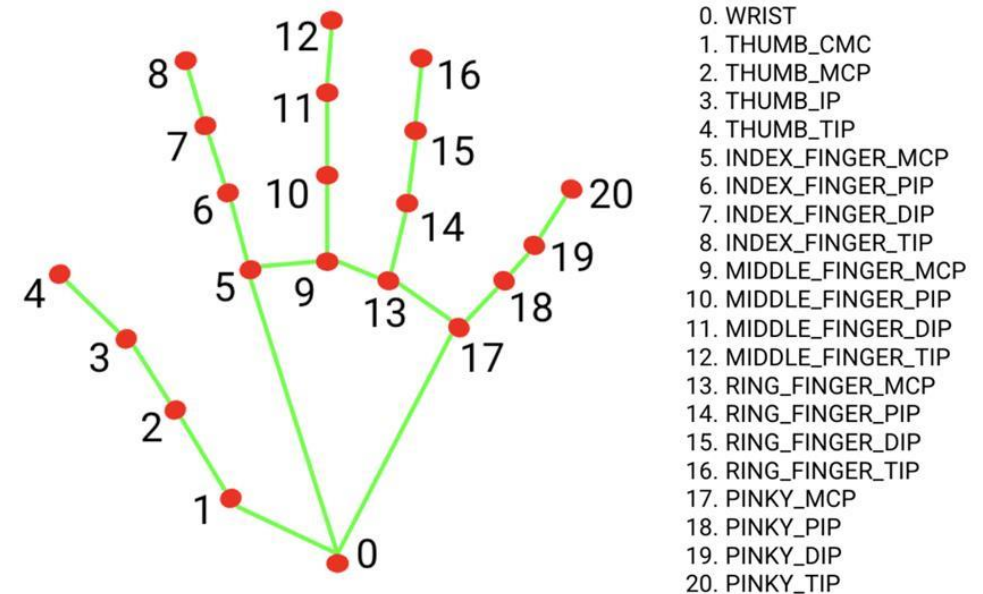
[https://colab.research.google.com/github/openvinotoolkit/openvino\\_notebooks/blob/latest/notebooks/yolov8-optimization/yolov8-keypoint-detection.ipynb](https://colab.research.google.com/github/openvinotoolkit/openvino_notebooks/blob/latest/notebooks/yolov8-optimization/yolov8-keypoint-detection.ipynb)



# 實作範例2 — 手部特徵點偵測 (MediaPipe Colab)



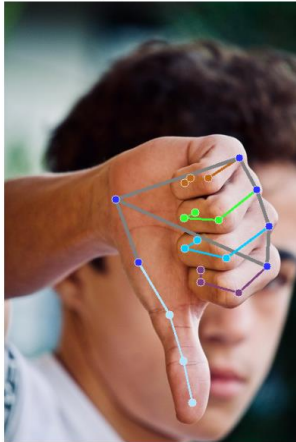
Model name	Input shape	Quantization type
HandLandmarker (full)	192 x 192, 224 x 224	float 16



[https://colab.research.google.com/github/googlesamples/mediapipe/blob/main/examples/hand\\_landmarker/python/hand\\_landmarker.ipynb](https://colab.research.google.com/github/googlesamples/mediapipe/blob/main/examples/hand_landmarker/python/hand_landmarker.ipynb)

# 實作範例3 — 手勢辨識 (MediaPipe Colab)

Thumb\_Down (0.77)



Thumb\_Up (0.73)



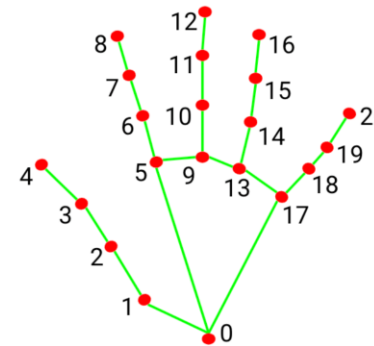
Victory (0.91)



Pointing\_Up (0.82)



Model name	Input shape	Quantization type
HandGestureClassifier	192 x 192, 224 x 224	float 16



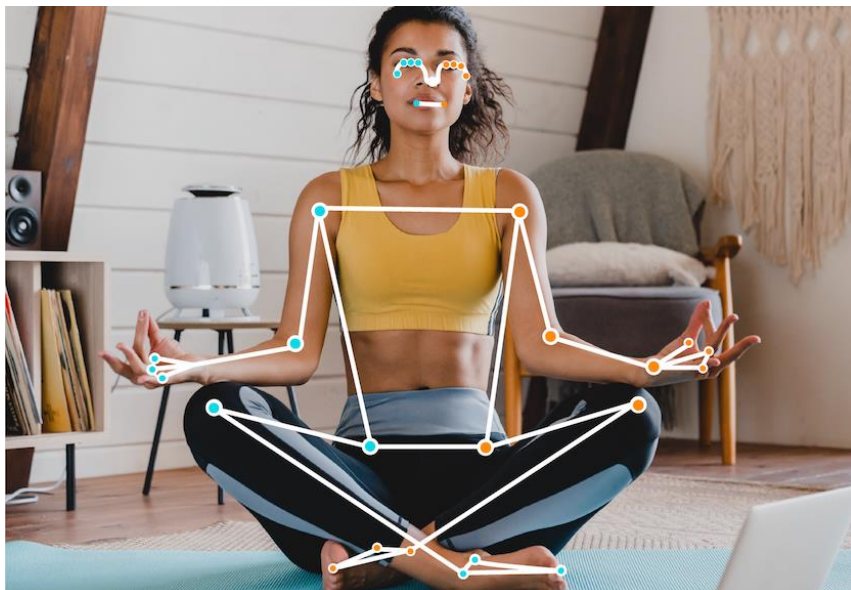
- 0. WRIST
- 1. THUMB\_CMC
- 2. THUMB\_MCP
- 3. THUMB\_IP
- 4. THUMB\_TIP
- 5. INDEX\_FINGER\_MCP
- 6. INDEX\_FINGER\_PIP
- 7. INDEX\_FINGER\_DIP
- 8. INDEX\_FINGER\_TIP
- 9. MIDDLE\_FINGER\_MCP
- 10. MIDDLE\_FINGER\_PIP
- 11. MIDDLE\_FINGER\_DIP
- 12. MIDDLE\_FINGER\_TIP
- 13. RING\_FINGER\_MCP
- 14. RING\_FINGER\_PIP
- 15. RING\_FINGER\_DIP
- 16. RING\_FINGER\_TIP
- 17. PINKY\_MCP
- 18. PINKY\_PIP
- 19. PINKY\_DIP
- 20. PINKY\_TIP

- 0 - Unrecognized gesture, label: Unknown
- 1 - Closed fist, label: Closed\_Fist
- 2 - Open palm, label: Open\_Palm
- 3 - Pointing up, label: Pointing\_Up
- 4 - Thumbs down, label: Thumb\_Down
- 5 - Thumbs up, label: Thumb\_Up
- 6 - Victory, label: Victory
- 7 - Love, label: ILoveYou

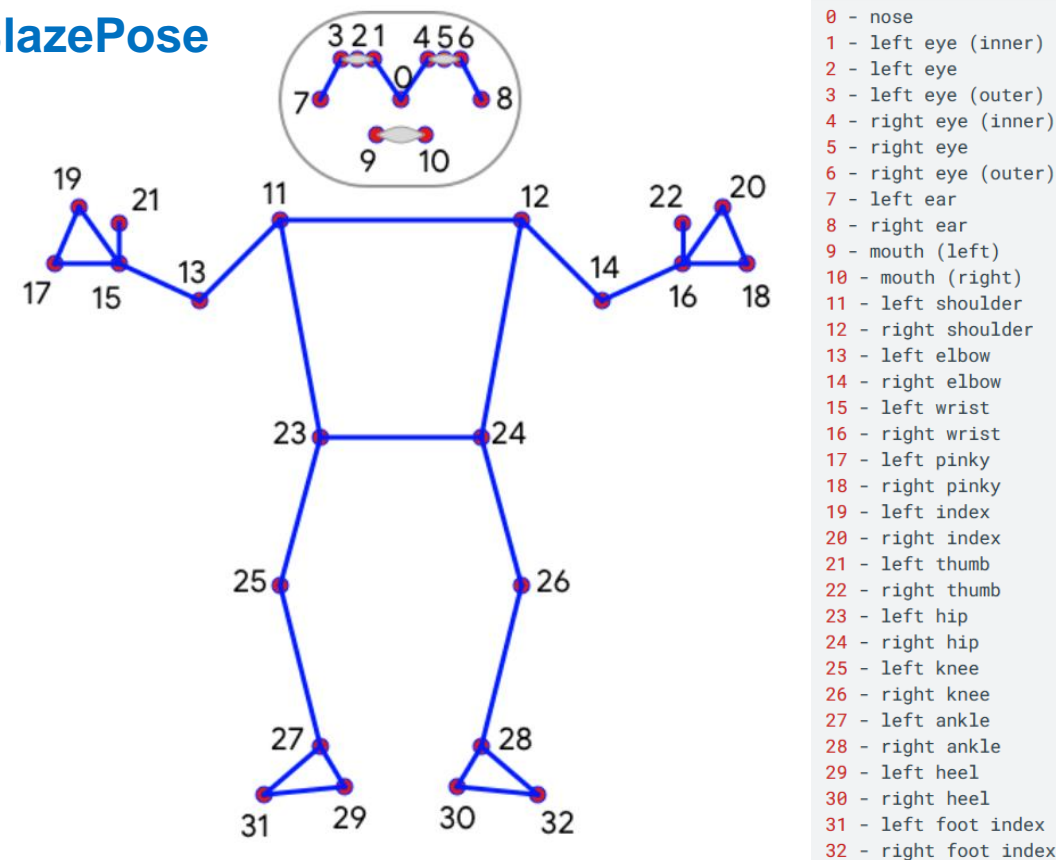


[https://colab.research.google.com/github/googlesamples/mediapipe/blob/main/examples/gesture\\_recognizer/python/gesture\\_recognizer.ipynb](https://colab.research.google.com/github/googlesamples/mediapipe/blob/main/examples/gesture_recognizer/python/gesture_recognizer.ipynb)

# 實作範例4 — 姿態特徵點偵測 (MediaPipe Colab)



## BlazePose



Model bundle	Input shape	Data type	Model Cards	Versions
Pose landmarker (lite)	Pose detector: 224 x 224 x 3 Pose landmarker: 256 x 256 x 3	float 16	<a href="#">info</a>	Latest
Pose landmarker (Full)	Pose detector: 224 x 224 x 3 Pose landmarker: 256 x 256 x 3	float 16	<a href="#">info</a>	Latest
Pose landmarker (Heavy)	Pose detector: 224 x 224 x 3 Pose landmarker: 256 x 256 x 3	float 16	<a href="#">info</a>	Latest

[https://colab.research.google.com/github/googlesamples/mediapipe/blob/main/examples/pose\\_landmarker/python/%5BMediaPipe\\_Python\\_Tasks%5D\\_Pose\\_Landmarker.ipynb](https://colab.research.google.com/github/googlesamples/mediapipe/blob/main/examples/pose_landmarker/python/%5BMediaPipe_Python_Tasks%5D_Pose_Landmarker.ipynb)



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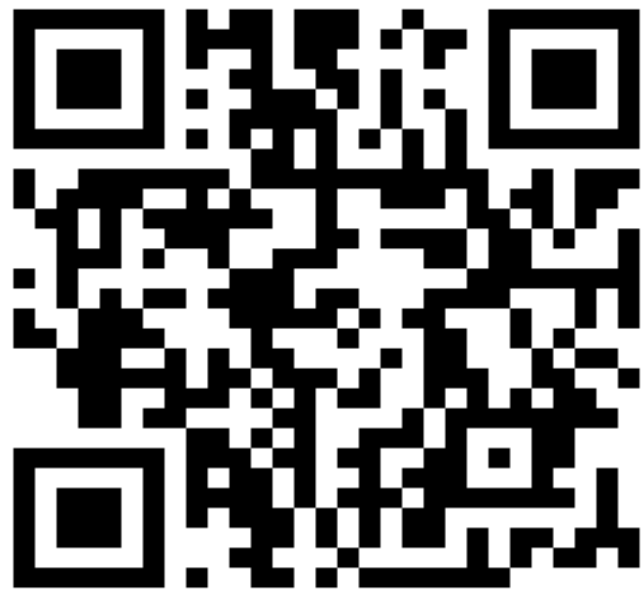
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